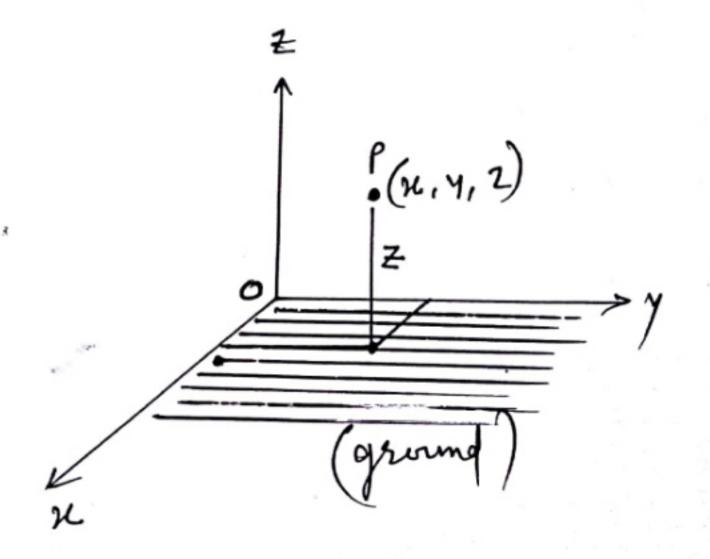
(1) unacademy Question Based On "Lagrangian"

Basie Concept:

2) P.v. 
$$Z = \chi \hat{i} + y \hat{j} + z \hat{k}$$

$$\vec{V} = \frac{d\vec{V}}{dt} = \frac{d\chi}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$$

$$\vec{V} = \chi \hat{i} + y \hat{j} + z \hat{k}$$



$$T = \frac{1}{2} m v^{2}$$

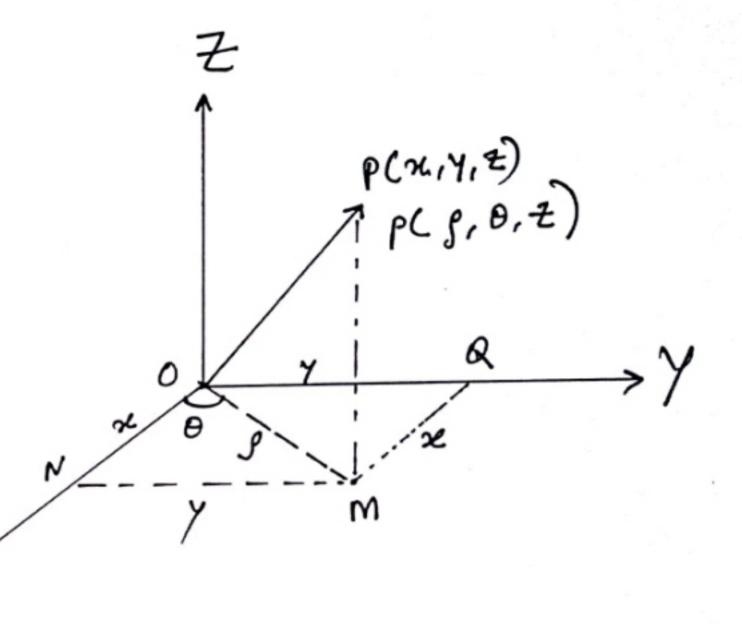
$$= \frac{1}{2} m \left( \sqrt{v_{x}^{2} + v_{y}^{2} + v_{z}^{2}} \right)^{2}$$

$$= \frac{1}{2} m \left( v_{n}^{2} + v_{y}^{2} + v_{z}^{2} \right)$$

$$Sin \theta = \frac{y}{\beta} \Rightarrow y = \beta Sin \theta$$

$$\tan \theta = \frac{y}{\pi} \Rightarrow \theta = \tan^{-1}\left(\frac{y}{\pi}\right)$$

Sometimes instead of j', we use 's'

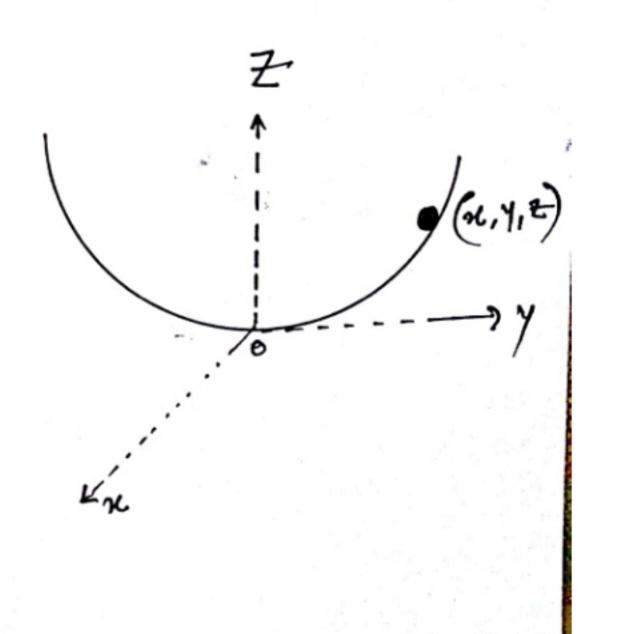


A particle of mass on moves inside a bowl. If the surface of bowl is given by the equation  $z = \frac{1}{2} R \left( \pi^2 + y^2 \right)$  where 'a' is a constant. The Lagrangian of the particle is  $\frac{1}{2} R \left( \dot{x}^2 + \dot{x}^2 \dot{\theta}^2 - g \alpha r^2 \right)$  (b)  $\frac{1}{2} R \left[ \left( 1 + \alpha^2 r^2 \right) \dot{s}^2 + \dot{s}^2 \dot{\theta}^2 - g \alpha r^2 \right]$ 

Solution.

Cylinen = = = = (x2+y2)

Here It will be more convenient to use eyendrical coordinates



$$\frac{\dot{z}}{z} = \frac{a}{z} \frac{dr^2}{dr} \cdot \frac{dr}{dt}$$

$$\dot{z} = \frac{\alpha}{2} 2 \lambda^{2-1} \dot{\lambda}$$

$$= \frac{dn}{dt} = \frac{d}{dt} 2 \cos \theta$$

$$= \frac{n + \cos \theta}{n} + \cos \theta$$

$$= \frac{n + \cos \theta}{n} + \cos \theta$$

$$= \frac{n + \cos \theta}{n} + \cos \theta$$

$$= -2 \sin \theta + \sin \theta$$

and 
$$y = \frac{1}{2} \frac{1}{8} \sin \theta$$

$$\frac{dy}{dt} = \frac{d}{dt} \left( \frac{1}{8} \sin \theta + \frac{1}{8} \sin \theta \right) \frac{dx}{dt}$$

$$y = \frac{1}{2} \frac{d}{dt} \sin \theta + \frac{1}{8} \sin \theta \frac{dx}{dt}$$

$$y = \frac{1}{2} \cos \theta \cdot \dot{\theta} + \frac{1}{8} \sin \theta \frac{dx}{dt}$$

New:  $T = \frac{1}{2} m \left( \frac{1}{12} + y^2 + \frac{1}{2} \right)$ 

$$T = \frac{1}{2} m \left( \frac{1}{12} \cos \theta + \frac{1}{12} \cos \theta \right)^2 + \left( \frac{1}{12} \cos \theta + \frac{1}{12} \sin \theta \right)^2 + \left( \frac{1}{12} \cos \theta \right)^2 + \left($$

$$T = \frac{1}{2} m \left[ \lambda^{2} \dot{\theta}^{2} \sin^{2}\theta + \dot{\lambda}^{2} \cos^{2}\theta + 2 \left( -\lambda \dot{\theta} \sin\theta \right) \left( \dot{\lambda} \cos\theta \right) + \alpha^{2} \dot{\theta}^{2} \cos^{2}\theta + \dot{\lambda}^{2} \sin^{2}\theta + 2 \left( \lambda \dot{\theta} (\cos\theta) \left( \dot{\lambda} \sin\theta \right) + \alpha^{2} \lambda^{2} \dot{\lambda}^{2} \right) \right]$$

Now 
$$V = mgh$$

$$V = mg \pm \frac{1}{2}$$

$$V = mg \left(\frac{a}{2} h^2\right) \qquad \therefore \pm \frac{ah^2}{2}$$

$$L_{1} = \frac{1}{2} m \left[ \kappa^{2} \dot{\theta}^{2} + \left( 1 + a^{2} \kappa^{2} \right) \dot{s}^{2} \right] - \frac{a m g \kappa^{2}}{2}$$

$$L = \frac{1}{2} m \left[ \kappa^2 \dot{\theta}^2 + \left( 1 + \alpha^2 \kappa^2 \right) \dot{\kappa}^2 - \alpha g \kappa^2 \right] \left( A m \right)$$