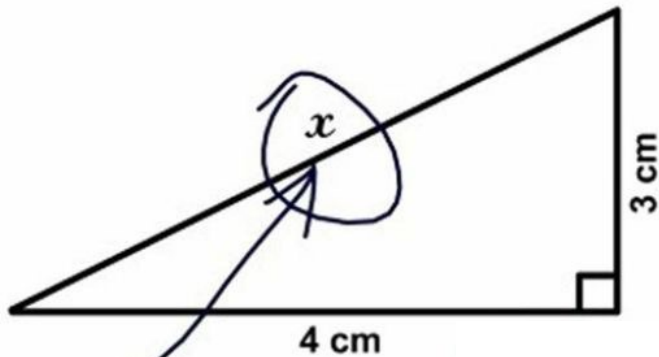


3. Find  $x$ .



*Here it is*

# AI as Search

CS B551  
Fall 2022

# Announcements

- Canvas, Q&A Community, Slack, etc.
- Activity posted on Canvas – due Monday!
- Assignment 0 coming soon!
  - Practice with searching, and with Python.
  - Lots of online resources to learn Python: Google Code, CodeAcademy, many, many tutorials, etc.

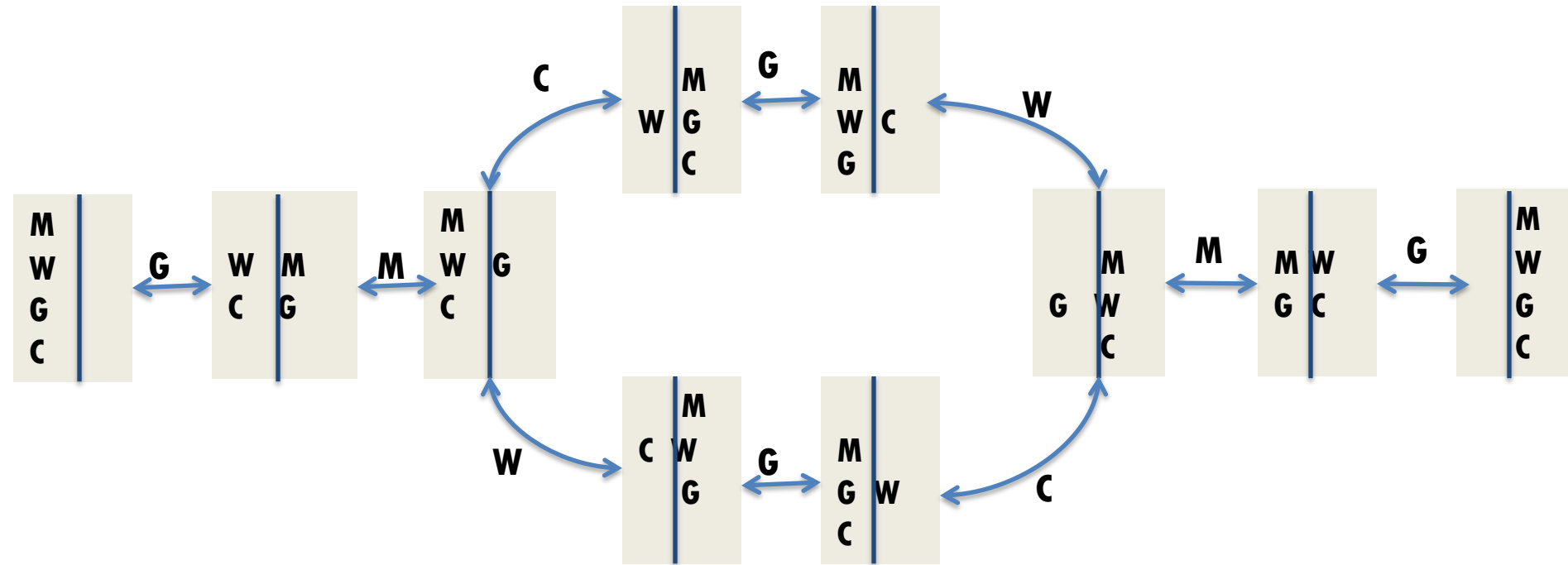
# An old puzzle...



Puzzles and games have long been considered a challenge for human intelligence:

- Chess in Persia and India ~4000 years ago
- Checkers in 3600-year-old Egyptian paintings
- Go in China over 3000 years ago

# A representation of the problem



M: Man goes alone  
W: Man takes wolf  
G: Man takes goat  
C: Man takes cabbage

State space  
represented as a  
graph

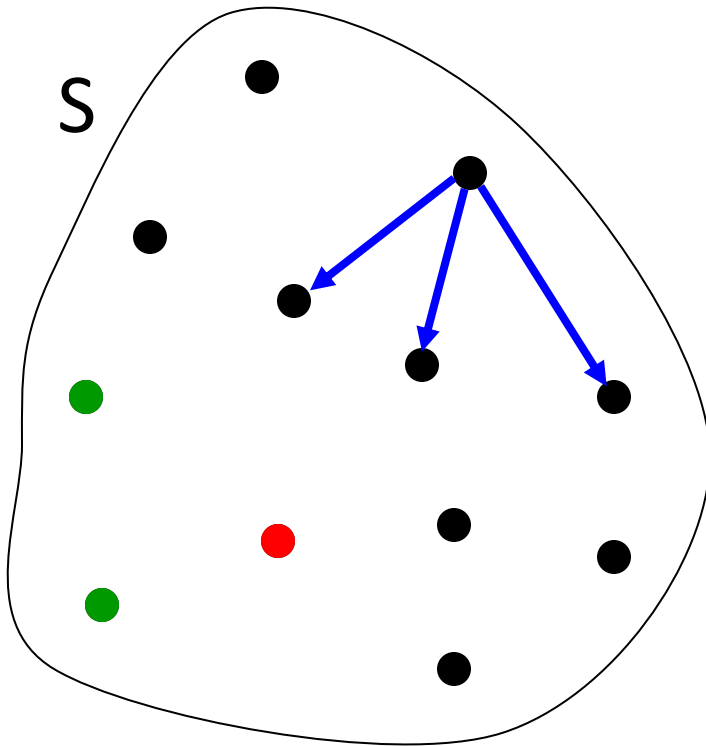
# Exploring Choices

- Problems that seem to require intelligence usually require exploring multiple choices.
- Search:
  - A systematic way of exploring choices.
  - The process of looking for a sequence of actions that reaches the goal.

# These abstractions have 5 parts:

1. Set of states  $S$
2. Initial state  $s_0$
3. A successor function  $SUCC: S \rightarrow 2^S$  that encodes possible transitions of the system. A successor is any state reachable from a given state by applying a single action.
4. Set of goal states
5. A cost function that calculates how “expensive” a successor is

# Defining a Search Problem

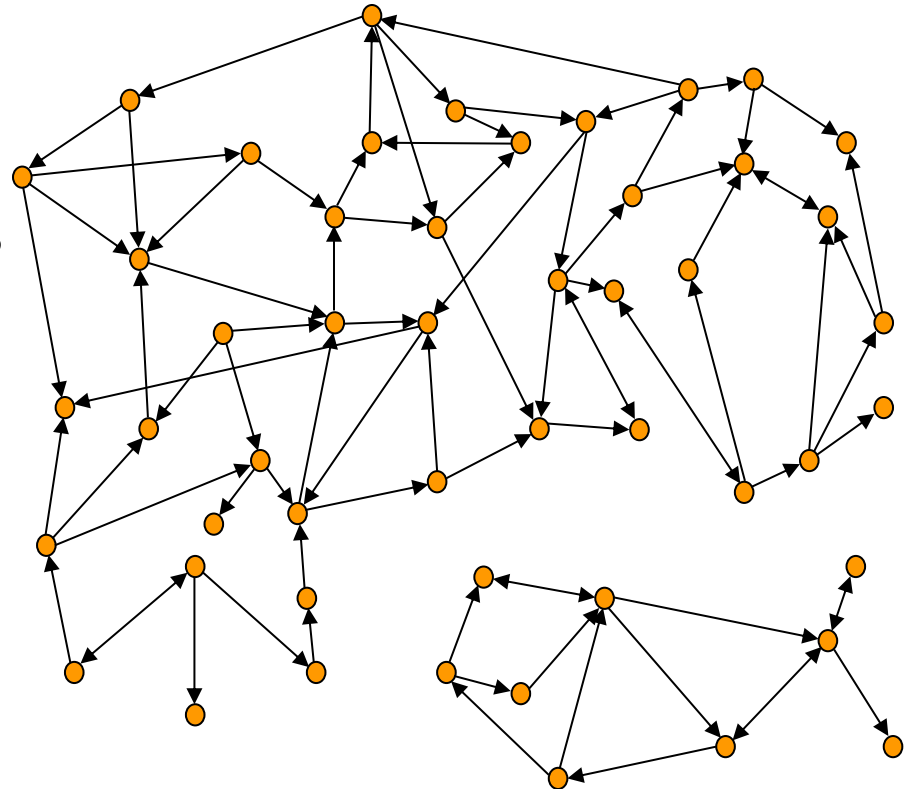


- State space  $S$
- Successor function:  
 $x \in S \rightarrow \text{succ}(x) \in 2^S$
- Initial state  $s_0$
- Goal test:  
 $x \in S \rightarrow \text{GOAL?}(x) = \text{T or F}$
- Cost



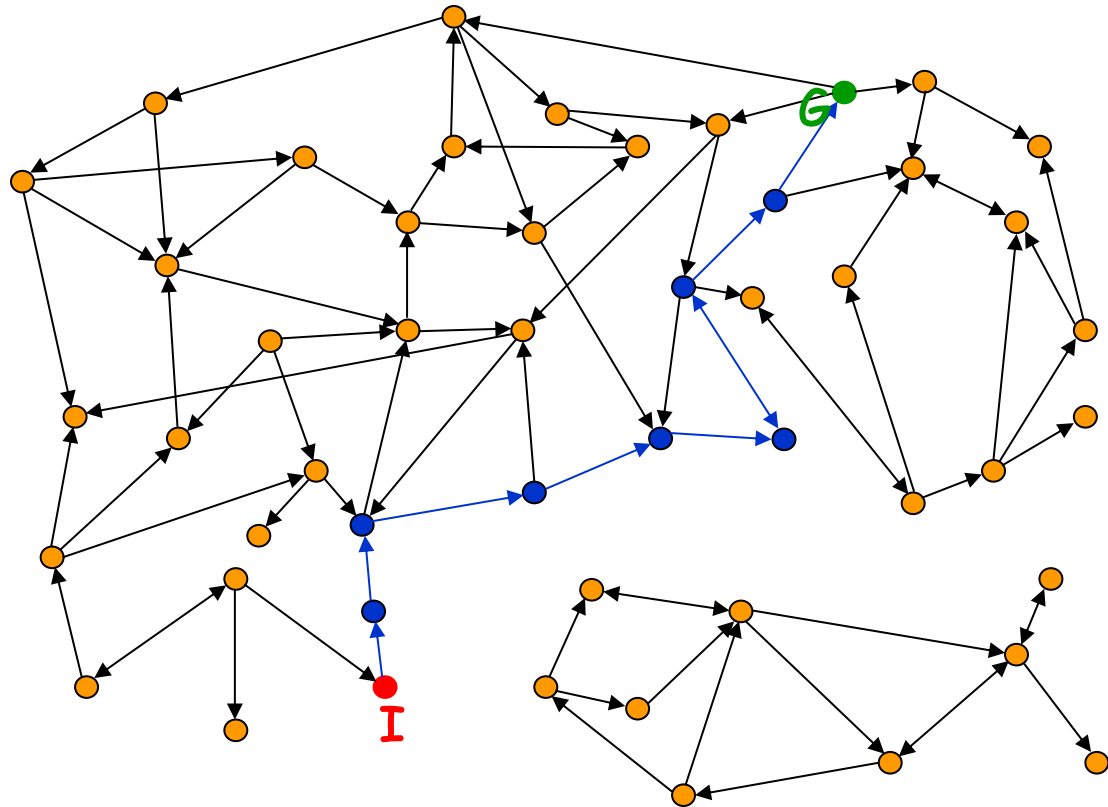
# State Graph

- Each state is represented by a distinct node
- An edge connects a node  $s$  to a node  $s'$  if  $s' \in \text{SUCC}(s)$
- The state graph may contain more than one connected component



# Solution to the Search Problem

- A **solution** is a path connecting the initial node to a goal node (any one)
- The **cost** of a path is the sum of the edge costs along this path
- An **optimal** solution is a solution path of minimum cost
- There might be no solution !



# Example: 8-Puzzle

8	2	
3	4	7
5	1	6

Initial state

1	2	3
4	5	6
7	8	

Goal state

# Example: 8-Puzzle

8	2	
3	4	7
5	1	6

Initial state

1	2	3
4	5	6
7	8	

Goal state

**State:** Any arrangement of 8 numbered tiles and an empty tile on a 3x3 board

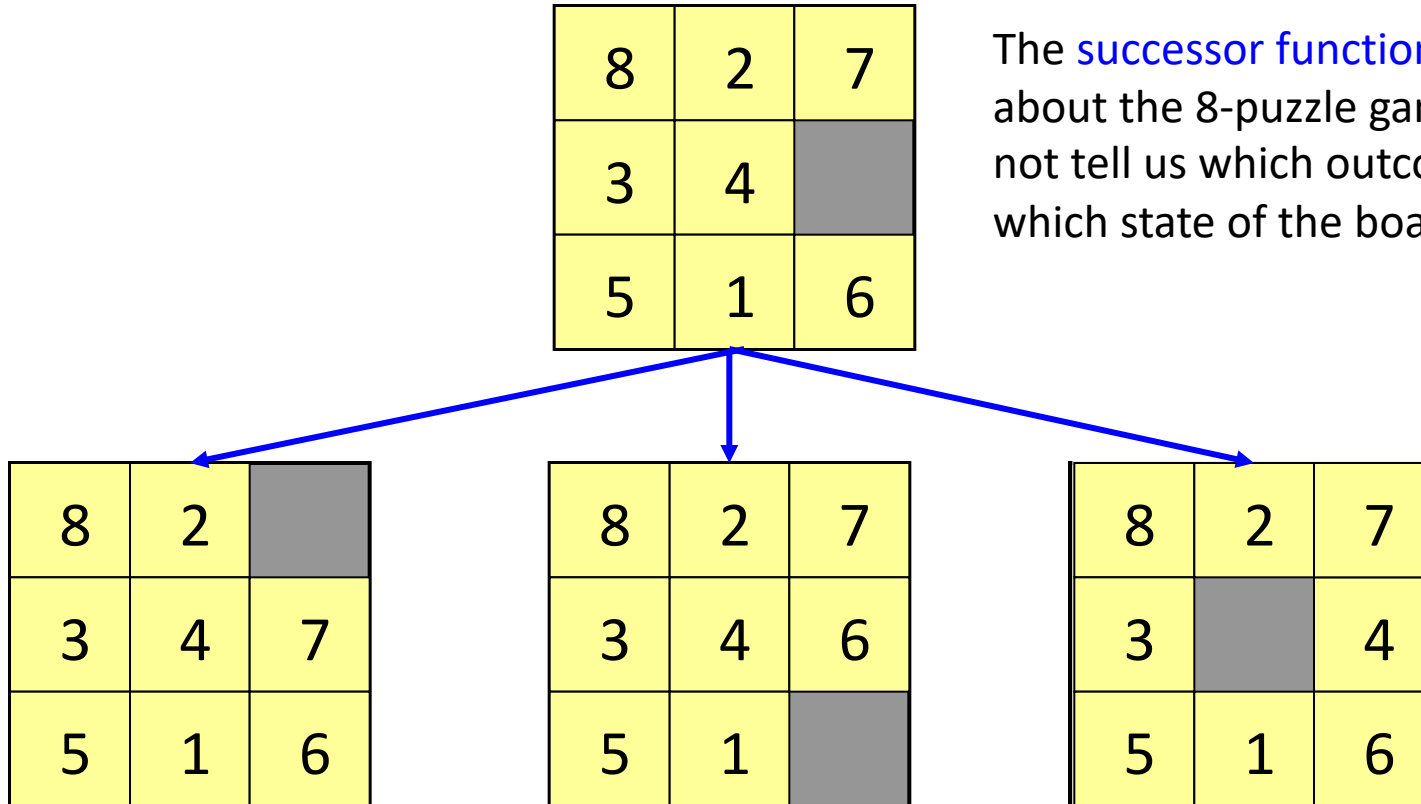
**Successor function:** given by available actions (sliding tiles) L, R, U, D.

**Cost:** How many moves were performed

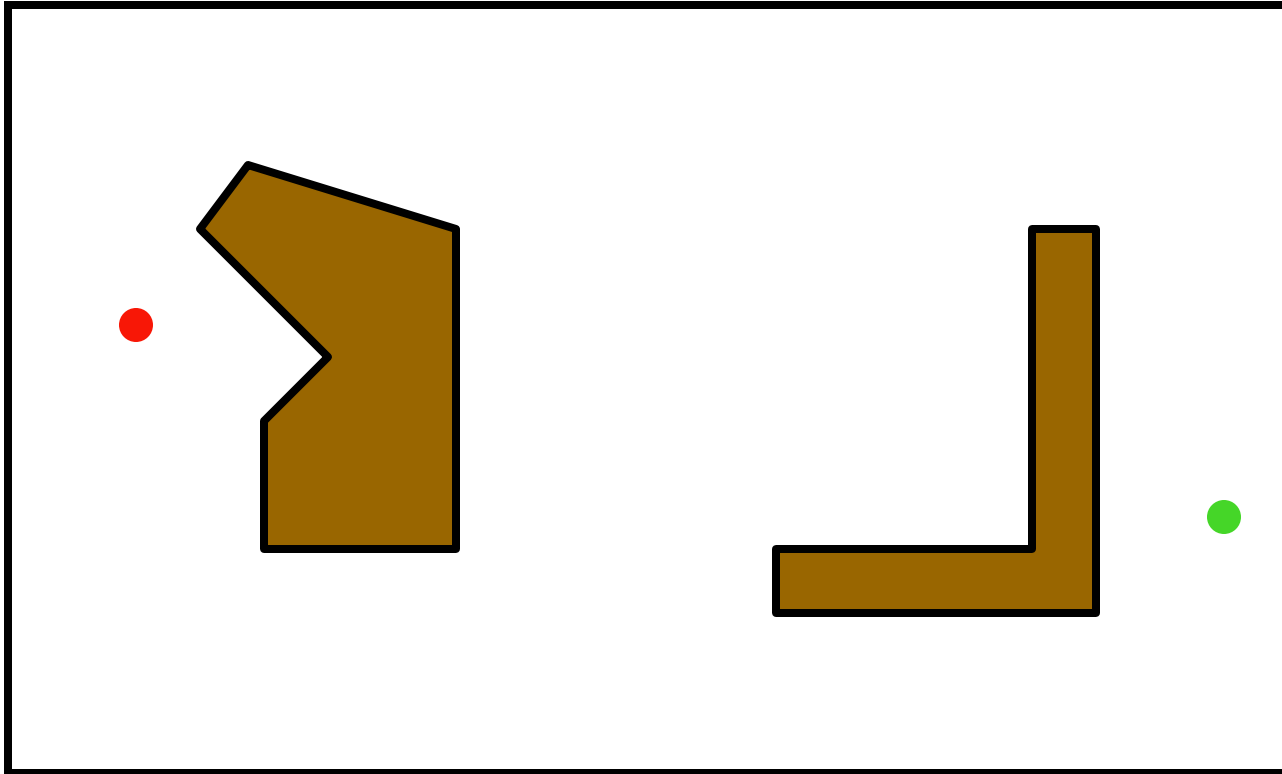
# Successor Function: 8-Puzzle

$\text{SUCC}(\text{state}) \rightarrow \text{subset of states}$

The **successor function** is knowledge about the 8-puzzle game, but it does not tell us which outcome to use, nor to which state of the board to apply it.

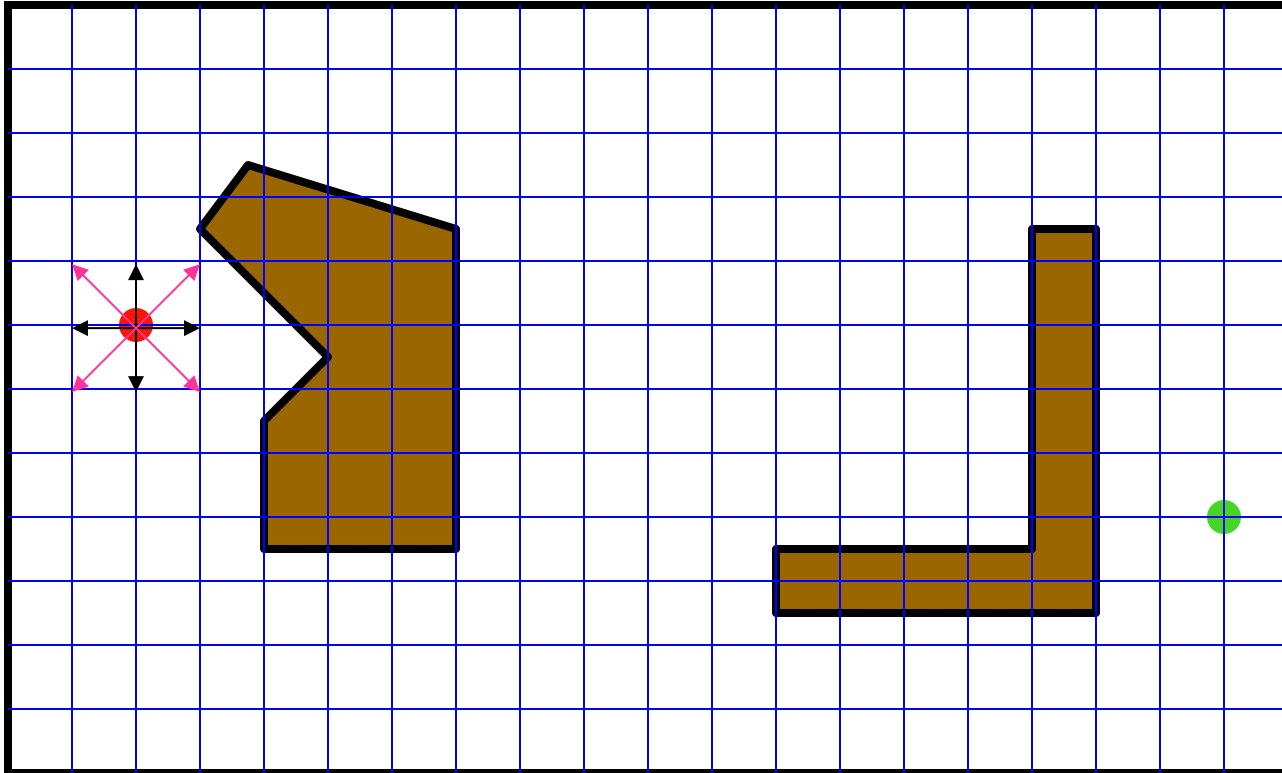


# Path Planning



What is the state space?

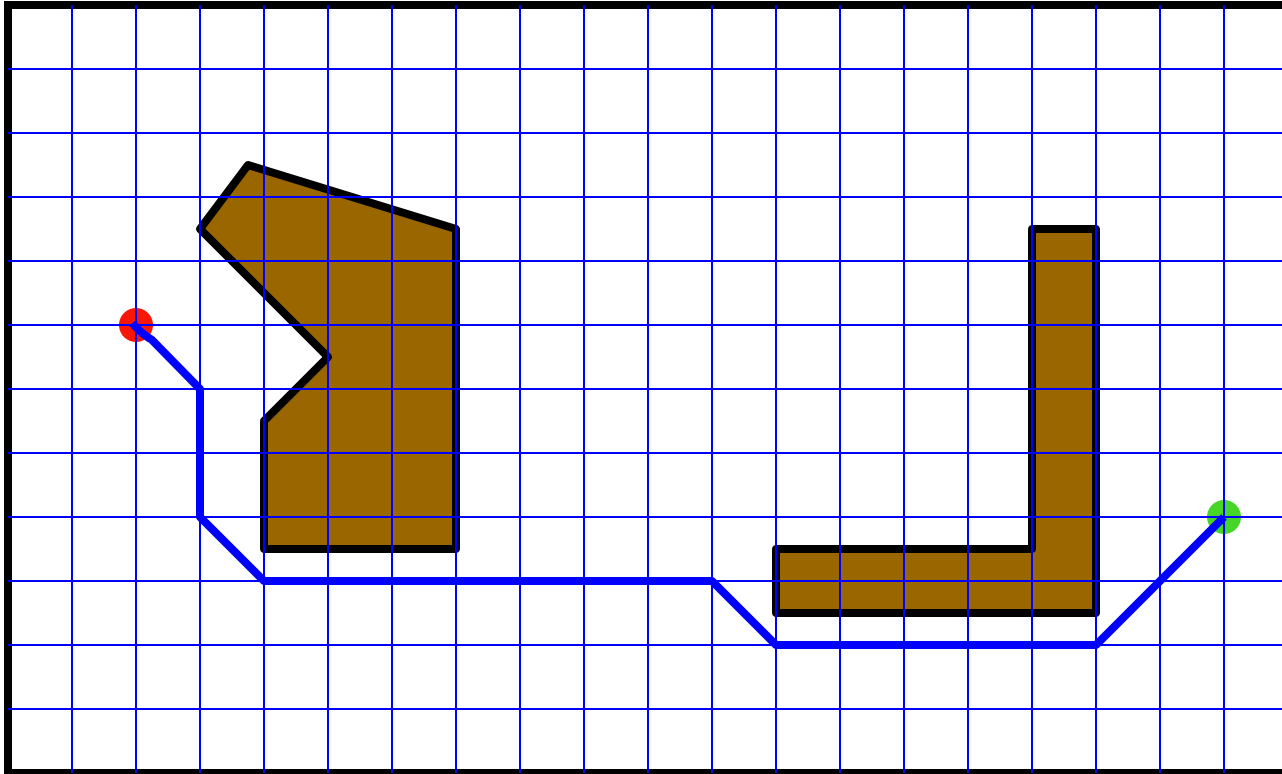
# Formulation #1



Cost of one horizontal/vertical step = 1

Cost of one diagonal step =  $\sqrt{2}$

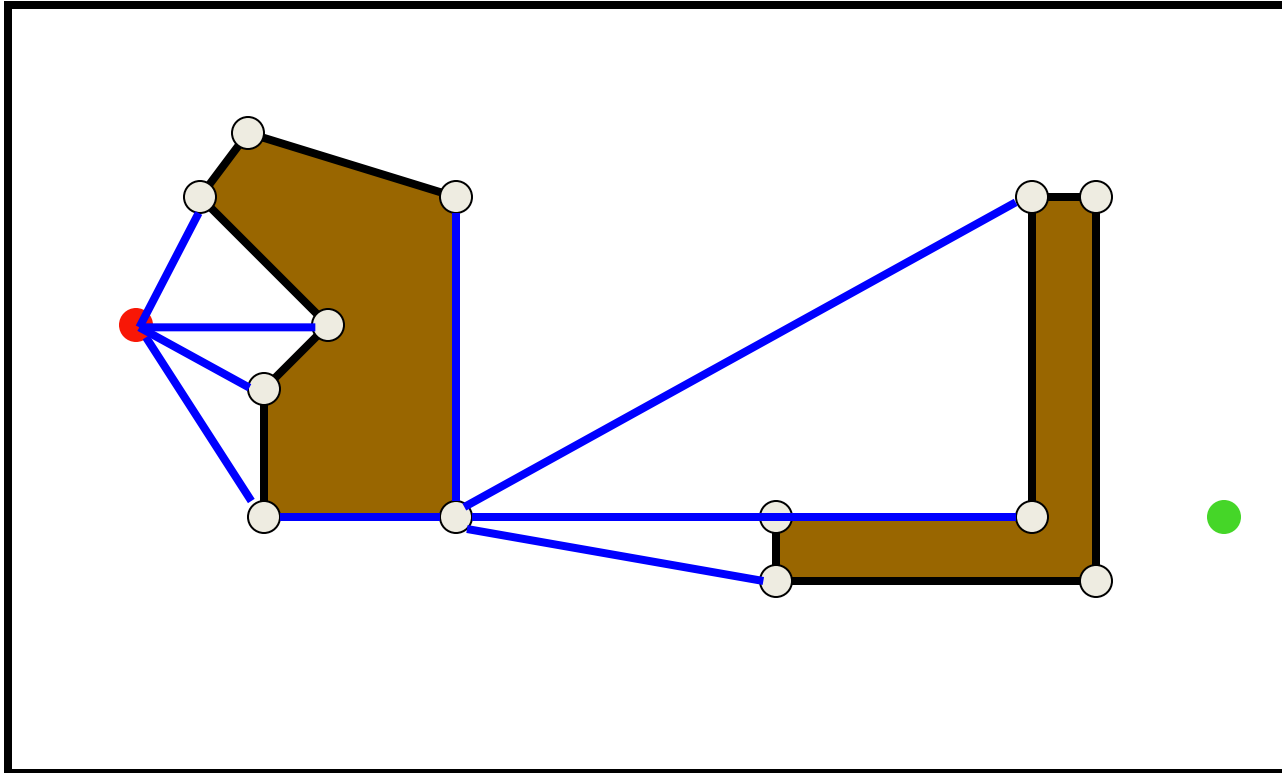
# Optimal Solution



This path is the shortest in the discretized state space, but not in the original continuous space

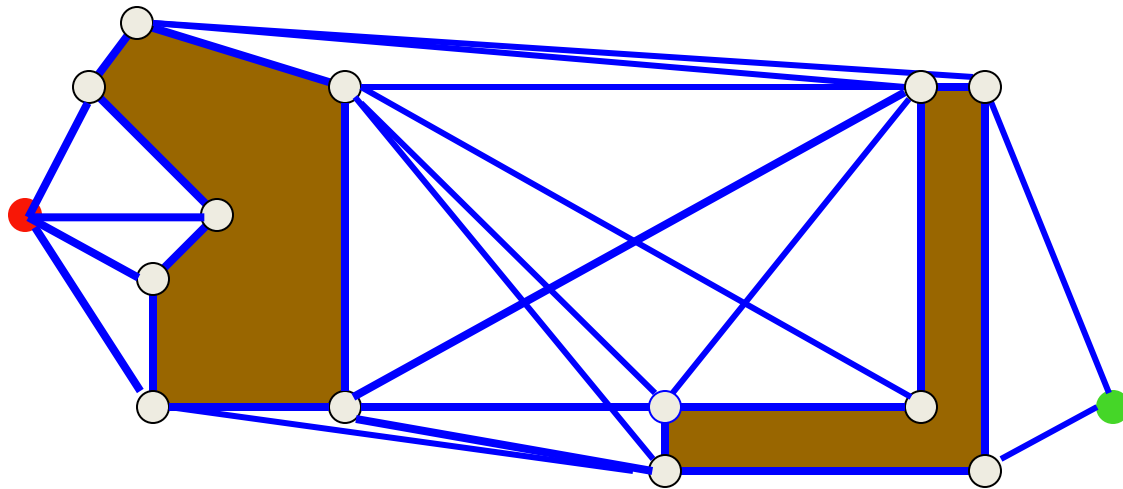


# Formulation #2



Cost of one step: length of segment

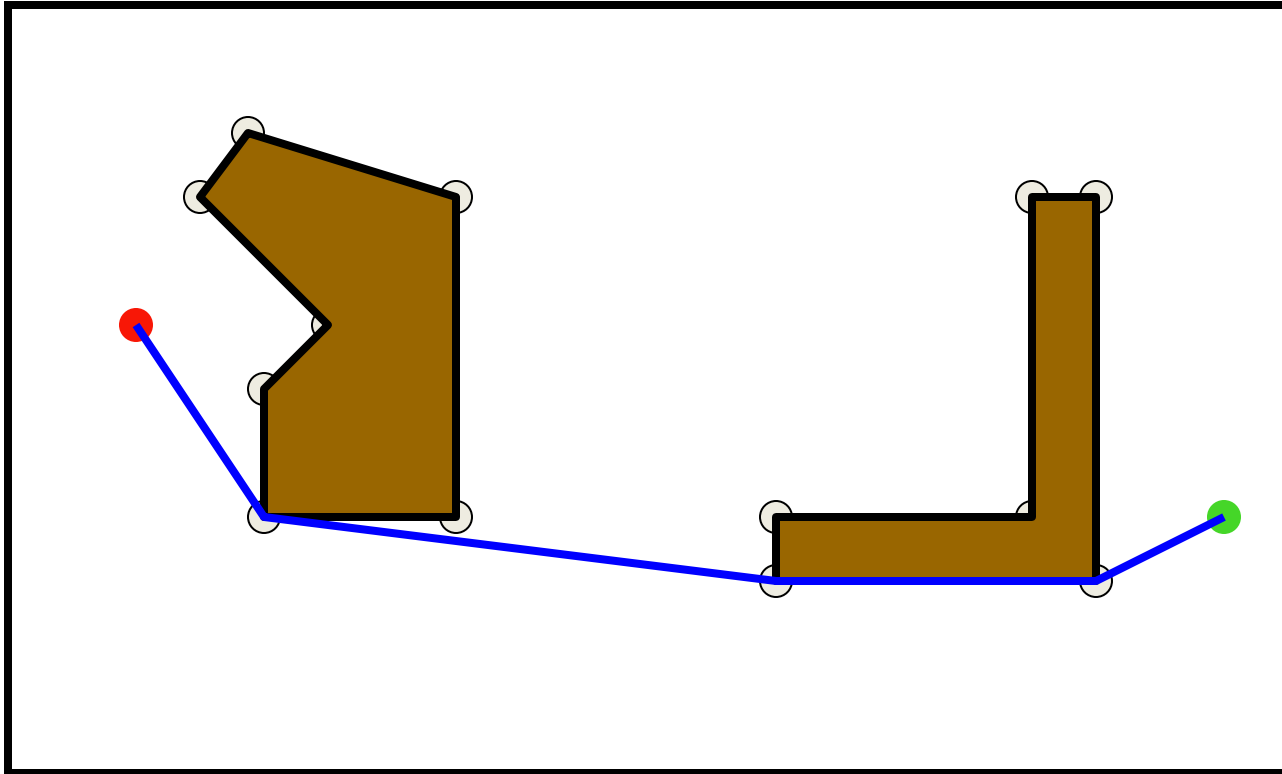
# Formulation #2



Visibility graph (any two points “see” each other iff the line segment between them is NOT in the exterior)

Cost of one step: length of segment

# Solution Path



The shortest path in this state space is also the shortest in the original continuous space

# What is a State?

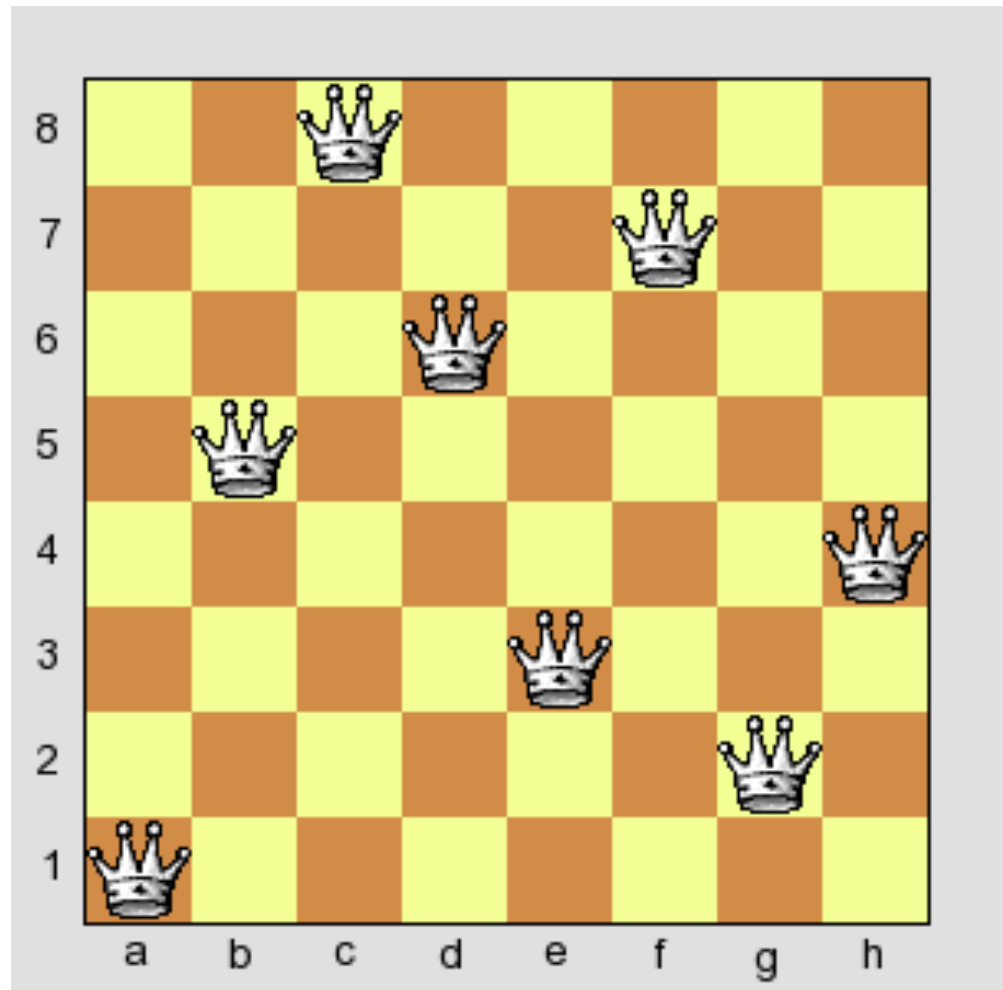
- **A state does:**
  - Represent all information meaningful to the problem at a given “instant in time” – past, present, or future
  - Exist in an *abstract, mathematical* sense
- **A state DOES NOT:**
  - Necessarily exist in the computer’s memory
  - Tell the computer how it arrived at the state
  - Tell the computer how to choose the next state
  - Need to be a unique representation

# What is a State Space?

- An abstract mathematical object
  - E.g., the set of all permutations of (1,...,8,empty)
- Membership should be **trivially testable**
  - So  $S = \{ s \mid s \text{ is reachable from the start state through transformations of the successor function} \}$  is *a bad definition* (not trivially testable).
- Edges should be **easily generated**
- *Again: the state space does NOT contain information about which edge to take (or not to take) in a given state*

# 8-Queens Problem

Place 8 queens in a chessboard so that no two queens are in the same row, column, or diagonal.

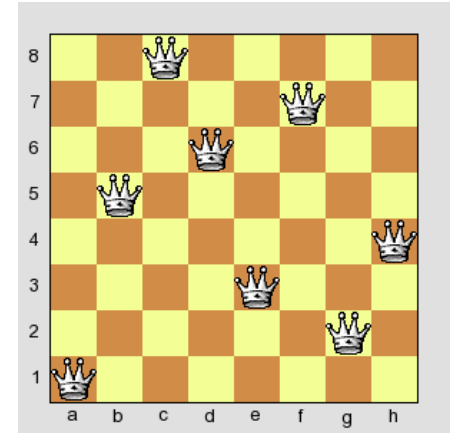


# 8-Queens Problem

Two main formulations of the problem:

## 1. An incremental formulation:

- **States:** Any arrangement of 0 to 8 queens on the board is a state.
- **Initial state:** No queens on the board.
- **Actions:** Add a queen to any empty square.
- **Goal test:** 8 queens are on the board, none attacked.



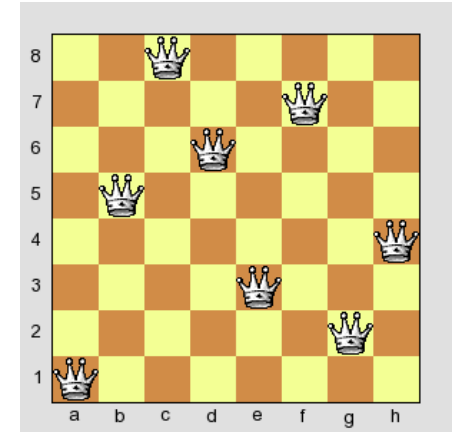
In this formulation, we have  $64 \cdot 63 \cdot \dots \cdot 57 \approx 1.8 \times 10^{14}$  possible sequences to investigate.

# 8-Queens Problem

Two main formulations of the problem:

2. Complete-state formulation: prohibit placing a queen in any square that is already attacked

- States: All possible arrangements of  $n$  queens ( $0 \leq n \leq 8$ ), one per column in the leftmost  $n$  columns, with no queen attacking another.
- Actions: Add a queen to any square in the leftmost empty column such that it is not attacked by any other queen.
- Goal test: 8 queens are on the board, none attacked.



This formulation reduces the 8-queens state space from  $1.8 \times 10^{14}$  to just 2,057, and solutions are easy to find.



**Next class: Search algorithms (ch 3.4 in the book)**