ADITYA WAGH

https://adityamwagh.me

in adityamwagh 🔾 adityamwagh @ adityamwagh@outlook.com 📞 (929) 424 1931

Final year graduate student well-versed in 3D computer vision tasks including but not limited to multi-view geometry, SfM, SLAM, Bundle Adjustment etc with an in-depth understanding of LiDAR point-cloud processing.

EDUCATION

New York University

New York City, NY

MS in Electrical and Computer Engineering; GPA: 3.72/4

Sep 2021 – May 2023

Coursework: Robot Perception, Robot Localisation, Deep Learning, High Performance ML, Foundations of Robotics, Probabilility & Stochastic Processes, Digital Signal Processing

Birla Institute of Technology and Science (BITS), Pilani

Pilani, India

B.Eng in Electronics Engineering

Aug 2015 - May 2019

EXPERIENCE

AI4CE Lab at New York University

New York City, NY

Graduate Research Asistant

Sep 2022 – Present

- o Developing new techniques to improve pair-wise LiDAR point cloud registration with low overlap; Currently experimenting with outlier rejection techniques to find the low overlapping region.
- o Teaching Assistant for ROB-GY 6203 Robot Perception a graduate level course about 3D Computer Vision.

Central Electronics Engineering Research Institute

Pilani, India

Deep Learning Intern

Jul 2018 – Dec 2018

- o Contributed to the development of a software pipeline for pixel wise annotation of a novel data set consisting of 6000+ Infrared and RGB aerial images of power cables
- o Fine-tuned a Mask-RCNN model for instance segmentation of power cables on this new dataset and achieved a test accuracy of approximately 70%

PROJECTS

• Fast 3D Object Detection in the Wild

MATLAB ⋅ Ω

- o Computed SIFT features for each image in database and queries using OpenCV's built-in SIFT feature extractor
- o Employed the k-means clustering algorithm to compute 800 cluster centroids to be used as visual words to generate a histogram of visual words in each image
- o Computed histograms of visual words for all the query images and database images and extracted similar images from the database by using the k-nearest neighbours algorithm on the generated histograms

Post-Earthquake Damage Assessment using Fully Convolutional Networks

Tensorflow, Keras · •

- Designed fully convolutional network for multiple semantic segmentation of building components and their damage state using a shared backbone
- o Implemented batch normalization layers to enable faster convergence and better generalization over real data since the data used for the project was synthetically generated using physics based graphical models
- o Achieved a mAP of 83% over 5 component classes and mAP of 70% for 5 damage state classes

Visual Place Recognition using Bag of Visual Words

OpenCV, Sklearn · 🖸

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• Deep Image Matching using Local Feature Trasformers

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- o Computed histograms of visual words for all the query images and database images and extracted similar images from the database by using the k-nearest neighbours algorithm on the generated histograms

State Estimation of a Quadrotor using On-board Camera and IMU

MATLAB · 🕥

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TECHNICAL SKILLS

- Languages: Python, C++, CUDA, Bash, MATLAB
- Tools & Platforms: VSCode, Vim, Git, GitHub, SLURM
- Frameworks: PyTorch, Keras, TensorFlow, OpenCV, Open3D Operating Systems: Linux, MacOS, Windows