

Learning theory for matrix inverse problems with gaussian priors

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Suppose $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a forward operator and we have data of the form

$$\begin{aligned} x &\in \mathcal{N}(0, \Sigma) \\ y &\in \mathcal{N}(Ax, \Gamma) \end{aligned}$$

Theorem 1: The maximum a posteriori (MAP) estimate of x given y

$$A_{MAP}^{-1}(y) = \arg \max_{x'} P(x'|y)$$

is

$$A_{MAP}^{-1}(y) = (A^T \Gamma^{-1} A + \Sigma^{-1})^{-1} A^T \Gamma^{-1} y$$

Proof: We have

$$P(x'|y) \propto \underbrace{P(y|x')}_{\mathcal{N}(Ax', I)} \underbrace{P(x')}_{\mathcal{N}(0, I)}$$

Instead of maximizing the posterior, we minimize the log of the posterior

$$\arg \max_{x'} P(x'|y) = \arg \min \log P(x'|y) = \arg \min (\log P(y|x') + \log P(x'))$$

where we let

$$\begin{aligned} f(x') &= \log P(y|x') + \log P(x') \\ &= \frac{1}{2} \|Ax - y\|_{\Gamma^{-1}}^2 + \frac{1}{2} \|x\|_{\Sigma^{-1}}^2 \end{aligned}$$

we compute

$$\nabla f = A^T \Gamma^{-1} (Ax - y) + \Sigma^{-1} x$$

Setting this to zero gives the conditions for a maximum

$$(A^T \Gamma^{-1} A + \Sigma^{-1}) x = A^T \Gamma^{-1} y$$

which gives a maximum likelihood solution as

$$x = (A^T \Gamma^{-1} A + \Sigma^{-1})^{-1} A^T \Gamma^{-1} y$$

which is the Tichonov regularized solution under Gaussian priors.

Theorem 2: We have

$$\arg \min_B \mathbb{E}_{(x,y)} \|B(y) - x\|_2^2 = \mathbb{E}_x(x | y)$$

where the minimization is taken over all operators $\mathbb{R}^m \rightarrow \mathbb{R}^n$.¹

¹This is also given in Bishop, 1.5.5

Proof: By the law of total probability

$$\mathbb{E}_{(x,y)} \|B(y) - x\|_2^2 = \mathbb{E}_y(\mathbb{E}_x(\|B(y) - x\|_2^2 \mid y))$$

By the monotonicity of the expectation we have

$$B(y) = \arg \min_z \mathbb{E}_x(\|z - x\|_2^2 \mid y)$$

we find this by differentiating and setting to zero

$$0 = \mathbb{E}_x(2(z - x) \mid y) = 2\mathbb{E}_x(z \mid y) - 2\mathbb{E}_x(x \mid y)$$

which gives

$$B(y) = \mathbb{E}_x(x \mid y)$$