# Bayesian model averaging is suboptimal for generalization under model misspecification

Andrés Masegosa

Department of Mathematics University of Almería Spain

#### • Notation:

- $\nu(x)$  is the data generating distribution (unknown).
- $p(\mathbf{x}|\boldsymbol{\theta})$  is a probabilistic model parametrized by  $\boldsymbol{\theta}.$
- $\forall \boldsymbol{\theta} \ \boldsymbol{\nu}(\mathbf{x}) \neq p(\mathbf{x}|\boldsymbol{\theta}).$

- Notation:
  - $\nu(x)$  is the data generating distribution (unknown).
  - $p(\mathbf{x}|\boldsymbol{\theta})$  is a probabilistic model parametrized by  $\boldsymbol{\theta}.$
  - $\forall \boldsymbol{\theta} \ \boldsymbol{\nu}(\mathbf{x}) \neq p(\mathbf{x}|\boldsymbol{\theta}).$
- ullet The **predictive posterior distribution** for a given  $ho(oldsymbol{ heta})$ ,

$$p(\mathbf{x}) = \int p(\mathbf{x}|\boldsymbol{\theta}) \rho(\boldsymbol{\theta}) d\boldsymbol{\theta} = \mathbb{E}_{\rho(\boldsymbol{\theta})}[p(\mathbf{x}|\boldsymbol{\theta})]$$

- Notation:
  - $\nu(x)$  is the data generating distribution (unknown).
  - $p(\mathbf{x}|\boldsymbol{\theta})$  is a probabilistic model parametrized by  $\boldsymbol{\theta}.$
  - $\forall \boldsymbol{\theta} \ \boldsymbol{\nu}(\mathbf{x}) \neq p(\mathbf{x}|\boldsymbol{\theta}).$
- The **predictive posterior distribution** for a given  $\rho(\theta)$ ,

$$p(\mathbf{x}) = \int p(\mathbf{x}|\boldsymbol{\theta}) \rho(\boldsymbol{\theta}) d\boldsymbol{\theta} = \mathbb{E}_{\rho(\boldsymbol{\theta})}[p(\mathbf{x}|\boldsymbol{\theta})]$$

• The learning problem is defined as,

$$\label{eq:rho_problem} \rho^{\star} = \arg\min_{\rho} KL(\textcolor{red}{\nu(\mathbf{x})}, \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\pmb{\theta})])$$

- Notation:
  - $\nu(x)$  is the data generating distribution (unknown).
  - $p(\mathbf{x}|\boldsymbol{\theta})$  is a probabilistic model parametrized by  $\boldsymbol{\theta}.$
  - $\forall \boldsymbol{\theta} \ \boldsymbol{\nu}(\mathbf{x}) \neq p(\mathbf{x}|\boldsymbol{\theta}).$
- ullet The **predictive posterior distribution** for a given  $ho(oldsymbol{ heta})$ ,

$$p(\mathbf{x}) = \int p(\mathbf{x}|\boldsymbol{\theta}) \rho(\boldsymbol{\theta}) d\boldsymbol{\theta} = \mathbb{E}_{\rho(\boldsymbol{\theta})}[p(\mathbf{x}|\boldsymbol{\theta})]$$

• The learning problem is defined as,

$$\rho^* = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\theta)]) = \arg\min_{\rho} \underbrace{\mathbb{E}_{\nu(\mathbf{x})}[\ln\frac{1}{\mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\theta)]}]}_{CE(\rho)}$$

- Notation:
  - $\nu(x)$  is the data generating distribution (unknown).
  - $p(\mathbf{x}|\boldsymbol{\theta})$  is a probabilistic model parametrized by  $\boldsymbol{\theta}.$
  - $\forall \boldsymbol{\theta} \ \boldsymbol{\nu}(\mathbf{x}) \neq p(\mathbf{x}|\boldsymbol{\theta}).$
- The **predictive posterior distribution** for a given  $\rho(\theta)$ ,

$$p(\mathbf{x}) = \int p(\mathbf{x}|\boldsymbol{\theta}) \rho(\boldsymbol{\theta}) d\boldsymbol{\theta} = \mathbb{E}_{\rho(\boldsymbol{\theta})}[p(\mathbf{x}|\boldsymbol{\theta})]$$

• The learning problem is defined as,

$$\rho^* = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\theta)]) = \arg\min_{\rho} \underbrace{\mathbb{E}_{\nu(\mathbf{x})}[\ln\frac{1}{\mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\theta)]}]}_{CE(\rho)}$$

### Learning from a finite dataset

• We do not have access to  $\nu(\mathbf{x})$ , only to a i.i.d. sample  $D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$ .

#### Remind!

$$\rho^{\star} = \arg\min_{\rho} CE(\rho) = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\boldsymbol{\theta})])$$

#### Remind!

$$\rho^{\star} = \arg\min_{\rho} CE(\rho) = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\boldsymbol{\theta})])$$

$$CE(\rho) \stackrel{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound}$$

#### Remind!

$$\rho^* = \arg\min_{\rho} CE(\rho) = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\boldsymbol{\theta})])$$

$$CE(\rho) \overset{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound} \overset{PAC-Bayes}{\lesssim} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta,D)] + \frac{KL(\rho,\pi) + \ln\frac{1}{\xi} + \psi_{\pi,\nu}(c,n)}{cn}}_{PAC-Bayes\ bound}$$

#### Remind!

$$\rho^{\star} = \arg\min_{\rho} CE(\rho) = \arg\min_{\rho} KL(\nu(\mathbf{x}), \mathbb{E}_{\rho(\theta)}[p(\mathbf{x}|\boldsymbol{\theta})])$$

$$CE(\rho) \overset{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound} \overset{PAC-Bayes}{\lesssim} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta,D)] + \frac{KL(\rho,\pi) + \ln\frac{1}{\xi} + \psi_{\pi,\nu}(c,n)}{cn}}_{PAC-Bayes\ bound}$$

#### The learning strategy is to minimize the PAC-Bayes bound

•  $\rho^{\star}$  is the **Bayesian posterior** for c=1 (Germain et al. 2016),

$$\rho^{\star} = p(\boldsymbol{\theta}|D) = \frac{p(D|\boldsymbol{\theta})\pi(\boldsymbol{\theta})}{\int p(D|\boldsymbol{\theta})\pi(\boldsymbol{\theta})d\boldsymbol{\theta}}$$

• The Bayesian learning strategy,

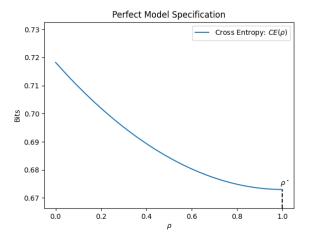
$$CE(\rho) \overset{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound} \overset{PAC-Bayes}{\lesssim} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta,D)] + \frac{KL(\rho,\pi) + \ln\frac{1}{\xi} + \psi_{\pi,\nu}(c,n)}{cn}}_{PAC-Bayes\ bound}$$

The Bayesian learning strategy,

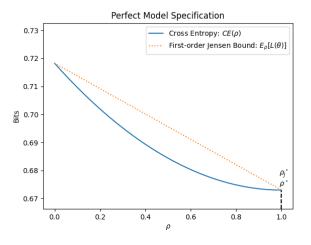
$$CE(\rho) \overset{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound} \overset{PAC-Bayes}{\lesssim} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta,D)] + \frac{KL(\rho,\pi) + \ln\frac{1}{\xi} + \psi_{\pi,\nu}(c,n)}{cn}}_{PAC-Bayes\ bound}$$

• The minimum of the Jensen bound is a Dirac-delta distribution centered around,

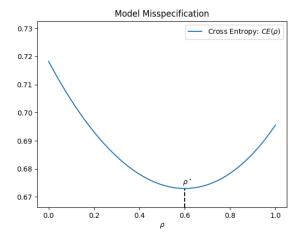
$$\boldsymbol{\theta}_{ML}^{\star} = \arg\min_{\boldsymbol{\theta}} KL(\boldsymbol{\nu}(\mathbf{x}), p(\mathbf{x}|\boldsymbol{\theta}))$$



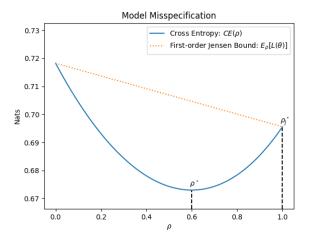
 $CE(\rho)$ 



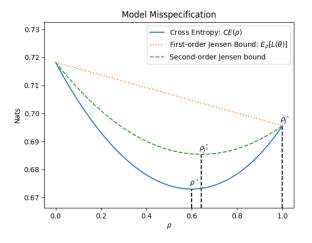
$$CE(\rho) \stackrel{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound}$$



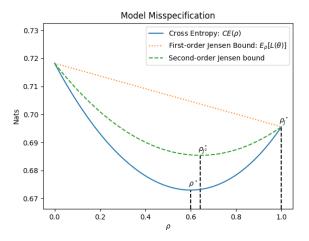
 $CE(\rho)$ 



$$CE(\rho) \stackrel{Jensen}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)]}_{Jensen\ bound}$$



$$CE(\rho) \overset{(Liao\&Berg,2019)}{\leq} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)] - \mathbb{V}(\rho)}_{Second-order\ Jensen\ boun}$$



$$\underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta)] - \mathbb{V}(\rho)}_{cond-order\ Jensen\ bound} \overset{PAC-Bayes}{\lesssim} \underbrace{\mathbb{E}_{\rho(\theta)}[L(\theta,D)] - \hat{\mathbb{V}}(\rho,D) + \frac{KL(\rho,\pi) + \ln\frac{1}{\xi} + \psi_{\pi,\nu}(c,n)}{cn}}_{Second-order\ PAC-Bayes\ bound}$$

Second-order Jensen bound

### A new learning framework

#### PAC<sup>2</sup>-Variational Inference

• Variational methods for minimizing second-order PAC-Bayes bounds,

$$\arg\min_{\rho\in Q} \mathbb{E}_{\rho(\theta)}[L(\theta,D)] - \hat{\mathbb{V}}(\rho,D) + \frac{KL(\rho,\pi)}{n}$$

where Q is a tractable family of densities (i.e. fully factorized Gaussian distribution).

### A new learning framework

#### PAC<sup>2</sup>-Variational Inference

• Variational methods for minimizing second-order PAC-Bayes bounds,

$$\arg\min_{\rho\in Q} \mathbb{E}_{\rho(\theta)}[L(\theta,D)] - \hat{\mathbb{V}}(\rho,D) + \frac{KL(\rho,\pi)}{n}$$

where Q is a tractable family of densities (i.e. fully factorized Gaussian distribution).

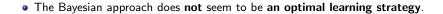
#### Variational Inference

Standard Variational methods tries to minimize the first-order PAC-Bayes bound,

$$\arg\min_{\rho\in Q} \mathbb{E}_{\rho(\theta)}[L(\theta,D)] + \frac{KL(\rho,\pi)}{n}$$

Conclusions

### Conclusions and Future Works



• Novel variational and ensemble learning algorithms.

https://github.com/PGM-Lab/PAC2BAYES