

MATHEMATICS-II (MATH F112)

Dr. Krishnendra Shekhawat

BITS PILANI
Department of Mathematics



Section 5.4

One-to-One and Onto Linear Transformations



One-to-One and Onto



One-to-One and Onto

Let $L : V \rightarrow W$ be a LT. L is **one-to-one** if and only if



One-to-One and Onto

Let $L : V \rightarrow W$ be a LT. L is **one-to-one** if and only if for all $v_1, v_2 \in V$, $L(v_1) = L(v_2)$ implies $v_1 = v_2$,



One-to-One and Onto

Let $L : V \rightarrow W$ be a LT. L is **one-to-one** if and only if for all $v_1, v_2 \in V$, $L(v_1) = L(v_2)$ implies $v_1 = v_2$, i.e., $v_1 \neq v_2$ implies $L(v_1) \neq L(v_2)$.



One-to-One and Onto

Let $L : V \rightarrow W$ be a LT. L is **one-to-one** if and only if for all $v_1, v_2 \in V$, $L(v_1) = L(v_2)$ implies $v_1 = v_2$, i.e., $v_1 \neq v_2$ implies $L(v_1) \neq L(v_2)$.

L is **onto** if and only if,



One-to-One and Onto

Let $L : V \rightarrow W$ be a LT. L is **one-to-one** if and only if for all $v_1, v_2 \in V$, $L(v_1) = L(v_2)$ implies $v_1 = v_2$, i.e., $v_1 \neq v_2$ implies $L(v_1) \neq L(v_2)$.

L is **onto** if and only if, for every $w \in W$, there is some $v \in V$ such that $L(v) = w$.



Example 1

Q: Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto (Why?)



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto (Why?)

Let $q \in P_2$.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto (Why?)

Let $q \in P_2$. Now, there must exist $p \in P_3$ such that
 $L(p) = q$.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$.
Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since,
 $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto (Why?)

Let $q \in P_2$. Now, there must exist $p \in P_3$ such that
 $L(p) = q$. Consider $p = \int q(x)dx$ with zero constant
term.



Example 1

Q:. Consider a LT $L : P_3 \rightarrow P_2$ given by $L(p) = p'$. Check if L is one-to-one and onto.

Sol. L is not one-to-one (Why?)

Consider $p_1 = x + 1$ and $p_2 = x + 2$. Since, $L(p_1) = L(p_2) = 1$, L is not one-to-one.

L is onto (Why?)

Let $q \in P_2$. Now, there must exist $p \in P_3$ such that $L(p) = q$. Consider $p = \int q(x)dx$ with zero constant term. Because $L(p) = q$, we see that L is onto.



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$.



Example 2

Q.: Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies$



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies$



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies [x_1, y_1] = [x_2, y_2]$.



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies [x_1, y_1] = [x_2, y_2]$. Hence, L is one-to-one.



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies [x_1, y_1] = [x_2, y_2]$. Hence, L is one-to-one.

L is not onto



Example 2

Q.: Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies [x_1, y_1] = [x_2, y_2]$. Hence, L is one-to-one.

L is not onto since, its range is not all of \mathbb{R}^3 .



Example 2

Q:. Consider a LT $L : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ given by $L([x, y]) = [2x, x - y, 0]$. Check if L is one-to-one and onto.

Sol. Let $L([x_1, y_1]) = L([x_2, y_2]) \implies [2x_1, x_1 - y_1, 0] = [2x_2, x_2 - y_2, 0] \implies [x_1, y_1] = [x_2, y_2]$. Hence, L is one-to-one.

L is not onto since, its range is not all of \mathbb{R}^3 . To be specific, there is no vector $[x, y] \in \mathbb{R}^2$ such that $L([x, y]) = [0, 0, 1]$.



Exercise

Q:. Which of the following transformations are one-to-one? onto?



Exercise

Q:. Which of the following transformations are one-to-one? onto?

1. $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = ([y, z, -y, 0])$.



Exercise

Q:. Which of the following transformations are one-to-one? onto?

1. $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = ([y, z, -y, 0])$.
2. $L : M_{22} \rightarrow M_{22}$ given by $L(A) = A^T$.



Exercise

Q:. Which of the following transformations are one-to-one? onto?

1. $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = ([y, z, -y, 0])$.
2. $L : M_{22} \rightarrow M_{22}$ given by $L(A) = A^T$.

Sol. 1. neither one-to-one nor onto



Exercise

Q:. Which of the following transformations are one-to-one? onto?

1. $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = ([y, z, -y, 0])$.
2. $L : M_{22} \rightarrow M_{22}$ given by $L(A) = A^T$.

Sol. 1. neither one-to-one nor onto

2. one-to-one and onto



Exercise

Q.: Which of the following transformations are one-to-one? onto?

1. $L : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ given by $L([x, y, z]) = ([y, z, -y, 0])$.
2. $L : M_{22} \rightarrow M_{22}$ given by $L(A) = A^T$.

Sol. 1. neither one-to-one nor onto

2. one-to-one and onto

3. Show that the LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $L([x, y, z]) = ([x - y, y])$ is onto but not one-one.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_V\}$ (i.e., $\dim \ker(L) = 0$).



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{0_V\}$ (i.e., $\dim \ker(L) = 0$).

Proof. Suppose L is one-to-one and let $v \in \ker(L)$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{\mathbf{0}_V\}$ (i.e., $\dim \ker(L) = 0$).

Proof. Suppose L is one-to-one and let $v \in \ker(L)$. We need to show that $v = \mathbf{0}_V$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{\mathbf{0}_V\}$ (i.e., $\dim \ker(L) = 0$).

Proof. Suppose L is one-to-one and let $v \in \ker(L)$. We need to show that $v = \mathbf{0}_V$. Now $L(v) = \mathbf{0}_W$



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{\mathbf{0}_V\}$ (i.e., $\dim \ker(L) = 0$).

Proof. Suppose L is one-to-one and let $v \in \ker(L)$. We need to show that $v = \mathbf{0}_V$. Now $L(v) = \mathbf{0}_W$ and from Theorem 5.1, $L(\mathbf{0}_V) = \mathbf{0}_W \implies L(v) = L(\mathbf{0}_V)$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if $\ker(L) = \{\mathbf{0}_V\}$ (i.e., $\dim \ker(L) = 0$).

Proof. Suppose L is one-to-one and let $v \in \ker(L)$. We need to show that $v = \mathbf{0}_V$. Now $L(v) = \mathbf{0}_W$ and from Theorem 5.1, $L(\mathbf{0}_V) = \mathbf{0}_W \implies L(v) = L(\mathbf{0}_V)$. Because L is one-to-one, we have $v = \mathbf{0}_V$.



Conversely, let $\ker(L) = \{0_V\}$.



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one.



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$.



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$. Now, $L(v_1) - L(v_2) = \mathbf{0}_W \implies$



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$. Now, $L(v_1) - L(v_2) = \mathbf{0}_W \implies L(v_1 - v_2) = \mathbf{0}_W \implies$



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$. Now,
$$L(v_1) - L(v_2) = \mathbf{0}_W \implies L(v_1 - v_2) = \mathbf{0}_W \implies v_1 - v_2 \in \ker(L).$$



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$. Now, $L(v_1) - L(v_2) = \mathbf{0}_W \implies L(v_1 - v_2) = \mathbf{0}_W \implies v_1 - v_2 \in \ker(L)$. Since, $\ker(L) = \{\mathbf{0}_V\} \implies$



Conversely, let $\ker(L) = \{\mathbf{0}_V\}$. We need to show that L is one-to-one. Let $v_1, v_2 \in V$ with $L(v_1) = L(v_2)$. Now, $L(v_1) - L(v_2) = \mathbf{0}_W \implies L(v_1 - v_2) = \mathbf{0}_W \implies v_1 - v_2 \in \ker(L)$. Since, $\ker(L) = \{\mathbf{0}_V\} \implies v_1 - v_2 = \mathbf{0}_V \implies v_1 = v_2$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(W)$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(W)$.

Proof. By definition, L is onto if and only if $\text{range}(L) = W$.



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(W)$.

Proof. By definition, L is onto if and only if $\text{range}(L) = W$. And from Theorem 4.16, $\dim V = \dim W$ if and only if $V = W$



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(W)$.

Proof. By definition, L is onto if and only if $\text{range}(L) = W$. And from Theorem 4.16, $\dim V = \dim W$ if and only if $V = W$ where W is a subspace of V .



Theorem: Let V and W be vector spaces, and let $L : V \rightarrow W$ be a LT. If W is finite dimensional, then L is onto if and only if $\dim(\text{range}(L)) = \dim(W)$.

Proof. By definition, L is onto if and only if $\text{range}(L) = W$. And from Theorem 4.16, $\dim V = \dim W$ if and only if $V = W$ where W is a subspace of V . This concludes the proof.



Example 3

Q: Consider a LT $L : M_{22} \rightarrow M_{23}$ given by

$$L \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$



Example 3

Q: Consider a LT $L : M_{22} \rightarrow M_{23}$ given by

$$L \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$

Is L one-to-one and onto.



Example 3

Q:. Consider a LT $L : M_{22} \rightarrow M_{23}$ given by

$$L \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix}$$

Is L one-to-one and onto. Also find a basis for $\text{range}(L)$.



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix,



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix, i.e.,
 $\dim(\ker(L)) = 0$



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix, i.e.,
 $\dim(\ker(L)) = 0$ implies L is one-to-one.



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix, i.e., $\dim(\ker(L)) = 0$ implies L is one-to-one.

From Dimension Theorem, we can directly conclude that $\dim(\text{range}(L)) = \dim(M_{22}) - \dim(\ker(L)) = 4$.



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix, i.e., $\dim(\ker(L)) = 0$ implies L is one-to-one.

From Dimension Theorem, we can directly conclude that $\dim(\text{range}(L)) = \dim(M_{22}) - \dim(\ker(L)) = 4$. Hence, $\dim(\text{range}(L)) = 4 \neq \dim(M_{23}) \implies$



Sol. If $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \ker(L)$ then

$a - b = c - d = c + d = a + b = 0$ implies $a = b = c = d = 0$.

Hence, $\ker(L)$ contains only the zero matrix, i.e., $\dim(\ker(L)) = 0$ implies L is one-to-one.

From Dimension Theorem, we can directly conclude that $\dim(\text{range}(L)) = \dim(M_{22}) - \dim(\ker(L)) = 4$. Hence, $\dim(\text{range}(L)) = 4 \neq \dim(M_{23}) \implies L$ is not onto.



$$\text{range}(L) = \left\{ \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} \mid \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{22} \right\}$$



$$\text{range}(L) = \left\{ \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} \mid \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{22} \right\}$$

$$\begin{aligned} \text{Now, } \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} = \\ a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + b \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix} \implies \end{aligned}$$



$$\text{range}(L) = \left\{ \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} \mid \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{22} \right\}$$

$$\text{Now, } \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} =$$

$$a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + b \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix} \Rightarrow$$

$$\text{range}(L) =$$

$$\text{span} \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix} \right\} =$$

$$\text{span}(\mathbf{B}).$$



$$\text{range}(L) = \left\{ \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} \mid \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in M_{22} \right\}$$

$$\text{Now, } \begin{bmatrix} a-b & 0 & c-d \\ c+d & a+b & 0 \end{bmatrix} =$$

$$a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + b \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix} \Rightarrow$$

$$\text{range}(L) =$$

$$\text{span} \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \end{bmatrix} \right\} =$$

$$\text{span}(\mathbf{B}).$$

Since \mathbf{B} is LI, it forms a basis for $\text{range}(L)$.



Example 4

Q:. Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



Example 4

Q:. Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Is L one-to-one and onto.



Example 4

Q.: Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Is L one-to-one and onto.

Sol. The matrix $\begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix}$ row reduces to



Example 4

Q.: Consider a LT $L : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

Is L one-to-one and onto.

Sol. The matrix $\begin{bmatrix} -7 & 4 & -2 \\ 16 & -7 & 2 \\ 4 & -3 & 2 \end{bmatrix}$ row reduces to

$$\begin{bmatrix} 1 & 0 & -2/5 \\ 0 & 1 & -6/5 \\ 0 & 0 & 0 \end{bmatrix}.$$



From range method,



From range method, $\dim(\text{range}(L)) = 2$



From range method, $\dim(\text{range}(L)) = 2$ and from Dimension Theorem, $\dim(\ker(L)) = 1$.



From range method, $\dim(\text{range}(L)) = 2$ and from Dimension Theorem, $\dim(\ker(L)) = 1$. Hence, L is neither one-to-one nor onto.



From range method, $\dim(\text{range}(L)) = 2$ and from Dimension Theorem, $\dim(\ker(L)) = 1$. Hence, L is neither one-to-one nor onto.

Result: Let V and W be finite dimensional vector spaces with $\dim(V) = \dim(W)$. Let $L : V \rightarrow W$ be a LT.



From range method, $\dim(\text{range}(L)) = 2$ and from Dimension Theorem, $\dim(\ker(L)) = 1$. Hence, L is neither one-to-one nor onto.

Result: Let V and W be finite dimensional vector spaces with $\dim(V) = \dim(W)$. Let $L : V \rightarrow W$ be a LT. Then L is one-to-one if and only if L is onto.



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$.



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.

Sol. $L(I_n) =$



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.

Sol. $L(I_n) = AI_n - I_nA = 0_n$.



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.

Sol. $L(I_n) = AI_n - I_nA = 0_n$. Hence, $I_n \in \ker(L)$



Example 5

Q:. Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.

Sol. $L(I_n) = AI_n - I_nA = 0_n$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one.



Example 5

Q.: Let A be a fixed $n \times n$ matrix, and consider a LT $L : M_{nn} \rightarrow M_{nn}$ given by $L(B) = AB - BA$. Is L one-to-one and onto.

Sol. $L(I_n) = AI_n - I_nA = 0_n$. Hence, $I_n \in \ker(L)$ and so, L is not one-to-one. Now from Dimension Theorem, we can conclude L is not onto.



Example 6

Q:. Consider a LT $L : P \rightarrow P$ given by $L(p(x)) = xp(x)$.



Example 6

Q:. Consider a LT $L : P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.



Example 6

Q.: Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies$



Example 6

Q:. Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.



Example 6

Q:. Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.
Hence, L is one-to-one.



Example 6

Q:. Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.

Hence, L is one-to-one. Now, the constant polynomial is not in $\text{range}(L)$,



Example 6

Q:. Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.

Hence, L is one-to-one. Now, the constant polynomial is not in $\text{range}(L)$, L is not onto



Example 6

Q:. Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.

Hence, L is one-to-one. Now, the constant polynomial is not in $\text{range}(L)$, L is not onto (Here we can not use Dimension Theorem)



Example 6

Q.: Consider a LT $L: P \rightarrow P$ given by $L(p(x)) = xp(x)$. Is L one-to-one and onto.

Sol. $\ker(L) = \{p(x) | L(p(x)) = 0_P\} \implies \ker(L) = \{0_P\}$.

Hence, L is one-to-one. Now, the constant polynomial is not in $\text{range}(L)$, L is not onto (Here we can not use Dimension Theorem because P is infinite dimensional).



Exercises

Q:. Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$



Exercises

Q:. Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto.



Exercises

Q:. Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is onto but not one-to-one.



Exercises

Q.: Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is onto but not one-to-one.

Q.: Consider a LT $L : P_2 \rightarrow P_2$ given by
 $L(ax^2 + bx + c) = (a+b)x^2 + (b+c)x + (a+c)$.



Exercises

Q.: Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is onto but not one-to-one.

Q.: Consider a LT $L : P_2 \rightarrow P_2$ given by $L(ax^2 + bx + c) = (a+b)x^2 + (b+c)x + (a+c)$. Is L one-to-one and onto.



Exercises

Q.: Consider a LT $L : M_{23} \rightarrow M_{22}$ given by

$$L \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} = \begin{bmatrix} a+b & a+c \\ d+e & d+f \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is onto but not one-to-one.

Q.: Consider a LT $L : P_2 \rightarrow P_2$ given by $L(ax^2 + bx + c) = (a+b)x^2 + (b+c)x + (a+c)$. Is L one-to-one and onto.

Sol. L is one-to-one and onto.



Q:. Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$



Q.: Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto.



Q:. Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is not one-to-one but onto.



Q:. Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}\right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is not one-to-one but onto.

Q:. Consider a LT $L : U_3 \rightarrow M_{33}$ given by
 $L(A) = (A + A^T)/2$.



Q:. Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is not one-to-one but onto.

Q:. Consider a LT $L : U_3 \rightarrow M_{33}$ given by $L(A) = (A + A^T)/2$. Is L one-to-one and onto.



Q:. Consider a LT $L : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ given by

$$L\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}\right) = \begin{bmatrix} -5 & 3 & 1 & 18 \\ -2 & 1 & 1 & 6 \\ -7 & 3 & 4 & 19 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Is L one-to-one and onto.

Sol. L is not one-to-one but onto.

Q:. Consider a LT $L : U_3 \rightarrow M_{33}$ given by $L(A) = (A + A^T)/2$. Is L one-to-one and onto.

Sol. L is one-to-one but not onto.

