

Chapter 7 \rightarrow Integration and Variation

7.1) Tensor Densities

A tensor density of weight w transforms like an ordinary tensor, except that there will now be a w^{th} power of the Jacobian.

$$J = \left| \frac{\partial x^a}{\partial x'^b} \right|$$

$$I^{a, \dots}_{b, \dots} = J^w \frac{\partial x'^a}{\partial x^c} \dots \frac{\partial x^d}{\partial x'^b} I^c_{d, \dots}$$

$$\nabla_c I^{a, \dots}_{b, \dots} = \text{usual terms of tensor cov. derivative} + (-w \Gamma^d_{dc} I^{a, \dots}_{b, \dots})$$

In general, for a tensor density of weight w

$$\nabla_c I^a = \partial_c I^a + \Gamma^a_{bc} I^b - w \Gamma^b_{bc} I^a$$
$$\Rightarrow \nabla_a I^a = \partial_a I^a + \Gamma^a_{ba} I^b - w \Gamma^b_{ba} I^a$$
$$\text{for } w = +1 \Rightarrow \boxed{\nabla_a I^a = \partial_a I^a}$$

The Levi-Civita Symbol.

The Levi-Civita alternating symbol / tensor is a tensor whose components are $+1, -1$ if the $(abcd)$ is an even, odd permutation of 0123 respectively. i.e. $\epsilon_{0123} = \epsilon_{1230} = 1$, $\epsilon_{0123} = -\epsilon_{0213} = +1$

All the other components are zero.

Some Identities: [where δ is so defined st. $\delta^{abcd}_{efgh} = 0$]

$$\epsilon^{abcd} \epsilon_{efgh} = \delta^{abcd}_{efgh}$$

$$\epsilon^{abcd} \epsilon_{efgd} = \delta^{abc}_{efg}$$

$$\epsilon^{abcd} \epsilon_{efcd} = 2\delta^{ab}_{ef}$$

$$\epsilon^{abcd} \epsilon_{abcd} = 4!$$

$$\epsilon^{abcd} \epsilon_{cbcd} = 3! \delta^a_e$$

The Metric Determinant

$$g_{ab}(x') = \frac{\partial x^e}{\partial x'^a} \frac{\partial x^d}{\partial x'^b} g_{ed}(x) \Rightarrow g' = J^2 g$$

This means that the metric determinant is a scalar density of weight 2.

In GR, we'll be working with metrics of negative signature and hence g will be negative

$$(-g')^{1/2} = J (-g)^{1/2} \left[\text{which makes } \sqrt{-g} \text{ a scalar density of weight 1} \right]$$

This also means that if T^a is some vector,

$$\nabla_a (\sqrt{-g} T^a) = \partial_a (\sqrt{-g} T^a)$$

Finding the determinant of the Metric.

Consider a square matrix $A = (a_{ij})$. Let its determinant be given by a , and the cofactor of a_{ij} be given by A_{ij} . Then, we have,

$$a = \sum_{i,j} a_{ij} A_{ij}$$

$$\frac{\partial a}{\partial a_j} = A^j \Rightarrow \frac{\partial a}{\partial x^k} = \frac{\partial a}{\partial a_j} \frac{\partial a_j}{\partial x^k} = A^j \frac{\partial a_j}{\partial x^k}$$

But we know that the inverse of matrix A is a matrix with components b_{ij} given by,

$$b_{ij} = \frac{A^i_j}{a}$$

$$\Rightarrow \frac{\partial a}{\partial x^k} = a b_{ij} \frac{\partial a_j}{\partial x^k}; \text{ Now substituting } g \text{ for } a_j.$$

$$\partial_c g = g g^{ab} \frac{\partial g_{ab}}{\partial x^c} = g g^{ab} \partial_c g^{ab}$$

But we also know that

$$\partial_c g_{ab} = \Gamma_{ac}^d g_{bd} + \Gamma_{bc}^d g_{ad}$$

$$\begin{aligned} \Rightarrow \partial_c g &= g g^{ab} [\Gamma_{ac}^d g_{bd} + \Gamma_{bc}^d g_{ad}] \\ &= g \Gamma_{dc}^d + g \Gamma_{dc}^d = 2g \Gamma_{dc}^d \end{aligned}$$

$$\nabla_c g = \partial_c g - 2g \Gamma_{ac}^a \quad (\text{since } g \text{ is a scalar density of weight } 2)$$

$$\partial_c (\sqrt{-g}) = \frac{1}{2\sqrt{-g}} \partial_c (-g) = 0$$

$$\Rightarrow \partial_c [\sqrt{-g} T_{b...}^a] = \sqrt{-g} \partial_c T_{b...}^a \quad \text{and} \quad \nabla_c [\sqrt{-g} T_{b...}^a] = \sqrt{-g} \nabla_c T_{b...}^a$$

Variational Method for Geodesics

We start off by defining action, $\mathcal{L}[x^a, \dot{x}^a, u]$ which is a functional.

$$\mathcal{L} = \int_{p_1}^{p_2} [g_{ab}(x) \dot{x}^a \dot{x}^b] du = \int_{p_1}^{p_2} ds = s$$

Euler-Lagrange equations say $\rightarrow \frac{\partial \mathcal{L}}{\partial x^a} - \frac{d}{du} \left[\frac{\partial \mathcal{L}}{\partial \dot{x}^a} \right] = 0$

We need to massage this a bit

$$2\mathcal{L} \left[\frac{\partial \mathcal{L}}{\partial x^a} - \frac{d}{du} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}^a} \right) \right] = 0$$

$$\Rightarrow \left(\frac{\partial \mathcal{L}^2}{\partial x^a} - \frac{d}{du} \left[\frac{\partial \mathcal{L}^2}{\partial \dot{x}^a} \right] \right) + \left(2 \frac{\partial \mathcal{L}}{\partial \dot{x}^a} \frac{d\mathcal{L}}{du} \right) = 0$$

$$\Rightarrow \frac{\partial \mathcal{L}^2}{\partial x^a} - \frac{d}{du} \left[\frac{\partial \mathcal{L}^2}{\partial \dot{x}^a} \right] = \frac{\partial [g_{bc} \dot{x}^b \dot{x}^c]}{\partial x^a} - \frac{d}{du} \left[\frac{\partial [g_{bc} \dot{x}^b \dot{x}^c]}{\partial \dot{x}^a} \right]$$

$$\Rightarrow = \partial_a g_{bc} \dot{x}^b \dot{x}^c - \frac{2d}{du} [g_{ac} \dot{x}^c]$$

$$= \partial_a g_{bc} \dot{x}^b \dot{x}^c - 2g_{ac} \ddot{x}^c - 2\partial_b g_{ac} \dot{x}^b \dot{x}^c$$

$$= -2g_{ac} \ddot{x}^c - \dot{x}^b \dot{x}^c \{g_{bc}, a\}$$

$$2 \frac{\partial \mathcal{L}}{\partial \dot{x}^a} \frac{d\mathcal{L}}{du} = \frac{2 \partial [g_{bc} \dot{x}^b \dot{x}^c]}{\partial \dot{x}^a} \left\{ \frac{d}{du} \left[\frac{ds}{du} \right] \right\}$$

$$= 2(g_{bc} \dot{x}^b \dot{x}^c)^{-1/2} \{g_{ad} \dot{x}^d\} \frac{d^2 s}{du^2}$$

$$= 2 \frac{\ddot{s}}{\dot{s}} g_{ad}$$

\Rightarrow

$$\ddot{x}^a + \Gamma_{bc}^a \dot{x}^b \dot{x}^c = \frac{\ddot{s}}{\dot{s}} \dot{x}^a$$

$$\text{If } u=s \Rightarrow \ddot{x}^a + \Gamma_{bc}^a \dot{x}^b \dot{x}^c = 0$$

One can almost always choose a different affine parametrization, such that $\bar{S} = ds + \beta$. Note that in case of null geodesics, we can no longer do this, and then,

$$\ddot{x}^a + \Gamma_{bc}^a \dot{x}^b \dot{x}^c = \lambda(u) \dot{x}^a$$

where $\lambda(u)$ is a function of parameter u , and \dot{x}^a satisfies $g_{ab} \dot{x}^a \dot{x}^b = 0$

Isometries

If g_{ab} is inva under $x \rightarrow x'$, $g_{ab}(y) = g_{a'b'}(y)$

The transformation is called an isometry.

We know,
$$g_{ab}(x) = \frac{\partial x'^c}{\partial x^a} \frac{\partial x'^d}{\partial x^b} g_{cd}'(x')$$

This is isometry if,
$$g_{ab}(x) = \frac{\partial x'^c}{\partial x^a} \frac{\partial x'^d}{\partial x^b} g_{cd}(x')$$

Considering infinitesimal coordinate transformation,

$$x'^a = x^a + \epsilon X^a$$

$$\frac{\partial x'^a}{\partial x^b} = \delta_b^a + \epsilon \partial_b X^a$$

$$\begin{aligned} g_{ab}(x) &= \left(\delta_a^c + \epsilon \partial_a X^c \right) \left(\delta_b^d + \epsilon \partial_b X^d \right) \left(g_{cd}(x) + \epsilon X^e \partial_e g_{cd}(x) \right) \\ &= g_{ab}(x) + \epsilon \left[\partial_a X^c \delta_b^d g_{cd} + \partial_b X^d \delta_a^c g_{cd} + X^e \partial_e g_{cd} \delta_a^c \delta_b^d \right] \\ &= g_{ab} + \epsilon \left[\partial_a X^c g_{bc} + \partial_b X^d g_{ad} + X^e \partial_e g_{ab} \right] + O(\epsilon^2) \end{aligned}$$

$$\Rightarrow L_X g_{ab} = 0 \quad \text{ic} \quad \nabla_b X_a + \nabla_a X_b = 0$$

This is Killing equation, X is Killing vector.