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Room No. 1120

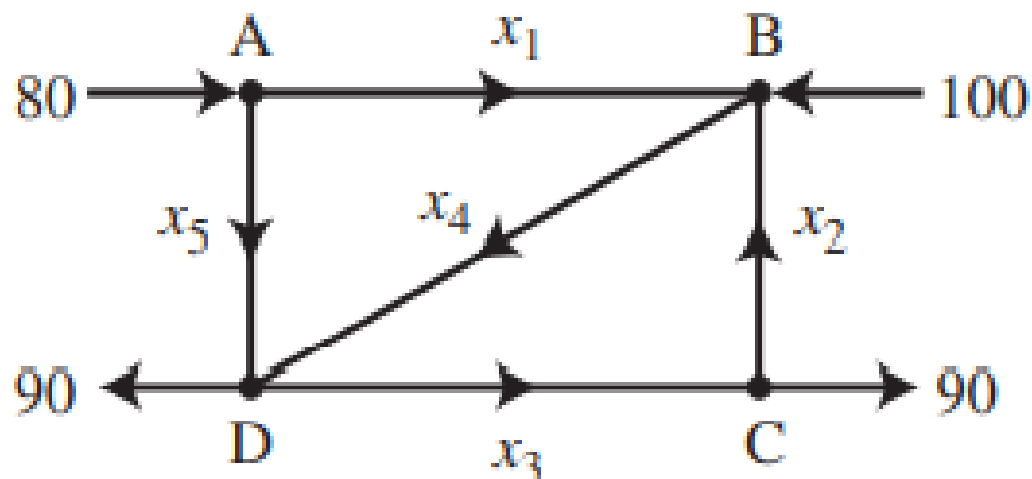
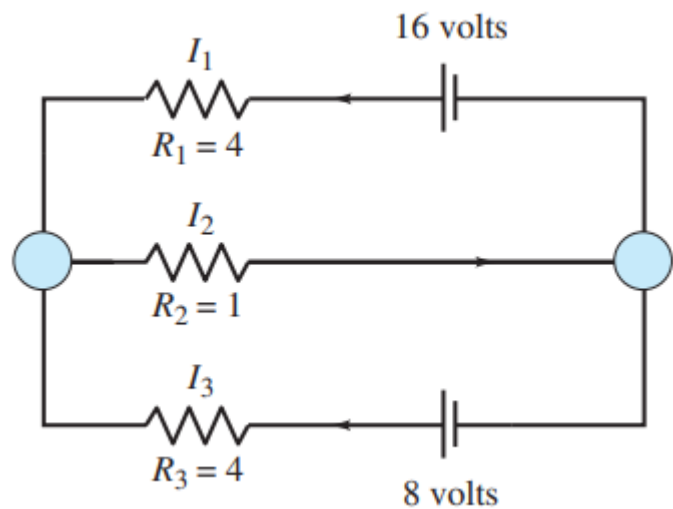
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Wassily Lontief ,
Harvard Professor

1973 Nobel Prize in
Economic Science

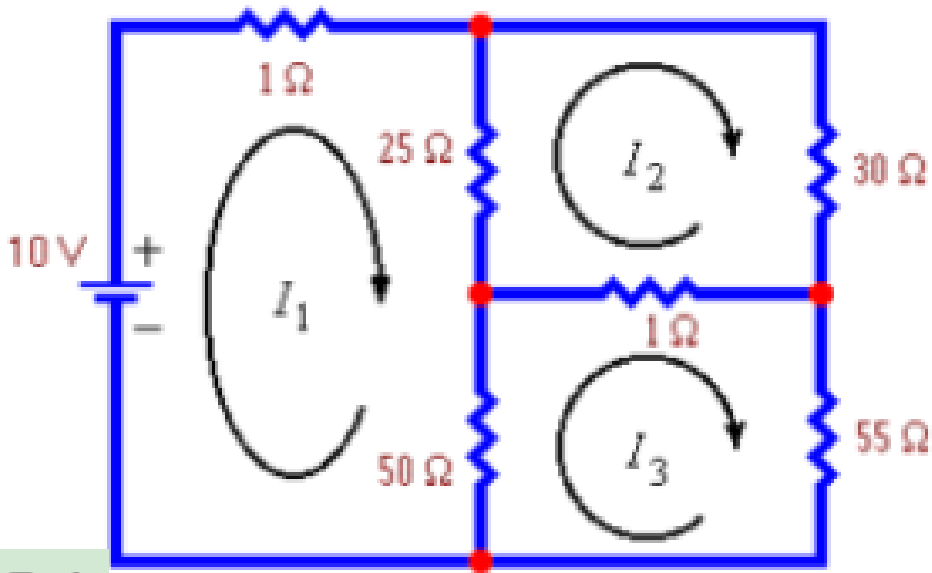


Uniform motion problems

	<i>Distance = Rate × Time</i>		
Travel by car	60 <i>x</i>	60 mph	<i>x</i>
Travel by air	350 <i>y</i>	350 mph	<i>y</i>
Total	1,930 mi		8 hours

$60x + 350y = 1,930$

$x + y = 8$



Stress analysis

Renting a car



	Jane	Charlie	Mary	Fred
<i>J</i>	0	1	1	1
<i>C</i>	1	0	1	0
<i>M</i>	1	1	0	1
<i>F</i>	0	1	1	0
Total	2	3	3	2

Application to Economics

Polynomial Interpolation



Mixture problems

Spring Mass Systems

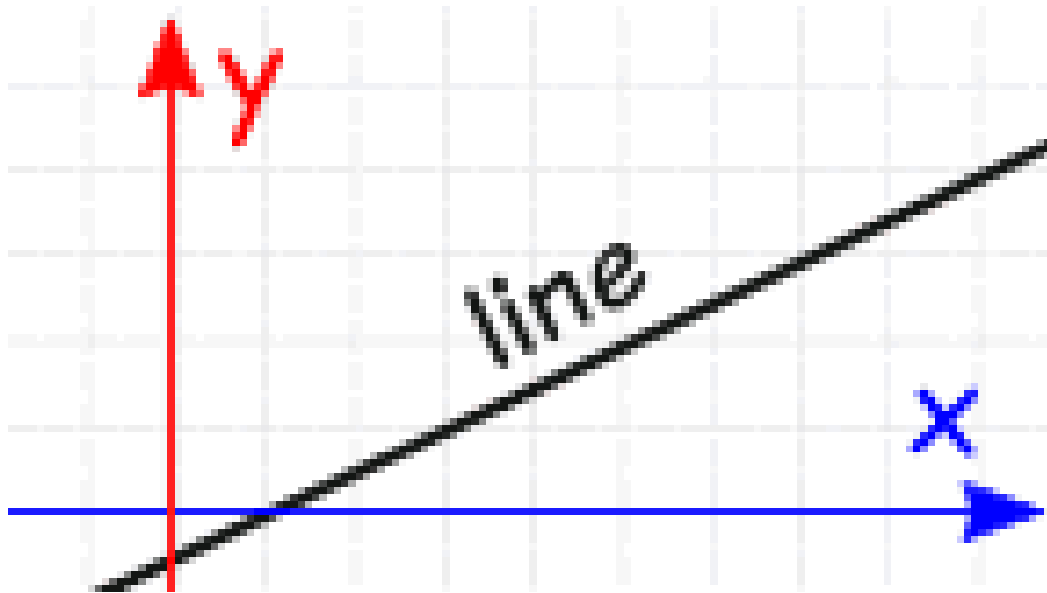
Aim

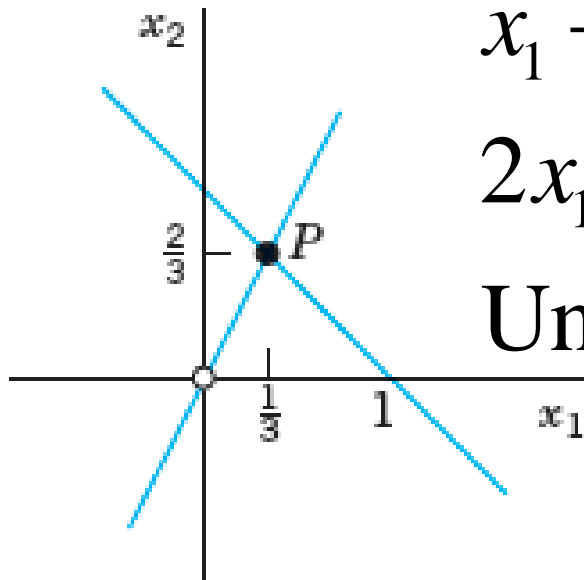
To Solve

System of Linear Equations

A **Linear Equation** can be in 2 dimensions (such as **x** and **y**)

$$ax + by = c$$

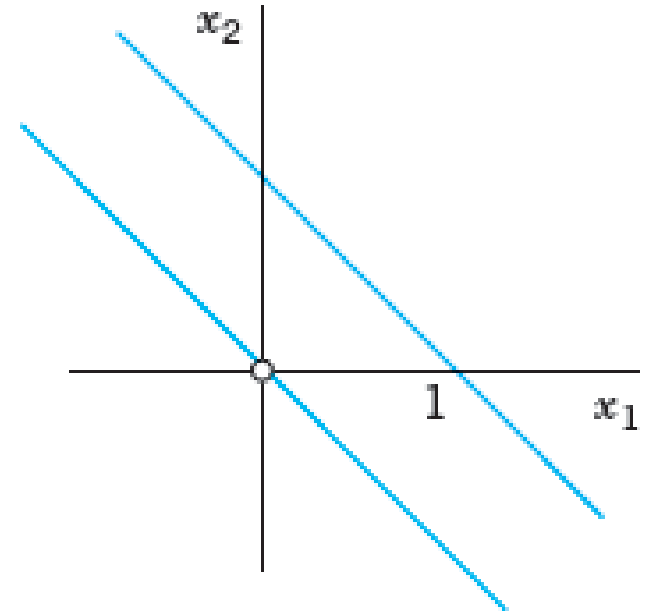




$$x_1 + x_2 = 1$$

$$2x_1 - x_2 = 0$$

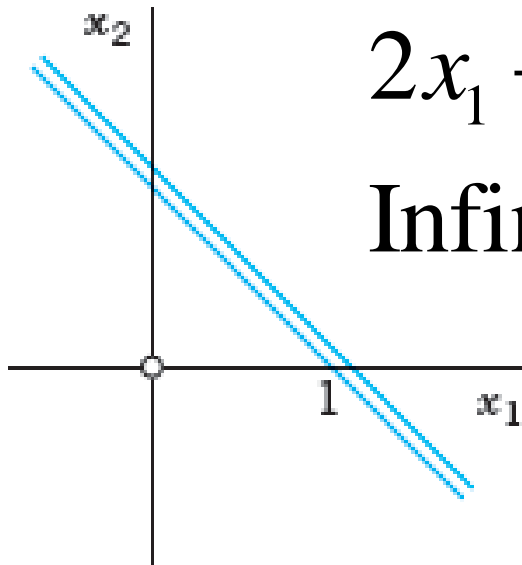
Unique soln



$$x_1 + x_2 = 1$$

$$2x_1 + 2x_2 = 2$$

Infinite soln

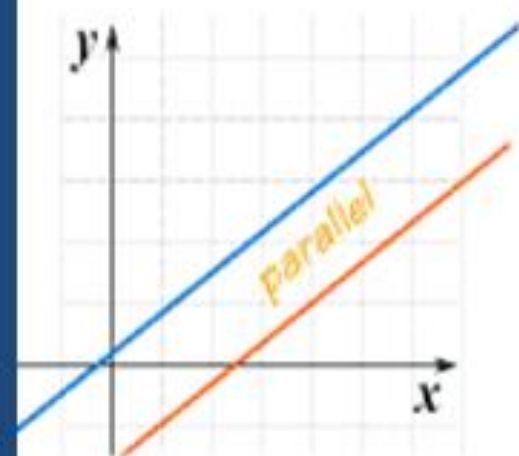


$$x_1 + x_2 = 1$$

$$x_1 + x_2 = 0$$

No soln

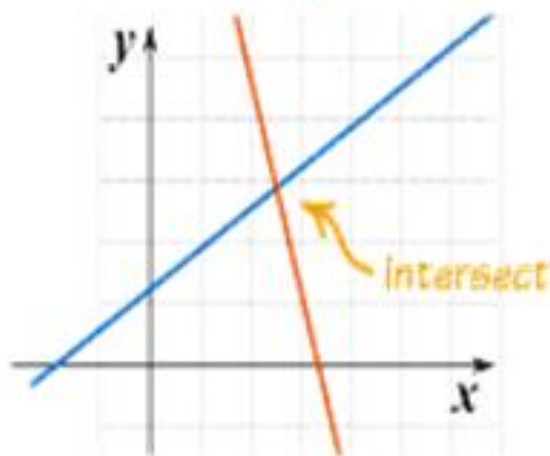
"Inconsistent"



No Solution

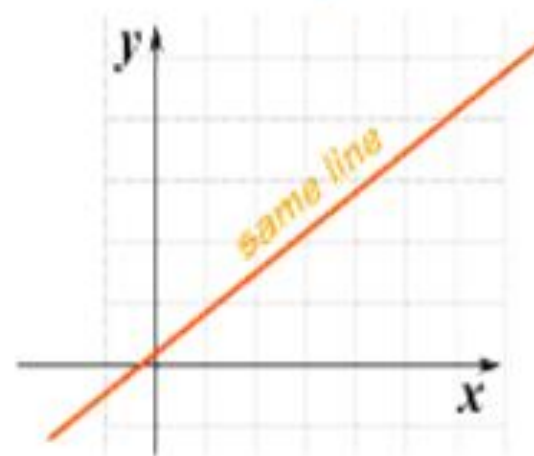
"Consistent"

"Independent"



One Solution

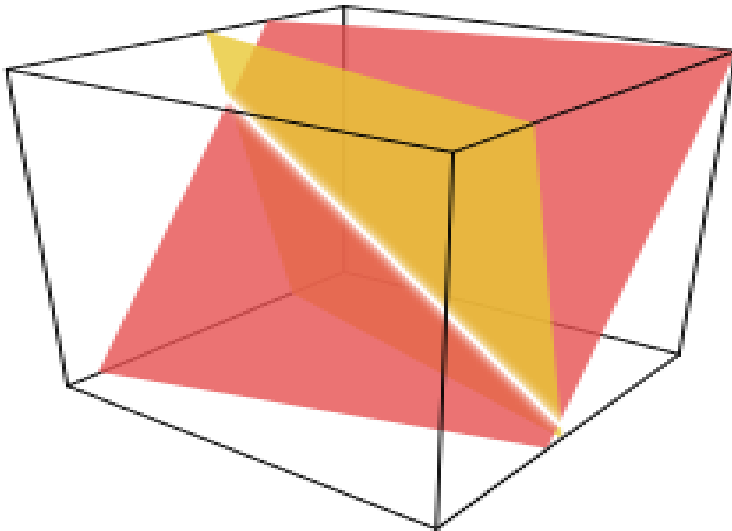
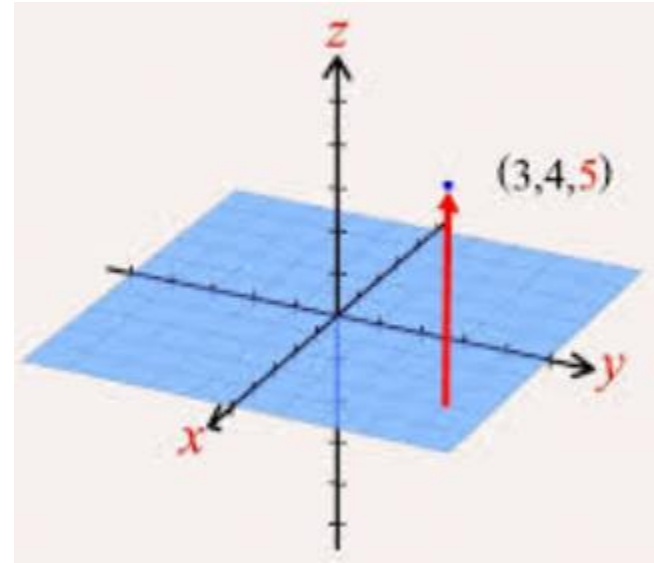
"Dependent"



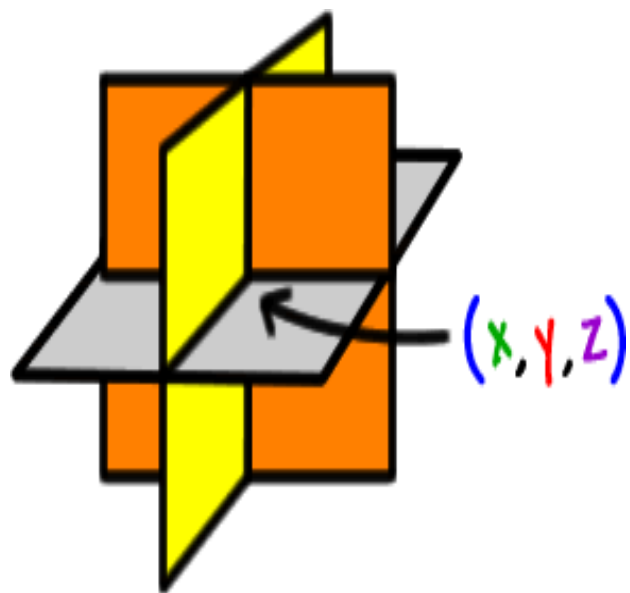
∞ Solutions

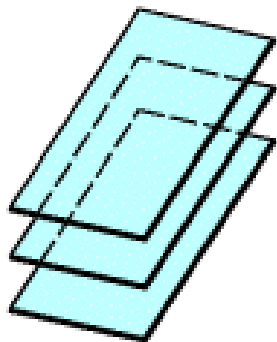
A **Linear Equation** can be in 3 dimensions
(such as **x**, **y** and **z**)

$$ax + by + cz = d$$

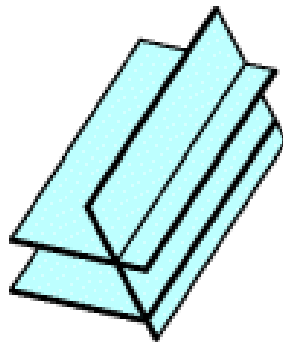


A linear system in three variables determines a collection of planes. The intersection point is the solution

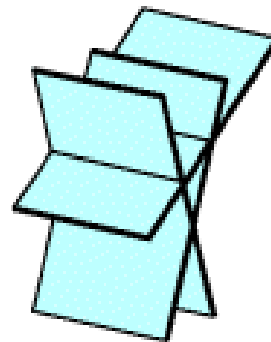




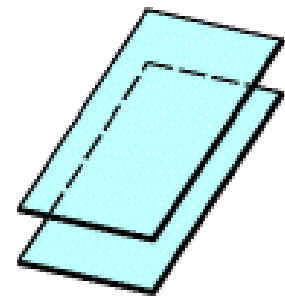
No solutions
(three parallel planes;
no common intersection)



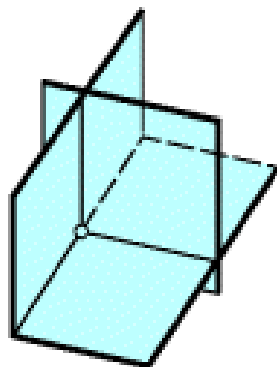
No solutions
(two parallel planes;
no common intersection)



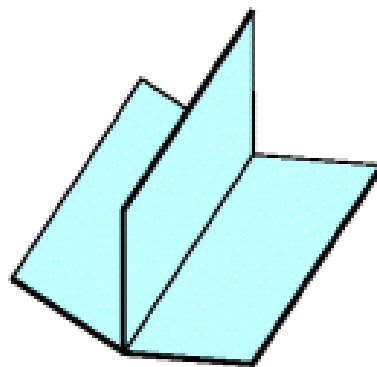
No solutions
(no common intersection)



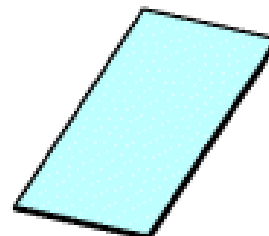
No solutions
(two coincident planes
parallel to the third;
no common intersection)



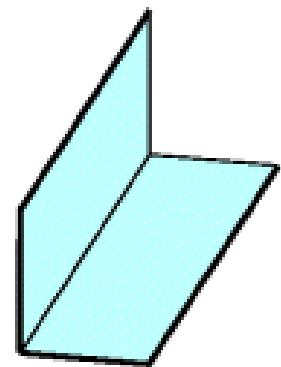
One solution
(intersection is a point)



Infinitely many solutions
(intersection is a line)

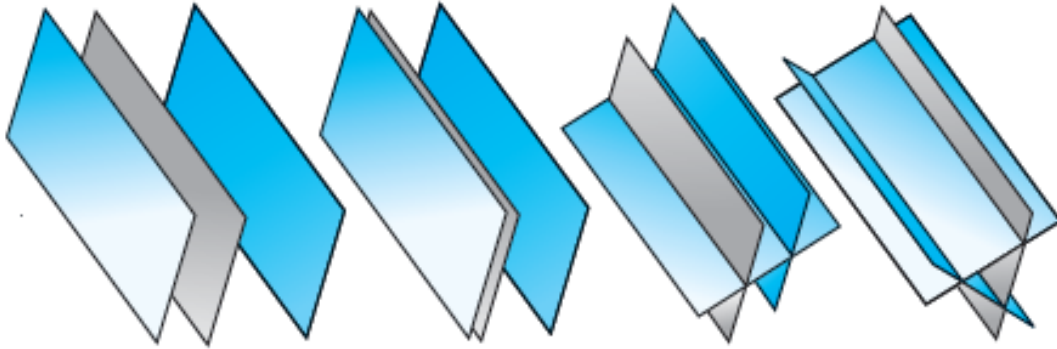


Infinitely many solutions
(planes are all coincident;
intersection is a plane)

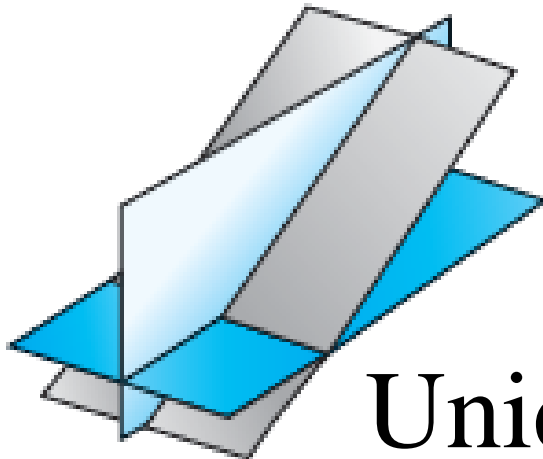
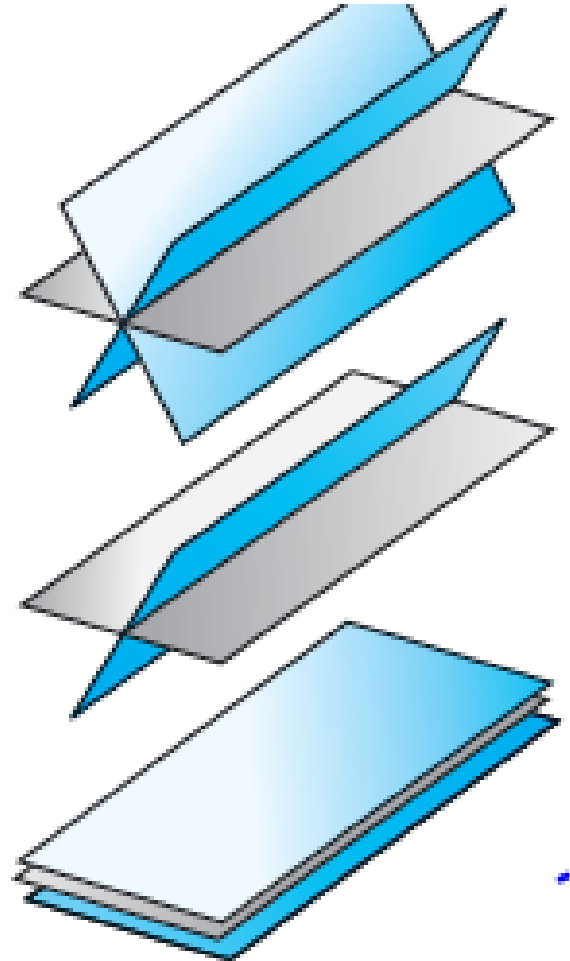


Infinitely many solutions
(two coincident planes;
intersection is a line)

No solution



Infinite soln



Unique soln

System of Linear Equations

Consider a system of m equations and n unknowns.

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

.....

.....

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

The above system of equation can be written in the matrix form as $AX=B$

$$A = [a_{ij}]_{m \times n}$$

$$= \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{m \times n} \rightarrow \begin{matrix} \text{coefficient} \\ \text{matrix} \end{matrix}$$

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \rightarrow \begin{matrix} \text{Matrix of} \\ \text{unknowns} \end{matrix} \quad B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}_{m \times 1} \rightarrow \begin{matrix} \text{Matrix of} \\ \text{constants} \end{matrix}$$

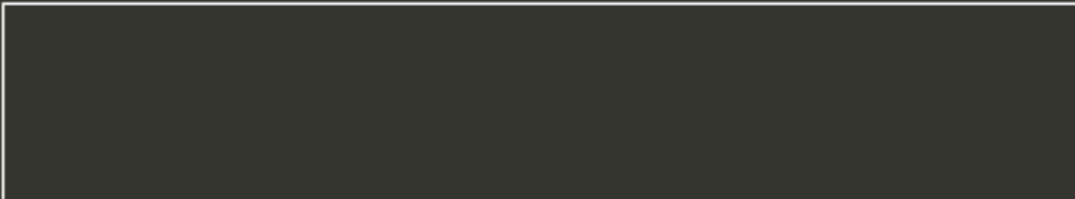
A solution of the system is a list (s_1, s_2, \dots, s_n) of numbers that satisfies each and every equation when the values s_1, s_2, \dots, s_n are substituted for x_1, x_2, \dots, x_n .

The set of all possible solutions is called the solution set of the linear system.

Two linear systems are called equivalent if they have the same solution set.

Classification

$$A X = B$$


$$B=0$$

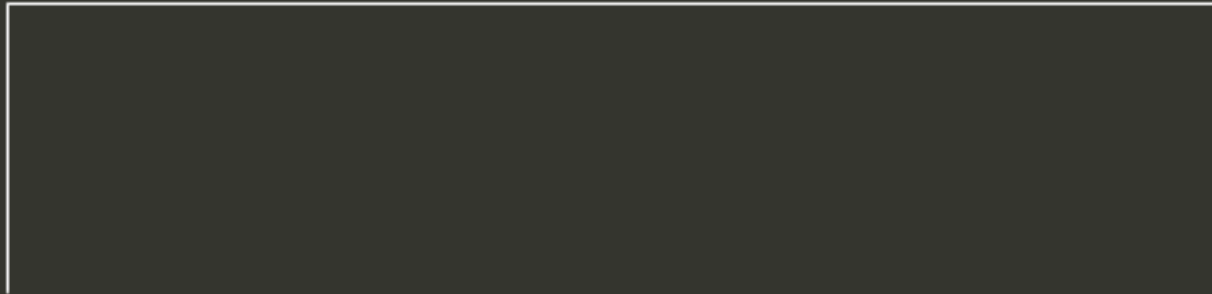
Homogeneous
System

$$B \neq 0$$

Non-homogeneous
System

Homogeneous System

Always Consistent



$\rho(A)$ = number of unknowns

UNIQUE SOLUTION

$X=0$

Trivial Solution

Less than

$\rho(A) < \text{number of unknowns}$

An **INFINITE** number

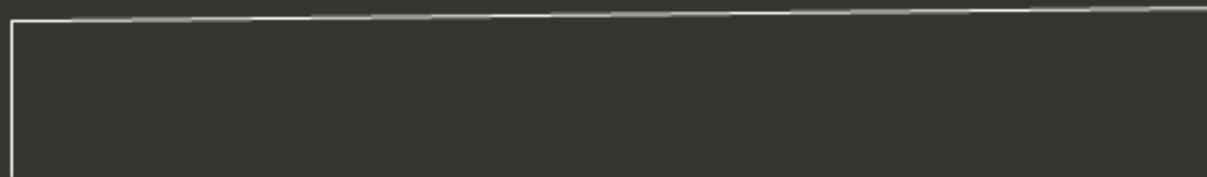
of solutions

Non-Trivial Solution

Augmented Matrix: denoted as $(A \mid B)$
is the matrix obtained by attaching additional
column B to matrix A . $[A : B] = [a_{ij} : b_i]_{m \times (n+1)}$

Non-homogeneous System

- ◆ Not always consistent



$$\rho(A | B) = \rho(A)$$

Consistent
System

$$\rho(A | B) \neq \rho(A)$$

Inconsistent
System

Consistent non-homogeneous system

* $\rho(A \ B) = \rho(A) = \text{the number of unknowns}$

System possess a **UNIQUE** solution

* $\rho(A \ B) = \rho(A) < \text{the number of unknowns}$

System has an **INFINITE** number of solutions

Inconsistent Non-homogeneous system

$$\rho(A \ B) \neq \rho(A).$$

*System has **NO** solution.*

The behavior of a linear system is determined by the relationship between the number of equations (m) and the number of unknowns (n):

➤ A system with fewer equations than unknowns has no solution then the system is known as a **underdetermined system**.

➤ Usually, a system with the same number of equations and unknowns has a single unique solution.

➤ Usually, a system with more equations than unknowns has no solution. Such a system is also known as an **overdetermined** system.

Summary

$\rho[A : B] = \rho[A] = r$ (say) \Rightarrow the system is always consistent

If $\rho[A : B] = \rho[A] = r = n$ (number of unknowns)
 \Rightarrow the system has a unique solution.

In case of homogeneous system, unique solution is a **Trivial solution**.

$r < n \Rightarrow$ the system has infinite number of solutions.

$r < n \Rightarrow n - r$ variables are “free variables.”

Non-pivot variable is considered as a free variable

If x_p is a particular solution of the nonhomogeneous system $AX=B$ then every solution of this system can be written in the form $x = x_p + x_h$ where x_h is a solution of the corresponding homogeneous system $AX=0$.

Observations :

1. If $AX = 0$, is such that A is $n \times n$ matrix, *i.e.*, we have n – equations in n – unknowns, then system will have

a) nontrivial solution also iff $|A| = \det(A) = 0$.

b) Trivial solution only iff $|A| = \det(A) \neq 0$.

2. For $A_{m \times n} X = 0$, and if $m < n$, then always have non-trivial solution also and there are at least $n - m$ variables are free.

Observations :

1. If $AX = 0$, is such that A is $n \times n$ matrix, *i.e.*, we have n – equations in n – unknowns, then system will have
 - a) nontrivial solution also iff $|A| = \det(A) = 0$.
 - b) Trivial solution only iff $|A| = \det(A) \neq 0$.
2. For $A_{m \times n} X = 0$, and if $m < n$, then always have non-trivial solution also (in this case at least $n - m$ variables are free).
3. If $AX = B$, $B \neq 0$ is such that A is $n \times n$ matrix, *i.e.*, we have n – equations in n – unknowns, then system will have unique solution iff $|A| = \det(A) \neq 0$ and the unique solution is $X = A^{-1}B$.

Rank of a Matrix

Let $A_{m \times n}$ be any matrix, $r \geq 0$ is said to be rank of the matrix A denoted as $\rho(A)$ if the matrix has

1. at least one non-zero minor of order ' r '
2. all the minors of order ' $r+1$ ' are zero

OR

The order of highest order non-vanishing minor is the rank of the matrix.

OR

The order of highest order non-zero determinant present in in the matrix is the rank of the matrix.

Theorem: Elementary transformations do not alter the rank of the matrix.

Echelon Form (Row reduced form)

(To reduce a matrix into an Echelon form, only row transformations are permitted.)

1. The first non-zero element in each row, called the **leading entry**, is 1.
2. All elements below the leading element are zero.
3. Each leading entry is in a column to the right of the leading entry in the previous row.
4. Rows with all zero elements, if any, are below rows having a non-zero element.

pivot elements

$$\left[\begin{array}{ccccc}
 \textcircled{1} & 2 & 3 & 5 & -7 \\
 \hline
 0 & 0 & \textcircled{1} & -2 & 5 \\
 \hline
 0 & 0 & 0 & \textcircled{1} & -2 \\
 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0
 \end{array} \right]_{6 \times 5}$$

Leading entry – First non-zero element in a row called as leading entry or **pivot element**.

Pivot elements are the elements whose position should not be altered by application of row transformations.

If matrix A is in Echelon form then, rank of A ,
 $\rho(A)$ = number of non-zero rows in Echelon form.

Equivalent Matrices : - A matrix B is said to be an equivalent matrix of matrix A , shown as $B \sim A$ if and only if B is obtained by applying elementary transformations on A .

$$\text{Example 1. } A = \begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & 2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

$$R_1 : R_1 + R_4 \Rightarrow A \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ -1 & 2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

$$R_2 + R_1, R_3 + 2R_1, R_4 - R_1 \Rightarrow \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & 3 & -2 & -2 & 3 \\ 0 & -1 & -2 & -7 & 3 \\ 0 & 3 & 6 & -4 & -9 \end{bmatrix}$$

$$R_{23} \Rightarrow \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & -1 & -2 & -7 & 3 \\ 0 & 3 & -2 & -2 & 3 \\ 0 & 3 & 6 & -4 & -9 \end{bmatrix}$$

$$-R_2 \Rightarrow \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & 1 & 2 & 7 & -3 \\ 0 & 3 & -2 & -2 & 3 \\ 0 & 3 & 6 & -4 & -9 \end{bmatrix}$$

$$R_3 - 3R_2, R_4 - 3R_2 \Rightarrow \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & 1 & 2 & 7 & -3 \\ 0 & 0 & -8 & -23 & 12 \\ 0 & 0 & 0 & -25 & 0 \end{bmatrix}$$

$$-\frac{1}{8}R_3 \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & 1 & 2 & 7 & -3 \\ 0 & 0 & 1 & 23/8 & -12/8 \\ 0 & 0 & 0 & -25 & 0 \end{bmatrix}$$

$$-\frac{1}{25}R_4 \sim \begin{bmatrix} 1 & 1 & -1 & -5 & 2 \\ 0 & 1 & 2 & 7 & -3 \\ 0 & 0 & 1 & 23/8 & -12/8 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$



Consider, $A = \begin{bmatrix} 1 & -1 & 3 & 0 \\ 2 & 3 & 1 & 5 \\ 2 & -2 & h & 0 \end{bmatrix}$. What is the value of h

for which rank of A , i) $\rho(A) > 2$ ii) $\rho(A) < 3$

iii) Is there any real value of h , for which $\rho(A) = 1$?

$$A = \begin{bmatrix} 1 & -1 & 3 & 0 \\ 2 & 3 & 1 & 5 \\ 2 & -2 & h & 0 \end{bmatrix} \xrightarrow{R_2 - 2R_1, R_3 - 2R_1} \begin{bmatrix} 1 & -1 & 3 & 0 \\ 0 & 5 & -5 & 5 \\ 0 & 0 & h-6 & 0 \end{bmatrix}$$

i) If $h - 6 \neq 0 \Rightarrow$ No. of non zero rows in Echelon form = 3
Hence $\rho(A)=3$.

ii) If $h - 6 = 0 \Rightarrow$ No. of non zero rows in Echelon form = 2
Hence $\rho(A)=2$.

iii) There is no real value of h , for which $\rho(A)=1$.

$$A = \begin{bmatrix} 3 & 2 & 5 & 7 & 12 \\ 1 & 1 & 2 & 3 & 5 \\ 3 & 3 & 6 & 9 & 15 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2 \Rightarrow \begin{bmatrix} 1 & 1 & 2 & 3 & 5 \\ 3 & 2 & 5 & 7 & 12 \\ 3 & 3 & 6 & 9 & 15 \end{bmatrix} R_2 - 3R_1, R_3 - 3R_1 \Rightarrow$$

$$\begin{bmatrix} 1 & 1 & 2 & 3 & 5 \\ 0 & -1 & -1 & 1 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \therefore \rho(A) = 2$$

