

Aditya Bhat

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SUMMARY

Computer Vision and Deep Learning Engineer with 3+ years of industry and research experience, adept in **Python, C++, C#**, with practical expertise in **3D/2D** detection, tracking, segmentation, sensor fusion, camera calibration, and game development.

EDUCATION

MSc In Computer Science(Specializing in Computer Vision) | Rutgers University, New Brunswick, NJ | CGPA: 4.0 **Sep 2021 - May 2023**
BE In Information Science | BMS Institute of Technology Bangalore, India **Aug 2013 - Jun 2017**

SKILLS

Language: Python, C++, SQL. | **Frameworks:** PyTorch, Tensorflow, Open3D, Point Cloud Library(PCL), OpenCV, Numpy, scikit-learn, PIL.

Models: Detectron 2, Complex Yolov4, SFA3D, YOLOv5, Mask RCNN, SORT, DeepSORT | **Tools:** Unity 3D, Git, VSCode.

PROJECTS

3D Object Detection Using SFA3D (Language and libraries used: Python, Pytorch, OpenCV)

- Used Waymo Open Dataset and extracted **LiDAR Point Clouds** from range images. Converted point clouds to 2D bird's-eye view, trained SFA3D for 200 epochs, and visualized the results.

Sensor Fusion and Object Tracking (Language and libraries used: Python)

- Implemented an **Extended Kalman filter** and track management system with track state and score, initialization and deletion. Applied sensor fusion via the nonlinear camera measurement model and a sensor visibility check.

Motion Planning and Decision Making for Autonomous Vehicles(Language used: C++)

- Created a Behavior and Motion Planner to avoid collisions and navigate intersections. Used **Finite State Machines**, collision checking, and cost function to select the best trajectory.

Object Detection in an Urban Environment (Language and libraries used: Python, Pytorch)

- Trained the **YOLOv5** model to recognize and classify object categories such as 'cars', 'buses', 'trucks', and 'pedestrians'. Implemented **DeepSORT** to accurately track the detected objects.

WORK EXPERIENCE

Nokia Bell Labs

New Jersey, US

Applied AI/ML Machine Vision Intern

Jun 2022 - Aug 2022

- Computed homography matrices to **Calibrate the on-site Cameras** and checked the performance of the resultant estimation.
- Developed a custom lightweight classification model to detect the occlusions in the robots with a test accuracy of 95%.
- Implemented a Keypoint Detection model on over 2000 images to **reconstruct** the occluded bot using **Detectron2**. This process also facilitated in determining the occlusion level.
- Worked on an **Object Tracking System** that combines the localized estimates of objects from multiple cameras using a scoring system.

Thinking Stack

Bangalore, India

AI/ML Engineer

Oct 2020 - Jun 2021

- Developed 5 custom **YOLOv5 models** for detecting safety PPE kit, and trained with up to 4 augmentation techniques achieving an overall mAP(.50) value of 0.81.
- Built an image augmentation pipeline that enhanced model performance through data processing and increased lower-class image counts, resulting in a 10% accuracy boost.
- Researched and prototyped a drowsiness detection system using dlib library for **eye-tracking** and extracting facial features.

DHS Informatics

Bangalore, India

Machine Learning Intern

Feb 2020 - Jul 2020

- Utilized **Unity3d** and **ARCore** to create a Furniture Selection app to instantiate **3D models** of furniture. Extended functionalities to an AR Home application that enables architects to envision the appearance of housing plans in an empty area upon construction.
- Implemented a Content-Based Image Retrieval system, utilizing image histograms as feature descriptors to retrieve similar images as the query image.
- Developed and prototyped a **Facial Recognition system** with MediaPipe, and an attendance tracking system to record in-and-out times. Conducted experiments on facial recognition algorithms, including Local Binary Patterns Histograms and FisherFaces Recognizer.

Oracle Financial Service Software

Bangalore, India

Technical Analyst

Jun 2017 - Mar 2019

- Automated and installed Crime and Compliance Management tool, identified bugs using SQL and PL/SQL, coordinated with Product Development and Management Teams to resolve bugs, and ensured client satisfaction by heading meetings and providing fixes.

RESEARCH EXPERIENCE

INTELLIGENT VISUAL INTERFACES LAB, Rutgers University

New Jersey, US

Human Group Activity Recognition Using Synthetic Data.

Aug 2022 - Current

- Achieved 91% accuracy by training a **custom Mask RCNN** model on the Hieve dataset to detect and estimate the pose of 'person' class.
- Trained a **Siamese network** using 'Triplet loss' on a dataset to track people for the **DeepSort** algorithm and successfully tested synthetically generated datasets using this pipeline.