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function x_return = newton_raphson(func,dfunc,guess,disp_iterations,tol)
%NEWTON_RAPHSON Single variable function newton-raphson solver
% Inputs are:
% func      :a function handle function of x
% dfunc     :a function handle derivative of function of x
% guess     :a numeric array of Mx1 initial guess for function
% tol       :an optional scalar solver tolerance
%
% Output is:
% x         :a numeric array of Mx1 root of function for each guess

arguments
    func
    dfunc
    guess(:,1) {mustBeNumeric, mustBeReal}
    disp_iterations {mustBeNumericOrLogical} = false;
    tol {mustBeNumeric, mustBeReal, mustBePositive} = 1e-8
end

x_return = zeros(1,length(guess));

% Loop through each guess
for i = 1:length(guess)
    x = guess(i);
    err = inf;
    count = 1;

    if disp_iterations
        fprintf('Initial Guess = %0.1f\n',x)
    end

% Find values of x that satisfy tolerance
    while err > tol
        xnew = x - (func(x)./dfunc(x));
        err = abs(xnew-x);
        x = xnew;
        if disp_iterations
            fprintf('Iteration %d: x = %0.4f\n',count,x)
        end
        count = count + 1;
    end
    if disp_iterations && i ~= length(guess)
        disp('---')
    end
    x_return(i) = x;
end
end
```