

```
%%%%%%%%%%%% Newton's Method Implementation %%%%%%%%%%%%%%
%%%%%%%%%%%% By Max Yi Ren and Emrah Bayrak %%%%%%%%%%%%%%
```

```
function solution = newton(f,g,H,x0,opt)
    % Set initial conditions
    x = x0; % Set current solution to the initial guess
    iter = 0; % Set iteration counter to 0
    solution.x([1,2],1) = x;
    % Calculate the norm of the gradient
    gnorm = norm(g(x),2);

    while gnorm>opt.eps % if not terminated
        iter = iter + 1;

        % opt.linesearch switches line search on or off.
        % You can first set the variable "a" to different constant values and see how
it % affects the convergence.
        if opt.linesearch
            a = lineSearch1(f,g,H,x,opt);
        else
            a = 0.001;
        end

        % Newton's method:
        x = x - a*inv(H(x))*g(x);

        % save current step
        solution.x([1,2],iter+1) = x;

        % Update termination criterion:
        gnorm = norm(g(x),2);
    end
    disp(x);
    disp(iter);
```