1. Understood that main functionality of the code is written in the loop() function which is called on a continuous basis (while(1)) in main.c
2. Void loop() is located in mw.c
3. Made any and all changes to code in mw.c
4. To get a basic understanding of just the c code, I turned on and off an LED on the board using one of the channels in the ez-gui app.
5. Understood that all the values of the channels of the ez-gui app can be accessed by one of AUX1,AUX2,AUX3 and AUX4.
6. Understood that user data can be taken using rcData. These user input values are then corrected and fined tuned by the pids and the output in the form of rcCommand is given to the motors.
7. Understood that there are three leds on board (led0,led1 and led2). These can be turned on/off by using the command led0\_op(true) to turn led0 on and led0\_op(false) to turn it off.

1. Started off by understanding the parts of code relevant to the task assigned to me.