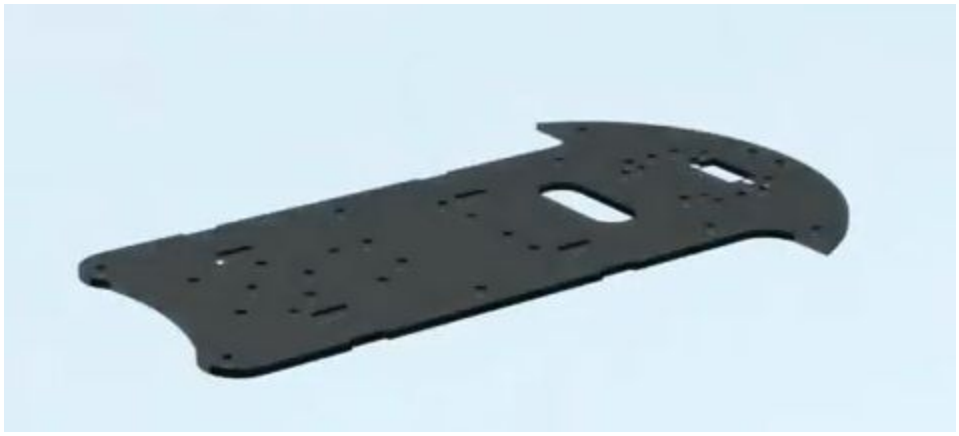
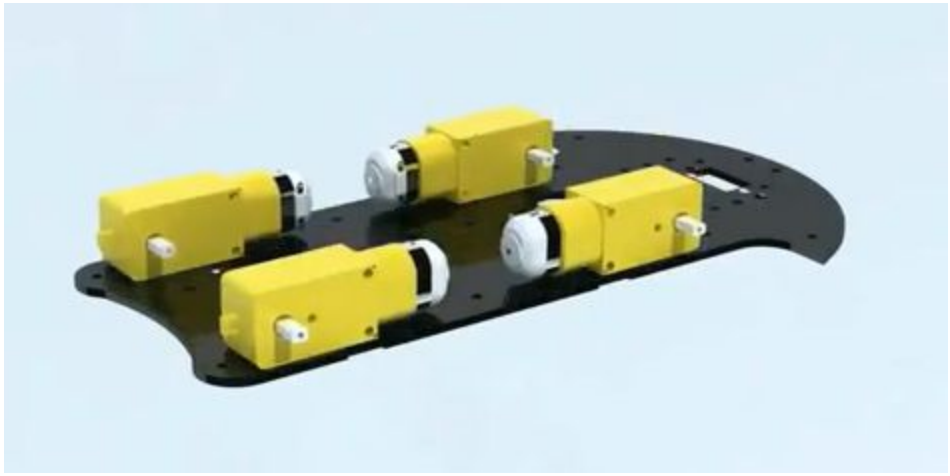
Step 1

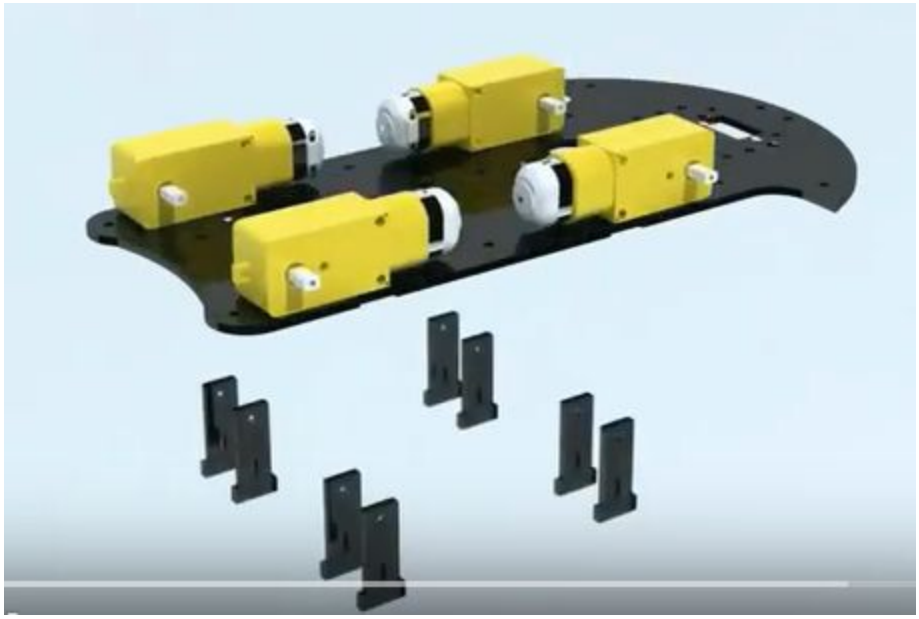
Chassis



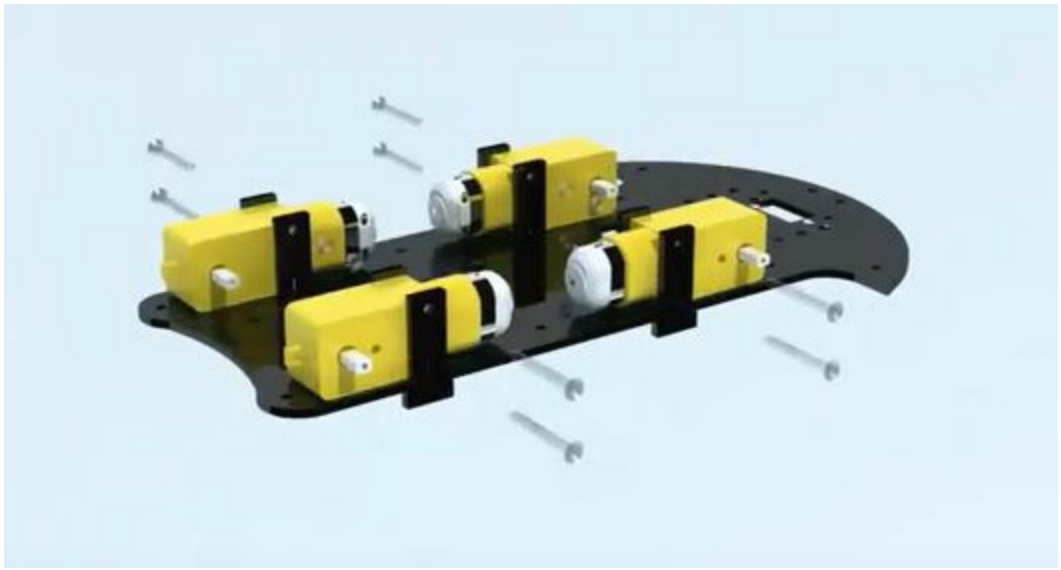
Step 2 : Place Geared Motors



Step 3 :

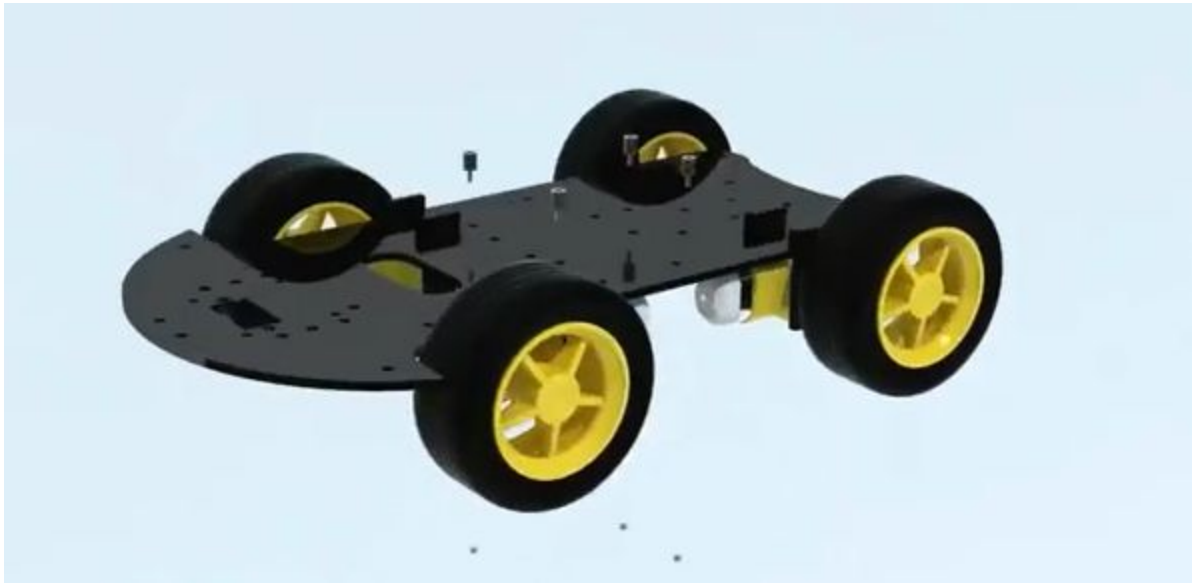


Step 4 : Screw the motors to the board



Step 5 : Add wheels

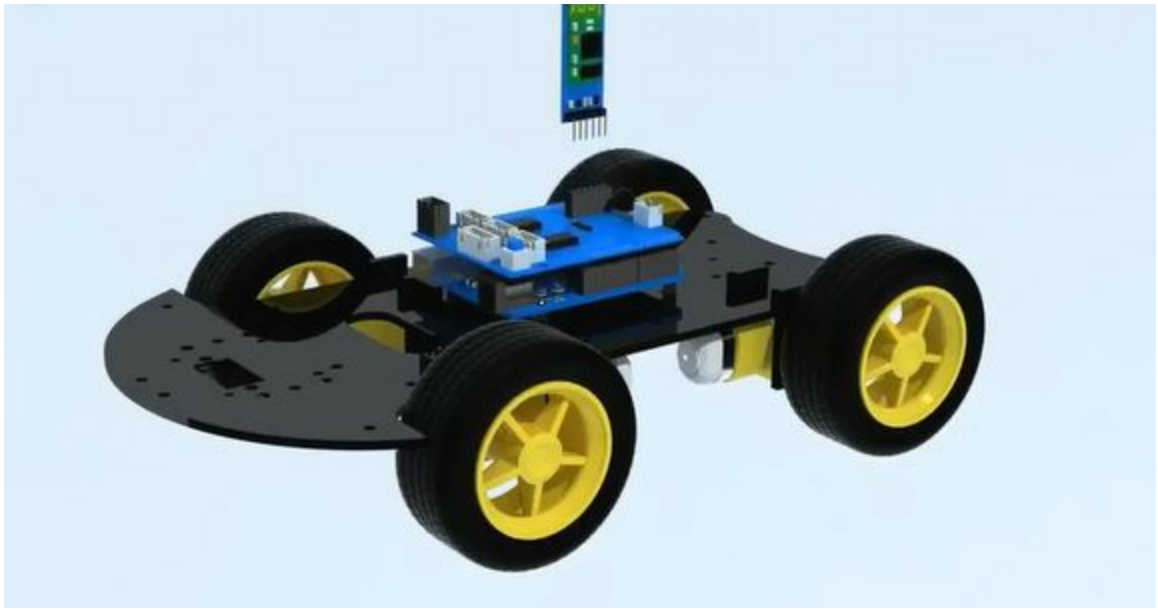
Step 6 : Turn upside down and add screws



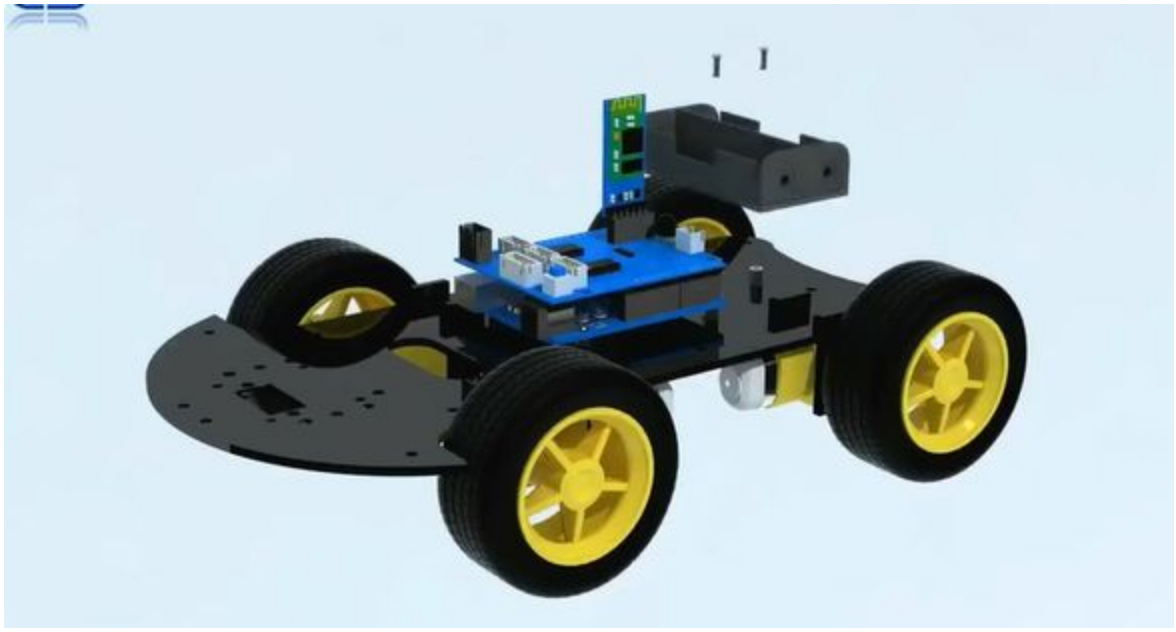
Step 7 : Place the Arduino board

Step 8 : Place the Arduino shield

Step 9 : Add the Bluetooth sensor



Step 10 : Screw the battery holder to chassis

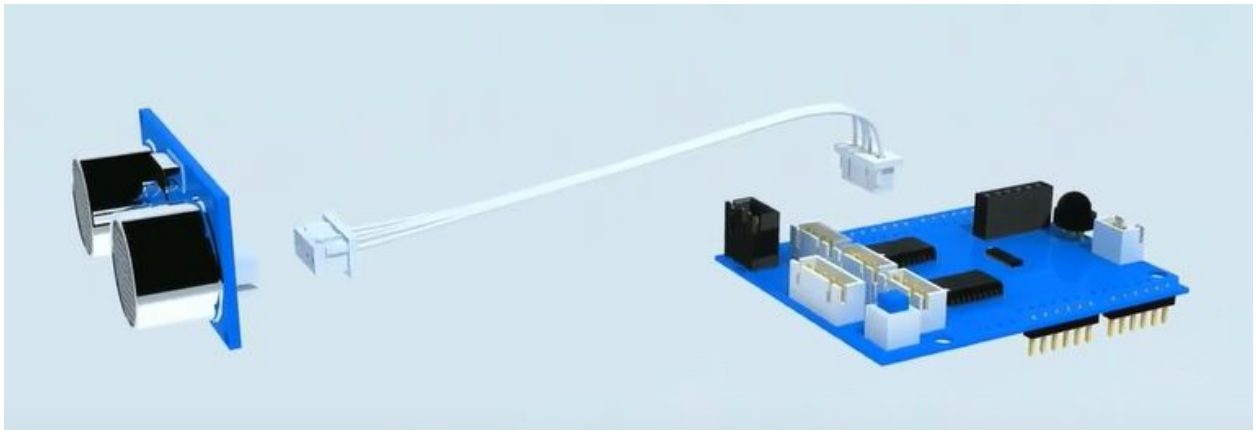


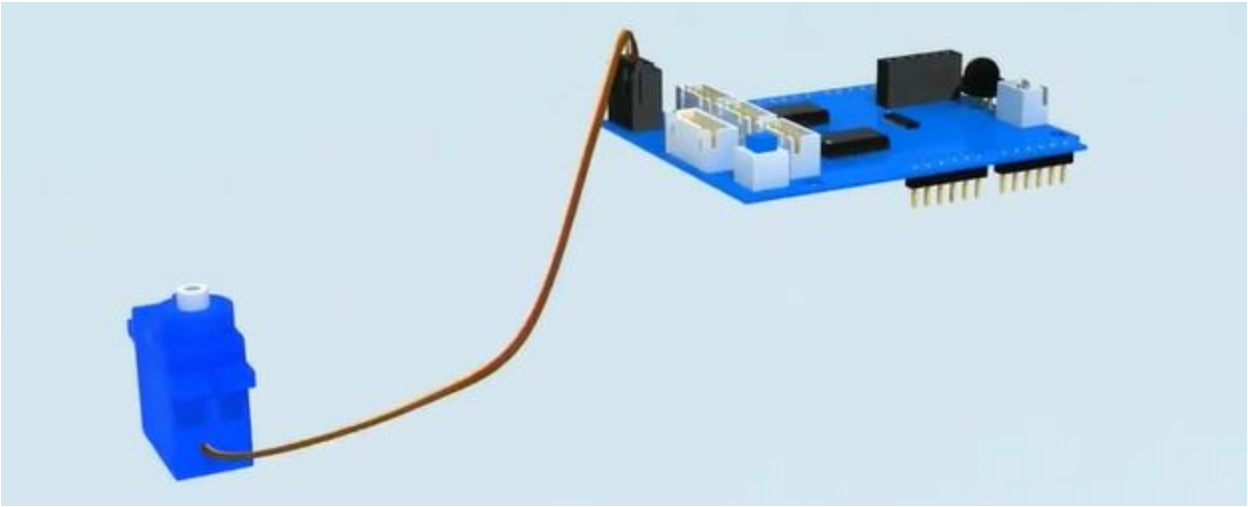
Step 11 – Place the servo motor

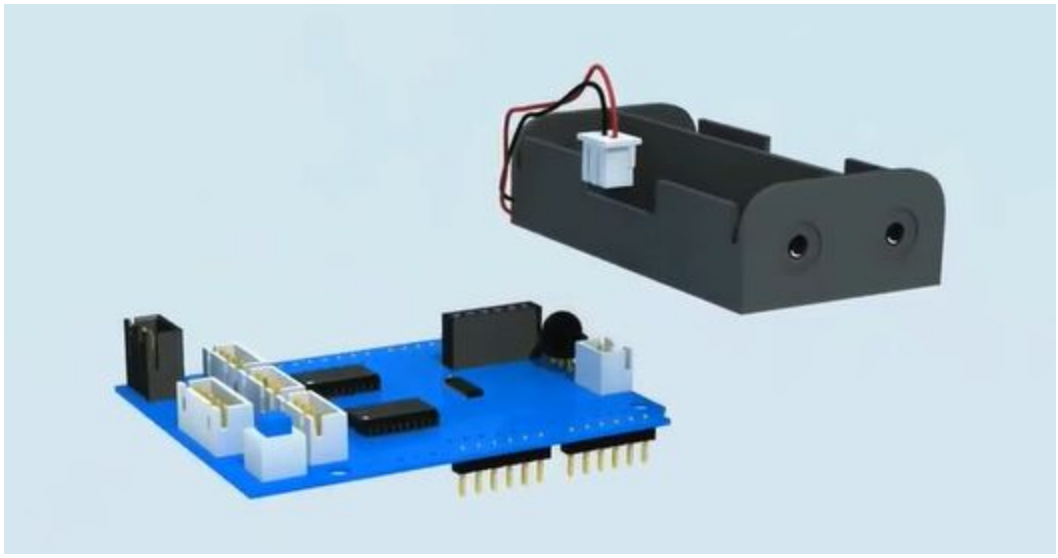
Step 12 : Place the podium

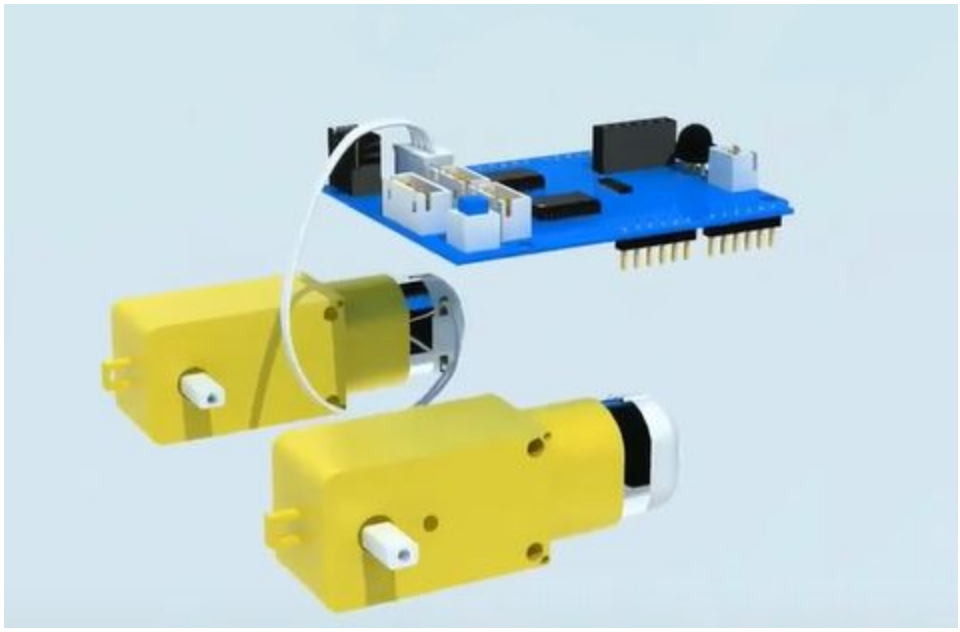
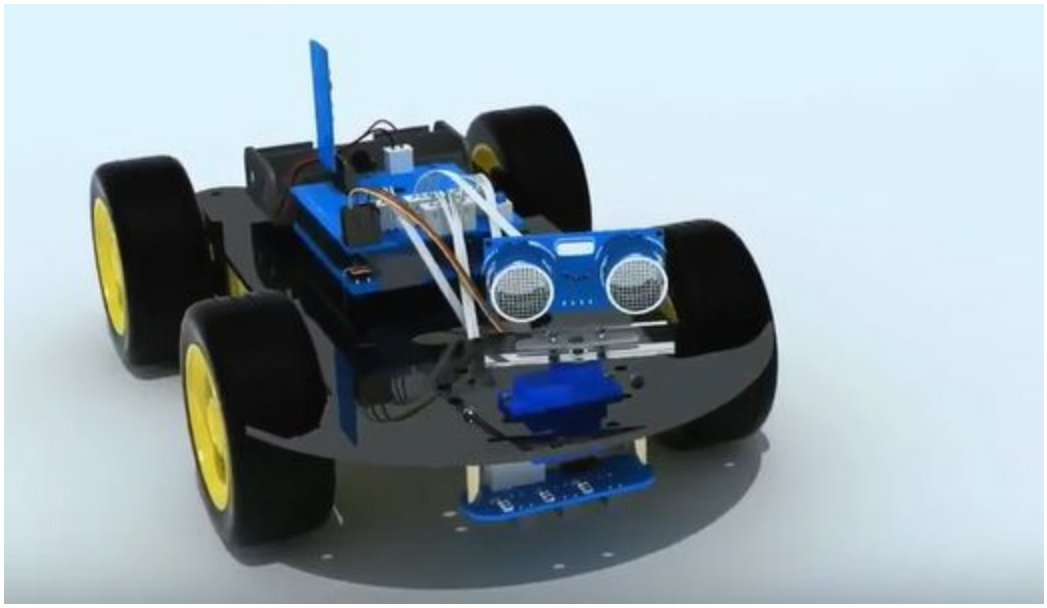
Step 13 : Place the ultrasound distance sensor

Circuit :









All Set :