

Chapter 4 : A.P. French

Lec : 5, 6, 10, 17 Tut : 4, 8, 13 Suggested : 2, 3, 7, 9, 11, 12, 14, 15

Problem no. 16 is not in the course.

4.4. From (1)  $kh = mg \Rightarrow \frac{k}{m} = \frac{g}{h}$  and From (2)  $bu = mg \Rightarrow \frac{b}{m} = \frac{g}{u}$

(a) Diff. eq. of damped harmonic motion :  $m\ddot{x} + b\dot{x} + kx = 0$

$$\Rightarrow \ddot{x} + \frac{b}{m}\dot{x} + \frac{k}{m}x = 0 \Rightarrow \ddot{x} + \frac{g}{u}\dot{x} + \frac{g}{h}x = 0$$

(b)  $\gamma = \frac{b}{m} = \frac{g}{u} = \frac{g}{3\sqrt{gh}} = \frac{1}{3}\sqrt{\frac{g}{h}}$  and  $\omega_0^2 = \frac{g}{h}; \therefore \omega^2 = \omega_0^2 - \frac{\gamma^2}{4} \Rightarrow \omega = \sqrt{\frac{35}{36} \frac{g}{h}}$

(c)  $E = E_0 e^{-\gamma t} \Rightarrow \frac{E}{E_0} = e^{-1} = e^{-\gamma t} \Rightarrow t = \frac{1}{\gamma} = 3\sqrt{\frac{h}{g}}$

(d)  $Q = \frac{\omega}{\gamma} = \sqrt{\frac{35}{36} \frac{g}{h}} \times 3\sqrt{\frac{h}{g}} = \sqrt{\frac{35}{4}} \approx 3$

(e)  $x = Ae^{-\frac{\gamma}{2}t} \cos(\omega t - \delta); \text{ At } t = 0, x = 0; \therefore \cos(-\delta) = 0 \Rightarrow \delta = \frac{\pi}{2}$

At  $t = 0, \dot{x} = v_0$  (say)  $\Rightarrow A\left(-\frac{\gamma}{2}\right)e^{-\frac{\gamma}{2}t} \cos(\omega t - \delta) - A\omega e^{-\frac{\gamma}{2}t} \sin(\omega t - \delta) = v_0$

At  $t = 0, \therefore \dot{x} = 0 - A\omega \sin(-\delta) = A\omega = v_0 \Rightarrow v_0 = A\omega \Rightarrow A = \frac{v_0}{\omega}$

$\therefore x = \frac{v_0}{\omega} e^{-\frac{\gamma}{2}t} \cos(\omega t - \delta) = \frac{v_0}{\omega} e^{-\frac{\gamma}{2}t} \cos\left(\omega t - \frac{\pi}{2}\right) = \frac{v_0}{\omega} e^{-\frac{\gamma}{2}t} \sin \omega t$  Do the graph.

(f)  $F = F_0 \cos \omega t \approx F_0 e^{i\omega t} = mge^{i\omega t}$

$\therefore m\ddot{x} + b\dot{x} + kx = mge^{i\omega t} \Rightarrow x = \frac{ge^{i\omega t}}{[-\omega_0^2 + \omega^2 + i\gamma\omega]}; x^* = \frac{ge^{-i\omega t}}{[-\omega_0^2 + \omega^2 - i\gamma\omega]} = -\frac{ge^{-i\omega t}}{[\omega_0^2 - \omega^2 + i\gamma\omega]} =$

$\therefore A^2(\omega) = xx^* = \frac{g^2}{[(\omega^2 - \omega_0^2)^2 + \gamma^2\omega^2]} \Rightarrow A(\omega) = \frac{g}{\sqrt{[(\omega^2 - \omega_0^2)^2 + \gamma^2\omega^2]}}$

Now,  $\omega_0^2 = \frac{g}{h}, \omega^2 = \frac{2g}{h}$  and  $\gamma^2\omega^2 = \left(\frac{1}{3}\sqrt{\frac{g}{h}} \cdot \sqrt{2}\sqrt{\frac{g}{h}}\right)^2 = \frac{2}{9} \frac{g^2}{h^2}; \therefore A(\omega) = \frac{g}{\sqrt{\frac{g^2}{h^2} + \frac{2}{9} \frac{g^2}{h^2}}} = h \frac{3}{\sqrt{11}} \approx 0.9h$

4.8. (a) If the spring force is absent, the diff. eq.

$$m\ddot{x} + b\dot{x} = 0; \text{ The trial solution given : } x = C - \frac{v_0}{\gamma} e^{-\gamma t} \therefore \dot{x} = v_0 e^{-\gamma t} \text{ and } \ddot{x} = -v_0 \gamma e^{-\gamma t}$$

$$\Rightarrow m\ddot{x} + b\dot{x} = -mv_0 \gamma e^{-\gamma t} + bv_0 e^{-\gamma t} = v_0 (-m\gamma + b) e^{-\gamma t} = v_0 \left( -m \frac{b}{m} + b \right) e^{-\gamma t} = 0.$$

So, the trial solution satisfies the diff. eq. and hence is a possible form of solution.

$$(b) x = A \cos(\omega t - \delta); \text{ At } t = 0, x = 0 \text{ and } \dot{x} = v_0 \text{ (say)} \therefore \cos(-\delta) = 0 \text{ and } \delta = \frac{\pi}{2}$$

In absence of spring force, the differential equation :  $m\ddot{x} + b\dot{x} = F_0 \cos \omega t \approx \text{real part of } F_0 e^{i\omega t}$

$$\therefore \ddot{x} + \gamma \dot{x} = \frac{F_0}{m} e^{i\omega t} \Rightarrow \text{Following the mathematical method :}$$

$$x = \frac{\frac{F_0}{m} e^{i\omega t}}{-\omega^2 + i\gamma\omega} = -\frac{\frac{F_0}{m} e^{i\omega t}}{\omega^2 - i\gamma\omega}; \therefore xx^* = \left( -\frac{\frac{F_0}{m} e^{i\omega t}}{\omega^2 - i\gamma\omega} \right) \left( -\frac{\frac{F_0}{m} e^{i\omega t}}{\omega^2 - i\gamma\omega} \right)^*$$

$$= \frac{\left( \frac{F_0}{m} \right)^2}{(\omega^2 - i\gamma\omega)(\omega^2 + i\gamma\omega)} = \frac{\left( \frac{F_0}{m} \right)^2}{(\omega^4 + \gamma^2 \omega^2)};$$

$$\therefore \boxed{\text{Amplitude} = \sqrt{xx^*} = \frac{F_0}{m\sqrt{\omega^4 + \gamma^2 \omega^2}} \text{ and } \tan \delta = \frac{\gamma\omega}{\omega^2} = \frac{\gamma}{\omega}}$$

$$\therefore \text{Complete solution : } x = C - \frac{v_0}{\gamma} e^{-\gamma t} + A \cos(\omega t - \delta)$$

$$\text{At } t = 0, x = 0; \Rightarrow C - \frac{v_0}{\gamma} + A \cos \delta = 0 \Rightarrow \boxed{C = \frac{v_0}{\gamma} - A \cos \delta}$$

$$\text{At } t = 0, \dot{x} = 0; \Rightarrow v_0 - A\omega \sin(-\delta) = v_0 + A\omega \sin \delta = 0 \Rightarrow \boxed{v_0 = -A\omega \sin \delta}$$

$$\therefore \boxed{C = \frac{v_0}{\gamma} - A \cos \delta = -A \left( \frac{\omega}{\gamma} \sin \delta + \cos \delta \right)}$$

4.13.

(a) w.r.t. the fig.

$$\omega_0 = 40 \text{ s}^{-1} \text{ and } \Delta\omega = 2 \text{ s}^{-1} \Rightarrow \boxed{Q = \frac{\omega_0}{\Delta\omega} = 20}$$

$$(b) \gamma = \frac{\omega_0}{Q} = \Delta\omega = 2 \text{ s}^{-1}$$

$$\therefore E(t) = E_0 e^{-\gamma t} = E_0 \cdot e^{-5} \Rightarrow \gamma t = 5 \Rightarrow t = \frac{5}{\gamma} = \frac{5}{2} = 2.5 \text{ s}^{-1}.$$

$$\text{Time period of oscillation: } \frac{2\pi}{\omega_0} = \frac{2\pi}{40} = \frac{\pi}{20} = 0.05\pi \text{ s}$$

$$\therefore 0.05\pi \text{ sec} \equiv 1 \text{ cycle} \Rightarrow 0.05\pi \text{ sec} = \frac{2.5}{0.05\pi} = \frac{50}{3.14} = 15.92 \approx 16 \text{ cycle}.$$