

README

Compiling

```
make all
```

Running

```
./main.o <input-file> <output-file> <optinal heuristic/relevant action selector id>
```

Optional Argument

If planning using Forward A* Search: Heuristic ID:

- 0: Optimal Height Based Heuristic.
- 1: Non-Optimal Total Goal Propositions Satisfied Count Based. **(default)**

If planning using Goal Stack Planner: Relevant Action Selector ID:

- 0: First Relevant Action Based.
- 1: Most Relevant Action Based.
- 2: Least Used Action with tie breaking with Most Relevant Action Based.
- 3: Manually coded Proposition-Action Tables Based. **(default)**