

# MA-110 Linear Algebra and Differential Equations

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# Diagonalizability: Summary

**Thus:** If an  $n \times n$  matrix  $A$  has  $n$  linearly independent eigenvectors  $v_1, \dots, v_n$ , then  $A$  is diagonalizable. Moreover, if  $\lambda_1, \dots, \lambda_n$  are the corresponding eigenvalues, then  $P^{-1}AP = \Lambda$ , where the diagonalizing matrix is  $P = (v_1 \ \cdots \ v_n)$ , and the diagonal matrix is  $\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix}$ , i.e.,  $P^{-1}AP = \Lambda$ , where

The diagonal entries of  $\Lambda$  are eigenvalues of  $A$  and

The columns of  $P$  are corresponding eigenvectors of  $A$ .

The EVD of  $A$  is  $A = P\Lambda P^{-1}$ .

**Note:**  $P$  need not be unique, e.g., replace  $v_1$  by  $2v_1$ , etc.

## Extra Reading: Simultaneous Diagonalizability

Assume  $A$  and  $B$  are diagonalizable. Then  $A$  and  $B$  have same eigenvector matrix  $S$  if and only if  $AB = BA$ .

*Proof.* ( $\Rightarrow$ ) Assume  $S^{-1}AS = \Lambda_1$  and  $S^{-1}BS = \Lambda_2$ , where  $\Lambda_1$  and  $\Lambda_2$  are diagonal matrices. Then

$AB = (S\Lambda_1S^{-1})(S\Lambda_2S^{-1}) = S(\Lambda_1\Lambda_2)S^{-1}$  and  $BA = S(\Lambda_2\Lambda_1)S^{-1}$ . Since  $\Lambda_1\Lambda_2 = \Lambda_2\Lambda_1$ , we get  $AB = BA$ .

(*Part of*  $\Leftarrow$ ) Assume  $AB = BA$ . If  $Ax = \lambda x$ , then  $ABx = B(Ax) = B(\lambda x) = \lambda Bx$ . If  $Bx = 0$ , then  $x$  is an eigenvector of  $B$ , associated to  $\mu = 0$ . If  $Bx \neq 0$ , then  $x$  and  $Bx$  both are eigenvectors of  $A$ , associated to  $\lambda$ .

*Special case:* Assume all the eigenspaces of  $A$  are one dimensional. Then  $Bx = \mu x$  for some scalar  $\mu \Rightarrow x$  is an eigenvector of  $B$ . We will not prove the general case.

# Eigenvalues of $A^k$

- If  $Av = \lambda v$ , then  $A^2v = A(Av) = A(\lambda v) = \lambda(Av) = \lambda^2v$ .  
Similarly  $A^k v = \lambda^k v$  for any  $k \geq 0$ .

Thus if  $v$  is an eigenvector of  $A$  with associated eigenvalue  $\lambda$ , then  $v$  is also an eigenvector of  $A^k$  with associated eigenvalue  $\lambda^k$  for  $k \geq 0$ . If  $A$  is invertible, then  $\lambda \neq 0$ . Hence, the same also holds for  $k < 0$  since  $A^{-1}v = \lambda^{-1}v$ .

- If  $A$  is diagonalizable, then  $P^{-1}AP = \Lambda$  is diagonal where columns of  $P$  are eigenvectors of  $A$ .

Since  $(P^{-1}A^kP) = \Lambda^k$ , which is diagonal, we see that  $A^k$  is diagonalizable, and the eigenvectors of  $A^k$  are same as eigenvectors of  $A$ . Similarly, the same also holds for  $k < 0$  if  $A$  is invertible.

**Question:** What is the EVD of  $A^k$ .

## Reading Slide - Application: Fibonacci Numbers

Let  $F_0 = 0$ ,  $F_1 = 1$  and  $F_k = F_{k-1} + F_{k-2}$  for  $k \geq 2$  define the Fibonacci sequence. What is the  $k$ th term?

If  $u_k = \begin{pmatrix} F_{k+1} \\ F_k \end{pmatrix}$ , then  $\begin{pmatrix} F_{k+1} \\ F_k \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} F_k \\ F_{k-1} \end{pmatrix}$ , i.e.,

$u_k = Au_{k-1}$  for  $n \geq 1$ , where  $A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \Rightarrow u_k = A^k u_0$  for  $k \geq 1$ .

Characteristic polynomial of  $A$ :  $\lambda^2 - \lambda - 1$ ; Eigenvalues:

$$\lambda_1 = \frac{1 + \sqrt{5}}{2}, \lambda_2 = \frac{1 - \sqrt{5}}{2}.$$

There are 2 distinct eigenvalues  $\Rightarrow$  the associated eigenvectors  $x_1$  and  $x_2$  are linearly independent  $\Rightarrow \{x_1, x_2\}$  is a basis for  $\mathbb{R}^2$ .

Write  $u_0 = c_1 x_1 + c_2 x_2$ . Then  $u_k = A^k u_0 = A^k (c_1 x_1 + c_2 x_2)$   
 $= c_1 A^k x_1 + c_2 A^k x_2 = c_1 \left( \frac{1 + \sqrt{5}}{2} \right)^k x_1 + c_2 \left( \frac{1 - \sqrt{5}}{2} \right)^k x_2.$

**Q:** Find  $x_1$ ,  $x_2$ ,  $c_1$  and  $c_2$  and get the exact formula for  $F_k$ .

# An Application: Predator-Prey Model

Let the owl and rat populations at time  $k$  be  $O_k$  and  $R_k$  respectively. Owls prey on the rats, so if there are no rats, the population of owls will go down by 50%. If there are no owls to prey on the rats, then the rat population will increase by 10%.

In particular, the rat and owl populations dependence is as follows:

$$\begin{aligned}O_{k+1} &= 0.5O_k + 0.4R_k \\R_{k+1} &= -pO_k + 1.1R_k\end{aligned}$$

The term  $-p$  calculates the rats preyed by the owls.

Thus, if  $P_k = \begin{pmatrix} O_k \\ R_k \end{pmatrix}$  and  $A = \begin{pmatrix} 0.5 & 0.4 \\ -p & 1.1 \end{pmatrix}$ , then  $P_{k+1} = AP_k$  for all  $k$ . In particular,  $P_k = A^k P_0$ .

**Exercise:** If we start with a certain initial population of owls and rats, how many will be there in, say, 50 years, i.e., given  $P_0$ , what is  $P_{50}$ ? What is the steady state, i.e., what is  $\lim_{k \rightarrow \infty} P_k$ ?

# An Application: Steady State

Suppose we have a system where the current state  $u_k$  depends on the previous one  $u_{k-1}$  linearly, i.e.,  $u_k = Au_{k-1}$ . Then observe that  $u_k = A^k u_0$ . The steady state of the system is  $u_\infty = \lim_{k \rightarrow \infty} (u_k)$ . How do we find this?

- If  $u_0$  is an eigenvector of  $A$  associated to  $\lambda$ , then  $u_k = \lambda^k u_0$ .
- Let  $v_1, \dots, v_r$  be eigenvectors of  $A$  associated respectively to  $\lambda_1, \dots, \lambda_r$ . If  $u_0 \in \text{Span}\{v_1, \dots, v_r\}$ , i.e.,  $u_0 = c_1 v_1 + \dots + c_r v_r$  for scalars  $c_1, \dots, c_r$ , then

$u_k = A^k u_0 = c_1 A^k v_1 + \dots + c_r A^k v_r = c_1 \lambda_1^k v_1 + \dots + c_r \lambda_r^k v_r$ . In particular, if  $A$  is diagonalizable, then there is a basis of  $\mathbb{R}^n$  of eigenvectors of  $A$ . Hence, this is applicable to every  $u_0 \in \mathbb{R}^n$ .

Let  $A$  be diagonalizable, and  $u_k$  represent population.

- Under what conditions will there be a population explosion?
- What conditions will force the population to become extinct?
- When does it stabilise (to a non-zero value)?

**Hint:** Depends on  $|\lambda_i|$ .

## Extra Reading: Complex Eigenvalues

**Example:** Rotation by  $90^\circ$  in  $\mathbb{R}^2$  is given by  $Q = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ . It

has no **real** eigenvectors since rotation by  $90^\circ$  changes the direction.

$Q$  has eigenvalues, but they are **not real**.  $\det(Q - \lambda I) = \lambda^2 + 1 \Rightarrow \lambda_1 = i$  and  $\lambda_2 = -i$ , where  $i^2 = -1$ . Let us compute the eigenvectors.

$$(Q - iI)x_1 = \begin{pmatrix} -i & -1 \\ 1 & -i \end{pmatrix} x_1 = 0 \Rightarrow x_1 = \begin{pmatrix} 1 \\ -i \end{pmatrix}, (Q + iI)x_2 =$$

$$\begin{pmatrix} i & -1 \\ 1 & i \end{pmatrix} x_2 = 0 \Rightarrow x_2 = \begin{pmatrix} 1 \\ i \end{pmatrix}.$$

The eigenvalues, though imaginary, are distinct, hence eigenvectors are linearly independent.

$$\text{If } P = (x_1 \ x_2) = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix}, \text{ then } P^{-1}QP = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}.$$



## Extra Reading : Complex Vectors

**Conclusion:** We need complex numbers  $\mathbb{C}$  even if we are working with real matrices. Over  $\mathbb{C}$ , an  $n \times n$  matrix  $A$  always has  $n$  eigenvalues.

**Reason:** Fundamental theorem of Algebra

Every polynomial over  $\mathbb{C}$  of degree  $n$  has  $n$  roots in  $\mathbb{C}$ .

# Inner product on $\mathbb{R}^n$

**Defn.** Define the **inner product** (dot product) of two vectors

$$v, w \in \mathbb{R}^n \text{ as } \boxed{v \cdot w = v^T w}$$

For  $v, w$  in  $\mathbb{R}^n$  and  $c$  in  $\mathbb{R}$

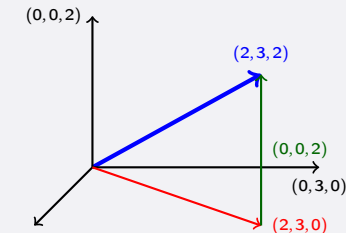
- $v \cdot w = v^T w = v_1 w_1 + \cdots + v_n w_n = w^T v = w \cdot v.$
- (Bilinearity)
$$(v + w) \cdot z = (v + w)^T z = v^T z + w^T z = v \cdot z + w \cdot z$$
$$cv \cdot w = (cv)^T w = c(v^T w) = v^T (cw) = v \cdot cw.$$
- $v \cdot v = v^T v \geq 0$  and  $v^T v = 0$  if and only if  $v = 0$ .

Define **length** (or norm) of  $v$  in  $\mathbb{R}^n$  to be  $\boxed{\|v\| = \sqrt{v \cdot v}.}$

Henceforth we will use  $v^T w$  directly to write the dot product.

## Reading : Length of a vector in $\mathbb{R}^3$ and $\mathbb{R}^n$

Let  $v = (2, 3, 2)$ . By Pythagoras theorem,  $\|v\|$   
 $= \sqrt{\|(2, 3, 0)\|^2 + \|(0, 0, 2)\|^2}$



$$= \sqrt{2^2 + 3^2 + 2^2} = \sqrt{17}.$$

Generalize by induction: Let  $v = (x_1, \dots, x_n)^T \in \mathbb{R}^n$ . Define

$$\|v\| = \sqrt{\|(x_1, \dots, x_{n-1}, 0)\|^2 + \|(0, 0, \dots, x_n)\|^2}$$

$$= \sqrt{x_1^2 + \dots + x_{n-1}^2 + x_n^2} = \sqrt{v^T v}.$$

The length in  $\mathbb{R}^n$  is compatible with the vector space structure.

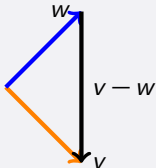
Let  $v, w \in \mathbb{R}^n$  and  $c \in \mathbb{R}$ . Then,

- $\|v\| \geq 0$  and  $\|v\| = 0$  if and only if  $v = 0$ .
- $\|cv\| = |c|\|v\|$  •  $\|v + w\| \leq \|v\| + \|w\|$  (Triangle Inequality)

# Orthogonal vectors in $\mathbb{R}^n$

We say vectors  $v$  and  $w$  in  $\mathbb{R}^n$  are orthogonal (perpendicular) if they satisfy the Pythagoras theorem, that is,

$$\|v\|^2 + \|w\|^2 = \|v - w\|^2$$



$$\begin{aligned}\|v\|^2 + \|w\|^2 &= (v - w)^T (v - w) \\ &= (v^T - w^T)(v - w) \\ &= v^T v - w^T v + v^T w + w^T w \\ &= \|v\|^2 - 2 v^T w + \|w\|^2 \quad (\text{since } w^T v = v^T w)\end{aligned}$$

Therefore,  $v$  and  $w$  are defined to be **orthogonal** if and only if  $v^T w = 0$ .

**Think!** What can be said about  $\text{Span}\{v\}$  and  $\text{Span}\{w\}$  when  $v$  and  $w$  are orthogonal to each other in  $\mathbb{R}^3$ ?

# Orthogonal and Orthonormal Sets

**Defn.** A set of *non-zero* vectors  $\{v_1, \dots, v_k\} \subset \mathbb{R}^n$ , is said to be an **orthogonal set** if  $v_i^T v_j = 0$  for all  $i, j = 1, \dots, n$ ,  $i \neq j$ .

**Examples:**  $\{(1, 3, 1), (-1, 0, 1)\} \subset \mathbb{R}^3$ ,  
 $\{(2, 1, 0, -1), (0, 1, 0, 1), (-1, 1, 0, -1)\} \subseteq \mathbb{R}^4$ ,  
 $\{(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}), (\frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}})\} \subseteq \mathbb{R}^3$ ,  $\{e_1, \dots, e_n\} \subseteq \mathbb{R}^n$ .

Of these, the last two examples have all unit vectors (vectors of length one).

**Defn.** An orthogonal set  $\{v_1, \dots, v_k\} \subseteq \mathbb{R}^n$  with all unit vectors, i.e.,  $\|v_i\| = 1$  for all  $i$ , is called an **orthonormal set**.

**Note:** If  $\{v_1, \dots, v_k\}$  is an orthogonal set, then  $\{u_1, \dots, u_k\}$  is orthonormal, for  $u_i = v_i / \|v_i\|$ .

**Exercise:** If  $S = \{v_1, \dots, v_k\}$  is an orthogonal set, then  $v_k$  is orthogonal to each  $v \in \text{Span}\{v_1, \dots, v_{k-1}\}$ .

# Orthogonality and Linear Independence

**Theorem:** An orthogonal set in  $\mathbb{R}^n$  is linearly independent.

*Proof.* Let  $\{v_1, \dots, v_k\}$  be an orthogonal set in  $\mathbb{R}^n$ , i.e.  $v_i \neq 0$  and  $v_i^T v_j = 0$  for  $i \neq j$ . Note that for  $i = j$ ,  $v_i^T v_i = \|v_i\|^2 \neq 0$ . Assume for some  $a_1, \dots, a_k \in \mathbb{R}$ ,

$$\begin{aligned} a_1 v_1 + a_2 v_2 + \dots + a_k v_k &= 0 \\ \Rightarrow (a_1 v_1 + a_2 v_2 + \dots + a_k v_k)^T v_1 &= 0 \cdot v_1 = 0 \\ \Rightarrow (a_1 v_1^T + a_2 v_2^T + \dots + a_k v_k^T) v_1 &= 0 \\ \Rightarrow a_1 v_1^T v_1 + a_2 v_2^T v_1 + \dots + a_k v_k^T v_1 &= 0 \\ &\Rightarrow a_1 \|v_1\|^2 = 0 \\ &\Rightarrow a_1 = 0 \text{ since } v_1 \neq 0 \end{aligned}$$

Similarly, we get  $a_2 = \dots = a_n = 0$ . Hence  $\{v_1, \dots, v_k\}$  is linearly independent.

**True/False:** Any matrix whose columns form an orthogonal set is invertible. Give example

# Matrices with Orthogonal Columns

Let  $A = [v_1 \cdots v_n]$  be  $m \times n$ . If  $\{v_1, \dots, v_n\}$  form an *orthonormal* set in  $\mathbb{R}^m$ , then

$$A^T A = \begin{pmatrix} v_1^T \\ \vdots \\ v_n^T \end{pmatrix} (v_1 \cdots v_n) = \begin{pmatrix} v_1^T v_1 & \cdots & v_1^T v_n \\ \vdots & & \vdots \\ v_n^T v_1 & \cdots & v_n^T v_n \end{pmatrix} = I_n.$$

**Defn.** A square matrix  $A$  whose column vectors form an orthonormal set is called an **orthogonal** matrix.

If  $Q = [u_1 \cdots u_n]$  is an orthogonal matrix, then

- $\{u_1, \dots, u_n\}$  is an orthonormal set (by definition)
- $Q^T Q = I = Q Q^T$  Why?
- $\|Qv\| = \sqrt{(Qv)^T (Qv)} = \sqrt{v^T Q^T Q v} = \sqrt{v^T v} = \|v\|.$   
 $\Rightarrow$  the only (real) eigenvalues of  $Q$ , if they exist, are  $\pm 1$ .
- Row vectors of  $Q$  are orthonormal since  $Q Q^T = I$ .

# Orthogonal Matrices: Examples

**Examples:**

1.  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$
2.  $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}.$
3.  $\frac{1}{3} \begin{pmatrix} 2 & 1 & -2 \\ 2 & -2 & 1 \\ 1 & 2 & 2 \end{pmatrix}.$
4.  $\frac{1}{2} \begin{pmatrix} 1 & -1 & -1 & 1 \\ 1 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -1 & 1 & -1 & 1 \end{pmatrix}.$