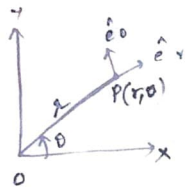


Central forces :

$$\vec{F} = F \hat{e}_r \quad n=2 \text{ Inverse square force}$$

$$\left[ \vec{F} = \frac{K}{r^n} \hat{e}_r \right] \quad n=-1 \text{ SHM}$$

Polar Coord's.  $\vec{r} = r \hat{e}_r$ 

$$\vec{v} = v_r \hat{e}_r + v_\theta \hat{e}_\theta$$

$$= \dot{r} \hat{e}_r + r \dot{\theta} \hat{e}_\theta$$

$$\vec{a} = a_r \hat{e}_r + a_\theta \hat{e}_\theta$$

$$a_r = \frac{d^2 r}{dt^2} - r \left( \frac{d\theta}{dt} \right)^2$$

$$a_\theta = 2 \left( \frac{dr}{dt} \right) \left( \frac{d\theta}{dt} \right) + r \frac{d^2 \theta}{dt^2}$$

as forces are radial in nature

$$\therefore a_\theta = 0$$

$$2 \left( \frac{dr}{dt} \right) \left( \frac{d\theta}{dt} \right) + r \frac{d^2 \theta}{dt^2} = 0$$

\* by r

$$2r \left( \frac{dr}{dt} \right) \left( \frac{d\theta}{dt} \right) + r^2 \frac{d^2 \theta}{dt^2} = 0$$

$$\frac{d}{dt} \left( r^2 \frac{d\theta}{dt} \right) = 0$$

$$\boxed{r^2 \frac{d\theta}{dt} = \text{constant}} \quad \longrightarrow (1)$$

$$\vec{L} = \vec{r} \times \vec{p}$$

$$= r \hat{e}_r \times m \vec{v}$$

$$= r \hat{e}_r \times m \left[ \frac{dr}{dt} \hat{e}_r + r \frac{d\theta}{dt} \hat{e}_\theta \right]$$

$$= m r^2 \frac{d\theta}{dt} (\hat{e}_r \times \hat{e}_\theta)$$

 $\downarrow$   
 $\hat{n} \rightarrow \text{unit vector normal to } (r, \theta)$ 

$$\vec{L} = m r^2 \frac{d\theta}{dt} \hat{n}$$

$$\left| \frac{\vec{L}}{m} \right| = r^2 \frac{d\theta}{dt}$$

$$\vec{L} = \vec{r} \times \vec{p} \quad \text{Alternate method}$$

Hence

 $\vec{L}$  is conserved

$$\frac{d\vec{L}}{dt} = \frac{d\vec{r}}{dt} \times \vec{p} + \vec{r} \times \frac{d\vec{p}}{dt}$$

$$= \vec{v} \times m \vec{v} + \vec{r} \times \vec{F}_{ext}$$

$$= \downarrow 0 + \vec{r} \times \vec{F}(r)$$

$$= 0$$

Areal Velocity :-

$\vec{r} \rightarrow \vec{r} + d\vec{r}$  in dt time

$$d\vec{S} = \frac{1}{2} \vec{r} \times d\vec{r} = \frac{1}{2} r (r d\theta) \hat{n}$$

Areal Velocity  $\frac{d\vec{S}}{dt} = \frac{1}{2} r^2 \frac{d\theta}{dt} \hat{n}$

$$\frac{d\vec{S}}{dt} = \frac{\vec{L}}{2m} = \text{constant}$$

Equation of Orbit :- Inverse Square force

$$F_r = -\frac{C}{r^2} \quad (\text{say}) \quad C > 0 = -Cu^2$$

$$F_r = m \left( \frac{d^2 r}{dt^2} - r \left( \frac{d\theta}{dt} \right)^2 \right) \quad \text{--- (2)}$$

①  $\vec{L}$  is conserved

$$\therefore m r^2 \frac{d\theta}{dt} = \text{constant} = L$$

$$\Rightarrow \frac{d\theta}{dt} = \frac{L}{m r^2} = \frac{k}{r^2}$$

② let  $u = \frac{1}{r}$

$$\frac{d\theta}{dt} = k u^2$$

$$L = T + V$$

$$= \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

$$m\ddot{r} - m r \dot{\theta}^2 + \frac{dV}{dr} = 0 \rightarrow \text{Lagrange's EOM for } \vec{r}, \text{ generalized}$$

$$\vec{F}_r = -\frac{dV}{dr} = m\ddot{r} - m r \dot{\theta}^2$$

$$k = \frac{L}{m}$$

$$\frac{dr}{dt} = \frac{d}{dt} \left( \frac{1}{u} \right) = -\frac{1}{u^2} \frac{du}{dt} = -\frac{1}{u^2} \cdot \frac{du}{d\theta} \cdot \frac{d\theta}{dt}$$

$$\frac{dr}{dt} = -\frac{1}{u^2} \cdot k u^2 \cdot \frac{du}{d\theta} = -k \frac{du}{d\theta}$$

$$\begin{aligned} \frac{d^2 r}{dt^2} &= \frac{d}{dt} \left( -k \frac{du}{d\theta} \right) = -k \frac{d}{dt} \left( \frac{du}{d\theta} \right) = -k^2 u^2 \frac{d^2 u}{d\theta^2} \\ &= -k \frac{d}{d\theta} \left( \frac{du}{d\theta} \right) \cdot \frac{d\theta}{dt} \end{aligned}$$

Put in eqn (2)

$$-C u^2 = m \left( -k^2 u^2 \frac{d^2 u}{d\theta^2} - \frac{1}{u} (k u^2)^2 \right)$$

$$\frac{C}{m k^2} = \left( \frac{d^2 u}{d\theta^2} + u \right)$$

$$\text{let } \frac{C}{m k^2} = A \quad (\text{say})$$

$$\frac{d^2 u}{d\theta^2} + u = A$$

$$\frac{d^2 u}{d\theta^2} + (u - A) = 0$$

Rewriting this eq<sup>n</sup>,

$$\frac{d^2 (u - A)}{d\theta^2} + (u - A) = 0$$

$$\text{as } \frac{d^2 A}{d\theta^2} = 0$$

$$\rightarrow (u - A) = B \cos(\theta - \theta_0)$$

$$u = A + B \cos(\theta - \theta_0)$$

$$\frac{1}{r} = A \left[ 1 + \frac{B}{A} \cos(\theta - \theta_0) \right]$$

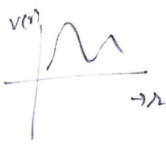
$$\text{Put } p = \frac{1}{A} \text{ and } e = \frac{B}{A}$$

$$\frac{1}{r} = 1 + e \cos(\theta - \theta_0)$$

Std. eq<sup>n</sup> of Conic section

$$p = \text{orbital parameter} = \frac{1}{A} = \frac{mk^2}{C} = \frac{mL^2}{m^2 c} = \frac{L^2}{mc}$$

$$r(t), \theta(t)$$



$$\text{gravitational force } C = G M m \text{ (say).}$$

$$p = \frac{L^2}{G M m^2}$$

$$e = \frac{B}{A} = \frac{B L^2}{G M m^2}$$

$e > 1$	Hyperbola	] unbounded Motions
$e = 1$	Parabola	
$e = 0$	Circle	] Bounded Motions.
$e < 1$	Ellipse	

Perigee and Apogee

$$\frac{p}{r} = 1 + e \cos(\theta - \theta_0)$$

$$\theta = 0.$$

$$\frac{p}{r_{\min}} = 1 + e$$

$$\frac{p}{r_{\max}} = 1 - e$$

$$\theta = \pi$$

$$\frac{r_{\max}}{r_{\min}} = \frac{1+e}{1-e}$$

$$e = \frac{r_{\max} - r_{\min}}{r_{\max} + r_{\min}}$$

$$p = \frac{2 r_{\max} r_{\min}}{r_{\max} + r_{\min}}$$