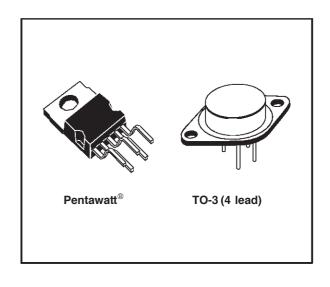


ADJUSTABLE VOLTAGE AND CURRENT REGULATOR

- ADJUSTABLE OUTPUT CURRENT UP TO 2 A (GUARANTEED UP TO T_i = 150 °C)
- ADJUSTABLE OUTPUT VOLTAGE DOWN TO 2.85 V
- INPUT OVERVOLTAGE PROTECTION (UP TO 60 V, 10 ms)
- SHORT CIRCUIT PROTECTION
- OUTPUT TRANSISTOR S.O.A. PROTECTION
- THERMAL OVERLOAD PROTECTION
- LOW BIAS CURRENT ON REGULATION PIN
- LOW STANDBY CURRENT DRAIN



DESCRIPTION

The L200 is a monolithic integrated circuit for voltage and current programmable regulation. It is available in Pentawatt® package or 4-lead TO-3 metal case. Current limiting, power limiting, thermal shutdown and input overvoltage protection (up to

60 V) make the L200 virtually blow-out proof. The L200 can be used to replace fixed voltage regulators when high output voltage precision is required and eliminates the need to stock a range of fixed voltage regulators.

ABSOLUTE MAXIMUM RATINGS

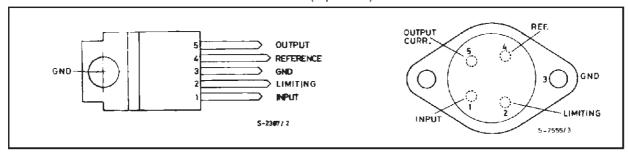
Symbol	Parameter	Value	Unit
Vi	DC Input Voltage	40	V
Vi	Peak Input Voltage (10 ms)	60	V
ΔV_{i-o}	Dropout Voltage	32	V
Io	Output Current	internally limited	
P _{tot}	Power Dissipation	internally limited	
T _{stg}	Storage Temperature	-55 to 150	°C
T _{op}	Operating Junction Temperature for L200C	-25 to 150	°C
	for L200	-55 to 150	°C

THERMAL DATA

		TO-3	Pentawatt [®]
R _{th j-case}	Thermal Resistance Junction-case Max	4 °C/W	3 °C/W
R _{th j-amb}	Thermal Resistance Junction-ambient Max	35 °C/W	50 °C/W

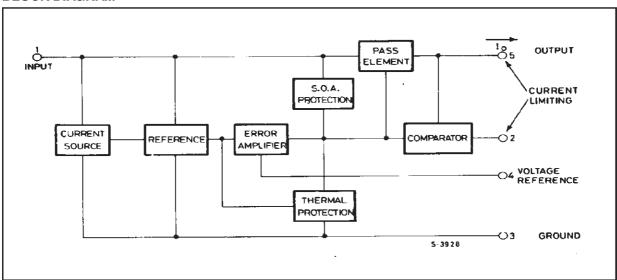
January 2000 1/12

CONNECTION DIAGRAMS AND ORDER CODES (top views)



Туре	Pentawatt [®]	TO-3
L200		L200 T
L200 C	L200 CH L200 CV	L200 CT

BLOCK DIAGRAM



APPLICATION CIRCUITS

Figure 1. Programmable Voltage Regulator with Current Limiting

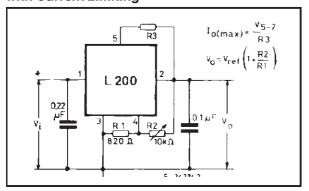
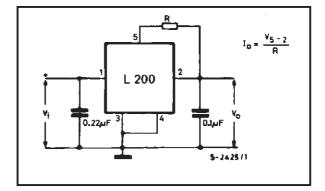
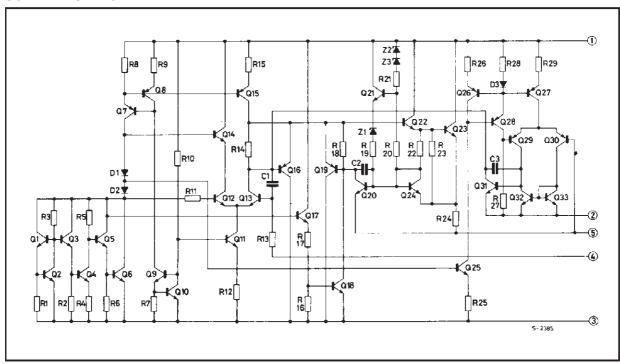


Figure 2. Programmable Current Regulator.



SCHEMATIC DIAGRAM



ELECTRICAL CHARACTERISTICS (T_{amb} = 25 °C, unless otherwise specified)

Symbol Parameter	Test Conditions	Min.	Тур.	Max.	Unit	1
------------------	-----------------	------	------	------	------	---

VOLTAGE REGULATION LOOP

I _d	Quiescent drain Current (pin 3)	V _i = 20 V		4.2	9.2	mA
e _N	Output Noise Voltage	$Vo = Vref$ $I_0 = 10 \text{ mA}$ $B = 1 \text{ MHz}$		80		μV
Vo	Output Voltage Range	I _o = 10 mA	2.85		36	٧
$\frac{\Delta V_o}{V_o}$	Voltage Load Regulation (note 1)	$\Delta I_0 = 2 A$ $\Delta I_0 = 1.5 A$		0.15 0.1	1 0.9	%
$\frac{\Delta V_i}{\Delta V_o}$	Line Regulation	$V_0 = 5 \text{ V}$ $V_i = 8 \text{ to } 18 \text{ V}$	48	60		dB
SVR	Supply Voltage Rejection	$V_0 = 5 \text{ V}$ $I_0 = 500 \text{ mA}$ $\Delta V_i = 10 \text{ V}_{pp}$ $f = 100 \text{ Hz}$ (note 2)	48	60		dB
ΔV_{i-o}	Droupout Voltage between Pins 1 and 5	$I_0 = 1.5 \text{ A}$ $\Delta V_0 \le 2\%$		2	2.5	٧
V _{ref}	Reference Voltage (pin 4)	V _i = 20 V I _o = 10 mA	2.64	2.77	2.86	٧

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ELECTRICAL CHARACTERISTICS (continued)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
ΔV_{ref}	Average Temperature Coefficient of Reference Voltage	V_i = 20 V		-0.25 -1.5		mV/°C mV/°C
I ₄	Bias Current and Pin 4			3	10	μА
Δ I ₄ Δ T • I ₄	Average Temperature Coefficient (pin 4)			-0.5		%/°C
Zo	Output Impedance	$V_i = 10 \text{ V}$ $V_o = V_{ref}$ $I_o = 0.5 \text{ A}$ $f = 100 \text{ Hz}$		1.5		mΩ

CURRENT REGULATION LOOP

V _{SC}	Current Limit Sense Voltage between Pins 5 and 2	$V_i = 10 \text{ V} $ $V_o = V_{ref}$ $I_5 = 100 \text{ mA}$	0.38	0.45	0.52	V
$\frac{\Delta V_{SC}}{\Delta T \cdot V_{SC}}$	Average Temperature Coefficient of V _{SC}			0.03		%/°C
$\frac{\Delta I_0}{I_0}$	Current Load Regulation	$Vi = 10 V$ $\Delta Vo = 3V$ $I_0 = 0.5 A$ $I_0 = 1A$ $I_0 = 1.5 A$		1.4 1 0.9		% %
I _{SC}	Peak Short Circuit Current	V _i - V ₀ = 14 V (pins 2 and 5 short circuited)			3.6	А

Note 1: A load step of 2 A can be applied provited that input-output differential voltage is lower than 20 V (see Figure 3).

Note 2: The same performance can be maintained at higher output levels if a bypassing capacitor is provited between pins 2 and 4.

Figure 3. Typical Safe Operating Area Protection.

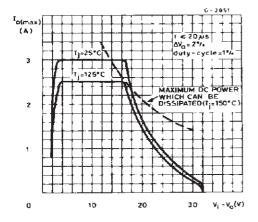


Figure 4. Quiescent Current vs. Supply Voltage.

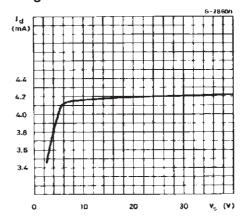


Figure 5. Quiescent Current vs. Junction Voltage.

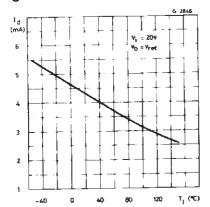


Figure 6. Quiescent Current vs. Output Current.

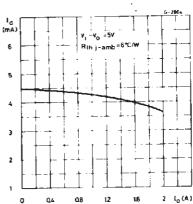


Figure 7. Output Noise Voltage vs. Output Voltage.

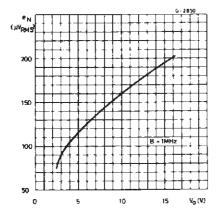


Figure 8. Output Noise Voltage vs. Frequency.

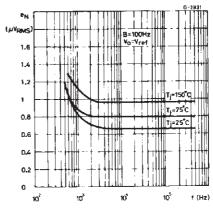


Figure 9. Reference Voltage vs. Junction Temperature.

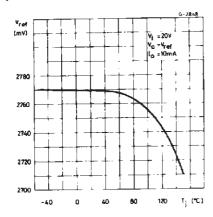


Figure 10. Voltage Load Regulation vs. Junction Temperature.

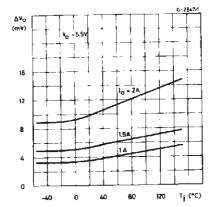


Figure 11. Supply Voltage Rejection vs. Frequency.

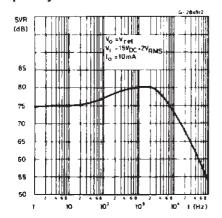


Figure 12. Dropout Voltage vs. Junction Temperature.

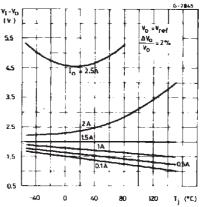


Figure 13. Output Impedance vs. Frequency.

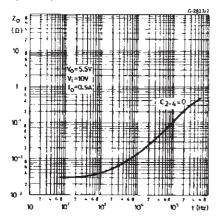


Figure 14. Output Impedance vs. Output Current.

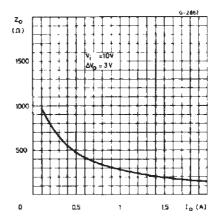
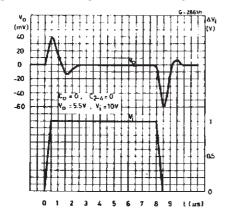
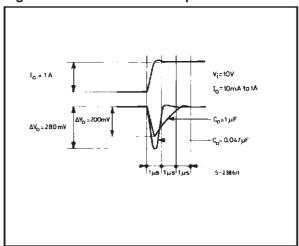


Figure 15. Voltage Transient Reponse.



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Figure 16. Load Transient Reponse.



L7/

Figure 17. Load Transient Reponse

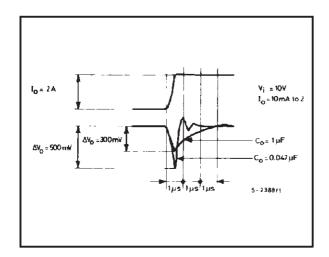
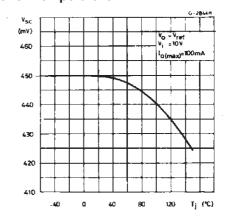


Figure 18. Current Limit Sense Voltage vs. JunctionTemperature.



APPLICATIONS CIRCUITS

Figure 19. - Programmable Voltage Regulator

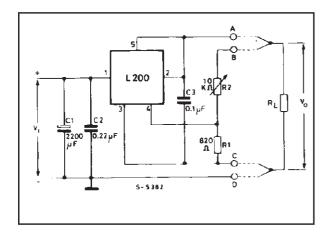


Figure 20. - P.C.Board and Components Layout of Figure 19.

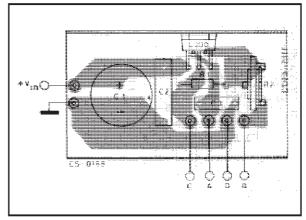


Figure 21. - High Current Voltage Regulator with Short Circuit Protection.

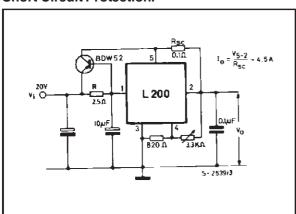
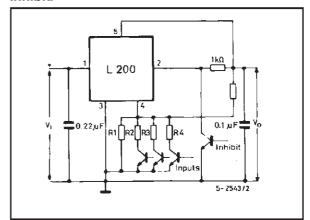


Figure 22. - Digitally Selected Regulator with Inhibit.



0.10 V₀ = V_{ref} to 26 V 100 KΩ A 100 KΩ

Figure 23. Programmable Voltage and Current Regulator.

Note: Connecting point A to a negative voltage (for example - 3V/10 mA) it is possible to extend the output voltage range down to 0 V and obtain the current limiting down to this level (output short-circuit condition).

Figure 24. High Current Regulator with NPN Pass Transistor.

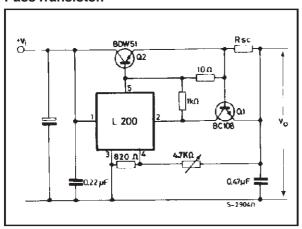


Figure 25. High Current Tracking Regualtor.

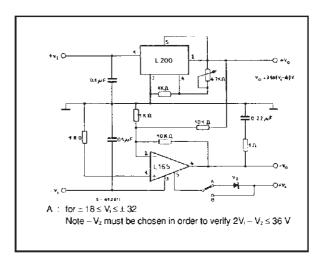


Figure 26. High Input and Output Voltage.

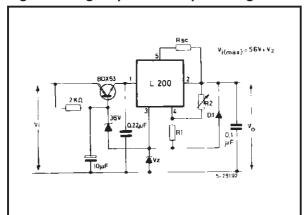
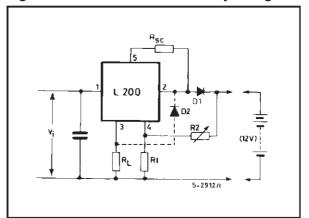


Figure 27. Constant Current Battery Charger.



The resistors R_1 and R_2 determine the final charging voltage and R_{SC} the initial charging current. D_1 prevents discharge of the battery throught the regulator.

The resistor RL limits the reverse currents through ther regulator (which should be 100 mA max) when the battery is accidentally reverse connected. If $\rm R_L$ is in series with a bulb of 12 V/50 mA rating this will indicate incorrect connection.

Figure 28. 30 W Motor Speed Control.

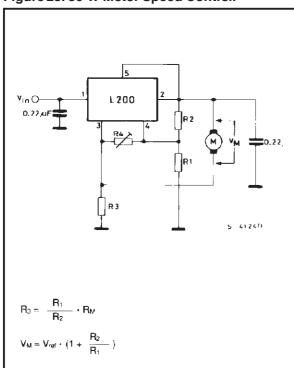


Figure 29. Loww Turn on.

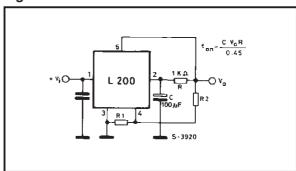
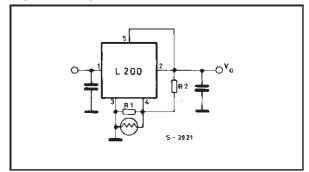
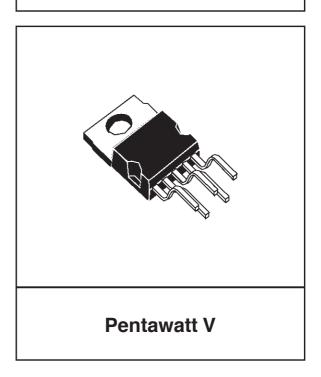


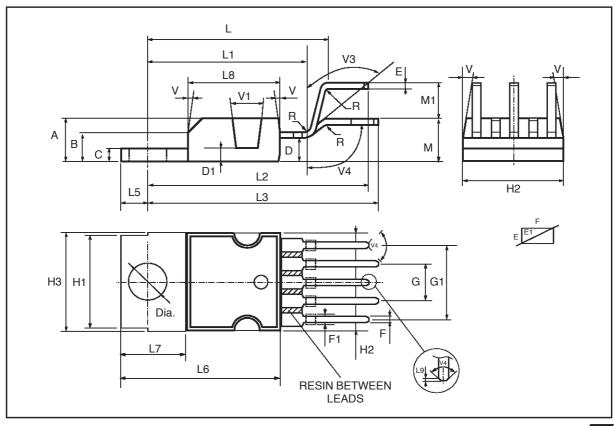
Figure 30. Light Controller.



DIM		mm		inch			
DIM.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.	
Α			4.8			0.189	
С			1.37			0.054	
D	2.4		2.8	0.094		0.110	
D1	1.2		1.35	0.047		0.053	
Е	0.35		0.55	0.014		0.022	
E1	0.76		1.19	0.030		0.047	
F	0.8		1.05	0.031		0.041	
F1	1		1.4	0.039		0.055	
G	3.2	3.4	3.6	0.126	0.134	0.142	
G1	6.6	6.8	7	0.260	0.268	0.276	
H2			10.4			0.409	
НЗ	10.05		10.4	0.396		0.409	
L	17.55	17.85	18.15	0.691	0.703	0.715	
L1	15.55	15.75	15.95	0.612	0.620	0.628	
L2	21.2	21.4	21.6	0.831	0.843	0.850	
L3	22.3	22.5	22.7	0.878	0.886	0.894	
L4			1.29			0.051	
L5	2.6		3	0.102		0.118	
L6	15.1		15.8	0.594		0.622	
L7	6		6.6	0.236		0.260	
L9		0.2			0.008		
М	4.23	4.5	4.75	0.167	0.177	0.187	
M1	3.75	4	4.25	0.148	0.157	0.167	
V4	40° (typ.)						

OUTLINE AND MECHANICAL DATA



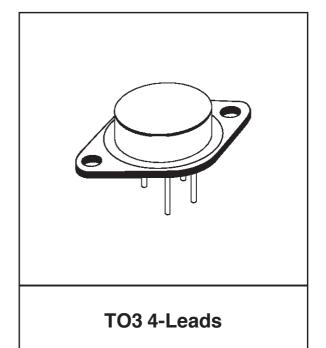


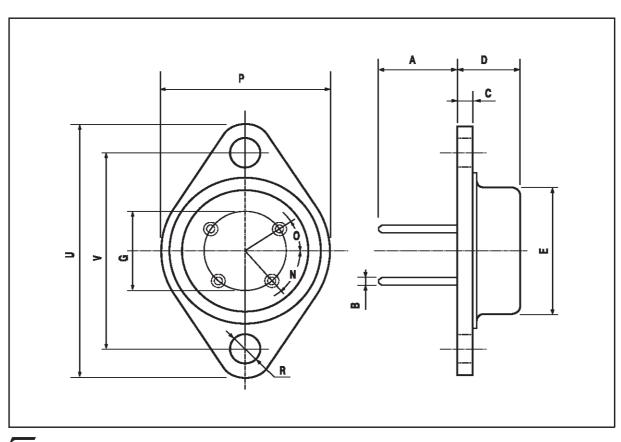
4

DIM.		mm			inch	
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
А		11.8			0.46	
B (*)		1		0.39		
С			2.5			0.098
D			9.6			0.37
Е			20			0.78
G		12.7			0.50	
N			50°((typ.)		
0			30°((typ.)		
Р			26.2			1.03
R	3.88		4.20	0.15		0.16
U			39.5			1.55
V		30.1			1.18	

(*) Measured with Gauge

OUTLINE AND MECHANICAL DATA





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