

Mathematics-II (MATH F112)

Linear Algebra

Jitender Kumar

Department of Mathematics
Birla Institute of Technology and Science Pilani
Pilani-333031



Chapter: 5 (Linear Transformations)

- 1 Introduction to Linear Transformations
- 2 The Dimension Theorem
- 3 One-to-One and Onto Linear Transformations
- 4 Isomorphism
- 5 Coordinatization (4.7)
- 6 The Matrix of a Linear Transformation



Section 5.1: Linear Transformations

Let \mathcal{V} and \mathcal{W} be real vector spaces.



Section 5.1: Linear Transformations

Let \mathcal{V} and \mathcal{W} be real vector spaces. A map $L : \mathcal{V} \rightarrow \mathcal{W}$ is called a **Linear map** or **Linear transformation (LT)**



Section 5.1: Linear Transformations

Let \mathcal{V} and \mathcal{W} be real vector spaces. A map $L : \mathcal{V} \rightarrow \mathcal{W}$ is called a **Linear map** or **Linear transformation (LT)** if and only if both of the following are true:



Section 5.1: Linear Transformations

Let \mathcal{V} and \mathcal{W} be real vector spaces. A map $L : \mathcal{V} \rightarrow \mathcal{W}$ is called a **Linear map** or **Linear transformation (LT)** if and only if both of the following are true:

- $L(\mathbf{u} + \mathbf{v}) = L(\mathbf{u}) + L(\mathbf{v})$ for all $\mathbf{u}, \mathbf{v} \in \mathcal{V}$



Section 5.1: Linear Transformations

Let \mathcal{V} and \mathcal{W} be real vector spaces. A map $L : \mathcal{V} \rightarrow \mathcal{W}$ is called a **Linear map** or **Linear transformation (LT)** if and only if both of the following are true:

- $L(\mathbf{u} + \mathbf{v}) = L(\mathbf{u}) + L(\mathbf{v})$ for all $\mathbf{u}, \mathbf{v} \in \mathcal{V}$
- $L(c\mathbf{u}) = cL(\mathbf{u})$ for all $c \in \mathbb{R}$ and all $\mathbf{u} \in \mathcal{V}$



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$

Check whether L is a LT.



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$

Check whether L is a LT.

Solution: Let $A, B \in \mathcal{M}_{mn}$ and $c \in \mathbb{R}$. Note that



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$

Check whether L is a LT.

Solution: Let $A, B \in \mathcal{M}_{mn}$ and $c \in \mathbb{R}$. Note that

- $L(A + B) = (A + B)^T = A^T + B^T = L(A) + L(B)$



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$

Check whether L is a LT.

Solution: Let $A, B \in \mathcal{M}_{mn}$ and $c \in \mathbb{R}$. Note that

- $L(A + B) = (A + B)^T = A^T + B^T = L(A) + L(B)$
- $L(cA) = (cA)^T = cA^T = cL(A).$



Example 1: For $A \in M_{mn}$, consider the mapping

$L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by

$$L(A) = A^T.$$

Check whether L is a LT.

Solution: Let $A, B \in \mathcal{M}_{mn}$ and $c \in \mathbb{R}$. Note that

- $L(A + B) = (A + B)^T = A^T + B^T = L(A) + L(B)$
- $L(cA) = (cA)^T = cA^T = cL(A)$.

Hence, L is a LT.



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.

Solution: For $c = 2 \in \mathbb{R}$ and $[1, 2] \in \mathbb{R}^2$ consider



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.

Solution: For $c = 2 \in \mathbb{R}$ and $[1, 2] \in \mathbb{R}^2$ consider

$$L(2([1, 2])) = L([2, 4])$$



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.

Solution: For $c = 2 \in \mathbb{R}$ and $[1, 2] \in \mathbb{R}^2$ consider

$$\begin{aligned} L(2([1, 2])) &= L([2, 4]) \\ &= [2, 4, 8] \neq 2L([1, 2]) \end{aligned}$$



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.

Solution: For $c = 2 \in \mathbb{R}$ and $[1, 2] \in \mathbb{R}^2$ consider

$$\begin{aligned} L(2([1, 2])) &= L([2, 4]) \\ &= [2, 4, 8] \neq 2L([1, 2]) \end{aligned}$$

Thus, $L(c([x, y])) \neq cL([x, y]) \forall c \in \mathbb{R}$ and $[x, y] \in \mathbb{R}^2$



Example 2: For each $[x, y] \in \mathbb{R}^2$, consider a map

$L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by

$$L([x, y]) = [x, y, xy].$$

Check whether L is a LT.

Solution: For $c = 2 \in \mathbb{R}$ and $[1, 2] \in \mathbb{R}^2$ consider

$$\begin{aligned} L(2([1, 2])) &= L([2, 4]) \\ &= [2, 4, 8] \neq 2L([1, 2]) \end{aligned}$$

Thus, $L(c([x, y])) \neq cL([x, y]) \forall c \in \mathbb{R}$ and $[x, y] \in \mathbb{R}^2$

Hence, L is not a LT.



Exercise: Check which of the following maps are LT.



Exercise: Check which of the following maps are LT.

1 $L : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ given by $L(a + bx + cx^2) = [a, b, c]$.



Exercise: Check which of the following maps are LT.

- 1 $L : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ given by $L(a + bx + cx^2) = [a, b, c]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by $L([x, y, z]) = [x - y, y + z]$.



Exercise: Check which of the following maps are LT.

- 1 $L : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ given by $L(a + bx + cx^2) = [a, b, c]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by $L([x, y, z]) = [x - y, y + z]$.
- 3 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $L([a, b]) = [a, -b]$.



Exercise: Check which of the following maps are LT.

- 1 $L : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ given by $L(a + bx + cx^2) = [a, b, c]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by $L([x, y, z]) = [x - y, y + z]$.
- 3 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $L([a, b]) = [a, -b]$.
- 4 $L : \mathbb{R} \rightarrow \Phi$ given by $L(x) = \sin x$.



Exercise: Check which of the following maps are LT.

- 1 $L : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ given by $L(a + bx + cx^2) = [a, b, c]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given by $L([x, y, z]) = [x - y, y + z]$.
- 3 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by $L([a, b]) = [a, -b]$.
- 4 $L : \mathbb{R} \rightarrow \Phi$ given by $L(x) = \sin x$.
- 5 $L : \mathbb{R} \rightarrow \mathbb{R}$ given by $L(x) = x^2$.



Linear Operator: Let \mathcal{V} be a vector space.



Linear Operator: Let \mathcal{V} be a vector space. A **linear operator** on \mathcal{V} is a LT whose domain and codomain are both \mathcal{V} .



Linear Operator: Let \mathcal{V} be a vector space. A **linear operator** on \mathcal{V} is a LT whose domain and codomain are both \mathcal{V} .

Example 3: The mapping $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $L([x, y, z]) = [x, y, -z]$ is a linear operator.



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT.



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then

1 $L(\mathbf{0}_{\mathcal{V}}) = \mathbf{0}_{\mathcal{W}}$



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then

1 $L(\mathbf{0}_{\mathcal{V}}) = \mathbf{0}_{\mathcal{W}}$

2 $L(-\mathbf{v}) = -L(\mathbf{v})$, for all $\mathbf{v} \in \mathcal{V}$



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then

- 1 $L(\mathbf{0}_{\mathcal{V}}) = \mathbf{0}_{\mathcal{W}}$
- 2 $L(-\mathbf{v}) = -L(\mathbf{v})$, for all $\mathbf{v} \in \mathcal{V}$
- 3 For $n \geq 2$ and $a_1, a_2, \dots, a_n \in \mathbb{R}$,

If $\mathbf{v} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \dots + a_n\mathbf{v}_n$, then



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then

- 1 $L(\mathbf{0}_{\mathcal{V}}) = \mathbf{0}_{\mathcal{W}}$
- 2 $L(-\mathbf{v}) = -L(\mathbf{v})$, for all $\mathbf{v} \in \mathcal{V}$
- 3 For $n \geq 2$ and $a_1, a_2, \dots, a_n \in \mathbb{R}$,

If $\mathbf{v} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \dots + a_n\mathbf{v}_n$, then
$$L(\mathbf{v}) = L(a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \dots + a_n\mathbf{v}_n)$$



Theorem 1: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Suppose $\mathbf{0}_{\mathcal{V}}$ be the zero vector in \mathcal{V} and $\mathbf{0}_{\mathcal{W}}$ be the zero vector in \mathcal{W} . Then

- 1 $L(\mathbf{0}_{\mathcal{V}}) = \mathbf{0}_{\mathcal{W}}$
- 2 $L(-\mathbf{v}) = -L(\mathbf{v})$, for all $\mathbf{v} \in \mathcal{V}$
- 3 For $n \geq 2$ and $a_1, a_2, \dots, a_n \in \mathbb{R}$,

$$\begin{aligned} \text{If } \mathbf{v} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \cdots + a_n\mathbf{v}_n, \text{ then} \\ L(\mathbf{v}) &= L(a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \cdots + a_n\mathbf{v}_n) \\ &= a_1L(\mathbf{v}_1) + a_2L(\mathbf{v}_2) + \cdots + a_nL(\mathbf{v}_n). \end{aligned}$$



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:

$$[-3, 2, 4] = -3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1]$$



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:

$$\begin{aligned} [-3, 2, 4] &= -3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1] \\ L([-3, 2, 4]) &= L(-3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1]) \end{aligned}$$



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$,
 $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:

$$\begin{aligned} [-3, 2, 4] &= -3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1] \\ L([-3, 2, 4]) &= L(-3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1]) \\ &= -3L([1, 0, 0]) + 2L([0, 1, 0]) + 4L([0, 0, 1]) \end{aligned}$$



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$, $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:

$$\begin{aligned} [-3, 2, 4] &= -3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1] \\ L([-3, 2, 4]) &= L(-3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1]) \\ &= -3L([1, 0, 0]) + 2L([0, 1, 0]) + 4L([0, 0, 1]) \\ &= -3[-2, 1, 0] + 2[3, -2, 1] + 4[0, -1, 3] \end{aligned}$$



Example 4: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear operator such that $L([1, 0, 0]) = [-2, 1, 0]$, $L([0, 1, 0]) = [3, -2, 1]$, and $L([0, 0, 1]) = [0, -1, 3]$.

- Find $L([-3, 2, 4])$.
- Find $L([x, y, z])$ for all $[x, y, z]$ in \mathbb{R}^3 .

Solution:

$$\begin{aligned} [-3, 2, 4] &= -3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1] \\ L([-3, 2, 4]) &= L(-3[1, 0, 0] + 2[0, 1, 0] + 4[0, 0, 1]) \\ &= -3L([1, 0, 0]) + 2L([0, 1, 0]) + 4L([0, 0, 1]) \\ &= -3[-2, 1, 0] + 2[3, -2, 1] + 4[0, -1, 3] \\ &= [12, 11, 14] \end{aligned}$$



Similarly,

$$L([x, y, z]) = L(x[1, 0, 0] + y[0, 1, 0] + z[0, 0, 1])$$



Similarly,

$$L([x, y, z]) = L(x[1, 0, 0] + y[0, 1, 0] + z[0, 0, 1])$$

$$L([x, y, z]) = x[-2, 1, 0] + y[3, -2, 1] + z[0, -1, 3]$$



Similarly,

$$L([x, y, z]) = L(x[1, 0, 0] + y[0, 1, 0] + z[0, 0, 1])$$

$$L([x, y, z]) = x[-2, 1, 0] + y[3, -2, 1] + z[0, -1, 3]$$

$$L([x, y, z]) = [-2x + 3y, x - 2y - z, y + 3z]$$



Similarly,

$$L([x, y, z]) = L(x[1, 0, 0] + y[0, 1, 0] + z[0, 0, 1])$$

$$L([x, y, z]) = x[-2, 1, 0] + y[3, -2, 1] + z[0, -1, 3]$$

$$L([x, y, z]) = [-2x + 3y, x - 2y - z, y + 3z]$$

Note that

$$L\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -2 & 3 & 0 \\ 1 & -2 & -1 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



Exercise: Suppose $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear operator and $L([1, 1]) = [3, 0]$ and $L([-1, 1]) = [0, 1]$. Find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.



Exercise: Suppose $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear operator and $L([1, 1]) = [3, 0]$ and $L([-1, 1]) = [0, 1]$. Find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.

Answer: $L([x, y]) = \left[\frac{3x+3y}{2}, \frac{-x+y}{2} \right]$.



Exercise: Suppose $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear operator and $L([1, 1]) = [3, 0]$ and $L([-1, 1]) = [0, 1]$. Find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.

Answer: $L([x, y]) = \left[\frac{3x+3y}{2}, \frac{-x+y}{2} \right]$.

Remark: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Also, let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be a basis for \mathcal{V} .



Exercise: Suppose $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear operator and $L([1, 1]) = [3, 0]$ and $L([-1, 1]) = [0, 1]$. Find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.

Answer: $L([x, y]) = \left[\frac{3x+3y}{2}, \frac{-x+y}{2} \right]$.

Remark: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Also, let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be a basis for \mathcal{V} . If $\mathbf{v} \in \mathcal{V}$, $L(\mathbf{v})$ is completely determined by $\{L(\mathbf{v}_1), L(\mathbf{v}_2), \dots, L(\mathbf{v}_n)\}$.



Composition of Linear transformations



Composition of Linear transformations

Theorem 2: Let \mathcal{V}_1 , \mathcal{V}_2 and \mathcal{V}_3 be vector spaces and let $L_1 : \mathcal{V}_1 \rightarrow \mathcal{V}_2$ and $L_2 : \mathcal{V}_2 \rightarrow \mathcal{V}_3$ be linear transformations. Then $L_2 \circ L_1 : \mathcal{V}_1 \rightarrow \mathcal{V}_3$ given by $(L_2 \circ L_1)(\mathbf{v}) = L_2(L_1(\mathbf{v}))$, for all $\mathbf{v} \in \mathcal{V}_1$, is a LT.



Example 5: Let $L_1 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ and $L_2 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be linear operators defined as $L_1(ax^2 + bx + c) = 2ax + b$ and $L_2(ax^2 + bx + c) = 2ax^2 + bx$, respectively.



Example 5: Let $L_1 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ and $L_2 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be linear operators defined as $L_1(ax^2 + bx + c) = 2ax + b$ and $L_2(ax^2 + bx + c) = 2ax^2 + bx$, respectively. Compute $L_2 \circ L_1$ and $L_1 \circ L_2$.



Example 5: Let $L_1 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ and $L_2 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be linear operators defined as $L_1(ax^2 + bx + c) = 2ax + b$ and $L_2(ax^2 + bx + c) = 2ax^2 + bx$, respectively. Compute $L_2 \circ L_1$ and $L_1 \circ L_2$.

Answer:

- $L_2 \circ L_1(ax^2 + bx + c) = 2ax.$



Example 5: Let $L_1 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ and $L_2 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be linear operators defined as $L_1(ax^2 + bx + c) = 2ax + b$ and $L_2(ax^2 + bx + c) = 2ax^2 + bx$, respectively. Compute $L_2 \circ L_1$ and $L_1 \circ L_2$.

Answer:

- $L_2 \circ L_1(ax^2 + bx + c) = 2ax.$
- $L_1 \circ L_2(ax^2 + bx + c) = 4ax + b.$



Example 5: Let $L_1 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ and $L_2 : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be linear operators defined as $L_1(ax^2 + bx + c) = 2ax + b$ and $L_2(ax^2 + bx + c) = 2ax^2 + bx$, respectively. Compute $L_2 \circ L_1$ and $L_1 \circ L_2$.

Answer:

- $L_2 \circ L_1(ax^2 + bx + c) = 2ax.$
- $L_1 \circ L_2(ax^2 + bx + c) = 4ax + b.$

Clearly, $L_2 \circ L_1 \neq L_1 \circ L_2.$



Section 5.3: The Dimension Theorem

Kernel of a linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT.



Section 5.3: The Dimension Theorem

Kernel of a linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **kernel** of L , denoted by $\ker(L)$,



Section 5.3: The Dimension Theorem

Kernel of a linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **kernel** of L , denoted by $\ker(L)$, is the subset of all vectors in \mathcal{V} that map to $\mathbf{0}_{\mathcal{W}}$, i.e.



Section 5.3: The Dimension Theorem

Kernel of a linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **kernel** of L , denoted by $\ker(L)$, is the subset of all vectors in \mathcal{V} that map to $\mathbf{0}_{\mathcal{W}}$, i.e.

$$\ker(L) = \{\mathbf{v} \in \mathcal{V} \mid L(\mathbf{v}) = \mathbf{0}_{\mathcal{W}}\}.$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$.



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\ker(L) = \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\}$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [0, y] = [0, 0]\}\end{aligned}$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [0, y] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid y = 0\}\end{aligned}$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [0, y] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid y = 0\} \\ &= \{[x, 0, z] \mid x, z \in \mathbb{R}\}\end{aligned}$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [0, y] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid y = 0\} \\ &= \{[x, 0, z] \mid x, z \in \mathbb{R}\}\end{aligned}$$

In this Example, **Note that**

$$\ker(L) = \{[x, 0, z] \mid x, z \in \mathbb{R}\}$$



Example 6: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by $L([x, y, z]) = [0, y]$. Find $\ker(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [0, y] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid y = 0\} \\ &= \{[x, 0, z] \mid x, z \in \mathbb{R}\}\end{aligned}$$

In this Example, **Note that**

$$\ker(L) = \{[x, 0, z] \mid x, z \in \mathbb{R}\}$$

is a subspace of the vector space \mathbb{R}^3 .



Result: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT, then $\ker(L)$ is a subspace of \mathcal{V} .



Range of a linear transformation:



Range of a linear transformation:

Definition: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT.



Range of a linear transformation:

Definition: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **range** of L , denoted by $\text{range}(L)$, is the subset of all vectors in \mathcal{W} that are image of some vector in \mathcal{V} , i.e.



Range of a linear transformation:

Definition: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **range** of L , denoted by $\text{range}(L)$, is the subset of all vectors in \mathcal{W} that are image of some vector in \mathcal{V} , i.e.

$$\text{range}(L) = \{L(\mathbf{v}) \mid \mathbf{v} \in \mathcal{V}\}$$

Thus a vector $\mathbf{w} \in \text{range}(L)$



Range of a linear transformation:

Definition: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. The **range** of L , denoted by $\text{range}(L)$, is the subset of all vectors in \mathcal{W} that are image of some vector in \mathcal{V} , i.e.

$$\text{range}(L) = \{L(\mathbf{v}) \mid \mathbf{v} \in \mathcal{V}\}$$

Thus a vector $\mathbf{w} \in \text{range}(L)$ implies there exists some vector $\mathbf{v} \in \mathcal{V}$ such that $L(\mathbf{v}) = \mathbf{w}$.



Result: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT, then $\text{range}(L)$ is a subspace of \mathcal{W} .



Result: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT, then $\text{range}(L)$ is a subspace of \mathcal{W} .

Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 5 & 1 & -1 \\ -3 & 0 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



Result: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT, then $\text{range}(L)$ is a subspace of \mathcal{W} .

Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 5 & 1 & -1 \\ -3 & 0 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

- Is $[1, -2, 3]^T \in \ker(L)$?



Result: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT, then $\text{range}(L)$ is a subspace of \mathcal{W} .

Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 5 & 1 & -1 \\ -3 & 0 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

- Is $[1, -2, 3]^T \in \ker(L)$?
- Is $[2, -1, 4]^T \in \text{range}(L)$?



Hint: Note that $L([1, -2, 3]^T) = [0, 0, 0]^T$



Hint: Note that $L([1, -2, 3]^T) = [0, 0, 0]^T$ implies $[1, -2, 3]^T \in \ker(L)$.



Hint: Note that $L([1, -2, 3]^T) = [0, 0, 0]^T$ implies $[1, -2, 3]^T \in \ker(L)$.

Note that to check $[2, -1, 4]^T \in \text{range}(L)$ is same as to check whether given system of linear equations

$$5x + y - z = 2$$

$$-3x + z = -1$$

$$x - y - z = 4$$

is consistent or not.



Hint: Note that $L([1, -2, 3]^T) = [0, 0, 0]^T$ implies $[1, -2, 3]^T \in \ker(L)$.

Note that to check $[2, -1, 4]^T \in \text{range}(L)$ is same as to check whether given system of linear equations

$$5x + y - z = 2$$

$$-3x + z = -1$$

$$x - y - z = 4$$

is consistent or not.

Since above system of equations is **inconsistent** (show it!),



Hint: Note that $L([1, -2, 3]^T) = [0, 0, 0]^T$ implies $[1, -2, 3]^T \in \ker(L)$.

Note that to check $[2, -1, 4]^T \in \text{range}(L)$ is same as to check whether given system of linear equations

$$5x + y - z = 2$$

$$-3x + z = -1$$

$$x - y - z = 4$$

is consistent or not.

Since above system of equations is **inconsistent** (show it!), $[2, -1, 4]^T \notin \text{range}(L)$.



Example 7: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [0, y] \text{ for all } [x, y, z] \in \mathbb{R}^3$$



Example 7: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [0, y] \text{ for all } [x, y, z] \in \mathbb{R}^3$$

- Find $\text{range}(L)$.



Example 7: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [0, y] \text{ for all } [x, y, z] \in \mathbb{R}^3$$

- Find $\text{range}(L)$.
- Find the dimension of $\ker(L)$ and $\text{range}(L)$.



Example 7: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [0, y] \text{ for all } [x, y, z] \in \mathbb{R}^3$$

- Find $\text{range}(L)$.
- Find the dimension of $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\text{range}(L) = \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\}$$



Example 7: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [0, y] \text{ for all } [x, y, z] \in \mathbb{R}^3$$

- Find $\text{range}(L)$.
- Find the dimension of $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\begin{aligned} \text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[0, y] \mid y \in \mathbb{R}\} \end{aligned}$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$.



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?).



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\ker(L) = \{[x, 0, z] \mid x, z \in \mathbb{R}\}$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\ker(L) = \{[x, 0, z] \mid x, z \in \mathbb{R}\} \quad (\text{see Example 6})$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\begin{aligned} \ker(L) &= \{[x, 0, z] \mid x, z \in \mathbb{R}\} \quad (\text{see Example 6}) \\ &= \{x[1, 0, 0] + z[0, 0, 1] \mid x, z \in \mathbb{R}\} \end{aligned}$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\begin{aligned} \ker(L) &= \{[x, 0, z] \mid x, z \in \mathbb{R}\} \quad (\text{see Example 6}) \\ &= \{x[1, 0, 0] + z[0, 0, 1] \mid x, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0, 0], [0, 0, 1]\} \end{aligned}$$



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\begin{aligned} \ker(L) &= \{[x, 0, z] \mid x, z \in \mathbb{R}\} \quad (\text{see Example 6}) \\ &= \{x[1, 0, 0] + z[0, 0, 1] \mid x, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0, 0], [0, 0, 1]\} \end{aligned}$$

Now, the set $\{[1, 0, 0], [0, 0, 1]\}$ of vectors is LI subset of \mathbb{R}^3 (verify!).



$$\text{range}(L) = \{y[0, 1] \mid y \in \mathbb{R}\}$$

Note that $\text{range}(L) = \text{span}\{[0, 1]\}$. Since $\{[0, 1]\}$ is LI subset of \mathbb{R}^2 (Why?). Thus, the set $B = \{[0, 1]\}$ is a basis of $\text{range}(L)$ so that $\dim(\text{range}(L)) = 1$

$$\begin{aligned} \ker(L) &= \{[x, 0, z] \mid x, z \in \mathbb{R}\} \quad (\text{see Example 6}) \\ &= \{x[1, 0, 0] + z[0, 0, 1] \mid x, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0, 0], [0, 0, 1]\} \end{aligned}$$

Now, the set $\{[1, 0, 0], [0, 0, 1]\}$ of vectors is LI subset of \mathbb{R}^3 (verify!). Hence, the set $\{[1, 0, 0], [0, 0, 1]\}$ forms a basis of $\ker(L)$ and $\dim(\ker(L)) = 2$.



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$.



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\ker(L) = \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\}$$



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [x - 2y, y + z] = [0, 0]\}\end{aligned}$$



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [x - 2y, y + z] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid x = 2y, z = -y\}\end{aligned}$$



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [x - 2y, y + z] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid x = 2y, z = -y\} \\ &= \{[2y, y, -y] \mid y \in \mathbb{R}\}\end{aligned}$$



Example 8: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a LT given by

$$L([x, y, z]) = [x - 2y, y + z].$$

Find $\ker(L)$ and $\text{range}(L)$. Also, find basis for $\ker(L)$ and $\text{range}(L)$.

Solution:

$$\begin{aligned}\ker(L) &= \{[x, y, z] \in \mathbb{R}^3 \mid L([x, y, z]) = \mathbf{0}_{\mathbb{R}^2}\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid [x - 2y, y + z] = [0, 0]\} \\ &= \{[x, y, z] \in \mathbb{R}^3 \mid x = 2y, z = -y\} \\ &= \{[2y, y, -y] \mid y \in \mathbb{R}\} \\ &= \text{span}\{[2, 1, -1]\}\end{aligned}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\text{range}(L) = \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\begin{aligned}\text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[x - 2y, y + z] \mid x, y, z \in \mathbb{R}\}\end{aligned}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\begin{aligned}\text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[x - 2y, y + z] \mid x, y, z \in \mathbb{R}\} \\ &= \{x[1, 0] + y[-2, 1] + z[0, 1] \mid x, y, z \in \mathbb{R}\}\end{aligned}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\begin{aligned}\text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[x - 2y, y + z] \mid x, y, z \in \mathbb{R}\} \\ &= \{x[1, 0] + y[-2, 1] + z[0, 1] \mid x, y, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0], [-2, 1], [0, 1]\}\end{aligned}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\begin{aligned}\text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[x - 2y, y + z] \mid x, y, z \in \mathbb{R}\} \\ &= \{x[1, 0] + y[-2, 1] + z[0, 1] \mid x, y, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0], [-2, 1], [0, 1]\} \\ &= \text{span}\{[1, 0], [0, 1]\}\end{aligned}$$



Since the set $B = \{[2, 1, -1]\}$ is LI. Therefore,
 $B = \{[2, 1, -1]\}$ is a basis of $\ker(L)$. Now

$$\begin{aligned}\text{range}(L) &= \{L([x, y, z]) \mid [x, y, z] \in \mathbb{R}^3\} \\ &= \{[x - 2y, y + z] \mid x, y, z \in \mathbb{R}\} \\ &= \{x[1, 0] + y[-2, 1] + z[0, 1] \mid x, y, z \in \mathbb{R}\} \\ &= \text{span}\{[1, 0], [-2, 1], [0, 1]\} \\ &= \text{span}\{[1, 0], [0, 1]\}\end{aligned}$$

Since the set $\{[1, 0], [0, 1]\}$ is LI. Thus,

$$\{[1, 0], [0, 1]\}$$

is a basis for $\text{range}(L)$.



Exercise: Given a map

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(ax^3 + bx^2 + cx + d) = 3ax^2 + 2bx + c.$$

- 1 Show that L is a linear transformation.



Exercise: Given a map

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(ax^3 + bx^2 + cx + d) = 3ax^2 + 2bx + c.$$

- 1 Show that L is a linear transformation.
- 2 Find $\ker(L)$ and $\text{range}(L)$.



Exercise: Given a map

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(ax^3 + bx^2 + cx + d) = 3ax^2 + 2bx + c.$$

- 1 Show that L is a linear transformation.
- 2 Find $\ker(L)$ and $\text{range}(L)$.

Answer:

$$\ker(L) = \{0x^3 + 0x^2 + 0x + d \mid d \in \mathbb{R}\}$$

$$\text{range}(L) = \mathcal{P}_2.$$



Exercise: Given a map

$L : \mathbb{R}^4 \rightarrow \mathcal{P}_2$ given by

$$L([a, b, c, d]) = a + (b + c)x + (b - d)x^2.$$

1 Find $\ker(L)$ and $\text{range}(L)$.



Exercise: Given a map

$$L : \mathbb{R}^4 \rightarrow \mathcal{P}_2 \quad \text{given by}$$

$$L([a, b, c, d]) = a + (b + c)x + (b - d)x^2.$$

- 1 Find $\ker(L)$ and $\text{range}(L)$.
- 2 Find a basis for $\ker(L)$ and $\text{range}(L)$.



Exercise: Given a map

$L : \mathbb{R}^4 \rightarrow \mathcal{P}_2$ given by

$$L([a, b, c, d]) = a + (b + c)x + (b - d)x^2.$$

- 1 Find $\ker(L)$ and $\text{range}(L)$.
- 2 Find a basis for $\ker(L)$ and $\text{range}(L)$.

Answer:

$$\ker(L) = \{[0, b, -b, b] \mid b \in \mathbb{R}\} \text{ and } B = \{[0, 1, -1, 1]\}$$



Exercise: Given a map

$$L : \mathbb{R}^4 \rightarrow \mathcal{P}_2 \quad \text{given by}$$

$$L([a, b, c, d]) = a + (b + c)x + (b - d)x^2.$$

- 1 Find $\ker(L)$ and $\text{range}(L)$.
- 2 Find a basis for $\ker(L)$ and $\text{range}(L)$.

Answer:

$$\ker(L) = \{[0, b, -b, b] \mid b \in \mathbb{R}\} \quad \text{and} \quad B = \{[0, 1, -1, 1]\}$$

$$\text{range}(L) = \text{span}\{1, x + x^2, x, x^2\} \quad \text{and} \quad B = \{1, x, x + x^2, x^2\}$$



Example 9: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be a LT given by

$$L([x, y, z]) = [x, y - z, x - y + z, x + y - z].$$



Example 9: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be a LT given by

$$L([x, y, z]) = [x, y - z, x - y + z, x + y - z].$$

Find a basis for $\ker(L)$ and $\text{range}(L)$.



Example 9: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be a LT given by

$$L([x, y, z]) = [x, y - z, x - y + z, x + y - z].$$

Find a basis for $\ker(L)$ and $\text{range}(L)$.

Answer:

- $\{[0, 1, 1]\}$ is a basis of $\ker(L)$.
- $\{[1, 0, 1, 1], [0, 1, -1, 1]\}$ is a basis for $\text{range}(L)$.



Alternative approach for finding a basis for $\ker(L)$ (Kernel Method) Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.



Alternative approach for finding a basis for $\ker(L)$ (Kernel Method) Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

Step 1: Express $L(X) = AX$ for some $m \times n$ matrix A .



Alternative approach for finding a basis for $\ker(L)$ (Kernel Method) Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

Step 1: Express $L(X) = AX$ for some $m \times n$ matrix A . In [Example 9](#), note that $L(X) = AX$ where



Alternative approach for finding a basis for $\ker(L)$ (Kernel Method)

Let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

Step 1: Express $L(X) = AX$ for some $m \times n$ matrix A . In [Example 9](#), note that $L(X) = AX$ where

$$X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix}$$



Step 2: Find matrix B, the RREF of A.



Step 2: Find matrix B, the RREF of A.

$$B = \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



Step 2: Find matrix B , the RREF of A .

$$B = \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 3: Solve the system $BX = 0$ to find $\ker(L)$ such that $\ker(L) = \text{span}(S)$ for some $S \subseteq \mathbb{R}^n$.



Step 2: Find matrix B , the RREF of A .

$$B = \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 3: Solve the system $BX = 0$ to find $\ker(L)$ such that $\ker(L) = \text{span}(S)$ for some $S \subseteq \mathbb{R}^n$. The system corresponding to B is $x = 0, y = z$.

$$\ker(L) = \{X \in \mathbb{R}^n \mid L(X) = AX = 0\}$$



Step 2: Find matrix B , the RREF of A .

$$B = \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 3: Solve the system $BX = 0$ to find $\ker(L)$ such that $\ker(L) = \text{span}(S)$ for some $S \subseteq \mathbb{R}^n$. The system corresponding to B is $x = 0, y = z$.

$$\begin{aligned} \ker(L) &= \{X \in \mathbb{R}^n \mid L(X) = AX = 0\} \\ &= \{X \in \mathbb{R}^n \mid BX = 0\} \end{aligned}$$



Step 2: Find matrix B , the RREF of A .

$$B = \text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 3: Solve the system $BX = 0$ to find $\ker(L)$ such that $\ker(L) = \text{span}(S)$ for some $S \subseteq \mathbb{R}^n$. The system corresponding to B is $x = 0, y = z$.

$$\begin{aligned} \ker(L) &= \{X \in \mathbb{R}^n \mid L(X) = AX = 0\} \\ &= \{X \in \mathbb{R}^n \mid BX = 0\} \\ &= \{[0, y, y] \mid y \in \mathbb{R}\} \end{aligned}$$



$$\ker(L) = \text{span}\{[0, 1, 1]\}$$



$$\ker(L) = \text{span}\{[0, 1, 1]\}$$

$$\ker(L) = \text{span}(S), \text{ where } S = \{[0, 1, 1]\}$$



$$\ker(L) = \text{span}\{[0, 1, 1]\}$$

$$\ker(L) = \text{span}(S), \text{ where } S = \{[0, 1, 1]\}$$

Step 4: Find a LI subset of S which forms a basis for $\ker(L)$.



$$\ker(L) = \text{span}\{[0, 1, 1]\}$$

$$\ker(L) = \text{span}(S), \text{ where } S = \{[0, 1, 1]\}$$

Step 4: Find a LI subset of S which forms a basis for $\ker(L)$. Since the set $\{[0, 1, 1]\}$ is a LI so it is a basis of $\ker(L)$.



Alternative approach to find a basis for $\text{range}(L)$ (Range Method)

Step 1: Find RREF of A .



Alternative approach to find a basis for $\text{range}(L)$ (Range Method)

Step 1: Find RREF of A .

$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



Alternative approach to find a basis for $\text{range}(L)$ (Range Method)

Step 1: Find RREF of A .

$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 2: Column vectors in A corresponding to **pivot columns** of $\text{RREF}(A)$ forms a basis for $\text{range}(L)$.



Alternative approach to find a basis for $\text{range}(L)$ (Range Method)

Step 1: Find RREF of A .

$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 2: Column vectors in A corresponding to **pivot columns** of $\text{RREF}(A)$ forms a basis for $\text{range}(L)$.
Note that, Columns I and II have leading entry.



Alternative approach to find a basis for range(L) (Range Method)

Step 1: Find RREF of A .

$$\text{RREF}(A) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Step 2: Column vectors in A corresponding to **pivot columns** of $\text{RREF}(A)$ forms a basis for range(L).

Note that, Columns I and II have leading entry. Thus, the corresponding column vector of A i.e.

$\{[1, 0, 1, 1], [0, 1, -1, 1]\}$ is a basis of range (L).



The Dimension Theorem:



The Dimension Theorem: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT and \mathcal{V} is finite dimensional, then $\text{range}(L)$ is finite dimensional, and

$$\dim(\ker(L)) + \dim(\text{range}(L)) = \dim(\mathcal{V}).$$



The Dimension Theorem: If $L : \mathcal{V} \rightarrow \mathcal{W}$ is a LT and \mathcal{V} is finite dimensional, then $\text{range}(L)$ is finite dimensional, and

$$\dim(\ker(L)) + \dim(\text{range}(L)) = \dim(\mathcal{V}).$$

Sometimes $\dim(\ker(L))$ and $\dim(\text{range}(L))$ is also known as **nullity** (L) and **rank** (L) , respectively.



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Solution:

$$\ker(L) = \{a + bx + cx^2 \in \mathcal{P}_2 \mid L(a + bx + cx^2) = \mathbf{0}_{\mathcal{P}_3}\}$$



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Solution:

$$\ker(L) = \{a + bx + cx^2 \in \mathcal{P}_2 \mid L(a + bx + cx^2) = \mathbf{0}_{\mathcal{P}_3}\}$$

$$\ker(L) = \{\mathbf{0}_{\mathcal{P}_2}\}$$



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Solution:

$$\ker(L) = \{a + bx + cx^2 \in \mathcal{P}_2 \mid L(a + bx + cx^2) = \mathbf{0}_{\mathcal{P}_3}\}$$

$$\ker(L) = \{\mathbf{0}_{\mathcal{P}_2}\} \text{ implies } \dim(\ker(L)) = 0.$$



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Solution:

$$\ker(L) = \{a + bx + cx^2 \in \mathcal{P}_2 \mid L(a + bx + cx^2) = \mathbf{0}_{\mathcal{P}_3}\}$$

$$\ker(L) = \{\mathbf{0}_{\mathcal{P}_2}\} \text{ implies } \dim(\ker(L)) = 0.$$

Since $\dim \mathcal{P}_2 = 3$ **by dimension theorem**, we have



Example 10: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_3$ given by

$$L(a + bx + cx^2) = x(a + bx + cx^2).$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Solution:

$$\ker(L) = \{a + bx + cx^2 \in \mathcal{P}_2 \mid L(a + bx + cx^2) = \mathbf{0}_{\mathcal{P}_3}\}$$

$$\ker(L) = \{\mathbf{0}_{\mathcal{P}_2}\} \text{ implies } \dim(\ker(L)) = 0.$$

Since $\dim \mathcal{P}_2 = 3$ **by dimension theorem**, we have

$$\dim(\text{range}(L)) = 3 - 0 = 3.$$



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A)$$



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) \text{ (sum of the diagonal entries of } A \text{)}.$$



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) \text{ (sum of the diagonal entries of } A \text{)}.$$

Find $\ker(L)$, $\dim(\ker(L))$, $\text{range}(L)$ and $\dim(\text{range}(L))$.



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) (\text{sum of the diagonal entries of } A).$$

Find $\ker(L)$, $\dim(\ker(L))$, $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer:

$$\ker(L) = \left\{ \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & -a-e \end{bmatrix}_{3 \times 3} \mid a, b, c, d, e, f, g, h \in \mathbb{R} \right\}$$

Note that



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) (\text{sum of the diagonal entries of } A).$$

Find $\ker(L)$, $\dim(\ker(L))$, $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer:

$$\ker(L) = \left\{ \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & -a-e \end{bmatrix}_{3 \times 3} \mid a, b, c, d, e, f, g, h \in \mathbb{R} \right\}$$

Note that $\dim(\ker(L)) = 8$ ([show it](#)).



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) (\text{sum of the diagonal entries of } A).$$

Find $\ker(L)$, $\dim(\ker(L))$, $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer:

$$\ker(L) = \left\{ \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & -a-e \end{bmatrix}_{3 \times 3} \mid a, b, c, d, e, f, g, h \in \mathbb{R} \right\}$$

Note that $\dim(\ker(L)) = 8$ ([show it](#)). Since $\text{range}(L) = \mathbb{R}$



Exercise: Consider a LT $L : \mathcal{M}_{33} \rightarrow \mathbb{R}$ given by

$$L(A) = \text{trace}(A) (\text{sum of the diagonal entries of } A).$$

Find $\ker(L)$, $\dim(\ker(L))$, $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer:

$$\ker(L) = \left\{ \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & -a-e \end{bmatrix}_{3 \times 3} \mid a, b, c, d, e, f, g, h \in \mathbb{R} \right\}$$

Note that $\dim(\ker(L)) = 8$ ([show it](#)). Since $\text{range}(L) = \mathbb{R}$ so that $\dim(\text{range}(L)) = 1$.



Exercise: Let \mathcal{W} be the vector space of all 2×2 symmetric matrices. Define a LT $L : \mathcal{W} \rightarrow \mathcal{P}_2$ by

$$L\left(\begin{bmatrix} a & b \\ b & c \end{bmatrix}\right) = (a - b) + (b - c)x + (c - a)x^2$$



Exercise: Let \mathcal{W} be the vector space of all 2×2 symmetric matrices. Define a LT $L : \mathcal{W} \rightarrow \mathcal{P}_2$ by

$$L \left(\begin{bmatrix} a & b \\ b & c \end{bmatrix} \right) = (a - b) + (b - c)x + (c - a)x^2$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.



Exercise: Let \mathcal{W} be the vector space of all 2×2 symmetric matrices. Define a LT $L : \mathcal{W} \rightarrow \mathcal{P}_2$ by

$$L \left(\begin{bmatrix} a & b \\ b & c \end{bmatrix} \right) = (a - b) + (b - c)x + (c - a)x^2$$

Find $\dim(\ker(L))$ and $\dim(\text{range}(L))$.

Answer: $\dim(\ker(L)) = 1$ and $\dim(\text{range}(L)) = 2$.



Exercise: Let $\{e_1, e_2, e_3, e_4\}$ be standard basis for \mathbb{R}^4 and $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ be a LT given by



Exercise: Let $\{e_1, e_2, e_3, e_4\}$ be standard basis for \mathbb{R}^4 and $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ be a LT given by

$$L(e_1) = [1, 1, 1], \quad L(e_2) = [1, -1, 1]$$

$$L(e_3) = [1, 0, 0], \quad L(e_4) = [1, 0, 1]$$



Exercise: Let $\{e_1, e_2, e_3, e_4\}$ be standard basis for \mathbb{R}^4 and $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ be a LT given by

$$L(e_1) = [1, 1, 1], \quad L(e_2) = [1, -1, 1]$$

$$L(e_3) = [1, 0, 0], \quad L(e_4) = [1, 0, 1]$$

- Find $\ker(L)$ and $\dim(\ker(L))$.
- Find $\text{range}(L)$ and $\dim(\text{range}(L))$.



Exercise: Let $\{e_1, e_2, e_3, e_4\}$ be standard basis for \mathbb{R}^4 and $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ be a LT given by

$$L(e_1) = [1, 1, 1], \quad L(e_2) = [1, -1, 1]$$

$$L(e_3) = [1, 0, 0], \quad L(e_4) = [1, 0, 1]$$

- Find $\ker(L)$ and $\dim(\ker(L))$.
- Find $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer: $\dim(\ker(L)) = 1$ and $\dim(\text{range}(L)) = 3$.



Exercise: For each $\mathbf{p} \in \mathcal{P}_2$, consider $L : \mathcal{P}_2 \rightarrow \mathcal{P}_4$ given by $L(\mathbf{p}) = x^2\mathbf{p}$.

- Find $\ker(L)$ and $\dim(\ker(L))$.



Exercise: For each $\mathbf{p} \in \mathcal{P}_2$, consider $L : \mathcal{P}_2 \rightarrow \mathcal{P}_4$ given by $L(\mathbf{p}) = x^2\mathbf{p}$.

- Find $\ker(L)$ and $\dim(\ker(L))$.
- Find $\text{range}(L)$ and $\dim(\text{range}(L))$.



Exercise: For each $\mathbf{p} \in \mathcal{P}_2$, consider $L : \mathcal{P}_2 \rightarrow \mathcal{P}_4$ given by $L(\mathbf{p}) = x^2\mathbf{p}$.

- Find $\ker(L)$ and $\dim(\ker(L))$.
- Find $\text{range}(L)$ and $\dim(\text{range}(L))$.

Answer: $\dim(\ker(L)) = 0$ and $\dim(\text{range}(L)) = 3$.



Section 5.4

Definition: A linear transformation $L : \mathcal{V} \rightarrow \mathcal{W}$ **one-to-one** if and only if



Section 5.4

Definition: A linear transformation $L : \mathcal{V} \rightarrow \mathcal{W}$ **one-to-one** if and only if for all $\mathbf{v}_1, \mathbf{v}_2 \in \mathcal{V}$, $L(\mathbf{v}_1) = L(\mathbf{v}_2)$ implies $\mathbf{v}_1 = \mathbf{v}_2$,



Section 5.4

Definition: A linear transformation $L : \mathcal{V} \rightarrow \mathcal{W}$ **one-to-one** if and only if for all $\mathbf{v}_1, \mathbf{v}_2 \in \mathcal{V}$, $L(\mathbf{v}_1) = L(\mathbf{v}_2)$ implies $\mathbf{v}_1 = \mathbf{v}_2$, or if $\mathbf{v}_1 \neq \mathbf{v}_2$ implies $L(\mathbf{v}_1) \neq L(\mathbf{v}_2)$.



Section 5.4

Definition: A linear transformation $L : \mathcal{V} \rightarrow \mathcal{W}$ **one-to-one** if and only if for all $\mathbf{v}_1, \mathbf{v}_2 \in \mathcal{V}$, $L(\mathbf{v}_1) = L(\mathbf{v}_2)$ implies $\mathbf{v}_1 = \mathbf{v}_2$, or if $\mathbf{v}_1 \neq \mathbf{v}_2$ implies $L(\mathbf{v}_1) \neq L(\mathbf{v}_2)$.

L is **onto** if and only if,



Section 5.4

Definition: A linear transformation $L : \mathcal{V} \rightarrow \mathcal{W}$ **one-to-one** if and only if for all $\mathbf{v}_1, \mathbf{v}_2 \in \mathcal{V}$, $L(\mathbf{v}_1) = L(\mathbf{v}_2)$ implies $\mathbf{v}_1 = \mathbf{v}_2$, or if $\mathbf{v}_1 \neq \mathbf{v}_2$ implies $L(\mathbf{v}_1) \neq L(\mathbf{v}_2)$.

L is **onto** if and only if, for each $\mathbf{w} \in \mathcal{W}$, there is some $\mathbf{v} \in \mathcal{V}$ such that $L(\mathbf{v}) = \mathbf{w}$.



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.
Since, $L(\mathbf{p}_1) = L(\mathbf{p}_2) = 1$ implies



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.

Since, $L(\mathbf{p}_1) = L(\mathbf{p}_2) = 1$ implies L is not one-to-one.



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.

Since, $L(\mathbf{p}_1) = L(\mathbf{p}_2) = 1$ implies L is not one-to-one.

Let \mathbf{q} be an arbitrary element in \mathcal{P}_2 i.e.

$$\mathbf{q} = a + bx + cx^2.$$



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.

Since, $L(\mathbf{p}_1) = L(\mathbf{p}_2) = 1$ implies L is not one-to-one.

Let \mathbf{q} be an arbitrary element in \mathcal{P}_2 i.e.

$\mathbf{q} = a + bx + cx^2$. Note that $a + bx + cx^2 = \mathbf{p}'$, where $\mathbf{p} = ax + \left(\frac{b}{2}\right)x^2 + \left(\frac{c}{3}\right)x^3$ so that $L(\mathbf{p}) = \mathbf{q}$.



Example 11: Consider a LT

$L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$ given by

$$L(\mathbf{p}) = \mathbf{p}'.$$

Check if L is one-to-one and onto.

Solution: Consider $\mathbf{p}_1 = x + 2$ and $\mathbf{p}_2 = x + 4$.

Since, $L(\mathbf{p}_1) = L(\mathbf{p}_2) = 1$ implies L is not one-to-one.

Let \mathbf{q} be an arbitrary element in \mathcal{P}_2 i.e.

$\mathbf{q} = a + bx + cx^2$. Note that $a + bx + cx^2 = \mathbf{p}'$, where $\mathbf{p} = ax + \left(\frac{b}{2}\right)x^2 + \left(\frac{c}{3}\right)x^3$ so that $L(\mathbf{p}) = \mathbf{q}$. Hence, L is onto.



Exercise: Which of the following transformations are one-to-one? onto?

- 1 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = [y, z, -y, 0]$.
- 3 $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{22}$ given by $L(A) = A^T$.



Exercise: Which of the following transformations are one-to-one? onto?

- 1 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = [y, z, -y, 0]$.
- 3 $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{22}$ given by $L(A) = A^T$.

Answer:

- 1 one-to-one but not onto.



Exercise: Which of the following transformations are one-to-one? onto?

- 1 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = [y, z, -y, 0]$.
- 3 $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{22}$ given by $L(A) = A^T$.

Answer:

- 1 one-to-one but not onto.
- 2 neither one-to-one nor onto



Exercise: Which of the following transformations are one-to-one? onto?

- 1 $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$.
- 2 $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = [y, z, -y, 0]$.
- 3 $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{22}$ given by $L(A) = A^T$.

Answer:

- 1 one-to-one but not onto.
- 2 neither one-to-one nor onto
- 3 one-to-one and onto.



Theorem 3: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then



Theorem 3: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_{\mathcal{V}}\}$ (i.e., $\dim \ker(L) = 0$).



Theorem 3: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_{\mathcal{V}}\}$ (i.e., $\dim \ker(L) = 0$).

Theorem 4: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT.



Theorem 3: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_{\mathcal{V}}\}$ (i.e., $\dim \ker(L) = 0$).

Theorem 4: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. If \mathcal{W} is finite dimensional, then L is onto



Theorem 3: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_{\mathcal{V}}\}$ (i.e., $\dim \ker(L) = 0$).

Theorem 4: Let \mathcal{V} and \mathcal{W} be vector spaces, and let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. If \mathcal{W} is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(\mathcal{W})$.



Example 12: Consider a LT $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{23}$ given by

$$L \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = \begin{bmatrix} a - b & 0 & c - d \\ c + d & a + b & 0 \end{bmatrix}$$



Example 12: Consider a LT $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{23}$ given by

$$L \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = \begin{bmatrix} a - b & 0 & c - d \\ c + d & a + b & 0 \end{bmatrix}$$

Is L one-to-one and onto?



Example 12: Consider a LT $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{23}$ given by

$$L \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$

Is L one-to-one and onto?

Solution: Let $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$.



Example 12: Consider a LT $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{23}$ given by

$$L\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$

Is L one-to-one and onto?

Solution: Let $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$. Then

$$L\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$



Example 12: Consider a LT $L : \mathcal{M}_{22} \rightarrow \mathcal{M}_{23}$ given by

$$L\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$

Is L one-to-one and onto?

Solution: Let $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$. Then

$$L\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

We have $a-b=c-d=c+d=a+b=0$ implies $a=b=c=d=0$.



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}).



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}). Thus, L is one-to-one.



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}). Thus, L is one-to-one.

Note that



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}). Thus, L is one-to-one.

Note that

$$\begin{aligned}\dim(\text{range}(L)) &= \dim(\mathcal{M}_{22}) - \dim(\ker(L)) \\ &= 4 \\ &\neq \dim(\mathcal{M}_{23}).\end{aligned}$$



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}). Thus, L is one-to-one.

Note that

$$\begin{aligned}\dim(\text{range}(L)) &= \dim(\mathcal{M}_{22}) - \dim(\ker(L)) \\ &= 4 \\ &\neq \dim(\mathcal{M}_{23}).\end{aligned}$$

Hence, L is not onto.



Hence, $\ker(L)$ contains only the zero matrix (the zero vector of \mathcal{M}_{22}). Thus, L is one-to-one.

Note that

$$\begin{aligned}\dim(\text{range}(L)) &= \dim(\mathcal{M}_{22}) - \dim(\ker(L)) \\ &= 4 \\ &\neq \dim(\mathcal{M}_{23}).\end{aligned}$$

Hence, L is not onto.

Try to find a basis of $\text{range}(L)$.



Example 13: Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



Example 13: Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Is L one-to-one and onto?



Example 13: Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Is L one-to-one and onto?

Solution: The RREF of matrix $A = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix}$ is

$$\begin{bmatrix} 1 & 0 & -\frac{2}{5} \\ 0 & 1 & -\frac{6}{5} \\ 0 & 0 & 0 \end{bmatrix}.$$



From range method,



From range method, $\dim(\text{range}(L)) = 2$



From range method, $\dim(\text{range}(L)) = 2$ and by
Dimension theorem, $\dim(\ker(L)) = 1$.



From range method, $\dim(\text{range}(L)) = 2$ and by **Dimension theorem**, $\dim(\ker(L)) = 1$. Hence, L is neither one-to-one nor onto.



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$.



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) =$



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$.



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one.



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one. By **Dimension theorem**, we see that



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one. By **Dimension theorem**, we see that

$$\dim(\text{range}(L)) = n^2 - \dim(\ker(L))$$



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one. By **Dimension theorem**, we see that

$$\begin{aligned}\dim(\text{range}(L)) &= n^2 - \dim(\ker(L)) \\ &\neq n^2 \\ &\neq \dim \mathcal{M}_{nn}\end{aligned}$$



Example 14: Let A be a fixed $n \times n$ matrix, and consider a LT $L : \mathcal{M}_{nn} \rightarrow \mathcal{M}_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto?

Solution: $L(I_n) = AI_n - I_nA = 0_{n \times n}$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one. By **Dimension theorem**, we see that

$$\begin{aligned}\dim(\text{range}(L)) &= n^2 - \dim(\ker(L)) \\ &\neq n^2 \\ &\neq \dim \mathcal{M}_{nn}\end{aligned}$$

Hence, L is not onto.



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$.



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$

implies $\ker(L) = \{0_{\mathcal{P}}\}$.



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$

implies $\ker(L) = \{0_{\mathcal{P}}\}$. Hence, L is one-to-one.



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$

implies $\ker(L) = \{0_{\mathcal{P}}\}$. Hence, L is one-to-one. Note that the nonzero constant polynomials is not in $\text{range}(L)$,



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$

implies $\ker(L) = \{0_{\mathcal{P}}\}$. Hence, L is one-to-one. Note that the nonzero constant polynomials are not in $\text{range}(L)$, L is not onto.



Example 15: Consider a LT $L : \mathcal{P} \rightarrow \mathcal{P}$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto?

Solution:

$$\ker(L) = \{p(x) | L(p(x)) = 0_{\mathcal{P}}\}$$

implies $\ker(L) = \{0_{\mathcal{P}}\}$. Hence, L is one-to-one. Note that the nonzero constant polynomials is not in $\text{range}(L)$, L is not onto.

Question: Can we apply Dimension theorem here?



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a + b & a + c \\ d + e & d + f \end{bmatrix}$$



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a + b & a + c \\ d + e & d + f \end{bmatrix}$$

Is L one-to-one and onto?



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a + b & a + c \\ d + e & d + f \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is onto but not one-to-one.



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is onto but not one-to-one.

Exercise: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by

$$L(ax^2 + bx + c) = (a+b)x^2 + (b+c)x + (a+c).$$



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a + b & a + c \\ d + e & d + f \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is onto but not one-to-one.

Exercise: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by

$L(ax^2 + bx + c) = (a + b)x^2 + (b + c)x + (a + c)$. Is L one-to-one and onto?



Exercise: Consider a LT $L : \mathcal{M}_{23} \rightarrow \mathcal{M}_{22}$ given by

$$L \left(\begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \right) = \begin{bmatrix} a + b & a + c \\ d + e & d + f \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is onto but not one-to-one.

Exercise: Consider a LT $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by

$L(ax^2 + bx + c) = (a + b)x^2 + (b + c)x + (a + c)$. Is L one-to-one and onto?

Answer: L is one-to-one and onto.



Exercise: Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$



Exercise: Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto?



Exercise: Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is not one-to-one but onto.



Exercise: Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto?

Answer: L is not one-to-one but onto.



Section 5.5



Section 5.5

Invertible linear transformation:



Section 5.5

Invertible linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is an **invertible LT** if and only if



Section 5.5

Invertible linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is an **invertible LT** if and only if there is a function $M : \mathcal{W} \rightarrow \mathcal{V}$ such that $(M \circ L)(\mathbf{v}) = \mathbf{v}$, for all $v \in \mathcal{V}$, and $(L \circ M)(\mathbf{w}) = \mathbf{w}$, for all $\mathbf{w} \in \mathcal{W}$.



Section 5.5

Invertible linear transformation: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then L is an **invertible LT** if and only if there is a function $M : \mathcal{W} \rightarrow \mathcal{V}$ such that $(M \circ L)(\mathbf{v}) = \mathbf{v}$, for all $v \in \mathcal{V}$, and $(L \circ M)(\mathbf{w}) = \mathbf{w}$, for all $\mathbf{w} \in \mathcal{W}$.

Such a function M , **denoted by L^{-1}** , is called an **inverse** of L .



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .

Example 16: Show that $L : \mathcal{P}_n \rightarrow \mathcal{P}_n$ given by $L(\mathbf{p}) = \mathbf{p} + \mathbf{p}'$ is an isomorphism.



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .

Example 16: Show that $L : \mathcal{P}_n \rightarrow \mathcal{P}_n$ given by $L(\mathbf{p}) = \mathbf{p} + \mathbf{p}'$ is an isomorphism.

Solution: First we need to show that L is a linear operator.



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .

Example 16: Show that $L : \mathcal{P}_n \rightarrow \mathcal{P}_n$ given by $L(\mathbf{p}) = \mathbf{p} + \mathbf{p}'$ is an isomorphism.

Solution: First we need to show that L is a linear operator.

$$L(\mathbf{p} + \mathbf{q}) = (\mathbf{p} + \mathbf{q}) + (\mathbf{p} + \mathbf{q})'$$



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .

Example 16: Show that $L : \mathcal{P}_n \rightarrow \mathcal{P}_n$ given by $L(\mathbf{p}) = \mathbf{p} + \mathbf{p}'$ is an isomorphism.

Solution: First we need to show that L is a linear operator.

$$\begin{aligned} L(\mathbf{p} + \mathbf{q}) &= (\mathbf{p} + \mathbf{q}) + (\mathbf{p} + \mathbf{q})' \\ &= \mathbf{p} + \mathbf{p}' + \mathbf{q} + \mathbf{q}' \end{aligned}$$



Isomorphism: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ that is both one-to-one and onto is called as **isomorphism** from \mathcal{V} to \mathcal{W} .

Example 16: Show that $L : \mathcal{P}_n \rightarrow \mathcal{P}_n$ given by $L(\mathbf{p}) = \mathbf{p} + \mathbf{p}'$ is an isomorphism.

Solution: First we need to show that L is a linear operator.

$$\begin{aligned} L(\mathbf{p} + \mathbf{q}) &= (\mathbf{p} + \mathbf{q}) + (\mathbf{p} + \mathbf{q})' \\ &= \mathbf{p} + \mathbf{p}' + \mathbf{q} + \mathbf{q}' \\ &= L(\mathbf{p}) + L(\mathbf{q}) \text{ for all } \mathbf{p}, \mathbf{q} \in \mathcal{P}_n. \end{aligned}$$



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$.



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\ker L = \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = \mathbf{0}_{\mathcal{P}_n}\}$$



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = 0_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = 0_{\mathcal{P}_n}\}\end{aligned}$$



Similarly, (**show that**) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = 0_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = 0_{\mathcal{P}_n}\} \\ &= \{0_{\mathcal{P}_n}\}\end{aligned}$$



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = 0_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = 0_{\mathcal{P}_n}\} \\ &= \{0_{\mathcal{P}_n}\}\end{aligned}$$

implies L is one-to-one.



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = 0_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = 0_{\mathcal{P}_n}\} \\ &= \{0_{\mathcal{P}_n}\}\end{aligned}$$

implies L is one-to-one.

By Dimension theorem,

$$\dim \text{range}(L) = \dim \mathcal{P}_n = n + 1$$

so that $\text{range}(L) = \mathcal{P}_n$.



Similarly, (**show that**) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = \mathbf{0}_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = \mathbf{0}_{\mathcal{P}_n}\} \\ &= \{\mathbf{0}_{\mathcal{P}_n}\}\end{aligned}$$

implies L is one-to-one.

By Dimension theorem,

$$\dim \text{range}(L) = \dim \mathcal{P}_n = n + 1$$

so that $\text{range}(L) = \mathcal{P}_n$. Thus, L is onto.



Similarly, (show that) $L(c \mathbf{p}) = cL(\mathbf{p})$ for all real c and $\mathbf{p} \in \mathcal{P}_n$. Hence, L is a linear operator.

$$\begin{aligned}\ker L &= \{\mathbf{p} \in \mathcal{P}_n \mid L(\mathbf{p}) = \mathbf{0}_{\mathcal{P}_n}\} \\ &= \{\mathbf{p} \in \mathcal{P}_n \mid \mathbf{p} + \mathbf{p}' = \mathbf{0}_{\mathcal{P}_n}\} \\ &= \{\mathbf{0}_{\mathcal{P}_n}\}\end{aligned}$$

implies L is one-to-one.

By Dimension theorem,

$$\dim \text{range}(L) = \dim \mathcal{P}_n = n + 1$$

so that $\text{range}(L) = \mathcal{P}_n$. Thus, L is onto. Hence, L is an isomorphism.



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.

Hint: First find $L([x, y, z])$ for all $[x, y, z] \in \mathbb{R}^3$.



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.

Hint: First find $L([x, y, z])$ for all $[x, y, z] \in \mathbb{R}^3$. Note that

$$L([x, y, z]) = [x + z, x + y + z, y + z].$$



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.

Hint: First find $L([x, y, z])$ for all $[x, y, z] \in \mathbb{R}^3$. Note that

$$L([x, y, z]) = [x + z, x + y + z, y + z].$$

and $\ker(L) = \{0_{\mathbb{R}^3}\}$.



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.

Hint: First find $L([x, y, z])$ for all $[x, y, z] \in \mathbb{R}^3$. Note that

$$L([x, y, z]) = [x + z, x + y + z, y + z].$$

and $\ker(L) = \{0_{\mathbb{R}^3}\}$. Thus, L is one-to-one.



Example 17: Show that the linear operator

$$L : \mathbb{R}^3 \rightarrow \mathbb{R}^3 \text{ such that}$$

$$L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$$

is an isomorphism.

Hint: First find $L([x, y, z])$ for all $[x, y, z] \in \mathbb{R}^3$. Note that

$$L([x, y, z]) = [x + z, x + y + z, y + z].$$

and $\ker(L) = \{0_{\mathbb{R}^3}\}$. Thus, L is one-to-one. Use dimension theorem and Theorem 4 to conclude L is onto. Hence, L is an isomorphism.



Result: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a linear transformation, where \mathcal{V} and \mathcal{W} be finite dimensional vector spaces such that $\dim(\mathcal{V}) = \dim(\mathcal{W})$. Then L is one-to-one if and only if L is onto.



Exercise: Show that the linear operator $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by $L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2$ is an isomorphism.



Exercise: Show that the linear operator $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ given by $L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2$ is an isomorphism.

Exercise: Show that the linear transformation $L : \mathcal{M}_{mn} \rightarrow \mathcal{M}_{nm}$ given by $L(A) = A^T$ is an isomorphism.



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT.



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT. Moreover, if L is invertible, then L^{-1} is also a LT.



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT. Moreover, if L is invertible, then L^{-1} is also a LT.

Example 18: Let $L : \mathbb{R}^3 \rightarrow \mathcal{P}_2$ be a LT given by

$$L([x, y, z]) = x + (x + y - z)t + (x + y + z)t^2.$$



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT. Moreover, if L is invertible, then L^{-1} is also a LT.

Example 18: Let $L : \mathbb{R}^3 \rightarrow \mathcal{P}_2$ be a LT given by

$$L([x, y, z]) = x + (x + y - z)t + (x + y + z)t^2.$$

Is L invertible?



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT. Moreover, if L is invertible, then L^{-1} is also a LT.

Example 18: Let $L : \mathbb{R}^3 \rightarrow \mathcal{P}_2$ be a LT given by

$$L([x, y, z]) = x + (x + y - z)t + (x + y + z)t^2.$$

Is L invertible? If yes, find L^{-1} .



Theorem: A LT $L : \mathcal{V} \rightarrow \mathcal{W}$ is an isomorphism if and only if L is an invertible LT. Moreover, if L is invertible, then L^{-1} is also a LT.

Example 18: Let $L : \mathbb{R}^3 \rightarrow \mathcal{P}_2$ be a LT given by

$$L([x, y, z]) = x + (x + y - z)t + (x + y + z)t^2.$$

Is L invertible? If yes, find L^{-1} .

Solution: First **show that** L is both one-to-one and onto. Hence, invertible.



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$

$$\Rightarrow L([x, y, z]) = a + bt + ct^2$$



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$

$$\Rightarrow L([x, y, z]) = a + bt + ct^2$$

$$\Rightarrow x + (x + y - z)t + (x + y + z)t^2 = a + bt + ct^2$$



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$

$$\Rightarrow L([x, y, z]) = a + bt + ct^2$$

$$\Rightarrow x + (x + y - z)t + (x + y + z)t^2 = a + bt + ct^2$$

$$\Rightarrow x = a, x + y - z = b, x + y + z = c$$



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$

$$\Rightarrow L([x, y, z]) = a + bt + ct^2$$

$$\Rightarrow x + (x + y - z)t + (x + y + z)t^2 = a + bt + ct^2$$

$$\Rightarrow x = a, x + y - z = b, x + y + z = c$$

$$\Rightarrow x = a, y = \frac{b + c - 2a}{2}, z = \frac{c - b}{2}.$$



Let $L^{-1} : \mathcal{P}_2 \rightarrow \mathbb{R}^3$ be defined by

$$L^{-1}(a + bt + ct^2) = [x, y, z]$$

$$\Rightarrow L([x, y, z]) = a + bt + ct^2$$

$$\Rightarrow x + (x + y - z)t + (x + y + z)t^2 = a + bt + ct^2$$

$$\Rightarrow x = a, x + y - z = b, x + y + z = c$$

$$\Rightarrow x = a, y = \frac{b + c - 2a}{2}, z = \frac{c - b}{2}.$$

$$\text{Hence, } L^{-1}(a + bx + cx^2) = \left[a, \frac{b+c-2a}{2}, \frac{c-b}{2} \right].$$



Exercise: Let $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be a LT given by
$$L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2.$$



Exercise: Let $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be a LT given by
 $L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2$. Is L
invertible?



Exercise: Let $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be a LT given by $L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2$. Is L invertible? If yes, find L^{-1} .



Exercise: Let $L : \mathcal{P}_2 \rightarrow \mathcal{P}_2$ be a LT given by $L(a + bx + cx^2) = (b + c) + (a + c)x + (a + b)x^2$. Is L invertible? If yes, find L^{-1} .

Answer:

$$L^{-1}(a+bx+cx^2) = \frac{1}{2}(b+c-a) + \frac{1}{2}(a+c-b)x + \frac{1}{2}(a+b-c)x^2.$$



Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by
 $L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3.$



Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by
 $L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$.
Is L invertible?



Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by
 $L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$.
Is L invertible? If yes, find L^{-1} .



Exercise: Let $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a LT given by
 $L(e_1) = e_1 + e_2, L(e_2) = e_2 + e_3, L(e_3) = e_1 + e_2 + e_3$.
Is L invertible? If yes, find L^{-1} .

Answer: $L^{-1}([x, y, z]) = [y - z, y - x, x - y + z]$.



Isomorphic vector spaces: Let \mathcal{V} and \mathcal{W} be vector spaces. Then \mathcal{V} is isomorphic to \mathcal{W} , denoted by $\mathcal{V} \cong \mathcal{W}$, if and only if there exists an isomorphism $L : \mathcal{V} \rightarrow \mathcal{W}$.



Isomorphic vector spaces: Let \mathcal{V} and \mathcal{W} be vector spaces. Then \mathcal{V} is isomorphic to \mathcal{W} , denoted by $\mathcal{V} \cong \mathcal{W}$, if and only if there exists an isomorphism $L : \mathcal{V} \rightarrow \mathcal{W}$.

Theorem 5: Suppose $\mathcal{V} \cong \mathcal{W}$ and \mathcal{V} and \mathcal{W} are finite dimensional. Then \mathcal{V} is isomorphic to \mathcal{W} if and only if $\dim(\mathcal{V}) = \dim(\mathcal{W})$.



Exercise: Show that \mathbb{R}^n and \mathcal{P}_n are not isomorphic.



Exercise: Show that \mathbb{R}^n and \mathcal{P}_n are not isomorphic.

Solution: Since, $\dim(\mathbb{R}^n) = n \neq n + 1 = \dim(\mathcal{P}_n)$,



Exercise: Show that \mathbb{R}^n and \mathcal{P}_n are not isomorphic.

Solution: Since, $\dim(\mathbb{R}^n) = n \neq n + 1 = \dim(\mathcal{P}_n)$, \mathbb{R}^n and \mathcal{P}_n are not isomorphic.



Exercise: Show that \mathbb{R}^n and \mathcal{P}_n are not isomorphic.

Solution: Since, $\dim(\mathbb{R}^n) = n \neq n + 1 = \dim(\mathcal{P}_n)$, \mathbb{R}^n and \mathcal{P}_n are not isomorphic.

Exercise: Let W be the vector space of all symmetric 2×2 matrices. Show that W is isomorphic to \mathbb{R}^3 .



Exercise: Show that the subspace

$$W = \{\mathbf{p} \in \mathcal{P}_3 \mid \mathbf{p}(0) = 0\}$$

is isomorphic to \mathcal{P}_2 .



Section 4.7

Ordered Basis: An **ordered basis** for vector space \mathcal{V} is an ordered n -tuple of vectors $(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ such that the set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a basis for \mathcal{V} .



Section 4.7

Ordered Basis: An **ordered basis** for vector space \mathcal{V} is an ordered n -tuple of vectors $(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ such that the set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a basis for \mathcal{V} .

- (e_1, e_2) and (e_2, e_1) are two ordered bases for \mathbb{R}^2 .



Coordinationization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ be an ordered basis for a vector space \mathcal{V} .



Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ be an ordered basis for a vector space \mathcal{V} . Suppose that $\mathbf{w} \in \mathcal{V}$ such that

$$\mathbf{w} = a_1 \mathbf{v}_1 + \dots + a_n \mathbf{v}_n$$



Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ be an ordered basis for a vector space \mathcal{V} . Suppose that $\mathbf{w} \in \mathcal{V}$ such that

$$\mathbf{w} = a_1 \mathbf{v}_1 + \dots + a_n \mathbf{v}_n$$

Then $[\mathbf{w}]_B$, the **coordinatization or coordinates of \mathbf{w} with respect to B** is the n -vector $[a_1, a_2, \dots, a_n]$.



Example 19: Let $B = ([4, 2], [1, 3])$ be an ordered basis for \mathbb{R}^2 .



Example 19: Let $B = ([4, 2], [1, 3])$ be an ordered basis for \mathbb{R}^2 . Note that

$$[4, 2] = 1[4, 2] + 0[1, 3].$$



Example 19: Let $B = ([4, 2], [1, 3])$ be an ordered basis for \mathbb{R}^2 . Note that

$$[4, 2] = 1[4, 2] + 0[1, 3].$$

Hence, $[4, 2]_B = [1, 0]$.



Example 19: Let $B = ([4, 2], [1, 3])$ be an ordered basis for \mathbb{R}^2 . Note that

$$[4, 2] = 1[4, 2] + 0[1, 3].$$

Hence, $[4, 2]_B = [1, 0]$. Similarly,

$$[11, 13] = 2[4, 2] + 3[1, 3].$$



Example 19: Let $B = ([4, 2], [1, 3])$ be an ordered basis for \mathbb{R}^2 . Note that

$$[4, 2] = 1[4, 2] + 0[1, 3].$$

Hence, $[4, 2]_B = [1, 0]$. Similarly,

$$[11, 13] = 2[4, 2] + 3[1, 3].$$

Hence, $[11, 13]_B = [2, 3]$.



Example 20: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{V} of \mathbb{R}^5 .



Example 20: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{V} of \mathbb{R}^5 .

Compute $[-23, 30, -7, -1, -7]_B, [1, 2, 3, 4, 5]_B$.



Example 20: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{V} of \mathbb{R}^5 .

Compute $[-23, 30, -7, -1, -7]_B, [1, 2, 3, 4, 5]_B$.

Solution: To find $[-23, 30, -7, -1, -7]_B$,



Example 20: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{V} of \mathbb{R}^5 .

Compute $[-23, 30, -7, -1, -7]_B, [1, 2, 3, 4, 5]_B$.

Solution: To find $[-23, 30, -7, -1, -7]_B$, we need to solve the following equation

$$[-23, 30, -7, -1, -7] = a[-4, 5, -1, 0, -1] + b[1, -3, 2, 2, 5] + c[1, -2, 1, 1, 3]$$



or equivalently



or equivalently

$$-4a + b + c = -23$$

$$5a - 3b - 2c = 30$$

$$-a + 2b + c = -7$$

$$2b + c = -1$$

$$-a + 5b + 3c = -7$$



or equivalently

$$-4a + b + c = -23$$

$$5a - 3b - 2c = 30$$

$$-a + 2b + c = -7$$

$$2b + c = -1$$

$$-a + 5b + 3c = -7$$

To solve this system, note that the RREF of the augmented matrix



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & -23 \\ 5 & -3 & -2 & 30 \\ -1 & 2 & 1 & -7 \\ 0 & 2 & 1 & -1 \\ -1 & 5 & 3 & -7 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & -23 \\ 5 & -3 & -2 & 30 \\ -1 & 2 & 1 & -7 \\ 0 & 2 & 1 & -1 \\ -1 & 5 & 3 & -7 \end{array} \right] \text{ is}$$



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & -23 \\ 5 & -3 & -2 & 30 \\ -1 & 2 & 1 & -7 \\ 0 & 2 & 1 & -1 \\ -1 & 5 & 3 & -7 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & -23 \\ 5 & -3 & -2 & 30 \\ -1 & 2 & 1 & -7 \\ 0 & 2 & 1 & -1 \\ -1 & 5 & 3 & -7 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Hence, the unique solution for the system is

$$a = 6, b = -2, c = 3$$

implies



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & -23 \\ 5 & -3 & -2 & 30 \\ -1 & 2 & 1 & -7 \\ 0 & 2 & 1 & -1 \\ -1 & 5 & 3 & -7 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Hence, the unique solution for the system is

$$a = 6, b = -2, c = 3$$

implies

$$[-23, 30, -7, -1, -7]_B = [6, -2, 3].$$



To find $[1, 2, 3, 4, 5]_B$, we need solve the following system



To find $[1, 2, 3, 4, 5]_B$, we need solve the following system

$$-4a + b + c = 1$$

$$5a - 3b - 2c = 2$$

$$-a + 2b + c = 3$$

$$2b + c = 4$$

$$-a + 5b + 3c = 5$$



To find $[1, 2, 3, 4, 5]_B$, we need solve the following system

$$-4a + b + c = 1$$

$$5a - 3b - 2c = 2$$

$$-a + 2b + c = 3$$

$$2b + c = 4$$

$$-a + 5b + 3c = 5$$

To solve this system, note that the RREF of



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & 1 \\ 5 & -3 & -2 & 2 \\ -1 & 2 & 1 & 3 \\ 0 & 2 & 1 & 4 \\ -1 & 5 & 3 & 5 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & 1 \\ 5 & -3 & -2 & 2 \\ -1 & 2 & 1 & 3 \\ 0 & 2 & 1 & 4 \\ -1 & 5 & 3 & 5 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & 1 \\ 5 & -3 & -2 & 2 \\ -1 & 2 & 1 & 3 \\ 0 & 2 & 1 & 4 \\ -1 & 5 & 3 & 5 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

This system has no solution,



$$\left[\begin{array}{ccc|c} -4 & 1 & 1 & 1 \\ 5 & -3 & -2 & 2 \\ -1 & 2 & 1 & 3 \\ 0 & 2 & 1 & 4 \\ -1 & 5 & 3 & 5 \end{array} \right] \text{ is } \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

This system has no solution, implies that the vector $[1, 2, 3, 4, 5]$ is not in $\text{span}(B) = \mathcal{V}$.



Coordinationization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let

$B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$.



Coordination Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:



Coordination Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$



Coordinationization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order,



Coordination Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.



Coordinatization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$,



Coordinatization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$, say $[C|\mathbf{w}] = \text{RREF}([A|\mathbf{v}])$.



Coordination Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$, say $[C|\mathbf{w}] = \text{RREF}([A|\mathbf{v}])$.
- If there is a row of $[C|\mathbf{w}]$ that contains all zeros on the left and has a nonzero entry on the right,



Coordination Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$, say $[C|\mathbf{w}] = \text{RREF}([A|\mathbf{v}])$.
- If there is a row of $[C|\mathbf{w}]$ that contains all zeros on the left and has a nonzero entry on the right, then $\mathbf{v} \notin \text{span}(B) = \mathcal{V}$,



Coordinatization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$, say $[C|\mathbf{w}] = \text{RREF}([A|\mathbf{v}])$.
- If there is a row of $[C|\mathbf{w}]$ that contains all zeros on the left and has a nonzero entry on the right, then $\mathbf{v} \notin \text{span}(B) = \mathcal{V}$, i.e., coordinatization is not possible.



Coordinatization Method:

Let \mathcal{V} be a nontrivial subspace of \mathbb{R}^n , let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for \mathcal{V} , and let $\mathbf{v} \in \mathbb{R}^n$. To compute $[\mathbf{v}]_B$, we perform the following steps:

- Form an augmented matrix $[A|\mathbf{v}]$ by using the vectors in B as the columns of A , in order, and using \mathbf{v} as a column on the right.
- Find $\text{RREF}([A|\mathbf{v}])$, say $[C|\mathbf{w}] = \text{RREF}([A|\mathbf{v}])$.
- If there is a row of $[C|\mathbf{w}]$ that contains all zeros on the left and has a nonzero entry on the right, then $\mathbf{v} \notin \text{span}(B) = \mathcal{V}$, i.e., coordinatization is not possible. Otherwise, $\mathbf{v} \in \text{span}(B) = \mathcal{V}$.



- Eliminate all rows consisting entirely of zeros in $[C|\mathbf{w}]$ to obtain $[I_k|\mathbf{y}]$.



- Eliminate all rows consisting entirely of zeros in $[C|\mathbf{w}]$ to obtain $[I_k|\mathbf{y}]$. Then, $[\mathbf{v}]_B = \mathbf{y}$,



- Eliminate all rows consisting entirely of zeros in $[C|\mathbf{w}]$ to obtain $[I_k|\mathbf{y}]$. Then, $[\mathbf{v}]_B = \mathbf{y}$, the last column of $[I_k|\mathbf{y}]$.



Example 21: Let

$$B = \left(\begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 3 & 1 \end{bmatrix} \right)$$

be an ordered basis of the subspace \mathcal{W} of \mathcal{M}_{22} .



Example 21: Let

$$B = \left(\begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 3 & 1 \end{bmatrix} \right)$$

be an ordered basis of the subspace \mathcal{W} of \mathcal{M}_{22} .

Compute $[\mathbf{v}]_B$ if exists, where $\mathbf{v} = \begin{bmatrix} -3 & -2 \\ 0 & 3 \end{bmatrix}$.



Solution: Consider

$$[A|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 2 & 1 & -3 \\ -2 & -1 & -1 & -2 \\ 0 & 1 & 3 & 0 \\ 1 & 0 & 1 & 3 \end{array} \right]$$



Solution: Consider

$$[A|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 2 & 1 & -3 \\ -2 & -1 & -1 & -2 \\ 0 & 1 & 3 & 0 \\ 1 & 0 & 1 & 3 \end{array} \right]$$

Note that the row reduced echelon form is

$$\text{RREF}[A|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



The row reduced matrix contains no rows with all zero entries on the left and a nonzero entry on the right, so $[\mathbf{v}]_B$ exists,



The row reduced matrix contains no rows with all zero entries on the left and a nonzero entry on the right, so $[\mathbf{v}]_B$ exists, and

$$[\mathbf{v}]_B = [2, -3, 1].$$



Fundamental properties of Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for a vector space \mathcal{V} . Suppose $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k \in \mathcal{V}$ and a_1, a_2, \dots, a_k are scalars. Then



Fundamental properties of Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for a vector space \mathcal{V} . Suppose $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k \in \mathcal{V}$ and a_1, a_2, \dots, a_k are scalars. Then

- $[\mathbf{w}_1 + \mathbf{w}_2]_B = [\mathbf{w}_1]_B + [\mathbf{w}_2]_B$



Fundamental properties of Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for a vector space \mathcal{V} . Suppose $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k \in \mathcal{V}$ and a_1, a_2, \dots, a_k are scalars. Then

- $[\mathbf{w}_1 + \mathbf{w}_2]_B = [\mathbf{w}_1]_B + [\mathbf{w}_2]_B$
- $[a_1 \mathbf{w}_1]_B = a_1 [\mathbf{w}_1]_B$



Fundamental properties of Coordinatization: Let $B = (\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k)$ be an ordered basis for a vector space \mathcal{V} . Suppose $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k \in \mathcal{V}$ and a_1, a_2, \dots, a_k are scalars. Then

- $[\mathbf{w}_1 + \mathbf{w}_2]_B = [\mathbf{w}_1]_B + [\mathbf{w}_2]_B$
- $[a_1 \mathbf{w}_1]_B = a_1 [\mathbf{w}_1]_B$
- $[a_1 \mathbf{w}_1 + a_2 \mathbf{w}_2 + \dots + a_k \mathbf{w}_k]_B = a_1 [\mathbf{w}_1]_B + a_2 [\mathbf{w}_2]_B + \dots + a_k [\mathbf{w}_k]_B.$



Exercise: Let

$$B = (3x^2 - x + 2, x^2 + 2x - 3, 2x^2 + 3x - 1)$$

be an ordered basis of the subspace \mathcal{W} of \mathcal{P}_2 .



Exercise: Let

$$B = (3x^2 - x + 2, x^2 + 2x - 3, 2x^2 + 3x - 1)$$

be an ordered basis of the subspace \mathcal{W} of \mathcal{P}_2 .
Compute $[\mathbf{v}]_B$ if exists, where $\mathbf{v} = 13x^2 - 5x + 20$.



Exercise: Let

$$B = (3x^2 - x + 2, x^2 + 2x - 3, 2x^2 + 3x - 1)$$

be an ordered basis of the subspace \mathcal{W} of \mathcal{P}_2 .
Compute $[\mathbf{v}]_B$ if exists, where $\mathbf{v} = 13x^2 - 5x + 20$.

Answer: $[\mathbf{v}]_B = [4, -5, 3]$.



Exercise: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 .



Exercise: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 .

Consider $x = [1, 0, -1, 0, 4]$, $y = [0, 1, -1, 0, 3]$ and $z = [0, 0, 0, 1, 5]$.



Exercise: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 .

Consider $x = [1, 0, -1, 0, 4]$, $y = [0, 1, -1, 0, 3]$ and $z = [0, 0, 0, 1, 5]$. Compute $[2x - 7y + 3z]_B$.



Exercise: Let

$$B = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$$

be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 .

Consider $x = [1, 0, -1, 0, 4]$, $y = [0, 1, -1, 0, 3]$ and $z = [0, 0, 0, 1, 5]$. Compute $[2x - 7y + 3z]_B$.

Answer: $[2x - 7y + 3z]_B = [-2, 9, -15]$.



Example 22: Let

$C = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$ be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 .



Example 22: Let

$C = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$ be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 . Using simplified span method on C , compute an ordered basis $B = (x, y, z)$ for \mathcal{W} .



Example 22: Let

$C = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$ be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 . Using simplified span method on C , compute an ordered basis $B = (x, y, z)$ for \mathcal{W} . Also, compute $[x]_C, [y]_C, [z]_C$.



Example 22: Let

$C = ([-4, 5, -1, 0, -1], [1, -3, 2, 2, 5], [1, -2, 1, 1, 3])$ be an ordered basis of the subspace \mathcal{W} of \mathbb{R}^5 . Using simplified span method on C , compute an ordered basis $B = (x, y, z)$ for \mathcal{W} . Also, compute $[x]_C, [y]_C, [z]_C$.

Solution: We have the following augmented matrix

$$\left[A \mid x \ y \ z \right] = \left[\begin{array}{ccc|ccc} -4 & 1 & 1 & 1 & 0 & 0 \\ 5 & -3 & -2 & 0 & 1 & 0 \\ -1 & 2 & 1 & -1 & -1 & 0 \\ 0 & 2 & 1 & 0 & 0 & 1 \\ -1 & 5 & 3 & 4 & 3 & 5 \end{array} \right]$$



Row reduce echelon form of the above matrix is



Row reduce echelon form of the above matrix is

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -5 & -4 & -3 \\ 0 & 0 & 1 & 10 & 8 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$



Row reduce echelon form of the above matrix is

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -5 & -4 & -3 \\ 0 & 0 & 1 & 10 & 8 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Clearly, $[x]_C = [1, -5, 10]$, $[y]_C = [1, -4, 8]$ and $[z]_C = [1, -3, 7]$.



Row reduce echelon form of the above matrix is

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -5 & -4 & -3 \\ 0 & 0 & 1 & 10 & 8 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Clearly, $[x]_C = [1, -5, 10]$, $[y]_C = [1, -4, 8]$ and $[z]_C = [1, -3, 7]$. Here, the matrix

$$P = \begin{bmatrix} 1 & 1 & 1 \\ -5 & -4 & -3 \\ 10 & 8 & 7 \end{bmatrix}$$



Row reduce echelon form of the above matrix is

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -5 & -4 & -3 \\ 0 & 0 & 1 & 10 & 8 & 7 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Clearly, $[x]_C = [1, -5, 10]$, $[y]_C = [1, -4, 8]$ and $[z]_C = [1, -3, 7]$. Here, the matrix

$P = \begin{bmatrix} 1 & 1 & 1 \\ -5 & -4 & -3 \\ 10 & 8 & 7 \end{bmatrix}$ is called the transition matrix from B -coordinates to C -coordinates.



Transition Matrix:



Transition Matrix: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C .



Transition Matrix: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C . Let P be the $n \times n$ matrix whose i^{th} column, for $1 \leq i \leq n$, equals $[\mathbf{b}_i]_C$, where \mathbf{b}_i is the i^{th} basis vector in B .



Transition Matrix: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C . Let P be the $n \times n$ matrix whose i^{th} column, for $1 \leq i \leq n$, equals $[\mathbf{b}_i]_C$, where \mathbf{b}_i is the i^{th} basis vector in B . Then P is called the **transition matrix** from B -coordinates to C -coordinates



Transition Matrix: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C . Let P be the $n \times n$ matrix whose i^{th} column, for $1 \leq i \leq n$, equals $[\mathbf{b}_i]_C$, where \mathbf{b}_i is the i^{th} basis vector in B . Then P is called the **transition matrix from B -coordinates to C -coordinates** (or transition matrix from B to C).



Transition Matrix Method:



Transition Matrix Method: To find the transition matrix P from B to C ,



Transition Matrix Method: To find the transition matrix P from B to C , we apply row reduction on

$$\left[\begin{array}{cccc|cccc} 1^{st} & 2^{nd} & & k^{th} & 1^{st} & 2^{nd} & & k^{th} \\ \text{vector} & \text{vector} & \dots & \text{vector} & \text{vector} & \text{vector} & \dots & \text{vector} \\ \text{in} & \text{in} & & \text{in} & \text{in} & \text{in} & & \text{in} \\ C & C & & C & B & B & & B \end{array} \right]$$



Transition Matrix Method: To find the transition matrix P from B to C , we apply row reduction on

$$\left[\begin{array}{cccc|cccc} 1^{st} & 2^{nd} & & k^{th} & 1^{st} & 2^{nd} & & k^{th} \\ \text{vector} & \text{vector} & \dots & \text{vector} & \text{vector} & \text{vector} & \dots & \text{vector} \\ \text{in} & \text{in} & & \text{in} & \text{in} & \text{in} & & \text{in} \\ C & C & & C & B & B & & B \end{array} \right]$$

to produce

$$\left[\begin{array}{c|c} I_k & P \\ \hline \text{rows of} & \text{zeroes} \end{array} \right]$$



Example 23: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$



Example 23: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$

and

$$C = \left(\begin{bmatrix} 22 & 7 \\ 0 & 2 \end{bmatrix}, \begin{bmatrix} 12 & 4 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 33 & 12 \\ 0 & 2 \end{bmatrix} \right)$$

of \mathcal{U}_2 (the set of 2×2 upper triangular matrices),



Example 23: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$

and

$$C = \left(\begin{bmatrix} 22 & 7 \\ 0 & 2 \end{bmatrix}, \begin{bmatrix} 12 & 4 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 33 & 12 \\ 0 & 2 \end{bmatrix} \right)$$

of \mathcal{U}_2 (the set of 2×2 upper triangular matrices), find the transition matrix P from B to C .



Solution: Apply row reduction on



Solution: Apply row reduction on

$$\left[\begin{array}{ccc|ccc} 22 & 12 & 33 & 7 & 1 & 1 \\ 7 & 4 & 12 & 3 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 2 & 1 & 2 & 0 & -1 & 1 \end{array} \right]$$



Solution: Apply row reduction on

$$\left[\begin{array}{ccc|ccc} 22 & 12 & 33 & 7 & 1 & 1 \\ 7 & 4 & 12 & 3 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 2 & 1 & 2 & 0 & -1 & 1 \end{array} \right]$$

we get

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & -2 & 1 \\ 0 & 1 & 0 & -4 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$



The transition matrix P from B to C is



The transition matrix P from B to C is

$$\begin{bmatrix} 1 & -2 & 1 \\ -4 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix}.$$



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 .



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 . Let

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

be the transition matrix from B to C .



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 . Let

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

be the transition matrix from B to C . Find the basis B .



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 . Let

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

be the transition matrix from B to C . Find the basis B .

Solution:

$$x = 1 \cdot a + 2 \cdot b - 1 \cdot c = [3, 2, 0]$$



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 . Let

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

be the transition matrix from B to C . Find the basis B .

Solution:

$$x = 1 \cdot a + 2 \cdot b - 1 \cdot c = [3, 2, 0]$$



Example 24: Let

$C = (a, b, c) = ([1, 0, 1], [1, 1, 0], [0, 0, 1])$ and
 $B = (x, y, z)$ be ordered bases of \mathbb{R}^3 . Let

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 1 \\ -1 & -1 & 1 \end{bmatrix}$$

be the transition matrix from B to C . Find the basis B .

Solution:

$$x = 1 \cdot a + 2 \cdot b - 1 \cdot c = [3, 2, 0]$$

$$y = 1 \cdot a + 1 \cdot b - 1 \cdot c = [2, 1, 0]$$

$$z = 2 \cdot a + 1 \cdot b + 1 \cdot c = [3, 1, 3].$$



Hence,

$$B = ([3, 2, 0], [2, 1, 0], [3, 1, 3]).$$



Hence,

$$B = ([3, 2, 0], [2, 1, 0], [3, 1, 3]).$$

Change of Coordinates Using the Transition Matrix

Theorem: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C .



Hence,

$$B = ([3, 2, 0], [2, 1, 0], [3, 1, 3]).$$

Change of Coordinates Using the Transition Matrix

Theorem: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C . Let P be an $n \times n$ matrix.



Hence,

$$B = ([3, 2, 0], [2, 1, 0], [3, 1, 3]).$$

Change of Coordinates Using the Transition Matrix

Theorem: Suppose that \mathcal{V} is a nontrivial n -dimensional vector space with ordered bases B and C . Let P be an $n \times n$ matrix. Then P is the transition matrix from B to C if and only if for every $\mathbf{v} \in \mathcal{V}$, $P[\mathbf{v}]_B = [\mathbf{v}]_C$.



Example 25: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$



Example 25: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$

and

$$C = \left(\begin{bmatrix} 22 & 7 \\ 0 & 2 \end{bmatrix}, \begin{bmatrix} 12 & 4 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 33 & 12 \\ 0 & 2 \end{bmatrix} \right)$$

of \mathcal{U}_2 (set of 2×2 upper triangular matrices).



Example 25: For the ordered bases

$$B = \left(\begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \right)$$

and

$$C = \left(\begin{bmatrix} 22 & 7 \\ 0 & 2 \end{bmatrix}, \begin{bmatrix} 12 & 4 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 33 & 12 \\ 0 & 2 \end{bmatrix} \right)$$

of \mathcal{U}_2 (set of 2×2 upper triangular matrices). Find $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$, where $\mathbf{v} = \begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix}$.



Solution: Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = 4 \begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} - 6 \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$



Solution: Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = 4 \begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} - 6 \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

Hence, $[\mathbf{v}]_B = [4, 3, -6]^T$.



Solution: Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = 4 \begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} - 6 \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

Hence, $[\mathbf{v}]_B = [4, 3, -6]^T$. Now, since $[\mathbf{v}]_C = P[\mathbf{v}]_B$ and

$$P = \begin{bmatrix} 1 & -2 & 1 \\ -4 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix} \text{ (see Example 23)}$$

implies



Solution: Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = 4 \begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} - 6 \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

Hence, $[\mathbf{v}]_B = [4, 3, -6]^T$. Now, since $[\mathbf{v}]_C = P[\mathbf{v}]_B$ and

$$P = \begin{bmatrix} 1 & -2 & 1 \\ -4 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix} \text{ (see Example 23)}$$

implies $[\mathbf{v}]_C = [-8, -19, 13]^T$.



Solution: Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = 4 \begin{bmatrix} 7 & 3 \\ 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} - 6 \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

Hence, $[\mathbf{v}]_B = [4, 3, -6]^T$. Now, since $[\mathbf{v}]_C = P[\mathbf{v}]_B$ and

$$P = \begin{bmatrix} 1 & -2 & 1 \\ -4 & 1 & 1 \\ 1 & 1 & -1 \end{bmatrix} \text{ (see Example 23)}$$

implies $[\mathbf{v}]_C = [-8, -19, 13]^T$. Clearly,

$$\begin{bmatrix} 25 & 24 \\ 0 & -9 \end{bmatrix} = -8 \begin{bmatrix} 22 & 7 \\ 0 & 2 \end{bmatrix} - 19 \begin{bmatrix} 12 & 4 \\ 0 & 1 \end{bmatrix} + 13 \begin{bmatrix} 33 & 12 \\ 0 & 2 \end{bmatrix}$$



Theorem: Let B and C be ordered bases for a nontrivial finite dimensional vector space \mathcal{V} , and let P be the transition matrix from B to C . Then P is nonsingular, and P^{-1} is the transition matrix from C to B .



Example 26: For an ordered basis

$B = ([1, -4, 1, 2, 1], [6, -24, 5, 8, 3], [3, -12, 3, 6, 2])$ of a subspace \mathcal{V} of \mathbb{R}^5 .



Example 26: For an ordered basis

$B = ([1, -4, 1, 2, 1], [6, -24, 5, 8, 3], [3, -12, 3, 6, 2])$ of a subspace \mathcal{V} of \mathbb{R}^5 .

- Use the Simplified Span Method to find a second ordered basis C .



Example 26: For an ordered basis

$B = ([1, -4, 1, 2, 1], [6, -24, 5, 8, 3], [3, -12, 3, 6, 2])$ of a subspace \mathcal{V} of \mathbb{R}^5 .

- Use the Simplified Span Method to find a second ordered basis C .

Solution: Consider

$$B = \begin{bmatrix} 1 & -4 & 1 & 2 & 1 \\ 6 & -24 & 5 & 8 & 3 \\ 3 & -12 & 3 & 6 & 2 \end{bmatrix}$$



Example 26: For an ordered basis

$B = ([1, -4, 1, 2, 1], [6, -24, 5, 8, 3], [3, -12, 3, 6, 2])$ of a subspace \mathcal{V} of \mathbb{R}^5 .

- Use the Simplified Span Method to find a second ordered basis C .

Solution: Consider

$$B = \begin{bmatrix} 1 & -4 & 1 & 2 & 1 \\ 6 & -24 & 5 & 8 & 3 \\ 3 & -12 & 3 & 6 & 2 \end{bmatrix}$$

Note that

$$\text{RREF}(B) = \begin{bmatrix} 1 & -4 & 0 & -2 & 0 \\ 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$



$$C = ([1, -4, 0, -2, 0], [0, 0, 1, 4, 0], [0, 0, 0, 0, 1]).$$



$$C = ([1, -4, 0, -2, 0], [0, 0, 1, 4, 0], [0, 0, 0, 0, 1]).$$

- Find the transition matrix P from B to C .



$$C = ([1, -4, 0, -2, 0], [0, 0, 1, 4, 0], [0, 0, 0, 0, 1]).$$

- Find the transition matrix P from B to C .

Answer:

$$P = \begin{bmatrix} 1 & 6 & 3 \\ 1 & 5 & 3 \\ 1 & 3 & 2 \end{bmatrix}$$



- Find the transition matrix Q from C to B .



- Find the transition matrix Q from C to B .

Answer:

$$Q = P^{-1} = \begin{bmatrix} 1 & -3 & 3 \\ 1 & -1 & 0 \\ -2 & 3 & -1 \end{bmatrix}$$



- For the given vector $\mathbf{v} = [2, -8, -2, -12, 3] \in \mathcal{V}$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.



- For the given vector $\mathbf{v} = [2, -8, -2, -12, 3] \in \mathcal{V}$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.

$$[B|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 6 & 3 & 2 \\ -4 & -24 & -12 & -8 \\ 1 & 5 & 3 & -2 \\ 2 & 8 & 6 & -12 \\ 1 & 3 & 2 & 3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 17 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -13 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$



- For the given vector $\mathbf{v} = [2, -8, -2, -12, 3] \in \mathcal{V}$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.

$$[B|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 6 & 3 & 2 \\ -4 & -24 & -12 & -8 \\ 1 & 5 & 3 & -2 \\ 2 & 8 & 6 & -12 \\ 1 & 3 & 2 & 3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 17 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -13 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Thus,

$$[\mathbf{v}]_B = [17, 4, -13]$$



- For the given vector $\mathbf{v} = [2, -8, -2, -12, 3] \in \mathcal{V}$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.

$$[B|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 6 & 3 & 2 \\ -4 & -24 & -12 & -8 \\ 1 & 5 & 3 & -2 \\ 2 & 8 & 6 & -12 \\ 1 & 3 & 2 & 3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 17 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -13 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Thus,

$$[\mathbf{v}]_B = [17, 4, -13]$$

Since $P[\mathbf{v}]_B = [\mathbf{v}]_C$ implies



- For the given vector $\mathbf{v} = [2, -8, -2, -12, 3] \in \mathcal{V}$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.

$$[B|\mathbf{v}] = \left[\begin{array}{ccc|c} 1 & 6 & 3 & 2 \\ -4 & -24 & -12 & -8 \\ 1 & 5 & 3 & -2 \\ 2 & 8 & 6 & -12 \\ 1 & 3 & 2 & 3 \end{array} \right] = \left[\begin{array}{ccc|c} 1 & 0 & 0 & 17 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 1 & -13 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Thus,

$$[\mathbf{v}]_B = [17, 4, -13]$$

Since $P[\mathbf{v}]_B = [\mathbf{v}]_C$ implies

$$[\mathbf{v}]_C = [2, -2, 3].$$



Exercise: For the ordered bases

$$B = (2x^2 + 3x - 1, 8x^2 + x + 1, x^2 + 6)$$

and

$$C = (x^2 + 3x + 1, 3x^2 + 4x + 1, 10x^2 + 17x + 5)$$

of \mathcal{P}_2 , find the transition matrix P from B to C .



Exercise: For the ordered bases

$$B = (2x^2 + 3x - 1, 8x^2 + x + 1, x^2 + 6)$$

and

$$C = (x^2 + 3x + 1, 3x^2 + 4x + 1, 10x^2 + 17x + 5)$$

of \mathcal{P}_2 , find the transition matrix P from B to C .

Answer: $P = \begin{bmatrix} 20 & -30 & -69 \\ 24 & -24 & -80 \\ -9 & 11 & 31 \end{bmatrix}$



Exercise: Let $P = \begin{bmatrix} 2 & 2 & 1 \\ 1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$ be the transition

matrix from B to C . If $C = \left\{ \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$, find the basis B .



Exercise: Let $P = \begin{bmatrix} 2 & 2 & 1 \\ 1 & -1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$ be the transition

matrix from B to C . If $C = \left\{ \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$, find the basis B .

Answer: $B = \left\{ \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ -1 \\ 3 \end{bmatrix}, \begin{bmatrix} 5 \\ 5 \\ 2 \end{bmatrix} \right\}$



Exercise: For an ordered basis

$$B = ([3, -1, 4, 6], [6, 7, -3, -2], [-4, -3, 3, 4], [-2, 0, 1, 2])$$

of a subspace \mathcal{W} of \mathbb{R}^4 , perform the following steps:

- 1 Use the Simplified Span Method to find a second ordered basis C .
- 2 Find the transition matrix P from B to C .
- 3 Find the transition matrix Q from C to B .
- 4 For the given vector $\mathbf{v} = [10, 14, 3, 12]$, calculate $[\mathbf{v}]_B$ and $[\mathbf{v}]_C$.



Section 5.2

The Matrix of a linear transformation:



Section 5.2

The Matrix of a linear transformation: Let \mathcal{V} and \mathcal{W} be two finite dimensional real vector spaces such that $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ and $C = \{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m\}$ be an ordered basis of \mathcal{V} and \mathcal{W} , respectively.



Section 5.2

The Matrix of a linear transformation: Let \mathcal{V} and \mathcal{W} be two finite dimensional real vector spaces such that $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ and $C = \{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m\}$ be an ordered basis of \mathcal{V} and \mathcal{W} , respectively.

Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be any linear transformation.



Section 5.2

The Matrix of a linear transformation: Let \mathcal{V} and \mathcal{W} be two finite dimensional real vector spaces such that $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ and $C = \{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m\}$ be an ordered basis of \mathcal{V} and \mathcal{W} , respectively.

Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be any linear transformation. For $\mathbf{v}_j \in \mathcal{V}$, $L(\mathbf{v}_j) \in \mathcal{W}$. For each j , $1 \leq j \leq n$. Since C is a basis of \mathcal{W} , for $a_{ij} \in \mathbb{R}$, we can write



Section 5.2

The Matrix of a linear transformation: Let \mathcal{V} and \mathcal{W} be two finite dimensional real vector spaces such that $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ and $C = \{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_m\}$ be an ordered basis of \mathcal{V} and \mathcal{W} , respectively.

Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be any linear transformation. For $\mathbf{v}_j \in \mathcal{V}$, $L(\mathbf{v}_j) \in \mathcal{W}$. For each j , $1 \leq j \leq n$. Since C is a basis of \mathcal{W} , for $a_{ij} \in \mathbb{R}$, we can write

$$L(\mathbf{v}_j) = a_{1j}\mathbf{w}_1 + a_{2j}\mathbf{w}_2 + \cdots + a_{mj}\mathbf{w}_m$$



Thus, we have

$$L(\mathbf{v}_1) = a_{11}\mathbf{w}_1 + a_{21}\mathbf{w}_2 + \cdots + a_{m1}\mathbf{w}_m$$

$$L(\mathbf{v}_2) = a_{12}\mathbf{w}_1 + a_{22}\mathbf{w}_2 + \cdots + a_{m2}\mathbf{w}_m$$

.....

$$L(\mathbf{v}_n) = a_{1n}\mathbf{w}_1 + a_{2n}\mathbf{w}_2 + \cdots + a_{mn}\mathbf{w}_m$$



Define

$$A_{BC} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{m \times n}.$$

The matrix A_{BC} is called the **matrix of linear transformation L** w.r.t. the bases B and C .



Define

$$A_{BC} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}_{m \times n}.$$

The matrix A_{BC} is called the **matrix of linear transformation** L w.r.t. the bases B and C .

Remark: i^{th} column of the matrix A_{BC} is $[L(\mathbf{v}_i)]_C$.



Theorem: Let \mathcal{V} and \mathcal{W} be non-trivial vector spaces, with $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathcal{V} and \mathcal{W} , respectively. Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT.



Theorem: Let \mathcal{V} and \mathcal{W} be non-trivial vector spaces, with $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathcal{V} and \mathcal{W} , respectively. Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then there is a unique $m \times n$ matrix A_{BC} such that $A_{BC}[\mathbf{v}]_B = [L(\mathbf{v})]_C$, for all $\mathbf{v} \in \mathcal{V}$.



Theorem: Let \mathcal{V} and \mathcal{W} be non-trivial vector spaces, with $\dim(\mathcal{V}) = n$ and $\dim(\mathcal{W}) = m$. Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathcal{V} and \mathcal{W} , respectively. Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a LT. Then there is a unique $m \times n$ matrix A_{BC} such that $A_{BC}[\mathbf{v}]_B = [L(\mathbf{v})]_C$, for all $\mathbf{v} \in \mathcal{V}$. Furthermore, for $1 \leq i \leq n$, the i^{th} column of $A_{BC} = [L(\mathbf{v}_i)]_C$.



Example: Consider the LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_2$, given by

$$L(\mathbf{p}(x)) = x\mathbf{p}(x)$$

with ordered bases $B = (x, 1)$ and $C = (x^2, x - 1, x + 1)$ of \mathcal{P}_1 and \mathcal{P}_2 , respectively.



Example: Consider the LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_2$, given by

$$L(\mathbf{p}(x)) = x\mathbf{p}(x)$$

with ordered bases $B = (x, 1)$ and $C = (x^2, x - 1, x + 1)$ of \mathcal{P}_1 and \mathcal{P}_2 , respectively. Compute A_{BC} .



Example: Consider the LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_2$, given by

$$L(\mathbf{p}(x)) = x\mathbf{p}(x)$$

with ordered bases $B = (x, 1)$ and $C = (x^2, x - 1, x + 1)$ of \mathcal{P}_1 and \mathcal{P}_2 , respectively. Compute A_{BC} .

Solution: Since

$L(x) = x^2 = 1(x^2) + 0(x - 1) + 0(x + 1)$ so that



Example: Consider the LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_2$, given by

$$L(\mathbf{p}(x)) = x\mathbf{p}(x)$$

with ordered bases $B = (x, 1)$ and $C = (x^2, x - 1, x + 1)$ of \mathcal{P}_1 and \mathcal{P}_2 , respectively. Compute A_{BC} .

Solution: Since

$L(x) = x^2 = 1(x^2) + 0(x - 1) + 0(x + 1)$ so that

$$[L(x)]_C = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$



Similarly, $L(1) = x = 0(x^2) + \frac{1}{2}(x - 1) + \frac{1}{2}(x + 1)$
implies



Similarly, $L(1) = x = 0(x^2) + \frac{1}{2}(x - 1) + \frac{1}{2}(x + 1)$
implies

$$[L(1)]_C = \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}.$$



Similarly, $L(1) = x = 0(x^2) + \frac{1}{2}(x - 1) + \frac{1}{2}(x + 1)$
implies

$$[L(1)]_C = \begin{bmatrix} 0 \\ 1/2 \\ 1/2 \end{bmatrix}.$$

Hence,

$$A_{BC} = \begin{bmatrix} 1 & 0 \\ 0 & 1/2 \\ 0 & 1/2 \end{bmatrix}.$$



Method for computing A_{BC} : Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Also, let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.



Method for computing A_{BC} : Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Also, let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

- Compute $L(\mathbf{v}_i)$ for all $i = 1, 2, \dots, n$.



Method for computing A_{BC} : Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Also, let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

- Compute $L(\mathbf{v}_i)$ for all $i = 1, 2, \dots, n$.
- Form the augmented matrix

$$[\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_m \mid L(\mathbf{v}_1) \mid L(\mathbf{v}_2) \mid \dots \mid L(\mathbf{v}_n)]$$



Method for computing A_{BC} : Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Also, let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

- Compute $L(\mathbf{v}_i)$ for all $i = 1, 2, \dots, n$.
- Form the augmented matrix

$$[\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_m \mid L(\mathbf{v}_1) \mid L(\mathbf{v}_2) \mid \dots \mid L(\mathbf{v}_n)]$$

- Apply row reduction on

$$[\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_m \mid L(\mathbf{v}_1) \mid L(\mathbf{v}_2) \mid \dots \mid L(\mathbf{v}_n)].$$



Method for computing A_{BC} : Let $B = (\mathbf{v}_1, \dots, \mathbf{v}_n)$ and $C = (\mathbf{w}_1, \dots, \mathbf{w}_m)$ be ordered bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Also, let $L : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a LT.

- Compute $L(\mathbf{v}_i)$ for all $i = 1, 2, \dots, n$.
- Form the augmented matrix

$$[\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_m \mid L(\mathbf{v}_1) \mid L(\mathbf{v}_2) \mid \dots \mid L(\mathbf{v}_n)]$$

- Apply row reduction on

$$[\mathbf{w}_1 \ \mathbf{w}_2 \ \dots \ \mathbf{w}_m \mid L(\mathbf{v}_1) \mid L(\mathbf{v}_2) \mid \dots \mid L(\mathbf{v}_n)].$$

to produce $[I_m \mid A_{BC}]$.



Example: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b$$

with ordered bases $B = ([5, 3], [3, 2])$ and

$$C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$$

of \mathbb{R}^2 and \mathcal{P}_2 , respectively.



Example: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b$$

with ordered bases $B = ([5, 3], [3, 2])$ and

$$C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$$

of \mathbb{R}^2 and \mathcal{P}_2 , respectively. Compute A_{BC} .



Example: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b$$

with ordered bases $B = ([5, 3], [3, 2])$ and

$$C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$$

of \mathbb{R}^2 and \mathcal{P}_2 , respectively. Compute A_{BC} .

Solution: Since $L[5, 3] = 10x^2 + 12x + 6$



Example: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b$$

with ordered bases $B = ([5, 3], [3, 2])$ and

$$C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$$

of \mathbb{R}^2 and \mathcal{P}_2 , respectively. Compute A_{BC} .

Solution: Since $L[5, 3] = 10x^2 + 12x + 6$ and $L[3, 2] = 7x^2 + 7x + 4$. Consider



Example: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b$$

with ordered bases $B = ([5, 3], [3, 2])$ and

$$C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$$

of \mathbb{R}^2 and \mathcal{P}_2 , respectively. Compute A_{BC} .

Solution: Since $L[5, 3] = 10x^2 + 12x + 6$ and $L[3, 2] = 7x^2 + 7x + 4$. Consider

$$\left[\begin{array}{ccc|cc} 3 & -2 & 1 & 10 & 7 \\ -2 & 2 & -1 & 12 & 7 \\ 0 & -1 & 1 & 6 & 4 \end{array} \right]$$



RREF of the above matrix is

$$\left[\begin{array}{ccc|cc} 1 & 0 & 0 & 22 & 14 \\ 0 & 1 & 0 & 62 & 39 \\ 0 & 0 & 1 & 68 & 43 \end{array} \right]$$



RREF of the above matrix is

$$\left[\begin{array}{ccc|cc} 1 & 0 & 0 & 22 & 14 \\ 0 & 1 & 0 & 62 & 39 \\ 0 & 0 & 1 & 68 & 43 \end{array} \right]$$

so that

$$A_{BC} = \begin{bmatrix} 22 & 14 \\ 62 & 39 \\ 68 & 43 \end{bmatrix}$$



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$.



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 .



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 . Using A_{BC} , find $L(4x^3 - 5x^2 + 6x - 7)$.



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 . Using A_{BC} , find $L(4x^3 - 5x^2 + 6x - 7)$.

Solution: Standard basis of \mathcal{P}_3 is



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 . Using A_{BC} , find $L(4x^3 - 5x^2 + 6x - 7)$.

Solution: Standard basis of \mathcal{P}_3 is $\{x^3, x^2, x, 1\}$.



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 . Using A_{BC} , find $L(4x^3 - 5x^2 + 6x - 7)$.

Solution: Standard basis of \mathcal{P}_3 is $\{x^3, x^2, x, 1\}$. Since $L(x^3) = 3x^2$, $L(x^2) = 2x$, $L(x) = 1$, $L(1) = 0$, we have



Example: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{P}_2$, given by $L(\mathbf{p}) = \mathbf{p}'$. Compute A_{BC} with respect to standard bases $B = \{x^3, x^2, x, 1\}$ of \mathcal{P}_3 and $C = \{x^2, x, 1\}$ of \mathcal{P}_2 . Using A_{BC} , find $L(4x^3 - 5x^2 + 6x - 7)$.

Solution: Standard basis of \mathcal{P}_3 is $\{x^3, x^2, x, 1\}$. Since $L(x^3) = 3x^2$, $L(x^2) = 2x$, $L(x) = 1$, $L(1) = 0$, we have

$$A_{BC} = \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$



Since

$$[L(4x^3 - 5x^2 + 6x - 7)]_C = A_{BC}[(4x^3 - 5x^2 + 6x - 7)]_B$$



Since

$$[L(4x^3 - 5x^2 + 6x - 7)]_C = A_{BC}[(4x^3 - 5x^2 + 6x - 7)]_B$$



Since

$$\begin{aligned}[L(4x^3 - 5x^2 + 6x - 7)]_C &= A_{BC}[(4x^3 - 5x^2 + 6x - 7)]_B \\ &= A_{BC} \begin{bmatrix} 4 \\ -5 \\ 6 \\ -7 \end{bmatrix} = \begin{bmatrix} 12 \\ -10 \\ 6 \end{bmatrix}\end{aligned}$$

Thus, $L(4x^3 - 5x^2 + 6x - 7) = 12x^2 - 10x + 6$



Since

$$\begin{aligned}[L(4x^3 - 5x^2 + 6x - 7)]_C &= A_{BC}[(4x^3 - 5x^2 + 6x - 7)]_B \\ &= A_{BC} \begin{bmatrix} 4 \\ -5 \\ 6 \\ -7 \end{bmatrix} = \begin{bmatrix} 12 \\ -10 \\ 6 \end{bmatrix}\end{aligned}$$

Thus, $L(4x^3 - 5x^2 + 6x - 7) = 12x^2 - 10x + 6$

Also, note that

$$L(4x^3 - 5x^2 + 6x - 7) = (4x^3 - 5x^2 + 6x - 7)' = 12x^2 - 10x + 6$$



Example: Let the matrix of LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_1$ with respect to basis $B = (x + 1, x - 1)$ be $\begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$.



Example: Let the matrix of LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_1$ with respect to basis $B = (x + 1, x - 1)$ be $\begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$. Find the matrix of L with respect to basis $C = (x, 1)$.



Example: Let the matrix of LT $L : \mathcal{P}_1 \rightarrow \mathcal{P}_1$ with respect to basis $B = (x + 1, x - 1)$ be $\begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$. Find the matrix of L with respect to basis $C = (x, 1)$.

Solution: Since $A_{BB} = \begin{bmatrix} 2 & 3 \\ -1 & -2 \end{bmatrix}$, we have

$$L(x + 1) = 2(x + 1) - 1(x - 1) = x + 3$$

$$L(x - 1) = 3(x + 1) - 2(x - 1) = x + 5$$



$$L(ax + b) = L\left(\frac{a+b}{2}(x+1) + \frac{a-b}{2}(x-1)\right)$$



$$L(ax + b) = L\left(\frac{a+b}{2}(x+1) + \frac{a-b}{2}(x-1)\right)$$

$$L(ax + b) = \left(\frac{a+b}{2}(x+3) + \frac{a-b}{2}(x+5)\right)$$



$$L(ax + b) = L\left(\frac{a+b}{2}(x+1) + \frac{a-b}{2}(x-1)\right)$$

$$L(ax + b) = \left(\frac{a+b}{2}(x+3) + \frac{a-b}{2}(x+5)\right)$$

so that $L(x) = x + 4$ and $L(1) = -1$.



$$L(ax + b) = L\left(\frac{a+b}{2}(x+1) + \frac{a-b}{2}(x-1)\right)$$

$$L(ax + b) = \left(\frac{a+b}{2}(x+3) + \frac{a-b}{2}(x+5)\right)$$

so that $L(x) = x + 4$ and $L(1) = -1$.

Hence,

$$A_{CC} = \begin{bmatrix} 1 & 0 \\ 4 & -1 \end{bmatrix}.$$



Exercise: Consider the LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$, given by $L([x, y, z]) = [x + y, y - z]$.



Exercise: Consider the LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$, given by $L([x, y, z]) = [x + y, y - z]$. Compute A_{BC} with respect to bases $B = ([1, 0, 1], [0, 1, 1], [1, 1, 1])$ and $C = ([1, 2], [-1, 1])$.



Exercise: Consider the LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$, given by $L([x, y, z]) = [x + y, y - z]$. Compute A_{BC} with respect to bases $B = ([1, 0, 1], [0, 1, 1], [1, 1, 1])$ and $C = ([1, 2], [-1, 1])$.

Answer: $A_{BC} = \begin{bmatrix} 0 & 1/3 & 2/3 \\ -1 & -2/3 & -4/3 \end{bmatrix}$



Exercise: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{M}_{22}$, given by

$$L(ax^3 + bx^2 + cx + d) = \begin{bmatrix} -3a - 2c & -b + 4d \\ 4b - c + 3d & -6a - b + 2d \end{bmatrix}.$$

Compute A_{BC} with respect to standard bases for \mathcal{P}_3 and \mathcal{M}_{22} .



Exercise: Consider the LT $L : \mathcal{P}_3 \rightarrow \mathcal{M}_{22}$, given by

$$L(ax^3 + bx^2 + cx + d) = \begin{bmatrix} -3a - 2c & -b + 4d \\ 4b - c + 3d & -6a - b + 2d \end{bmatrix}.$$

Compute A_{BC} with respect to standard bases for \mathcal{P}_3 and \mathcal{M}_{22} .

Answer:

$$A_{BC} = \begin{bmatrix} -3 & 0 & -2 & 0 \\ 0 & -1 & 0 & 4 \\ 0 & 4 & -1 & 3 \\ -6 & -1 & 0 & 2 \end{bmatrix}$$



Exercise: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b.$$



Exercise: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b.$$

Compute A_{BC} with respect to bases $B = ([5, 3], [3, 2])$ and $C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$.



Exercise: Consider the LT $L : \mathbb{R}^2 \rightarrow \mathcal{P}_2$, given by

$$L([a, b]) = (-a + 5b)x^2 + (3a - b)x + 2b.$$

Compute A_{BC} with respect to bases $B = ([5, 3], [3, 2])$ and $C = (3x^2 - 2x, -2x^2 + 2x - 1, x^2 - x + 1)$.

Answer:

$$A_{BC} = \begin{bmatrix} 22 & 14 \\ 62 & 39 \\ 68 & 43 \end{bmatrix}$$



Exercise: Let $B = ([1, 2], [2, -1])$ and $C = ([1, 0], [0, 1])$ be ordered bases for \mathbb{R}^2 . If $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a LT such that $A_{BC} = \begin{bmatrix} 4 & 3 \\ 2 & -4 \end{bmatrix}$. Find $L([5, 5])$, Also, find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.



Exercise: Let $B = ([1, 2], [2, -1])$ and $C = ([1, 0], [0, 1])$ be ordered bases for \mathbb{R}^2 . If $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a LT such that $A_{BC} = \begin{bmatrix} 4 & 3 \\ 2 & -4 \end{bmatrix}$. Find $L([5, 5])$, Also, find $L([x, y])$ for all $[x, y] \in \mathbb{R}^2$.

Answer: $L([5, 5]) = [15, 2]$.



Exercise: Let

$$B = ([1, 1, 0, 0], [0, 1, 1, 0], [0, 0, 1, 1], [0, 0, 0, 1]) \text{ and}$$

$$C = ([1, 1, 1], [1, 2, 3], [1, 0, 0])$$

be ordered bases for \mathbb{R}^4 and \mathbb{R}^3 , respectively. If

$$L : \mathbb{R}^4 \rightarrow \mathbb{R}^3 \text{ be a LT such that } A_{BC} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}.$$

Find L ?



Exercise: Let

$$B = ([1, 1, 0, 0], [0, 1, 1, 0], [0, 0, 1, 1], [0, 0, 0, 1]) \text{ and}$$

$$C = ([1, 1, 1], [1, 2, 3], [1, 0, 0])$$

be ordered bases for \mathbb{R}^4 and \mathbb{R}^3 , respectively. If

$$L : \mathbb{R}^4 \rightarrow \mathbb{R}^3 \text{ be a LT such that } A_{BC} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}.$$

Find L ?

Answer:

$$L([x_1, x_2, x_3, x_4]) = [-2x_1 + 3x_2 + x_4, x_2 + 2x_3, x_2 + 3x_4]$$



Matrix for the composition of Linear Transformations:



Matrix for the composition of Linear Transformations:

Theorem: Let $\mathcal{V}_1, \mathcal{V}_2$ and \mathcal{V}_3 be nontrivial finite dimensional vector spaces with ordered bases B, C and D , respectively.



Matrix for the composition of Linear Transformations:

Theorem: Let $\mathcal{V}_1, \mathcal{V}_2$ and \mathcal{V}_3 be nontrivial finite dimensional vector spaces with ordered bases B, C and D , respectively. Let $L_1 : \mathcal{V}_1 \rightarrow \mathcal{V}_2$ be a linear transformation with matrix A_{BC} and let $L_2 : \mathcal{V}_2 \rightarrow \mathcal{V}_3$ be a linear transformation with matrix A_{CD} . Then matrix

$$A_{BD} = A_{CD}A_{BC}$$

is the matrix of linear transformation

$L_2 \circ L_1 : \mathcal{V}_1 \rightarrow \mathcal{V}_3$ with respect to the bases B and D



Example: Let $L_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and $L_2 : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by

$$L_1([x, y]) = [y, x]$$

$$L_2([x, y]) = [x + y, x - y, y]$$

- Find the matrix of L_1 and L_2 with respect to the standard basis in each case.



Example: Let $L_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and $L_2 : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by

$$L_1([x, y]) = [y, x]$$

$$L_2([x, y]) = [x + y, x - y, y]$$

- Find the matrix of L_1 and L_2 with respect to the standard basis in each case.
- Find the matrix of $L_2 \circ L_1$ with respect to standard basis of \mathbb{R}^2 and \mathbb{R}^3 .



Answer: The matrix of L_1 w.r. to $B = \{[1, 0], [0, 1]\}$ is

$$A_{BB} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$



Answer: The matrix of L_1 w.r. to $B = \{[1, 0], [0, 1]\}$ is

$$A_{BB} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

The matrix of L_2 w. r. to the bases $C = [1, 0], [0, 1]$ and $D = \{[1, 0, 0], [0, 1, 0], [0, 0, 1]\}$ is

$$A_{CD} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 0 & 1 \end{bmatrix}$$



Thus, the matrix A_{BD} of the linear transformation $L_2 \circ L_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ w.r. to the bases B and D is

$$A_{BD} = A_{CD}A_{BB} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -1 & 1 \\ 1 & 0 \end{bmatrix}$$



Theorem: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a linear transformation between n -dimensional vector spaces \mathcal{V} and \mathcal{W} and let B and C are ordered bases for \mathcal{V} and \mathcal{W} , respectively. Then L is an isomorphism (or invertible) if and only if the matrix representation A_{BC} for L with respect to B and C is nonsingular.



Theorem: Let $L : \mathcal{V} \rightarrow \mathcal{W}$ be a linear transformation between n -dimensional vector spaces \mathcal{V} and \mathcal{W} and let B and C are ordered bases for \mathcal{V} and \mathcal{W} , respectively. Then L is an isomorphism (or invertible) if and only if the matrix representation A_{BC} for L with respect to B and C is nonsingular.

In this case If D_{CB} is the matrix for L^{-1} with respect to C and B then $A_{BC}^{-1} = D_{CB}$.



Example: Let L_1 and L_2 be linear operators on \mathbb{R}^3 .
Let

$$A = \begin{bmatrix} 0 & -2 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 0 & 1 \\ 0 & -3 & 0 \end{bmatrix}$$

be matrices for L_1 and L_2 respectively, with respect to standard basis.



Example: Let L_1 and L_2 be linear operators on \mathbb{R}^3 .
Let

$$A = \begin{bmatrix} 0 & -2 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 0 & 1 \\ 0 & -3 & 0 \end{bmatrix}$$

be matrices for L_1 and L_2 respectively, with respect to standard basis.

- Show that L_1 and L_2 are isomorphisms.



Example: Let L_1 and L_2 be linear operators on \mathbb{R}^3 .
Let

$$A = \begin{bmatrix} 0 & -2 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 0 & 1 \\ 0 & -3 & 0 \end{bmatrix}$$

be matrices for L_1 and L_2 respectively, with respect to standard basis.

- Show that L_1 and L_2 are isomorphisms.

Answer: Since $\text{rank}(A) = 3$ and $\text{rank}(B) = 3$, the matrices A and B are nonsingular.



Example: Let L_1 and L_2 be linear operators on \mathbb{R}^3 .
Let

$$A = \begin{bmatrix} 0 & -2 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 0 & 1 \\ 0 & -3 & 0 \end{bmatrix}$$

be matrices for L_1 and L_2 respectively, with respect to standard basis.

- Show that L_1 and L_2 are isomorphisms.

Answer: Since $\text{rank}(A) = 3$ and $\text{rank}(B) = 3$, the matrices A and B are nonsingular. Hence, L_1 and L_2 are isomorphisms.



- Find matrices for L_1^{-1} and L_2^{-1} .



- Find matrices for L_1^{-1} and L_2^{-1} .

Answer: Since $L_1^{-1}(\mathbf{v}) = A^{-1}(\mathbf{v})$.



- Find matrices for L_1^{-1} and L_2^{-1} .

Answer: Since $L_1^{-1}(\mathbf{v}) = A^{-1}(\mathbf{v})$. Using row reduction (see Chapter 3), we have

$$A^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & -2 & 0 \end{bmatrix}$$



- Find matrices for L_1^{-1} and L_2^{-1} .

Answer: Since $L_1^{-1}(\mathbf{v}) = A^{-1}(\mathbf{v})$. Using row reduction (see Chapter 3), we have

$$A^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & -2 & 0 \end{bmatrix}$$

Similarly, $L_2^{-1}(\mathbf{v}) = B^{-1}(\mathbf{v})$, where

$$B^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1/3 \\ 2 & 1 & 0 \end{bmatrix}.$$



Thank You

