

Chapter 5 #: 1, 2, 3, 4, 6, 7, 10, 15

Problem 1

```
fprintf('Problem 1\n')
```

Problem 1

```
clear all  
A=[3, 0, -2; 0, 1, 2; 0, -2, 1]
```

```
A = 3x3  
    3     0    -2  
    0     1     2  
    0    -2     1
```

```
lambda=eig(A) %calculates eigenvalues of A
```

```
lambda = 3x1 complex  
    3.0000 + 0.0000i  
    1.0000 + 2.0000i  
    1.0000 - 2.0000i
```

```
[v,d]=eig(A) %calculates eigenvalues AND eigenvectors of A
```

```
v = 3x3 complex  
    1.0000 + 0.0000i    0.3162 + 0.3162i    0.3162 - 0.3162i  
    0.0000 + 0.0000i    0.0000 - 0.6325i    0.0000 + 0.6325i  
    0.0000 + 0.0000i    0.6325 + 0.0000i    0.6325 + 0.0000i  
d = 3x3 complex  
    3.0000 + 0.0000i    0.0000 + 0.0000i    0.0000 + 0.0000i  
    0.0000 + 0.0000i    1.0000 + 2.0000i    0.0000 + 0.0000i  
    0.0000 + 0.0000i    0.0000 + 0.0000i    1.0000 - 2.0000i
```

```
%eigenvectors given as columns of v  
%corresponding eigenvalues are on diagonal of d  
lambda=eig(sym(A)) %uses sym to find and display eigenvalues
```

```
lambda =
```

$$\begin{pmatrix} 3 \\ 1 - 2i \\ 1 + 2i \end{pmatrix}$$

```
[v,d]=eig(sym(A))
```

```
v =
```

$$\begin{pmatrix} 1 & \frac{1}{2} - \frac{1}{2}i & \frac{1}{2} + \frac{1}{2}i \\ 0 & i & -i \\ 0 & 1 & 1 \end{pmatrix}$$

```
d =
```

$$\begin{pmatrix} 3 & 0 & 0 \\ 0 & 1-2i & 0 \\ 0 & 0 & 1+2i \end{pmatrix}$$

```
d(1,1) %first eigenvalue of A
```

```
ans = 3
```

```
v(:,1) %corresponding first eigenvector of A
```

```
ans =
```

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

```
A*v(:,1)
```

```
ans =
```

$$\begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$$

```
d(1,1)*v(:,1) %verifies that A*v=lambda*v for first
```

```
ans =
```

$$\begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$$

```
% eigenvalue-eigenvector pair; the last two  
%answers should be identical
```

```
A*v(:,3)
```

```
ans =
```

$$\begin{pmatrix} -\frac{1}{2} + \frac{3}{2}i \\ 2-i \\ 1+2i \end{pmatrix}$$

```
d(3,3)*v(:,3) %verifies that A*v=lambda*v for third
```

```
ans =
```

$$\begin{pmatrix} -\frac{1}{2} + \frac{3}{2}i \\ 2-i \\ 1+2i \end{pmatrix}$$

Problem 2

```
fprintf('Problem 2\n')
```

Problem 2

```
clear all
```

```
A=[-2,-1,-2; -4,-5,2; -5,-1,1]
```

```
A = 3×3
    -2    -1    -2
    -4    -5     2
    -5    -1     1
```

```
[v,d]=eig(sym(A))
```

```
v =
( 1  -1/2  1 )
( -1  1/2  2 )
( 1  1  1 )
```

```
d =
( -3  0  0 )
( 0  3  0 )
( 0  0 -6 )
```

```
syms t c1 c2 c3
```

%Type the line below on a single line, not with a <return>.

```
soln=[exp(d(1,1)*t)*v(:,1),exp(d(2,2)*t)*v(:,2),exp(d(3,3)*t)*v(:,3)]
```

```
soln =
( e^{-3t}  -e^{3t}/2  e^{-6t} )
( -e^{-3t}  e^{3t}/2  2e^{-6t} )
( e^{-3t}  e^{3t}  e^{-6t} )
```

```
%general soln is soln*[c1; c2; c3]
```

```
soln0=subs(soln,t,0)
```

```
soln0 =
( 1  -1/2  1 )
( -1  1/2  2 )
( 1  1  1 )
```

```
x0=[2; -1; -3]
```

```
x0 = 3×1
     2
```

-1
-3

```
cvals=soln0\X0
```

cvals =

$$\begin{pmatrix} 0 \\ -\frac{10}{3} \\ \frac{1}{3} \end{pmatrix}$$

```
v1n=v(:,1)*cvals(1)
```

v1n =

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

```
v2n=v(:,2)*cvals(2)
```

v2n =

$$\begin{pmatrix} \frac{5}{3} \\ -\frac{5}{3} \\ -\frac{10}{3} \end{pmatrix}$$

```
v3n=v(:,3)*cvals(3)
```

v3n =

$$\begin{pmatrix} \frac{1}{3} \\ \frac{2}{3} \\ \frac{1}{3} \end{pmatrix}$$

```
Vmat=[v1n,v2n,v3n]
```

Vmat =

$$\begin{pmatrix} 0 & \frac{5}{3} & \frac{1}{3} \\ 0 & -\frac{5}{3} & \frac{2}{3} \\ 0 & -\frac{10}{3} & \frac{1}{3} \end{pmatrix}$$

```
xvec=[exp(d(1,1)*t); exp(d(2,2)*t); exp(d(3,3)*t)]
```

xvec =

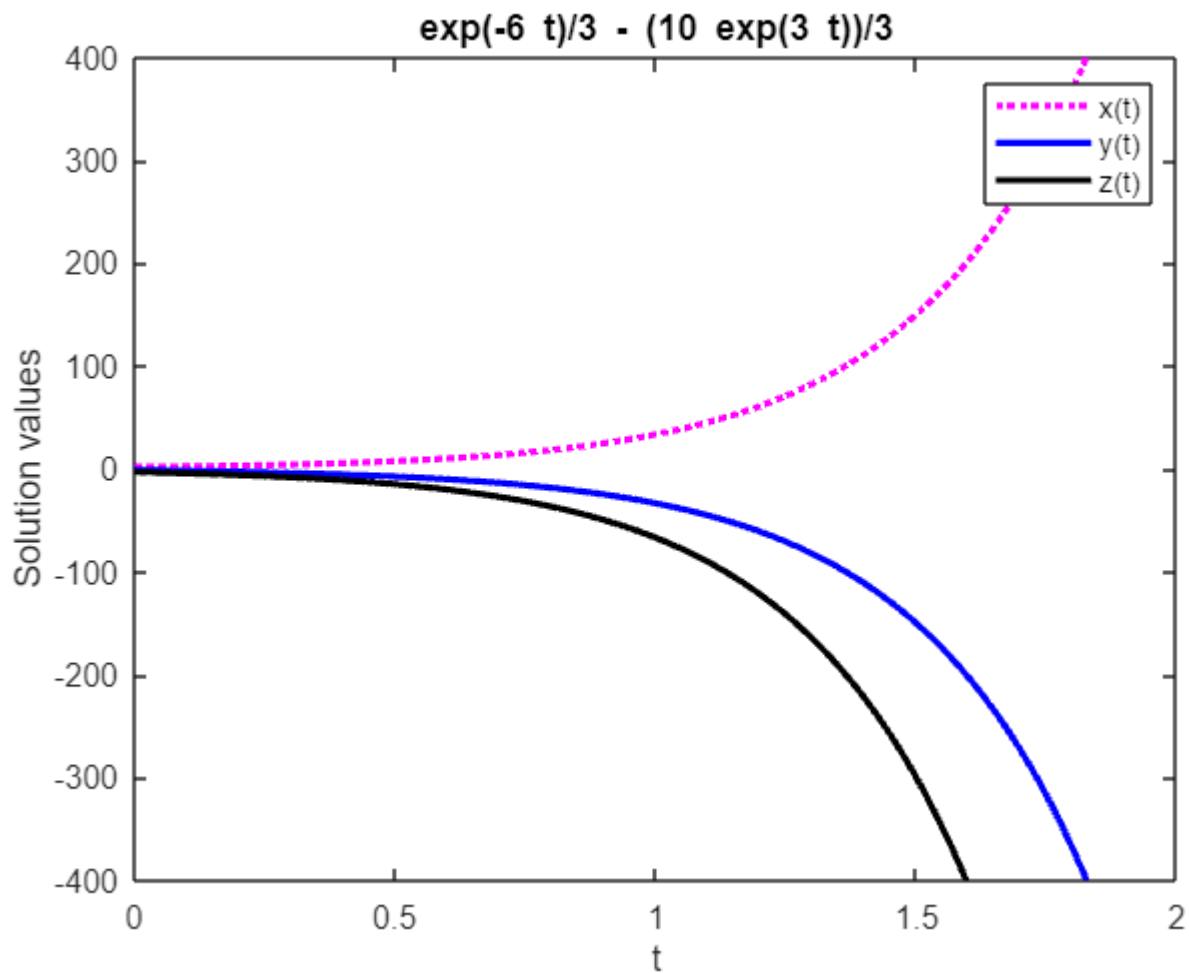
$$\begin{pmatrix} e^{-3t} \\ e^{3t} \\ e^{-6t} \end{pmatrix}$$

```
soln=Vmat*xvec %the solution to the IVP
```

soln =

$$\begin{pmatrix} \frac{5e^{3t}}{3} + \frac{e^{-6t}}{3} \\ \frac{2e^{-6t}}{3} - \frac{5e^{3t}}{3} \\ \frac{e^{-6t}}{3} - \frac{10e^{3t}}{3} \end{pmatrix}$$

```
h1=ezplot(soln(1),[0,2]);  
set(h1,'Color','m','LineStyle',':','LineWidth',2)  
hold on  
h2=ezplot(soln(2),[0,2]);  
set(h2,'Color','b','LineStyle','-','LineWidth',2)  
h3=ezplot(soln(3),[0,2]);  
set(h3,'Color','k','LineWidth',2)  
axis([0 2 -400 400])  
xlabel('t')  
ylabel('Solution values')  
legend('x(t)','y(t)','z(t)')  
hold off
```



Problem 3

```
fprintf('Problem 3\n')
```

Problem 3

```
clear all
syms t c1 c2
A=[-1,-2; 2,-1]
```

```
A = 2x2
    -1    -2
     2    -1
```

```
[v,d]=eig(sym(A))
```

```
v =
    (-i  i)
    ( 1  1)
d =
```

$$\begin{pmatrix} -1-2i & 0 \\ 0 & -1+2i \end{pmatrix}$$

```
real(v(:,1))
```

```
ans =
```

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

```
a_vec=real(v(:,1))
```

```
a_vec =
```

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

```
b_vec=imag(v(:,1))
```

```
b_vec =
```

$$\begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

```
alpha=real(d(1,1))%real part of 1st eigenvalue
```

```
alpha = -1
```

```
beta=imag(d(1,1))%imaginary part of 1st eigenvalue
```

```
beta = -2
```

```
solnx1=exp(alpha*t)*(a_vec*cos(beta*t)-b_vec*sin(beta*t))
```

```
solnx1 =
```

$$\begin{pmatrix} -\sin(2t) e^{-t} \\ \cos(2t) e^{-t} \end{pmatrix}$$

```
solnx2=exp(alpha*t)*(a_vec*sin(beta*t)+b_vec*cos(beta*t))
```

```
solnx2 =
```

$$\begin{pmatrix} -\cos(2t) e^{-t} \\ -\sin(2t) e^{-t} \end{pmatrix}$$

```
%solnx1 and solnx2 are from Eq.(5.75)
```

```
soln=c1*solnx1+c2*solnx2
```

```
soln =
```

$$\begin{pmatrix} -c_2 \cos(2t) e^{-t} - c_1 \sin(2t) e^{-t} \\ c_1 \cos(2t) e^{-t} - c_2 \sin(2t) e^{-t} \end{pmatrix}$$

Problem 4

```
fprintf('Problem 4\n')
```

Problem 4

```
clear all
syms c1 c2 c3 t
A=sym([-1,2,-4; 0,-1,0; 0,0,-1])
```

A =

$$\begin{pmatrix} -1 & 2 & -4 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

```
[V,E]=eig(A)
```

V =

$$\begin{pmatrix} 1 & 0 \\ 0 & 2 \\ 0 & 1 \end{pmatrix}$$

E =

$$\begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

%output for MATLAB 7.0.1 was V(:,1)=[1,0; 0,2; 0,1]
eqA1=A-E(1,1)*eye(3,3)

eqA1 =

$$\begin{pmatrix} 0 & 2 & -4 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```
equ_v1=eqA1\V(:,1) %soln to eqA1*equ v1=V(:,1)
```

Warning: Solution is not unique because the system is rank-deficient.

equ_v1 =

$$\begin{pmatrix} 0 \\ 1 \\ 2 \\ 0 \end{pmatrix}$$

```
equ_v2=eqA1\V(:,2) %soln to eqA1*equ v2=V(:,2)
```

Warning: Solution does not exist because the system is inconsistent.

equ_v2 =

$$\begin{pmatrix} \infty \\ \infty \\ \infty \end{pmatrix}$$

%only V(:,1) yields an answer and so we work with equ v1

soln=c1*exp(E(1,1)*t)*V(:,2)+c2*exp(E(1,1)*t)*V(:,1)+c3*(t*exp(E(1,1)*t)*V(:,1))+exp(E(1,1)*t)*

soln =

$$\begin{pmatrix} c_2 e^{-t} + c_3 t e^{-t} \\ \frac{e^{-t}}{2} + 2 c_1 e^{-t} \\ c_1 e^{-t} \end{pmatrix}$$

Problem 6

```
fprintf('Problem 6\n')
```

Problem 6

```
clear all
```

```
A=[3, 1, 0; 2, 4, 0; 3, -1, 1]
```

```
A = 3x3
     3     1     0
     2     4     0
     3    -1     1
```

```
lambda=eig(A) %calculates eigenvalues of A
```

```
lambda = 3x1
     1
     5
     2
```

```
[v,d]=eig(A) %calculates eigenvalues AND eigenvectors of A
```

```
v = 3x3
     0     0.4444     0.2357
     0     0.8889    -0.2357
     1.0000     0.1111     0.9428
d = 3x3
     1     0     0
     0     5     0
     0     0     2
```

```
%eigenvectors given as columns of v
```

```
%corresponding eigenvalues are on diagonal of d
```

```
lambda=eig(sym(A)) %uses sym to find and display eigenvalues
```

```
lambda =
```

$$\begin{pmatrix} 1 \\ 2 \\ 5 \end{pmatrix}$$

```
[v,d]=eig(sym(A))
```

```
v =
```

$$\begin{pmatrix} 4 & 0 & \frac{1}{4} \\ 8 & 0 & -\frac{1}{4} \\ 1 & 1 & 1 \end{pmatrix}$$

```
d =
```

$$\begin{pmatrix} 5 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

```
d(1,1) %first eigenvalue of A
```

```
ans = 5
```

```
v(:,1) %corresponding first eigenvector of A
```

```
ans =
```

$$\begin{pmatrix} 4 \\ 8 \\ 1 \end{pmatrix}$$

```
A*v(:,1)
```

```
ans =
```

$$\begin{pmatrix} 20 \\ 40 \\ 5 \end{pmatrix}$$

```
d(1,1)*v(:,1) %verifies that A*v=lambda*v for first
```

```
ans =
```

$$\begin{pmatrix} 20 \\ 40 \\ 5 \end{pmatrix}$$

```
% eigenvalue-eigenvector pair; the last two  
%answers should be identical
```

```
A*v(:,3)
```

```
ans =
```

$$\begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 2 \end{pmatrix}$$

```
d(3,3)*v(:,3) %verifies that A*v=lambda*v for third
```

```
ans =
```

$$\begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 2 \end{pmatrix}$$

Problem 7

```
fprintf('Problem 7A\n')
```

```
Problem 7A
```

```
clear all
A=[2, 1; 1, 2]
```

```
A = 2x2
     2     1
     1     2
```

```
lambda=eig(A) %calculates eigenvalues of A
```

```
lambda = 2x1
         1
         3
```

```
[v,d]=eig(A) %calculates eigenvalues AND eigenvectors of A
```

```
v = 2x2
    -0.7071    0.7071
     0.7071    0.7071
d = 2x2
     1     0
     0     3
```

```
%eigenvectors given as columns of v
%corresponding eigenvalues are on diagonal of d
lambda=eig(sym(A)) %uses sym to find and display eigenvalues
```

```
lambda =
```

$$\begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

```
[v,d]=eig(sym(A))
```

$$v = \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$d = \begin{pmatrix} 1 & 0 \\ 0 & 3 \end{pmatrix}$$

```
d(1,1) %first eigenvalue of A
```

```
ans = 1
```

```
v(:,1) %corresponding first eigenvector of A
```

$$ans = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

```
A*v(:,1)
```

$$ans = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

```
d(1,1)*v(:,1) %verifies that A*v=lambda*v for first
```

$$ans = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

```
% eigenvalue-eigenvector pair; the last two  
%answers should be identical
```

```
A*v(:,2)
```

$$ans = \begin{pmatrix} 3 \\ 3 \end{pmatrix}$$

```
d(2,2)*v(:,2) %verifies that A*v=lambda*v for third
```

$$ans = \begin{pmatrix} 3 \\ 3 \end{pmatrix}$$

```
fprintf('Problem 7B\n')
```

```
Problem 7B
```

```
B=[1, 3; 3, 1]
```

```
B = 2x2
    1    3
    3    1
```

```
lambda=eig(B) %calculates eigenvalues of B
```

```
lambda = 2x1
    -2
     4
```

```
[v,d]=eig(B) %calculates eigenvalues AND eigenvectors of B
```

```
v = 2x2
   -0.7071    0.7071
    0.7071    0.7071
d = 2x2
   -2     0
    0     4
```

```
%eigenvectors given as columns of v
%corresponding eigenvalues are on diagonal of d
lambda=eig(sym(B)) %uses sym to find and display eigenvalues
```

```
lambda =
    (-2)
     (4)
```

```
[v,d]=eig(sym(B))
```

```
v =
    (-1  1)
     (1  1)
d =
    (-2  0)
     (0  4)
```

```
d(1,1) %first eigenvalue of B
```

```
ans = -2
```

```
v(:,1) %corresponding first eigenvector of B
```

```
ans =
    (-1)
     (1)
```

```
B*v(:,1)
```

```
ans =
     (2)
    (-2)
```

```
d(1,1)*v(:,1) %verifies that B*v=lambda*v for first
```

ans =

$$\begin{pmatrix} 2 \\ -2 \end{pmatrix}$$

% eigenvalue-eigenvector pair; the last two

%answers should be identical

B*v(:,2)

ans =

$$\begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

d(2,2)*v(:,2) %verifies that B*v=lambda*v for third

ans =

$$\begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

Problem 10

fprintf('Problem 10\n')

Problem 10

clear all

syms c1 c2 t

A=sym([-4, -1; 6, 1])

A =

$$\begin{pmatrix} -4 & -1 \\ 6 & 1 \end{pmatrix}$$

[V,E]=eig(A)

V =

$$\begin{pmatrix} -\frac{1}{2} & -\frac{1}{3} \\ 1 & 1 \end{pmatrix}$$

E =

$$\begin{pmatrix} -2 & 0 \\ 0 & -1 \end{pmatrix}$$

%output for MATLAB 7.0.1 was V(:,1)=[1,0; 0,2; 0,1]

eqA1=A-E(1,1)*eye(2,2)

eqA1 =

$$\begin{pmatrix} -2 & -1 \\ 6 & 3 \end{pmatrix}$$

```
equ_v1=eqA1\V(:,1) %soln to eqA1*equ v1=V(:,1)
```

Warning: Solution does not exist because the system is inconsistent.

equ_v1 =

$$\begin{pmatrix} \infty \\ \infty \end{pmatrix}$$

```
equ_v2=eqA1\V(:,2) %soln to eqA1*equ v2=V(:,2)
```

Warning: Solution is not unique because the system is rank-deficient.

equ_v2 =

$$\begin{pmatrix} \frac{1}{6} \\ 0 \end{pmatrix}$$

%only V(:,2) yields an answer and so we work with equ v2

```
soln=c1*exp(E(1,1)*t)*V(:,2)+c2*exp(E(1,1)*t)*V(:,1)+exp(E(1,1)*t)*(equ_v2)
```

soln =

$$\begin{pmatrix} \frac{e^{-2t}}{6} - \frac{c_1 e^{-2t}}{3} - \frac{c_2 e^{-2t}}{2} \\ c_1 e^{-2t} + c_2 e^{-2t} \end{pmatrix}$$

Problem 15

```
fprintf('Problem 15\n')
```

Problem 15

```
clear all  
syms t c1 c2  
A=[-4,2; -10, 4]
```

A = 2×2
-4 2
-10 4

```
[v,d]=eig(sym(A))
```

v =

$$\begin{pmatrix} \frac{2}{5} + \frac{1}{5}i & \frac{2}{5} - \frac{1}{5}i \\ 1 & 1 \end{pmatrix}$$

d =

$$\begin{pmatrix} -2i & 0 \\ 0 & 2i \end{pmatrix}$$

```
real(v(:,1))
```

ans =

$$\begin{pmatrix} \frac{2}{5} \\ 1 \end{pmatrix}$$

```
a_vec=real(v(:,1))
```

```
a_vec =
```

$$\begin{pmatrix} \frac{2}{5} \\ 1 \end{pmatrix}$$

```
b_vec=imag(v(:,1))
```

```
b_vec =
```

$$\begin{pmatrix} \frac{1}{5} \\ 0 \end{pmatrix}$$

```
alpha=real(d(1,1))%real part of 1st eigenvalue
```

```
alpha = 0
```

```
beta=imag(d(1,1))%imaginary part of 1st eigenvalue
```

```
beta = -2
```

```
solnx1=exp(alpha*t)*(a_vec*cos(beta*t)-b_vec*sin(beta*t))
```

```
solnx1 =
```

$$\begin{pmatrix} \frac{2 \cos(2t)}{5} + \frac{\sin(2t)}{5} \\ \cos(2t) \end{pmatrix}$$

```
solnx2=exp(alpha*t)*(a_vec*sin(beta*t)+b_vec*cos(beta*t))
```

```
solnx2 =
```

$$\begin{pmatrix} \frac{\cos(2t)}{5} - \frac{2 \sin(2t)}{5} \\ -\sin(2t) \end{pmatrix}$$

```
%solnx1 and solnx2 are from Eq.(5.75)
```

```
soln=c1*solnx1+c2*solnx2
```

```
soln =
```

$$\begin{pmatrix} c_1 \left(\frac{2 \cos(2t)}{5} + \frac{\sin(2t)}{5} \right) + c_2 \left(\frac{\cos(2t)}{5} - \frac{2 \sin(2t)}{5} \right) \\ c_1 \cos(2t) - c_2 \sin(2t) \end{pmatrix}$$