

FUZZY LOGIC

Aditya Raj

11BIT0155

Afzal Ahmad

11BIT0038

Arun Ravindran

11BIT0035

OVERVIEW

- What is Fuzzy Logic?
- Where did it begin?
- Fuzzy Logic vs. Neural Networks
- Fuzzy Logic in Control Systems
- Fuzzy Logic in Other Fields

WHAT IS FUZZY LOGIC?

Definition of fuzzy

- A way to represent variation or imprecision in logic
 - A way to make use of natural language in logic
 - Approximate reasoning
- Humans say things like "If it is sunny and warm today, I will drive fast"

TRADITIONAL REPRESENTATION OF LOGIC



Slow

Speed = 0



Fast

Speed = 1

```
bool speed;  
get the speed  
if ( speed == 0) {  
    // speed is slow  
}  
else {  
    // speed is fast  
}
```

FUZZY LOGIC REPRESENTATION

- For every problem must represent in terms of fuzzy sets.
- What are fuzzy sets?



Slowest

[0.0 – 0.25]



Slow

[0.25 – 0.50]



Fast

[0.50 – 0.75]



Fastest

[0.75 – 1.00]

FUZZY LOGIC REPRESENTATION



Slowest

Slow

Fast

Fastest

```
float speed;  
get the speed  
if ((speed >= 0.0)&&(speed < 0.25)) {  
    // speed is slowest  
}  
else if ((speed >= 0.25)&&(speed < 0.5))  
{  
    // speed is slow  
}  
else if ((speed >= 0.5)&&(speed < 0.75))  
{  
    // speed is fast  
}  
else // speed >= 0.75 && speed < 1.0  
{  
    // speed is fastest  
}
```

ORIGINS OF FUZZY LOGIC

- Traces back to Ancient Greece
- Lotfi Asker Zadeh (1965)
 - First to publish ideas of fuzzy logic.
- Professor Toshio Terano (1972)
 - Organized the world's first working group on fuzzy systems.
- F.L. Smidth & Co. (1980)
 - First to market fuzzy expert systems.

FUZZY LOGIC VS. NEURAL NETWORKS

- How does a Neural Network work?
- Both model the human brain.
 - Fuzzy Logic
 - Neural Networks
- Both used to create behavioral systems.

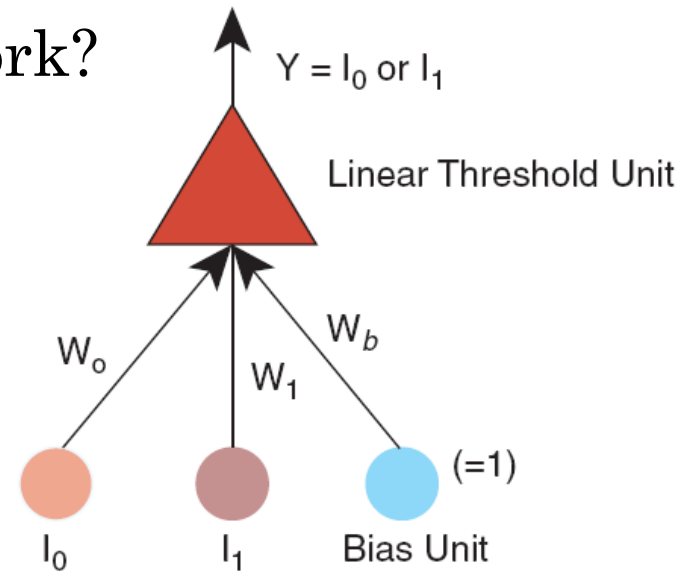


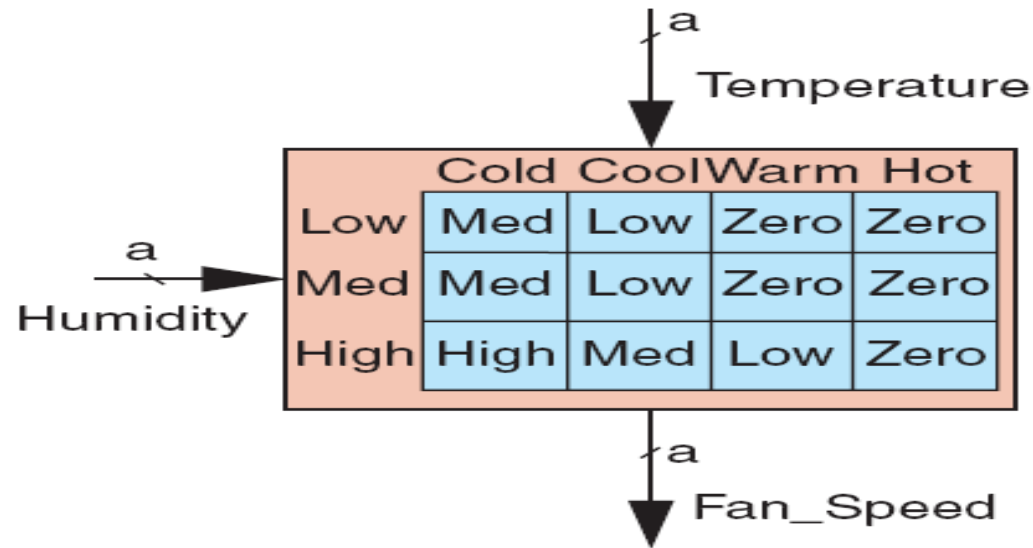
Fig. 2 A simple, single-unit adaptive network

FUZZY LOGIC IN CONTROL SYSTEMS

- Fuzzy Logic provides a more efficient and resourceful way to solve Control Systems.

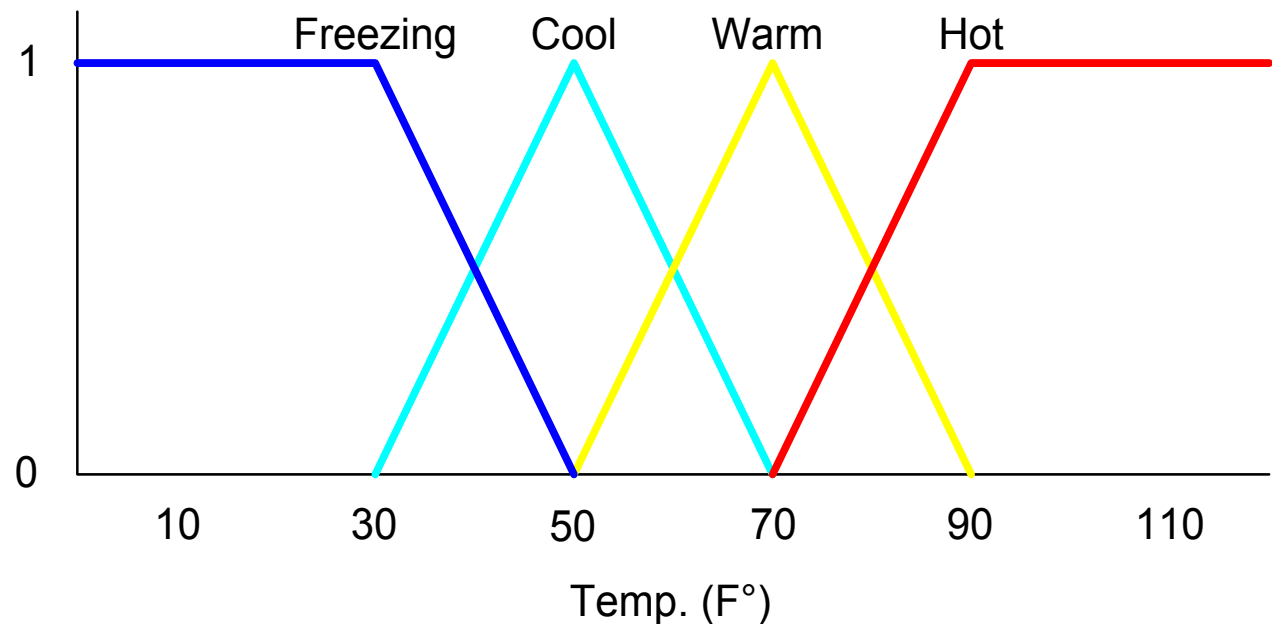
TEMPERATURE CONTROLLER

- The problem
 - Change the speed of a heater fan, based off the room temperature and humidity.
- A temperature control system has four settings
 - Cold, Cool, Warm, and Hot
- Humidity can be defined by:
 - Low, Medium, and High



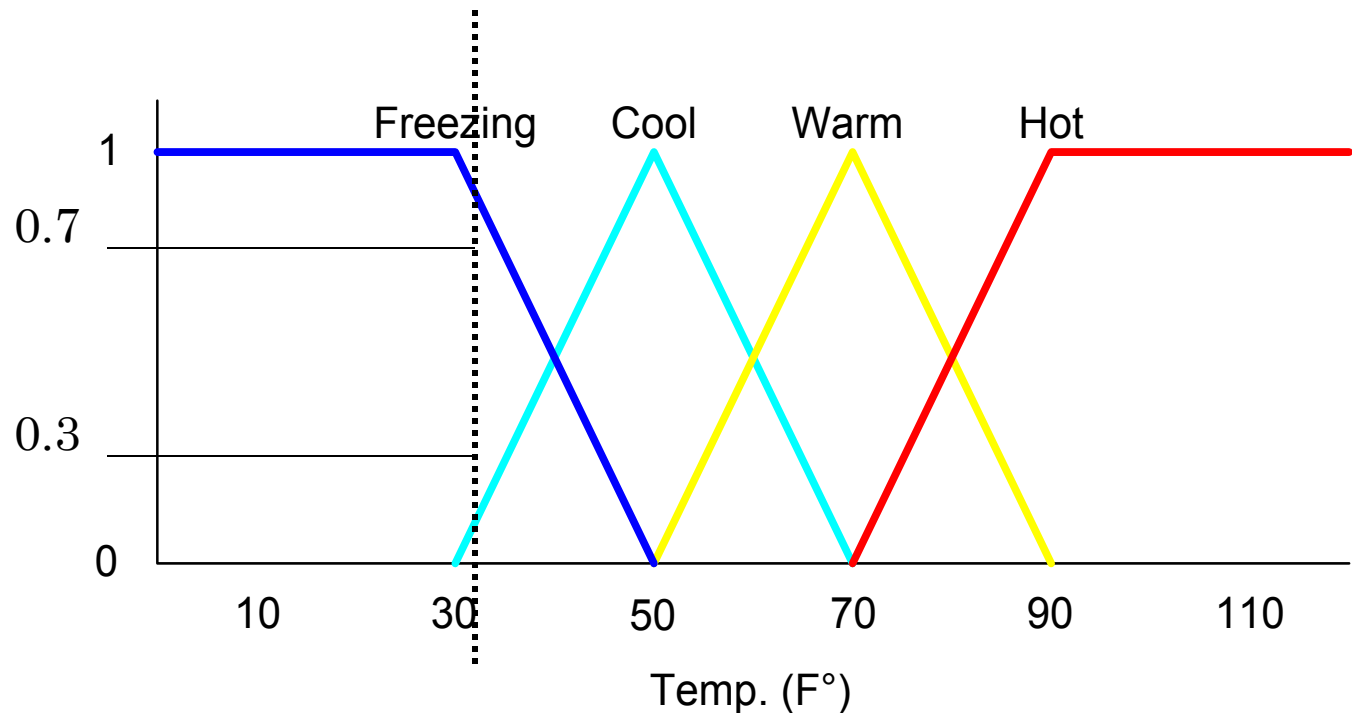
Membership Functions

- Temp: {Freezing, Cool, Warm, Hot}
- Degree of Truth or "Membership"



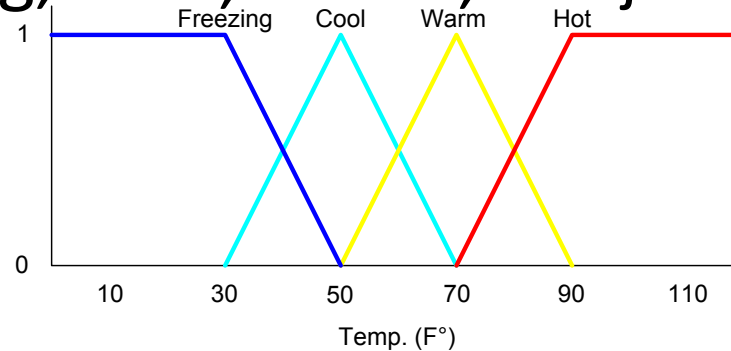
Membership Functions

- How cool is 36 F° ?
- It is 30% Cool and 70% Freezing

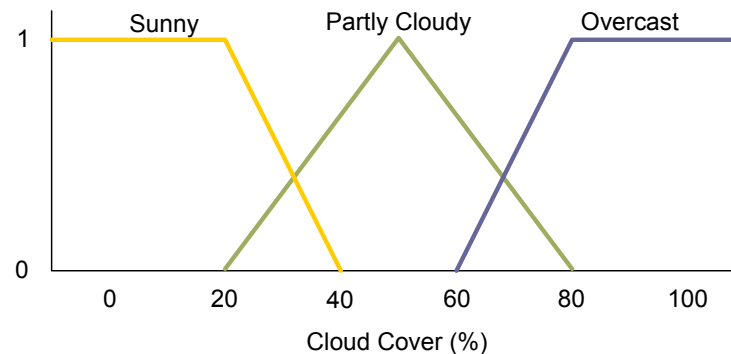


Inputs: Temperature, Cloud Cover

- Temp: {Freezing, Cool, Warm, Hot}



- Cover: {Sunny, Partly, Overcast}



Example Speed Calculation

- How fast will I go if it is
 - 65 F°
 - 25 % Cloud Cover ?

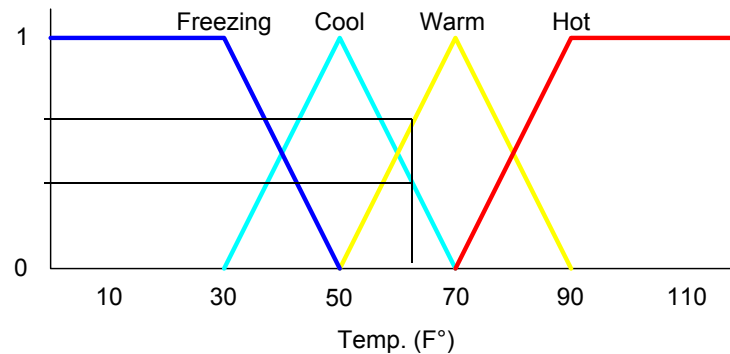
Rules

- If it's Sunny and Warm, drive Fast
 $\text{Sunny}(\text{Cover}) \wedge \text{Warm}(\text{Temp}) \Rightarrow \text{Fast}(\text{Speed})$
- If it's Cloudy and Cool, drive Slow
 $\text{Cloudy}(\text{Cover}) \wedge \text{Cool}(\text{Temp}) \Rightarrow \text{Slow}(\text{Speed})$
- Driving Speed is the combination of output of these rules...

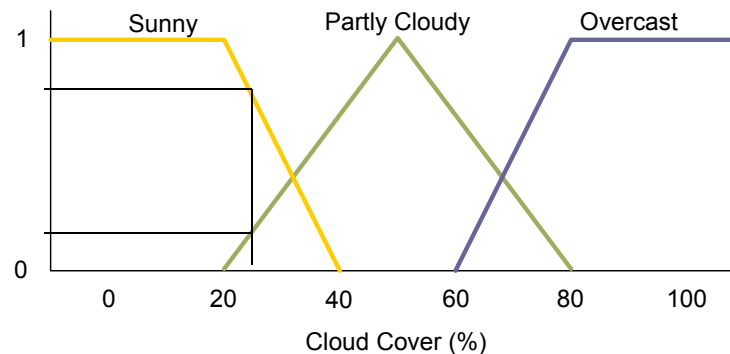
Fuzzification:

Calculate Input Membership Levels

- $65\text{ F}^\circ \Rightarrow \text{Cool} = 0.4, \text{Warm} = 0.7$



- $25\% \text{ Cover} \Rightarrow \text{Sunny} = 0.8, \text{Cloudy} = 0.2$



...Calculating...

- If it's Sunny and Warm, drive Fast

$\text{Sunny}(\text{Cover}) \wedge \text{Warm}(\text{Temp}) \Rightarrow \text{Fast}(\text{Speed})$

$$0.8 \wedge 0.7 = 0.7$$

$$\Rightarrow \text{Fast} = 0.7$$

- If it's Cloudy and Cool, drive Slow

$\text{Cloudy}(\text{Cover}) \wedge \text{Cool}(\text{Temp}) \Rightarrow \text{Slow}(\text{Speed})$

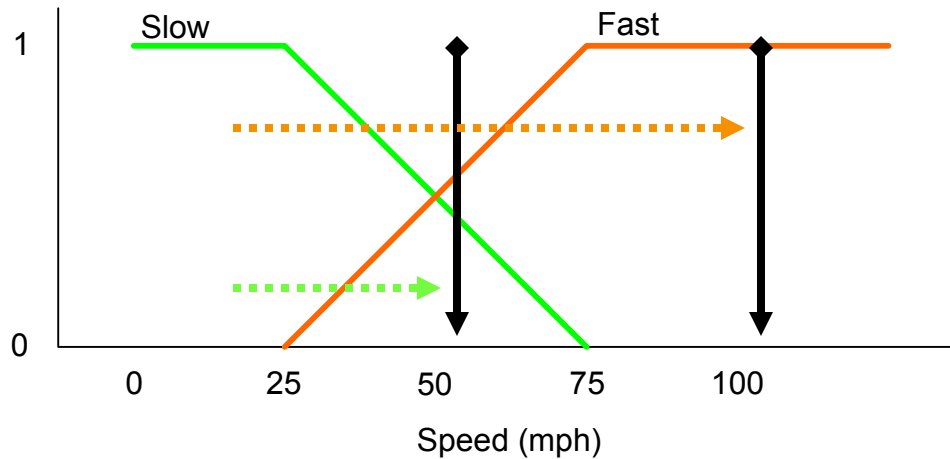
$$0.2 \wedge 0.4 = 0.2$$

$$\Rightarrow \text{Slow} = 0.2$$

Defuzzification:

Constructing the Output

- Speed is 20% Slow and 70% Fast



- Speed = weighted mean
= $(2 \cdot 25 + 7 \cdot 75) / (9)$
= 63.8 mph

Similarity Degree

- $A = B$ if and only if that every element of the union $A \cup B$ also belongs to the intersection $A \cap B$.
- So, it is reasonable to define the degree of similarity as $d(A, B) = P(A \cap B) / P(A \cup B)$.
- The smaller the ratio, the more there are elements from one of the sets which do not belong to the other.

- So, the sets A and B are equal if, $d=1$.
and $P(A \cap B) / P(A \cup B) =$

$$\frac{c \cdot \sum_x \mu_{A \cap B}(x)}{c \cdot \sum_x \mu_{A \cup B}(x)} = \frac{\sum_{i=1}^n \min(a_i, b_i)}{\sum_{i=1}^n \max(a_i, b_i)}$$

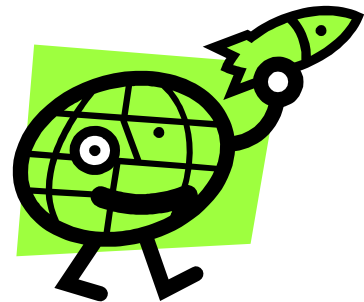
Intuitionistic Triangular Fuzzy Number

- Let $A = \{(x, t(x), s(x)) / x \in X\}$ be an IFS, then $(t(x), s(x))$ be an intuitionistic number for better understanding we take no. such as ,
 $A = \{(a, b, c)(l, m, n)\}$ where $(a, b, c) \in F(I)$ and $(l, n, m) \in F(I)$



For two intuitionistic fuzzy path length :

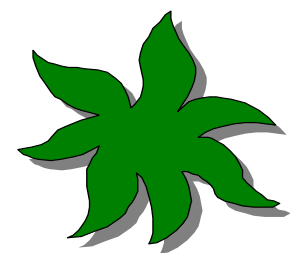
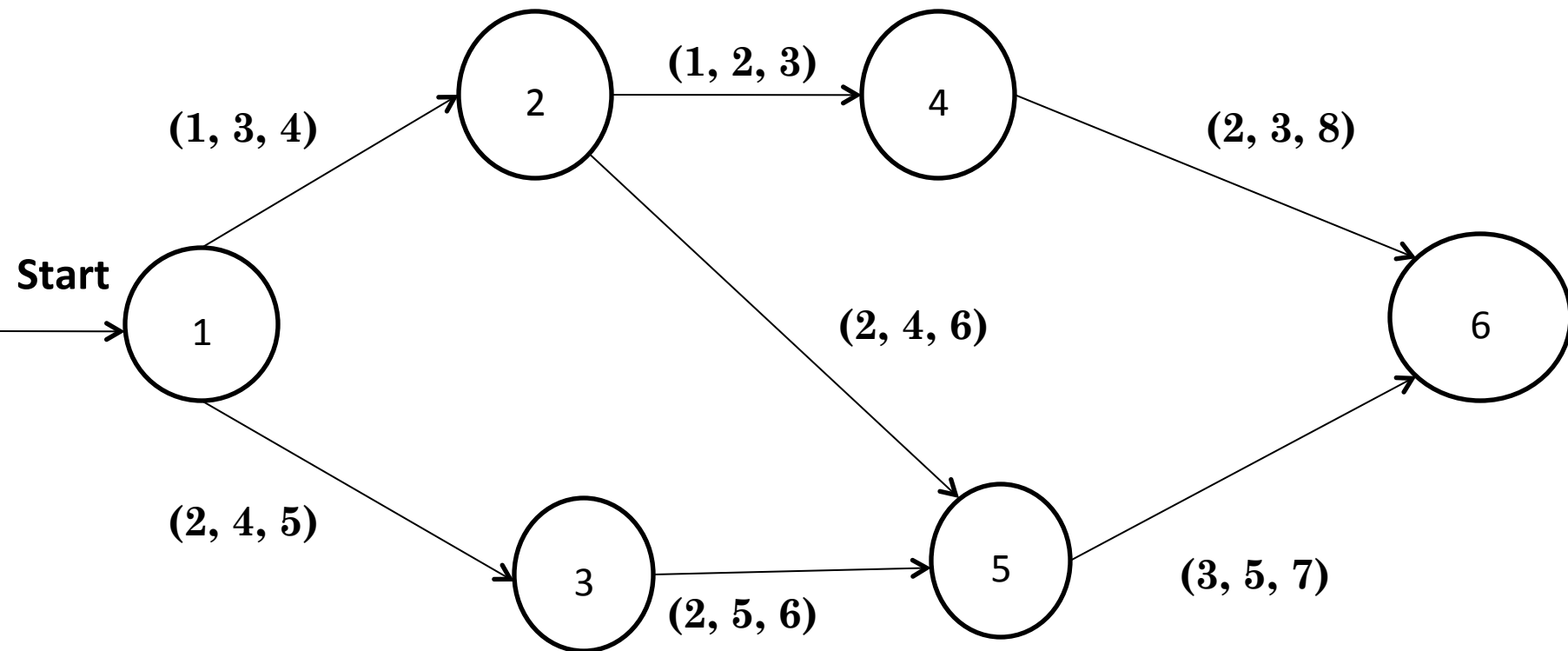
- $L1 = ((a1, b1, c1) (l1, m1, n1))$ and $L2 = ((a2, b2, c2) (l2, m2, n2))$,
- For membership function $Lmin = (a \ b \ c)$
 - $a = \min(a1, a2)$
 - $b = \{$
 $\min(b1, b2) \quad \text{if} \quad \min(b1, b2) \leq \max(a1, a2);$
 $(b1 * b2) - (a1 * a2) / (b1 + b2) - (a1 + a2)$
 $\quad \text{if} \quad \min(b1, b2) > \max(a1, a2);$
 $\}$
- $c = \min[\min(c1, c2), \max(b1, b2)]$



For non membership function

- $L_{\max} = (l \ m \ n)$
- $l = \min(l_1, l_2)$
- $m = \begin{cases} \min(m_1, m_2) & \text{if } \max(m_1, m_2) > \min(l_1, l_2) \\ (m_1 * m_2) - (l_1 * l_2) / (m_1 + m_2) - (l_1 + l_2) & \text{if } \max(m_1, m_2) \leq \min(l_1, l_2) \end{cases}$
- $n = \max[\max(n_1, n_2), \min(m_1, m_2)]$





Step1: P1: 1-2-4-6 \rightarrow L1 = (4, 8, 15)

P2: 1-2-5-6 \rightarrow L2 = (6, 12, 17)

P3: 1-3-5-6 \rightarrow L3 = (7, 14, 18)

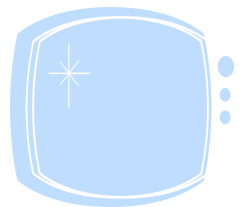
Step 2: $L_{\min} = (a, b, c) = L1 = (4, 8, 15)$

Step 3: Compute (a, b, c) :

$$b = (12 * 8) - (6 * 4) / (12 + 8) - (6 + 4) = 7.2$$

$$a = \min(4, 6) = 4;$$

$$c = \min(15, 12) = 12;$$



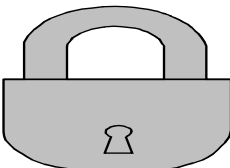
Step 5:

Set $L_{\min} = (4, 7.2, 12)$

$$S(L_i, L_{\min}) = \begin{cases} 0 \\ \frac{100(c-a)^2}{2(c_1-a_1)[(c-b)(b_1-a_1)]} \end{cases}$$

$$L_i \cap L_{\min} = \emptyset$$

$$L_i \cap L_{\min} = \emptyset$$



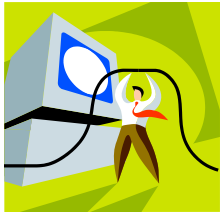
And put the values in this formula for all path i.e. p_1, p_2, p_3 and get the value of that path

path	member function
P1: 1-2-4-6	L1 = (4, 8, 15)
P2: 1-2-5-6	L2=(6, 12, 17)
P3: 1-3-5-6	L3=(7, 14, 18)



Table 1 represents the only member function for the given path and it's length $L_{\min}=(4,8,15)$

I	Path	$S(L_i, L_{\min})$	RANK
1	P1: 1-2-4-6	3.12	1 st
2	P2: 1-2-5-6	7.2	2 nd
3	P3: 1-3-5-6	9.5	3 rd



Drawbacks to Fuzzy logic

- Requires tuning of membership functions
- Fuzzy Logic control may not scale well to large or complex problems
- Deals with imprecision, and vagueness, but not uncertainty

CONCLUSION

- Fuzzy logic provides an alternative way to represent linguistic and subjective attributes of the real world in computing.
- It is able to be applied to control systems and other applications in order to improve the efficiency and simplicity of the design process.

