

# A23 CS101 Endsem Answers and Rubrics HELLO

Q1

This is the correct code for version 1

```
for (unsigned int i = 0; i < N; i++) { // Line 1
//do not deduct marks if i is changed to 1 in Line 1
//If student changes i to I in line 1 then he should be given
//1 mark total of line 2 and 3. Check Line 2 and 3 accordingly.
    const int current = data[i]; // Line 2           Marks=0.5
    unsigned int newPosition = i; // Line 3           Marks=0.5

while (newPosition > 0 && current < data[newPosition - 1]) //line4
                                                    Marks=3
{
    // Shift elements to the right
    data[newPosition] = data[newPosition - 1]; //Blank A   Marks=2
    newPosition--; // Line 6           Marks=0.5
}

// Insert the current element into the correct position
data[newPosition] = current; // Blank B
Alternate Solution : data[newPosition] = data[i]; // Blank B
                                                    Marks=2
}
```

This is the correct code for version 2

```
for (unsigned int i = 1; i < N; i++) {
    for (unsigned int j = i; j > 0; j--) { // Blank A           Marks=4.5
        if (data[j] < data[j-1]) { // Blank B           Marks=2
            // Swap elements
            const int temp = data[j];
```

```

        data[j] = data[j-1];
        data[j-1] = temp;
    }
}

```

Q2

(a)

```

#include <iostream>
using namespace std;
struct student {
    unsigned int RollNum;
    unsigned int BestFriendsCount;
    student * BestFriends[3];
};

bool Search (student & Y, student & X, bool * Checked)
{
    Checked[Y.RollNum] = true; // or 1           0.5 marks
    cout << "checking: " << Y.RollNum << endl;
    if (Y.RollNum == X.RollNum)
    {
        return true; // or 1           0.5 marks
    }
    bool found = false;
    for (unsigned int k = 0; k < Y.BestFriendsCount; k++)
    {
        student Z = *(Y.BestFriends[k]);
        if (!Checked[Z.RollNum]) /.?
            // or if (Checked[Z.RollNum] == false) 1 mark
            found = Search (Z,X,Checked);           0.5, 0.5
        marks
        if (found)                                   1 mark
            return true; or found; or 1;           0.5 marks
    }
    return false; or found; or 0;           0.5 marks
}

```

(b) – For the output, 1 mark for each correct line. If some line is wrong, do not check the ones after that

```
checking: 0;
checking: 1
checking: 3
checking: 5
checking: 4
```

Verbose:

*TODO: Rubrics for execution trace will be finalized after looking at students' answers*

---

0      4

Call: Y.RollNum = A, X.RollNum = E

checking: 0

Call: Y.RollNum = B, X.RollNum = E

checking: 1

Call: Y.RollNum = D, X.RollNum = E

checking: 3

Call: Y.RollNum = F, X.RollNum = E

checking: 5

Call: Y.RollNum = E, X.RollNum = E

checking: 4

1

**(c)**– If some line is wrong, do not check the ones after that

checking: 0    0.7 marks

checking: 1    0.7 marks

checking: 3    0.7 marks

checking: 5    0.7 marks

checking: 4    0.7 marks

checking: 2    0.7 marks

checking: 6    0.8 marks

Verbose:

---

0      7

Call: Y.RollNum = A, X.RollNum = H

checking: 0

Call: Y.RollNum = B, X.RollNum = H

checking: 1

Call: Y.RollNum = D, X.RollNum = H

checking: 3

Call: Y.RollNum = F, X.RollNum = H

```

checking: 5
Call: Y.RollNum = E, X.RollNum = H
checking: 4
Call: Y.RollNum = C, X.RollNum = H
checking: 2
Call: Y.RollNum = G, X.RollNum = H
checking: 6
0

```

Q3

(a)

$$MSE = \frac{1}{n} \sum_{i=1}^n (f(x_i) - y_i)^2$$

In the context of a regression problem, the goal is to find the parameters  $a$ ,  $b$ , and  $c$  in the quadratic model  $f(x) = ax^2 + bx + c$  that best fit the given data points  $(x_i, y_i)$  for  $i = 0, 1, \dots, 100$ .

A common quality-of-fit criterion in regression is the sum of squared errors (SSE). The SSE is defined as the sum of the squared differences between the predicted values ( $f(x_i)$ ) and the actual observed values ( $y_i$ ) for all data points. Mathematically, the SSE is given by:

$$SSE = \sum_{i=0}^{100} (f(x_i) - y_i)^2$$

Substitute the expression for  $f(x)$  into the SSE formula:

$$SSE = \sum_{i=0}^{100} (a(x_i)^2 + b(x_i) + c - y_i)^2$$

**Marking Scheme for I)- BOTH SSE and MSE are correct. The student has to write any one.**

**Award 3 marks if the mathematical expression is fully correct and 0 marks if the expression is incorrect in any way.**

**II) Marking Scheme-**

**In PART 3 and 4, assign 1.5 marks for each step; award 0.5 marks if partially correct.**

*In PART 5, allocate 1 mark for a correct answer and 0.5 marks if the contents of matrices are partially correct.*

## II. Derive Equations in the Form of $Mv = b$ :

### 1. Model Prediction:

$$f(x_i) = ax_i^2 + bx_i + c$$

### 2. Loss Function (Mean Squared Error):

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (ax_i^2 + bx_i + c - y_i)^2$$

### 3. Partial Derivatives with Respect to $a$ , $b$ , and $c$ :

$$\frac{\partial \text{MSE}}{\partial a} = \frac{2}{n} \sum_{i=1}^n x_i^2 (ax_i^2 + bx_i + c - y_i)$$

$$\frac{\partial \text{MSE}}{\partial b} = \frac{2}{n} \sum_{i=1}^n x_i (ax_i^2 + bx_i + c - y_i)$$

$$\frac{\partial \text{MSE}}{\partial c} = \frac{2}{n} \sum_{i=1}^n (ax_i^2 + bx_i + c - y_i)$$

### 4. Set Partial Derivatives to Zero and Solve for $a$ , $b$ , and $c$ :

$$\frac{\partial \text{MSE}}{\partial a} = 0 \Rightarrow a \sum_{i=1}^n x_i^4 + b \sum_{i=1}^n x_i^3 + c \sum_{i=1}^n x_i^2 = \sum_{i=1}^n x_i^2 y_i$$

$$\frac{\partial \text{MSE}}{\partial b} = 0 \Rightarrow a \sum_{i=1}^n x_i^3 + b \sum_{i=1}^n x_i^2 + c \sum_{i=1}^n x_i = \sum_{i=1}^n x_i y_i$$

$$\frac{\partial \text{MSE}}{\partial c} = 0 \Rightarrow a \sum_{i=1}^n x_i^2 + b \sum_{i=1}^n x_i + nc = \sum_{i=1}^n y_i$$

### 5. Matrix Form $Mv = b$ :

$$M = \begin{bmatrix} \sum_{i=1}^n x_i^4 & \sum_{i=1}^n x_i^3 & \sum_{i=1}^n x_i^2 \\ \sum_{i=1}^n x_i^3 & \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i \\ \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i & n \end{bmatrix}, \quad v = \begin{bmatrix} a \\ b \\ c \end{bmatrix}, \quad b = \begin{bmatrix} \sum_{i=1}^n x_i^2 y_i \\ \sum_{i=1}^n x_i y_i \\ \sum_{i=1}^n y_i \end{bmatrix}$$

III) Method: Gauss Jordan Elimination/ Least Square along with its description.

*Marking Scheme- 2 Marks if proper description of algorithm is given 0.5 if not.*

Q4

```
#include <iostream>
#include<cstdlib>
//If written 'Not Required' or written any valid library like
cstdlib marks will be provided Marks=1
using namespace std;
int main () {
    rand(-1); //Write srand(-1) //srand(0) or remove the line. Unnecessary or remove -1
Marks=1
    long int N = 1e3 or N = 0; Marks=1
    double average = 0;
    while (N --> 0) or while(N++<0) if N is set to zero
    {`
        const double temp = rand()*1.0/RAND_MAX; Marks=2

        ;... OR
        const double temp = (double)rand()/RAND_MAX;
        OR
        const double temp = rand()/(1.0+RAND_MAX);
        unsigned char draw = 0; //If char is changed to int/float no negative marks
        if ( temp<=1.0/21) draw = 1; Marks=1.5
        if (temp>1.0/21 && temp<=3.0/21) draw = 2; Marks=1.5
        if (temp>3.0/21 && temp<=6.0/21) draw = 3; Marks=1.5
        if (temp>6.0/21 && temp<=10.0/21) draw = 4; Marks=1.5
        if (temp>10.0/21 && temp<=15.0/21) draw = 5; Marks=1.5
        if(temp>15.0/21) draw = 6; Marks=1.5

        OR

        if ( temp*21 < 1) draw = 1;
```

```

        if ( temp*21 >= 1 && temp*21< 3) draw = 2;
        if ( temp*21 >= 3 && temp*21< 6) draw = 3;
        if ( temp*21 >= 6 && temp*21< 10) draw = 4;
        if ( temp*21 >= 10 && temp*21< 15) draw = 5;`
        if ( temp*21 >= 15 ) draw = 6;

        average = average + draw;
    }
    average = average / 1000;  or 1e3 or average/N if N is set to zero
    Marks=1
    cout.precision (10);
    cout << average << endl;
}

\

```

## Q5

```

#include <iostream>
using namespace std;
template <class T>
class Vector
{
private:
    unsigned int size;
    T *data;
    void copy(const Vector<T> &);

public:
    Vector(unsigned int n = 8) : size(n), data(new T[size])
    {
        if (n == 0)
            data = NULL;
    }

    Vector(const Vector<T> &v) : size(v.size), data(new T[size])
    {
        copy(v);
    }
}

```

```

~Vector()
{
    ///////////////added this line////////////////
    delete[] data;
} // 1 and only 1 statement

unsigned int length() const
{
    return size;
}

T &operator[](unsigned int i) const
{
    // return data[i / size];
    return data[i];
}

Vector<T> &operator=(const Vector<T> &) const; //remove const
};

template <class T>
void Vector<T>::copy(const Vector<T> &v)
{
    const unsigned int num = (size < v.size) ? size : v.size;
    for (unsigned int i = 0; i < num; i++)
        data[i] = v.data[i]; // inverted
}

template <class T>
Vector<T> &Vector<T>::operator=(const Vector<T> &v) const
{
    // 1 and only 1 statement
    delete[] data;

    data = new T[v.size];
    size = v.size; ////inverted
    copy(v);
    // 1 and only 1 statement
    return *this;
}

```

Marks = 2

Marks = 2

Marks=1.5

Marks = 2

Marks=1.5

Marks = 2

Marks = 2

Marks = 2



```

int main()
{
    Vector<int> v(10);
    for (int i = 0; i < v.length(); i++)
        v[i] = i;
    for (int i = 0; i < v.length(); i++)
        cout << v[i] << " ";
    cout << endl;
    cout << "-----" << endl;
    Vector<int> w(v);
    for (int i = 0; i < w.length(); i++)
        cout << w[i] << " ";
    cout << endl;
    cout << "-----" << endl;
    Vector<int> x;
    for (int i = 0; i < x.length(); i++)
        x[i] = -i;
    for (int i = 0; i < x.length(); i++)
        cout << x[i] << " ";
    cout << endl;
    cout << "-----" << endl;
    v = w = x;
    for (int i = 0; i < v.length(); i++)
        cout << v[i] << " ";
    cout << endl;
    for (int i = 0; i < w.length(); i++)
        cout << w[i] << " ";
    cout << endl;
    cout << "-----" << endl;
    Vector<float> y(3);
    for (int i = 0; i < y.length(); i++)
        cout << y[i] << " ";
    cout << endl;
    Vector<float> z(0);
    for (int i = 0; i < z.length(); i++)
        cout << z[i] << " ";
    cout << endl;
    z = y;
    for (int i = 0; i < z.length(); i++)
        cout << z[i] << " ";
    cout << endl;
}

```