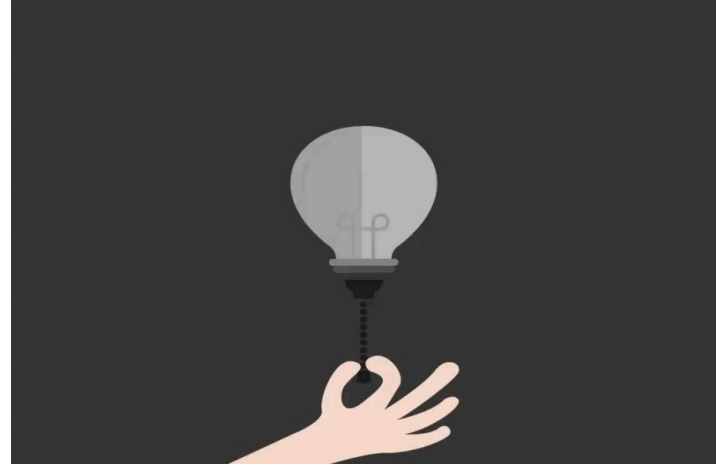


# Arduino Sensor Program

Aditya Kesari

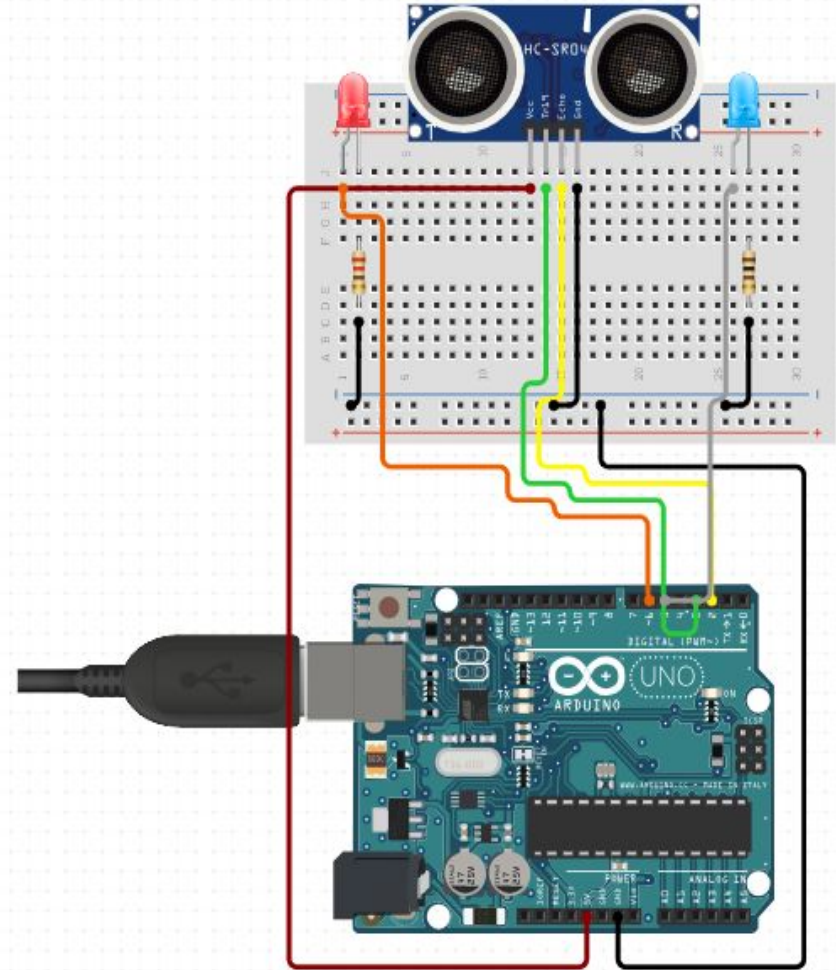
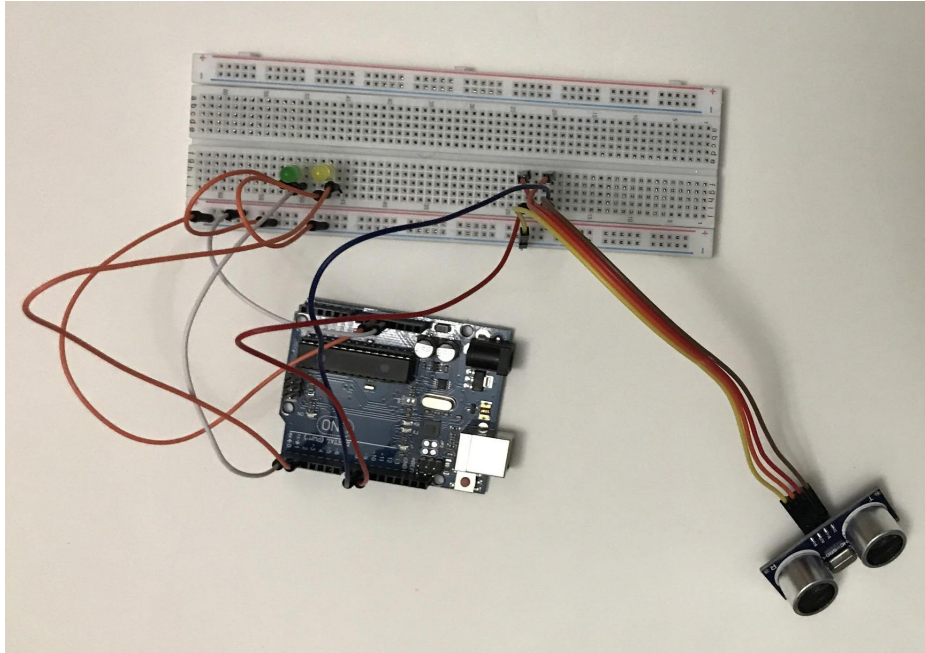
# Objective

Create a program where a sensor activates if an objective is present at a certain distance.

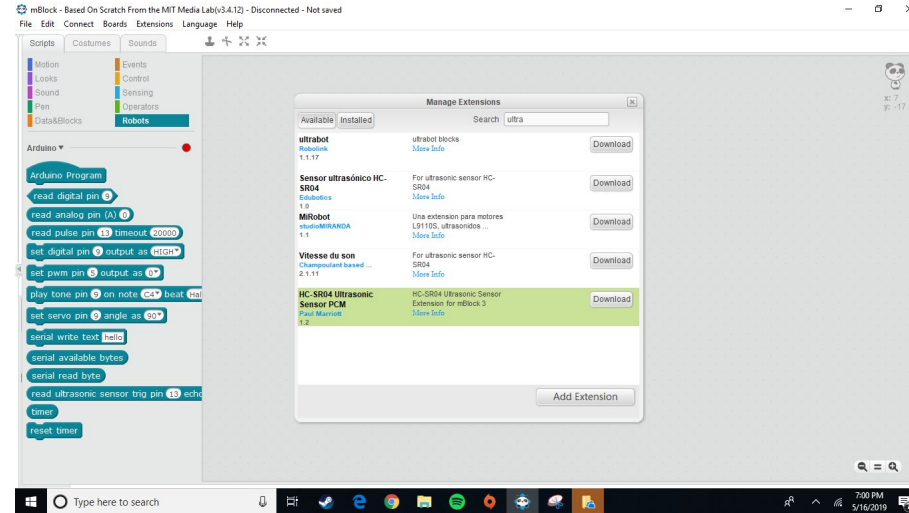
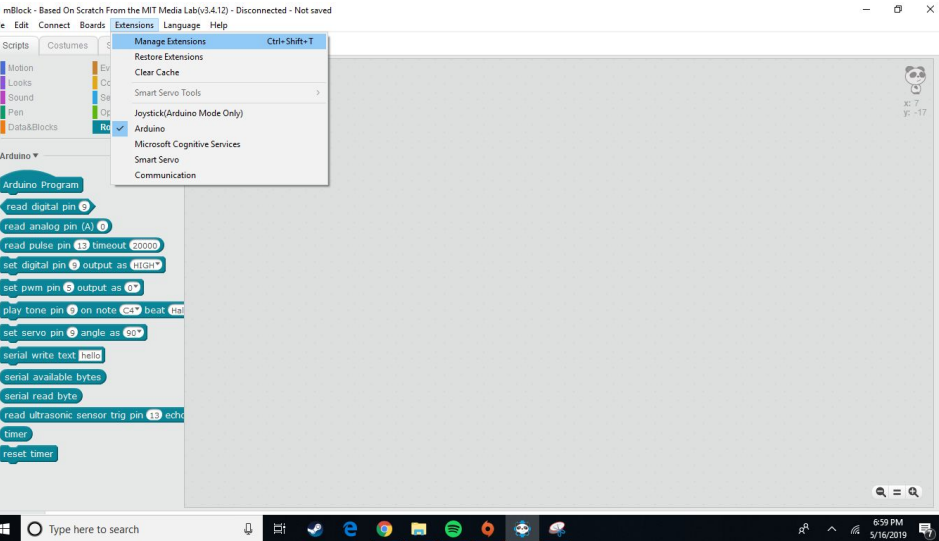


# Sensor - Arduino Board

Follow the demonstration carefully!



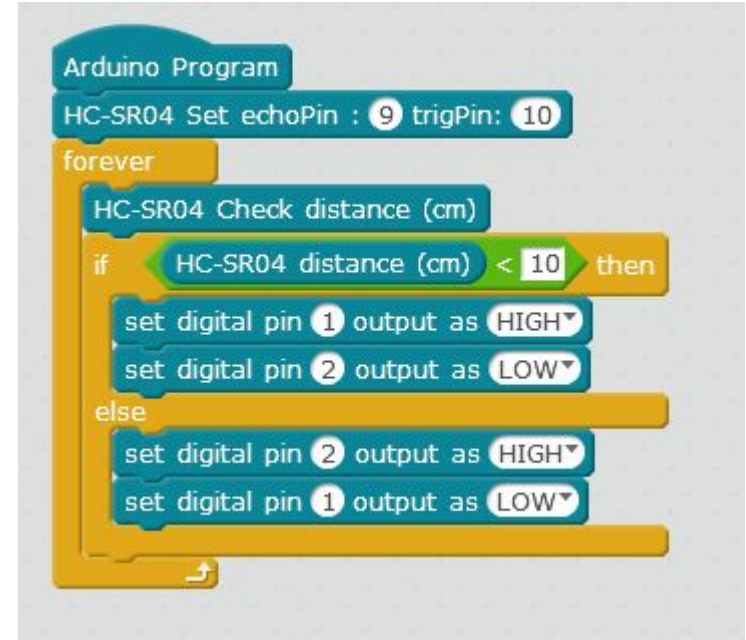
# Add HC-SR04 Extensions in mBot ?



# Sensor - Programming

HC-SR04 distance - set how far the sensor notices a change (in cm)

echoPin and trigPin are components of the sensor



# HC SR- 04



This is the HC-SR04 ultrasonic ranging sensor. This economical sensor provides 2cm to 400cm of non-contact measurement

- Stable performance, accurate measurement range
- Using IO trigger for at least 10us high level signal
- Automatically send 8 40KHz, and detect whether there is a signal to return

# Sensor Dynamics

Velocity of Speed = 343 meter / sec

If you know the time a sound travels , you can find the distance

Let's say, time  $t = 0.0006$  sec

Velocity = distance / time

Therefore the distance =  $343 \times 100 \times 0.0006 \text{ sec} = 20\text{cm}$