

# Dynamical Systems: Homework #1

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Aditya Vijaykumar

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## Problem 1

$$\dot{x} = x^{1/3} \implies \frac{dx}{x^{1/3}} = dt \implies \frac{2}{3}(x^{2/3} - x_0^{2/3}) = t \implies x(t) = \left(x_0^{2/3} + \frac{3}{2}t\right)^{3/2} \quad (1)$$

For  $x_0 = 0$ , we have  $x(t) = \left(\frac{3t}{2}\right)^{3/2}$ . As the function  $f(y) = y^{3/2}$  is only defined for  $y \geq 0$ , this solution has maximum interval of existence  $t \in [0, \infty)$ . For  $x_0 = 0$ , we also have the trivial solution  $x(t) = 0$  which has maximum interval of existence  $t \in (-\infty, \infty)$ . So there are at least two distinct solutions for  $x_0 = 0$ . One can also imagine patching up the above solutions at origin and forming other possible solutions.

For the case where  $x_0 \neq 0$ , we are only left with [1]. As  $x_0^{2/3} > 0, \forall x_0 \neq 0$ , the maximal interval of existence for  $x(t)$  is  $\left[-\frac{2}{3}x_0^{2/3}, \infty\right)$ .

If we try to solve the problem numerically, we only get the trivial solution  $x(t) = 0$  for  $x_0 = 0$ .

## Problem 2

Part (a)

$$\dot{x} = x(x^2 - 1)$$

For  $x_0 = 0, 1, -1$ ,  $x(t) = 0, 1, -1$  respectively is a solution for all times.

$$\begin{aligned} \therefore \frac{dx}{x(x-1)(x+1)} &= dt \\ \therefore -\frac{dx}{x} + \frac{1}{2} \left[ \frac{dx}{x+1} + \frac{dx}{x-1} \right] &= dt \\ \frac{1}{2} \log \left| \frac{x_0^2(x^2-1)}{x^2(x_0^2-1)} \right| &= t \\ \frac{(x^2-1)}{x^2} &= \pm \frac{x_0^2-1}{x_0^2} e^{2t} \\ x(t) &= \sqrt{\frac{1}{1 \pm \frac{x_0^2-1}{x_0^2} e^{2t}}} \end{aligned}$$

We take only the  $-$  sign in the above expression as the  $+$  sign does not satisfy the initial condition.

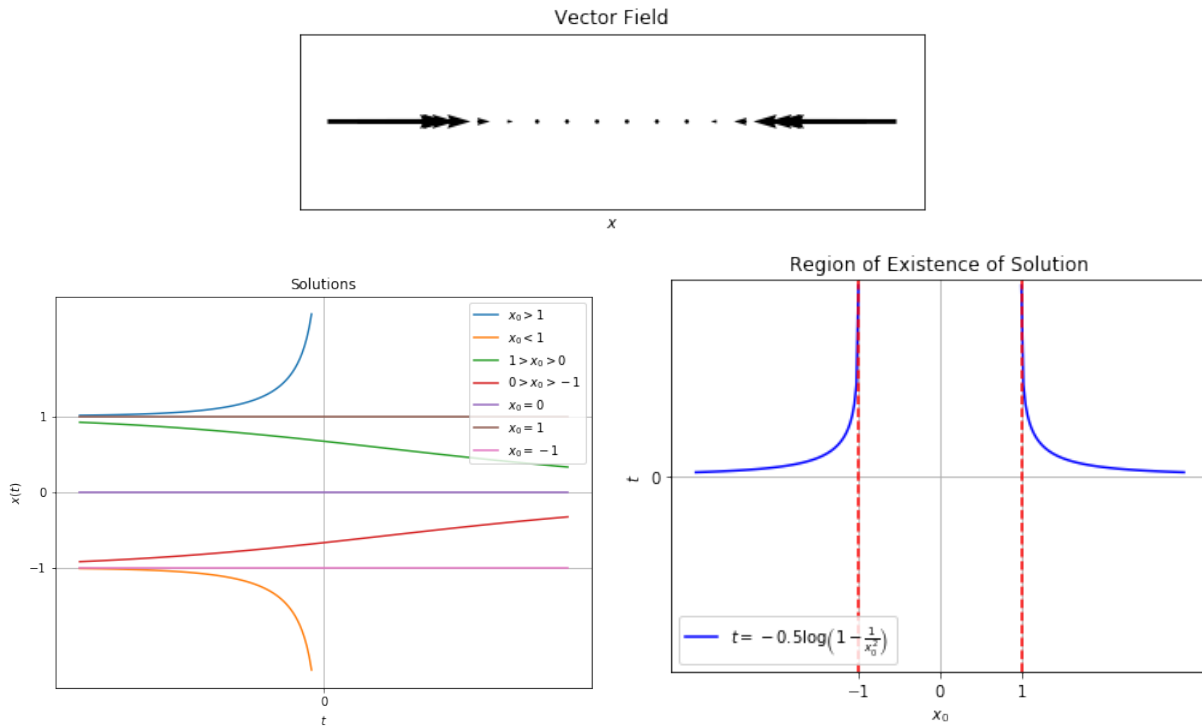
$$x(t) = \frac{x_0}{|x_0|} \sqrt{\frac{1}{1 - \frac{x_0^2 - 1}{x_0^2} e^{2t}}}$$

where the  $\frac{x_0}{|x_0|}$  has been multiplied to take care of sign. For the problem to have the above solution, one must have,

$$1 - \frac{x_0^2 - 1}{x_0^2} e^{2t} > 0 \implies t < -\frac{1}{2} \log \frac{x_0^2 - 1}{x_0^2} \quad \text{if } x_0^2 > 1$$

$$\text{and } t \in (-\infty, \infty) \quad \text{if } x_0^2 < 1$$

Figure 1: Q2 (a)



### Part (b)

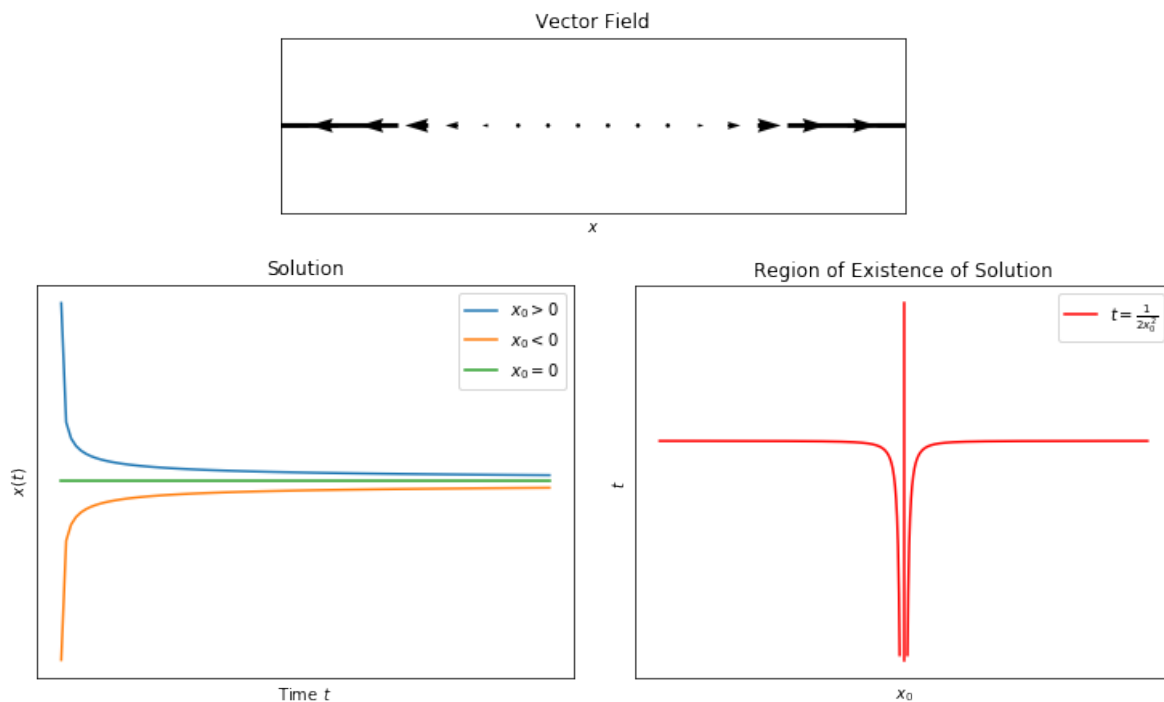
$$\dot{x} = -x^3$$

The above equation has the trivial solution  $x(t) = 0; \forall t$  for  $x_0 = 0$ . We proceed to find solutions for other values of  $x_0$ .

$$\begin{aligned} \dot{x} = -x^3 &\implies -\frac{dx}{x^3} = dt \implies \frac{1}{2x^2} \Big|_{x_0}^x = t \implies \frac{1}{x^2} = \frac{1}{x_0^2} + 2t \\ &\implies x = + \frac{x_0}{\sqrt{1 + 2x_0^2 t}} \end{aligned}$$

The above solution will exist for  $t > -\frac{1}{2x_0^2}; x_0 \neq 0$ . The region of existence is also plotted below.

Figure 2: Q2 (b)

**Part (c)**

Given that

$$\begin{aligned}
 E &= \frac{x_2^2}{2} + \frac{x_1^2}{2} - \frac{x_1^4}{4} \\
 \dot{E} &= x_2 \dot{x}_2 + x_1 \dot{x}_1 - \dot{x}_1 x_1^3 \\
 &= -x_1 x_2 + x_1^3 x_2 + x_1 x_2 - x_2 x_1^3 = 0 \\
 E &= \text{constant}
 \end{aligned}$$

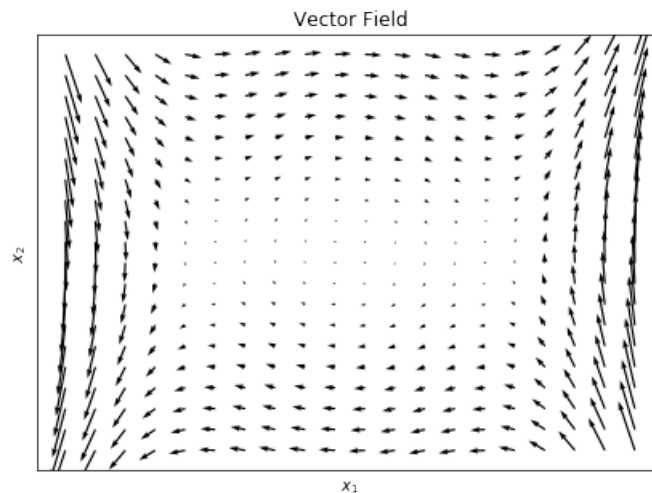
Hence the system as defined in the question is a Hamiltonian system. Now we can proceed to analytically solve this equation,

$$\begin{aligned}
 \frac{\dot{x}_1^2}{2} + \frac{x_1^2}{2} - \frac{x_1^4}{4} &= E \\
 \Rightarrow \dot{x}_1 &= \sqrt{2E + \frac{x_1^4}{2} - x_1^2} \\
 \Rightarrow x &= \int dx_1 \sqrt{2E + \frac{x_1^4}{2} - x_1^2}
 \end{aligned}$$

**Problem 3**

*Solved completely in the Jupyter Notebook.*

Figure 3: Q2 (c)



## Problem 4

One definition of religion is <sup>1</sup> :-

*A religion involves a communal, transmittable body of teachings and prescribed practices about an ultimate, sacred reality or state of being **that calls for reverence or awe**, a body which guides its practitioners into what it describes as a saving, illuminating or emancipatory relationship to this reality through a personally transformative life of prayer, ritualized meditation, and/or moral practices like repentance and personal re-generation.*

One can argue whether this definition is really general, but I think to first order religions like Hinduism, Islam and Christianity agree with this definition.

If one is pedantic about it, science, unlike religion, is only a recently coined term and has been in vogue only since the 19th Century<sup>2</sup>. The most accepted definition of a scientific hypothesis was given by Karl Popper in 1959, *which, in short, states that scientific hypotheses should in-principle be falsifiable. There is no reference made to an absolute authority of science*, which then is the most striking difference between science and religion.

Note that this is not to say there aren't any similarities between science and religion - science communities also have cults like religion.

<sup>1</sup>Dictionary of Philosophy of Religion, Taliaferro & Marty 2010

<sup>2</sup><https://plato.stanford.edu/entries/religion-science/#WhatScieWhatReli>