

# Aditya Narayanan

979-402-1128 | [adityan@utexas.edu](mailto:adityan@utexas.edu) | [github.com/adityanarayanan03](https://github.com/adityanarayanan03) | [linkedin.com/in/aditya-n-03](https://linkedin.com/in/aditya-n-03)

## EDUCATION

### The University of Texas at Austin - Junior, Electrical and Computer Engineering Honors

- GPA: 4.0/4.0
- Current Coursework: Algorithms, Real Analysis, Circuit Theory, Engineering Communications
- Relevant Completed Coursework: Computer Vision, Software Design, Embedded Systems, Matrices and Matrix Calculations

### College Station High School

Class of 2021

- Took courses at Texas A&M University while in high school, including Signals and Systems, Random Signals and Systems, Differential Equations, Materials Science, and Multivariable/Vector Calculus
- Texas A&M GPA: 4.0/4.0

## SKILLS

**Languages:** Proficient in Python, Experience with MATLAB, C, C++

**Packages/Frameworks:** Numpy, Pytorch, PyZMQ, Python-multiprocessing

**Tools:** Robot Operating System (ROS), Git, Linux, Docker, Fusion 360

**Microcontrollers/Microprocessors:** Arduino, Raspberry Pi, Nvidia Jetson Nano

## EXPERIENCE

### Swarm Robotics Lab

UT Austin, June 2021-Present

- *Summer 2022:* Programmed and ran hardware experiments on a cluster of NVIDIA Jetson Nano embedded GPUs implementing a novel system for distributed robotic data collection from autonomous vehicles. Wrote code in Python, using ZMQ (Zero MQ) for custom data sharing, and Pytorch for ML model training and real-time inference on Jetson Nano GPUs. Used results from hardware experiments to extract benchmarks of on-edge model inference and communication costs, which were included in revisions of a submission to CoRL 2022 (Conference on Robot Learning).
- *June 2021 - May 2022:* researched computer vision on edge-computing devices using Python on Nvidia Jetson Nano hardware.

### Learning and Emerging Networked Systems Lab

Texas A&M University, 2021

- Implemented various Simultaneous Localization and Mapping (SLAM) techniques on the AWS DeepRacer as part of research into autonomous navigation and path-planning using deep reinforcement learning. Wrote custom ROS packages to integrate sensors with DeepRacer hardware.

### STEM to SHTM Internship

Stanford University, 2020

- Implemented neural networks on low power edge-computing devices. Built an audio classification model with Tensorflow/Keras, explored the effects of model quantization using Tensorflow Lite, and ran real-time inference on an Arduino Nano 33 BLE Sense.

### Intelligent Systems Lab

Texas A&M University, 2019

- Implemented a sensor fusion algorithm using the Kalman Filter for attitude estimation on low-cost IMU sensors. Built real-time attitude estimation system on Raspberry Pi with Python and MPU9250 sensor along with test platform for evaluation.

## CONFERENCES/PUBLICATIONS

### 2020 Materials Research Society Fall Symposium

- Zhang, Z., Zhang, D., Narayanan, A., Ramabadran, A., Simon, M., Rafailovich, M., Deng, Y., Zhang, P., "AI-Guided Coarse-Graining for More Efficient Modeling of SARS-CoV-2 Spike Glycoprotein", 2020 MRS Spring/Fall Meeting & Exhibit, November 28 - December 4, 2020. (abstract #3480255)

### 2021 American Chemical Society Spring Meeting

- Presented research on coarse-grained modeling for efficient simulation of SARS-CoV-2 Spike Glycoprotein.

## PROJECTS

### Pool Testing Backlight

2020

- Developed a tool to help lab technicians with COVID Pool Testing: [github.com/adityanarayanan03/pool-testing-backlight](https://github.com/adityanarayanan03/pool-testing-backlight)

### V5 Serial Plotter

2020

- Developed serial plotter application for use with the VEX V5 System. [github.com/adityanarayanan03/V5SerialPlotter](https://github.com/adityanarayanan03/V5SerialPlotter)

## AWARDS

### USA Physics Olympiad

2020

- Among 400 students selected nationwide to take the USA Physics Olympiad Exam based on score on F=ma exam

### American Invitational Mathematics Exam

2020

- Among 500 students selected nationwide to take the American Invitational Mathematics Exam (AIME). Scored 7/15, with national median being 6/15.

### VEX Robotics Competition

2019-2020

- Advanced to Texas State and CREATE US Open (National) tournaments based on numerous regional awards.