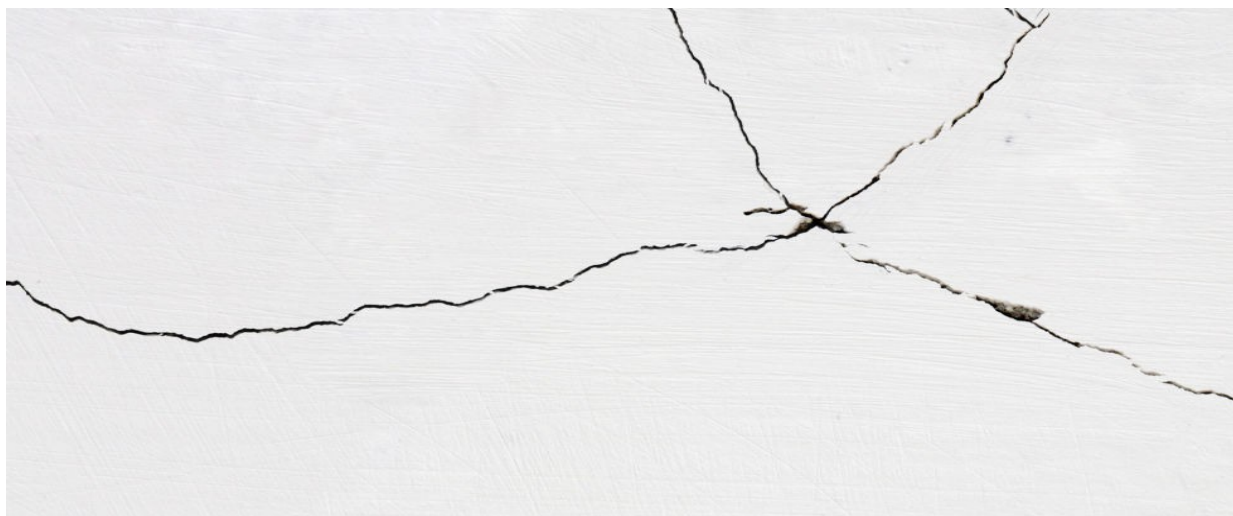


Brief Output Review of Crack Detection

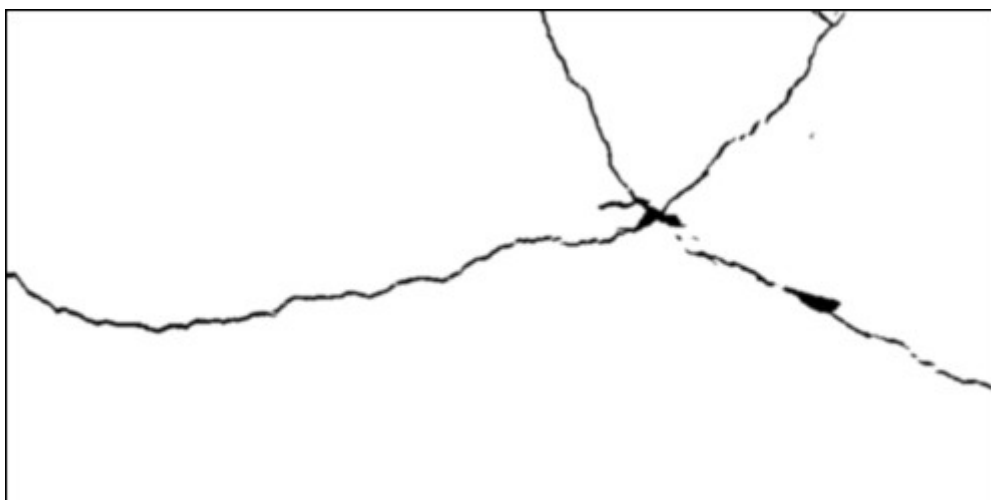
1) ORIGINAL IMAGE



2) THRESHOLDING



3) SMOOTHING



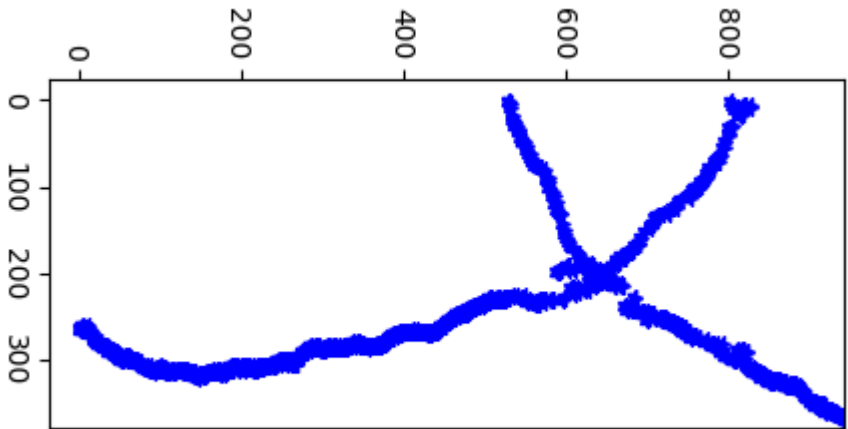
5)BLOB DETECTION



6)SKELETON



7)FINAL



The blue line are bunch of points, which should be given to robot and traced by it. They are in a order such that consecutive points do not have same x component. Which makes sure that while following a trajectory robot moves in continues forward motion. That is, if we zoom the result graph no two points on x axis will have same value.

In the form :

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