# MFCM with the math done in continuum and with smoothness criterion on b

Awais Ashfaq<sup>1</sup> and Jonas Adler<sup>2</sup>

<sup>1</sup> KTH Royal Institute of Technology and Halmstad University

#### 1 Introduction

This follows the paper "A modified fuzzy C means algorithm for shading correction in craniofacial CBCT images" but performs the deriviations in continuum and adds further regularity conditions on the bias field.

#### 2 Bias-field estimation in continuum

The observed CBCT image is modelled as a sum of true signal and a spatially slow varying bias-field.

$$y(t) = x(t) + b(t) \quad \forall t \in \Omega$$
 (1)

where

 $\Omega \subset \mathbb{R}^n$  is the domain of the image

y is the observed intensity

x is the true intensity

b is the bias intensity

The FCM objective function is given by

$$J = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(x) (x(t) - c_i)^2 dt$$
 (2)

where

I is the number of clusters

 $c_i$  is the center of the  $i^{th}$  cluster

 $\mu_i(t)$  is the degree of membership of point t in the  $i^{th}$  cluster and  $\mu_{in} \in [0, 1]$ . m is the level of fuzziness.  $m \in (1, \infty)$ . m = 1 would imply a strict partitioning between clusters. Higher values of m imply smaller membership values and hence fuzzier clusters. For a given data point, sum of the membership values for every cluster is normalized to 1.

$$\sum_{i=1}^{I} \mu_i(t) = 1 \quad \forall \, t \in \Omega \tag{3}$$

<sup>&</sup>lt;sup>2</sup> KTH Royal Institute of Technology and Elekta Instrument AB

The modified FCM objective function, following the idea as proposed by Ahmed et al is given by

$$J^* = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt$$
 (4)

where  $C_k x$  is the convolution of x with k, where k controls the neighbourhood influence.

$$C_k x = \int x(t-\tau)k(\tau)d\tau$$

In CBCT acquisition, intensity values correspond to attenuation coefficients of the material being scanned which in turn roughly correspond to the material's density. It is thus important to have a piece-wise smooth solution while keeping the true intensity values x close to the observed intensity values y (see Eq. 1). In order to preserve this information, we assume that the bias-field has zero mean.

$$\int_{\Omega} b(t)dt = \int_{\Omega} y(t) - x(t)dt = 0$$
 (5)

The task of minimizing  $J^*$  in Eq. 4 with constraints given by Eq. 3 and 5 is a nonlinear optimization problem. Mathematically,

minimize 
$$J^*$$
subject to  $\sum_{i=1}^{I} \mu_i(t) = 1 \quad \forall t \in \Omega$ 

$$\int_{\Omega} (y(t) - x(t)) dt = 0$$

#### 2.1 Solution via coordinate descent

To minimize  $J^*$  we form the Lagrangian

$$\mathcal{L} = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt + \int_{\Omega} \gamma(t) \left( 1 - \sum_{i=1}^{I} \mu_i(t) \right) dt + \lambda \int_{\Omega} (y(t) - x(t)) dt$$
(6)

which we can find the explicit gradient of by straightforward computation

$$\nabla_{\mu_i(t)} \mathcal{L} = m\mu_i^{m-1}(t) [C_k(x - c_i)^2](t) - \gamma(t)$$

$$\nabla_{c_i} \mathcal{L} = 2 \int_{\Omega} [C_k^* \mu_i^m](t) (c_i - x(t)) dt$$

$$\nabla_{x(t)} \mathcal{L} = 2 \sum_{i=1}^I [C_k^* \mu_i^m](t) (x(t) - c_i) - \lambda$$

$$\nabla_{\gamma(t)} \mathcal{L} = \left(1 - \sum_{i=1}^I \mu_i(t)\right)$$

$$\nabla_{\lambda} \mathcal{L} = \int_{\Omega} (y(t) - x(t)) dt$$

where  $C_k^*$  is the adjoint of  $C_k$ . If k is symmetric,  $C_k^* = C_k$ . For an optimal solution, all of these derivatives would be simultaneously zero. However, finding such a point is non-trivial and we resort to coordinate descent to find an optimal solution. Solving for  $\mu_i(t)$ 

$$\mu_i(t) = \left(\frac{\gamma(t)}{m[C_k(x - c_i)^2](t)}\right)^{\frac{1}{m-1}}$$

Using the constraint in Eq. 3 we calculate  $\gamma(t)$  as

$$\gamma(t) = \frac{m}{\left(\sum_{j=1}^{I} \left(\frac{1}{[C_k(x-c_i)^2](t)}\right)^{\frac{1}{m-1}}\right)^{m-1}}$$

Update equation for membership matrix  $\mu$  is given by

$$\mu_i(t) = \frac{1}{\sum_{j=1}^{I} \left( \frac{[C_k(x-c_i)^2](t)}{[C_k(x-c_j)^2](t)} \right)^{\frac{1}{m-1}}}$$
(7)

Update equation for cluster center c is given by

$$c_i = \frac{\int_{\Omega} [C_k^* \mu_i^m](t) x(t) dt}{\int_{\Omega} [C_k^* \mu_i^m](t) dt}$$

$$\tag{8}$$

Update equation for x is given by

$$x(t) = \frac{\sum_{i=1}^{I} c_i [C_k^* \mu_i^m](t) + \lambda}{\sum_{i=1}^{I} [C_k^* \mu_i^m](t)}$$
(9)

and  $\lambda$  can be evaluated using constraint Eq. 5

$$\lambda = \frac{\int_{\Omega} \left( y(t) - \frac{\sum_{i=1}^{I} c_{i} [C_{k}^{*} \mu_{i}^{m}](t)}{\sum_{i=1}^{I} [C_{k}^{*} \mu_{i}^{m}](t)} \right) dt}{\int_{\Omega} \left( \sum_{i=1}^{I} [C_{k}^{*} \mu_{i}^{m}](t) \right)^{-1} dt}$$
(10)

### 3 Penalized square of bias

We here penalize on the square of the bias instead of using the zero mean condition 5, forcing it to be "low"

$$J^* = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt + \lambda \int_{\Omega} (y(t) - x(t))^2 dt$$
 (11)

where  $\lambda$  is a regularization constant that can be selected. To solve this, we form the lagrangian

$$\mathcal{L} = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt + \lambda \int_{\Omega} (y(t) - x(t))^2 dt + \int_{\Omega} \gamma(t) \left(1 - \sum_{i=1}^{I} \mu_i(t)\right) dt \quad (12)$$

which we can find the explicit gradient of. All terms become the same as above, except the lambda derivative, which is no longer needed and x which is given by

$$\nabla_{x(t)} \mathcal{L} = 2 \sum_{i=1}^{I} [C_k^* \mu_i^m](t) (x(t) - c_i) + 2\lambda (x(t) - y(t))$$

The updates are also the same as above, except for x

$$x(t) = \frac{\sum_{i=1}^{I} c_i [C_k^* \mu_i^m](t) + \lambda y(t)}{\sum_{i=1}^{I} [C_k^* \mu_i^m](t) + \lambda}$$
(13)

## 4 Penalized square of gradient of bias

We here additionally penalize on the square of the gradient of the bias, forcing it to be "low", so called Tichonov regularization

$$J^* = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt + \lambda_1 \int_{\Omega} (y(t) - x(t))^2 dt + \lambda_2 \int_{\Omega} ([\nabla (y - x)](t))^2 dt$$
(14)

To solve this we form the lagrangian

$$\mathcal{L} = \sum_{i=1}^{I} \int_{\Omega} \mu_i^m(t) [C_k(x - c_i)^2](t) dt +$$

$$\lambda_1 \int_{\Omega} (y(t) - x(t))^2 dt + \lambda_2 \int_{\Omega} ([\nabla (y - x)](t))^2 dt + \int_{\Omega} \gamma(t) \left(1 - \sum_{i=1}^{I} \mu_i(t)\right) dt$$
(15)

which we can find the explicit gradient of. All terms become the same as above, except for x which is given by

$$\nabla_{x(t)} \mathcal{L} = 2 \sum_{i=1}^{I} [C_k^* \mu_i^m](t) (x(t) - c_i) + \lambda_1 (x(t) - y(t)) - 2\lambda_2 [\Delta(x - y)](t)$$

where  $\Delta = -\nabla^T \nabla$  is the Laplacian operator. The updates are also the same as above, except for x we get a system of equations

$$\sum_{i=1}^{I} \left[ C_k^* \mu_i^m \right](t) x(t) + \lambda_1 x(t) - \lambda_2 [\Delta x](t) = \sum_{i=1}^{I} c_i \left[ C_k^* \mu_i^m \right](t) + \lambda_1 y - \lambda_2 [\Delta y](t)$$
 (16)

We can solve it using the CG method (conjugate\_gradient in ODL).