

Mathematics-II (MATH F112)

Linear Algebra

Jitender Kumar

Department of Mathematics
Birla Institute of Technology and Science Pilani
Pilani-333031



Section 3.4

Eigenvalues and Eigenvectors



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Example 1: For the matrix

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Note that $A \begin{bmatrix} 4 \\ 3 \\ 0 \end{bmatrix} = 2 \begin{bmatrix} 4 \\ 3 \\ 0 \end{bmatrix}$ implies $\lambda = 2$ is an **eigenvalue** of A and $X = [4, 3, 0]$ is the **eigenvector** corresponding to 2.



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Thus, if X is an eigenvector of A corresponding to an eigenvalue λ then, for $c \in \mathbb{R}$, cX is also an eigenvector corresponding to λ . Hence, there are infinitely many eigenvectors corresponding to an eigenvalue.



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Theorem: Let A be $n \times n$ matrix and λ be a real number. Then λ is an eigenvalue of A if and only if $|\lambda I_n - A| = 0$.



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Theorem: Let A be $n \times n$ matrix and λ be a real number. Then λ is an eigenvalue of A if and only if $|\lambda I_n - A| = 0$. The eigenvectors are the nontrivial solutions of the homogeneous system

$$(\lambda I_n - A)X = \mathbf{0}.$$



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The eigenvalues of an $n \times n$ matrix A are precisely the real roots of the characteristic polynomial $p_A(x)$.



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$$\begin{aligned} p_A(x) &= |xI_3 - A| = \begin{vmatrix} x-1 & 0 & -1 \\ 0 & x-2 & 3 \\ 0 & 0 & x+5 \end{vmatrix} \\ &= (x-1)(x-2)(x+5) \end{aligned}$$



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In Example 3 The algebraic multiplicity of each of the eigenvalues ($\lambda_1 = 1$, $\lambda_2 = 2$, $\lambda_3 = -5$) is 1.



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$$A = \begin{bmatrix} 4 & 0 & -2 \\ 6 & 2 & -6 \\ 4 & 0 & -2 \end{bmatrix}$$

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Theorem: Let A be an $n \times n$ matrix and λ be an eigenvalue of A . Then the eigenspace E_λ corresponding to λ is a subspace of \mathbb{R}^n .



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The geometric multiplicity of an eigenvalue λ is the dimension of its corresponding eigenspace E_λ i.e.



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$$E_1 = \{[a, 0] \mid a \in \mathbb{R}\} = \{a[1, 0] \mid a \in \mathbb{R}\}.$$



For the matrix B , the characteristic polynomial

$$p_B(x) = |xI_3 - B| = \begin{vmatrix} x-4 & 0 & 2 \\ -6 & x-2 & 6 \\ -4 & 0 & x+2 \end{vmatrix} = x(x-2)^2.$$



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$$(\lambda I_3 - B)X = 0 \text{ implies } -BX = 0.$$



The augmented matrix is

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The associated system is

$$x_1 - \frac{1}{2}x_3 = 0 \quad \text{and} \quad x_2 - \frac{3}{2}x_3 = 0$$



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$$E_0 = \text{span}\{[1, 3, 2]\} = \text{span}(B),$$

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$$\text{G.M. of } 0 = \dim E_0 = 1.$$



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$$[2I_3 - B|0] = \left[\begin{array}{ccc|c} -2 & 0 & 2 & 0 \\ -6 & 0 & 6 & 0 \\ -4 & 0 & 4 & 0 \end{array} \right]$$

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Now $E_2 = \text{span}(B)$, where $B = \{[0, 1, 0], [1, 0, 1]\}$. Since, B is LI (([verify it](#))), it is a basis for E_2 .

Note that

$$\text{G.M. of } 2 = \dim E_2 = 2.$$



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Example 5: Let A be a 2×2 matrix with eigenvectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ corresponding to eigenvalues $\lambda_1 = -1, \lambda_2 = 2$.



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Solution:

$$A^{10}X = \begin{bmatrix} 2051 \\ 4093 \end{bmatrix}_{2 \times 1}$$



Exercise: Consider

$$A = \begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$$



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- Find all the eigenvalues of A and compute their algebraic multiplicity.
- Find eigenspaces corresponding to each of the eigenvalues of A and compute their geometric multiplicity.



Exercise: Consider

$$A = \begin{bmatrix} -9 & 4 & 4 \\ -8 & 3 & 4 \\ -16 & 8 & 7 \end{bmatrix}$$



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Thank You

