

# Install and Test Darknet on Raspberry Pi

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## Prerequisites

- OpenCV
- OpenMP
- OpenBLAS

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## What is Darknet

- Darknet is an open source neural network framework written in C and CUDA (Compute Unified Device Architecture) supporting CPU (Central Processing Unit) and GPU (Graphical Processing Unit) computation.
  - ▶ Site: <https://pjreddie.com/darknet/>
  - ▶ GitHub : <https://github.com/pjreddie/darknet>
    - ➡ This version may cause error on Raspberry Pi while running.
- Alexey's version
  - ▶ <https://github.com/AlexeyAB/darknet>



"Darknet: Open Source Neural Networks in C", Joseph Redmon, <http://pjreddie.com/darknet>, 2013-2016.

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## Building Darknet

- Visit
  - ▶ <https://github.com/AlexeyAB/darknet>
- Download
  - ▶ make a directory
  - ▶ \$ mkdir work && cd work
  - ▶ \$ git clone <https://github.com/AlexeyAB/darknet.git>
  - ▶ \$ mv darknet darknet-alexey
- Modify 'Makefile'
  - ▶ cd darknet-alexey
  - ▶ \$ vi Makefile
    - ➔ set 1 for OpenCV if you installed it.
- Compile
  - ▶ \$ make
- At last
  - ▶ **'darknet'**: executable
- Nvidia CUDA related
  - ▶ GPU, CUDNN, CUDNN\_HALF
- x86 Vector related
  - ▶ AVX
- Multi-core/computer related
  - ▶ OpenMP
- Shared library
  - ▶ LIBSO
- 3D camera
  - ▶ ZED\_CAMERA

```
GPU=0
CUDNN=0
CUDNN_HALF=0
OPENCV=1
AVX=0
OPENMP=0
LIBSO=0
ZED_CAMERA=0
```

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## Darknet usage

- \$ ./darknet function [function\_arguments]
- functions
  - ▶ look 'darknet/examples/darknet.c' file and its related C files.
  - ▶ detect [cfg\_file] [weights\_file] [options]
  - ▶ detector [train/test/valid] [data\_cfg] [cfg\_file] [weights\_file] [options]
  - ▶ yolo [train/test/valid] [cfg\_file] [weights\_file] [options]
  - ▶ cifar [train/test/valid] [cfg\_file] [weights\_file] [options]

```
$ ./darknet detect cfg/yolov3.cfg weights/yolov3.weights data/dog.jpg
$ ./darknet detector test cfg/coco.data cfg/yolov3.cfg weights/yolov3.weights data/dog.jpg

$ ./darknet detector test cfg/voc.data cfg/yolo.cfg weights/yolo.weights data/dog.jpg
```

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## Testing Darknet using Tiny-YOLO (1/2)

### ■ Download weight file

- ▶ \$ cd ~/work/darknet-alexey
- ▶ \$ mkdir weights && cd weights
- ▶ \$ wget <https://pjreddie.com/media/files/yolov3-tiny.weights>

### ■ Run Tiny-YOLO

- ▶ \$ cd ~/work/darknet-alexey
- ▶ \$ ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg

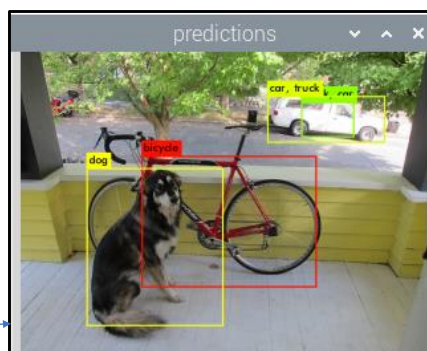
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## Testing Darknet using Tiny-YOLO (2/2)

```

pi@raspberrypi: ~/work/darknetAlexeyAB
File Edit Tabs Help
[pi@raspberrypi] ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg
layer  filters  size/stride/dil  input  output
0 conv  16          3 x 3/ 1        416 x 416 x 3 -> 416 x 416 x 16 0.150 BF
1 max    1          2 x 2/ 2        416 x 416 x 16 -> 208 x 208 x 16 0.003 BF
2 conv  32          3 x 3/ 1        208 x 208 x 16 -> 208 x 208 x 32 0.399 BF
3 max    3          2 x 2/ 2        208 x 208 x 32 -> 104 x 104 x 32 0.001 BF
4 conv  64          3 x 3/ 1        104 x 104 x 32 -> 104 x 104 x 64 0.399 BF
5 max    5          2 x 2/ 2        104 x 104 x 64 -> 52 x 52 x 64 0.001 BF
6 conv  128         3 x 3/ 1        52 x 52 x 64 -> 52 x 52 x 128 0.399 BF
7 max    7          2 x 2/ 2        52 x 52 x 128 -> 26 x 26 x 128 0.000 BF
8 conv  256         3 x 3/ 1        26 x 26 x 128 -> 26 x 26 x 256 0.399 BF
9 max    9          2 x 2/ 2        26 x 26 x 256 -> 13 x 13 x 256 0.000 BF
10 conv 512         3 x 3/ 1        13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
11 max  11          2 x 2/ 1        13 x 13 x 512 -> 13 x 13 x 512 0.000 BF
12 conv 1024         3 x 3/ 1        13 x 13 x 512 -> 13 x 13 x1024 1.595 BF
13 conv 256         1 x 1/ 1        13 x 13 x1024 -> 13 x 13 x 256 0.089 BF
14 conv 512         3 x 3/ 1        13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
15 conv 255         1 x 1/ 1        13 x 13 x 512 -> 13 x 13 x 255 0.044 BF
16 yolo
[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
17 route 13
18 conv 128         1 x 1/ 1        13 x 13 x 256 -> 13 x 13 x128 0.011 BF
19 upsample 2x      13 x 13 x128 -> 26 x 26 x128
20 route 19 8
21 conv 256         3 x 3/ 1        26 x 26 x 384 -> 26 x 26 x 256 1.196 BF
22 conv 255         1 x 1/ 1        26 x 26 x 256 -> 26 x 26 x 255 0.088 BF
23 yolo
[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
Total BFLOPS 5.871
Loading weights from weights/yolov3-tiny.weights...
seen 64
Done!
data/dog.jpg: Predicted in 31128.772000 milli-seconds. 31 sec
dog: 81%
bicycle: 38%
car: 71%
truck: 41%
car: 62%
car: 39%

```

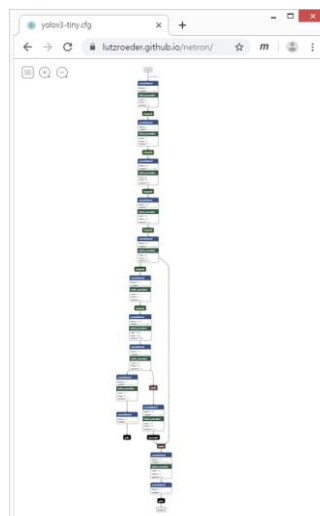
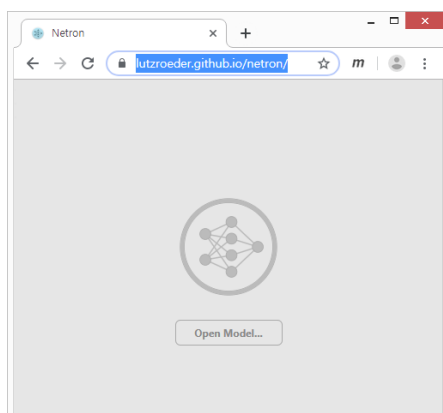


Type 'q' on the picture in order to quit.

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# Network visualizer

- <https://github.com/lutzroeder/netron>
- <https://lutzroeder.github.io/netron/>



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## Darknet profiling (1/2)

- 'gprof' 사용
  - ▶ 컴파일 단계에서 '-pg' 선택자 사용
  - ▶ 프로그램 수행 결과로 'gmon.out' 파일 생성
  - ▶ 'gprof' 프로그램으로 분석
- 1) 'Makefile'의 'CFLAGS'에 '-pg' 추가
  - ▶ CFLAGAS+=-pg
- 2) 'make' 실행
  - ▶ \$ make clean && make GPROF=1
- 3) run
  - ▶ \$ ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg
- 4) 'gprof' 실행
  - ▶ \$ gprof darknet gmon.out > gprof.txt
- 5) 'gprof.txt' 파일 검토
  - ▶ \$ head -20 gprof.txt

```
GPU=0
CUDNN=0
CUDNN_HALF=0
OPENCV=1
AVX=0
OPENMP=0
LIBSO=0
ZED_CAMERA=0
GPROF=0

....
ifeq ($(GPROF), 1)
CFLAGS+=-pg
endif
...
```

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## Darknet profiling (2/2)

```
File Edit Tabs Help
[pi@raspberrypi] ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg
layer filters size/stride input output
0 conv 16 3 x 3/1 416 x 416 x 3 -> 416 x 416 x 16 0.150 BF
1 max 2 x 2/2 416 x 416 x 16 -> 208 x 208 x 16 0.003 BF
2 conv 32 3 x 3/1 208 x 208 x 16 -> 208 x 208 x 32 0.399 BF
3 max 2 x 2/2 208 x 208 x 32 -> 104 x 104 x 32 0.001 BF
4 conv 64 3 x 3/1 104 x 104 x 32 -> 104 x 104 x 64 0.399 BF
5 max 2 x 2/2 104 x 104 x 64 -> 52 x 52 x 64 0.001 BF
6 conv 128 3 x 3/1 52 x 52 x 64 -> 52 x 52 x 128 0.399 BF
7 max 2 x 2/2 52 x 52 x 128 -> 26 x 26 x 128 0.000 BF
8 conv 256 3 x 3/1 26 x 26 x 128 -> 26 x 26 x 256 0.399 BF
9 max 2 x 2/2 26 x 26 x 256 -> 13 x 13 x 256 0.000 BF
10 conv 512 3 x 3/1 13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
11 max 2 x 2/1 13 x 13 x 512 -> 13 x 13 x 512 0.000 BF
12 conv 1024 3 x 3/1 13 x 13 x 512 -> 13 x 13 x 1024 0.500 BF
13 conv 256 1 x 1/1 13 x 13 x 1024 -> 13 x 13 x 256 0.009 BF
14 conv 512 3 x 3/1 13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
15 conv 256 1 x 1/1 13 x 13 x 512 -> 13 x 13 x 256 0.044 BF
16 yolo
[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
17 route 13
18 conv 128 1 x 1/1 13 x 13 x 256 -> 13 x 13 x 128 0.011 BF
19 upsample 2x 13 x 13 x 128 -> 26 x 26 x 128
20 route 18
21 conv 256 3 x 3/1 26 x 26 x 384 -> 26 x 26 x 256 1.196 BF
22 conv 255 1 x 1/1 26 x 26 x 256 -> 26 x 26 x 255 0.088 BF
23 yolo
[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
Total 61.095 s.971
Loading weights from weights/yolov3-tiny.weights...
seen 64
Done!
data/dog.jpg: Predicted in 30936.748000 milli-seconds.
dog: 01%
bicycle: 38%
car: 71%
truck: 41%
truck: 62%
car: 38%
[pi@raspberrypi] ls
dirbary/ appveyor.yml backup/ build.sh had_list
dog/ build/ build.ps1 build.sh* cfg/
cmake/ cmakeLists.txt darknet/ DarknetConfig.cmake.in
darknet_normal* darknet_openblas* darknet_opennmp* darknet_py
darknet_video.py data/ gmm_openblas.c* gmon.out
image_yolov2.sh* image_yolov3.sh* include/ json_image_streams.sh*
LICENSE Makefile Makefile_openblas* net_cam_v3.sh*
obj/ predictions.jpg README.ad results/
scripts/ video_v2.sh* video_yolov3.sh*
weights/
[pi@raspberrypi]
```

```
File Edit Tabs Help
[pi@raspberrypi] gprof darknet gmon.out > gprof.txt
[pi@raspberrypi] head -20 gprof.txt
Flat profile:

Each sample counts as 0.01 seconds.
% cumulative self self total
time seconds seconds calls s/call s/call name
96.19 30.53 30.53 3694 0.01 0.01 gemm_nn
1.20 30.91 0.38 1 0.38 0.38 fuse_conv_batchnorm
0.44 31.05 0.14 13 0.01 0.02 make_convolutional_layer
0.44 31.19 0.14 9 0.02 0.02 im2col_cpu_ext
0.43 31.33 0.14 8845488 0.00 0.00 rand_uniform
0.28 31.42 0.09 6 0.02 0.02 forward_maxpool_layer_avx
0.22 31.49 0.07 13 0.01 0.01 activate_array_cpu_custom
0.22 31.56 0.07 1 0.07 0.07 stbi_convert_format
0.13 31.60 0.04 761 0.00 0.00 mat_to_image
0.13 31.64 0.04 13 0.00 0.00 add_bias
0.13 31.68 0.04 1 0.04 0.04 resize_image
0.06 31.70 0.02 1 0.02 0.02 image_to_mat
0.06 31.72 0.02 1 0.02 0.09 save_image_options
0.03 31.73 0.01 12 0.00 0.00 activate_array
0.03 31.74 0.01 1 0.01 0.01 constrain_image
[pi@raspberrypi]
```

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## How to deal with 'gemm\_nn'(1/3)

```
src/gemm.c
#ifdef OPENBLAS
#include <blas.h>

void gemm( int    TA
, int    TB
, int    M
, int    N
, int    K
, float  ALPHA
, float  *A
, int    lda
, float  *B
, int    ldb
, float  BETA
, float  *C
, int    ldc)
{
    cblas_sgemm(CblasRowMajor
, (TA==0) ? CblasNoTrans : CblasTrans
, (TB==0) ? CblasNoTrans : CblasTrans
, M
, N
, K
, ALPHA
, A
, lda
, B
, ldb
, BETA
, C
, ldc
, // OPENBLAS_CONST blasint M
, // OPENBLAS_CONST blasint N
, // OPENBLAS_CONST blasint K
, // OPENBLAS_CONST float alpha
, // OPENBLAS_CONST float *A
, // OPENBLAS_CONST blasint lda
, // OPENBLAS_CONST float *B
, // OPENBLAS_CONST blasint ldb
, // OPENBLAS_CONST float beta
, // float *C
, // OPENBLAS_CONST blasint ldc
);
}
```

- Use optimized GEMM in 'src/gemm.c'
- Change 'Makefile'

```
Makefile
...
OPENBLAS=0
...
ifeq ($(OPENBLAS), 1)
COMMON += -DOPENBLAS
CFLAGS += -DOPENBLAS -I/opt/OpenBLAS/include
LDFLAGS += /opt/OpenBLAS/lib/libopenblas.a
endif
...
```

```
#else
void gemm(int TA, int TB, int M, int N, int K, float ALPHA,
float *A, int lda,
float *B, int ldb,
float BETA,
float *C, int ldc)
{
    gemm_cpu( TA, TB, M, N, K, ALPHA, A, lda, B, ldb, BETA, C, ldc);
}
#endif
```

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## How to deal with 'gemm\_nn'(2/3)

- Install OpenBLAS
  - ▶ \$ sudo apt-get install libopenblas-dev
- \$ make clean && make OPENBLAS=1 \
- GPROF=1
- \$ ./darknet detect cfg/yolov3-tiny.cfg \
- weights/yolov3-tiny.weights data/dog.jpg
- \$ gprof darknet gmon.out > gprof.txt
- \$ head -20 gprof.txt

```
pi@raspberrypi: ~/work/darknet/AlexeyAB
File Edit Tabs Help
[pi@raspberrypi] gprof darknet gmon.out > gprof.txt
[pi@raspberrypi] head -20 gprof.txt
Flat profile:

Each sample counts as 0.01 seconds.
% cumulative self self total
time seconds seconds calls ms/call ms/call name
21.47 0.93 0.38 1 388.00 388.00 sgemm_kernel_L4_M4_22
13.56 1.17 0.24 8845488 0.00 0.00 fuse_conv_batchnorm
10.17 1.35 0.18 13 13.85 32.31 make_convolutional_layer
3.95 1.42 0.07 9 6.67 6.67 sgemm_tcopy_L4_M4_20
3.39 1.48 0.06 1 50.00 50.00 im2col_cpu_ext
2.82 1.53 0.05 1 50.00 50.00 resize_image
2.82 1.58 0.05 inner_thread
2.26 1.62 0.04 blas_thread_server
1.69 1.65 0.03 761 0.04 0.04 mat_to_image
1.69 1.68 0.03 sgemm_kernel_L4_M4_100
1.13 1.70 0.02 sgemm_kernel_L2_M4_22
1.13 1.72 0.02 sgemm_kernel_L4_M4_20
1.13 1.74 0.02 sgemm_ncopy_L4_M4_20
0.56 1.75 0.01 13 0.77 0.77 add_bias
[pi@raspberrypi]
```

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## How to deal with 'gemm\_nn'(3/3)

```

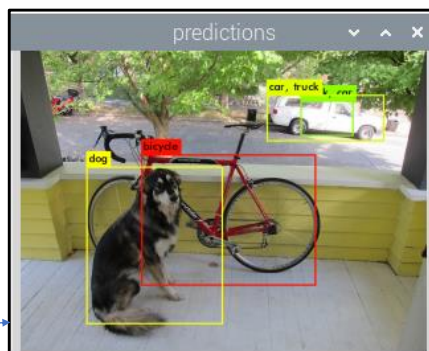
pi@raspberrypi: ~/work/darknet/AlexeyAB
File Edit Tabs Help
[pi@raspberrypi] ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg
layer  filters  size/strd(dil)  input  output
0 conv  16  3 x 3/ 1  416 x 416 x 3 -> 416 x 416 x 16 0.150 BF
1 max   2  2 x 2/ 2  416 x 416 x 16 -> 208 x 208 x 16 0.003 BF
2 conv  32  3 x 3/ 1  208 x 208 x 16 -> 208 x 208 x 32 0.399 BF
3 max   2  2 x 2/ 2  208 x 208 x 32 -> 104 x 104 x 32 0.001 BF
4 conv  64  3 x 3/ 1  104 x 104 x 32 -> 104 x 104 x 64 0.399 BF
5 max   2  2 x 2/ 2  104 x 104 x 64 -> 52 x 52 x 64 0.001 BF
6 conv  128 3 x 3/ 1  52 x 52 x 64 -> 52 x 52 x 128 0.399 BF
7 max   2  2 x 2/ 2  52 x 52 x 128 -> 26 x 26 x 128 0.000 BF
8 conv  256 3 x 3/ 1  26 x 26 x 128 -> 26 x 26 x 256 0.399 BF
9 max   2  2 x 2/ 2  26 x 26 x 256 -> 13 x 13 x 256 0.000 BF
10 conv 512 3 x 3/ 1  13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
11 max   2  2 x 2/ 1  13 x 13 x 512 -> 13 x 13 x 512 0.000 BF
12 conv 1024 3 x 3/ 1  13 x 13 x 512 -> 13 x 13 x 1024 1.595 BF
13 conv 256 1 x 1/ 1  13 x 13 x 1024 -> 13 x 13 x 256 0.089 BF
14 conv 512 3 x 3/ 1  13 x 13 x 256 -> 13 x 13 x 512 0.399 BF
15 conv 255 1 x 1/ 1  13 x 13 x 512 -> 13 x 13 x 255 0.044 BF
16 yolo

[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
17 route 13
18 conv 128 1 x 1/ 1  13 x 13 x 256 -> 13 x 13 x 128 0.011 BF
19 upsample 2x 13 x 13 x 128 -> 26 x 26 x 128
20 route 19 8
21 conv 256 3 x 3/ 1  26 x 26 x 384 -> 26 x 26 x 256 1.196 BF
22 conv 255 1 x 1/ 1  26 x 26 x 256 -> 26 x 26 x 255 0.088 BF
23 yolo

[yolo] params: iou loss: mse, iou_norm: 0.75, cls_norm: 1.00, scale_x_y: 1.00
Total BFLOPS 5.571
Loading weights from weights/yolov3-tiny.weights...
seen 64
Done!
data/dog.jpg: Predicted in 1235.776000 milli-seconds.
dog: 81%
bicycle: 38%
car: 71%
truck: 41%
car: 39%

```

- use 'fim' to see the result
- \$ fim predict.png



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## Make a long story short

### ■ Get Darknet-AlexeyAB version and modify

- ▶ \$ cd ~/work/codes/darknet-projects
- ▶ \$ git clone https://github.com/AlexeyAB/darknet.git
- ▶ \$ mv darknet darknet-alexey-blas
- ▶ \$ cd darknet-alexey-blas
- ▶ \$ patch Makefile < ../patch\_Makefile.txt
- ▶ \$ patch src/gemm.c < ../patch\_gemm.txt
- ▶ \$ make
- ▶ \$ ./darknet detect cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights data/dog.jpg
- ▶ \$ fim predict.png

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## Darknet using OpenMP

- OpenMP will use multi-thread

- ▶ Install OpenMP

- \$ sudo apt-get update
    - \$ sudo apt-get install libomp-dev

- Simply set 'OPENMP' 1

- It can be run along with other options.

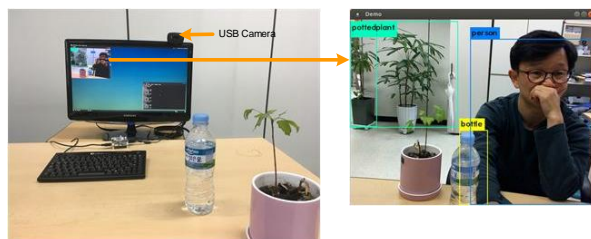
- ▶ OPENCV
  - ▶ OPENBLAS
  - ▶ GPROF

```
GPU=0
CUDNN=0
CUDNN_HALF=0
OPENCV=1
AVX=0
OPENMP=1
LIBSO=0
ZED_CAMERA=0
...
```

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## Running Tiny-YOLO with USB-CAM

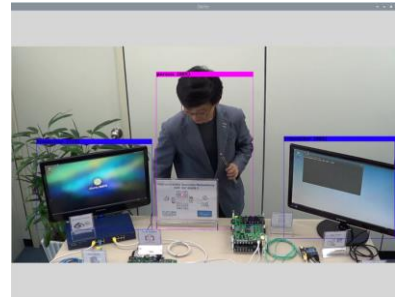
- \$ ./darknet detector demo cfg/coco.data cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights -c 0



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## Running Tiny-YOLO with video stream

- \$ ./darknet detector demo cfg/coco.data cfg/yolov3-tiny.cfg weights/yolov3-tiny.weights video.mp4



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