MATHEMATICS-II (MATH F112)

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Section 5.3

The Dimension Theorem





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$$\ker(L) = \{ v \in V | L(v) = \mathbf{0}_W \}$$





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Result: If $L: V \to W$ is a LT, then $\ker(L)$ is a subspace of V.





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$$range(L) = \{L(v)|v \in V\}$$

Thus a vector $w \in range(L)$ if there exists some vector $v \in V$ such that L(v) = w.





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$$\begin{cases} \text{range}(L) = \{L([x, y, z]) | [x, y, z] \in \mathbb{R}^3\} \\ = \{[0, y] | y \in \mathbb{R}\} \\ = \{y[0, 1] | y \in \mathbb{R}\} \end{cases}$$



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Note that range(L) = span{[0,1]}. Since {[0,1]} is LI subset of \mathbb{R}^2 (Why?).





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Now, $\{[1,0,0],[0,0,1]\}$ is a LI subset of \mathbb{R}^3 , hence, they form a basis for $\ker(L)$.



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&= \{[x - 2y, y + z] | x, y, z \in \mathbb{R}\} \\
&= \{x[1, 0] + y[-2, 1] + z[0, 1] | x, y, z \in \mathbb{R}\}
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Basis for range(L) is {[1,0],[0,1]}.



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Sol. $\ker(L) = \{[0, b, -b, b] | b \in \mathbb{R}\} = \operatorname{span}\{[0, 1, -1, 1]\}$ and $\operatorname{range}(L) = \operatorname{span}\{1, x + x^2, x, x^2\} = \operatorname{span}\{1, x, x^2\}.$

Q: Let $L: \mathbb{R}^3 \to \mathbb{R}^4$ be a LT given by

L([x,y,z]) = [x,y-z,x-y+z,x+y-z]. Find a basis for $\ker(L)$ and $\operatorname{range}(L)$.



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L([x,y,z]) = [x,y-z,x-y+z,x+y-z]. Find a basis for $\ker(L)$ and $\operatorname{range}(L)$.

Sol. $\{[0,1,1]\}$ is a basis for for ker(L) and

 $\{[1,0,1,1],[0,1,-1,1]\}$ is a basis for range(L).





Let $L: \mathbb{R}^n \to \mathbb{R}^m$ be a LT.



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For Example 4, we have L(X) = AX where

$$X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ and } A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix}$$





$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



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Step 2: Find matrix B, the RREF of A.

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$$BX = 0$$
 gives

$$x = 0, y = z \implies \ker(L) = \{[0, z, z] | z \in \mathbb{R}\} = \operatorname{span}\{[0, 1, 1]\}$$



Step 4: Find a LI subset of S which forms a basis for $\ker(L)$.



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For Example 4, $\{[0,1,1]\}$ is a basis for for ker(L).



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 $\{[1,0,1,1],[0,1,-1,1]\}$ is a basis of range (L).

Q:. Let $L: \mathbb{R}^3 \to \mathbb{R}^3$ be a LT given by

$$L\begin{pmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 5 & 1 & -1 \\ -3 & 0 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$



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• Is $[1, -2, 3]^T \in \ker(L)$.



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- Is $[2,-1,4]^T \in \text{range}(L)$.



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- Is $[1, -2, 3]^T \in \ker(L)$.
- Is $[2,-1,4]^T \in \text{range}(L)$.

Sol. Yes, $[1, -2, 3]^T \in \ker(L)$ because $L([1, -2, 3]^T) = [0, 0, 0]^T$.





If $v = [2, -1, 4]^T \in \text{range}(L)$, then there would exist a vector $X = [x, y, z]^T$ such that AX = v.



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$$\begin{cases} 5x + y - z = 2 \\ -3x + z = -1 \\ x - y - z = 4 \end{cases}$$



If $v = [2, -1, 4]^T \in \text{range}(L)$, then there would exist a vector $X = [x, y, z]^T$ such that AX = v. This is equivalent to the system

$$\begin{cases} 5x + y - z = 2 \\ -3x + z = -1 \end{cases}$$
 which has no solution.
$$x - y - z = 4$$



The Dimension Theorem



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If $L: V \to W$ is a LT and V is finite dimensional, then range(L) is finite dimensional, and

$$\dim(\ker(L)) + \dim(\operatorname{range}(L)) = \dim(V)$$



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If $L: V \to W$ is a LT and V is finite dimensional, then range(L) is finite dimensional, and

$$\dim(\ker(L)) + \dim(\operatorname{range}(L)) = \dim(V)$$

Note: $\dim(\ker(L))$ is called $\operatorname{nullity}(L)$ and $\dim(\operatorname{range}(L))$ is called $\operatorname{rank}(L)$.





Q:. Consider a LT $L: P_2 \to P_3$ given by

$$L(a+bx+cx^2) = x(a+bx+cx^2).$$



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Sol.

$$\ker(L) = \{(a+bx+cx^2) \in P_2 | L(a+bx+cx^2) = 0_{P_3} \}$$

$$= \{(a+bx+cx^2) \in P_2 | ax+bx^2+cx^3 = 0 \}$$

$$= \{(a+bx+cx^2) \in P_2 | a=b=c=0 \}$$

$$= \{0_{P_2} \}$$

$$\implies$$
 dim(ker(L)) = 0.



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Also $\dim(\operatorname{range}(L)) = 3$ (why).



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 (why). Since, $\dim(P_2) = 3$,



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$$\implies$$
 dim(ker(L)) = 0.

Also $\dim(\operatorname{range}(L)) = 3$ (why). Since, $\dim(P_2) = 3$, clearly, we have $\dim(\ker(L)) + \dim(\operatorname{range}(L)) = \dim(P_2)$.





Q:. Consider a LT $L: M_{33} \to \mathbb{R}$ given by

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 $L(A) = \operatorname{trace}(A)$. Find $\ker(L)$, $\dim(\ker(L))$, $\operatorname{range}(L)$ and $\dim(\operatorname{range}(L))$.

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L(A) = trace(A). Find $\ker(L)$, $\dim(\ker(L))$, range(L) and $\dim(\text{range}(L))$.

Sol.
$$\ker(L) = \begin{cases} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & -a - e \end{bmatrix} \in M_{33} | a, b, c, d, e, f, g, h \in \mathbb{R} \end{cases} \Longrightarrow$$



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 $\dim(\ker(L)) = 3$ and $\dim(\operatorname{range}(L)) = 6$.





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Sol. False, range(L) is a subspace of W.

Exercises

Q:. Let W be the vector space of all 2×2 symmetric matrices. Define a LT $L: W \to P_2$ by

$$L\left(\begin{bmatrix} a & b \\ b & c \end{bmatrix}\right) = (a-b) + (b-c)x + (c-a)x^2$$

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Find $\dim(\ker(L))$ and $\dim(\operatorname{range}(L))$.

Sol. dim(ker(L)) = 1 and dim(range(L)) = 2.



Q:. Let $\{e_1, e_2, e_3, e_4\}$ be standard basis for \mathbb{R}^4 and $L: \mathbb{R}^4 \to \mathbb{R}^3$ be a LT given by



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Sol. $\dim(\ker(L)) = 1$ and $\dim(\operatorname{range}(L)) = 3$.



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