

AFRL-VA-WP-TR-1999-3051

**DEVELOPMENT OF THE
AERODYNAMIC/AEROSERVOELASTIC
MODULES IN ASTROS**



**VOLUME 3: ZAERO APPLICATIONS
MANUAL (F33615-96-C-3217)**

**P.C. CHEN
D. SARHADDI
D.D. LIU**

**ZONA Technology, Inc.
7430 E. Stetson Drive, Ste 205
Scottsdale, AZ 85251**

**A. G. STRIZ
University of Oklahoma**

FEBRUARY 1999

FINAL REPORT FOR PERIOD SEPTEMBER 1996 – SEPTEMBER 1998

Approved for public release; distribution unlimited

**AIR VEHICLES DIRECTORATE
AIR FORCE RESEARCH LABORATORY
AIR FORCE MATERIEL COMMAND
WRIGHT-PATTERSON AIR FORCE BASE, OH 45433-7542**

19991115 072

DTIC QUALITY INSPECTED 4

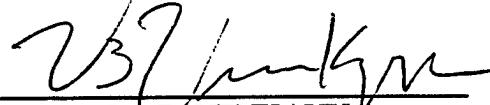
NOTICE

USING GOVERNMENT DRAWINGS, SPECIFICATIONS, OR OTHER DATA INCLUDED IN THIS DOCUMENT FOR ANY PURPOSE OTHER THAN GOVERNMENT PROCUREMENT DOES NOT IN ANY WAY OBLIGATE THE UNITED STATES GOVERNMENT. THE FACT THAT THE GOVERNMENT FORMULATED OR SUPPLIED THE DRAWINGS, SPECIFICATIONS, OR OTHER DATA DOES NOT LICENSE THE HOLDER OR ANY OTHER PERSON OR CORPORATION; OR CONVEY ANY RIGHTS OR PERMISSION TO MANUFACTURE, USE, OR SELL ANY PATENTED INVENTION THAT MAY BE RELATED TO THEM.

THIS REPORT IS RELEASEABLE TO THE NATIONAL TECHNICAL INFORMATION SERVICE (NTIS). AT NTIS, IT WILL BE AVAILABLE TO THE GENERAL PUBLIC, INCLUDING FOREIGN NATIONS.

THIS TECHNICAL REPORT HAS BEEN REVIEWED AND IS APPROVED FOR PUBLICATION.

VICTORIA A. TISCHLER
Aerospace Engineer
Design and Analysis Branch



VIPPERLA B. VENKAYYA
Leader, Multidisciplinary Design
Design & Analysis Branch



NELSON D. WOLF, Chief
Design and Analysis Branch
Structures Division

IF YOUR ADDRESS HAS CHANGED, IF YOU WISH TO BE REMOVED FROM OUR MAILING LIST, OR IF THE ADDRESSEE IS NO LONGER EMPLOYED BY YOUR ORGANIZATION, PLEASE NOTIFY AFRL/VASD BLDG 45, 2130 8TH STREET, SUITE 1, WRIGHT-PATTERSON AFB OH 45433-7542 TO HELP MAINTAIN A CURRENT MAILING LIST.

COPIES OF THIS REPORT SHOULD NOT BE RETURNED UNLESS RETURN IS REQUIRED BY SECURITY CONSIDERATIONS, CONTRACTUAL OBLIGATIONS, OR NOTICE ON A SPECIFIED DOCUMENT.

REPORT DOCUMENTATION PAGE

Form Approved
OMB No. 0704-0188

Public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302, and to the Office of Management and Budget, Paperwork Reduction Project (0704-0188), Washington, DC 20503.

1. AGENCY USE ONLY (Leave Blank)	2. REPORT DATE FEBRUARY 04, 1999	3. REPORT TYPE AND DATES COVERED FINAL 24 SEP 1996 – 24 SEP 1998	
4. TITLE AND SUBTITLE DEVELOPMENT OF THE AERODYNAMIC/AEROSERVOELASTIC MODULES IN ASTROS VOLUME 3 – ZAERO APPLICATIONS MANUAL		5. FUNDING NUMBERS C: F09603-95-D-0175 PE: 65520F PR: STTR TA: 41 WU: 00	
6. AUTHOR(S) P. C. Chen, D. D. Liu, D. Sarhaddi, ZONA Technology, Inc.; A.G. Striz, University of Oklahoma			
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) ZONA Technology, Inc. 7434 E. Stetson Drive, Suite 205 Scottsdale, AZ 85251 Tel 602-945-9988 / Fax 602-945-6588		8. PERFORMING ORGANIZATION REPORT NUMBER ZONA 99-11C	
9. SPONSORING/MONITORING AGENCY(S) AND ADDRESS(ES) Air Vehicles Directorate Air Force Research Laboratory Air Force Materiel Command Wright-Patterson Air Force Base, Oh 45433-7542 POC: Dr V. B. Venkayya, AFRL/VASD, 937-255-2582		10. SPONSORING/MONITORING AGENCY REPORT NUMBER AFRL-VA-WP-TR-1999-3051	
11. SUPPLEMENTARY NOTES			
12a. DISTRIBUTION/AVAILABILITY STATEMENT APPROVED FOR PUBLIC RELEASE; DISTRIBUTION UNLIMITED		12b. DISTRIBUTION CODE	
13. ABSTRACT (Maximum 200 words) This report is a part of the documentations which describe the complete development of an STTR Phase II effort entitled, "Development of the Aerodynamic/Aeroservoelastic Modules in ASTROS." This report is one of four manuals that comprise the final report. The remaining reports consist of the ZAERO User's Manual (Volume I), the ZAERO Programmer's Manual (Volume II) and the ZAERO Theoretical Manual (Volume IV). ASTROS* is the seamless integration of the ZAERO module into ASTROS. As an aerodynamic enhancement to ASTROS, ZAERO is the ZONA aerodynamic module, unified for all Mach number ranges. This manual assumes the reader is familiar with the ASTROS system (Version 10.0), its terminology and user interface. This Applications Manual is divided into to Volumes. Volume I presents sample analysis cases in the flutter and static aeroelasticity disciplines that focus on the the different aerodynamic methods (i.e. subsonic, transonic, supersonic and hypersonic) within ZAERO. Volume II presents three complete optimization cases of more complicated configurations.			
14. SUBJECT TERMS Multidisciplinary Optimization, ZAERO Module, ASTROS*, Subsonic-Transonic-Supersonic-Hypersonic Aerodynamics, Aeroelasticity, Aerosevoelasticity, Flutter			15. NUMBER OF PAGES 158
			16. PRICE CODE
17. SECURITY CLASSIFICATION OF REPORT UNCLASSIFIED	18. SECURITY CLASSIFICATION OF THIS PAGE UNCLASSIFIED	19. SECURITY CLASSIFICATION OF THIS ABSTRACT UNCLASSIFIED	20. LIMITATION OF ABSTRACT SAR

Table of Contents

	Page
1.0 INTRODUCTION	1
Volume I <i>Flutter and Static Aeroelastic Cases</i>	
2.0 FLUTTER CASES	2
2.1 <u>Case 1</u> : Subsonic ($M=0.45$) Flutter Analysis of a 15-Degree Sweptback Wing (HA145E)	2
2.2 <u>Case 2</u> : Low Supersonic ($M=1.3$) Flutter Analysis of a 15-Degree Sweptback Wing (HA145FB) With and Without Thickness Effect	7
2.3 <u>Case 3</u> : High Supersonic ($M=3.0$) Flutter Analysis of a 15-Degree Sweptback Wing (HA145G) With and Without Thickness Effect	12
2.4 <u>Case 4</u> : Sample Wing-Body-Tiptank Flutter Analysis	17
2.5 <u>Case 5</u> : AGARD Standard 445.6 Wing – Transonic Flutter Analysis	25
3.0 STATIC AEROELASTICITY (TRIM CASES)	38
3.1 <u>Case 1</u> : Forward Swept Wing in Level Flight (HA144A)	38
3.2 <u>Case 2</u> : Forward Swept Wing Airplane in Antisymmetric Maneuvers (HA144D)	44

List of Figures

Figure No.	Description	Page
2.1.1	15 Degree Sweptback Wing (a) Structural Model and (b) Aerodynamic Model.	2
2.1.2	Flutter Results of Case HA145E, $M=0.45$.	4
2.2.1	15 Degree Sweptback Planform and Cross Section (Tuovilla, W.J., NACA RM L55E11, 1955).	7
2.4.1	Aerodynamic Model of Sample Wing-Body-Tiptank Case.	17
2.4.2	Cropped Delta Wing Structural Finite Element Model.	18
2.4.3	K-Method Flutter Curves of Wing-Body-Tiptank Case ($M=0.8$, Sea Level Density).	20
2.4.4	P-K Method Flutter Curves of Wing-Body-Tiptank Case ($M=0.8$, Sea Level Density).	21
2.4.5	K-Method Flutter Curves of Wing-Body-Tiptank Case ($M=1.2$, Sea Level Density).	21
2.4.6	P-K Method Flutter Curves of Wing-Body-Tiptank Case ($M=1.2$, Sea Level Density).	21
2.5.1	Aerodynamic Model of the AGARD Standard 445.6 Wing.	25
2.5.2	AGARD Standard 445.6 Weakened Wing Natural Frequencies and Mode Shapes (1 st 5 modes).	26
2.5.3	AGARD Standard 445.6 Weakened Wing CAPTSD (Euler) and ENSAERO (Navier-Stokes = N-S) Steady Pressure Results ($M=0.95$, $\alpha=0.0^\circ$).	27
2.5.4	Plots of Flutter Speed Coefficients and Frequency Ratios of the AGARD Standard 445.6 Weakened Wing (matched point analysis).	31
3.1.1	Forward Swept Wing (FSW) (a) Structural Model and (b) Aerodynamic Model.	38
3.2.1	Side View of FSW Showing the Vertical Tail Fin (a) Structural Model and (b) Aerodynamic Model.	44

List of Tables

Table No.	Description	Page
2.1.1	Natural Frequencies and Generalized Mass of Case HA145E.	3
2.2.1	Flutter Results of Case HA145FB ($M=1.3$, $\sigma=0.20606$).	9
2.3.1	Flutter Results of Case HA145FB ($M=3.0$, $\sigma=0.391$).	14
2.4.1	Natural Frequencies and Generalized Mass of the Wing-Body-Tiptank Case.	20
2.5.1	Measured Modal Frequencies and Panel Mass of the AGARD Standard 445.6 Weakened Wing Model.	30
2.5.2	Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.	30
2.5.3	Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.	31
3.1.1	Longitudinal Stability Derivatives of FSW Aircraft at Mach 0.9.	40
3.1.2	Longitudinal Stability Derivatives of FSW Aircraft at Mach 1.3.	40
3.2.1	Lateral Aerodynamic Stability Derivatives of FSW Aircraft with Vertical Tail at Mach 0.9.	46
3.2.2	Trim Set 1 – Steady Roll Solution at Mach 0.9 (flexible aircraft).	46
3.2.3	Trim Set 2 – Abrupt Roll Solution at Mach 0.9 (flexible aircraft).	47

FOREWORD

This final report is submitted in fulfillment of CDRL CLIN 0001, Data Item A001, Title: Scientific and Technical Reports of a Small Business Technology Transfer (STTR) Phase II contract No. F33615-96-C-3217 entitled, "Development of the Aerodynamic/Aeroservoelastic Modules in ASTROS," covering the performance period from 24 September 1996 to 24 September 1998. This document provides the sample cases demonstrating the main features of the ZAERO module in ASTROS*.

This work was performed by ZONA Technology, Inc. and its subcontractor, the University of Oklahoma (Research Institute). This work is the second phase of a continuing two-phase STTR contract supported by AFRL/Wright-Patterson. The first phase STTR contract No. F33615-95-C-3219 entitled, "Enhancement of the Aeroservoelastic Capability in ASTROS," was completed in May 1996 and published as WL-TR-96-3119. Started in September 1996, the present second phase STTR contract was conducted by the same team members as in Phase I. These contributors are: P.C. Chen (P.I.), D. Sarhaddi and D.D. Liu of ZONA Technology Inc. and Fred Striz of the University of Oklahoma.

At AFRL/Wright-Patterson, Capt. Gerald Andersen is the contract monitor and Dr. V.B. Venkayya is the initiator of the whole STTR effort. The technical advice and assistance received from Mr. Doug Niell of The MacNeal Schwendler Corporation, Dr. V.B. Venkayya and others from AFRL during the course of the present phase on the development of ASTROS* are gratefully acknowledged.

1.0 INTRODUCTION

There are four major documents that describe the ZONA Aerodynamics (ZAERO) Module which has been seamlessly integrated into the Automated STRuctural Optimization System (ASTROS). These are: the ZAERO User's, Programmer's, Application and Theoretical Manuals for ASTROS*. While ZAERO represents the ZONA Aerodynamics Module, ASTROS* is defined as the seamless integration of ZAERO into ASTROS, i.e. ASTROS* = ZAERO + ASTROS. This Applications Manual provides guidelines and sample cases to demonstrate the key features and use of the ZAERO module within ASTROS.

This Applications Manual is divided into to Volumes. Volume I presents sample analysis cases in the flutter and static aeroelasticity disciplines. Volume II provides sample optimization cases of more complex configurations.

The aerodynamic models in Volume I are kept small and are intended to demonstrate proper implementation and usage of the four ZAERO methods (i.e. ZONA6/subsonic, ZTAIC/transonic, ZONA7/supersonic and ZONA7U/hypersonic), as well as, proper aerodynamic geometry modeling and splining of the aerodynamic model to the structure.

The aerodynamic models in Volume II involve more realistic aircraft configurations and are consequently more complicated. Emphasis is placed on ASTROS* optimization using the ZAERO method.

Sections 2.0 and 3.0 comprise Volume I and present the Flutter and Static Aeroelastic cases, respectively. Many cases are taken from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68, and have been modified for ASTROS* input for validation of the ZAERO results.

Section 4.0 comprises Volume II of this manual and presents the static aeroelastic, normal modes and combined multidisciplinary (MDO) optimization cases.

VOLUME I

Flutter and Static Aeroelastic Analysis Cases

2.0 FLUTTER CASES

2.1 Case 1: Subsonic ($M=0.45$) Flutter Analysis of a 15-Degree Sweptback Wing (HA145E)

- **Purpose:** Demonstrate a wing only, subsonic (i.e. ZONA6 method) flutter case using the P-K and K flutter solution methods.
- **Description of Input:**

A 15 degree sweptback wing (modified HA145E case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68) is considered for this case. The structural and aerodynamic models are shown in Fig 2.1.1.

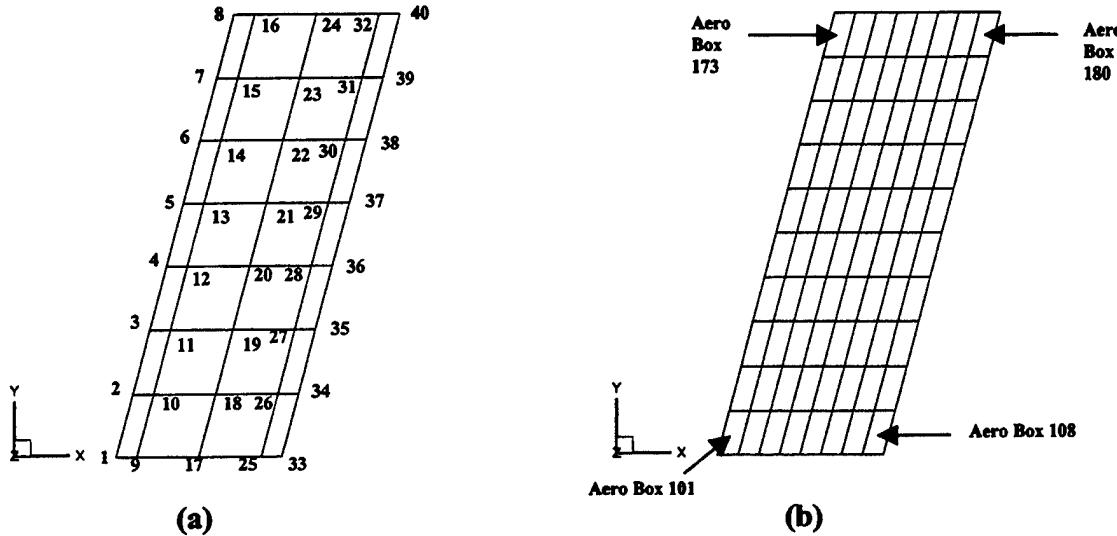


Figure 2.1.1 15 Degree Sweptback Wing (a) Structural Model and (b) Aerodynamic Model.

- Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 1 that selects the single-point constraints for grid points, REDUCE = 25 that selects the analysis set degrees of freedom, and METHOD = 10 that selects the eigenvalue extraction method to be used.

- Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 for a description of the structural model.

- Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.1092E-07 slinches (sea level density) and reference length of 2.07055 inches are used.

The **MKAEROZ** bulk data card specifies a freestream Mach number of 0.45 and 10 reduced frequencies from 0.0001 to 0.20.

- Aerodynamic Model

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x- and y- coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

- Spline

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by SETK = 101 and a **SET1** bulk data card by SETG = 100. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with WID of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.1 for **SET1 GRID** point id's and Fig 2.1.1.a).

- Flutter

A **FLUTTER** bulk data card with SETID=30 requests that the P-K and K methods be used (METHOD entry set to PKK). The DENS entry refers to an **FLFACT** bulk data card with SID=1 that lists the density ratios for this case. The IDMK=1000 entry refers to the **MKAEROZ** bulk data card for this flutter case establishing the Mach number and reduced frequencies to be used. Finally, the VEL entry refers to an **FLFACT** bulk data card that lists the velocities to be used by the P-K flutter analysis method.

• Description of Output:

Two disciplines were performed in this ASTROS* run – a modal analysis and flutter analysis. The structural natural frequencies and generalized mass for the first four modes generated by the ASTROS* modal analysis is shown in Table 2.1.1 along with the MSC/NASTRAN results.

Table 2.1.1 Natural Frequencies and Generalized Mass of Case HA145E.

Mode No.	ASTROS*		MSC/NASTRAN	
	Natural Frequency (Hz)	Generalized Mass	Natural Frequency (Hz)	Generalized Mass
1	34.7220	2.4861E-05	34.3439	2.4855E-05
2	211.469	8.7983E-06	210.000	9.0881E-06
3	260.147	8.6338E-06	260.429	8.5232E-06
4	645.657	7.4457E-06	634.761	7.9439E-06

The flutter results using ZONA6 aerodynamics of ASTROS* by both the P-K and K methods are compared with that of MSC/NASTRAN using DLM with the KE method (see Fig 2.1.2).

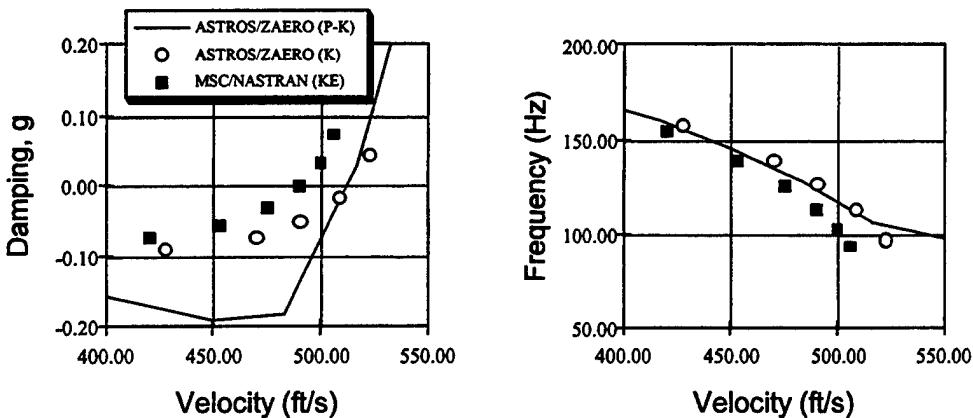


Figure 2.1.2 Flutter Results of Case HA145E, $M=0.45$.

Excellent agreement in terms of flutter speed at zero damping between the ASTROS* P-K and K methods is obtained validating the K method. However, a small difference of flutter speed is observed between ASTROS* and MSC/NASTRAN. This difference is most likely caused by the differences in the data obtained from the dynamic analyses (Table 2.1.1).

- ***Input Data Listing:***

Listing 2.1 Input Data for the 15 Degree Sweptback Wing (HA145E).

```

ASSIGN DATABASE ICWCU3 PASS NEW DELETE
SOLUTION
TITLE = ZAERO FLUTTER CASE (HA145E): HALF SPAN 15-DEG SWEPT UNTAPERED WING
SUBTIT = PK & K-METHOD OF FLUTTER ANALYSIS
ANALYZE
  PRINT ROOTS = ALL
  BOUNDARY SPC = 1, REDUCE = 25, METHOD = 10
  LABEL = MODAL ANALYSIS
  MODES
  FLUTTER (FLCOND=30)
  LABEL = SUBSONIC CASE M=0.45
END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
GRID 1      0.0  0.0  0.0
GRID 2      .211491  .7893  0.0
GRID 3      .422983  1.5786  0.0
GRID 4      .634474  2.3679  0.0
GRID 5      .845966  3.1572  0.0
GRID 6      1.05746  3.9465  0.0
GRID 7      1.26995  4.7358  0.0
GRID 8      1.48044  5.5251  0.0
GRID 9      2.58819  0.0  0.0
GRID 10     .47031  .7893  0.0
GRID 11     .681802  1.5786  0.0
GRID 12     .893293  2.3679  0.0
GRID 13     1.10478  3.1572  0.0
GRID 14     1.31628  3.9465  0.0
GRID 15     1.52777  4.7358  0.0
GRID 16     1.73926  5.5251  0.0
GRID 17     1.03528  0.0  0.0
GRID 18     1.24677  .7893  0.0
GRID 19     1.45826  1.5786  0.0
GRID 20     1.66975  2.3679  0.0
GRID 21     1.88124  3.1572  0.0
GRID 22     2.09273  3.9465  0.0
GRID 23     2.30422  4.7358  0.0
GRID 24     2.51572  5.5251  0.0
GRID 25     1.81173  0.0  0.0
GRID 26     2.02322  .7893  0.0
GRID 27     2.23472  1.5786  0.0
GRID 28     2.44621  2.3679  0.0

```


2.2 Case 2: Low Supersonic (M=1.3) Flutter Analysis of a 15-Degree Sweptback Wing (HA145FB) With and Without Thickness Effect

- **Purpose:** Demonstrate a wing only low supersonic flutter case with and without thickness effects using the P-K and K methods.
- **Description of Input:**

The same 15 degree sweptback wing presented in Case 1 is considered here. It is a modified sample test case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 (case HA145FB). Both the structural and aerodynamic models for this case were shown in Fig 2.1.1.

This case presents both the flat plate results (ZONA7 aerodynamics) and the wing with supersonic thickness effect results (ZONA7U aerodynamics) of a hexagonal wing cross section (Tuovila, W.J., NACA RM L55E11, 1955). The wing planform and cross section are shown in Fig 2.2.1.

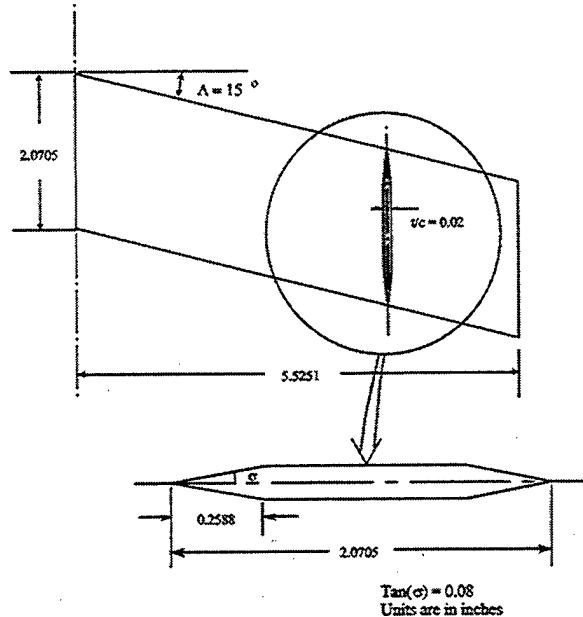


Figure 2.2.1 15 Degree Sweptback Planform and Cross Section (Tuovila, W.J., NACA RM L55E11, 1955).

- Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 1 that selects the single-point constraints for grid points, REDUCE = 25 that selects the analysis set degrees of freedom, and METHOD = 10 that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first FLCOND = 30 selects the flutter case with no thickness effect and the second FLCOND = 40 selects the flutter case with the supersonic thickness effect.

- Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68 for a description of the structural model.

- Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.145E-07 slinches (sea level density) and reference length of 2.07055 inches are used.

Two **MKAEROZ** bulk data cards are used to specify a freestream Mach number of 1.3 and 8 reduced frequencies ranging from 0.0001 to 0.08. Although both **MKAEROZ** bulk data cards have the same Mach number and reduced frequency input, two cards are required to compute both Aerodynamic Influence Coefficient (AIC) matrices using the linear aerodynamics method (ZONA7) and the nonlinear aerodynamics method (ZONA7U) which includes the supersonic thickness effect.

- Aerodynamic Model

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x- and y- coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

A **PAFOIL7** bulk data card is used to define the 2% thick hexagonal airfoil section. The **ITAX** entry refers to an **AEFACT** bulk data card that specifies four x-coordinate points in percentage of the airfoil chord length. **ITAX** is a negative integer to request that linear interpolation be used between the airfoil points. The **ITHR/T** and **ICAMR/T** entries refer to **AEFACT** bulk data cards that specify the airfoil wing root and tip half thickness and cambers, respectively, at each x-coordinate.

- Spline

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the **SETK** = 101 entry and a **SET1** bulk data card by the **SETG** = 100 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with **WID** of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.2 for **SET1 GRID** point id's and Fig 2.1.1).

- Flutter

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses; one without thickness effects (**IDMK**=1000 entry refers to the **MKAEROZ** bulk data card employing the linear ZONA7 method at Mach 1.3) and one with the wing thickness effects (**IDMK**=2000 entry refers to the **MKAEROZ** bulk data card employing the nonlinear ZONA7U method at Mach 1.3). Both **FLUTTER** cards request that the P-K and K methods be used (**METHOD** entry set to **PKK**) and use

the same density ratio and velocities specified in the **FLFACT** bulk data cards with SID=1 and 3, respectively.

• **Description of Output:**

The flutter results using ZONA7 aerodynamics of ASTROS* are compared with results from the ZONA51 method of MSC/NASTRAN (i.e. Aero Option II). Excellent agreement between the two methods are obtained (see Table 2.2.1). This is expected since the lifting surface part of ZONA7 is identical to that of ZONA51.

Table 2.2.1 Flutter Results of Case HA145FB (M = 1.3, σ = 0.20606).

	V_f (ft/s)	f_f (Hz)
Test	1280	102
W.P. Rodden	1405	129
MSC/NASTRAN P-K Method		
MSC/NASTRAN (ZONA51)	1576	132
ASTROS* K Method / P-K Method		
ZONA7 (no thickness)	1583 / 1601	132 / 130
ZONA7U (thickness effect)	1415 / 1426	123 / 122

σ = Density Ratio = ρ / ρ_{sl}

• **Input Data Listing:**

Listing 2.2 Input Data for the 15 Degree Sweptback Wing With and Without Thickness (HA145FB).

```

ASSIGN DATABASE ICWCU3 PASS NEW DELETE
SOLUTION
TITLE = ZZERO FLUTTER CASE (HA145FB): HALF SPAN 15-DEG SWEPT UNTAPERED WING
SUBTIT = PK & K-METHOD OF FLUTTER ANALYSIS, ZONA7 + ZONA7U
ANALYZE
PRINT ROOTS=ALL
BOUNDARY SPC = 1, REDUCE = 25, METHOD = 10
LABEL = MODAL ANALYSIS
MODES
FLUTTER (FLCOND=30)
LABEL = WITHOUT THICKNESS
FLUTTER (FLCOND=40)
LABEL = WITH THICKNESS
END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
GRID 1 0.0 0.0 0.0
GRID 2 .211491 .7893 0.0
GRID 3 .422983 1.5786 0.0
GRID 4 .634474 2.3679 0.0
GRID 5 .845966 3.1572 0.0
GRID 6 1.05746 3.9465 0.0
GRID 7 1.26895 4.7358 0.0
GRID 8 1.48044 5.5251 0.0
GRID 9 .258819 0.0 0.0
GRID 10 .47031 .7893 0.0
GRID 11 .681802 1.5786 0.0
GRID 12 .893293 2.3679 0.0
GRID 13 1.10478 3.1572 0.0
GRID 14 1.31628 3.9465 0.0
GRID 15 1.52777 4.7358 0.0
GRID 16 1.73926 5.5251 0.0
GRID 17 1.03524 0.0 0.0
GRID 18 1.24677 .7893 0.0
GRID 19 1.45826 1.5786 0.0
GRID 20 1.66975 2.3679 0.0
GRID 21 1.88124 3.1572 0.0
GRID 22 2.09273 3.9465 0.0
GRID 23 2.30422 4.7358 0.0
GRID 24 2.51572 5.5251 0.0
GRID 25 1.81173 0.0 0.0
GRID 26 2.02322 .7893 0.0

```


\$ TWO MKAEROZ BULK DATA CARDS ARE USED. THE FIRST MKAEROZ ACTIVATES THE \$
 \$ LINEAR METHOD (ZONA7) AND THE SECOND THE NONLINEAR METHOD (ZONA7U) \$
 \$ VIA THE METHOD FLAG. EACH MKAEROZ CARD IS REFERENCED BY A FLUTTER \$
 \$ CARD BELOW.
 \$
 \$ IDMK MACH METHOD IDFLT SAVE <--FILENAME--> PRINT \$
 MKAEROZ 1000 1.3 0 +MK1
 \$ FREQ1 FREQ2 ETC \$
 +MK1 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 \$
 \$
 MKAEROZ 2000 1.3 1 +MK2
 +MK2 0.0001 0.02 0.03 0.04 0.05 0.06 0.07 0.08 \$
 \$
 \$ * WING MACROELEMENT * \$
 \$
 \$ WID LABEL ACCORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7 \$
 CAERO7 101 WING 0 11 9 100 +CA101
 \$ XRL YRL ZRL RCH LRCHD ATTCHR \$
 +CA101 0.0 0.0 0.0 2.07055 0 0 +CA102
 \$ XRT YRT ZRT TCH LTCHD ATTCHT \$
 +CA102 1.48044 5.52510 0.0 2.07055 0 0 \$
 \$
 \$ THE PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL THICKNESS ALLOWING \$
 \$ FOR THE INPUT OF HALF THICKNESS, CAMBER AND LEADING EDGE RADII AT \$
 \$ THE WING ROOT AND TIP. THICKNESS AND CAMBER DISTRIBUTIONS BETWEEN \$
 \$ THE WING ROOT AND TIP ARE INTERPOLATED. FOR THIS CASE, A 2% THICK \$
 \$ HEXAGONAL AIRFOIL SECTION IS DEFINED. A NEGATIVE VALUE OF ITAX \$
 \$ REQUESTS THAT A LINEAR INTERPOLATION BE USED FOR THICKNESS AND \$
 \$ CAMBER DISTRIBUTIONS (POSITIVE VALUE IS FOR CUBIC INTERPOLATION). \$
 \$ THICKNESS AND CAMBER DISTRIBUTIONS ARE USED ONLY FOR SUPERSONIC \$
 \$ THICKNESS EFFECTS (ZONA7U) WHEN THE 'METHOD' ENTRY IS ACTIVE IN \$
 \$ MKAEROZ BULK DATA CARD.
 \$
 \$ ID ITAX ITHR ICAMR RADR ITHT ICAMT RADT \$
 PAFOIL7 100 -101 102 103 0.0 102 103 0.0 \$
 \$
 \$ SID D1 D2 ETC
 AEFFACT 101 0.0 12.5 87.5 100.
 AEFFACT 102 0.0 1.0 1.0 0.0
 AEFFACT 103 0.0 0.0 0.0 0.0 \$
 \$
 \$ * SURFACE SPLINE FIT ON THE WING * \$
 \$
 \$ EID MODEL CP SETK SETG DZ EPS \$
 SPLINE1 100 WING 101 100 0.0 \$
 \$
 \$ SETID MACROID BOX1 BOX2 ETC
 PANLST2 101 101 101 THRU 180 \$
 \$
 \$ SID G1 G2 ETC
 SET1 100 2 4 6 8 9 11 13 +\$1
 +\$1 15 18 20 22 24 25 27 29 +\$2
 +\$2 31 34 36 38 40 \$
 \$
 \$ * * FLUTTER ANALYSIS * * \$
 \$
 \$ THE FLUTTER BULK DATA CARDS EMPLOY THE PK AND K FLUTTER SOLUTION \$
 \$ METHODS. EACH FLUTTER CARD REFERS TO A DIFFERENT MKAEROZ BULK DATA \$
 \$ CARD. THE FIRST FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH AN IDMK \$
 \$ OF 1000 (WING WITHOUT THICKNESS CASE - ZONA7 AERODYNAMICS). THE \$
 \$ SECOND FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH IDMK = 2000 \$
 \$ (WING WITH THICKNESS CASE - ZONA7U AERODYNAMICS). \$
 \$
 \$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID \$
 FLUTTER 30 PKK 1 1000 3 +FL1
 \$ SYMXZ SYMXY EPS CURVFIT PRINT \$
 +FL1 1 \$
 \$
 FLUTTER 40 PKK 1 2000 3 +FL2
 +FL2 1 \$
 \$ SID F1 F2 ETC
 FLFACT 1 .20606
 FLFACT 3 14400. 15600. 16800. 18000. 19200. 20400.
 ENDDATA

2.3 Case 3: High Supersonic (M=3.0) Flutter Analysis of a 15-Degree Sweptback Wing (HA145G) With and Without Thickness Effect

- **Purpose:** Demonstrate a wing only, with and without thickness effect, high supersonic flutter case using the P-K and K methods.

- **Description of Input:**

The same 15 degree sweptback wing presented in Case 1 is considered. It is a modified sample test case from the MSC/NASTRAN Aeroelastic Analysis User's Guide (case HA145G). Both the structural and aerodynamic models were shown in Fig 2.1.1.

This case presents both the flat plate result (ZONA7 aerodynamics) and the wing with supersonic thickness effect result (ZONA7U aerodynamics) of a hexagonal wing cross section (Tuovila, W.J., NACA RM L55E11, 1955). The wing planform and cross section were shown in Fig 2.2.1.

There are two differences between the present case and Case 2. First, the Mach number for the present case is 3.0, whereas, Case 2 was 1.3. Second, the material properties (i.e. **MAT1** bulk data card) of the wing are different than that of Case 2. The wing of Case 2 was made of aluminum while the wing of Case 3 is made of magnesium. The nominal properties of magnesium include a moduli of elasticity $E = 6.0 \times 10^6$ and $G = 2.4 \times 10^6$ psi, with a density of 0.064 lb/in^3 . These moduli and density were adjusted to match experimental data. The adjusted values, used in the present **MAT1** card, are $E = 6.3604 \times 10^6$, $G = 2.5442 \times 10^6$ psi and a density of $0.0626202 \text{ lb/in}^3$.

- *Solution Control*

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 1 that selects the single-point constraints for grid points, REDUCE = 25 that selects the analysis set degrees of freedom, and METHOD = 10 that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first FLCOND = 30 selects the flutter case with no thickness effect and the second FLCOND = 40 selects the flutter case with the supersonic thickness effect.

- *Structural Model*

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis Guide for a description of the structural model.

- *Aerodynamic Parameters / Flight Conditions*

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of $1.145E-07$ slinches (sea level density) and reference length of 2.07055 inches are used.

Two **MKAEROZ** bulk data cards are used to specify a freestream Mach number of 3.0 and 8 reduced frequencies ranging from 0.0001 to 0.08. Although both **MKAEROZ** bulk data cards

have the same Mach number and reduced frequency input, two cards are required to compute both Aerodynamic Influence Coefficient (AIC) matrices using the linear aerodynamics method (ZONA7) and the nonlinear aerodynamics method (ZONA7U) which includes the supersonic thickness effect.

- Aerodynamic Model

One **CAERO7** wing macroelement is defined with 8 chordwise and 10 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are both 2.07055 inches with a 5.5251 inch semispan length. The wing tip x and y coordinates are located at 1.48044 and 5.5251 inches, respectively, establishing a 15 degree leading edge sweep angle.

A **PAFOIL7** bulk data card is used to define the 2% thick hexagonal airfoil section. The **ITAX** entry refers to an **AEFACT** bulk data card that specifies four x-coordinate points in percentage of the airfoil chord length. **ITAX** is a negative integer to request that linear interpolation be used between the airfoil points. The **ITHRT** and **ICAMRT** entries refer to **AEFACT** bulk data cards that specify the airfoil wing root and tip half thickness and cambers, respectively, at each x-coordinate.

- Spline

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the **SETK** = 101 entry and a **SET1** bulk data card by the **SETG** = 100 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with **WID** of 101), and splines all of the wing aerodynamic boxes (101 through 180) to the structural grid points listed in the **SET1** bulk data card (see Input Data Listing 2.3 for **SET1** **GRID** point id's and Fig 2.1.1).

- Flutter

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses; one without thickness effects (**IDMK**=1000 entry refers to the **MKAEROZ** bulk data card employing the linear ZONA7 method at Mach 3.0) and one with the wing thickness effects (**IDMK**=2000 entry refers to the **MKAEROZ** bulk data card employing the nonlinear ZONA7U method at Mach 3.0). Both **FLUTTER** cards request that the P-K and K methods be used (**METHOD** entry set to **PKK**) and use the same density ratio and velocities specified in the **FLFACT** bulk data cards with **SID**=1 and 3, respectively.

• Description of Output:

The flutter results using ZONA7 aerodynamics of ASTROS* are compared with results from the ZONA51 method of MSC/NASTRAN (i.e. Aero Option II). Excellent agreement between the two methods are obtained (see Table 2.3.1). This is expected since the lifting surface part of ZONA7 is identical to that of ZONA51.

Table 2.3.1 Flutter Results of Case HA145FB (M = 3.0, σ = 0.391).

	V_f (ft/s)	f_r (Hz)
Test	2030	146
W.P. Rodden	2077	149
ASTROS* K Method / P-K Method		
ZONA7 (no thickness)	2369 / 2448	158 / 154
ZONA7U (thickness effect)	1897 / 1923	154 / 152

σ = Density Ratio = ρ / ρ_{air}

• **Input Data Listing:**

Listing 2.3 Input Data for the 15 Degree Sweptback Wing With and Without Thickness (HA145G).

```

ASSIGN DATABASE ICWCUC3 PASS NEW DELETE
SOLUTION
TITLE - ZZERO FLUTTER CASE (HA145G): HALF SPAN 15-DEG SWEEP UNTAPERED WING
SUBTIT - PK & K METHOD OF FLUTTER ANALYSIS, ZONA7 + ZONA7U
ANALYZE
  PRINT ROOTS-ALL
  BOUNDARY SPC - 1, REDUCE - 25, METHOD - 10
  LABEL - MODAL ANALYSIS
  MODES
  LABEL - WITHOUT THICKNESS
  FLUTTER (FLCOND=30)
  LABEL - WITH THICKNESS
  FLUTTER (FLCOND=40)
END
BEGIN BULK
$...1...2....3....4....5....6....7....8....9....10...
GRID  1      0.0   0.0   0.0
GRID  2      .211491  .7893  0.0
GRID  3      .422983  1.5786 0.0
GRID  4      .634474  2.3679 0.0
GRID  5      .845966  3.1572 0.0
GRID  6      1.05746  3.9465 0.0
GRID  7      1.26895  4.7358 0.0
GRID  8      1.48044  5.5251 0.0
GRID  9      1.58819  0.0   0.0
GRID 10     .47031  .7893  0.0
GRID 11     .681802  1.5786 0.0
GRID 12     .893293  2.3679 0.0
GRID 13     1.10478  3.1572 0.0
GRID 14     1.31628  3.9465 0.0
GRID 15     1.52777  4.7358 0.0
GRID 16     1.73926  5.5251 0.0
GRID 17     1.03528  0.0   0.0
GRID 18     1.24677  .7893  0.0
GRID 19     1.45826  1.5786 0.0
GRID 20     1.66975  2.3679 0.0
GRID 21     1.88124  3.1572 0.0
GRID 22     2.09273  3.9465 0.0
GRID 23     2.30422  4.7358 0.0
GRID 24     2.51572  5.5251 0.0
GRID 25     1.81173  0.0   0.0
GRID 26     2.02322  .7893  0.0
GRID 27     2.23471  1.5786 0.0
GRID 28     2.44621  2.3679 0.0
GRID 29     2.6577  3.1572 0.0
GRID 30     2.86919  3.9465 0.0
GRID 31     3.08068  4.7358 0.0
GRID 32     3.29217  5.5251 0.0
GRID 33     2.07055  0.0   0.0
GRID 34     2.28204  .7893  0.0
GRID 35     2.49353  1.5786 0.0
GRID 36     2.70502  2.3679 0.0
GRID 37     2.91652  3.1572 0.0
GRID 38     3.12801  3.9465 0.0
GRID 39     3.3395   4.7358 0.0
GRID 40     3.55099  5.5251 0.0
$
CQUAD4 1      1      1      2      10      9      +
+M00000  .001   .001   .041   .041
CQUAD4 2      1      2      3      11      10      +
+M00001  .001   .001   .041   .041
CQUAD4 3      1      3      4      12      11      +
+M00002  .001   .001   .041   .041
CQUAD4 4      1      4      5      13      12      +
+M00003  .001   .001   .041   .041

```



```

$ THE PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL THICKNESS ALLOWING
$ FOR THE INPUT OF HALF THICKNESS, CAMBER AND LEADING EDGE RADII AT
$ THE WING ROOT AND TIP. THICKNESS AND CAMBER DISTRIBUTIONS BETWEEN
$ THE WING ROOT AND TIP ARE INTERPOLATED. FOR THIS CASE, A 2% THICK
$ HEXAGONAL AIRFOIL SECTION IS DEFINED. A NEGATIVE VALUE OF ITAX
$ REQUESTS THAT A LINEAR INTERPOLATION BE USED FOR THICKNESS AND
$ CAMBER DISTRIBUTIONS (POSITIVE VALUE IS FOR CUBIC INTERPOLATION).
$ THICKNESS AND CAMBER DISTRIBUTIONS ARE USED ONLY FOR SUPERSONIC
$ THICKNESS EFFECTS (ZONA7U) WHEN THE 'METHOD' ENTRY IS ACTIVE IN
$ MKAEROZ BULK DATA CARD.
$ ID ITAX ITHR ICAMR RADR ITHT ICAMT RADT
PAFOIL7 100 -101 102 103 0.0 102 103 0.0
$ SID D1 D2 ETC
AEFACT 101 0.0 12.5 87.5 100.
AEFACT 102 0.0 1.0 1.0 0.0
AEFACT 103 0.0 0.0 0.0 0.0
$ * SURFACE SPLINE FIT ON THE WING *
$ EID MODEL CP SETK SETG DZ EPS
SPLINE1 100 WING 101 100 0.0
$ SETID MACROID BOX1 BOX2 ETC
PANLST2 101 101 101 THRU 180
$ SID G1 G2 ETC
SET1 100 2 4 6 8 9 11 13 +S1
+S1 15 18 20 22 24 25 27 29 +S2
+S2 31 34 36 38 40
$ * * FLUTTER ANALYSIS * *
$ THE FLUTTER BULK DATA CARDS EMPLOY THE PK AND K FLUTTER SOLUTION
$ METHODS. EACH FLUTTER CARD REFERS TO A DIFFERENT MKAEROZ BULK DATA
$ CARD. THE FIRST FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH AN IDMK
$ OF 1000 (WING WITHOUT THICKNESS CASE - ZONA7 AERODYNAMICS). THE
$ SECOND FLUTTER CASE REFERS TO AN MKAEROZ CARD WITH IDMK = 2000
$ (WING WITH THICKNESS CASE - ZONA7U AERODYNAMICS).
$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID
FLUTTER 30 PKK 1 1000 3 +FL1
$ SYMXZ SYMY EPS CURVFIT PRINT
+FL1 1
$ FLUTTER 40 PKK 1 2000 3 +FL2
+FL2 1
$ SID F1 F2 ETC
FLFACT 1 .391
FLFACT 3 20000. 22000. 24000. 28000. 32000. 34000.
ENDDATA

```

2.4 Case 4: Sample Wing-Body-Tiptank Flutter Analysis

- **Purpose:** Demonstrate a subsonic and supersonic wing-body-tiptank flutter analysis case using the P-K and K methods.
- **Description of Input:**

A wing-body-tiptank configuration is considered for the present case. The aerodynamic model of this configuration is shown in Fig 2.4.1.

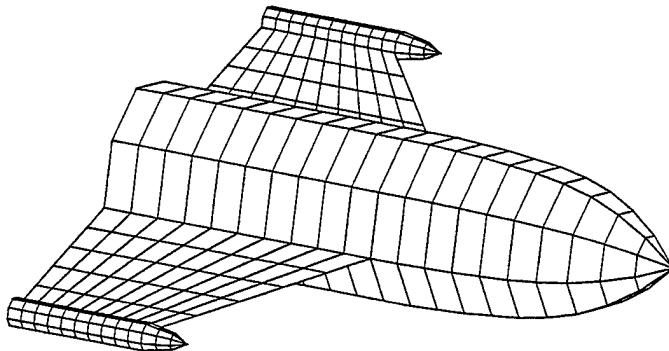


Figure 2.4.1 Aerodynamic Model of Sample Wing-Body-Tiptank Case.

- Solution Control

An analysis run is performed with the MODES and FLUTTER disciplines. The BOUNDARY condition specifies SPC = 10 that selects the single-point constraints for grid points, REDUCE = 30 that selects the analysis set degrees of freedom, and METHOD = 20 that selects the eigenvalue extraction method to be used. Two flutter cases are requested. The first FLCOND = 99 selects the subsonic ($M = 0.8$) flutter case and the second FLCOND = 100 selects the supersonic ($M = 1.2$) flutter case.

- Structural Model

A cropped delta wing with leading edge sweptback angle of 35.54° is used. The wing half-span and the root chord lengths are 70 inches and 100 inches, respectively. The wing is made of aluminum with a uniform thickness of 1.5 inches and is supported by an actuator at one third of the wing root. The aluminum wing is discretized into nine **CQUAD4** elements. The actuator is idealized by a **CBAR** element. Thus, the total number of grid points is seventeen. The **CBAR** is clamped at the grid point 20000, which is constrained for all six degrees of freedom. The cropped delta wing structural finite element (FEM) model is shown in Fig 2.4.2.

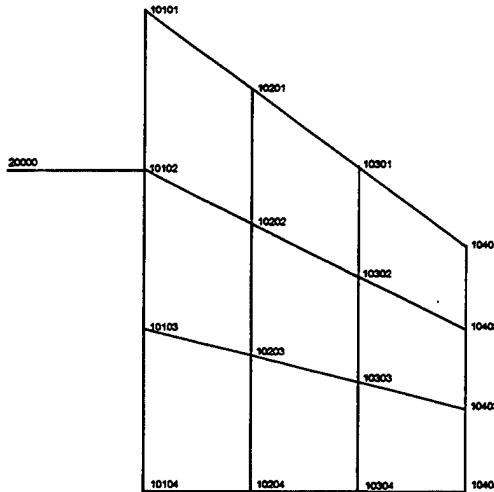


Figure 2.4.2 Cropped Delta Wing Structural Finite Element Model.

No structural FEM modeling is included for the body or tiptank in the present case. Spline of the tiptank to the wing is done via the **ATTACH** bulk data card, in which the rotational and displacement degrees of freedom are translated from a single grid point (i.e. grid no. 10402) to the entire tiptank. The fuselage, represented by a **BODY7** bulk data card, is not splined and, therefore, does not undergo any unsteady motion in this flutter analysis. However, body aerodynamics and wing-body aerodynamic interference (set via the ATTCHR/ATTCHT entries of the **CAERO7** bulk data card) are computed and accounted for in the analysis.

- Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.145E-07 slinches (sea level density) and reference length of 100.0 inches are used.

Two **MKAEROZ** bulk data cards with IDMK's of 10 and 20 are used to specify freestream Mach numbers of 0.8 and 1.2, respectively. Eleven reduced frequencies are input ranging from 0.0001 to 0.55.

- Aerodynamic Model

One **CAERO7** wing macroelement is defined with 11 chordwise and 6 spanwise evenly cut aerodynamic boxes. Root and tip chord lengths are 100 and 50 inches, respectively, with a 100 inch semispan length. The wing root is attached to the fuselage body with the ATTCHR entry set to the fuselage **BODY7** bulk data card id (BID) of 201 to ensure proper treatment of the wing-body aerodynamic interference effects. Likewise, the wing tip is attached to the tiptank with the ATTCHT entry set to the tiptank **BODY7** bulk data card id (BID) of 401. Using the attachment option will avoid the wing root and tip from being treated as "free lifting surface edges" which will lead to incorrect unsteady pressure results in these regions.

The fuselage is defined by a **BODY7** macroelement with 5 circumferential and 21 axial cuts. The **BODY7** coordinates are specified within a local coordinate system defined by an **ACOORD** bulk data card with an ID of 20 located at (-100.0, 0.0, 0.0) that references the basic system (0.0, 0.0,

0.0). Fuselage cross-sections are specified through the body-of-revolution type of input (ITYPEi = 1 of the **SEGMESH** bulk data card) with camber and cross-sectional radius given at each of the 21 axial stations.

The tiptank is defined by a **BODY7** macroelement with 9 circumferential and 14 axial cuts. The **BODY7** coordinates are specified within a local coordinate system defined by an **ACOORD** bulk data card with an ID of 30 located at (35.0, 105.0, 0.0) that references the basic system (0.0, 0.0, 0.0). Fuselage cross-sections are specified through the body-of-revolution type of input (ITYPEi = 1 of the **SEGMESH** bulk data card) with camber and cross-sectional radius given at each of the 14 axial stations.

Note that the selection of wing and body macroelement id's (WID and BID) is not completely arbitrary. These integers must be selected so that no duplicate grid and/or aerodynamic box id's occur. For example, if a wing macroelement is set up with an id of 11 that has 10 x 10 aero box cuts and another wing macroelement is used with an id of 51, then duplicate grid and aero box id's will occur. This is because ZAERO establishes internal aero grid and box id's with starting values based on the macroelement id. Therefore, an aero box and grid with an id of 51 will already exist from the first macroelement (see the ASTROS* User's Manual for detailed description). In the present case, the first body macroelement (BID = 201) has 5 radial and 21 axial cuts. This will generate internally 105 (i.e. 21 x 5) aerodynamic grid points and 80 (i.e. (21-1) x (5-1)) aerodynamic boxes. Therefore, the next available macroelement id would be 307 (i.e. 201 + 105 + 1).

- Spline

A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the SETK = 102 entry and a **SET1** bulk data card by the SETG = 103 entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with WID of 101), and splines all of the wing aerodynamic boxes (101 through 150) to the structural grid points listed in the **SET1** bulk data card.

An **ATTACH** bulk data card is used to transfer the displacement and rotational motion of a reference **GRID** point (REFGRID = 10402) located at the wing tip to the tiptank. A **PANLST2** bulk data card is referenced by the SETK = 402 entry splines all of the tiptank aerodynamic boxes (401 through 540) to the reference grid point.

- Flutter

Two **FLUTTER** bulk data cards are used to perform two separate flutter analyses. The first **FLUTTER** bulk data card (SETID=99) refers to an **MKAEROZ** bulk data card (IDMK=10) with a Mach number of 0.8. The second **FLUTTER** bulk data card (SETID=100) refers to an **MKAEROZ** bulk data card (IDMK=20) with a Mach number of 1.2. The referenced **FLFACT** bulk data cards in entries DENS and VEL specify the density ratios and velocities for the P-K method, respectively. Both **FLUTTER** bulk data cards request that the P-K and K methods be used (METHOD entry set to PKK).

- **Description of Output:**

The structural natural frequencies and generalized mass for the first five modes generated by the ASTROS* modal analysis is shown in Table 2.4.1.

Table 2.4.1 Natural Frequencies and Generalized Mass of the Wing-Body-Tiptank Case.

Mode No.	ASTROS*	
	Natural Frequency (Hz)	Generalized Mass
1	4.461	4.36703E-01
2	10.556	3.02312E-01
3	29.392	2.70375E-01
4	32.566	9.04735E-02
5	50.038	4.82148E-01

- **Subsonic Flutter Results ($M=0.8$)**

K-method flutter results of damping and frequency versus velocity for the first two modes are shown in Fig 2.4.3. The flutter crossing occur at $V_f = 956$ ft/s and $\omega_f = 7.92$ Hz.

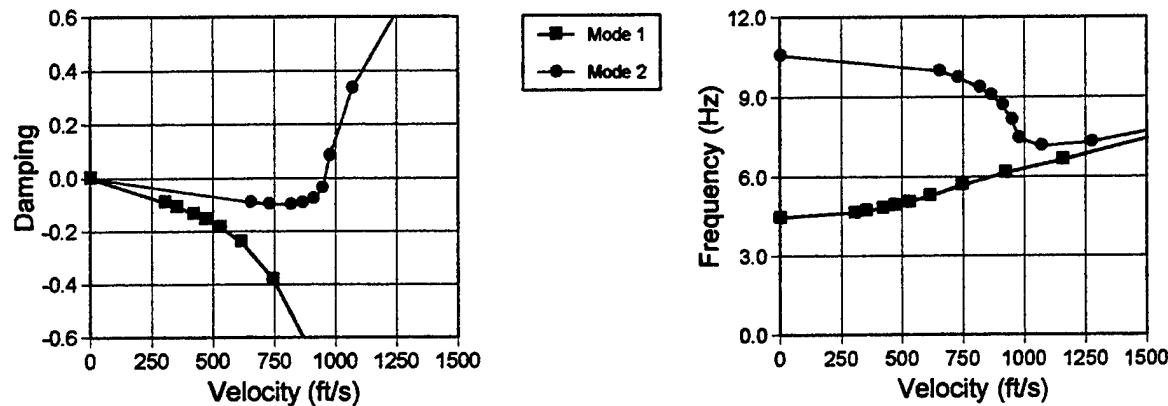


Figure 2.4.3 K-Method Flutter Curves of Wing-Body-Tiptank Case ($M=0.8$, Sea Level Density).

P-K method flutter results for this same case are shown in Fig 2.4.4. Flutter crossings occur at $V_f = 959$ ft/s and $\omega_f = 7.83$ Hz.

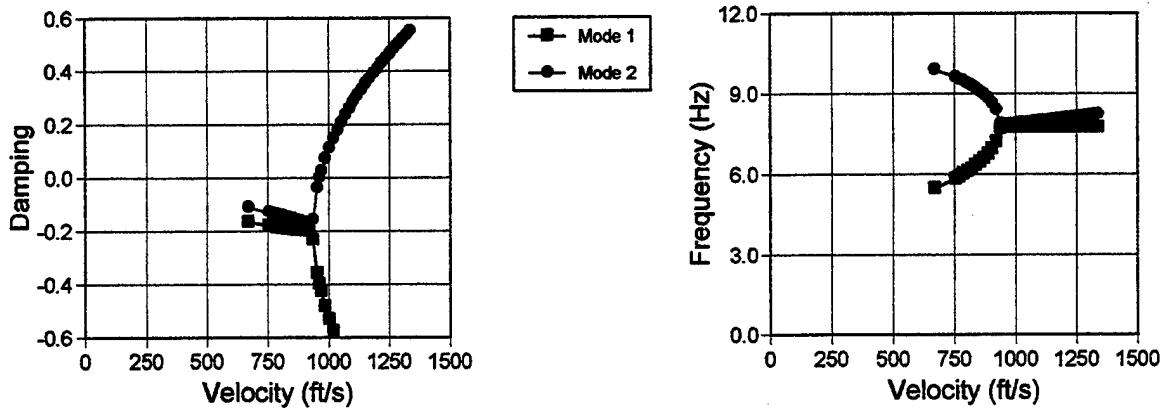


Figure 2.4.4 P-K Method Flutter Curves of Wing-Body-Tiptank Case (M=0.8, Sea Level Density).

- *Spersonic Flutter Results (M=1.2)*

K-method flutter results of damping and frequency versus velocity for the first two modes are shown in Fig 2.4.5. The flutter crossing occur at $V_f = 1014$ ft/s and $\omega_f = 8.35$ Hz.

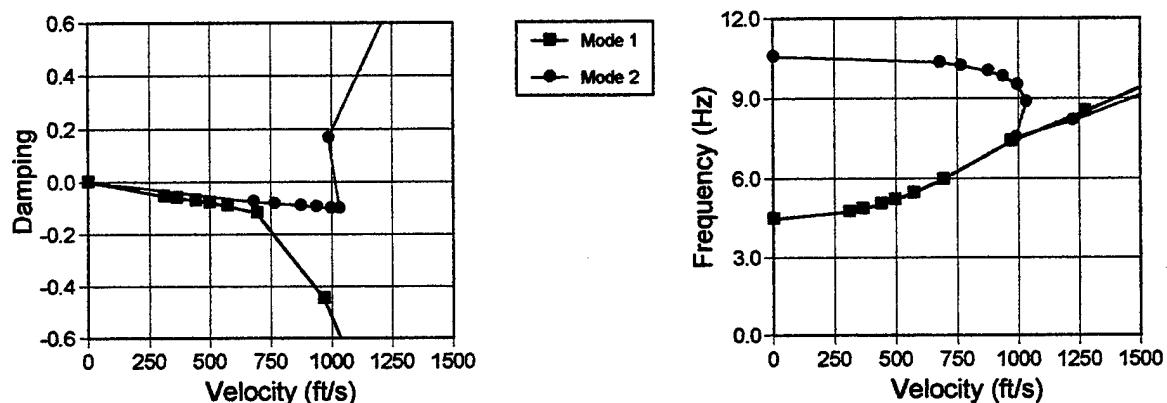


Figure 2.4.5 K-Method Flutter Curves of Wing-Body-Tiptank Case (M=1.2, Sea Level Density).

P-K method flutter results for this same case are shown in Fig 2.4.6. Flutter crossings occur at $V_f = 966$ ft/s and $\omega_f = 7.63$ Hz.

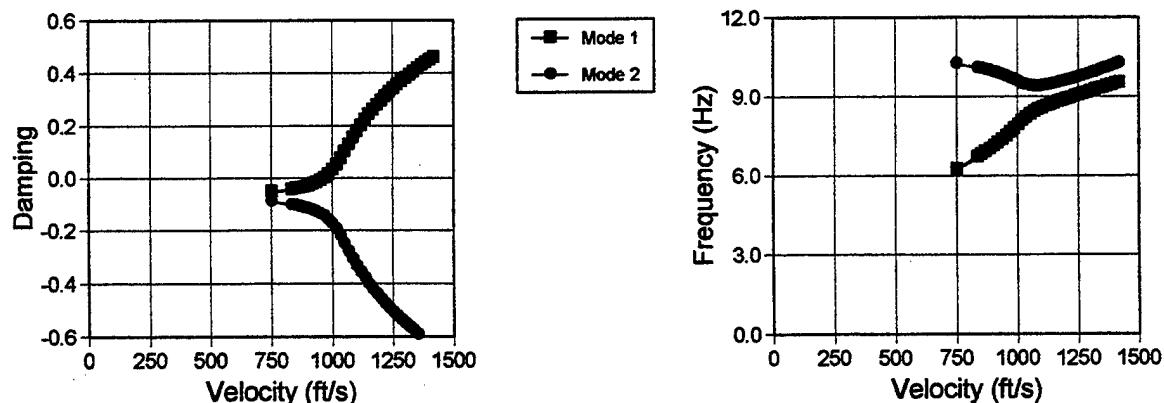


Figure 2.4.6 P-K Method Flutter Curves of Wing-Body-Tiptank Case (M=1.2, Sea Level Density).

Good agreement between the P-K and K-flutter methods are obtained for both Mach numbers. The larger discrepancy between the two methods for the supersonic case is due to the abrupt flutter point crossing in the K-method results (see Fig 2.4.5). Improved correlation can be obtained by increasing the number of reduced frequencies listed in the MKAEROZ bulk data card with $IDMK=20$ at the flutter point crossing (i.e. between $k=0.2$ and 0.225).

- *Input Data Listing:*

Listing 2.4 Input Data for the Wing-Body-Tiptank Case.

* AERO PARAMETERS / FLIGHT CONDITIONS *

ACSID XZSYM RHOREF REFC REFBS REFS GREF

AEROZ YES 1.145-07100.

TWO MKAEROZ CARDS ARE USED. THE FIRST ACTIVATES THE SUBSONIC METHOD (ZONA6) AND THE SECOND THE SUPERSONIC METHOD (ZONA7) - BASED ON THE INPUT MACH NUMBER.

IDMK MACH METHOD IDFLT SAVE <--FILENAME--> PRINT

MKAEROZ 10 0.8 0 ACQUIRE CROPAIC +MK1

FREQ1 FREQ2 ETC +MK1

+MK1 0.001 0.1 0.15 0.175 0.2 0.225 0.25 0.275 +MK1

+MK1 0.3 0.35 0.4

MKAEROZ 20 1.2 0 ACQUIRE CROPAIC +MK1

+MK1 0.001 0.1 0.15 0.175 0.2 0.225 0.25 0.275 +MK1

+MK1 0.3 0.35 0.4

* WING MACROELEMENT *

WID LABEL ACOORD NSPAN NCHORD LSPAN ZTAIC PAFOIL7

CAERO7 101 WING 6 11 +CA1

XRL YRL ZRL RCH LRCHD ATTCHR +CA2

+CA1 0.0 30.0 0.0 100.0 0 201

XRT YRT ZRT TCH LTCHD ATTCHT +CA2

+CA2 50.0 100.0 0.0 50.0 0 401

* BODY MACROELEMENT * (FUSELAGE)

TWO BODY7 BULK DATA CARDS ARE USED TO DEFINE THE FUSELAGE AND TIPTANK MACROELEMENTS. EACH BODY7 COORDINATES ARE BASED ON A LOCAL COORDINATE SYSTEM SPECIFIED BY THE ACCORD BULK DATA ENTRIES. THE BODY-OF-REVOLUTION TYPE OF INPUT IS USED FOR BOTH THE FUSELAGE AND TIPTANK TO SPECIFY THE CROSS-SECTIONAL RADIUS AND CAMBER (SEGMENT BULK DATA CARD).

COORDINATE SYSTEM FOR FUSELAGE

ID XORIGN YORIGN ZORIGN DELTA THETA

ACCORD 20 -100. 0.0 0.0 0.0 0.0

BID LABEL IPBODY7 ACOORD NSEG IDMESH1 IDMESH2 ETC

BODY7 201 FUSELAGE 20 1 201

IDMESH NAXIS NRAD

SEGMESS 201 21 5 +SE1

ITYPE X1 CAM1 YR1 ZR1 IDY1 IDZ1 +SE2

+SE1 1 0.0 0.0 0.0 +SE3

+SE2 1 10.0 0.0 10.0 +SE4

+SE3 1 20.0 0.0 17.0 +SE5

+SE4 1 30.0 0.0 22.0 +SE6

+SE5 1 40.0 0.0 25.0 +SE7

+SE6 1 50.0 0.0 27.0 +SE8

+SE7 1 60.0 0.0 28.0 +SE9

+SE8 1 70.0 0.0 29.0 +SE10

+SE9 1 80.0 0.0 29.5 +SE11

+SE10 1 90.0 0.0 30.0 +SE12

+SE11 1 100.0 0.0 30.0 +SE13

+SE12 1 110.0 0.0 30.0 +SE14

+SE13 1 120.0 0.0 30.0 +SE15

+SE14 1 130.0 0.0 30.0 +SE16

+SE15 1 140.0 0.0 30.0 +SE17

+SE16 1 150.0 0.0 30.0 +SE18

+SE17 1 160.0 0.0 30.0 +SE19

+SE18 1 170.0 0.0 30.0 +SE20

+SE19 1 180.0 0.0 30.0 +SE21

+SE20 1 190.0 0.0 30.0 +SE21 1 200.0 0.0 30.0

* BODY MACROELEMENT * (TIPTANK)

COORDINATE SYSTEM FOR TIPTANK

ID XORIGN YORIGN ZORIGN DELTA THETA

ACCORD 30 35.0 105.0 0.0 0.0 0.0

BID LABEL IPBODY7 ACOORD NSEG IDMESH1 IDMESH2 ETC

BODY7 401 TIPTANK 30 1 401

IDMESH NAXIS NRAD

SEGMESS 401 14 9 +SE1

ITYPE X1 CAM1 YR1 ZR1 IDY1 IDZ1 +SE2

+SE1 1 0.0 0.0 0.0 +SE3

+SE2 1 5.0 0.0 3.0 +SE4

+SE3 1 10.0 0.0 4.0 +SE5

+SE4 1 15.0 0.0 5.0 +SE6

+SE5 1 20.0 0.0 5.0

```

+SE6 1 25.0 0.0 5.0
+SE7 1 30.0 0.0 5.0
+SE8 1 35.0 0.0 5.0
+SE9 1 40.0 0.0 5.0
+SE10 1 45.0 0.0 5.0
+SE11 1 50.0 0.0 5.0
+SE12 1 55.0 0.0 5.0
+SE13 1 60.0 0.0 5.0
+SE14 1 65.0 0.0 5.0
$
$
$
$ * SURFACE SPLINE FIT ON THE WING *
$
$
$ EID MODEL CP SETK SETG DZ EPS
$ SPLINE1 101 WING 102 103 0.0 0.01
$
$ SETID MACROID BOX1 BOX2 ETC
$ PANLST2 102 101 101 THRU 150
$
$ SID G1 G2 ETC
$ SET1 103 10101 10102 10103 10104 10201 10202 10203 +SE1
+SE1 10204 10301 10302 10303 10304 10401 10402 10403 +SE2
+SE2 10404
$
$
$ * TIPTANK TO WING ATTACHMENT *
$
$
$ THE ATTACH BULK DATA CARD TRANSFERS THE DISPLACEMENT AND ROTATIONAL
$ MOTION OF A REFERENCE GRID POINT TO AN AERODYNAMIC BOX (ES). IN THIS
$ CASE, ALL OF THE TIPTANK AERO BOXES (401 THRU 504) WILL FOLLOW THE
$ MOTIONS OF THE REFERENCE GRID POINT (GRID 10402) LOCATED AT THE WING
$ TIP.
$
$ EID MODEL SETK REFGRID
$ ATTACH 401 402 10402
$
$ SETID MACROID BOX1 BOX2 ETC
$ PANLST2 402 401 401 THRU 504
$
$ * FLUTTER ANALYSIS *
$
$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID
$ FLUTTER 99 PKK 101 10 102 +FL1
$ SYMXZ SYMXY EPS CURVFIT PRINT
+FL1 1
$
$ SID F1 F2 ETC
$ FLFACT 101 1.0
$ FLFACT 102 8000. 9000. 10000. 11000. 12000. 13000. 14000. +FL1
+FL1 15000. 16000.
$
$ FLUTTER 100 PKK 101 20 103 +FL1
+FL1 1
$
$ FLFACT 103 9000. 10000. 11000. 12000. 13000. 14000. 15000. +FL1
+FL1 16000. 17000.
$
$ ENDDATA

```

2.5 Case 5: AGARD Standard 445.6 Wing – Transonic Flutter Analysis

- **Purpose:** Demonstrate a transonic wing flutter analysis case using the ZTAIC method with steady pressure input provided by CFD.

- **Description of Input:**

The AGARD Standard 445.6 Weakened (modified AGARD Test Case from the ASTROS Application Manual (AFWAL-TR-88-3028), also AGARD Report No. 765, and NASA TN D-1616) is considered in the present case for both subsonic and transonic Mach numbers ($M=0.678, 0.90, 0.95$). The wing is a 45 degree swept-back wing of aspect ratio 6 with a NASA 64A004 airfoil section. The ZONA6 (linear) and ZTAIC (nonlinear) method flutter results are compared with wind tunnel measurement data. The ZTAIC method (ZAERO's transonic method) wing sectional steady pressure input used in the present analysis are obtained by two Computational Fluid Dynamics (CFD) codes: the CAPTSD (2D Euler) and ENSAERO (3D Navier-Stokes) codes. Similar to the AGARD Test Case presented in the ASTROS Applications Manual, the structural finite element model of this wing is replaced by the input of mode shapes, generalized mass and stiffness matrices of the first five modes via the Direct Matrix Input (DMI) bulk data. The aerodynamic model of the AGARD Standard 445.6 Wing is shown in Fig 2.5.1.

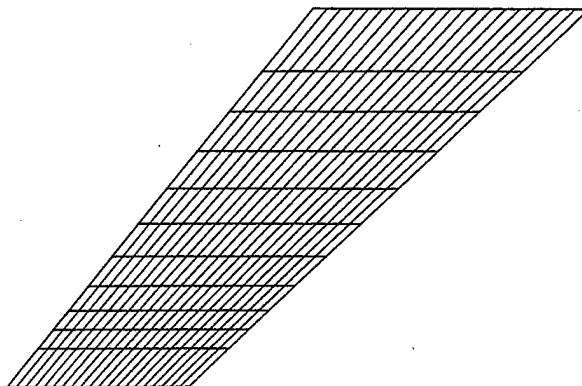


Figure 2.5.1 Aerodynamic Model of the AGARD Standard 445.6 Wing.

The natural frequencies and mode shapes of the weakened wing structure are presented in Fig 2.5.2. The dashed line wings represent the undeformed wing structure.

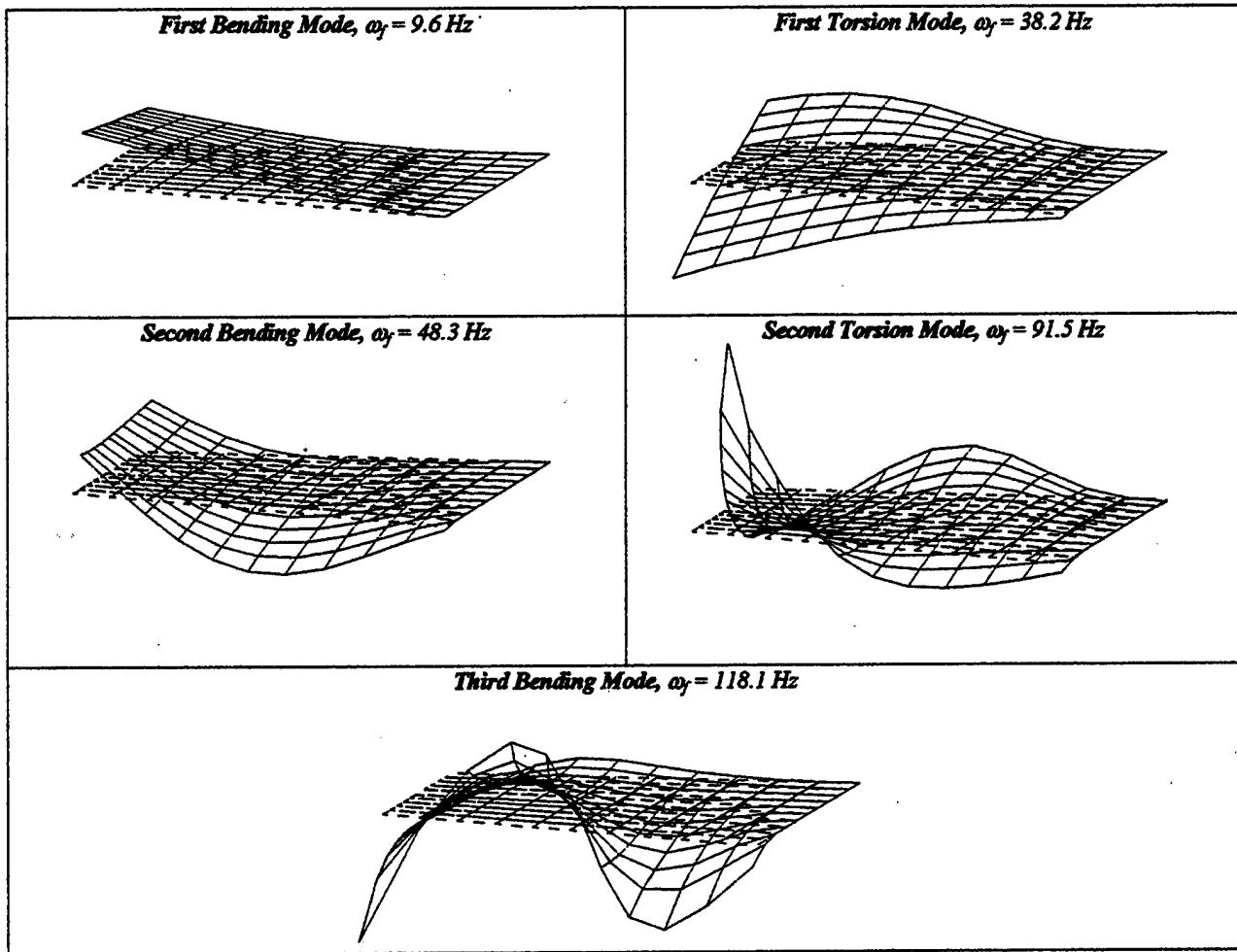


Figure 2.5.2 AGARD Standard 445.6 Weakened Wing Natural Frequencies and Mode Shapes (1st 5 modes).

For the present test case, wing sectional steady pressure input data is provided for all three Mach numbers. Steady pressure can be obtained by physical flight test data, wind tunnel data or by computational means (such as CFD). Accuracy of the ZTAIC method flutter results depends on the accuracy of the steady pressure input (i.e. ideal steady pressure input would come from flight test or wind tunnel measurement).

Differences in steady pressure input obtained by different sources (in this case 2 CFD codes) is shown in the following figure. The ZTAIC steady pressure input for Mach 0.95 and Angle-of-Attack (α) = 0° , used in the present case, as computed by the CAPTSD (Euler) and ENSAERO (Navier-Stokes) codes at 6 spanwise stations is shown in Fig 2.5.3.

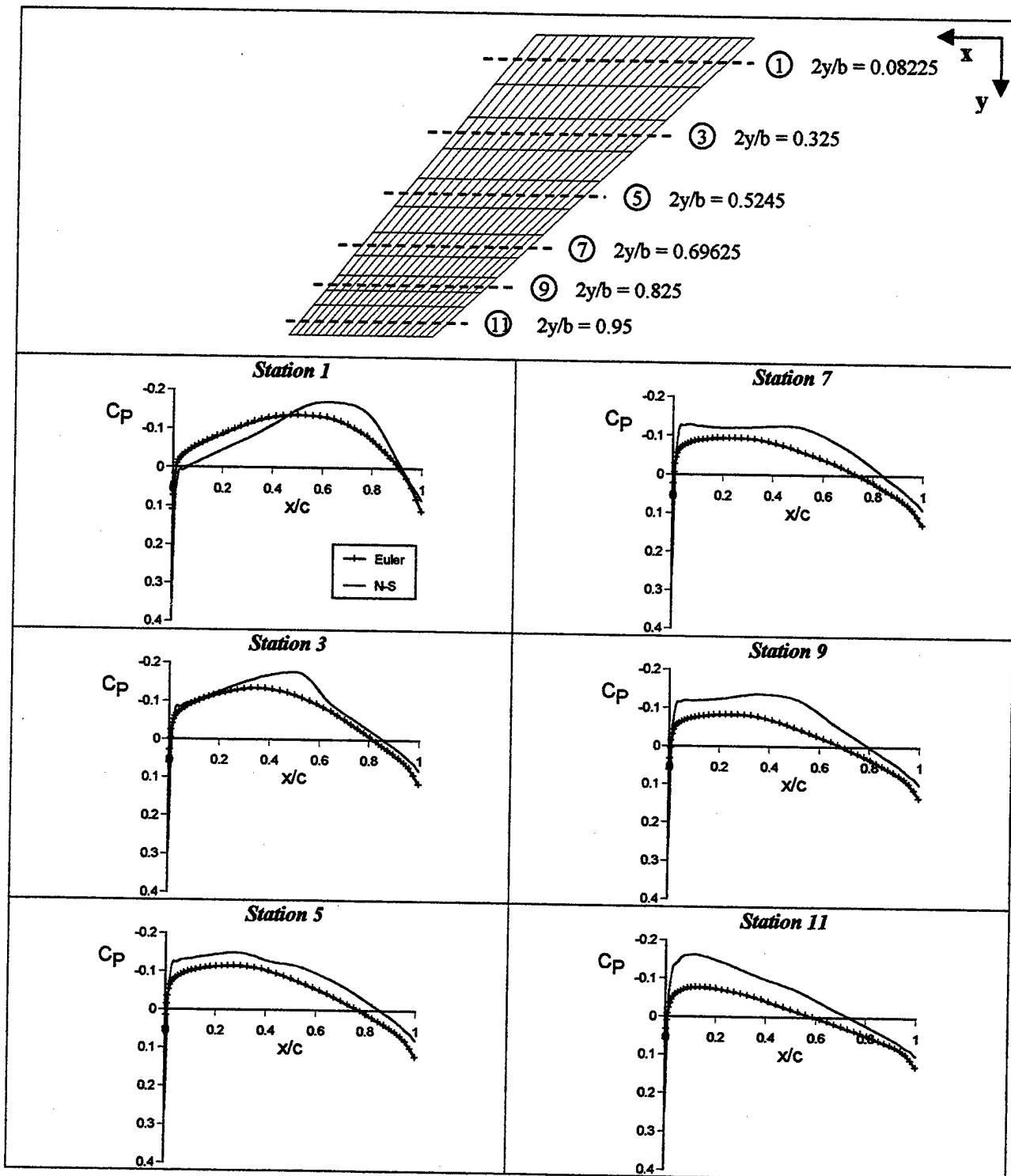


Figure 2.5.3 AGARD Standard 445.6 Weakened Wing CAPTSD (Euler) and ENSAERO (Navier-Stokes = N-S) Steady Pressure Results ($M=0.95, \alpha=0.0^\circ$).

Differences in terms of shock strength and location is seen between the Euler and Navier-Stokes results. The effect of these differences on the ZTAIC method flutter results is shown in the Description of Output section of the present case.

- Solution Control

Substantial modification to the ASTROS* standard Matrix Analysis Problem Oriented Language (MAPOL) sequence is implemented through the EDIT command. The optimization and global matrix assembly phases are deleted from the sequence. A modified flutter analysis routine is inserted omitting the dynamic matrix assembly to replace the standard flutter sequence.

An analysis is performed with six flutter subcases. The first case performs a ZTAIC (nonlinear) flutter analysis and the second a ZONA6 (linear) flutter analysis. This is repeated three times for each Mach number (M = 0.678, 0.90, 0.95).

- Structural Model

Structural model processing is replaced in this case by the mode shape, stiffness matrix and mass matrix input via the Direct Matrix Input (**DMI**) bulk data. Therefore, the ASTROS* structural input consists only of 121 grid points, all constrained in 5 degrees-of-freedom (DOF) with the 6th DOF (i.e. the z-translation) left free. This corresponds to 121 DOF for each mode. Five modes with corresponding natural frequencies are input by **DMI**'s. The mass matrix is a 5 x 5 identity matrix while the stiffness matrix is a diagonal matrix whose nonzero entries are the input eigenvalues.

- Aerodynamic Parameters / Flight Conditions

The **AEROZ** bulk data card specifies a symmetric model about the x-z plane. A reference density of 1.145E-07 slinches (sea level density) and reference length of 21.96 inches are used.

Six **MKAEROZ** bulk data cards are used to specify freestream Mach numbers of 0.678, 0.90 and 0.95 for both the linear (ZONA6) or nonlinear (ZTAIC) aerodynamic methods. Identical reduced frequencies ranging from 0.0001 to 0.5 are computed for all **MKAEROZ**.

The Aerodynamic Influence Coefficient (AIC) matrices associated with each **MKAEROZ** bulk data card are saved in filenames specified in the FILENAME entries. Mnemonic notation used for filenames consist of: Wing Name + Mach Number + Method Used. For example, 'AGARD678ZT' would be the AGARD wing at Mach 0.678 with the ZTAIC method used (i.e. METHOD entry set to 1 = nonlinear method).

- Aerodynamic Model

One wing macroelement is used to define the wing planform. 20 chordwise (evenly cut) and 11 spanwise (cuts specified in **AEFACT** bulk data card with SID=10) aerodynamic boxes are used. For the ZTAIC method to be "active" for this wing macroelement, the ZTAIC entry is set to 1001, which refers to a **ZTAIC** bulk data card that establishes the steady pressure input to be used on this wing.

- Spline

The infinite plate spline method (**SPLINE1**) is used to spline all of the wing aerodynamic boxes to the structural grid points. A **SPLINE1** bulk data card is used to spline the aerodynamic wing model to the structure. A **PANLST2** bulk data card is referenced by the **SETK = 10** entry and a **SET1** bulk data card by the **SETG =603** entry. The **PANLST2** defines the wing macroelement to be splined (**CAERO7** with **WID** of 1001), and splines all of the wing aerodynamic boxes (1001 through 1220) to the structural grid points listed in the **SET1** bulk data card (grids 1 through 121).

- Flutter

Six **FLUTTER** bulk data cards are input corresponding to each **FLUTTER** subcase specified in the solution control. The P-K and K methods of flutter solution are requested for all cases (**METHOD** entry set to **PKK**). Density ratios specified in the **DENS** entries refer to **FLFACT** bulk data cards which list density ratios that encompass the flutter matched point altitudes. **IDMK** entries refer to **MKAEROZ** bulk data cards that specify the Mach number/reduced frequencies for the flutter analysis. The same velocities for the P-K method are used for all flutter analyses (velocities listed in **FLFACT** bulk data card with **SID=40**).

- ZTAIC Method Steady Pressure Input

Transonic data for the ZTAIC method is input via the **ZTAIC**, **MACHCP** and **CHORDCP** bulk data entries. Only one set of steady pressure input can be used per ASTROS* run (i.e. either from wind tunnel measurement, Euler Code, N-S Code, etc.). Therefore, the **CHORDCP** bulk data used to input the steady pressure for all three Mach numbers of this case are saved in two separate files ('**tsdcp.inp**' for CAPTSD/Euler and '**nscp.inp**' for ENSAERO/Navier-Stokes steady pressure) and are included in the bulk data input via the ASTROS **INCLUDE** statement (see ASTROS User's Manual for details on the **INCLUDE** statement). The user can select the desired pressure input by uncommenting the corresponding **INCLUDE** statement (by removing the \$).

The ZTAIC bulk data card refers to 3 **MACHCP** bulk data cards that establish the Mach number and steady pressure input relations. Span locations and corresponding steady pressure for each section are specified by the **SPANID** and **CHDCP** entries, respectively.

For example, the **MACHCP** with ID of 1001 specifies a Mach number of 0.678. This Mach number must identically exist in the the **MKAEROZ** bulk data cards with the nonlinear method "active" (i.e. **METHOD** entry set to 1). The spanwise station indicies (**SPANID** entries) correspond to the wing macroelement span division centerline locations. In this case an **AEFACT** bulk data card with **ID=10** was used to specify the spanwise wing macroelement cuts. Therefore, the **SPANID=1** refers to the wing span location of 8.22% ($[0.0+16.45]/2$), **SPANID=2** refers to the wing span location of 21.85% ($[16.45+27.25]/2$), and so on.

CHORDCP entries in the '**tsdcp.inp**' and '**nscp.inp**' files contain the x-location of the pressure in percent chord length (X entries), the upper surface steady pressure coefficients (CPU entries), and the lower surface steady pressure coefficients (CPL entries).

- **Description of Output:**

A matched point flutter analysis is performed to compare with wind tunnel data provided in the following reference, Yates, E.C., Jr., Land, M.S. and Foughner, J.T., Jr., "Measured and Calculated Subsonic and Transonic Flutter Characteristics of a 45° Sweptback Wing Planform in Air and Freon-12 in the Langley Transonic Dynamics Tunnel," NASA TN D-1616, March 1963.

The weakened wing model (model 3) is considered for this case with a span of 2.5 feet. The measured modal frequencies and panel mass for this wing are given in Table 2.5.1

Table 2.5.1 Measured Modal Frequencies and Panel Mass of the AGARD Standard 445.6 Weakened Wing Model.

Model Description				Frequency (Hz)					Panel mass, slugs
Panel span, ft	Mounting	Structure	Model	$f_{h,1}$	$f_{h,2}$	$f_{t,1}$	$f_{t,2}$	f_{α}	m
2.50	Wall	Weakened	3	9.60	50.70	38.10	98.50	38.09	0.12764

Table 2.5.2 presents the computed matched point density and mass ratios for the present case. The flutter matched point is found by varying the ASTROS* density ratios (specified in the FLFAC bulk data cards SID's=301-306) so that the computed speed of sound (i.e. computed flutter velocity divided by the input Mach number) matches that of the wind tunnel test results.

Table 2.5.2 Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.

Mach	ZONA6		ZTAIC(TSD)		ZTAIC (N-S)		Experiment	
	ρ/ρ_{SL}	μ	ρ/ρ_{SL}	μ	ρ/ρ_{SL}	μ	ρ/ρ_{SL}	μ
0.678	0.184	61.52	0.190	63.53	0.186	62.85	0.170	68.75
0.90	0.084	146.12	0.080	139.16	0.074	157.96	0.081	143.92
0.95	0.066	198.13	0.059	177.12	0.052	224.80	0.052	225.82

ρ/ρ_{SL} =density ratio, ρ_{SL} =sea level density, μ =mass ratio, Experimental data from NASA TN D-1616 (March 1963)

The mass ratio $\mu = m / (\rho V)$ is defined as the mass of the wing divided by the mass of air contained within the volume of a conical frustum having the streamwise root chord as the lower base diameter, streamwise tip chord as the upper base diameter, and wing panel span as the height.

Table 2.5.3 presents the flutter frequency ratios and flutter speed coefficients for the present case.

Table 2.5.3 Computed Density and Mass Ratios of the AGARD Standard 445.6 Wing.

Mach	ZONA6		ZTAIC(TSD)		ZTAIC (N-S)		Experiment	
	$\frac{\omega}{\omega_\alpha}$	$\frac{U}{b_s \omega_\alpha \sqrt{\mu}}$						
0.678	0.5280	0.4343	0.5340	0.4399	0.5314	0.4363	0.4712	0.4174
0.90	0.4297	0.3754	0.4240	0.3666	0.4136	0.3522	0.4216	0.3700
0.95	0.3945	0.3460	0.3840	0.3276	0.3697	0.3068	0.3673	0.3059

Experimental data from NASA TN D-1616 (March 1963)

where ω is the flutter frequency, ω_α is the natural circular frequency of the wing in first uncoupled torsion mode ($2\pi f_\alpha$), U is the flutter velocity and b_s is the streamwise semichord measured at the wing root ($b_s=0.9165$ feet).

Figure 2.5.4 presents the flutter flutter speed coefficients and frequency ratios of Table 2.5.3. At the subsonic Mach number of 0.678, the ZTAIC results are in close agreement with those of ZONA6, as expected, since transonic effects (such as shock wave) are minimum or nonexistent. At transonic Mach numbers, the ZTAIC results predicts a pronounced transonic dip that is not observed in the linear (ZONA6) results. Better correlation of flutter speed coefficient with experimental results is seen at Mach 0.95 for the ZTAIC case with Navier-Stokes (N-S) pressure input. This is expected since the N-S results account for fluid viscosity, thereby giving better predictions of shock position and strength.

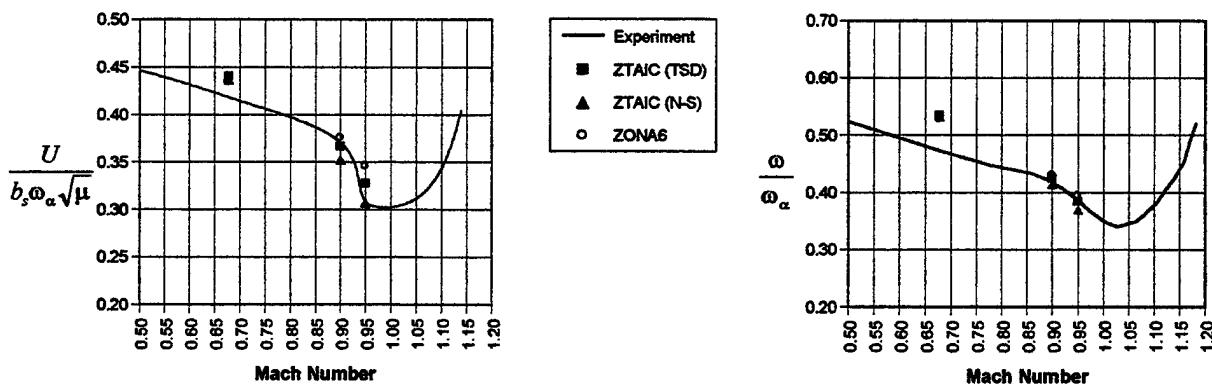


Figure 2.5.4 Plots of Flutter Speed Coefficients and Frequency Ratios of the AGARD Standard 445.6 Weakened Wing (matched point analysis).

• **Input Data Listing:**

Listing 2.5 Input Data for the AGARD Standard 445.6 Wing (Weakened Model).

```

ASSIGN DATABASE AGARD PASS NEW DELETE
EDIT NOLIST
INSERT 3
$ ***
*** EDIT:          (MAPOLSEQ VERSION 11.1)
*** TESTCASE DEMONSTRATING FLUTTER ANALYSIS WITH
*** DIRECT-INPUT OF MODE SHAPES AND FREQUENCIES.

```

```

*** $  

MATRIX [MODES], [KFLUT];  

REPLACE 371,1958  

$ ***  

*** EDIT:  

*** DELETE OPTIMIZATION PHASE.  

*** $  

REPLACE 1974,1975  

$ ***  

*** EDIT:  

*** DELETE GLOBAL MATRIX ASSEMBLY (EMA2).  

*** $  

REPLACE 2018,2746  

$ ***  

*** EDIT:  

*** REPLACE MATRIX REDUCTIONS, ANALYSIS SEGMENT AND DATA RECOVERY  

*** WITH SPECIAL FLUTTER ANALYSIS  

*** OMITTING DYNAMIC MATRIX ASSEMBLY (FLUTDMA).  

*** $  

CALL NREDUCE ( , [UGTKG], [PNSF(BC)], , , , [UGTKA] );  

PRINT("LOG=( ' >>>DISCIPLINE: NORMAL MODES' )");  

CALL REIG ( , BC, USET(BC), [KAA], [MAA], , , LAMBDA,  

          [PHIA], [MII], HSIZE(BC) );  

PRINT("LOG=( ' >>>DISCIPLINE: FLUTTER' )");  

CALL FLUTQHHz ( , BC, SUB, ESIZE(BC), PSIZE(BC), [AJK],  

                [SKU], [UGTKA], [MODES], USET(BC),  

                [TMN(BC)], [GSUBO(BC)], NGDR, AECOMPU, GEOMUA,  

                [PHIKH], [QHHFL(BC,SUB)], OAGRDDSP );  

PRINT("LOG=( ' >>>DISCIPLINE: FLUTTRAZ ' )");  

PRINT("LOG=( ' >>>DISCIPLINE: FLUTTRAZ ' )");  

CALL FLUTTRAZ ( , BC, SUB, [QHHFL(BC,SUB)], LAMBDA, HSIZE(BC),  

                ESIZE(BC), [MAA], [BHHFL(BC,SUB)],  

                [KFLUT], CLAMBDA, AEROZ );  

SOLUTION  

TITLE = AGARD STANDARD 445.6 WING TEST CASE USING THE ZTAIC (TRANSONIC) METHOD  

SUBTITLE = WEAKENED WING (MODEL 3) - AGARD RPT. NO. 765  

ANALYZE  

  PRINT (MODE = ALL) ROOT = ALL  

  BOUNDARY METHOD = 10  

  MODES  

    LABEL = WEAKENED MODES  

    FLUTTER (FLCOND = 1)  

    LABEL = ZTAIC (M=0.678) FLUTTER RESULTS  

    FLUTTER (FLCOND = 2)  

    LABEL = ZONA6 (M=0.678) FLUTTER RESULTS  

    FLUTTER (FLCOND = 3)  

    LABEL = ZTAIC (M=0.9) FLUTTER RESULTS  

    FLUTTER (FLCOND = 4)  

    LABEL = ZONA6 (M=0.9) FLUTTER RESULTS  

    FLUTTER (FLCOND = 5)  

    LABEL = ZTAIC (M=0.95) FLUTTER RESULTS  

    FLUTTER (FLCOND = 6)  

    LABEL = ZONA6 (M=0.95) FLUTTER RESULTS  

END  

BEGIN BULK  

$...1...2...3...4...5...6...7...8...9...10...$  

$  

GRID 1 0.0 0.0 0.0 12456  

GRID 2 2.196 0.0 0.0 12456  

GRID 3 4.392 0.0 0.0 12456  

GRID 4 6.588 0.0 0.0 12456  

GRID 5 8.784 0.0 0.0 12456  

GRID 6 10.75 0.0 0.0 12456  

GRID 7 13.17 0.0 0.0 12456  

GRID 8 15.37 0.0 0.0 12456  

GRID 9 17.56 0.0 0.0 12456  

GRID 10 19.76 0.0 0.0 12456  

GRID 11 21.96 0.0 0.0 12456  

$  

GRID 12 3.1866 3.0 0.0 12456  

GRID 13 5.3079 3.0 0.0 12456  

GRID 14 7.4293 3.0 0.0 12456  

GRID 15 9.5506 3.0 0.0 12456  

GRID 16 11.672 3.0 0.0 12456  

GRID 17 13.650 3.0 0.0 12456  

GRID 18 15.914 3.0 0.0 12456  

GRID 19 18.036 3.0 0.0 12456  

GRID 20 20.157 3.0 0.0 12456  

GRID 21 22.278 3.0 0.0 12456  

GRID 22 24.400 3.0 0.0 12456  

$  

GRID 23 6.3732 6.0 0.0 12456  

GRID 24 8.4199 6.0 0.0 12456  

GRID 25 10.466 6.0 0.0 12456  

GRID 26 12.513 6.0 0.0 12456  

GRID 27 14.560 6.0 0.0 12456  

GRID 28 16.600 6.0 0.0 12456  

GRID 29 18.653 6.0 0.0 12456  

GRID 30 20.700 6.0 0.0 12456  

GRID 31 22.744 6.0 0.0 12456  

GRID 32 24.793 6.0 0.0 12456  

GRID 33 26.840 6.0 0.0 12456  

$  

GRID 34 9.5598 9.0 0.0 12456  

GRID 35 11.531 9.0 0.0 12456  

GRID 36 13.504 9.0 0.0 12456  

GRID 37 15.476 9.0 0.0 12456

```

GRID	38	17.448	9.0	0.0	12456	\$
GRID	39	19.500	9.0	0.0	12456	
GRID	40	21.392	9.0	0.0	12456	
GRID	41	23.364	9.0	0.0	12456	
GRID	42	25.336	9.0	0.0	12456	
GRID	43	27.308	9.0	0.0	12456	
GRID	44	29.280	9.0	0.0	12456	
\$						
GRID	45	12.746	12.0	0.0	12456	
GRID	46	14.643	12.0	0.0	12456	
GRID	47	16.541	12.0	0.0	12456	
GRID	48	18.438	12.0	0.0	12456	
GRID	49	20.336	12.0	0.0	12456	
GRID	50	22.300	12.0	0.0	12456	
GRID	51	24.131	12.0	0.0	12456	
GRID	52	26.028	12.0	0.0	12456	
GRID	53	27.925	12.0	0.0	12456	
GRID	54	29.823	12.0	0.0	12456	
GRID	55	31.720	12.0	0.0	12456	
\$						
GRID	56	15.933	15.0	0.0	12456	
GRID	57	17.755	15.0	0.0	12456	
GRID	58	19.578	15.0	0.0	12456	
GRID	59	21.401	15.0	0.0	12456	
GRID	60	23.224	15.0	0.0	12456	
GRID	61	25.200	15.0	0.0	12456	
GRID	62	26.869	15.0	0.0	12456	
GRID	63	28.692	15.0	0.0	12456	
GRID	64	30.515	15.0	0.0	12456	
GRID	65	32.338	15.0	0.0	12456	
GRID	66	34.161	15.0	0.0	12456	
\$						
GRID	67	19.119	18.0	0.0	12456	
GRID	68	20.867	18.0	0.0	12456	
GRID	69	22.615	18.0	0.0	12456	
GRID	70	24.364	18.0	0.0	12456	
GRID	71	26.112	18.0	0.0	12456	
GRID	72	28.100	18.0	0.0	12456	
GRID	73	29.609	18.0	0.0	12456	
GRID	74	31.356	18.0	0.0	12456	
GRID	75	33.105	18.0	0.0	12456	
GRID	76	34.853	18.0	0.0	12456	
GRID	77	36.601	18.0	0.0	12456	
\$						
GRID	78	22.306	21.0	0.0	12456	
GRID	79	23.979	21.0	0.0	12456	
GRID	80	25.653	21.0	0.0	12456	
GRID	81	27.327	21.0	0.0	12456	
GRID	82	29.000	21.0	0.0	12456	
GRID	83	30.900	21.0	0.0	12456	
GRID	84	32.347	21.0	0.0	12456	
GRID	85	34.021	21.0	0.0	12456	
GRID	86	35.694	21.0	0.0	12456	
GRID	87	37.368	21.0	0.0	12456	
GRID	88	39.041	21.0	0.0	12456	
\$						
GRID	89	25.493	24.0	0.0	12456	
GRID	90	27.092	24.0	0.0	12456	
GRID	91	28.691	24.0	0.0	12456	
GRID	92	30.290	24.0	0.0	12456	
GRID	93	31.888	24.0	0.0	12456	
GRID	94	33.700	24.0	0.0	12456	
GRID	95	35.086	24.0	0.0	12456	
GRID	96	36.685	24.0	0.0	12456	
GRID	97	38.284	24.0	0.0	12456	
GRID	98	39.883	24.0	0.0	12456	
GRID	99	41.482	24.0	0.0	12456	
\$						
GRID	100	28.679	27.0	0.0	12456	
GRID	101	30.204	27.0	0.0	12456	
GRID	102	31.728	27.0	0.0	12456	
GRID	103	33.252	27.0	0.0	12456	
GRID	104	34.776	27.0	0.0	12456	
GRID	105	36.700	27.0	0.0	12456	
GRID	106	37.825	27.0	0.0	12456	
GRID	107	39.349	27.0	0.0	12456	
GRID	108	40.873	27.0	0.0	12456	
GRID	109	42.398	27.0	0.0	12456	
GRID	110	43.922	27.0	0.0	12456	
\$						
GRID	111	31.866	30.0	0.0	12456	
GRID	112	33.316	30.0	0.0	12456	
GRID	113	34.765	30.0	0.0	12456	
GRID	114	36.215	30.0	0.0	12456	
GRID	115	37.664	30.0	0.0	12456	
GRID	116	39.500	30.0	0.0	12456	
GRID	117	40.564	30.0	0.0	12456	
GRID	118	42.013	30.0	0.0	12456	
GRID	119	43.463	30.0	0.0	12456	
GRID	120	44.912	30.0	0.0	12456	
GRID	121	46.362	30.0	0.0	12456	
\$						
\$						
DIRECT INPUT MODE SHAPES						\$
\$						
DMI	MODES	RDP	REC	121	5	\$
+BC	1	1	-0.0405	-0.0153	0.0	ABC
+1T6	0.0	0.0	0.0	-0.0524	-0.104	0.00638
						MIT6
						0.0691
						MIT14

+1T14	0.113	0.166	0.225	0.306	0.402	0.538	0.697	0.914	M1T22
+1T22	0.195	0.317	0.462	0.628	0.816	1.03	1.27	1.56	M1T30
+1T30	1.88	2.25	2.68	0.815	1.08	1.38	1.70	2.05	M1T38
+1T38	2.45	2.86	3.32	3.84	4.41	5.03	2.01	2.42	M1T46
+1T46	2.87	3.35	3.86	4.43	5.00	5.63	6.30	7.03	M1T54
+1T54	7.80	3.80	4.36	4.95	5.57	6.22	6.97	7.63	M1T62
+1T62	8.39	9.19	10.0	10.9	6.16	6.85	7.56	8.29	M1T70
+1T70	9.06	9.96	10.7	11.5	12.4	13.3	14.3	9.05	M1T78
+1T78	9.82	10.6	11.4	12.3	13.3	14.0	14.9	15.9	M1T86
+1T86	16.9	17.9	12.4	13.2	14.0	14.9	15.8	16.8	M1T94
+1T94	17.6	18.5	19.5	20.5	21.5	16.0	16.8	17.7	M1T102
+1T102	18.6	19.5	20.6	21.3	22.2	23.2	24.2	25.1	M1T110
+1T110	19.8	20.6	21.5	22.4	23.2	24.4	25.0	26.0	M1T118
+1T118	26.9	27.8	28.8	2	1	-0.351	-0.128	0.00	M2T3
+2T3	0.0	0.0	0.0	0.0	0.0	-0.351	-0.128	0.00	M2T11
+2T11	0.137	0.335	0.514	0.668	0.767	0.778	0.636	0.238	M2T19
+2T19	-0.719	-2.35	-4.79	1.62	2.16	2.59	2.83	2.83	M2T27
+2T27	2.50	1.74	0.444	-1.50	-4.11	-7.53	5.22	5.84	M2T35
+2T35	6.13	6.03	5.48	4.35	2.76	0.476	-2.47	-6.10	M2T43
+2T43	-10.6	10.5	10.7	10.4	9.51	8.05	5.90	3.28	M2T51
+2T51	-0.074	-4.09	-8.80	-14.4	16.5	15.8	14.4	12.5	M2T59
+2T59	9.91	6.41	2.86	-1.61	-6.72	-12.5	-19.2	22.0	M2T67
+2T67	20.0	17.4	14.3	10.5	5.47	1.16	-4.39	-10.5	M2T75
+2T75	-17.3	-24.9	25.9	22.6	18.70	14.3	9.40	3.17	M2T83
+2T83	-2.01	-8.48	-15.5	-23.0	-31.30	27.40	22.90	17.9	M2T91
+2T91	12.40	6.52	-0.653	-6.50	-13.60	-21.2	-29.2	-37.9	M2T99
+2T99	26.30	20.70	14.80	8.64	2.11	-6.59	-11.9	-19.4	M2T107
+2T107	-27.3	-35.6	-44.50	22.6	16.50	10.2	3.58	-3.28	M2T115
+2T115	-12.4	-17.8	-25.6	-33.7	-42.3	-52.6	3	1	M3T0
+3T0	0.083	0.028	0.0	0.0	0.0	0.0	0.0	0.0	M3T8
+3T8	0.0	-0.566	-2.30	0.004	-0.034	-0.092	-0.196	-0.371	M3T16
+3T16	-0.631	-1.12	-1.95	-3.60	-6.19	-10.3	-1.62	-0.366	M3T24
+3T24	-0.694	-1.20	-1.95	-3.06	-4.68	-6.99	-10.2	-14.30	M3T32
+3T32	-20.0	-1.714	-1.25	-2.02	-3.13	-4.64	-6.76	-9.32	M3T40
+3T40	-12.7	-16.80	-21.90	-28.4	-1.45	-2.36	-3.62	-5.29	M3T48
+3T48	-7.44	-10.20	-13.4	-17.2	-21.7	-26.90	-33.20	-1.70	M3T56
+3T56	-2.93	-4.55	-6.59	-9.06	-12.2	-15.3	-19.1	-23.3	M3T64
+3T64	-27.9	-33.4	-0.549	-1.96	-3.72	-5.83	-8.27	-11.4	M3T72
+3T72	-14.1	-17.4	-20.8	-24.5	-28.7	2.87	1.46	-0.219	M3T80
+3T80	-2.15	-4.31	-6.98	-9.13	-11.7	-14.3	-16.8	-19.6	M3T88
+3T88	9.08	7.77	6.27	4.61	2.83	0.748	-0.857	-2.67	M3T96
+3T96	-4.39	-5.96	-7.42	17.9	16.6	15.3	13.9	12.4	M3T104
+3T104	10.7	9.73	8.52	7.48	6.67	6.20	28.2	26.9	M3T112
+3T112	25.7	24.5	23.4	22.1	21.4	20.7	20.3	20.2	M3T120
+3T120	21.0	4	1	-1.08	-0.416	0.0	0.0	0.0	M4T5
+4T5	0.0	0.0	0.0	0.0	-1.42	-5.22	0.482	1.01	M4T13
+4T13	1.43	1.73	1.85	1.77	1.34	-0.436	-1.56	-4.92	M4T21
+4T21	-10.7	4.61	5.67	6.33	6.46	6.01	4.90	3.04	M4T29
+4T29	0.289	-3.49	-8.37	-15.5	12.80	13.2	12.9	11.7	M4T37
+4T37	9.63	6.71	3.29	-0.953	-5.84	-11.4	-18.8	21.7	M4T45
+4T45	20.1	17.6	14.4	10.5	5.98	1.43	-3.46	-8.44	M4T53
+4T53	-13.4	-19.6	26.5	22.3	17.6	12.6	7.55	2.16	M4T61
+4T61	-2.14	-6.40	-10.1	-13.0	-16.0	23.7	17.6	11.8	M4T69
+4T69	6.36	1.49	-3.13	-5.83	-7.94	-8.79	-8.18	-6.13	M4T77
+4T77	13.0	6.90	1.72	-2.42	-5.38	-7.16	-7.28	-5.93	M4T85
+4T85	-2.81	2.36	10.5	-2.49	-6.48	-9.10	-10.3	-9.97	M4T93
+4T93	-7.71	-4.51	0.890	8.34	18.2	32.5	-17.3	-17.6	M4T101
+4T101	-16.5	-14.10	-10.1	-2.75	2.83	12.1	23.7	38.2	M4T109
+4T109	58.3	-26.2	-22.9	-18.6	-13.0	-5.87	5.57	13.6	M4T117
+4T117	26.7	42.8	63.6	104.0	5	1	-0.053	-0.03	M5T2
+5T2	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-2.72	M5T10
+5T10	-12.1	0.087	0.130	0.118	-0.006	-0.302	-0.821	-1.92	M5T18
+5T18	-4.00	-8.76	-17.0	-35.0	0.674	0.589	0.213	-0.596	M5T26
+5T26	-2.0	-4.24	-7.70	-12.9	-20.4	-30.7	-50.1	1.88	M5T34
+5T34	1.26	0.099	-1.75	-4.41	-8.14	-12.6	-18.2	-24.7	M5T42
+5T42	-32.1	-44.6	3.88	2.49	0.521	-2.04	-5.10	-8.63	M5T50
+5T50	-12.0	-15.2	-17.6	-18.7	-19.1	6.74	4.64	2.28	M5T58
+5T58	-0.164	-2.42	-4.27	-4.97	-4.35	-1.70	3.76	14.5	M5T66
+5T66	9.50	7.07	4.97	3.43	2.75	3.43	5.25	9.13	M5T74
+5T74	15.3	24.3	40.1	10.0	7.77	6.38	6.00	6.79	M5T82
+5T82	9.30	12.4	17.4	23.9	32.1	45.4	5.49	3.89	M5T90
+5T90	3.33	3.82	5.31	8.10	10.9	14.6	18.5	22.5	M5T98
+5T98	27.8	-5.57	-6.15	-5.98	-5.15	-3.85	-1.94	-0.901	M5T106
+5T106	0.032	-0.069	-1.91	-6.70	-21.1	-20.7	-20.2	-19.5	M5T114
+5T114	-18.9	-19.0	-19.7	-22.3	-27.4	-37.5	-70.9	5	\$
EIGR	10	GIV	5.	200.	5			+EI	
+EI	MASS								\$
\$	DIRECT INPUT OF THE GENERALIZED MASS MATRIX FOR THE								\$
\$	NORMAL MODES ANALYSIS								\$
\$									\$
DMI	MAA	RDP	DIAG	5	5				+D3
+D3	1	1	1.	2	2	1.	3	3	+D4
+D4	1.	4	4	1.	5	5	1.		\$
\$	DIRECT INPUT OF THE GENERALIZED STIFFNESS MATRIX FOR THE								\$
\$	NORMAL MODES ANALYSIS								\$
\$									\$
DMI	KAA	RDP	DIAG	5	5				+D1
+D1	1	1	3637.72	2	2	57502.973	3		+D2
+D2	9228.714	4	330846.95		5	550752.7			\$
\$	DIRECT INPUT OF THE GENERALIZED STIFFNESS MATRIX FOR THE								\$
\$	FLUTTER ANALYSIS								\$
\$									\$
DMI	KFLUT	CDP	DIAG	5	5				+D5

\$ BOXES TO THE WING STRUCTURE GRIDS. THE SETK BULK DATA CARD REFERS \$
 \$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES \$
 \$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=60) BULK DATA CARD. \$
 \$
 \$ EID MODEL CP SETK SETG DZ EPS \$
 SPLINE1 10 WING 10 60
 \$
 \$ SETID MACROID BOX1 BOX2
 PANLST1 10 1001 1001 1220
 \$
 \$ SID G1 G2 ETC
 SET1 60 1 THRU 121
 \$
 \$
 \$ * * FLUTTER ANALYSIS * *
 \$
 \$
 \$ SIX FLUTTER CARDS ARE USED. EACH FLUTTER CARD REFERS TO A SPECIFIC \$
 \$ MKAEROZ BULK DATA CARD THAT SPECIFIES THE MACH NUMBER, REDUCED \$
 \$ FREQUENCIES AND METHOD USED (I.E. LINEAR OR NONLINEAR) IN THE \$
 \$ ANALYSIS. ALL FLUTTER CARDS REQUEST BOTH THE P-K AND K FLUTTER \$
 \$ SOLUTION METHODS AND REFERENCE THE SAME FLFACT CARD (SID=40) WHICH \$
 \$ LISTS THE VELOCITIES USED BY THE P-K METHOD. EACH FLUTTER BULK DATA \$
 \$ CARD SPECIFIES DIFFERENT DENSITY RATIOS (VIA THE DENS ENTRY) TO \$
 \$ PERFORM A MATCHPOINT ANALYSIS. AIR DENSITY VALUES ARE COMPUTED FROM: \$
 \$ DENSITY RATIO X RHOREF (WHERE RHOREF IS SPECIFIED BY THE AEROZ BULK \$
 \$ DATA CARD).
 \$
 \$ * MACH 0.678 - ZTAIC FLUTTER CASE *
 \$
 \$
 \$ SETID METHOD DENS IDMK VEL MLIST KLIST EFFID \$
 FLUTTER 1 PKK 301 10 40 +FL1
 \$ SYMXZ SYMDY EPS CURVFIT PRINT \$
 +FL1 1
 \$
 \$ SID F1 F2 ETC
 FLFACT 40 8000. 8400. 9600. 10800. 12000. 13200. 14400.
 FLFACT 301 .17 .18 .19 .20 .22
 \$
 \$ * MACH 0.678 - ZONA6 FLUTTER CASE *
 \$
 \$ FLUTTER 2 PKK 302 20 40 +FL1
 +FL1 1
 FLFACT 302 .18 .182 .184 .186 .188
 \$
 \$ * MACH 0.9 - ZTAIC FLUTTER CASE *
 \$
 FLUTTER 3 PKK 303 30 40 +FL1
 +FL1 1
 FLFACT 303 .07 .075 .08 .0825 .085 .0875 .09
 \$
 \$ * MACH 0.9 - ZONA6 FLUTTER CASE *
 \$
 \$ FLUTTER 4 PKK 304 40 40 +FL1
 +FL1 1
 FLFACT 304 .082 .084 .085 .086 .088
 \$
 \$ * MACH 0.95 - ZTAIC FLUTTER CASE *
 \$
 \$ FLUTTER 5 PKK 305 50 40 +FL1
 +FL1 1
 FLFACT 305 .052 .054 .055 .056 .058 .059
 \$
 \$ * MACH 0.95 - ZONA6 FLUTTER CASE *
 \$
 \$ FLUTTER 6 PKK 306 60 40 +FL1
 +FL1 1
 FLFACT 306 .065 .066 .067 .068 .069
 \$
 \$
 \$ * * TRANSONIC DATA FOR ZTAIC METHOD * *
 \$
 \$
 \$ THE ZTAIC BULK DATA CARD IS REFERRED TO BY THE ZTAIC ENTRY OF THE \$
 \$ CAERO7 (WING MACROELEMENT) BULK DATA CARD. THE ZTAIC CARD REFERS \$
 \$ TO 3 MACHCP BULK DATA CARDS THAT ESTABLISH THE MACH NUMBER AND \$
 \$ STEADY INPUT PRESSURE RELATIONS. SPAN LOCATION AND CORRESPONDING \$
 \$ STEADY PRESSURE FOR THAT SECTION ARE SPECIFIED BY THE SPANID AND \$
 \$ CHDPC ENTRIES, RESPECTIVELY. FOR EXAMPLE:
 \$ THE STEADY PRESSURE INPUT FOR MACH 0.678 AT WING SPANWISE STATIONS 1 \$
 \$ THRU 11 IS ESTABLISHED BY THE MACHCP CARD WITH ID=1001. TO ESTABLISH \$
 \$ CORRESPONDENCE WITH AIC DATA, THIS STEADY PRESSURE MACH NUMBER OF \$
 \$ 0.678 MUST IDENTICALLY EXIST IN ONE OF THE MKAEROZ BULK DATA CARDS \$
 \$ WITH THE NONLINEAR METHOD ACTIVE (IN THIS CASE MKAEROZ WITH IDMK=10). \$
 \$ THE SPANWISE STATION INDICES CORRESPOND TO THE WING MACROELEMENT \$
 \$ SPAN DIVISIONS CENTERLINE LOCATIONS. IN THIS CASE AN AEFAC BULK \$
 \$ DATA CARD WITH SID=10 IS USED TO SPECIFY THE SPANWISE WING MACRO- \$
 \$ ELEMENT CUTS. THEREFORE, SPANID=1 REFERS TO THE WING SPAN LOCATION \$
 \$ OF 8.225%, SPANID=2 REFERS TO THE WING SPAN LOCATION OF 21.85%, ETC. \$
 \$ THE CHORDWISE STRIP STEADY PRESSURE AT MACH 0.678 AT 8.225% IS GIVEN \$
 \$ IN A CHORDCP BULK DATA CARD WITH ID=1001, AT 21.85% IS GIVEN IN A \$
 \$ CHORDCP BULK DATA CARD WITH ID=1002, ETC.
 \$
 \$ NOTE: THE CHORDCP BULK DATA CARDS ARE IN THE INCLUDE FILES (SEE BELOW) \$

```

$   ID      NFLAP    MACHCP   MACHCP   ETC
$   ZTAIC  1001     1001     1002     1003
$   ID      MACH     IGRID     INDICA   SPANID  CHDCP   SPANID  CHDCP
$   ZTAIC  1001     0.678    0         0         1         1001    2         2001
$   SPANID CHDCP   ETC
$   +MC1   3        3001     4         4001     5         5001    6         6001
$   +MC2   7        7001     8         8001     9         9001    10        10001
$   +MC3   11       11001
$   MACHCP 1002     0.9      0         0         1         1002    2         2002
$   +MC1   3        3002     4         4002     5         5002    6         6002
$   +MC2   7        7002     8         8002     9         9002    10        10002
$   +MC3   11       11002
$   MACHCP 1003     0.95    0         0         1         1003    2         2003
$   +MC1   3        3003     4         4003     5         5003    6         6003
$   +MC2   7        7003     8         8003     9         9003    10        10003
$   +MC3   11       11003
$   $ TWO SETS OF STEADY PRESSURE INPUT DATA ARE USED IN THE PRESENT
$   $ ANALYSIS (TRANSONIC SMALL DISTURBANCE [FROM CAPTSD CODE] AND
$   $ NAVIER-STOKES [FROM ENSAERO CODE]). AN INCLUDE STATEMENT IS USED
$   $ TO REQUEST THE DESIRED PRESSURE TO BE USED. ONLY ONE STEADY PRESSURE
$   $ INPUT CAN BE USED AT A TIME. THE USER IS INSTRUCTED TO UNCOMMENT THE
$   $ DESIRED INCLUDE FILE CONTAINING THE DESIRED STEADY PRESSURE INPUT.
$   $ NOTE THAT STEADY PRESSURE INPUT FOR ALL 3 MACH NUMBERS
$   $ (0.678, 0.9, 0.95) ARE INCLUDED IN EACH FILE.
$   $
INCLUDE tsdcp.inp
$ INCLUDE nsdp.inp
$ 
$ 
ENDDATA

```

3.0 STATIC AEROELASTICITY (TRIM CASES)

3.1 Case 1: Forward Swept Wing in Level Flight (HA144A)

- **Purpose:** Demonstrate a wing + canard configuration symmetric trim case at subsonic (ZONA6 method) and supersonic (ZONA7 method) Mach numbers.

- **Description of Input:**

A Forward Swept Wing (FSW) + canard airplane (modified HA144A case from the MSC/NASTRAN Aeroelastic Analysis User's Guide, Version 68) is considered for the present case. The structural and aerodynamic models are shown in Fig 3.1.1.

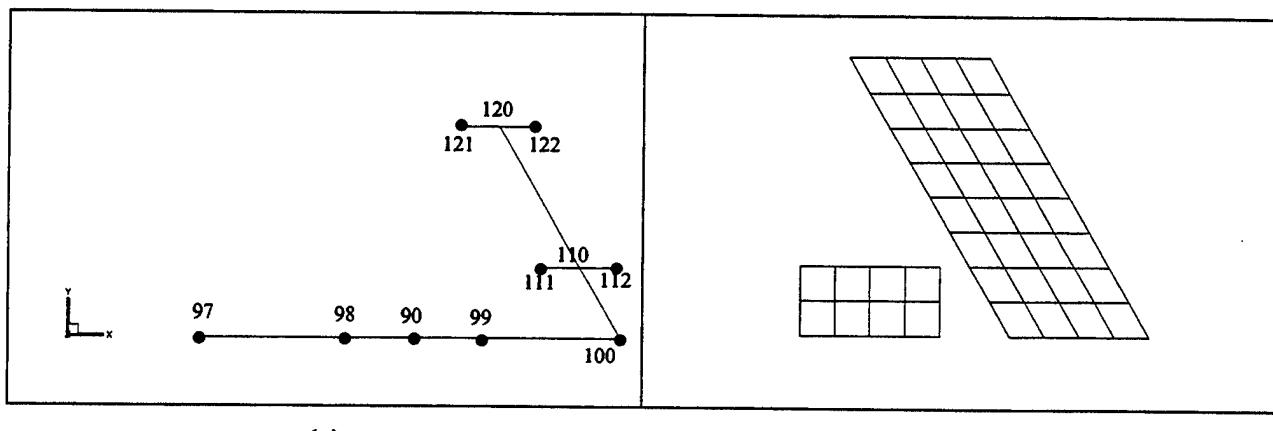


Figure 3.1.1 Forward Swept Wing (FSW) (a) Structural Model and (b) Aerodynamic Model.

- Solution Control

Three symmetric static aeroelastic (SZAERO) analyses are requested for each of the desired flight Mach numbers and dynamic pressures. The boundary conditions are as follows: MPC=100 (Multipoint Constraints) of the rigid bar element connections of the wing structure; SPC=1 (Single Point Constraints) constraining all degrees of freedom of GRID's 90, 97, 98, 99 and 100 except the z-axis translation and rotation about the y-axis; and SUPPORT=1 (Fictitious Support) for determinant reactions along the z-axis translation and rotation about the y-axis in the free body analysis.

- Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide (Version 68) for a description of the structural model.

- Aerodynamic Parameters / Flight Conditions

An **AEROZ** bulk data card is used to specify a symmetric model about the x-z plane. A reference chord of 10ft, reference span of 40ft and reference area of 400ft² for the full model is specified. The reference grid about which the stability derivative calculations are made is defined by GREF=90.

Two **MKAEROZ** bulk data cards are used for Mach 0.9 and 1.3. Reduced frequency input is not required for this case, since only static aeroelastic analysis is performed.

- Aerodynamic Model

Two **CAERO7** bulk data cards are used to define the wing and canard wing macroelements with (chord aero boxes x span aero boxes) 4 x 8 and 4 x 2 evenly cut aerodynamic boxes, respectively. A **PAFOIL7** card is used to define the airfoil camber to simulate the incidence angle of 0.1 deg used in the corresponding MSC/NASTRAN case (HA144A). This was done to account for differences between test and theory experimental pressure data at some reference condition.

An **AESURFZ** card is used to define the entire canard as a control surface. A **COORD2R** card is used to define the y-axis hinge line of the control surface (in this case hinged at quarter chord).

- Spline

The infinite plate spline method (**SPLINE1**) is used to spline all wing aerodynamic boxes to the structural grid points of the wing section. A beam spline (**SPLINE3**) is used to spline the canard to the structural grid points 98 and 99.

- Trim

Three **TRIM** bulk data cards are used to specify the following three trim flight conditions: (1) M=0.9, q=40 psf; (2) M=0.9, q=1200psf; and (3) M=1.3, q=1151psf; all in 1-G level flight. Trim parameters imposed for all three trim flight conditions are: no pitch rate (QRATE=0.0), 1-G load factor (NZ=32.2), and zero pitch acceleration (QACCEL=0.0). Aircraft angle-of-attack (ALPHA) and control surface rotation (ELEV) are set to FREE to be determined by the trim analysis.

• Description of Output:

The three flight conditions considered in this case are: Mach 0.9 at dynamic pressures equal to 40psf and 1200psf as well as Mach 1.3 at a dynamic pressure of 1151psf. Table 3.1.1 shows the longitudinal aerodynamic stability derivatives of the rigid and flexible aircraft at Mach 0.9. Excellent agreement can be seen between the ASTROS* results and those of MSC/NASTRAN. Also, good agreement is obtained for the final trim results. Similarly, good agreement for the Mach 1.3 case can be seen in Table 3.1.2 for both stability derivatives and trim results.

Table 3.1.1 Longitudinal Stability Derivatives of FSW Aircraft at Mach 0.9.

Derivative	ASTROS* Results			MSC/NASTRAN Results		
	Value for Rigid Airplane	Unrestrained Value $q=40$ psf	Unrestrained Value $q=1200$ psf	Value for Rigid Airplane	Unrestrained Value $q=40$ psf	Unrestrained Value $q=1200$ psf
C_{Z_0}	0.0084	0.0085	0.0127	0.0084	0.0085	0.0127
C_{M_0}	-0.0064	-0.0065	-0.0096	-0.006	-0.0061	-0.0087
C_{Z_u}	5.098	5.155	7.7412	5.071	5.127	7.772
C_{M_α}	-3.131	-3.173	-5.063	-2.871	-2.907	-4.557
C_{Z_q}	12.516	12.606	16.604	12.074	12.158	16.100
C_{M_q}	-10.875	-10.941	-13.874	-9.954	-10.007	-12.499
$C_{Z\delta_e}$	0.2551	0.2597	0.4680	0.2461	0.2520	0.5219
$C_{M\delta_e}$	0.5671	0.5638	0.4143	0.5715	0.5678	0.3956

Note: Units are (1/rad).

Trim Results (flexible aircraft):

	ASTROS* Results		MSC/NASTRAN Results		
	$q=40$ psf	$q=1200$ psf	$q=40$ psf	$q=1200$ psf	
Pitch Rate	0.00	0.00	0.00	0.00	(User Input)
Load Factor	32.20	32.20	32.20	32.20	(User Input)
Pitch Acceleration	0.00	0.00	0.00	0.00	(User Input)
Angle of Attack	9.54	0.177	9.69	0.079	(Computed)
Control Surface Rotation	31.48	1.156	28.22	1.107	(Computed)

Note: Units in degrees.

Table 3.1.2 Longitudinal Stability Derivatives of FSW Aircraft at Mach 1.3.

Derivative	ASTROS* Results		MSC/NASTRAN Results	
	Value for Rigid Airplane	Unrestrained Value $q=1151$ psf	Value for Rigid Airplane	Unrestrained Value $q=1151$ psf
C_{Z_0}	0.0074	0.0087	0.0074	0.0086
C_{M_0}	-0.0072	-0.0085	-0.0072	-0.0083
C_{Z_u}	4.8473	5.8156	4.847	5.783
C_{M_α}	-3.8845	-4.800	-3.885	-4.728
C_{Z_q}	9.5399	9.9148	9.055	9.305
C_{M_q}	-10.5375	-10.8857	-10.149	-10.360
$C_{Z\delta_e}$	0.6346	0.8467	0.6346	0.8802
$C_{M\delta_e}$	0.2378	0.0348	0.2378	0.0105

Note: Units are (1/rad).

Trim Results (flexible aircraft):

	ASTROS* Result	NASTRAN	
Pitch Rate	0.00	0.00	(User Input)
Load Factor	32.20	32.20	(User Input)
Pitch Acceleration	0.00	0.00	(User Input)
Angle of Attack	0.1025	-0.003	(Computed)
Control Surface Rotation	1.649	1.734	(Computed)

Note: Units in degrees.

• Input Data Listing:

Listing 2.6 Input Data for the Forward Swept Wing in Level Flight (HA144A).

```

ASSIGN DATABASE HA144A PASS NEW DELETE
SOLUTION
TITLE - ZAERO TRIM CASE (HA144A): FORWARD SWEPT WING IN LEVEL FLIGHT
SUBTITLE - SUBSONIC (M=0.9) AND SUPERSONIC (M=1.2) STABILITY DERIVATIVES
ANALYZE
    BOUNDARY MPC - 100, SPC - 1, SUPPORT - 90
    LABEL - SYMMETRIC FLIGHT CONDITIONS, ZAERO MODULE AERODYNAMICS
    SAERO SYMMETRIC ( TRIM - 1 )
    PRINT TRIM
    LABEL - TRIM CASE #1 - M - 0.9, Q - 40 PSF
    SAERO SYMMETRIC ( TRIM - 2 )
    PRINT TRIM
    LABEL - TRIM CASE #2 - M - 0.9, Q - 1200 PSF
    SAERO SYMMETRIC ( TRIM - 3 )
    PRINT TRIM
    LABEL - TRIM CASE #3 - M - 1.3, Q - 1151 PSF
END
BEGIN BULK
$...1...2...3...4...5...6...7...8...9...10...
GRID 90      15.   0.   0.
GRID 97      0.    0.   0.
GRID 98      10.   0.   0.
GRID 99      20.   0.   0.
GRID 100     30.   0.   0.
ASET 999     3     90
$           * WING GRIDS *
$           ID   CP   X1    X2    X3    CD    PS    SEID   $
$     111  24.61325 +5.  0.
$     110  27.11325 +5.  0.
$     112  29.61325 +5.  0.
$     121  18.83975+15. 0.
$     120  21.33975+15. 0.
$     122  23.83975+15. 0.
$           * * STRUCTURAL STIFFNESS PROPERTIES * *
$           * FUSELAGE STRUCTURE *
$           EID  PID  GA   GB   X1,GO  X2    X3    $
$     CBAR 101  100  97   98   0.    0.    1.
$     CBAR 102  100  98   90   0.    0.    1.
$     CBAR 100  100  90   99   0.    0.    1.
$     CBAR 103  100  99   100  0.    0.    1.
$           PID  MID  A    I1   I2    J    NSM   $
$     PBAR 100  1    2.0  .173611 0.15  0.5   +PB1
$     C1   C2   D1   D2   E1   E2   F1   F2   +
$     +PB1  1.0  1.0  1.0  -1.0  -1.0  1.0  -1.0  -1.0  +PB2
$     K1   K2   I12
$     +PB2  0.0
$           * WING STRUCTURE *
$           EID  PID  GA   GB   X1,GO  X2    X3    $
$     CBAR 110  101  100  110  0.    0.    1.
$     CBAR 120  101  110  120  0.    0.    1.
$           SETID EID  GA   GB   CNA   CNB   CMA   CMB   $
$     RBAR 100  111  110  111  123456
$     RBAR 100  112  110  112  123456
$     RBAR 100  121  120  121  123456
$     RBAR 100  122  120  122  123456
$           PID  MID  A    I1   I2    J    NSM   $

```



```

$ THE ENTIRE CANARD IS DEFINED AS A CONTROL SURFACE BY AN AESURFZ BULK $  

$ DATA CARD. THE AESURFZ CARD REFERS TO A PANLST2 BULK DATA CARD WHICH $  

$ SPECIFIES THAT AERO BOXES 1000 THROUGH 1007 BE USED AS THE CONTROL $  

$ SURFACE. THE AESURFZ CARD REFERENCES A RECTANGULAR COORDINATE SYSTEM $  

$ (COORD2R) THAT DEFINES THE Y-AXIS OF THE CONTROL SURFACE HINGE LINE. $  

$ THE CONTROL SURFACE IS HINGED ABOUT ITS QUARTER-CHORD. $  

$  

$     LABEL  TYPE  CID  SETK  SETG  

AESURFZ ELEV   SYM    1    1000  

$  

$     SETID  MACROID BOX1  BOX2  ETC  

PANLST2 1000  1000  1000  1001  1002  1003  1004  1005  +P1  

+P1  1006  1007  

$  

$     CID    RID    A1    A2    A3    B1    B2    B3  +CRD2  

CORD2R 1      0    12.5  0.0   0.0   12.5  0.0   10.0  

$  

$     C1    C2    C3  

+CRD2 20.0  0.0   10.0  

$  

$  

$     * SURFACE SPLINE FIT ON THE WING *  

$  

$  

$ THE INFINITE PLATE SPLINE METHOD IS USED TO SPLINE THE WING AERO $  

$ BOXES TO THE WING STRUCTURE GRIDS. THE SETK BULK DATA CARD REFERS $  

$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES $  

$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=1105) BULK DATA CARD. $  

$  

$     EID    MODEL  CP    SETK  SETG  DZ    EPS  

SPLINE1 1601  WING   1100  1105  0.0  

$  

$     SETID  MACROID BOX1  BOX2  

PANLST1 1100  1100  1100  1131  

$  

$     SID    G1    G2    ETC  

SET1   1105  100   110   111   112   120   121   122  

$  

$  

$ THE BEAM SPLINE METHOD IS USED ON THE CANARD. THE SETK ENTRY REFERS $  

$ TO THE PANLST2 BULK DATA CARD PREVIOUSLY DEFINED FOR THE AESURFZ BULK $  

$ DATA CARD LISTING ALL AERO BOXES LOCATED ON THE CANARD.  

$  

$     EID    MODEL  SETK  SETG  DZ    DTOR  CID  DTHX  +SP1  

SPLINE2 1501  CANARD 1000  1000  0.0   1.0   1   -1.0  

$  

$     DTMY  

+SP1  -1.0  

$  

$     SID    G1    G2    ETC  

SET1   1000  98    99  

$  

$  

$     * TRIM CONDITIONS *  

$  

$  

$ THREE TRIM CONDITIONS (ALL AT 1G LEVEL FLIGHT) ARE CONSIDERED FOR $  

$ THIS CASE. 1) M=0.9, Q=40.0 PSF, 2) M=0.9, Q=1200.0 PSF AND $  

$ 3) M=1.3, Q=1151 PSF. IDMK ENTRIES REFER TO MKAEROZ CARDS THAT $  

$ SPECIFY THE MACH NUMBER FOR EACH TRIM CASE. DYNAMIC PRESSURES OF $  

$ 40.0, 1200.0, AND 1151.0 ARE SPECIFIED IN THE QDE ENTRIES. A TRIM $  

$ TYPE OF PITCH IS SPECIFIED FOR SYMMETRIC TRIM OF LIFT AND PITCHING $  

$ MOMENT (2 DOF). TRIM FLIGHT CONDITIONS IMPOSED ARE NO PITCH RATE $  

$ (QRATE=0.0) ONE G LOAD FACTOR (NZ=32.2) AND ZERO PITCH ACCELERATION $  

$ (QACCEL=0.0). THE ANGLE-OF-ATTACK (ALPHA) AND CANARD SURFACE $  

$ ROTATION (ELEV) ARE SET TO FREE TO BE DETERMINED BY THE TRIM ANALYSIS.  

$  

$ TRIM CONDITION 1: 1 G LEVEL FLIGHT AT LOW SPEED  

$  

$     TRIMID IDMK  QDP    TRMTYP  EFFID  VO    PRINT  

TRIM  1      1000  40.0   PITCH   1.0   -2    +TR1  

$     LABEL1 VAL1  LABEL2 VAL2  ETC  

+TR1  QRATE  0.0   NZ    32.2   QACCEL  0.0   ALPHA  FREE  

+TR2  ELEV    FREE  

$  

$ TRIM CONDITION 2: 1 G LEVEL FLIGHT AT HIGH SUBSONIC SPEED  

$  

$     TRIMID IDMK  QDP    TRMTYP  EFFID  VO    PRINT  

TRIM  2      1000  1200.0  PITCH   1.0   -2    +TR3  

+TR3  QRATE  0.0   NZ    32.2   QACCEL  0.0   ALPHA  FREE  

+TR4  ELEV    FREE  

$  

$ TRIM CONDITION 3: 1 G LEVEL FLIGHT AT LOW SUPERSONIC SPEED  

$  

$     TRIMID IDMK  QDP    TRMTYP  EFFID  VO    PRINT  

TRIM  3      2000  1151.0  PITCH   1.0   -2    +TR5  

+TR5  QRATE  0.0   NZ    32.2   QACCEL  0.0   ALPHA  FREE  

+TR6  ELEV    FREE  

$  

$  

ENDDATA

```

3.2 Case 2: Forward Swept Wing Airplane in Antisymmetric Maneuvers (HA144D)

- **Purpose:** Demonstrate a wing + canard + vertical tail fin configuration antisymmetric trim case at subsonic (ZONA6 method) Mach number.

- **Description of Input:**

The FSW Airplane of Case 1 (Section 3.1) is reconsidered here for its lateral-directional stability characteristics. The half-span model is modified to add a sweptback vertical tail fin and to consider the antisymmetrical motions of the aircraft. The structural and aerodynamic models of the vertical tail fin portion of the aircraft is shown in Fig 3.2.1. The wing + canard aerodynamic models remain unchanged from those of Case 1 (Section 3.1) and are shown in Fig 3.1.1.

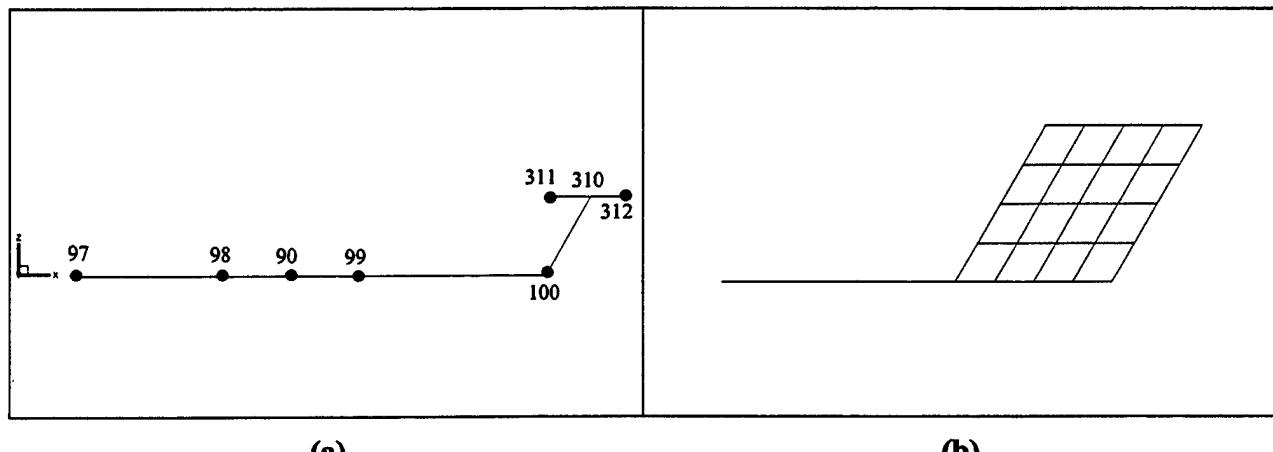


Figure 3.2.1 Side View of FSW Showing the Vertical Tail Fin (a) Structural Model and (b) Aerodynamic Model.

- Solution Control

Two symmetric static aeroelastic (SZAERO) analyses are requested both at Mach 0.9 and $q=1200\text{psf}$. The boundary conditions are as follows: MPC=100 (Multipoint Constraints) of the rigid bar element connections of the aircraft structure; SPC=2 (Single Point Constraints) constraining all degrees of freedom of GRID's 90, 97, 98, 99 and 100 except the y-axis translation (lateral motion), rotation about the x-axis (roll), and rotation about the z-axis (yaw); and SUPPORT=20 (Fictitious Support) for determinant reactions along the y-axis translation, rotations about the x- and z-axes in the free body analysis.

- Structural Model

The reader is referred to the MSC/NASTRAN Aeroelastic Analysis User's Guide (Version 68) for a description of the structural model.

- Aerodynamic Parameters / Flight Conditions

The flight conditions for this case are the same as those of Case 1 (Section 3.1), except only one **MKAEROZ** bulk data card is used for Mach 0.9

- Aerodynamic Model

The aerodynamic model is the same as that of Case 1 (Section 3.1) except for the control surface definitions. Two control surfaces are defined for the present case. An aileron is defined on the wing (aerodynamic boxes 1119, 1123, 1127 and 1131) and a rudder is defined on the vertical tail fin (aerodynamic boxes 3103, 3107, 3111, 3115). **COORD2R** cards are used to define the y-axis hinge line of the control surfaces.

- Spline

The spline of the aerodynamic model to the structure is the same as that of Case 1 except for the additional splining of the vertical tail fin to the tail structure. All 16 aerodynamic boxes of the vertical tail fin (3100 through 3115) are splined by the infinite plate spline method to the tail structural **GRID**'s (100, 311, 310, 312).

- Trim

Two subsonic trim cases are considered. The first, **TRIM 1**, finds the steady roll solution for an aileron rotation of 25 degrees (AILERON), zero yaw acceleration (RACCEL), zero roll acceleration (PACCEL), zero yaw rate (RRATE) and no side slip acceleration (NY). Computed trim parameters are the yaw angle (BETA), rudder deflection angle (RUDDER) and roll rate (PRATE). The second trim condition, **TRIM 2**, is an abrupt roll solution with the same trim conditions imposed in the first trim case, except that roll rate (PRATE) is set to zero and the roll acceleration (PACCEL) is set to FREE to be computed by the trim analysis.

• Description of Output:

Two trim cases (one for steady roll and one for abrupt roll) are examined at Mach 0.9 and dynamic pressure 1200psf. The results of the lateral-directional stability characteristics of ASTROS* and MSC/NASTRAN are compared in Table 3.2.1. Excellent agreement is seen between the two sets of results.

The trim results of the first trim case is shown in Table 3.2.2 and the second in Table 3.2.3. Good agreement are obtained for both trim cases.

Table 3.2.1 Lateral Aerodynamic Stability Derivatives of FSW Aircraft with Vertical Tail at Mach 0.9.

Derivative	ASTROS* Results		MSC/NASTRAN Results	
	Value for Rigid Airplane	Unrestrained Value $q=1200 \text{ psf}$	Value for Rigid Airplane	Unrestrained Value $q=1200 \text{ psf}$
C_{Y_β}	-0.7241	-0.7375	-0.7158	-0.7260
C_{l_β}	0.0340	0.0276	0.0328	0.0271
C_{n_β}	-0.2704	-0.2754	-0.2592	-0.2630
C_{Y_p}	-0.0824	-0.1015	-0.07965	-0.09466
C_{l_p}	-0.4207	-0.4364	-0.4185	-0.4448
C_{n_p}	-0.0278	-0.0348	-0.0261	-0.0314
C_{Y_r}	-0.7461	-0.7528	-0.7233	-0.7285
C_{l_r}	0.0453	0.0382	0.0429	0.0363
C_{n_r}	-0.2950	-0.2974	-0.2775	-0.2794
C_{Y_s}	0.3785	0.3641	0.3491	0.3381
C_{l_s}	-0.0414	-0.0361	-0.03745	-0.03229
C_{n_s}	0.1902	0.1848	0.1707	0.1665
$C_{Y_{sa}}$	-0.1214	-0.1088	-0.1082	-0.1026
$C_{l_{sa}}$	-0.2993	-0.2840	-0.2748	-0.2625
$C_{n_{sa}}$	-0.0458	-0.0411	-0.03948	-0.03753

Note: Units are (1/rad).

Table 3.2.2 Trim Set 1 - Steady Roll Solution at Mach 0.9 (flexible aircraft).

	ASTROS* Results	MSC/NASTRAN Results	
	$q=1200 \text{ psf}$	$q=1200 \text{ psf}$	
Control Surface Rotation (Deg)	25.00	25.00	(User Input)
Yaw Angle (Deg)	-0.79	-1.05	(Computed)
Yaw Acceleration (Rad/s/s)	0.00	0.00	(User Input)
Roll Acceleration (Rad/s/s)	0.00	0.00	(User Input)
Yaw Rate (Deg/s)	0.00	0.00	(User Input)
Control Surface Rotation (Deg)	1.29	1.18	(Computed)

<i>Roll Rate (Deg/s)</i>	-0.821	-0.745	<i>(Computed)</i>
<i>Side-Slip Acceleration (Rad/s/s)</i>	0.00	0.00	<i>(User Input)</i>

Table 3.2.3 Trim Set 2 - Abrupt Roll Solution at Mach 0.9 (flexible aircraft).

	ASTROS* Results	MSC/NASTRAN Results	
	q=1200 psf	q=1200 psf	
<i>Control Surface Rotation (Deg)</i>	25.00	25.00	<i>(User Input)</i>
<i>Yaw Angle (Deg)</i>	-3.78	-3.61	<i>(Computed)</i>
<i>Yaw Acceleration (Rad/s/s)</i>	0.00	0.00	<i>(User Input)</i>
<i>Roll Acceleration (Rad/s/s)</i>	-155	-143	<i>(Computed)</i>
<i>Yaw Rate (Deg/s)</i>	0.00	0.00	<i>(User Input)</i>
<i>Control Surface Rotation (Deg)</i>	0.61	0.63	<i>(Computed)</i>
<i>Roll Rate (Deg/s)</i>	0.00	0.00	<i>(User Input)</i>
<i>Side-Slip Acceleration (Rad/s/s)</i>	0.00	0.00	<i>(User Input)</i>

• ***Input Data Listing:***

Listing 2.7 Input Data for the Forward Swept Wing in Level Flight (HA144D).

```

ASSIGN DATABASE HA144D PASS NEW DELETE
SOLUTION
TITLE - ZAERO TRIM CASE (HA144D): FORWARD SWEPT WING WITH VERTICAL TAIL
SUBTITLE - SUBSONIC (M=0.9) LATERAL STABILITY DERIVATIVES
ANALYZE
  BOUNDARY MPC-100,SPC-2,SUPPORT-20
  LABEL = ANTISSYMMETRIC FLIGHT CONDITIONS, ZAERO MODULE AERODYNAMICS
  SAERO ANTISSYMMETRIC ( TRIM-1 )
  PRINT TRIM
  SAERO ANTISSYMMETRIC ( TRIM-2 )
  PRINT TRIM

END
BEGIN BULK
$...1...|...2...|...3...|...4...|...5...|...6...|...7...|...8...|...9...|...10...
GRID  90      15.    0.    0.
GRID  97      0.    0.    0.
GRID  98      10.   0.    0.
GRID  99      20.   0.    0.
GRID 100      30.   0.    0.

$           * WING GRID *
$           $           $           $
$     ID    CP     X1      X2      X3      CD      PS      SEID
$     GRID 111      24.61325 +5.    0.
$     GRID 110      27.11325 +5.    0.
$     GRID 112      29.61325 +5.    0.
$     GRID 121      18.83975+15.   0.
$     GRID 120      21.33975+15.   0.
$     GRID 122      23.83975+15.   0.

$           * VERTICAL FIN *
$     GRID 310      32.86667    5.
$     GRID 311      30.3867     5.
$     GRID 312      35.3867     5.

$     CBAR 310      301      100     310     0.     0.     1.
$     PBAR 301      1.       .75     .0866806 1.     .23148     +PB2
$     +PB2  .5       3.       .5      -3.     -.5      3.     -.5     -3.     +PB3
$     +PB3  0.
$     RBAR 100      311      310     311     123456
$     RBAR 100      312      310     312     123456

```



```

$                                * WING MACROELEMENTS *
$                                $                                $
$ FORWARD SWEEP WING - 4 x 8 AERO BOXES EVENLY CUT
$                                $                                $
$      WID      LABEL     ACOORD    NSPAN    NCHORD    LSPAN    ZTAIC    PAFOIL7
$      CAERO7  1100      WING        9        5        0        1101    +CA1
$      XRL      YRL      ZRL      RCH      LRCHD    ATTCHR
$      +CA1    25.      0.      10.      0.      0.      0.      +CA2
$      XRT      YRT      ZRT      TCH      LTCHD    ATTCHT
$      +CA2   13.4529920.  0.      10.      0.      0.      0.      +
$                                $                                $
$ A PAFOIL7 CARD IS USED TO DEFINE THE AIRFOIL CROSS-SECTION FOR THE
$ ZONA7U METHOD.  LIKE THE DMI INPUT USED IN THE HAI44A OF THE
$ MSC/NASTRAN AEROELASTIC USER GUIDE, THE PAFOIL7 WILL ACCOUNT FOR THE
$ DIFFERENCES BETWEEN TEST AND THEORY (WING CAMBER EFFECTS).
$                                $                                $
$      ID      ITAX     ITHR     ICAMR     RADR     ITHT     ICAMT     RADT
$      PAFOIL7 1101    1102    1103    1104     0.0    1103    1104     0.0
$      AEFACT  1102    0.0     50.0    100.0
$      AEFACT  1103    0.0     0.0     0.0
$ AEFACT TO DESCRIBE THE AIRFOIL CAMBER (0.1 DEG INCIDENCE)
$      AEFACT  1104    0.0    -0.0872  -0.1744
$                                $                                $
$ CANARD - 4 x 2 AERO BOXES EVENLY CUT
$                                $                                $
$      CAERO7 1000      CANARD      3        5        0        +CA1
$      +CA1    10.      0.0     0.0     10.      0.      0.      +CA2
$      +CA2    10.      5.0     0.0     10.      0.      0.      +
$                                $                                $
$ DEFINITION OF VERTICAL FIN 4 x 4 EVENLY CUT
$                                $                                $
$      CAERO7 3100      FIN        5        5        0        +CA1
$      +CA1   30.7735  0.      10.      10.      0.      0.      +CA2
$      +CA2   25.      0.      0.      10.      0.      0.      +
$                                $                                $
$ TWO CONTROL SURFACES ARE DEFINED: AN AILERON ON THE MAIN WING ( AERO
$ BOXES 1119, 1123, 1127 AND 1131 ) AND A RUDDER ON THE VERTICAL TAIL
$ ( AERO BOXES 3103, 3107, 3111 AND 3115). Y-AXES OF THE CONTROL SURFACES
$ HINGE LINES ARE SPECIFIED VIA THE CORD2R BULK DATA CARDS.
$                                $                                $
$      LABEL      TYPE      CID      SETK      SETG
$      AESURFZ AILERON ANTISYM 110      2000
$      SETID      MACROID BOX1      BOX2      ETC
$      PANLST2 2000    1100    1119    1123    1127    1131
$                                $                                $
$      AESURFZ RUDDER ANTISYM 301      3000
$                                $                                $
$      PANLST2 3000    3100    3103    3107    3111    3115
$                                $                                $
$      CID      RID      A1      A2      A3      B1      B2      B3
$      CORD2R 110      0      26.7265 10.      0.      26.7265 10.      -10.      +CORD1
$      C1      C2      C3
$      +CORD1  36.7265 15.7735 0.
$                                $                                $
$      CORD2R 301      0      32.5      0.      0.      32.5      -10.      0.      +CORD1
$      +CORD1  22.5      0.      5.7735
$                                $                                $
$                                * SURFACE SPLINE FIT ON THE WING *
$                                $                                $
$ THE INFINITE PLATE SPLINE METHOD IS USED TO SPLINE THE WING AERO
$ BOXES TO THE WING STRUCTURE GRIDS.  THE SETK BULK DATA CARD REFERS
$ TO A PANLST1 BULK DATA CARD THAT SPLINES ALL OF THE WING AERO BOXES
$ TO THE GRID POINTS SPECIFIED IN THE SET1 (SID=1105) BULK DATA CARD.
$                                $                                $
$      EID      MODEL      CP      SETK      SETG      DZ      EPS
$      SPLINE1 1601      WING      1100    1105     0.0
$                                $                                $
$      SETID      MACROID BOX1      BOX2
$      PANLST1 1100    1100    1100    1131
$                                $                                $
$      SID      G1      G2      ETC
$      SET1   1105    100     110     111     112     120     121     122
$                                $                                $
$ THE BEAM SPLINE METHOD IS USED ON THE CANARD.  THE SETK ENTRY REFERS
$ TO THE PANLST2 BULK DATA CARD PREVIOUSLY DEFINED FOR THE AESURFZ BULK
$ DATA CARD LISTING ALL AERO BOXES LOCATED ON THE CANARD.
$                                $                                $
$      EID      MODEL      SETK      SETG      DZ      DTOR      CID      DTHX
$      SPLINE2 1501      CANARD    1000    1000     0.0      1.0      1      -1.0      +SP1
$      DTHY
$      +SP1   -1.0
$                                $                                $
$      PANLST2 1000    1000    1000    1001    1002    1003    1004    1005    +P1
$      +P1   1006    1007
$                                $                                $
$      SID      G1      G2      ETC
$      SET1   1000    98      99
$ CORD2R DEFINES THE Y-AXIS FOR THE BEAM SPLINE
$      CID      CS      A1      A2      A3      B1      B2      B3
$      CORD2R 1      0      15.      0.      0.      15.0      0.      10.      +CRD2
$      C1      C2      C3
$      +CRD2  20.      0.      10.
$                                $                                $
$ VERTICAL FIN SPLINE TO STRUCTURE GRIDS (100, 310, 311, 312)
$                                $                                $

```


VOLUME II

Analysis and Optimization Cases

Table of Contents

Volume II *Analysis and Optimization Cases*

	Page
4.0 ANALYSIS AND OPTIMIZATION CASES	1
 <i>GAF WING MODEL</i>	
4.1 <u>Case 1.a: GAF (Generalized Advanced Fighter) Wing Model Analysis</u>	1
4.1.1 Structural Configuration and Static Analysis	1
4.1.2 Aerodynamic Configuration and Analysis by ENSAERO	2
4.1.3 Normal Modes Analysis Using ASTROS*	2
4.1.4 Flutter Analysis	3
4.2 <u>Case 1.b: GAF (Generalized Advanced Fighter) Wing Model Optimization</u>	23
4.2.1 Static Optimization	23
4.2.2 Normal Modes Optimization	23
4.2.3 Design Optimization for Static Loads and Normal Modes	23
4.2.4 Flutter Optimization	24
4.2.5 Multidisciplinary Design Optimization for Statics, Normal Modes, and Flutter	24
 <i>DAST WING MODEL</i>	
4.3 <u>Case 2.a: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Analysis</u>	32
4.3.1 Structural Configuration and Static Aeroelastic Analysis	32
4.3.2 Aerodynamic Configuration and Analysis by ENSAERO	34
4.3.3 Normal Modes Analysis Using ASTROS*	34
4.3.4 Flutter Analysis	35
4.4 <u>Case 2.b: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Optimization</u>	49
4.4.1 Static Aeroelastic Optimization	49
4.4.2 Normal Modes Optimization	49
4.4.3 Multidisciplinary Design Optimization for Static Aeroelasticity and Normal Modes	49

Table of Contents (cont.)

	Page
<i>AAW WING MODEL</i>	
4.5 <u>Case 3.a: AAW (ASTROS* Aeroelastic Wing) Model Analysis</u>	59
4.5.1 Structural Configuration and Static Aeroelastic Analysis	59
4.5.2 Aerodynamic Configuration and Analysis by ENSAERO	60
4.5.3 Normal Modes Analysis Using ASTROS*	60
4.5.4 Flutter Analysis	61
4.6 <u>Case 3.b: AAW (ASTROS* Aeroelastic Wing) Model Optimization</u>	79
4.6.1 Static Aeroelastic Optimization	79
4.6.2 Normal Modes Optimization	79
4.6.3 Multidisciplinary Design Optimization for Static Aeroelasticity and Normal Modes	79

List of Tables

Table No.	Description	Page
4.1.1	Weight Data Output of GAF Model.	4
4.1.2	Results of Normal Modes Analysis of GAF Model.	4
4.1.3	Results of Flutter Analyses of GAF Model.	5
4.2.1	Design Iteration History of GAF Model: Structural Optimization for Static Loads.	25
4.2.2	Design Iteration History of GAF Model: Structural Optimization for Normal Modes by ASTROS*.	25
4.2.3	Design Iteration History of GAF Model: Structural Optimization for Statics and Normal Modes by ASTROS*.	26
4.2.4	Final Design Variables of GAF Model: Structural Optimization for Statics and Normal Modes by ASTROS*.	26
4.2.5	Design Iteration History of GAF Model: Structural Optimization with Flutter Constraint at $M = 0.85$.	28
4.2.6	Design Iteration History of GAF Model: Multidisciplinary Design Optimization (Stress + Displacement + Natural Frequency + Flutter Speed) at $M = 0.85$.	28
4.2.7	Final Design Variable Values of GAF Model: Multidisciplinary Design Optimization (Stress + Displacement + Natural Frequency + Flutter Speed) at $M = 0.85$.	29
4.3.1	Weight Data Output of DAST Model.	36
4.3.2	Non-Dimensional Longitudinal Stability Derivatives of DAST Model: 10g Pull-up Maneuver, $M = 0.8$, by ZONA6 of ASTROS*, for Rigid and Flexible Structure.	36
4.3.3	Trim Parameters of DAST Model: 10g Pull-up Maneuver, $M = 0.80$, by ZONA6 of ASTROS*, for Rigid and Flexible Structure	37
4.3.4	Pressure Distribution of DAST Model: 10g Pull-up Maneuver, $M = 0.80$, by ZONA6 of ASTROS*, for Rigid Structure.	37

List of Tables (cont.)

Table No.	Description	Page
4.3.5	Results of Normal Modes Analysis of DAST Model	38
4.3.6	Results of Flutter Analyses of DAST Model	38
4.4.1	Design Iteration History of DAST Model: Structural Optimization for Static Aeroelasticity, 10g Pull-up Maneuver, $M = 0.80$, by ZONA6 of ASTROS*.	51
4.4.2	Design Iteration History of DAST Model: Structural Optimization for Normal Modes.	51
4.4.3	Design Iteration History of DAST Model: Multidisciplinary Design Optimization (Static Aeroelasticity + Normal Modes), at $M = 0.80$.	52
4.4.4	Final Design Variable Values of DAST Model: Disciplinary Design Optimization (Static Aeroelasticity + Normal Modes), at $M = 0.80$.	52
4.5.1	Non-Dimensional Longitudinal Stability Derivatives of AAW Model: 7g Pull-up Maneuver, $M = 0.85$, by ZONA6 of ASTROS*, for Rigid and Flexible Structure.	62
4.5.2	Non-Dimensional Longitudinal Stability Derivatives of AAW Model: 7g Pull-up Maneuver, $M = 0.85$, by ZTAIC of ASTROS*, for Rigid and Flexible Structure.	62
4.5.3	Non-Dimensional Longitudinal Stability Derivatives of AAW Model: 7g Pull-up Maneuver, $M = 1.15$, by ZONA7 of ASTROS*, for Rigid and Flexible Structure.	62
4.5.4	Non-Dimensional Longitudinal Stability Derivatives of AAW Model: 7g Pull-up Maneuver, $M = 3.0$, by ZONA7U of ASTROS*, for Rigid and Flexible Structure.	63
4.5.5	Trim Parameters of AAW Model: 7g Pull-up Maneuver, $M = 0.85$, by ZONA6 of ASTROS*, for Rigid and Flexible Structure.	63
4.5.6	Trim Parameters of AAW Model: 7g Pull-up Maneuver, $M = 0.85$, by ZTAIC of ASTROS*, for Rigid and Flexible Structure.	63
4.5.7	Trim Parameters of AAW Model: 7g Pull-up Maneuver, $M = 1.15$, by ZONA7 of ASTROS*, for Rigid and Flexible Structure.	64

List of Tables (cont.)

Table No.	Description	Page
4.5.8	Trim Parameters of AAW Model: 7g Pull-up Maneuver, $M = 3.0$, by ZONA7U of ASTROS*, for Rigid and Flexible Structure.	64
4.5.9	Results of Normal Modes Analysis of AAW Model.	64
4.5.10	Results of Flutter Analyses of AAW Model.	65
4.6.1	Design Iteration History of AAW Model: Structural Optimization for Static Aeroelasticity, 7g Pull-up Maneuver, $M = 0.85$, by ZONA6 of ASTROS*.	80
4.6.2	Design Iteration History of AAW Model: Structural Optimization for Normal Modes.	80
4.6.3	Design Iteration History of AAW Model: Multidisciplinary Optimization (Static Aeroelasticity + Normal Modes), $M = 0.85$, by ZONA6 of ASTROS*.	81
4.6.4	Final Design Variable Values of AAW Model: Multidisciplinary Optimization (Static Aeroelasticity + Normal Modes), $M = 0.85$, by ZONA6 of ASTROS*.	81
4.6.5	Design Iteration History of AAW Model: Multidisciplinary Optimization (Static Aeroelasticity + Normal Modes), $M = 1.15$, by ZONA7 of ASTROS*.	84
A.1	Summary of Analyses and Design Optimizations of Aircraft Wing Models.	90

List of Figures

Figure No.	Description	Page
4.1.1	Structural Configuration of GAF Wing by FEM.	5
4.1.2	Deflection Shape of GAF Model by Static Loads.	5
4.1.3	Aerodynamic Configuration of GAF Model and Aerodynamic Panels.	5
4.1.4.a	Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.85$, AoA = 0.0° , by ENSAERO.	6
4.1.4.b	Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.85$, AoA = 5.0° , by ENSAERO.	7
4.1.4.c	Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.90$, AoA = 0.0° , by ENSAERO	7
4.1.4.d	Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.90$, AoA = 5.0° , by ENSAERO.	8
4.1.5	Normal Modes of GAF Model.	8
4.1.6.a	Generalized Unsteady Aerodynamic Coefficients Q_{1j} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*.	9
4.1.6.b	Generalized Unsteady Aerodynamic Coefficients Q_{2j} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*.	9
4.1.7.a	Generalized Unsteady Aerodynamic Coefficients Q_{1j} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.	10
4.1.7.b	Generalized Unsteady Aerodynamic Coefficients Q_{2j} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.	10
4.1.8	V-f and V-g Plots of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* (Flutter Speed = 17,337 <i>in/sec</i> , Flutter Speed = 14.3 <i>Hz</i>).	11
4.1.9	Root-Locus Plot of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* (Flutter Speed = 15,888, <i>in/sec</i> , Flutter Frequency = 17.32 <i>Hz</i>).	12

List of Figures (cont.)

Figure No.	Description	Page
4.1.10.a	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS*.	13
4.1.10.b	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS*.	13
4.1.11.a	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* and Approximated by Minimum-State Method.	14
4.1.11.b	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* and Approximated by Minimum-State Method.	14
4.1.12	V-f and V-g Plots of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* (Flutter Speed = 18,172 <i>in/sec</i> , Flutter Frequency = 18.1 Hz).	15
4.1.13	Root-Locus Plot of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* (Flutter Speed = 16,581 <i>in/sec</i> , Flutter Frequency = 15.6 Hz).	16
4.1.14	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 1.15$, by ZONA7 of ASTROS*.	17
4.1.15	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 1.15$, by ZONA7 of ASTROS* and Approximated by Minimum-State Method.	17
4.1.16	V-f and V-g Plots of GAF Model: $M = 1.15$, by ZONA7 of ASTROS* (Flutter Speed = 20,776 <i>in/sec</i> , Flutter Frequency = 19.8 Hz).	18
4.1.17	Root-Locus Plot of GAF Model: $M = 1.15$, by ZONA7 of ASTROS* (Divergence Speed = 14,170 <i>in/sec</i> , no Flutter).	19
4.1.18	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 3.0$, by ZONA7U of ASTROS*.	20
4.1.19	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 3.0$, by ZONA7U of ASTROS* and Approximated by Minimum-State Method.	20
4.1.20	V-f and V-g Plots of GAF Model: $M = 3.0$, by ZONA7U of ASTROS* (Flutter Speed = 31,743 <i>in/sec</i> , Flutter Frequency = 21.1 Hz).	21

List of Figures (cont.)

Figure No.	Description	Page
4.2.21	Root-Locus Plot of GAF Model: $M = 3.0$, by ZONA7U of ASTROS* (Flutter Speed = 31,536 in/sec, Flutter Frequency = 21.3 Hz).	22
4.2.1	Design Variables and Numbering of GAF Model.	30
4.2.2	Iteration History of Structural Design Optimization of GAF Model: Statics, Normal Modes, and Both Disciplines (S + N) by ASTROS*.	30
4.2.3	Iteration History of Structural Design Optimization of GAF Model: Flutter Discipline at $M = 0.85$, by Root-Locus Method.	31
4.2.4	Design Iteration History of GAF Model: Multidisciplinary Design Optimization (Constraints on Stress, Displacement, Natural Frequency, Flutter Speed).	31
4.3.1	Structural Configuration of DAST Model by FEM.	39
4.3.2	Pressure Distribution of DAST Model: 10g Pull-up Trim Condition, $M = 0.8$, by ZONA6 of ASTROS*.	39
4.3.3	Deflection Shape of DAST Model: 10g Pull-up Trim Condition, $M = 0.8$, by ZONA6 of ASTROS*.	40
4.3.4	Aerodynamic Configuration of DAST Model.	40
4.3.5.a	Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.70$, AoA = 0.0°, by ENSAERO.	41
4.3.5.b	Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.70$, AoA = 5.0°, by ENSAERO.	41
4.3.5.c	Aerodynamic Pressure Coefficients of DAST Model for Euler Flow: $M = 0.80$, AoA = 0.0°, by ENSAERO.	42
4.3.5.d	Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.80$, AoA = 0.0°, by ENSAERO.	42
4.3.6	Normal Modes of DAST Model.	43

List of Figures (cont.)

Figure No.	Description	Page
4.3.7	Generalized Unsteady Aerodynamic Loads of DAST Model: $M = 0.80$, by ZONA6 of ASTROS*.	44
4.3.8	Generalized Unsteady Aerodynamic Coefficients Q_{ij} of DAST Model: $M = 0.80$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.	44
4.3.9	V-f and V-g Plots of DAST Model: $M = 0.80$, by ZONA6 of ASTROS* (Flutter Speed = 14,358 in/sec, Flutter Frequency = 48.67 Hz).	45
4.3.10	Root-Locus Plot of DAST Model: $M = 0.80$, ZONA6 of ASTROS* (Flutter Speed = 13,490 in/sec, Flutter Frequency = 36.3 Hz).	46
4.3.11	V-f and V-g Plots of DAST Model: $M = 0.80$, by ZTAIC of ASTROS* (Flutter Speed = 11,800 in/sec, Flutter Frequency = 56.0 Hz).	47
4.3.12	Root-Locus Plot of DAST Model: $M = 0.80$, by ZTAIC of ASTROS* (Flutter Speed = 12,893 in/sec, Flutter Frequency = 49.3 Hz).	48
4.4.1	Structural Design Variables and Numbering of DAST Model	58
4.4.2	Iteration History of Design Optimization of DAST Model for Static Aeroelasticity, Normal Modes, and Multiple Disciplines (S + N).	58
4.5.1	Structural Configuration of AAW Model by FEM.	66
4.5.2	Aerodynamic Paneling of AAW Model	66
4.5.3	Aerodynamic Pressure Distribution of AAW Main Wing Model: 7g Pull-up Trim Condition, $M = 0.85$, AoA = 6.974°, by ZONA6 of ASTROS*	67
4.5.4	Deflection Shape of AAW Model: 7g Pull-up Trim Condition, $M = 0.85$, by ZONA6 of ASTROS*.	67
4.5.5.a	Aerodynamic Pressure Coefficients of AAW Model for Navier-Stokes Flow: $M = 0.85$, AoA = 0.0°, by ENSAERO.	68
4.5.5.b	Aerodynamic Pressure Coefficients of AAW Model for Navier-Stokes Flow: $M = 0.85$, AoA = 8.6°, by ENSAERO.	68

List of Figures (cont.)

Figure No.	Description	Page
4.5.5.c	Aerodynamic Pressure Coefficients of AAW Model for Navier-Stokes Flow: $M = 0.95$, AoA = 0.0° , by ENSAERO.	69
4.5.5.d	Aerodynamic Pressure Coefficients of AAW Model for Navier-Stokes Flow: $M = 1.05$, AoA = 0.0° , by ENSAERO.	69
4.5.6	Normal Modes of AAW Model.	70
4.5.7	V-f and V-g Plots of AAW Model: $M = 0.85$, by ZONA6 of ASTROS* (Flutter Speed = 11,281 <i>in/sec</i> , Flutter Frequency = 14.80 Hz).	41
4.5.8	Root-Locus Plot of AAW Model: $M = 0.85$, by ZONA6 of ASTROS* (Flutter Speed = 10,978 <i>in/sec</i> , Flutter Frequency = 14.77 Hz).	72
4.5.9	V-f and V-g Plots of AAW Model: $M = 0.85$ by ZTAIC of ASTROS* (Flutter Speed = 10,714 <i>in/sec</i> , Flutter Frequency = 14.94 Hz).	73
4.5.10	Root-Locus Plot of AAW Model: $M = 0.85$, by ZTAIC of ASTROS* (Flutter Speed = 10,538 <i>in/sec</i> , Flutter Frequency = 14.73 Hz).	74
4.5.11	V-f and V-g Plots of AAW Model: $M = 1.15$, by ZONA7 ASTROS* (Flutter Speed = 11,088 <i>in/sec</i> , Flutter Frequency = 14.90 Hz).	75
4.5.12	Root-Locus Plot of AAW Model: $M = 1.15$, by ZONA7 ASTROS* (Flutter Speed = 11,308 <i>in/sec</i> , Flutter Frequency = 14.9 Hz).	76
4.5.13	V-f and V-g Plots of AAW Model: $M = 3.0$, by ZONA7U of ASTROS* (Flutter Speed = 58,768 <i>in/sec</i> , Flutter Frequency = 8.55 Hz).	77
4.5.14	Root-Locus Plot of AAW Model: $M = 3.0$, by ZONA7U of ASTROS* (No Flutter).	78
4.5.15	Design Variables and Numbering of AAW Inboard Wing Model.	85
4.5.16	Iteration History of Design Optimization of AAW Model for Static Aeroelasticity, Normal Modes, and Multiple Disciplines (S+N): $M = 0.85$, by ZONA6 of ASTROS*.	85

List of Figures (cont.)

Figure No.	Description	Page
4.5.17	Iteration History of Design Optimization of AAW Model for Static Aeroelasticity, Normal Modes, and Multiple Disciplines (S+N): $M = 1.15$ by ZONA7 of ASTROS*.	86

4.0 ANALYSIS AND OPTIMIZATION CASES

GAF WING MODEL

4.1 Case 1.a: GAF (Generalized Advanced Fighter) Wing Model Analysis

- *Purpose:* To test a public domain model in static, normal modes, and flutter analysis.

- *Description of input and results:*

The GAF model was an aircraft wing model composed of skins, spars, and ribs. A leading edge flap and a trailing edge control surface were attached to the main wing box. The wing was fixed at the root. More details about the model, the test cases, and their application to this model are given in Appendix A.

4.1.1 GAF Structural Configuration and Static Analysis

The structural configuration of the wing in the form of a FEM model is shown in Fig 4.1.1. Skins, spars, and ribs were modeled by **CQUAD4** elements, and **CELAS2** elements were used to connect the control surfaces to the wing box. A summary of the number of elements and grid points is shown in the following:

NUMBER OF GRID POINTS	288
NUMBER OF ELEMENTS	530
CROD	136
CELAS2	2
CQUAD4	371
RBE2	21

A static analysis was performed for applied static loads, distributed at given grid points, in the vertical direction, using **FORCE** cards. The wing was fixed as a cantilever by **SPC** cards. The identification number of the **FORCE** cards in the bulk data deck was called by a **STATIC** card and the ID number of the **SPC** cards in the bulk data deck was called by a **BOUNDARY** card in the case control deck. Displacements at grid points and stresses in elements were calculated, and the output print of these data was controlled by a **PRINT** card in the case control deck.

The weight of this structure was *671.60 lbs*, and the associated weight data of the initial structure are shown in Table 4.1.1. To print out these weight data, a **GPWG** bulk data card was entered in the bulk data deck, and the associated ID number was called in the **PRINT** card of the case control deck. The six components of the displacement were printed. The maximum vertical displacement at the wing tip was *27.068 in.* All stress components and the principal stresses were printed. The maximum principal stress in all elements was *64,000 psi*. The data were used

later as constraints in the structural design optimizations. The deformed shape of the structure is shown in Fig 4.1.2.

4.1.2 Aerodynamic Configuration and Analysis by ENSAERO

Aerodynamic analyses of the wing were performed by the CFD code, ENSAERO. The steady aerodynamic pressure coefficients calculated here were used later as input data for ZTAIC of ASTROS*. The steady aerodynamic pressure coefficients were calculated for Euler flow and also for Navier-Stokes flow, with the results of the Euler flow, via a RESTART statement. For all cases, the Reynolds number was 10,000,000 and spanwise and normal viscous terms were used. For turbulence, the Baldwin-Lomax turbulence model was used, and, for correction for vortex flow, Degani-Schiff modeling was used. Iteration indices were less than 1.0E-09 and iteration numbers were about 500 for the Euler flow and then more than 500 additional iterations for the Navier-Stokes flow. The aerodynamic configuration of the wing is shown in Fig 4.1.3. The total number of grid points was 151 x 44 x 34 in the x-, y-, and z- directions, respectively. The number of grid points on the wing was 61 x 34 on both lower and upper surfaces. The total number of iterations for Euler flow plus Navier-Stokes flow was about 1000, and the total CPU time on the CRAY computer was about 2 hours. In the transonic region belonged $M = 0.85$, convergence was slower than in the other regions, and more iterations were needed.

Two Mach number cases, $M = 0.85$ and $M = 0.90$, and two angle-of-attack (α) cases, $\alpha = 0.0^\circ$ and $\alpha = 5.0^\circ$, for a total of four cases were investigated. The results of the calculated aerodynamic pressure coefficients for Euler flow and for Navier-Stokes flow are shown in Fig 4.1.4. In Euler flow, the strength of the shock was larger than in Navier-Stokes flow. This seems to come about because of the viscous effects in the Navier-Stokes flow. The computed points were as follows:

- (1) $M = 0.85, \alpha = 0.0^\circ$ (Navier-Stokes Flow)
- (2) $M = 0.85, \alpha = 5.0^\circ$ (Navier-Stokes Flow)
- (3) $M = 0.90, \alpha = 0.0^\circ$ (Navier-Stokes Flow)
- (4) $M = 0.90, \alpha = 5.0^\circ$ (Navier-Stokes Flow)

Fig 4.1.4 shows that the flows were in the transonic regime at $M = 0.85$ and $M = 0.90$.

4.1.3 Normal Modes Analysis Using ASTROS*

Natural frequencies, the associated modes shapes, and the generalized stiffness and mass matrices were calculated in the normal modes discipline. For the calculation of the eigenvalues, the INV (Inverse Power) method was used. This method was selected via the EIGR bulk data card and the ID number of this card was called by METHOD in the BOUNDARY card in the case control deck. ASET cards were used to save computing time and neglect motions other than vertical. Mode normalization was used in MASS because it was convenient that the components of the generalized mass were unity.

Normal modes data for 8 modes from the lowest mode up to 90.0 Hz were calculated. The lowest eight natural frequencies of the GAF model were 10.22, 30.97, 35.89, 49.74, 58.04, 65.51, 76.09, and 84.75 Hz. The results are shown in Table 4.1.2 and the mode shapes are presented in

Fig 4.1.5. The first and second modes were bending modes and the third mode was the first torsion mode. These data were later used in the flutter calculations. The lowest natural frequency, 10.22 Hz, was used as a constraint in normal modes design optimization.

4.1.4 Flutter Analysis

Flutter analyses were performed by the K-method in ASTROS*, the P-K method in MSC/NASTRAN, and the root-locus method outside of these codes in three aerodynamic regimes: transonic, low supersonic, and high supersonic/hypersonic. Mach numbers $M=0.85$, 1.15, and 3.0 were selected to calculate flutter speeds. ZONA6 and ZTAIC of ASTROS* were used to calculate generalized unsteady aerodynamic loads at $M=0.85$, and ZONA7 and ZONA7U were used for $M=1.15$ and $M=3.0$, respectively. The results are compared with those for MSC/NASTRAN and the root-locus method in Table 4.1.3. The generalized unsteady aerodynamic loads calculated by ASTROS* were used in the root-locus method. Two CAERO7 cards were used: the CAERO7, 100001 card represented the wing with 15 x 11 aerodynamic boxes. The CAERO7, 200001 card represented the fuselage region with 15 x 2 aerodynamic boxes.

The generalized unsteady aerodynamic loads at $M=0.85$ were calculated by ZONA6. There were 8×8 generalized aerodynamic coefficient terms, Q_{ij} , for each reduced frequency k . The plots of the real and imaginary parts of Q_{ij} and Q_{2j} ($j = 1, 2,.. 8$) versus k are shown in Fig 4.1.6. Generalized unsteady aerodynamic loads were also approximated by the minimum-state method at $M=0.85$. In Fig 4.1.7, the Q_{ij} and Q_{2j} calculated by ZONA6 are shown as real part versus imaginary part by black and solid lines and the approximate Q_{ij} and Q_{2j} calculated by the minimum-state method are shown by color and dotted lines. The V-f and V-g plots for the results by ZONA6 of ASTROS* are shown in Fig 4.1.8. The flutter speed was 17,337 in/sec and the flutter frequency was 14.3 Hz. The root-locus plot to calculate the flutter speed is shown in Fig 4.1.9. The flutter speed was 15,888 in/sec and the flutter frequency was 17.3 Hz. The plots of Figs 4.1.10 – 4.1.13 are for the results by ZTAIC at $M=0.85$. The flutter speed and flutter frequency were 18,172 in/sec and 18.1 Hz, respectively, by the K-method, and 16,581 in/sec and 15.6 Hz by the root-locus method. It is normally expected that the nonlinear flutter speed is lower than the linear flutter speed in the transonic regime. However, for the case of the GAF model, the nonlinear flutter speed was slightly higher than the linear flutter speed. The plots of Figs 4.1.14 – 4.1.17 are for the results by ZONA7 at $M=1.15$. The flutter speed and flutter frequency were 20,776 in/sec and 19.8 Hz, respectively, by the K-method, while a divergence speed 14,170 in/sec was obtained by the root-locus method. The plots of Figs 4.1.18 – 4.1.21 are for the results by ZONA7U at $M=3.0$. The flutter speed and flutter frequency were 31,743 in/sec and 21.1 Hz, respectively, by the K-method and 33,536 in/sec and 21.3 Hz by the root-locus method. For subsonic flow at $M=0.85$ and supersonic flow at $M=1.15$, the root-locus results were close to the MSC/ NASTRAN results as shown in Table 4.1.3.

Table 4.1.1 Weight Data Output of GAF Model.

OUTPUT FROM GRID POINT WEIGHT GENERATOR
 REFERENCE POINT = 1
 XO = 3.685130E+01, YO = 0.000000E+00, ZO = 2.084700E+00
 M O

* 6.7160E+02 0.000E+00 0.0000E+00 0.0000E+00 -1.405E+03 -4.1995E+04 *
 * 0.0000E+00 6.716E+02 0.0000E+00 1.4051E+03 0.000E+00 2.8357E+04 *
 * 0.0000E+00 0.000E+00 6.7160E+02 4.1995E+04 -2.835E+04 0.0000E+00 *
 * 0.0000E+00 1.405E+03 4.1995E+04 3.6085E+06 -2.140E+06 5.7740E+04 *
 *-1.4051E+03 0.000E+00 -2.8357E+04 -2.1406E+06 1.635E+06 8.8539E+04 *
 *-4.1995E+04 2.835E+04 0.0000E+00 5.7740E+04 8.853E+04 5.2324E+06 *

S

* 1.00000E+00 0.00000E+00 0.00000E+00 *
 * 0.00000E+00 1.00000E+00 0.00000E+00 *
 * 0.00000E+00 0.00000E+00 1.00000E+00 *

DIRECTION

MASS AXIS SYSTEM (S)	MASS	X-C.G.	Y-C.G.	Z-C.G.
X	6.71602E+02	0.00000E+00	6.25301E+01	-2.09224E+00
Y	6.71602E+02	4.22239E+01	0.00000E+00	-2.09224E+00
Z	6.71602E+02	4.22239E+01	6.25301E+01	0.00000E+00

Table 4.1.2 Results of Normal Modes Analysis of GAF Model.

Mode	Eigenvalue (rad/s ²)	Freq. (Hz.)	Generalized Mass	Generalized Stiffness
1	4.12692E+03	1.02243E+01	1.00000E+00	4.12692E+03
2	3.78674E+04	3.09708E+01	1.00000E+00	3.78674E+04
3	5.08536E+04	3.58906E+01	1.00000E+00	5.08536E+04
4	9.76608E+04	4.97371E+01	1.00000E+00	9.76608E+04
5	1.32991E+05	5.80406E+01	1.00000E+00	1.32991E+05
6	1.69421E+05	6.55094E+01	1.00000E+00	1.69421E+05
7	2.28595E+05	7.60945E+01	1.00000E+00	2.28595E+05
8	2.83559E+05	8.47504E+01	1.00000E+00	2.83559E+05

Table 4.1.3 Results of Flutter Analyses of GAF Model.

No	Mach	Method	Flutter Speed (in/sec)	F. Freq. (Hz)	Remarks
1	0.85	ZONA6	17,336	14.3	
		ZTAIC	18,172	18.1	
		MSC/NASTRAN	15,800	16.7	
		Root-locus (ZONA6)	15,888	17.3	
		Root-locus (ZTAIC)	16,581	15.6	
2	1.15	ZONA7	20,776	19.8	
		MSC/NASTRAN	14,500	0.0	Divergence
		Root-locus (ZONA7)	14,170	0.0	Divergence
3	3.0	ZONA7U	31,743	21.1	
		MSC/NASTRAN	36,100	22.0	
		Root-locus (ZONA7U)	33,536	21.3	

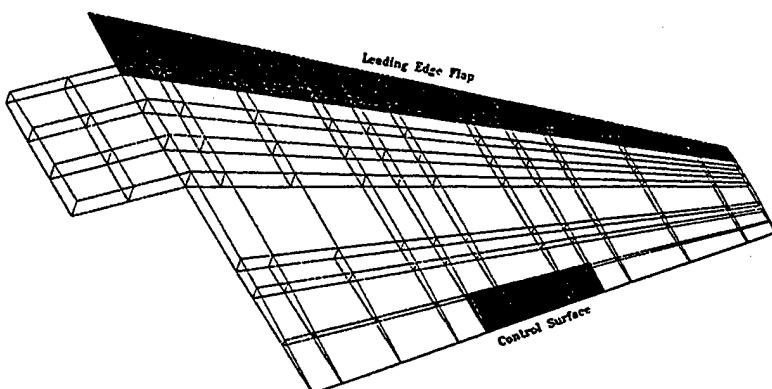


Figure 4.1.1 Structural Configuration of GAF Model by FEM.

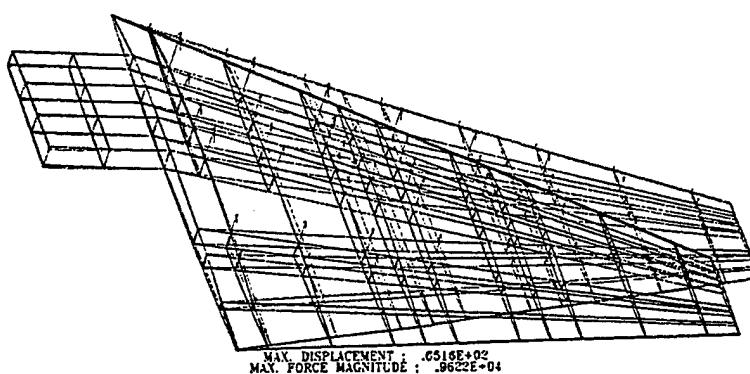


Figure 4.1.2 Deflection Shape of GAF Model for Static Loads.

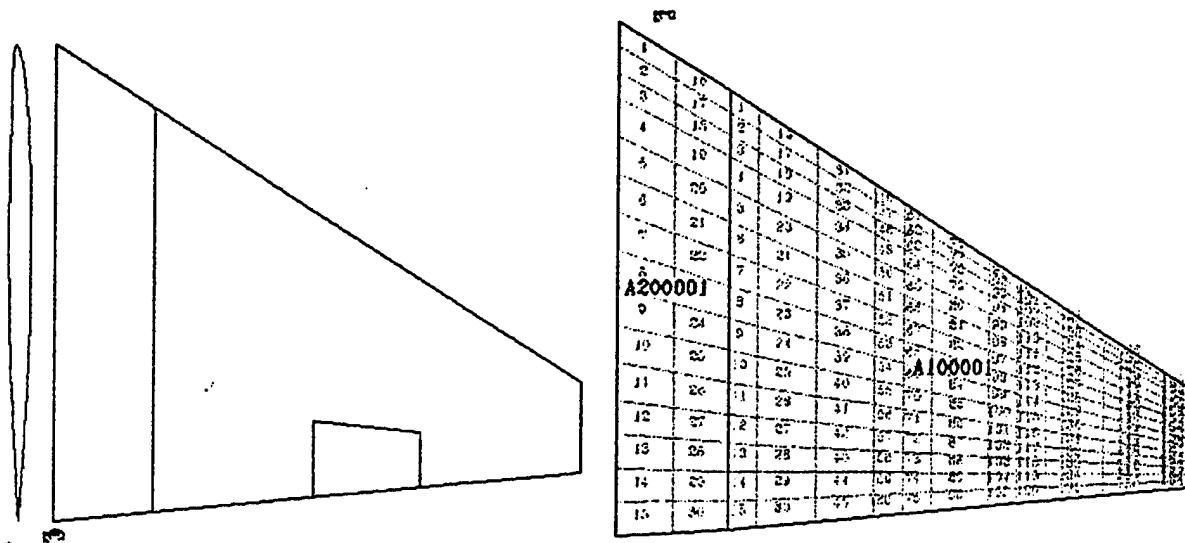


Figure 4.1.3 Aerodynamic Configuration of GAF Model and Aerodynamic Panels.

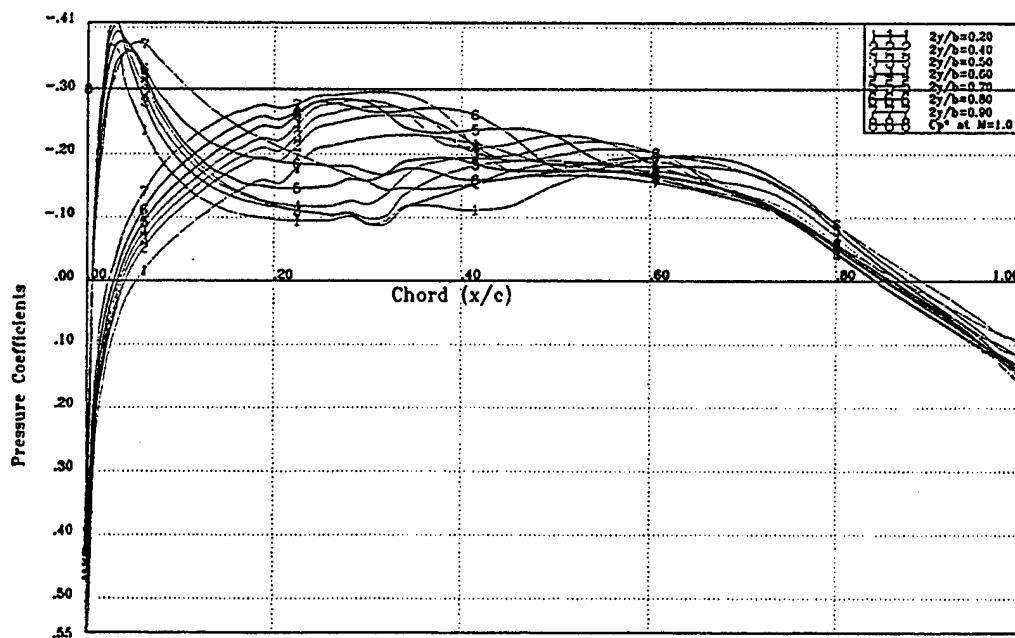


Figure 4.1.4.a Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.85$, $\text{AoA} = 0.0^\circ$, by ENSAERO.

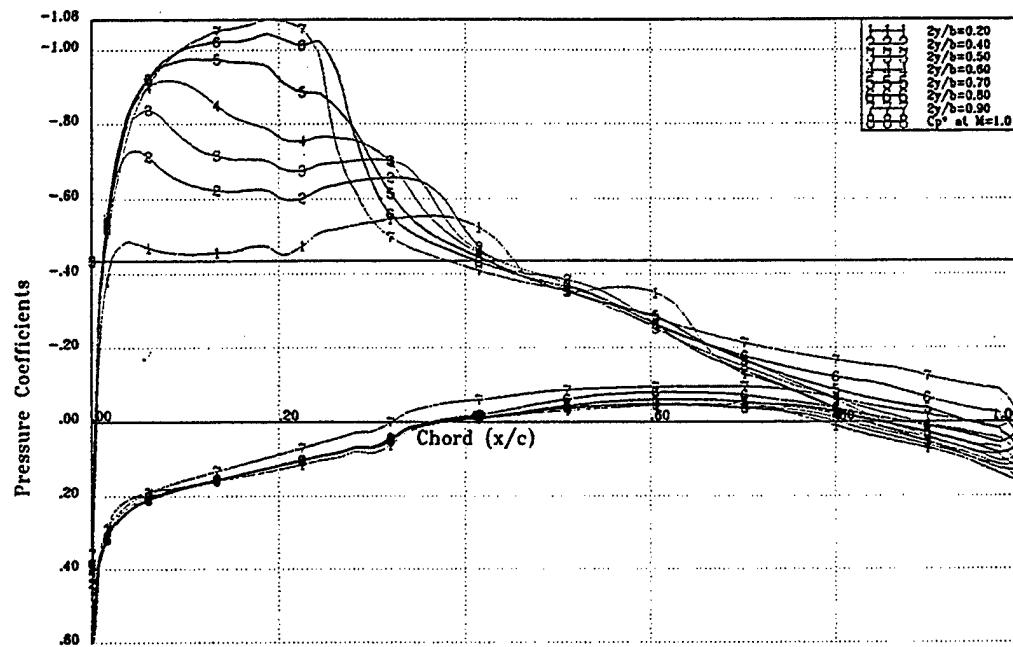


Figure 4.1.4.b Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.85$, $\text{AoA} = 5.0^\circ$, by ENSAERO.

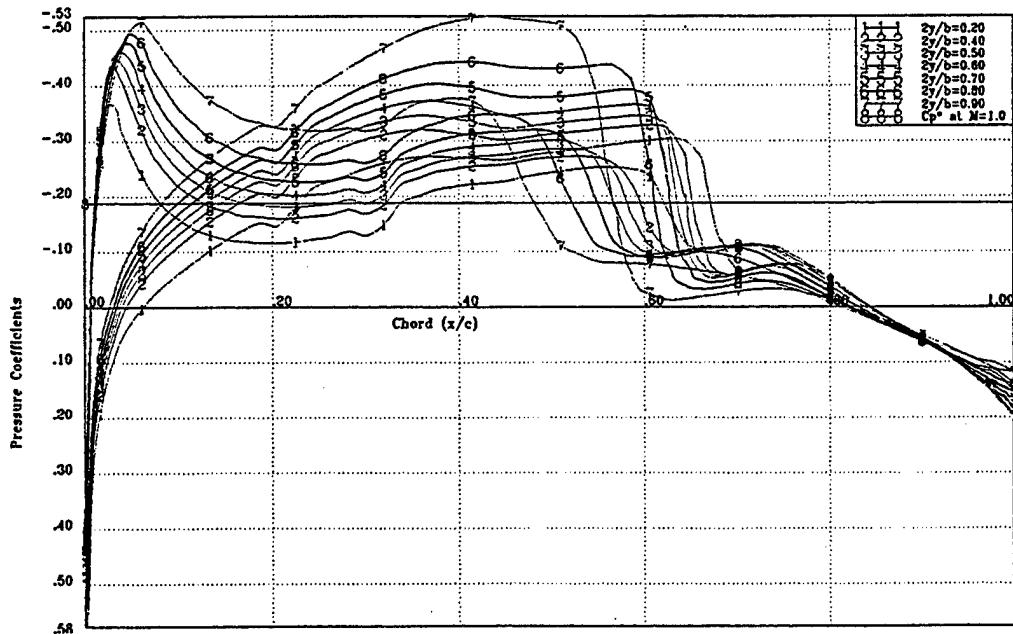


Figure 4.1.4.c Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.90$, $\text{AoA} = 0.0^\circ$, by ENSAERO.

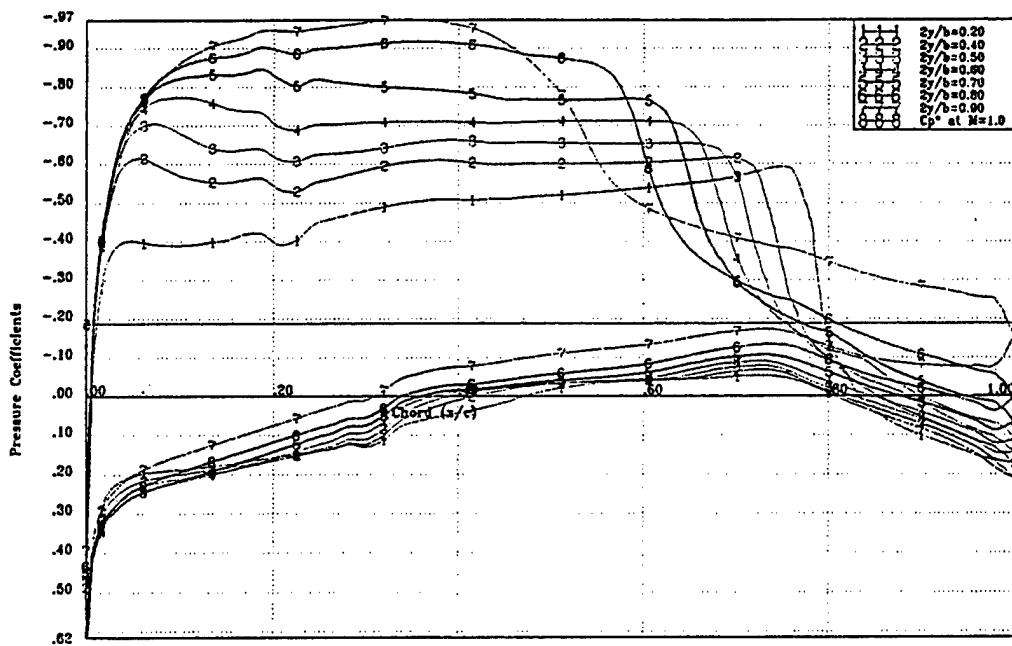


Figure 4.1.4.d Aerodynamic Pressure Coefficients of GAF Model for Navier-Stokes Flow: $M = 0.90$, AoA = 5.0° , by ENSAERO.

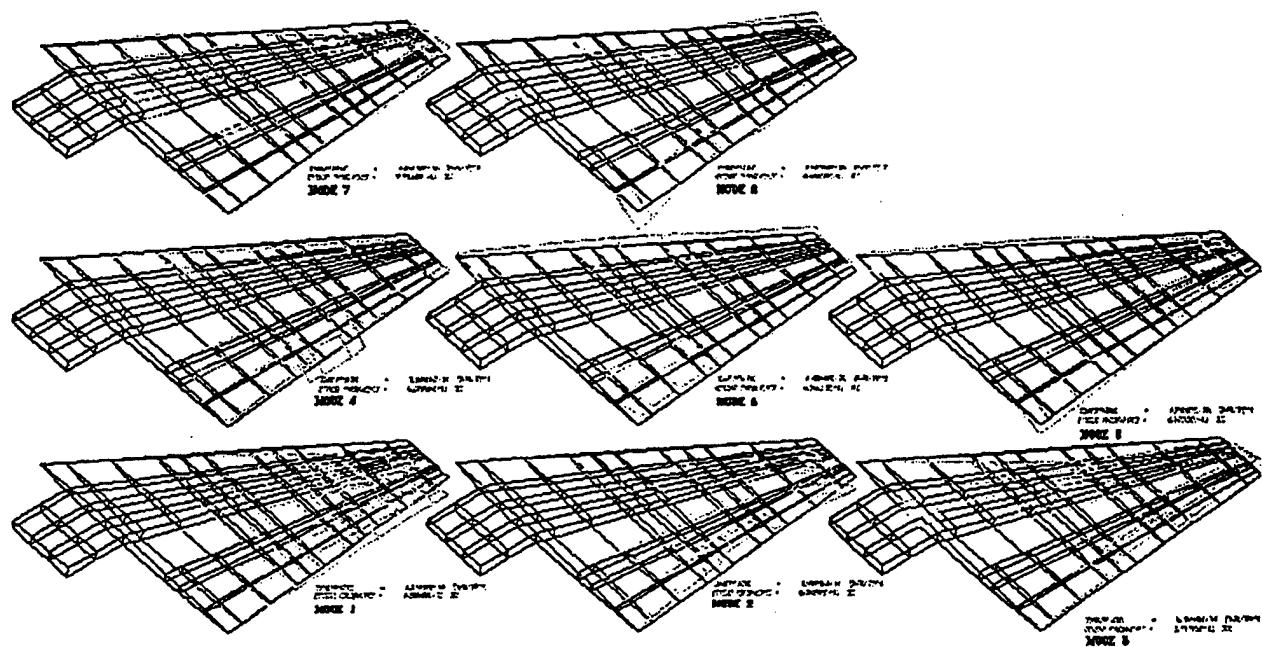


Figure 4.1.5 Normal Modes of GAF Model.

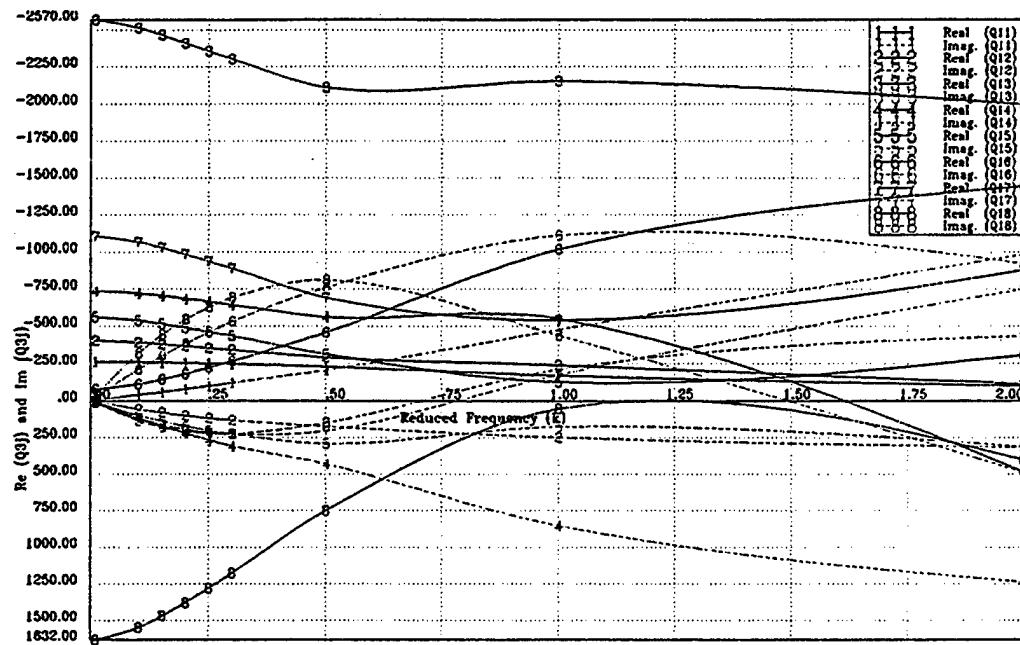


Figure 4.1.6.a Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*.

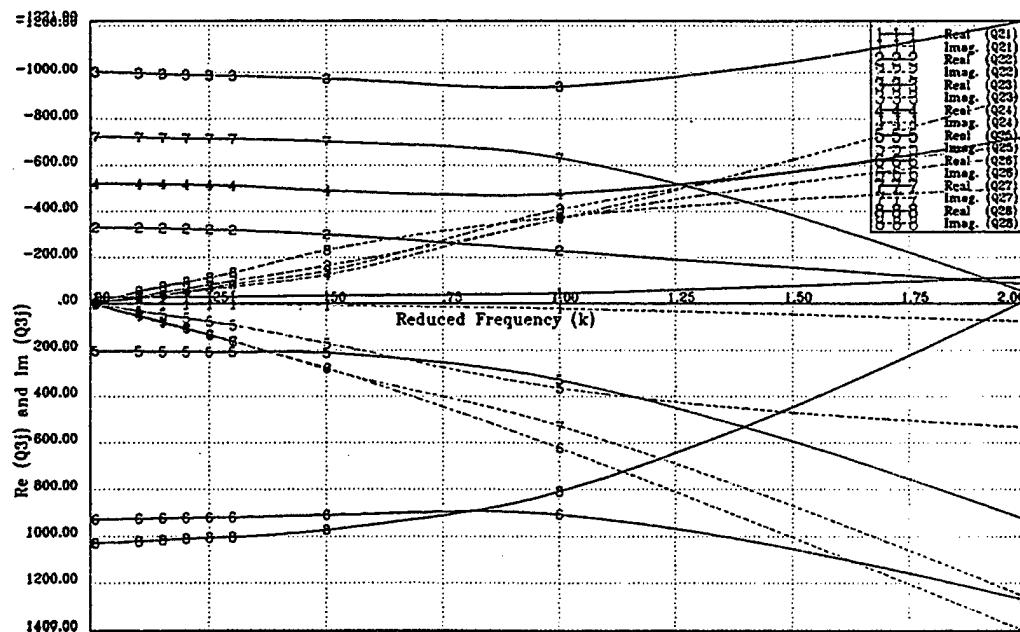


Figure 4.1.6.b Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*.

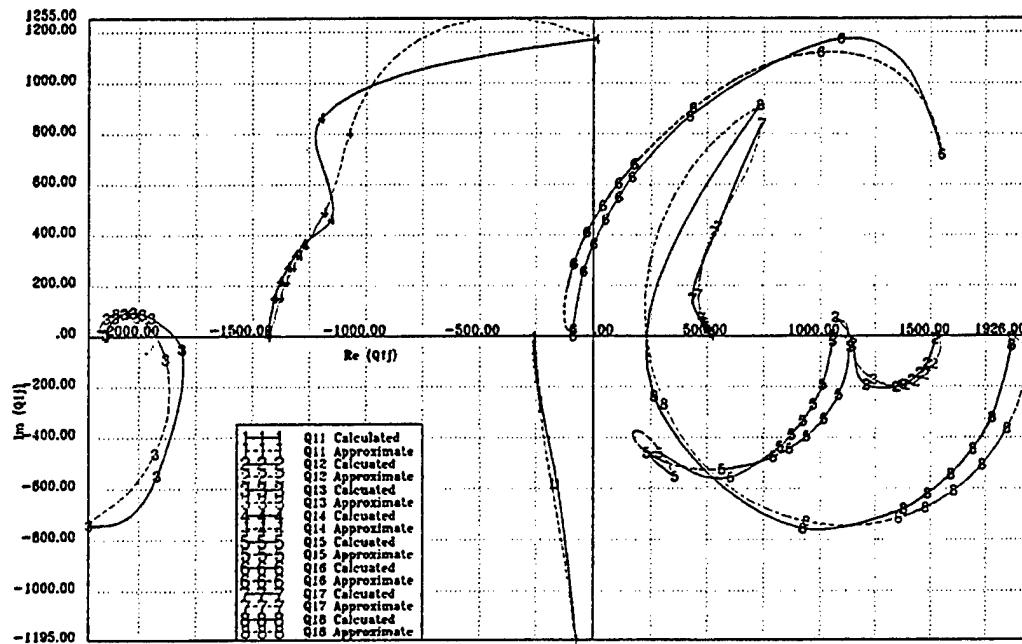


Figure 4.1.7.a Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.

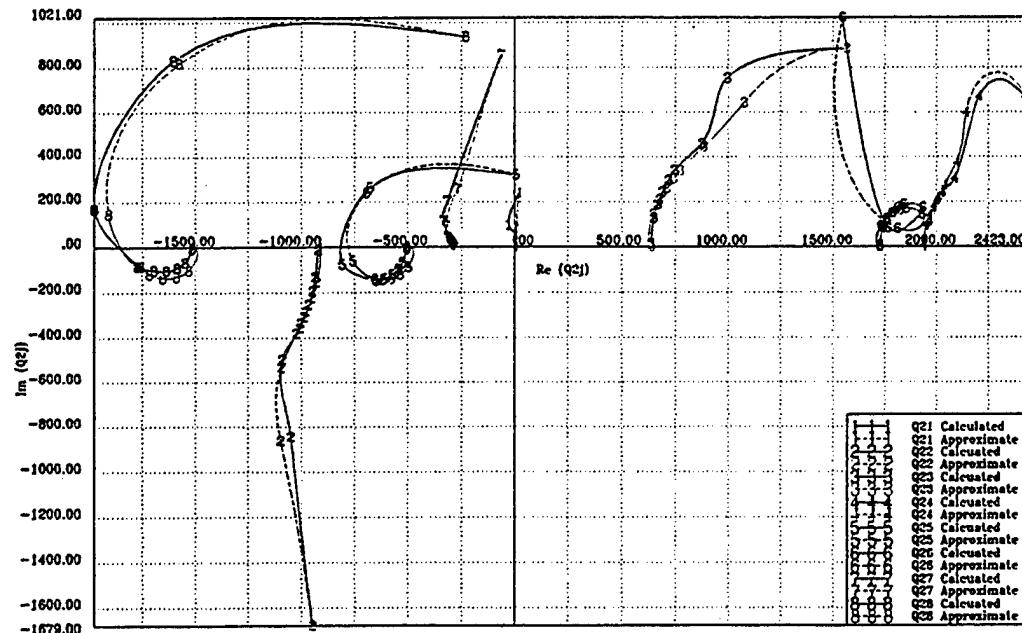


Figure 4.1.7.b Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.

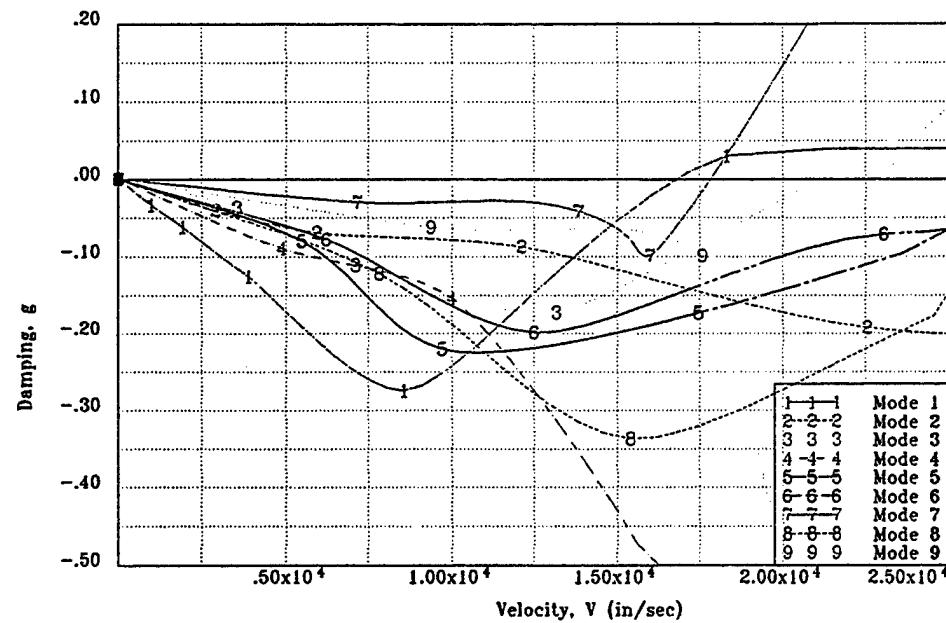
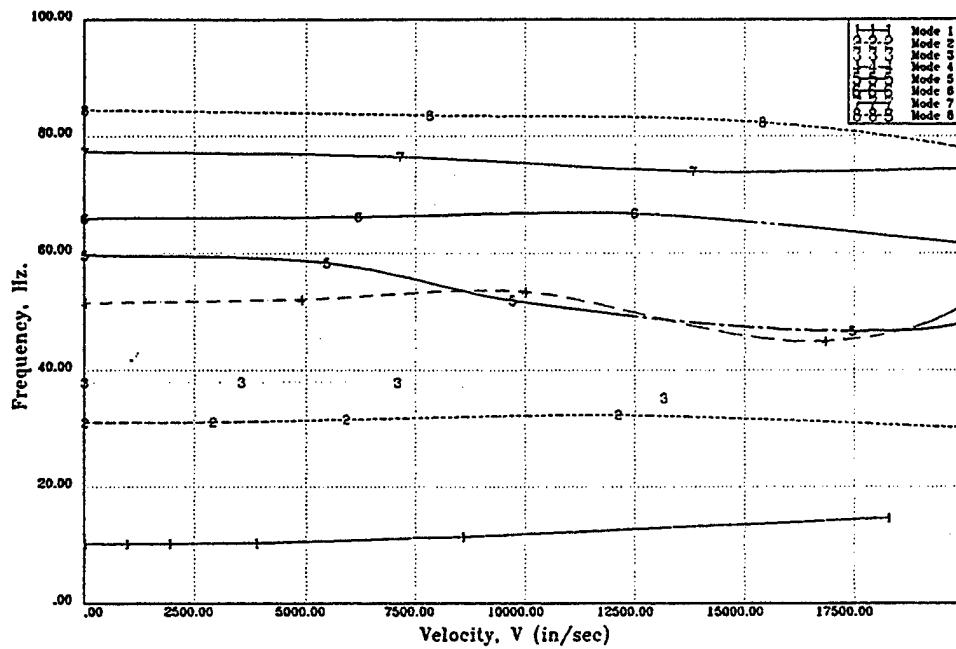


Figure 4.1.8 V-f and V-g Plots of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*
(Flutter Speed = 17,337 in/sec, Flutter Frequency = 14.3 Hz.)

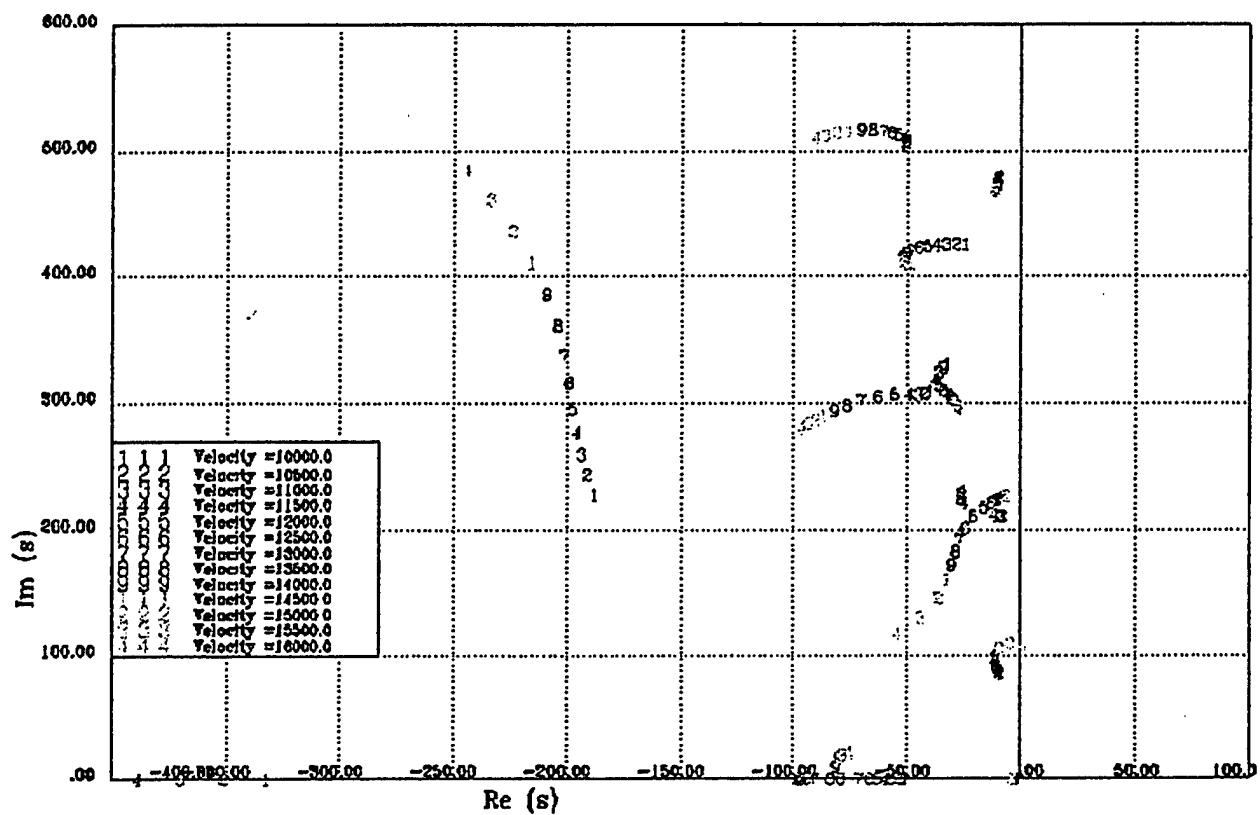


Figure 4.1.9 Root-Locus Plot of GAF Model: $M = 0.85$, by ZONA6 of ASTROS*
(Flutter Speed = 15,888 in/sec, Flutter Frequency = 17.32 Hz).

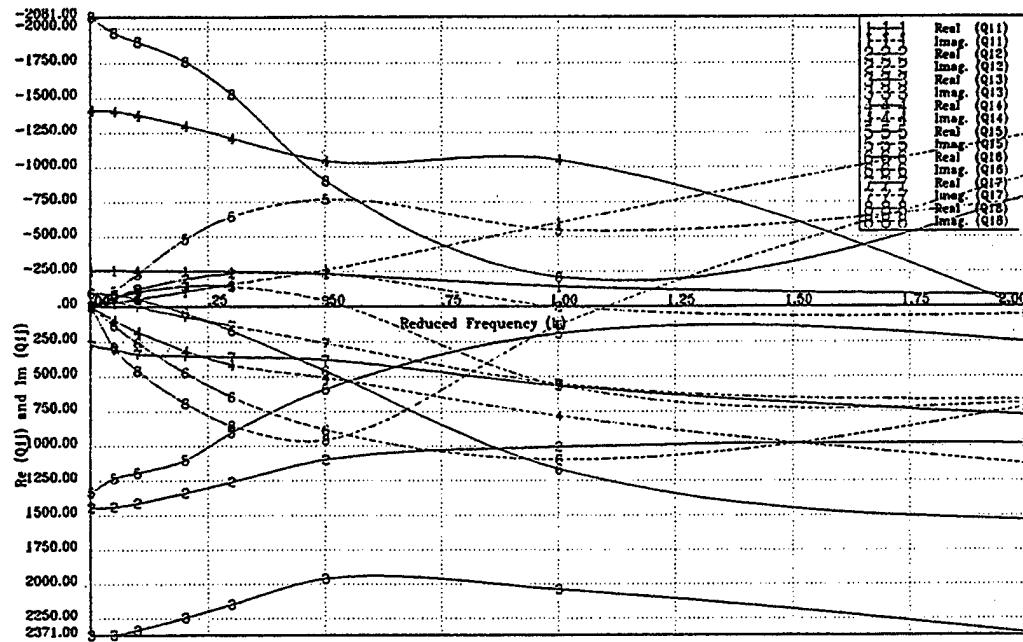


Figure 4.1.10.a Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS*.

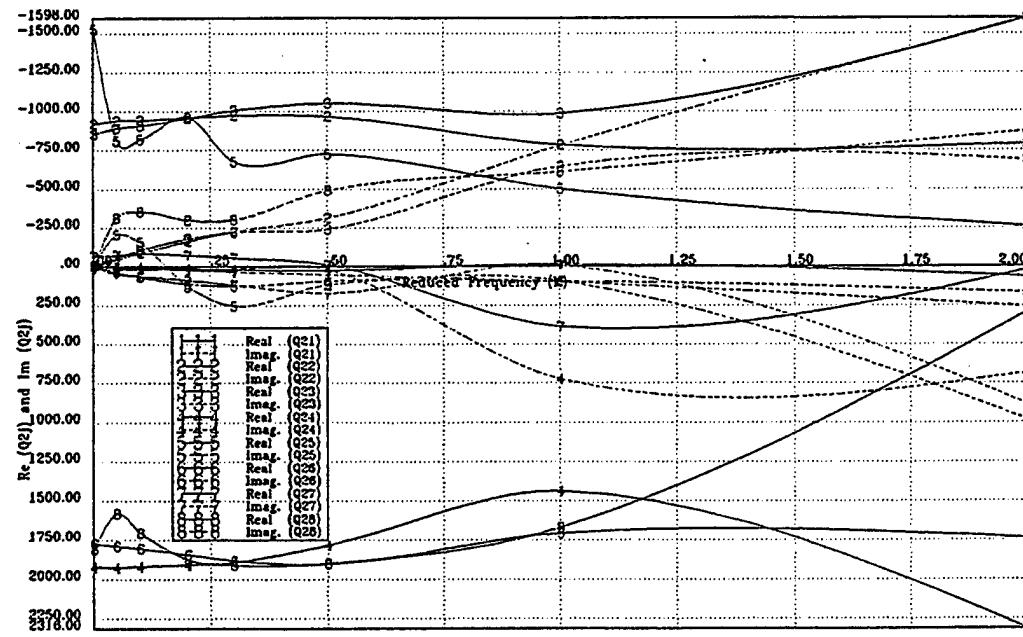


Figure 4.1.10.b Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS*.

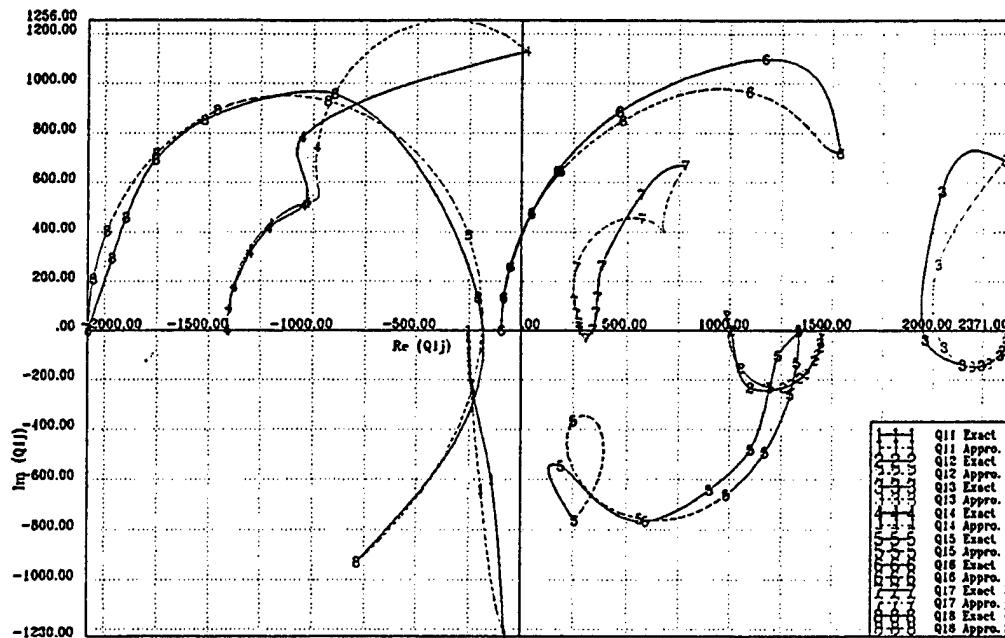


Figure 4.1.11.a Generalized Unsteady Aerodynamic Coefficients Q_{1j} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* and Approximated by Minimum-State Method.

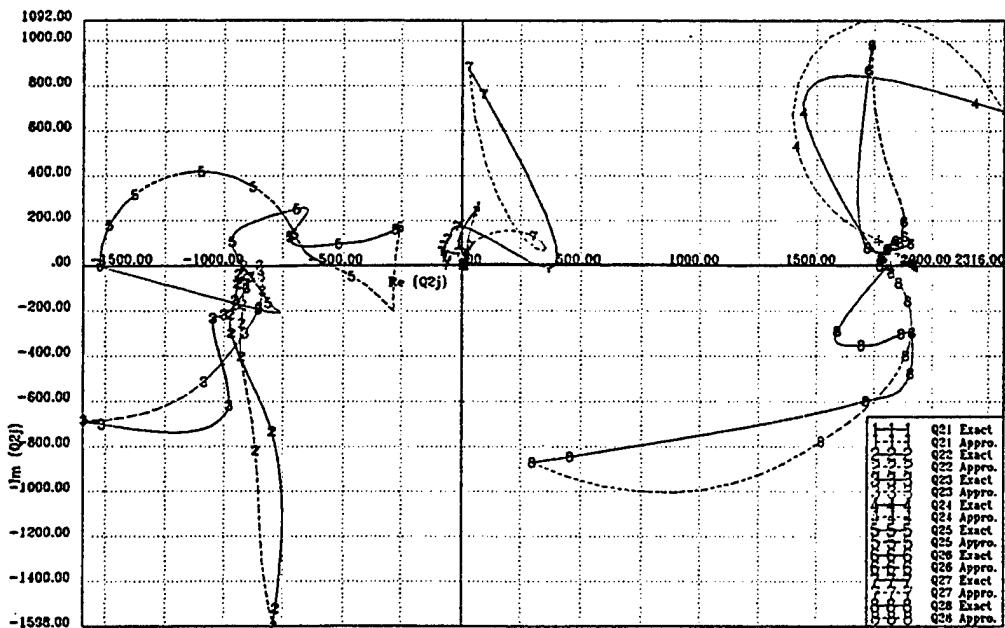


Figure 4.1.11.b Generalized Unsteady Aerodynamic Coefficients Q_{2j} of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* and Approximated by Minimum-State Method.

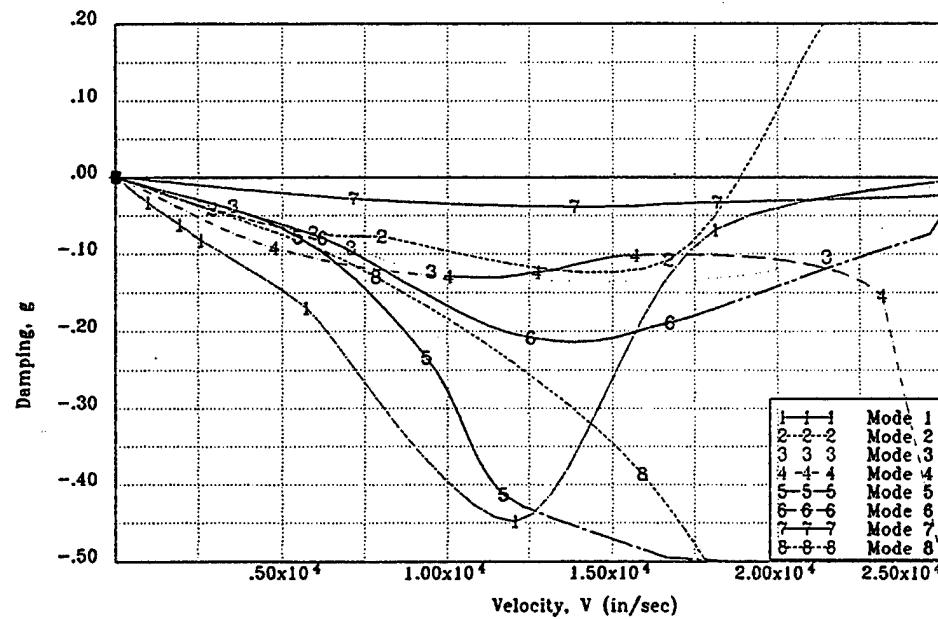
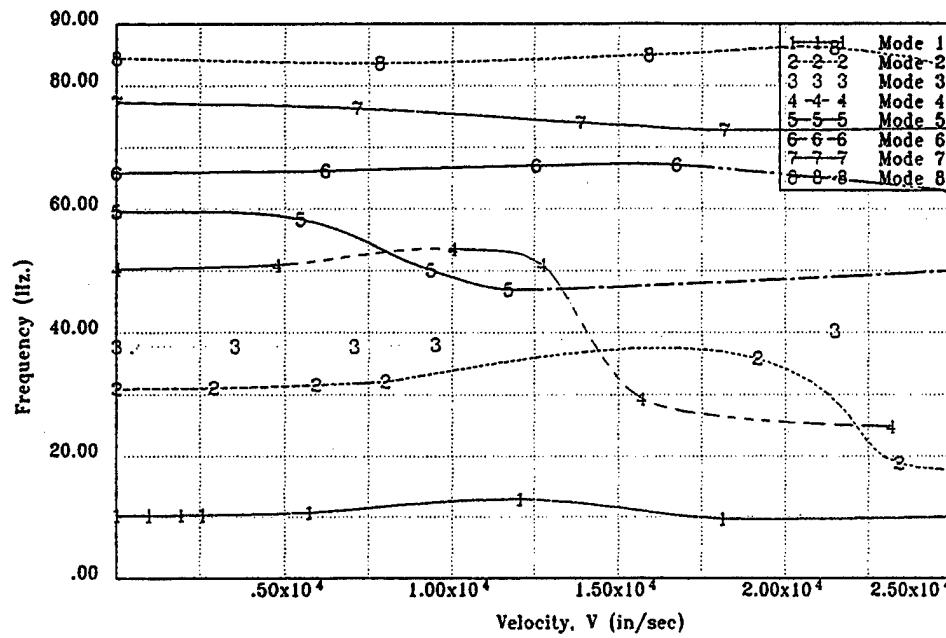


Figure 4.1.12 V-f and V-g Plots of GAF Model: $M = 0.85$, by ZTAIC of ASTROS* (Flutter Speed = 18,172 in/sec, Flutter Frequency = 18.1 Hz).

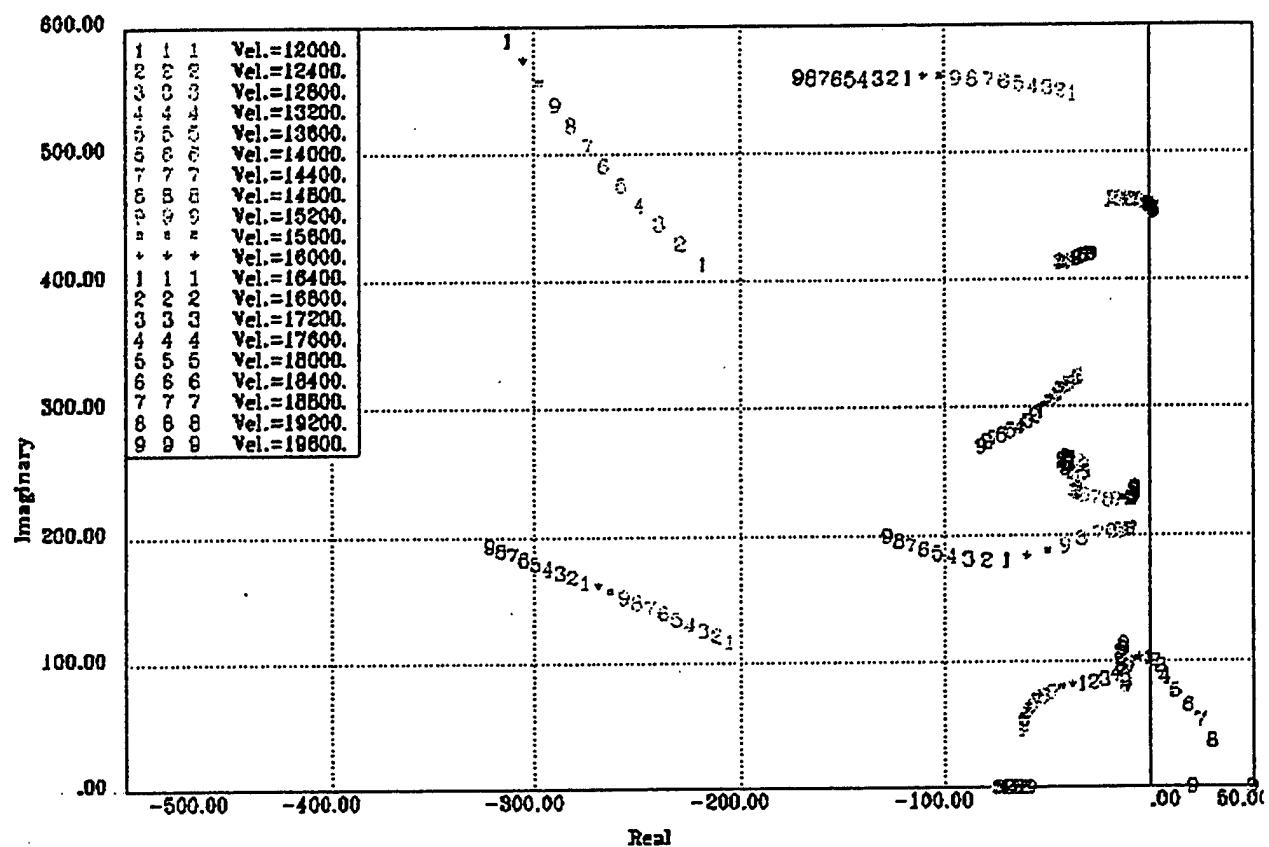


Figure 4.1.13 Root-Locus Plot of GAF Model: $M = 0.85$, by ZTAIC of ASTROS*
(Flutter Speed = 16,581 in/sec, Flutter Frequency = 15.6 Hz).

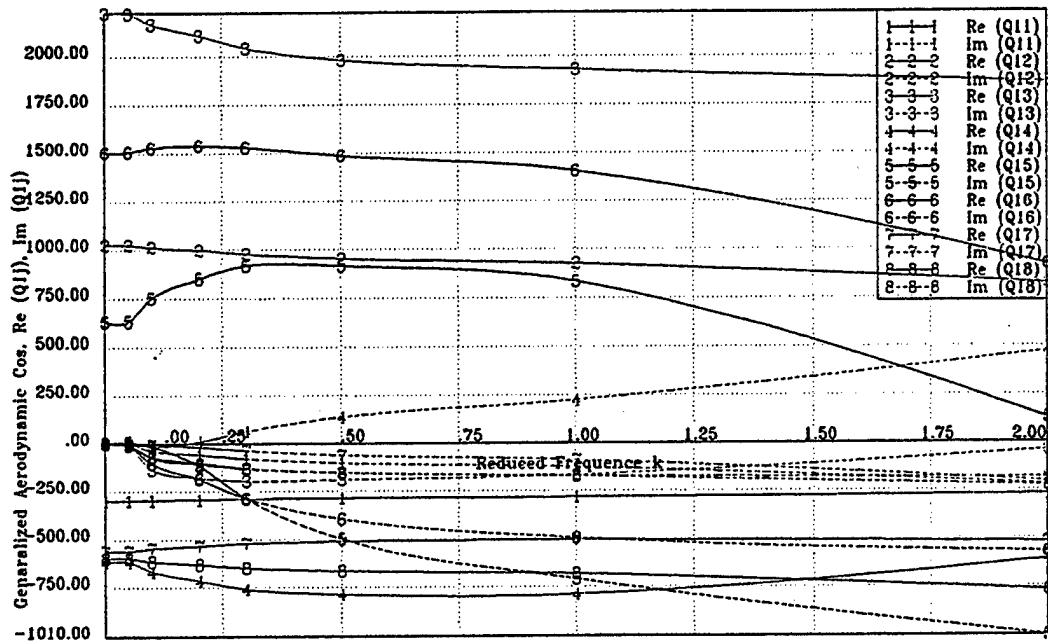


Figure 4.1.14 Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 1.15$, by ZONA7 of ASTROS*.

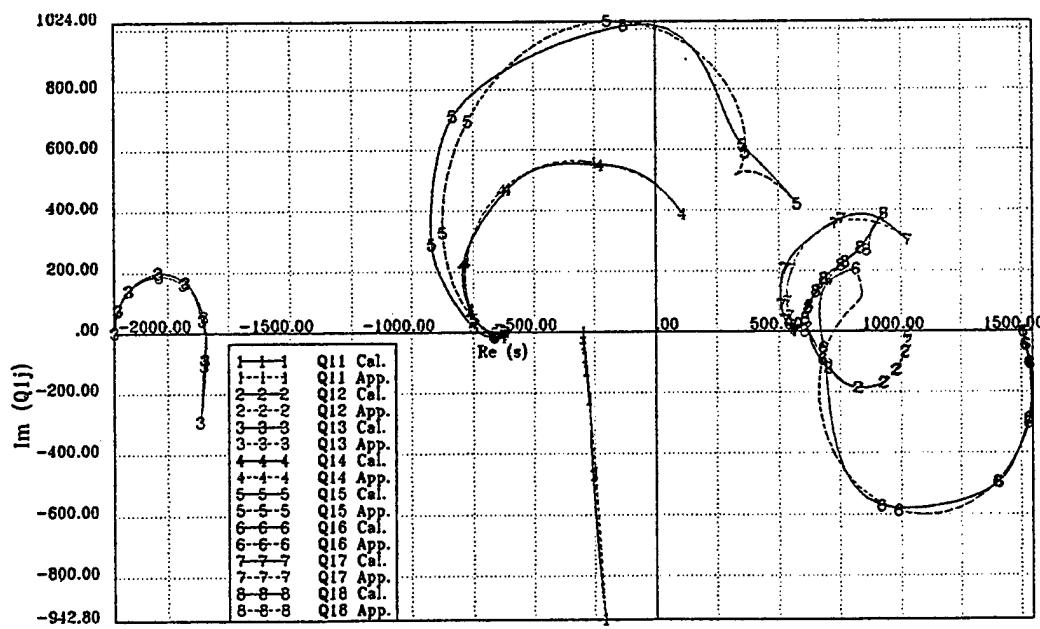


Figure 4.1.15 Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 1.15$, by ZONA7 of ASTROS* and Approximated by Minimum-State Method.

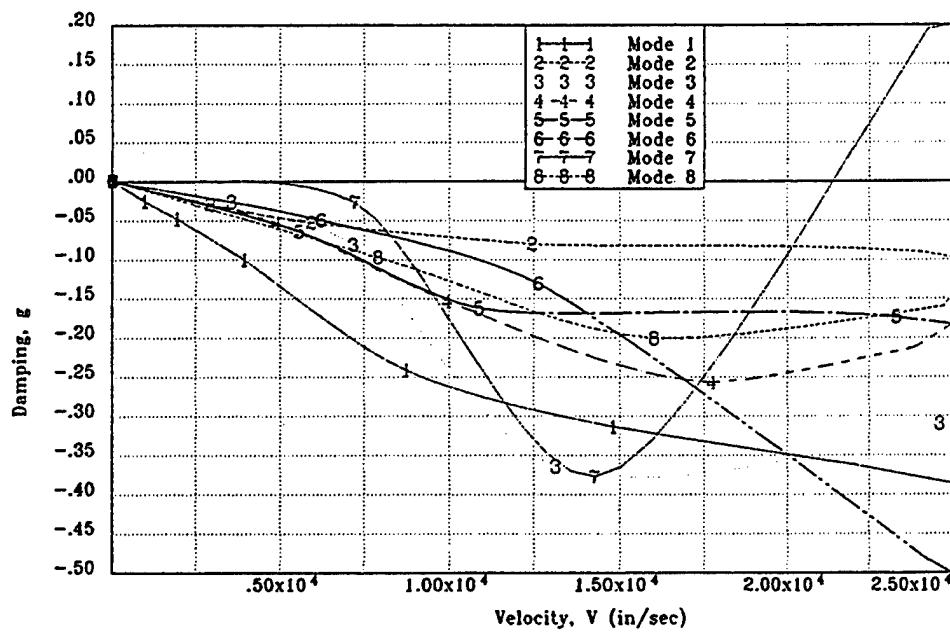
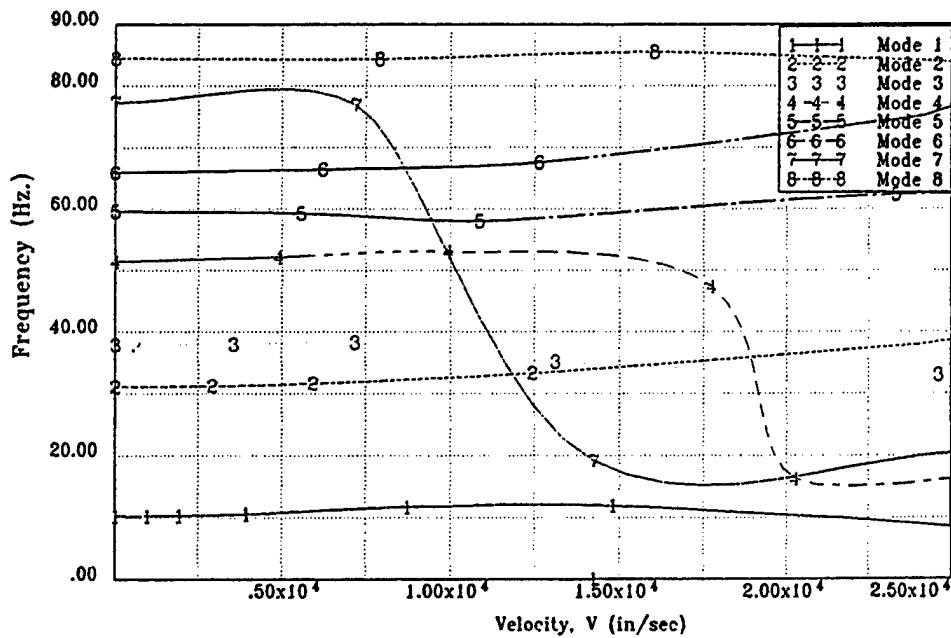


Figure 4.1.16 V-f and V-g Plots of GAF Model: $M = 1.15$, by ZONA7 of ASTROS*
(Flutter Speed = 20,776 in/sec, Flutter Frequency = 19.8 Hz).

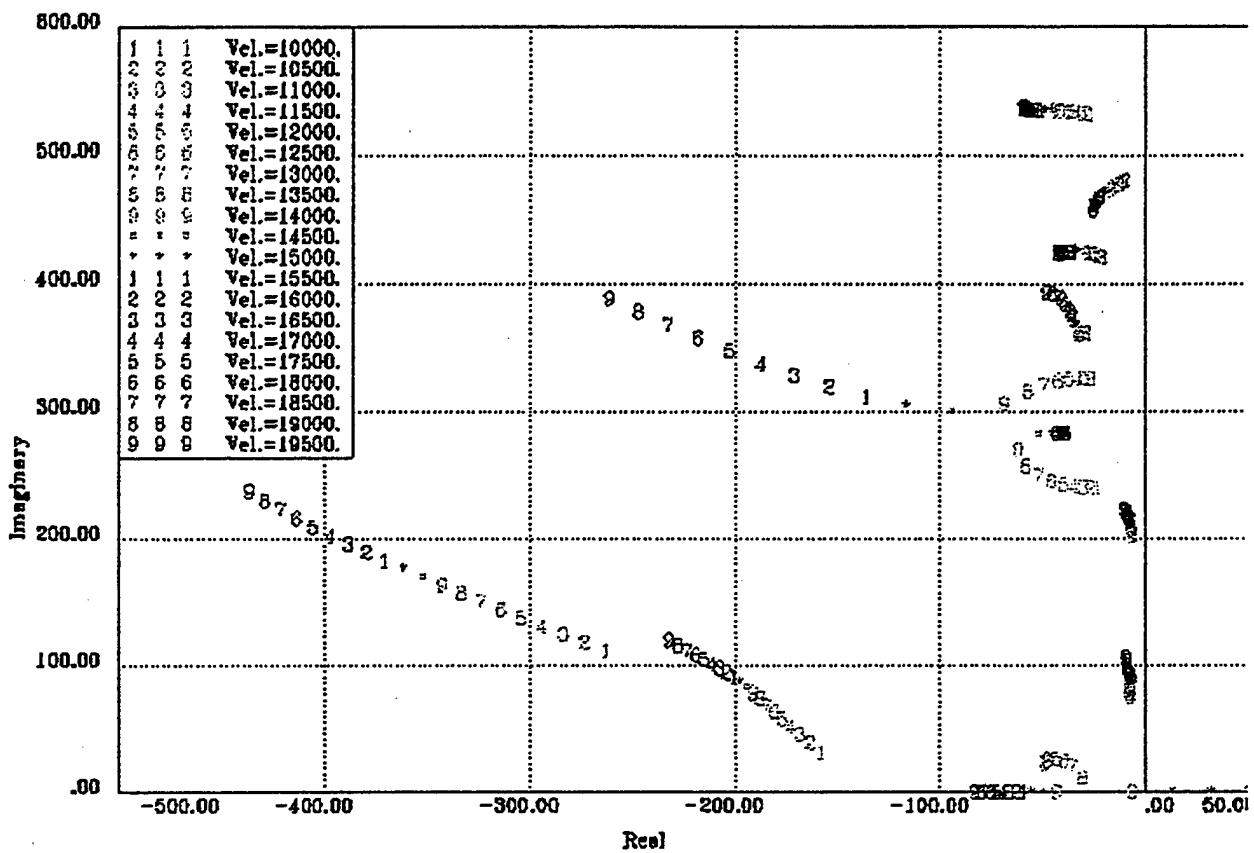


Figure 4.1.17 Root-Locus Plot of GAF Model: $M = 1.15$, by ZONA7 of ASTROS*
(Divergence Speed = 14,170 in/sec, No Flutter).

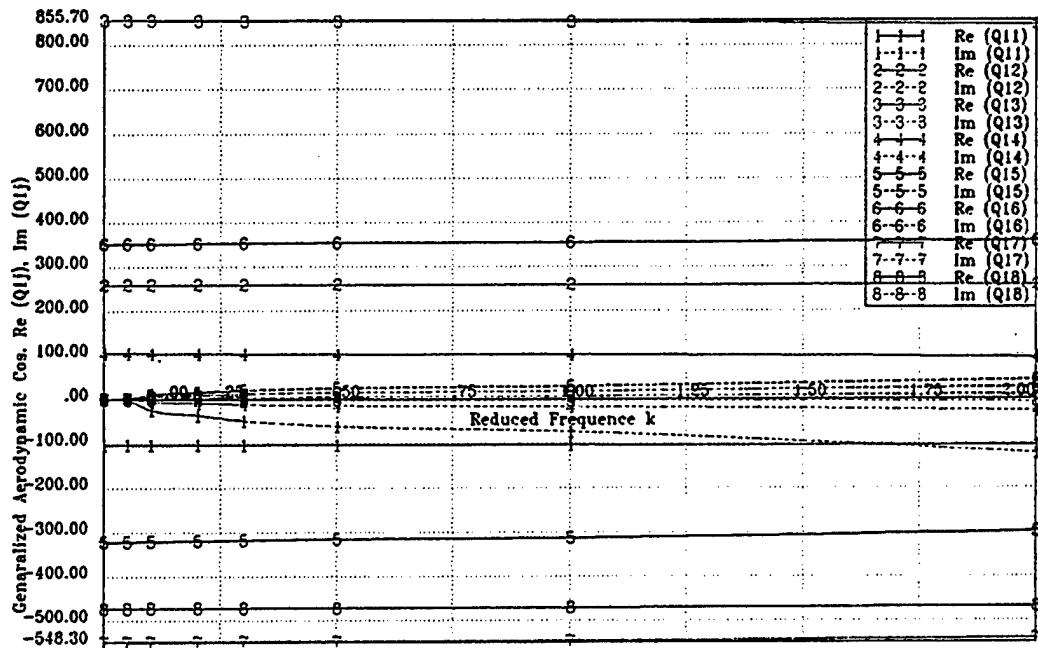


Figure 4.1.18 Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 3.0$, by ZONA7U of ASTROS*.

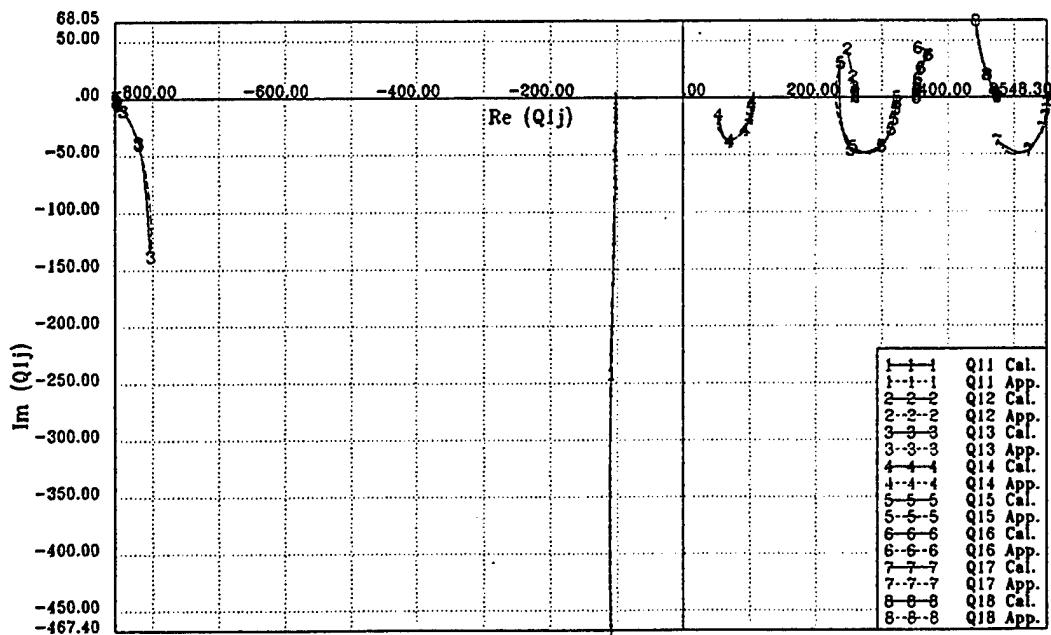


Figure 4.1.19 Generalized Unsteady Aerodynamic Coefficients Q_{ij} of GAF Model: $M = 3.0$, by ZONA7U of ASTROS* and Approximated by Minimum-State Method.

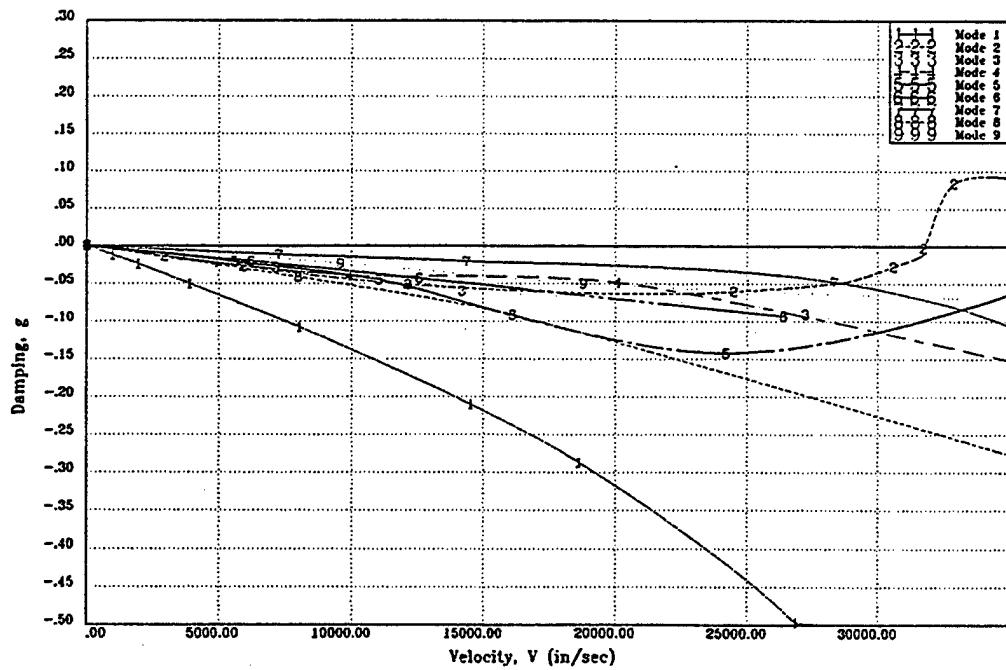
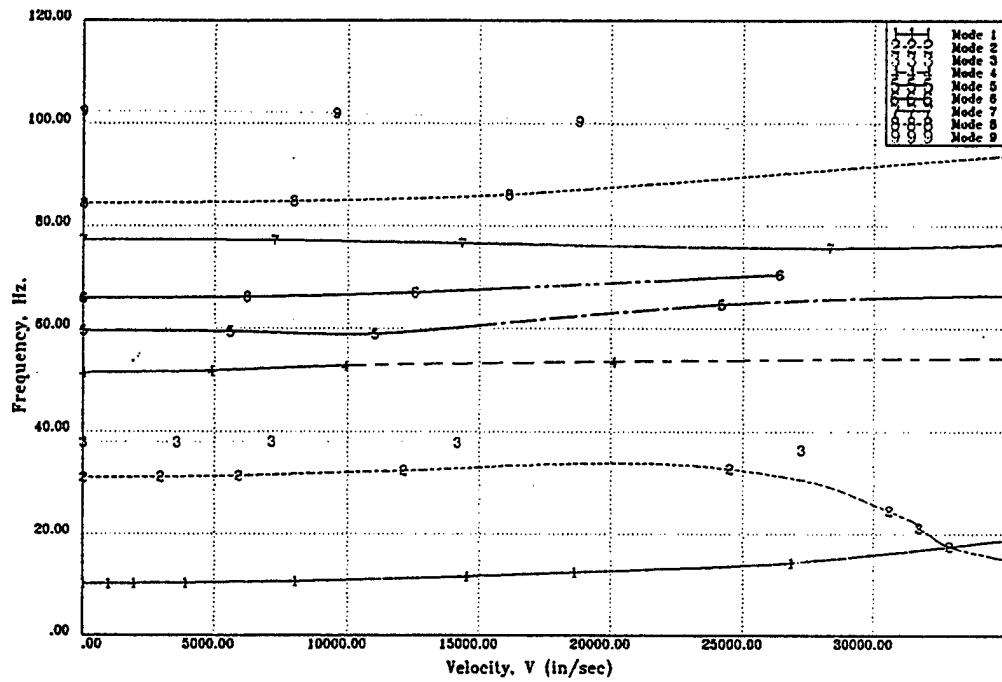


Figure 4.1.20 V-f and V-g Plots of GAF Model: $M = 3.0$, by ZONA7U of ASTROS*
(Flutter Speed = 31,743 in/sec, Flutter Frequency = 21.1 Hz).

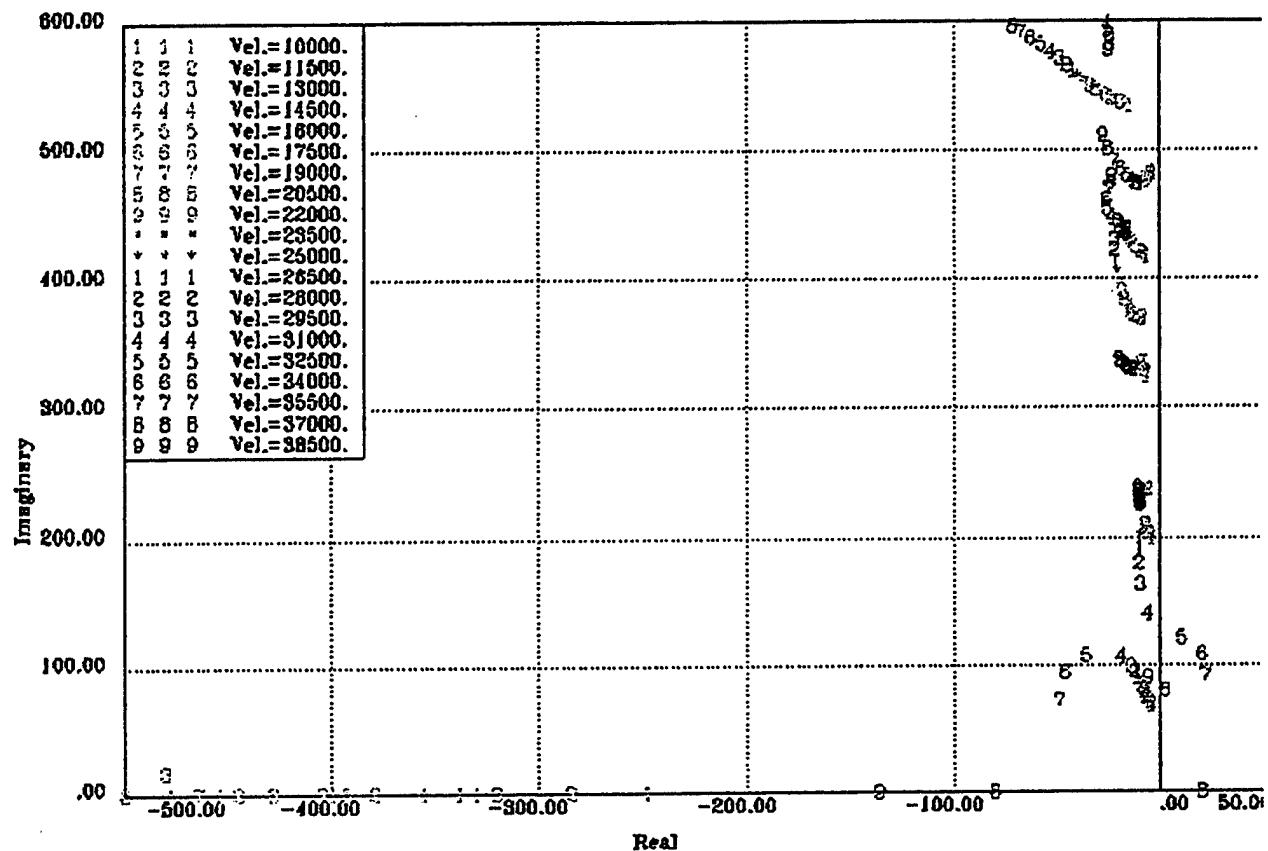


Figure 4.1.21 Root-Locus Plot of GAF Model: $M = 3.0$, by ZONA7U of ASTROS*
(Flutter Speed = 31,536 in/sec, Flutter Frequency = 21.3 Hz).

4.2 Case 1.b: GAF (Generalized Advanced Fighter) Wing Model Optimization

- **Purpose:** To test a public domain model in static, normal modes, and flutter optimization and MDO.
- **Description of input and results:**

4.2.1 Static Optimization

Static structural design optimization was performed. The design variables were the thicknesses of all skin elements. The objective function was the total weight of the skins. The constraints were the requirements for wing tip displacement and the stresses in the skins. The required wing tip displacement, 27.07 in, was the same as the result in the analysis of the original wing model. The required stress of 64,000 psi was the maximum stress in the same analysis. The number of global design variables was 52, and the design variables and their numbering are shown in Fig 4.2.1. The design variables were defined by DESVARP cards, which converted the properties of the elements into design variables. The upper and lower skins had the same property numbers and, thus, were the same design variables. This had the effect of linking the design variables of the upper and lower skins. The lower boundary of the design variables was the minimum material size, 0.118 in.

As a result of the static design optimization, the weight was reduced from 343.49 lbs to 313.37 lbs. In this optimization, the thicknesses of all skins started from their minimum basic material sizes. The iteration history of the design optimization is shown in Fig 4.2.2 and Table 4.2.1. The required CPU time was 1 minute 55.5 seconds. An 8.8 % weight reduction was achieved for this short CPU time in 15 iterations. The convergence was excellent.

4.2.2 Normal Modes Optimization

In the normal modes optimization, the lower bound of the first frequency was used as a constraint. The required frequency of 10.22 Hz was the same as the result from the original analysis of the model.

As a result of the normal modes design optimization, the weight was reduced from the original weight of 343.49 lbs to 312.26 lbs. The iteration history of the design optimization is also shown in Fig 4.2.2 and in Table 4.2.2. The required CPU time was 2 minute 48.3 seconds. A 9.1 % weight reduction was achieved for this short CPU time in 15 iterations. The convergence was excellent for this case with a structural design optimization and only one constraint.

4.2.3 Design Optimization for Static Loads and Normal Modes

Design optimization for static loads and normal modes was then performed. Displacements, stresses, and the lowest frequency were used as constraints. The constraint values, the required wing tip displacement of 27.07 in, the required maximum stress of 64,000 psi, and the required lowest frequency of 10.22 Hz, were the same as resulted from the original analyses.

As a result of the design optimization for the disciplines of statics and normal modes, the weight was reduced from 343.49 *lbs*, the weight of the original structure, to 313.28 *lbs*, for a reduction of about 10 %. More weight could still be taken off for smaller minimum basic sizes. The iteration history of the design optimization is again shown in Fig 4.2.2 and in Table 4.2.3. The final design variable values are given in Table 4.2.4. In this optimization, the initial design variable values were the minimum basic sizes not those from the original structure. This means that the design optimization can be performed easily without any initial sizing calculations either manually or by CAD.

4.2.4 Flutter Optimization

Structural design optimization with a flutter speed constraint was performed for the GAF model at $M=0.85$. ZONA6 in ASTROS* was used for calculating the aerodynamic loads. The constrained flutter speed was 16,107.8 *in/sec*. Flutter sensitivities with respect to design variables were calculated, the flutter constraints were formulated by linear approximation, and the optimization problem was solved using the optimizer NPSOL. The derivatives of the mass matrix and the stiffness matrix, necessary to calculate the flutter sensitivities, were obtained using the *MAPOL* language in ASTROS* for the static and normal modes disciplines. An iteration history of the design optimization for flutter speed is shown in Fig 4.2.3 and in Table 4.2.5. In this case, the lengthy set of iterations was stopped without applying the convergence criteria since the intent was only to show the convergence behavior.

4.2.5 Multidisciplinary Design Optimization of Statics, Normal Modes, and Flutter

With flutter speed, static strength, and frequency constraints, multidisciplinary design optimization was performed for the GAF model. The objective function was the total structural weight. The approximate optimization problem was calculated by NPSOL. The sensitivities of the static strength and frequency constraints, as well as the derivatives of the mass and stiffness matrices that are necessary to calculate the flutter sensitivities were obtained via the *MAPOL* programming language in ASTROS* from the static and normal modes disciplines. The sensitivity of the objective function, the total structural weight, was also obtained via *MAPOL*. The constraint values were the required wing tip displacement of 27.07 *in*, the required maximum stress of 64,000 *psi*, the required lowest frequency of 10.22Hz, and the required flutter speed of 16,108 *in/sec*. An iteration history of the multidisciplinary optimization with strength, displacement, natural frequency, and flutter speed constraints is shown in Fig 4.2.4 and Table 4.2.6. The final design variable values are given in Table 4.2.7. A weight reduction of 15.57 *lbs* was achieved compared with the weight of the original model, 343.49 *lbs*; this was a 4.5 % weight reduction in 6 iterations. The GAF model was an actual aircraft wing model supposed to be well designed at the outset, and the material minimum basic sizes were quite thick. Thus, a 4.5 % weight reduction in this small number of iterations can be considered a good result since strength, displacement, normal modes, and flutter constraints were considered simultaneously.

**Table 4.2.1: Design Iteration History of GAF Model:
Structural Optimization for Static Loads.**

Iteration Number	Objective Function	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
------------------	--------------------	---------------------	----------------------	--------------------	-------------------------

1	2.19373E+02	(Initial Function Value)				
2	2.86841E+02	90	21	45	27	not Converged
3	3.50363E+02	100	8	32	14	not Converged
4	3.40345E+02	36	11	18	6	not Converged
5	3.35738E+02	21	4	16	16	not Converged
6	3.32504E+02	41	3	18	17	not Converged
7	3.21375E+02	22	7	16	4	not Converged
8	3.18522E+02	22	7	17	10	not Converged
9	3.17345E+02	25	3	20	4	not Converged
10	3.16361E+02	23	3	20	4	not Converged
11	3.15494E+02	18	2	17	3	not Converged
12	3.14714E+02	18	3	18	3	not Converged
13	3.14138E+02	19	3	19	3	not Converged
14	3.13609E+02	20	3	19	6	not Converged
15	3.13368E+02	14	2	19	3	Converged

The Final Objective Function Value is: Fixed = 3.28112E+02
+ Designed = 3.13368E+02
Total = 6.41480E+02

**Table 4.2.2 Design Iteration History of GAF Model:
Structural Optimization for Normal Modes by ASTROS*.**

Iteration Number	Objective Function	Function Evaluation	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
------------------	--------------------	---------------------	---------------------	----------------------	--------------------	-------------------------

1	2.19373E+02	(Initial Function Value)				
2	2.71428E+02	90	21	1	1	not Converged
3	3.30081E+02	93	21	1	1	not Converged
4	3.50735E+02	88	7	1	1	not Converged
5	3.35437E+02	31	6	1	1	not Converged
6	3.26556E+02	23	5	1	1	not Converged
7	3.21226E+02	23	5	1	1	not Converged
8	3.18468E+02	24	5	1	1	not Converged
10	3.15728E+02	37	3	1	1	not Converged
11	3.14820E+02	22	4	1	1	not Converged
12	3.13932E+02	22	4	1	1	not Converged
13	3.13314E+02	18	3	1	1	not Converged
14	3.12698E+02	22	4	1	1	not Converged
15	3.12255E+02	26	2	1	1	Converged

The Final Objective Function Value is: Fixed = 3.28112E+02
+ Designed = 3.12255E+02
Total = 6.40367E+02

**Table 4.2.3 Design Iteration History of GAF Model:
Structural Optimization for Statics and Normal Modes by ASTROS*.**

Iteration Number	Objective Function	Function Evaluation	Gradient Evaluation	Retained Constraints	Active Constraints	Approximate Convergence
1	2.19373E+02 (Initial Function Value)					
2	2.96459E+02	N/A FSD	N/A FSD	163	N/A FSD	not Converged
3	3.06451E+02	N/A FSD	N/A FSD	163	N/A FSD	not Converged
4	3.04878E+02	N/A FSD	N/A FSD	163	N/A FSD	not Converged
8	3.16221E+02	15	4	35	3	not Converged
9	3.15302E+02	18	3	35	3	not Converged
10	3.14613E+02	18	3	34	3	not Converged
11	3.14112E+02	10	3	34	4	not Converged
12	3.13653E+02	30	2	34	13	not Converged
13	3.13341E+02	16	2	34	3	not Converged
14	3.13282E+02	14	2	36	3	Converged
The Final Objective Function Value is:				Fixed	=	3.28112E+02
				+ Designed	=	3.13282E+02
				Total	=	6.41394E+02

**Table 4.2.4 Final Design Variables of GAF Model:
Structural Optimization for Statics and Normal Modes by ASTROS*.**

Design Variable	Design Value	Minimum Value	Maximum Value	Objective Sensitivity
102	1.00000E+00	1.00000E+00	2.63158E+01	6.17620D+01
501	1.00000E+00	1.00000E+00	1.00000E+01	2.40229D+00
502	1.00000E+00	1.00000E+00	1.00000E+01	2.37495D+00
503	6.32244E+00	1.00000E+00	1.00000E+01	2.39868D+00
504	1.00000E+00	1.00000E+00	1.00000E+01	2.79464D+00
505	1.00000E+00	1.00000E+00	1.00000E+01	1.80651D+00
506	1.00000E+00	1.00000E+00	1.00000E+01	4.44667D+00
507	1.00000E+00	1.00000E+00	1.00000E+01	4.39610D+00
508	5.62066E+00	1.00000E+00	1.00000E+01	4.43999D+00
509	1.00000E+00	1.00000E+00	1.00000E+01	5.17293D+00
510	1.00000E+00	1.00000E+00	1.00000E+01	3.34383D+00
511	1.00000E+00	1.00000E+00	1.00000E+01	3.96945D+00
512	1.00000E+00	1.00000E+00	1.00000E+01	3.92430D+00
513	4.27849E+00	1.00000E+00	1.00000E+01	3.96349D+00
514	1.00000E+00	1.00000E+00	1.00000E+01	4.61772D+00
515	1.00000E+00	1.00000E+00	1.00000E+01	2.98490D+00

516	1.00000E+00	1.00000E+00	1.00000E+01	3.49222D+00
517	1.11060E+00	1.00000E+00	1.00000E+01	3.45248D+00
518	2.29648E+00	1.00000E+00	1.00000E+01	3.48694D+00
519	1.00000E+00	1.00000E+00	1.00000E+01	8.12499D+00
520	1.00000E+00	1.00000E+00	1.00000E+01	2.62597D+00
521	1.00000E+00	1.00000E+00	1.00000E+01	3.01498D+00
522	1.11721E+00	1.00000E+00	1.00000E+01	2.98071D+00
523	1.43451E+00	1.00000E+00	1.00000E+01	3.01046D+00
524	1.00000E+00	1.00000E+00	1.00000E+01	7.01463D+00
525	1.00000E+00	1.00000E+00	1.00000E+01	2.26705D+00
526	1.00000E+00	1.00000E+00	1.00000E+01	2.53777D+00
527	1.00000E+00	1.00000E+00	1.00000E+01	2.50890D+00
528	1.00000E+00	1.00000E+00	1.00000E+01	2.53393D+00
529	1.00000E+00	1.00000E+00	1.00000E+01	5.90423D+00
530	1.00000E+00	1.00000E+00	1.00000E+01	1.90813D+00
531	1.00000E+00	1.00000E+00	1.00000E+01	2.06054D+00
532	1.00000E+00	1.00000E+00	1.00000E+01	2.03709D+00
533	1.00000E+00	1.00000E+00	1.00000E+01	2.05740D+00
534	1.00000E+00	1.00000E+00	1.00000E+01	4.79383D+00
535	1.00000E+00	1.00000E+00	1.00000E+01	1.54923D+00
536	1.00000E+00	1.00000E+00	1.00000E+01	1.58330D+00
537	1.00000E+00	1.00000E+00	1.00000E+01	1.56532D+00
538	1.00000E+00	1.00000E+00	1.00000E+01	1.58091D+00
539	1.00000E+00	1.00000E+00	1.00000E+01	3.68346D+00
540	1.00000E+00	1.00000E+00	1.00000E+01	1.19032D+00
541	1.00000E+00	1.00000E+00	1.00000E+01	6.12696D-01
542	1.00000E+00	1.00000E+00	1.00000E+01	6.05731D-01
543	1.00000E+00	1.00000E+00	1.00000E+01	6.11756D-01
544	1.00000E+00	1.00000E+00	1.00000E+01	1.42533D+00
545	1.00000E+00	1.00000E+00	1.00000E+01	4.60569D-01

**Table 4.2.5 Design Iteration History of GAF Model:
Structural Optimization with Flutter Constraint at $M = 0.85$.**

Iteration No.	Weight (lbs)	Flutter Speed (in/sec)	Flutter Frequency (rad/sec)
1	343.78	16107.9 (Constraint)	105.74
2	324.12	16029.3	103.21
3	348.26	16200.6	103.85
4	315.77	15979.9	102.46
5	339.22	16158.3	103.13
6	315.77	15979.0	102.46
7	327.59	16076.0	102.86
8	339.76	16162.0	103.03
9	327.47	16077.4	102.78
10	333.61	16121.0	102.90
11	328.68	16085.8	102.82
12	333.15	16104.1	102.85

**Table 4.2.6 Design Iteration History of GAF Model:
Multidisciplinary Design Optimization at $M = 0.85$
(Stress + Displacement + Natural Frequency + Flutter Speed).**

Iteration No.	Weight (lbs)	F. Speed (in/sec)	F.freq. (Hz)	Tip Disp. (in)	M. Stress (psi)	1 st Freq. (Hz)
Required		16,107.8		27.38	64,000	10.208
1	219.37	15,232.2	13.72	63.38	164,000	6.00
2	324.61	16,086.6	14.38	37.20	125,000	8.07
3	386.50	16,517.5	14.42	25.57	76,260	9.32
4	366.36	16,492.7	16.42	25.29	64,260	10.28
5	339.64	16,267.7	16.60	26.44	62,550	10.32
6	328.86	16,112.3	16.45	26.44	62,480	10.32
7	327.92	16,106.2	16.44	26.80	63,650	10.27

**Table 4.2.7 Final Design Variable Values of GAF Model:
Multidisciplinary Design Optimization at $M = 0.85$
(Stress + Displacement + Natural Frequency + Flutter Speed).**

Variable	State	Value	L. bound	U. bound	Lagr multip.
VARBL 1	LL	1.0000	1.0000	1.0100	61.60661
VARBL 2	LL	1.3210	1.3210	1.3476	2.417356
VARBL 3	LL	3.0350	3.0350	3.0960	2.413862
VARBL 4	LL	5.0275	5.0275	5.1286	2.405284
VARBL 5	LL	1.0000	1.0000	1.0100	2.803832
VARBL 6	LL	1.0000	1.0000	1.0100	1.755699
VARBL 7	LL	1.3176	1.3176	1.3441	4.126373
VARBL 8	LL	2.8860	2.8860	2.9441	4.255834
VARBL 9	LL	4.3147	4.3147	4.4014	4.670451
VARBL 10	LL	1.0000	1.0000	1.0100	5.299779
VARBL 11	LL	1.0000	1.0000	1.0100	3.263696
VARBL 12	LL	1.1785	1.1785	1.2022	3.411701
VARBL 13	LL	2.1322	2.1322	2.1751	2.354970
VARBL 14	FR	3.4188	3.4037	3.4721	.000000
VARBL 15	LL	1.0000	1.0000	1.0100	4.830757
VARBL 16	LL	1.0000	1.0000	1.0100	2.668114
VARBL 17	LL	1.3602	1.3602	1.3876	2.827459
VARBL 18	LL	1.7225	1.7225	1.7571	2.866750
VARBL 19	LL	1.6573	1.6573	1.6906	3.743286
VARBL 20	LL	1.0000	1.0000	1.0100	8.890014
VARBL 21	LL	1.0000	1.0000	1.0100	2.52555
VARBL 22	LL	1.1280	1.1280	1.1507	2.982377
VARBL 23	LL	1.3032	1.3032	1.3294	3.038492
VARBL 24	LL	1.2682	1.2682	1.2937	3.038216
VARBL 25	LL	1.0000	1.0000	1.0100	7.012024
VARBL 26	LL	1.0000	1.0000	1.0100	2.286383
VARBL 27	LL	1.0000	1.0000	1.0100	2.525305
VARBL 28	LL	1.0221	1.0221	1.0427	2.497412
VARBL 29	LL	1.0000	1.0000	1.0100	2.541466
VARBL 30	LL	1.0000	1.0000	1.0100	5.922578
VARBL 31	LL	1.0000	1.0000	1.0100	1.907490
VARBL 32	LL	1.0000	1.0000	1.0100	2.060489
VARBL 33	LL	1.0000	1.0000	1.0100	2.033227
VARBL 34	LL	1.0000	1.0000	1.0100	2.053379
VARBL 35	LL	1.0000	1.0000	1.0100	4.786958
VARBL 36	LL	1.0000	1.0000	1.0100	1.548409
VARBL 37	LL	1.0000	1.0000	1.0100	1.582935
VARBL 38	LL	1.0000	1.0000	1.0100	1.565027
VARBL 39	LL	1.0000	1.0000	1.0100	1.580414
VARBL 40	LL	1.0000	1.0000	1.0100	3.682065
VARBL 41	LL	1.0000	1.0000	1.0100	1.189650

VARBL 42	LL	1.0000	1.0000	1.0100	.611605
VARBL 43	LL	1.0000	1.0000	1.0100	.605568
VARBL 44	LL	1.0000	1.0000	1.0100	.611541
VARBL 45	LL	1.0000	1.0000	1.0100	1.424990
VARBL 46	LL	1.0000	1.0000	1.0100	.460554
VARBL 47	LL	1.4474	1.4474	1.4765	4.104928
VARBL 48	LL	2.8321	2.8321	2.8890	4.009018
VARBL 49	LL	4.4457	4.4457	4.5350	3.914433
VARBL 50	LL	1.3709	1.3709	1.3985	4.135922
VARBL 51	LL	2.8615	2.8615	2.9190	3.974858
VARBL 52	LL	4.3594	4.3594	4.4470	3.893831

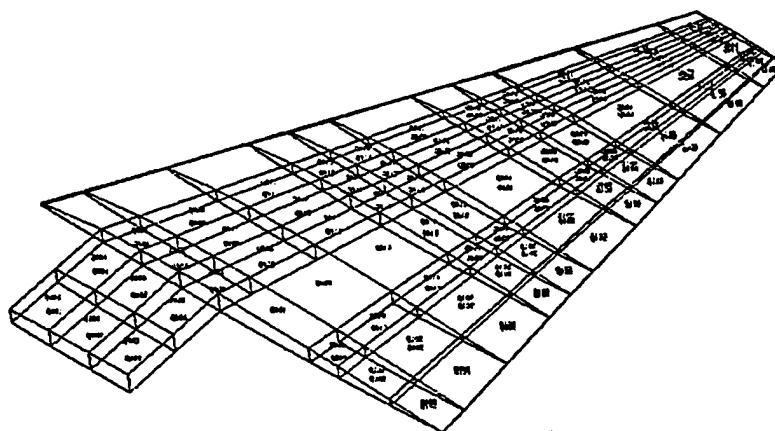


Figure 4.2.1 Design Variables and Numbering of GAF Model.

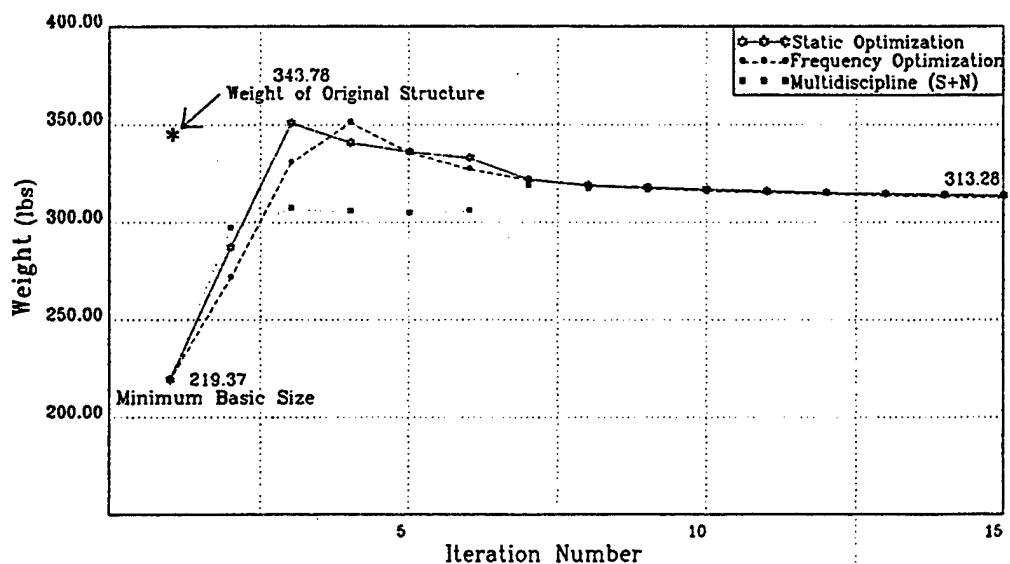


Figure 4.2.2 Iteration History of Structural Design Optimization of GAF Model: Statics, Normal Modes, and Both Disciplines (S + N) by ASTROS*.

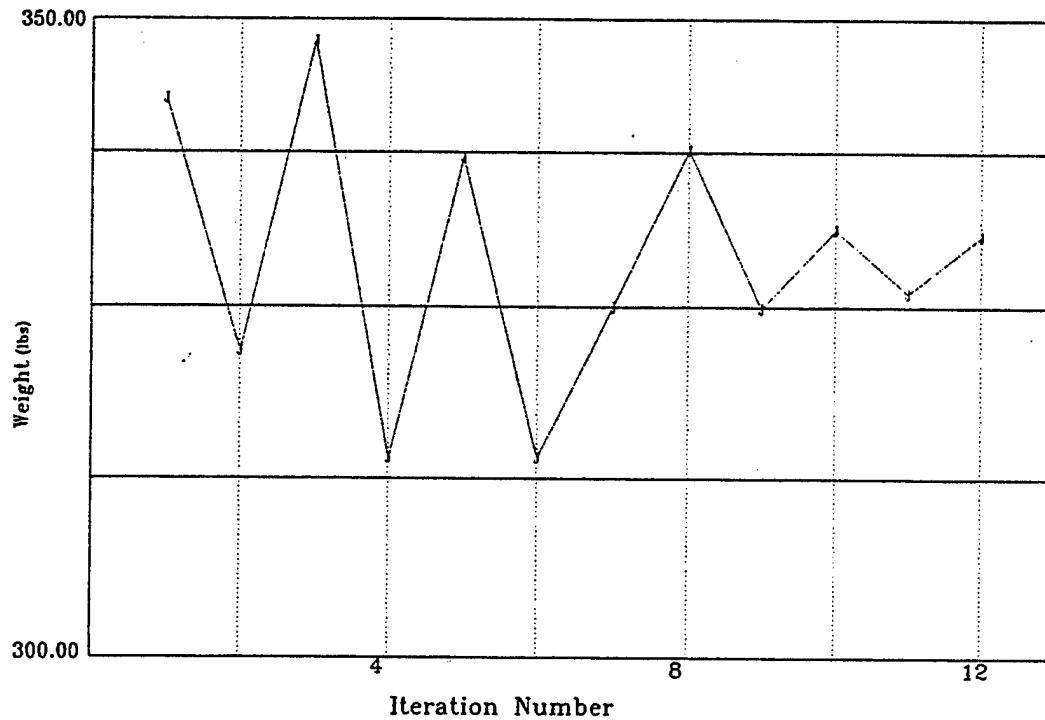


Figure 4.2.3 Iteration History of Structural Design Optimization of GAF Model: Flutter Discipline at $M = 0.85$, by Root-Locus Method.

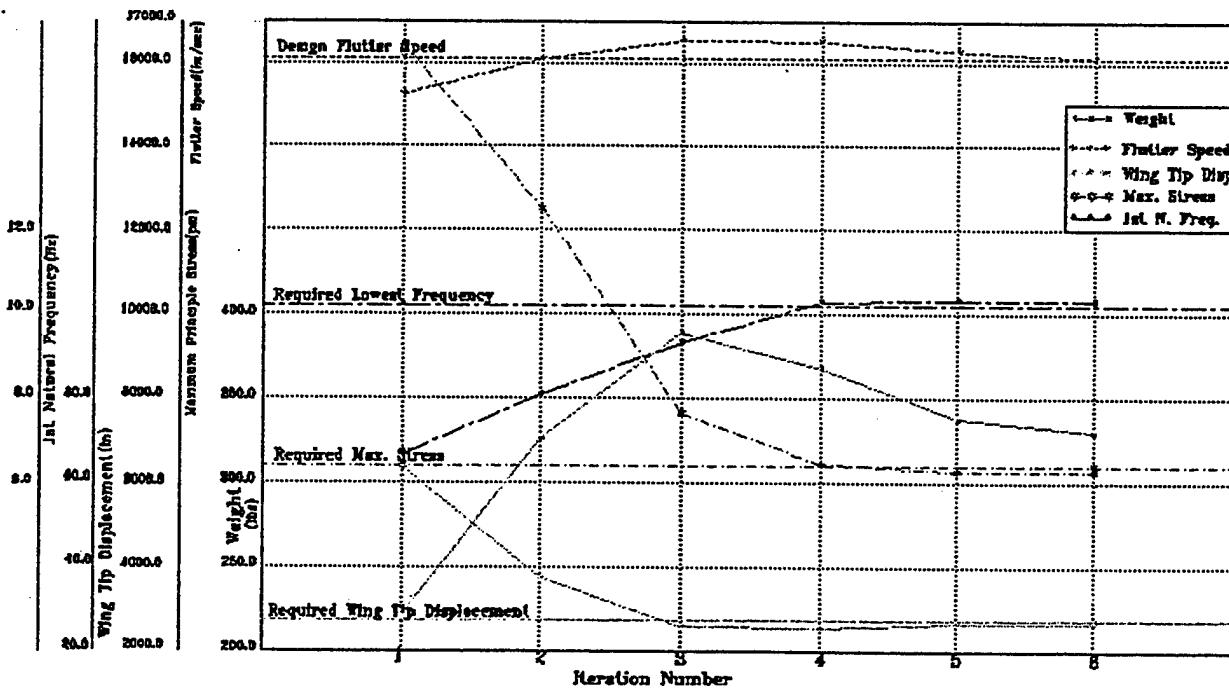


Figure 4.2.4 Design Iteration History of GAF Model: Multidisciplinary Design Optimization (Constraints on stress, displacement, natural frequency, flutter speed).

DAST WING MODEL

4.3 Case 2.a: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Analysis

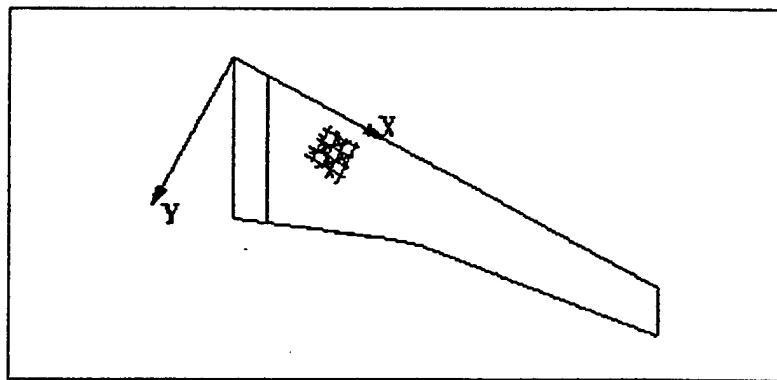
- **Purpose:** To test a composite structural wing model in static aeroelastic, normal modes, and flutter analysis.
- **Description of input and results:**

The DAST wing model was a structural model of a supercritical wing used on a drone in a flight test facility. The ASTROS* and MSC/NASTRAN data for the DAST model were obtained by converting data from an EAL (Engineering Analysis Language) model. The DAST model was a skin-spar-rib type wing made of composite material. To avoid an excessive number of local modes in the normal modes analysis and to improve performance of the model in the static aeroelastic and flutter analyses, ribs were added to the original structure. The stacking sequence of the composite skin panels was changed from the original stacking sequence [90/0] to a more realistic [90/ $\pm 45/0$].

Analyses and structural design optimizations of a composite wing model were the specific goal here. The boundary condition of the structure was free at the root, and its behavior was thought to be the same as that of a full aircraft. More details about the model, the test cases, and their application to this model are given in Appendix A.

4.3.1 Structural Configuration and Static Aeroelastic Analysis

A fuselage weight of 1177.2 *lbs* was added to the wing root by a CONM2 entry, and the total weight of the model became 1250.0 *lbs*, half the weight of the DAST model. The wing had two trailing edge control surfaces. Steady flight in the trim condition with control surface deflections was assumed. The skins were modeled by plate elements, composed of four plies. The material coordinates are shown in the following:



The lamina material of the composite was assumed to be AS/3501 graphite/epoxy. The stiffness and strength of each lamina are given below:

Lamina Stiffness:

$$E_1 = 1.8 \times 10^6 \text{ (psi)}$$

$$E_2 = 0.86 \times 10^6 \text{ (psi)}$$

$$v_{12} = 0.3$$

$$G_{12} = G_{1z} = G_{2z} = 0.46 \times 10^6 \text{ (psi)}$$

$$\rho = 0.057 \text{ (lbs/in}^3\text{)}$$

Lamina Strength:

$$S_L^{(+)} = 210,000 \text{ (psi)}$$

$$S_L^{(-)} = 170,000 \text{ (psi)}$$

$$S_T^{(+)} = 7,000 \text{ (psi)}$$

$$S_T^{(-)} = 36,000 \text{ (psi)}$$

$$S_{LT} = 9,000 \text{ (psi)}$$

The skins were modeled by **CQUAD4** and **CTRIA3** elements and the spar caps by **CBAR** elements. The property cards for the **CQUAD4** and **CTRIA3** elements were **PCOMP** entries. The structural configuration of the FEM model is shown in Fig 4.3.1. A summary of the number of grid points and elements is shown in the following.

NUMBER OF GRID POINTS	428
NUMBER OF ELEMENTS	1680
CROD	432
CONM2	449
CCBAR	172
CQUAD4	623
<u>CTRIA3</u>	<u>4</u>

Two **CAERO7** cards were used to generate the aerodynamic boxes because the trailing edge consisted of two separate straight lines. The inboard wing was composed of 15 x 7 boxes and the outboard wing of 15 x 10 boxes, thus, the total number of boxes was 275.

Symmetric static aeroelastic analysis was performed and the trim parameters, angle-of-attack and control surface deflection angle, were calculated under a 10g pull-up condition with zero pitching rate and zero pitching acceleration at Mach M=0.80. The inboard control surface was assumed to be fixed. The trim parameters were calculated when the structure was rigid and when the structure had elastic deformation. The displacements at given **GRID** points and the stresses in each ply of the plate elements were calculated at this trim condition. **ZONA6** was used to calculate the aerodynamics.

The weight data output is shown in Table 4.3.1 including the fuselage weight. The longitudinal stability derivatives of the aircraft for both the rigid and elastic cases are shown in Table 4.3.2. The calculated trim parameters for both the rigid and flexible structure at the trim condition are given in Table 4.3.3. The calculated angle-of-attack, 4.06° for the rigid case, was reasonable and

a large deflection angle, -45.98° , of the control surface was necessary to obtain trim since no horizontal tail was included. The steady pressure distributions as attributed to each parameter such as thickness, camber, angle-of-attack, pitching rate, pitching acceleration, and control surface deflection are shown in Table 4.3.4. The steady pressure distributions in the trim condition for all trim parameters are shown in Fig 4.3.2. The vertical displacement at GRID point 415 on the wing tip was 5.506 in, and the deflection shape in the trim condition is presented in Fig 4.3.3. This value was later used as constraint in the structural design optimization. The required CPU time was 9 minutes 25.0 seconds.

4.3.2 Aerodynamic Configuration and Analysis by ENSAERO

The aerodynamic analysis of the wing was performed by the CFD code, ENSAERO. The aerodynamic configuration of the wing is shown in Fig 4.3.4. The input data for this model were very similar to those for the GAF model. Steady aerodynamic pressure coefficients were calculated for Navier-Stokes flow. For all cases, the Reynolds number was 10,000,000, and spanwise and normal viscous terms were used. For turbulence, the Baldwin-Lomax turbulence model was used and, for correction for vortex flow, Degani-Schiff modeling. The iteration indices were less than 1.0E-09, and there were about 500 iterations for Euler flow and then another 500+ iterations for Navier-Stokes flow. The total size of the grid was 151 x 44 x 34 in the x-, y-, and z- directions, respectively. The number of grid points on the wing was 61 x 34 on both the lower and upper surfaces. The results of the calculated aerodynamic pressure coefficients for Navier Stokes flow are shown in Fig 4.3.5 for four cases:

- (1) $M = 0.70, \alpha = 0.0^\circ$, (Navier-Stokes Flow)
- (2) $M = 0.70, \alpha = 5.0^\circ$, (Navier-Stokes Flow)
- (3) $M = 0.80, \alpha = 0.0^\circ$, (Euler Flow)
- (4) $M = 0.80, \alpha = 0.0^\circ$, (Navier-Stokes Flow)

Fig 4.3.5 shows that the DAST model was just entering the transonic regime at Mach $M = 0.7$ when the angle-of-attack was 0.0° and was in the transonic regime at Mach 0.8. The strength of the shock in Euler flow was larger than that in Navier-Stokes flow.

4.3.3 Normal Modes Analysis Using ASTROS*

Natural frequencies, the associated modes shapes, and the generalized stiffness and mass matrices were calculated in the normal modes discipline as for the GAF model. To calculate eigenvalues, the INV (Inverse Power) method was used. Normal modes data for 10 modes from the lowest to 200.0 Hz were calculated for a symmetric boundary condition. The axial direction of the fuselage was fixed. The first two modes were the rigid body modes, vertical translation and pitching rotation. The lowest seven natural frequencies of the elastic modes were 11.3, 48.7, 55.7, 103.3, 130.8, 147.8, and 199.0 Hz. The required CPU time was 2 minutes 11.0 seconds.

The results of the computations are shown in Table 4.3.5, and the mode shapes are plotted in Fig 4.3.6. These data were later used in the flutter analysis. The lowest natural frequency, 10.22 Hz, was used as a constraint in the normal modes design optimization.

4.3.4 Flutter Analysis

Flutter analyses were performed by the K-method in ASTROS* and by the root-locus method for a Mach number of $M = 0.80$ using ZONA6 and ZTAIC methods. The results from ASTROS* and the root-locus method were compared and are shown in Table 4.3.6. The generalized unsteady aerodynamic loads calculated in ASTROS* were used in the root-locus method.

These generalized unsteady aerodynamic loads at $M = 0.85$ calculated by ZONA6 in ASTROS* and are shown in Fig 4.3.7. The generalized unsteady aerodynamic loads calculated by ZONA6 and approximated by the minimum-state method at $M = 0.85$ are presented in Fig 4.3.8. The V-f and V-g plots for the flutter results by ZONA6 in ASTROS* are shown in Fig 4.3.9 and the root-locus plots to calculate the flutter speed using the aerodynamics of ZONA6 in ASTROS* are given in Figs 4.3.10. The V-f and V-g plots for the flutter results by ZTAIC in ASTROS* are shown in Fig 4.3.11, and the root-locus plots to calculate the flutter speed using the aerodynamics of ZTAIC in ASTROS* are given in Figs 4.3.12. The flutter speed and flutter frequency by the K-method and ZONA6 were 14,358 *in/sec* and 48.67 Hz, respectively. The flutter speed and flutter frequency by the root-locus method and ZONA6 were 13,490 *in/sec* and 36.3 Hz, respectively. The flutter speed and flutter frequency by the K-method and ZTAIC were 11,800 *in/sec* and 56.01 Hz, respectively. Finally, the flutter speed and flutter frequency by the root-locus method and ZTAIC were 12,892 *in/sec* and 49.30 Hz, respectively. The required CPU time by the K-method and ZONA6 of ASTROS* was 13 minutes 13.5 seconds and that by the K-method and ZTAIC of ASTROS* 5 hours 22 minutes 31.4 seconds, respectively.

Table 4.3.1 Weight Data Output of DAST Model.

OUTPUT FROM GRID POINT WEIGHT GENERATOR

REFERENCE POINT = 1

XO = 2.417731E+02, YO = 1.805970E+01, ZO = 5.992480E+01

M O

* 1.3002E+03 0.0000E+00 0.0000E+00 0.0000E+00 -1.258E+03 6.7508E+03 *
 * 0.0000E+00 1.3002E+03 0.0000E+00 1.2586E+03 0.000E+00 2.6715E+04 *
 * 0.0000E+00 0.0000E+00 1.3002E+03 -6.7508E+03 -2.671E+04 0.0000E+00 *
 * 0.0000E+00 1.2586E+03 -6.7508E+03 3.3057E+05 5.025E+04 2.8499E+04 *
 * -1.2586E+03 0.0000E+00 -2.6715E+04 5.0253E+04 8.815E+05 1.1363E+03 *
 * 6.7508E+03 2.6715E+04 0.0000E+00 2.8499E+04 1.136E+03 1.1457E+06 *

DIRECTION

<u>AXIS SYSTEM (S)</u>	<u>MASS</u>	<u>X-C.G.</u>	<u>Y-C.G.</u>	<u>Z-C.G.</u>
X	1.300231E+03	0.000000E+00	-5.192037E+00	-9.680215E-01
Y	1.300231E+03	2.054661E+01	0.000000E+00	-9.680215E-01
Z	1.300231E+03	2.054661E+01	-5.192037E+00	0.000000E+00

I(Q)

* 5.62043E+05 *
 * 2.22358E+05 *
 * 4.03149E+05 *

Table 4.3.2 Non-Dimensional Longitudinal Stability Derivatives of DAST Model:
 10g Pull-up Maneuver, $M = 0.8$, by ZONA6 of ASTROS* for Rigid and Flexible Structure.

<u>TRIM IDENTIFICATION</u>	= 1	<u>REFERENCE GRID</u>	= 446
<u>REFERENCE AREA</u>	= 2.8236E+03	<u>REFERENCE CHORD</u>	= 4.0000E+01
<< LIFT >> << PITCHING MOMENT >>			
<u>PARAMETER</u>	<u>RIGID DIRECT</u>	<u>RIGID SPLINED</u>	<u>FLEX. DIRECT</u>
		<u>SPLINED</u>	<u>RIGID SPLINED</u>
Thickness/Camber	0.9860	0.9876	0.9097 -0.5291 -0.5291 -0.4653
Angle of Attack (1/deg)	0.2222	0.2224	0.2193 -0.0821 -0.0822 -0.0751
Angle of Attack (1/rad)	12.7330	12.7418	12.5669 -4.7045 -4.7117 -4.3015
Pitch Rate (s/deg)	0.3004	0.3007	0.2889 -0.1578 -0.1579 -0.1427
Pitch Rate (s/rad)	17.2142	17.2293	16.5505 -9.0398 -9.0457 -8.1754
Control Surface 1 (1/deg)	0.0255	0.0255	0.0241 -0.0119 -0.0119 -0.0110
Control Surface 1 (1/rad)	1.4584	1.4597	1.3820 -0.6799 -0.6804 -0.6292
Control Surface 2 (1/deg)	0.0105	0.0105	0.0086 -0.0104 -0.0104 -0.0085
Control Surface 2 (1/rad)	0.6039	0.6039	0.4951 -0.5945 -0.5945 -0.4863

Table 4.3.3 Trim Parameters of DAST Model:
10g Pull-up Maneuver, $M = 0.80$, by ZONA6 of ASTROS* for Rigid and Flexible Structure.

TRIM RESULTS FOR TRIM SET 1 OF TYPE PITCH

MACH NUMBER 8.00000E-01

DYNAMIC PRESSURE 6.55000E+00

VELOCITY 1.02700E+04

TRIM PARAMETERS:

DEFINITION	LABEL	FLEXIBLE	RIGID	
LOAD FACTOR	"NZ"	3.86399E+03	3.86399E+03	(Input)
PITCH ACCELERATION "QACCEL"	0.00000E+00	0.00000E+00	rad/s ²	(Input)
ANGLE OF ATTACK	"ALPHA"	4.03914E+00	4.06115E+00	deg (Computed)
CONTROL SURFACE	"AIL1"	0.00000E+00	0.00000E+00	deg (Input)
CONTROL SURFACE	"AIL2"	-4.50767E+01	-4.59823E+01	deg (Computed)
PITCH RATE	"QRATE"	0.00000E+00	0.00000E+00	deg/s (Input)
THICKNESS/CAMBER	"THKCAM"	1.00000E+00	1.00000E+00	(Input)

Table 4.3.4 Pressure Distribution of DAST Model:
10g Pull-up Maneuver, $M = 0.80$, by ZONA6 of ASTROS*, for Rigid Structure.

***** STEADY RIGID AERODYNAMIC PRESSURE OF TRIM PARAMETERS, MACH = 0.8

	NZ	/ QACCEL	/ THKCAM	/ ALPHA	/ QRATE	/ AIL1	/ AIL2	/
EXT ID	1.00000	1.00000	1.00000	1.00000	1.00000	1.00000	1.00000	
100001	0.000E+00	0.0000E+00	0.1187E+01	0.3902E+00	0.1944E+02	0.1130E-01	0.1297E-02	
100002	0.000E+00	0.0000E+00	0.3618E-02	0.1648E+00	0.5510E+02	0.5688E-02	0.6083E-03	
100003	0.000E+00	0.0000E+00	0.3257E+00	0.1358E+00	0.7387E+02	0.5331E-02	0.5410E-03	
100004	0.000E+00	0.0000E+00	0.3145E+00	0.1146E+00	0.8996E+02	0.5203E-02	0.4977E-03	
100005	0.000E+00	0.0000E+00	0.2030E+00	0.9709E-01	0.1070E+03	0.5334E-02	0.4711E-03	
100006	0.000E+00	0.0000E+00	0.1223E+00	0.8566E-01	0.1186E+03	0.5604E-02	0.4587E-03	
100007	0.000E+00	0.0000E+00	0.1675E+00	0.7631E-01	0.1269E+03	0.5946E-02	0.4493E-03	
100008	0.000E+00	0.0000E+00	0.2747E+00	0.6763E-01	0.1321E+03	0.6348E-02	0.4390E-03	
100010	0.000E+00	0.0000E+00	0.3706E+00	0.5213E-01	0.1314E+03	0.7075E-02	0.4055E-03	
100011	0.000E+00	0.0000E+00	0.5720E+00	0.4458E-01	0.1249E+03	0.7226E-02	0.3770E-03	
100012	0.000E+00	0.0000E+00	0.7607E+00	0.3684E-01	0.1134E+03	0.7027E-02	0.3366E-03	
100013	0.000E+00	0.0000E+00	0.8239E+00	0.2910E-01	0.9704E+02	0.6332E-02	0.2843E-03	
100014	0.000E+00	0.0000E+00	0.7120E+00	0.2675E-01	0.9062E+02	0.5954E-02	0.2648E-03	
100095	0.000E+00	0.0000E+00	0.1553E+00	0.1345E+00	0.1924E+03	0.1359E-01	0.1047E-02	
100096	0.000E+00	0.0000E+00	0.3246E+00	0.1135E+00	0.1798E+03	0.1395E-01	0.9832E-03	
100097	0.000E+00	0.0000E+00	0.3363E+00	0.9745E-01	0.1695E+03	0.1480E-01	0.9392E-03	
100098	0.000E+00	0.0000E+00	0.3187E+00	0.8368E-01	0.1593E+03	0.1623E-01	0.9021E-03	
100099	0.000E+00	0.0000E+00	0.3592E+00	0.7209E-01	0.1489E+03	0.1820E-01	0.8664E-03	
100100	0.000E+00	0.0000E+00	0.4803E+00	0.6178E-01	0.1373E+03	0.2069E-01	0.8246E-03	
100101	0.000E+00	0.0000E+00	0.6898E+00	0.5213E-01	0.1240E+03	0.2341E-01	0.7692E-03	
100102	0.000E+00	0.0000E+00	0.9059E+00	0.4272E-01	0.1080E+03	0.2483E-01	0.6926E-03	
100103	0.000E+00	0.0000E+00	0.1037E+01	0.3365E-01	0.8960E+02	0.2183E-01	0.5918E-03	
100104	0.000E+00	0.0000E+00	0.9455E+00	0.3095E-01	0.8326E+02	0.1956E-01	0.5533E-03	
100105	0.000E+00	0.0000E+00	0.4757E+00	0.1950E-01	0.5492E+02	0.1143E-01	0.3741E-03	
200001	0.000E+00	0.0000E+00	0.1347E+01	0.6808E+00	0.7119E+03	0.4181E-01	0.4223E-02	
200002	0.000E+00	0.0000E+00	0.6021E+00	0.2752E+00	0.3165E+03	0.1890E-01	0.1857E-02	
200003	0.000E+00	0.0000E+00	0.4546E+00	0.2171E+00	0.2684E+03	0.1633E-01	0.1574E-02	

200004	0.000E+00	0.0000E+00	0.3411E+00	0.1745E+00	0.2343E+03	0.1468E-01	0.1382E-02
200005	0.000E+00	0.0000E+00	0.1682E+00	0.1392E+00	0.2075E+03	0.1374E-01	0.1245E-02
200006	0.000E+00	0.0000E+00	0.3490E+00	0.1173E+00	0.1910E+03	0.1351E-01	0.1175E-02
200007	0.000E+00	0.0000E+00	0.3562E+00	0.1005E+00	0.1777E+03	0.1358E-01	0.1127E-02
200008	0.000E+00	0.0000E+00	0.3296E+00	0.8611E-01	0.1650E+03	0.1378E-01	0.1088E-02
200009	0.000E+00	0.0000E+00	0.3721E+00	0.7399E-01	0.1524E+03	0.1393E-01	0.1049E-02
200010	0.000E+00	0.0000E+00	0.4953E+00	0.6319E-01	0.1392E+03	0.1375E-01	0.1002E-02
200141	0.000E+00	0.0000E+00	0.1783E+00	0.5911E-01	0.1498E+03	0.2110E-02	0.1439E-01
200142	0.000E+00	0.0000E+00	0.1566E+00	0.4419E-01	0.1179E+03	0.1622E-02	0.1467E-01
200143	0.000E+00	0.0000E+00	0.1282E+00	0.3330E-01	0.9427E+02	0.1258E-02	0.1525E-01
200144	0.000E+00	0.0000E+00	0.1625E+00	0.2552E-01	0.7700E+02	0.9911E-03	0.1575E-01
200145	0.000E+00	0.0000E+00	0.2705E+00	0.1968E-01	0.6344E+02	0.7840E-03	0.1564E-01
200146	0.000E+00	0.0000E+00	0.4903E+00	0.1504E-01	0.5200E+02	0.6138E-03	0.1425E-01
200147	0.000E+00	0.0000E+00	0.6968E+00	0.1123E-01	0.4173E+02	0.4692E-03	0.1147E-01
200148	0.000E+00	0.0000E+00	0.8203E+00	0.8135E-02	0.3242E+02	0.3474E-03	0.8347E-02
200149	0.000E+00	0.0000E+00	0.6733E+00	0.7355E-02	0.2975E+02	0.3151E-03	0.7491E-02
200150	0.000E+00	0.0000E+00	0.2064E+00	0.4303E-02	0.1867E+02	0.1880E-03	0.4241E-02

Table 4.3.5 Results of Normal Modes Analysis of DAST Model.

MODE EXTRACTION ORDER	EIGENVALUE (rad/sec) ²	FREQUENCY (Hz)	GENERALIZED MASS	STIFFNESS
1	1	0.00000E+00	0.00000E+00	1.00000E+00
2	2	0.00000E+00	0.00000E+00	1.00000E+00
3	7	5.03062E+03	1.12884E+01	1.00000E+00
4	6	9.34976E+04	4.86654E+01	1.00000E+00
5	4	1.22573E+05	5.57209E+01	1.00000E+00
6	3	4.21470E+05	1.03325E+02	1.00000E+00
7	5	6.75673E+05	1.30824E+02	1.00000E+00
8	8	8.62662E+05	1.47822E+02	1.00000E+00
9	9	1.56335E+06	1.98998E+02	1.00000E+00

Table 4.3.6 Results of Flutter Analyses of DAST Model.

No.	Mach	Method	Flutter Speed (in/sec)	Flutter Freq. (Hz)	Remarks
1	0.80	k-method (ZONA6)	14,357.3	48.67	
2	0.80	Root-locus (ZOZA6)	13,489.5	36.30	
3	0.80	k-method (ZTAIC)	11,800.0	56.01	
4	0.80	Root-locus (ZTAIC)	12,892.0	49.30	

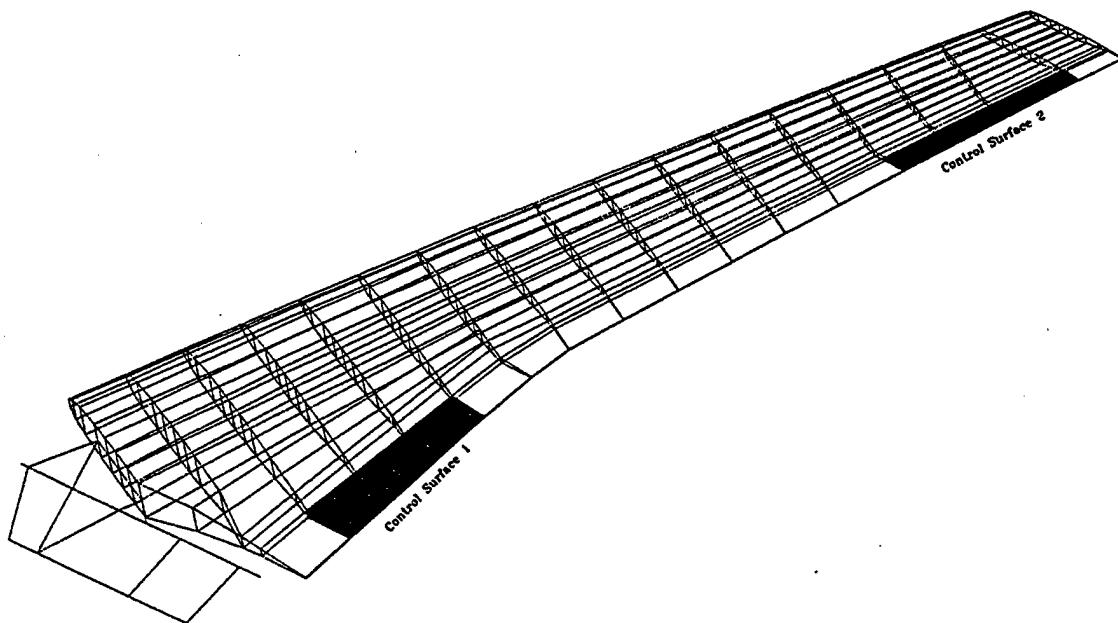


Figure 4.3.1 Structural Configuration of DAST Model by FEM.

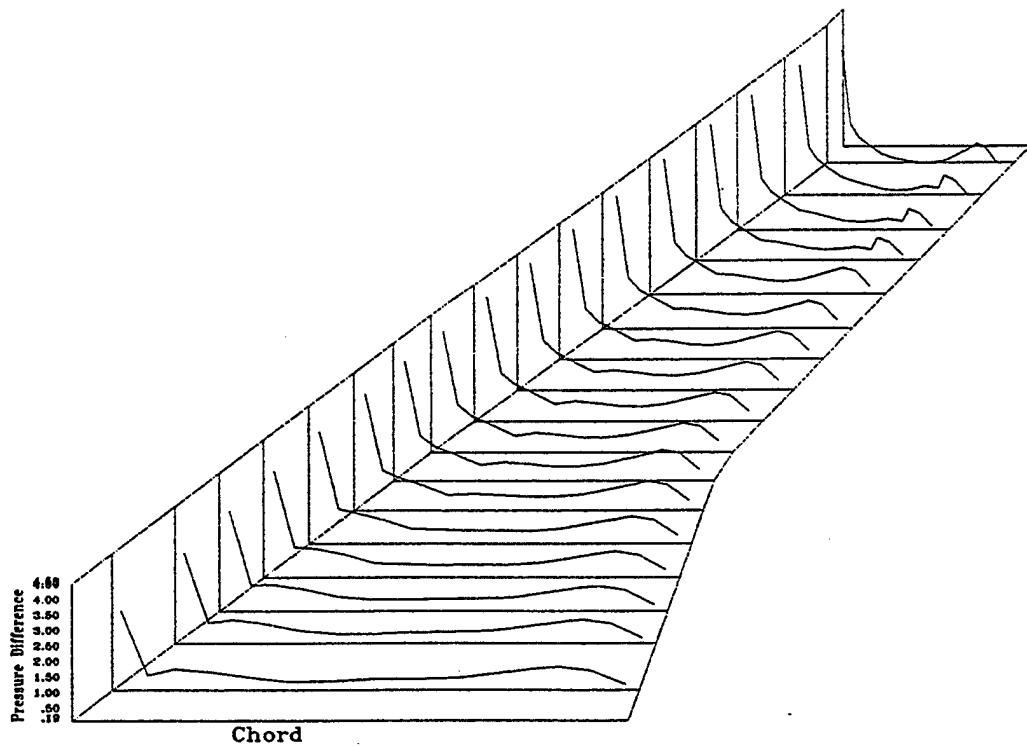


Figure 4.3.2 Pressure Distribution of DAST Model: 10g Pull-up Trim Condition, $M = 0.80$, by ZONA6 of ASTROS*.

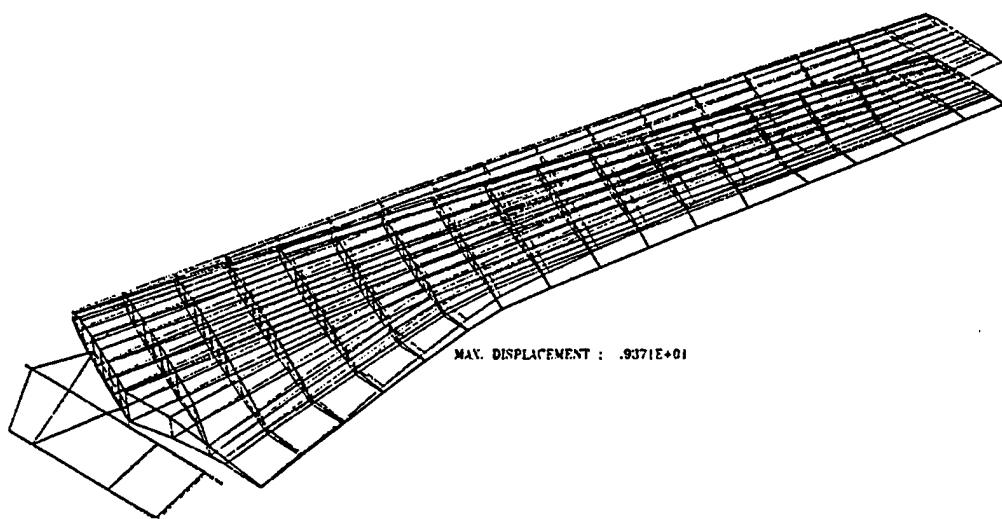


Figure 4.3.3 Deflection Shape of DAST Model: 10g Trim Condition, $M = 0.80$, by ZONA6 of ASTROS*.

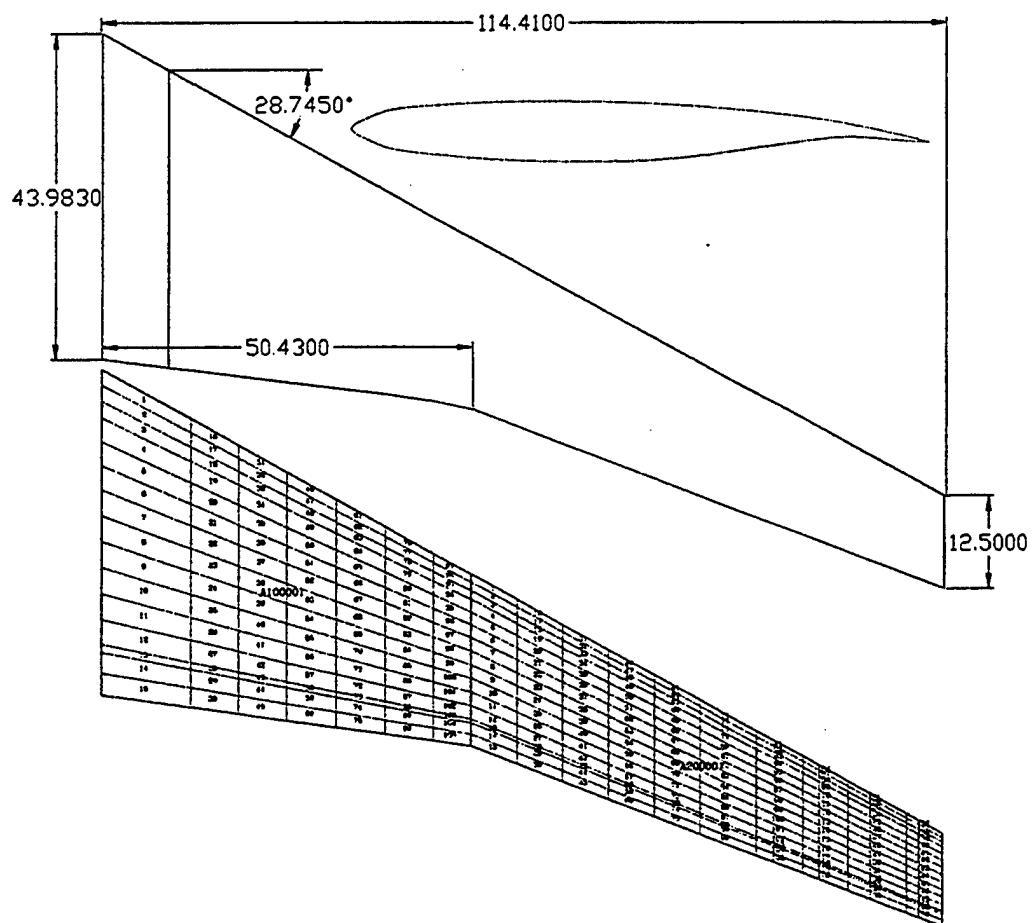


Figure 4.3.4 Aerodynamic Planform Configuration of DAST Model.

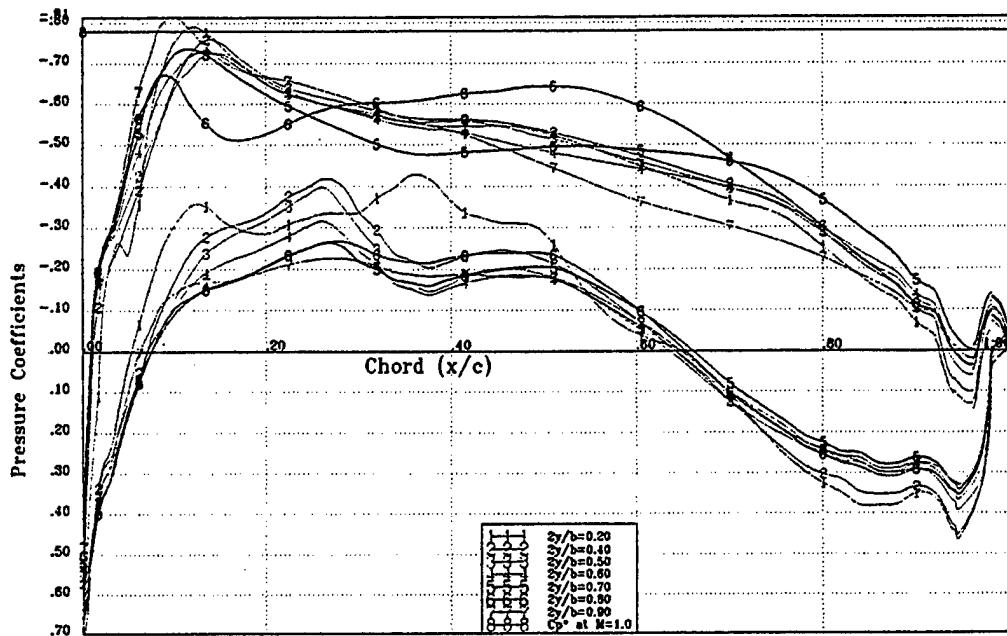


Figure 4.3.5.a Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.70$, $\text{AoA} = 0.0^\circ$, by ENSAERO.

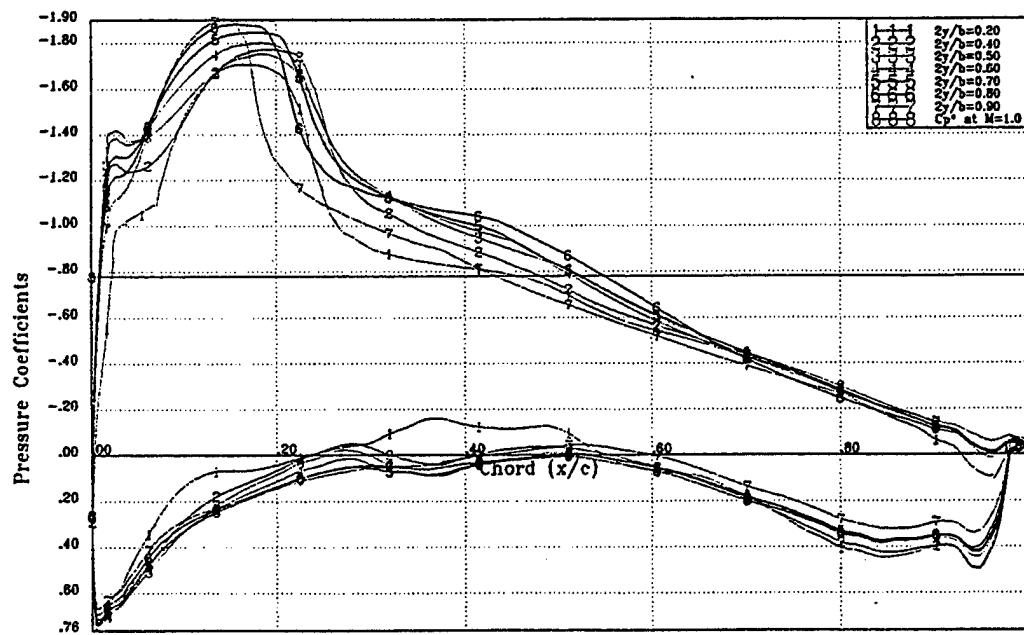


Figure 4.3.5.b Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.70$, $\text{AoA}=5.0^\circ$, by ENSAERO.

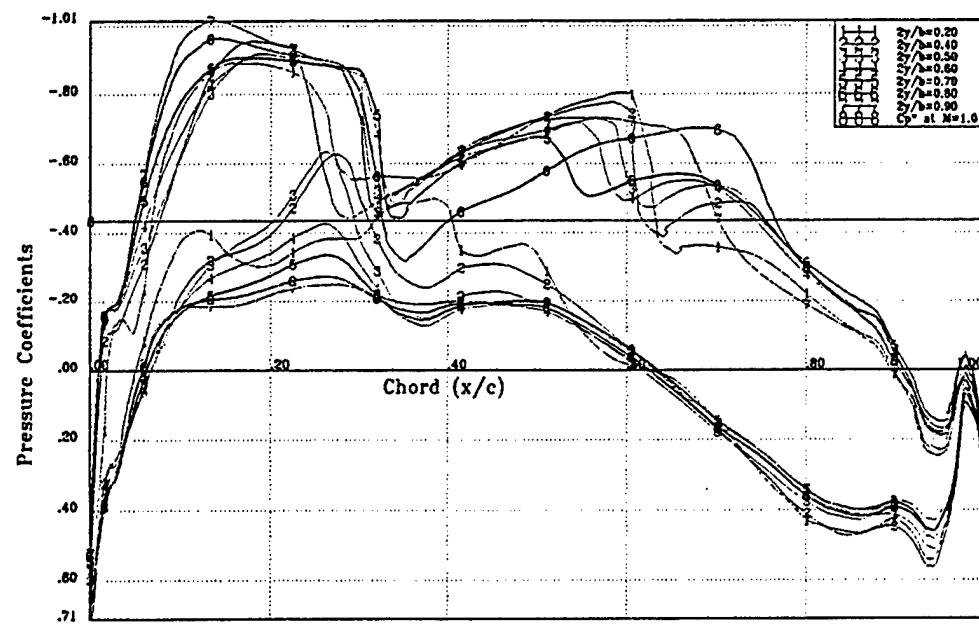


Figure 4.3.5.c Aerodynamic Pressure Coefficients of DAST Model for Euler Flow: $M = 0.80$, $\text{AoA}=0.0^\circ$, by ENSAERO.

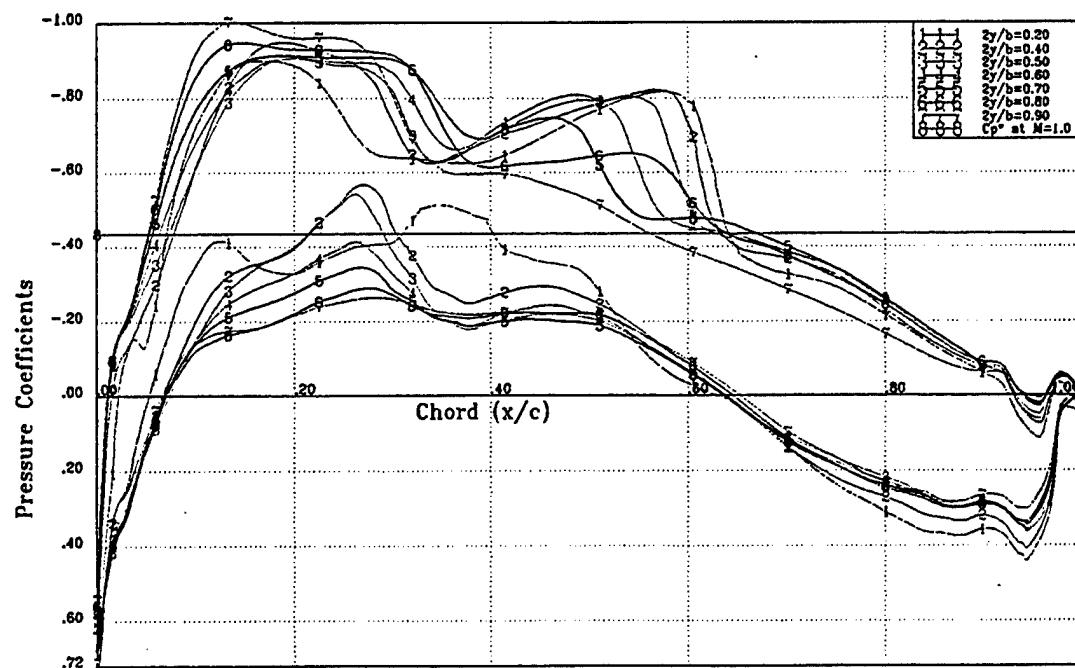


Figure 4.3.5.d Aerodynamic Pressure Coefficients of DAST Model for Navier-Stokes Flow: $M = 0.80$, $\text{AoA}=0.0^\circ$, by ENSAERO.

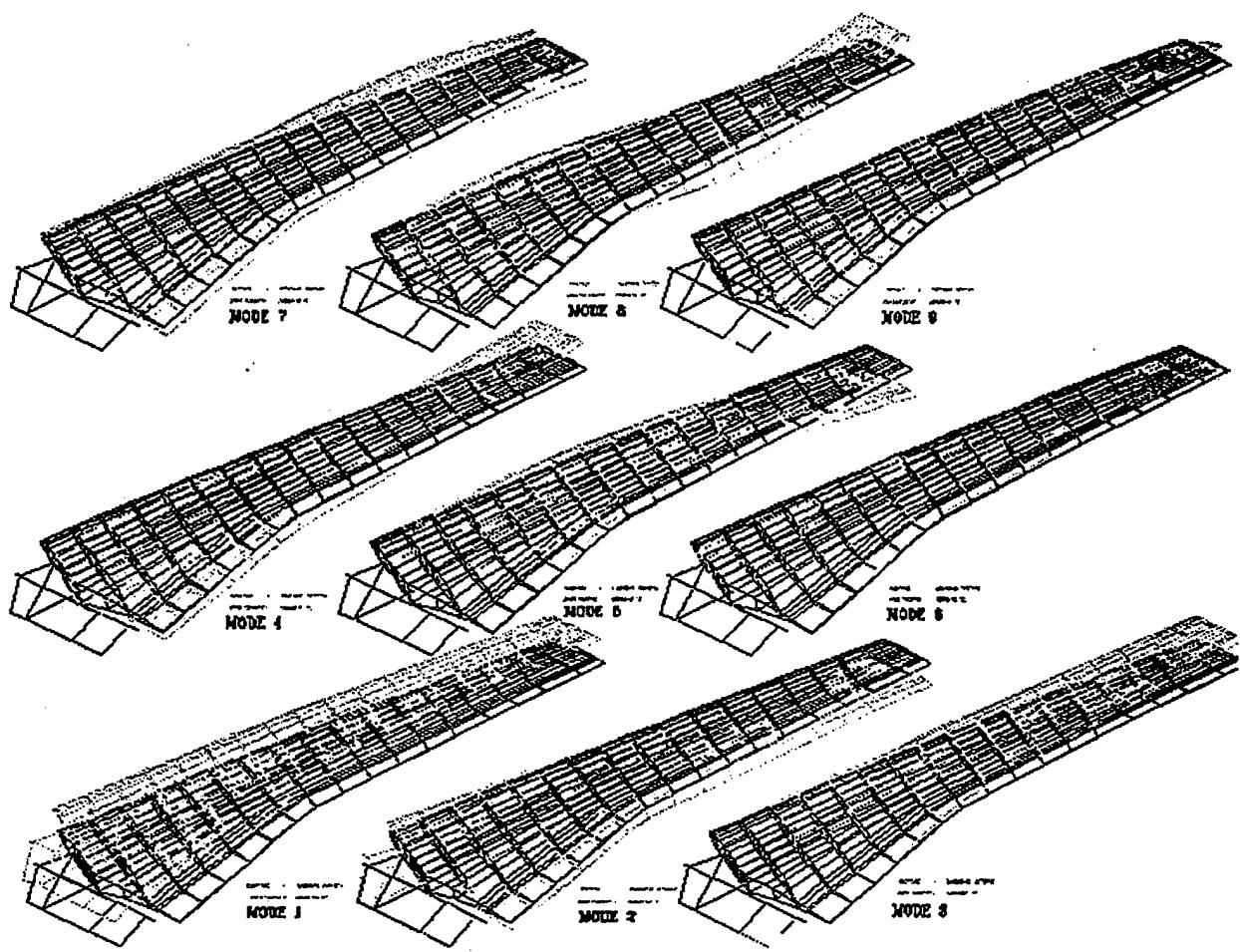


Figure 4.3.6 Normal Modes of DAST Model.

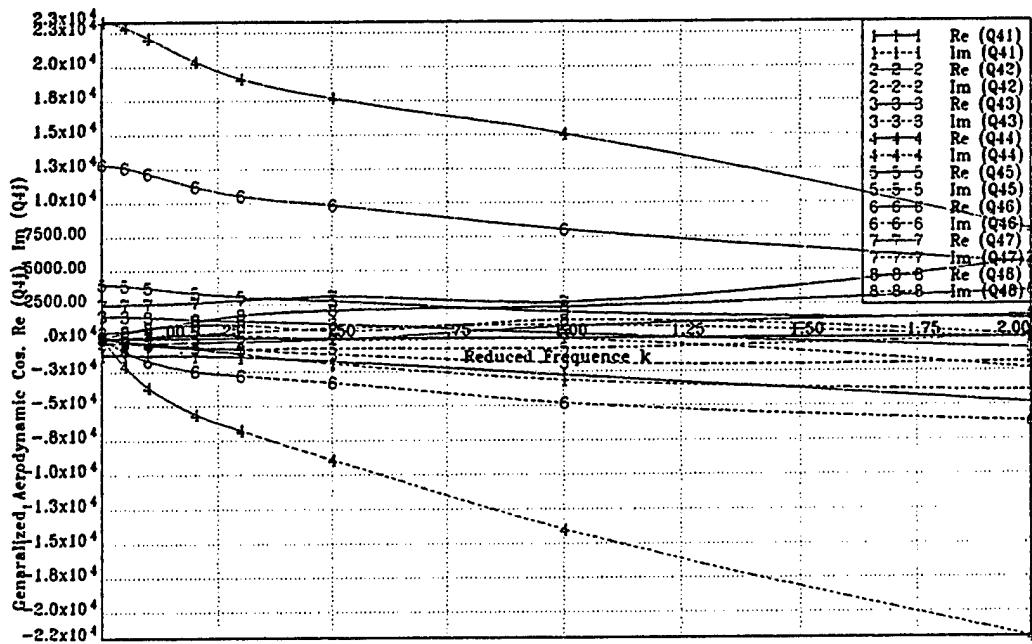


Figure 4.3.7 Generalized Unsteady Aerodynamic Loads of DAST Model: $M = 0.80$, by ZONA6 of ASTROS*.

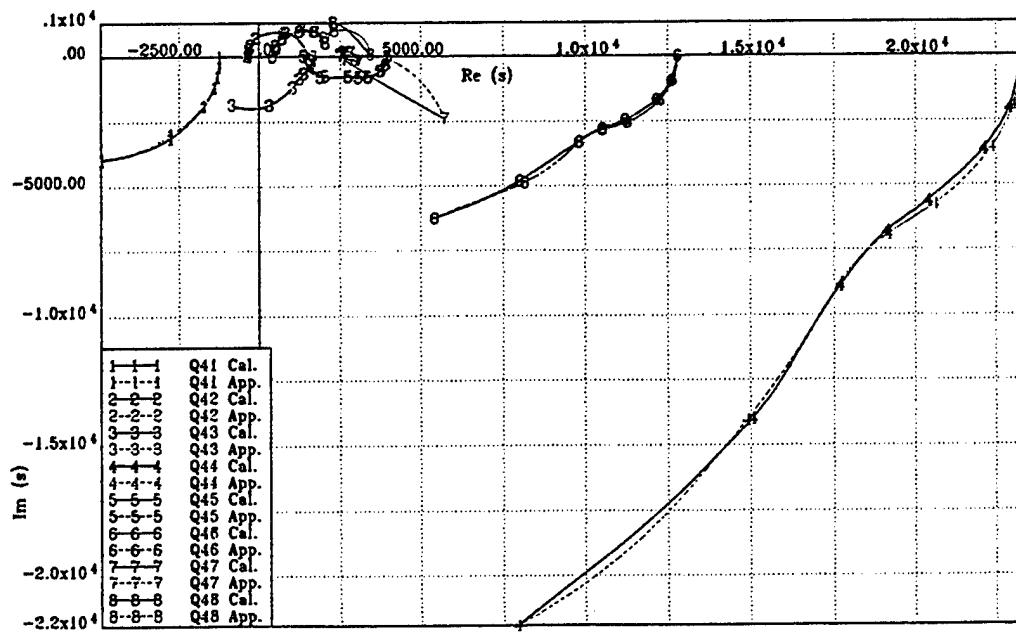


Figure 4.3.8 Generalized Unsteady Aerodynamic Coefficients Q_{ij} of DAST Model: $M = 0.80$, by ZONA6 of ASTROS* and Approximated by Minimum-State Method.

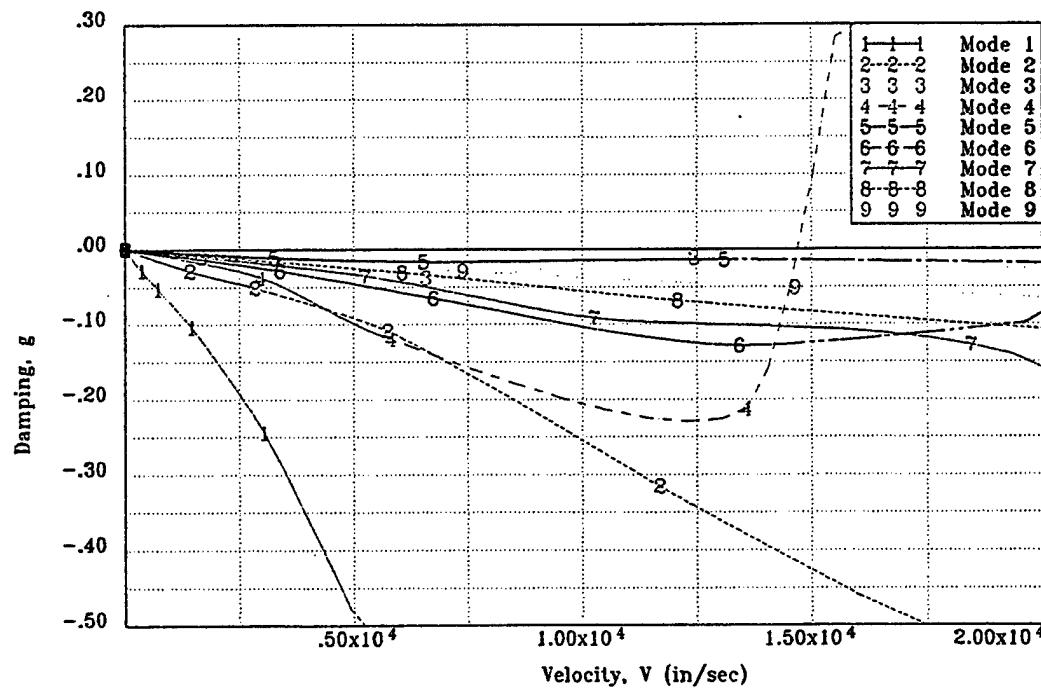
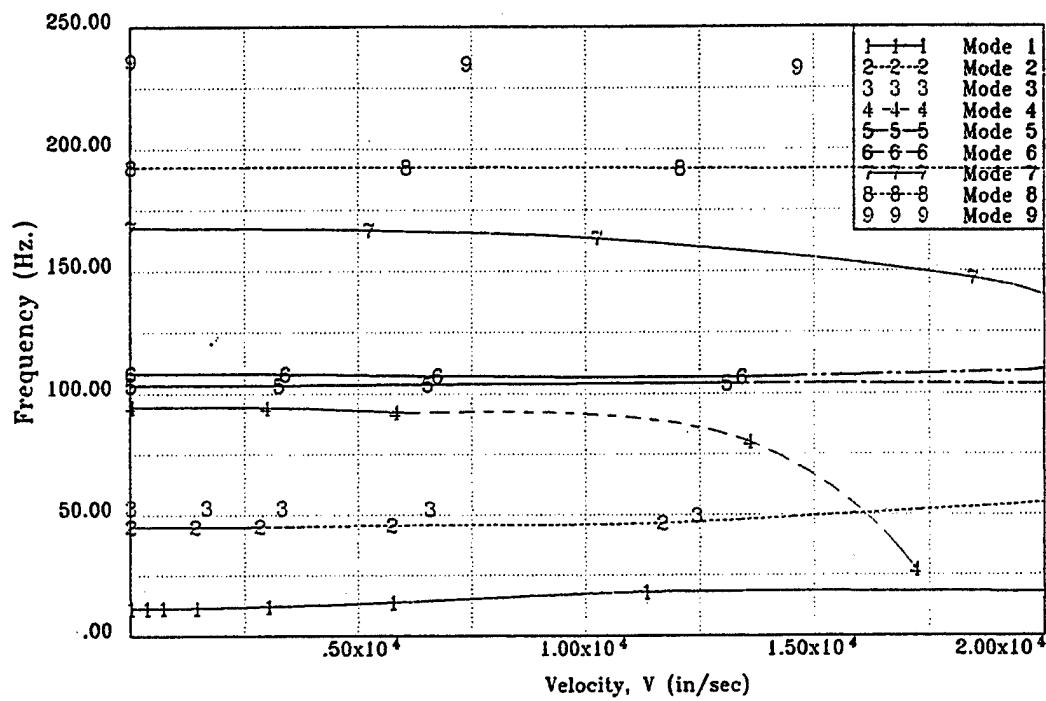


Figure 4.3.9 V-f and V-g Plots of DAST Model: $M = 0.80$, by ZONA6 of ASTROS* (Flutter Speed = 14,358 in/sec, Flutter Frequency = 48.67 Hz).

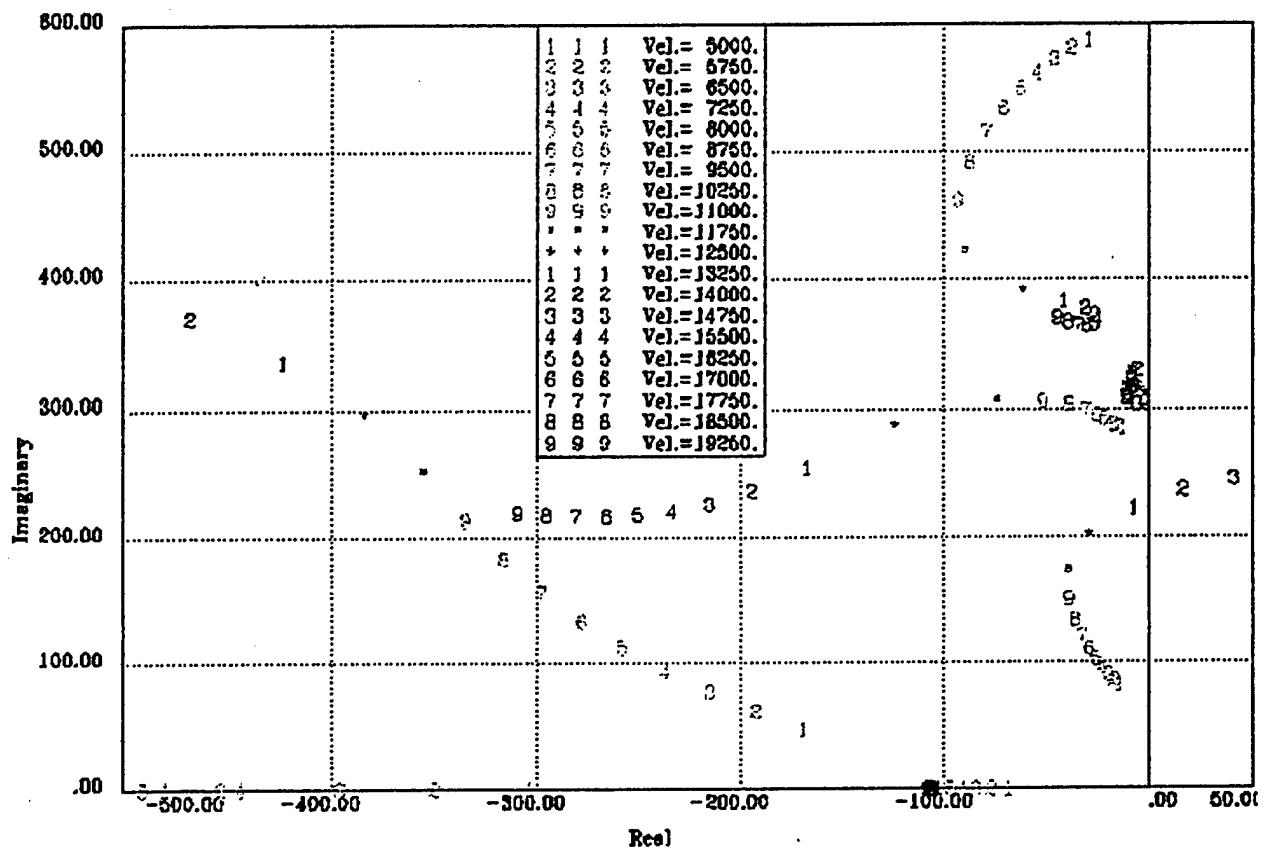


Figure 4.3.10 Root-Locus Plot of DAST Model: $M = 0.80$, ZONA6 of ASTROS* (Flutter Speed = 13,490 in/sec, Flutter Frequency = 36.3 Hz).

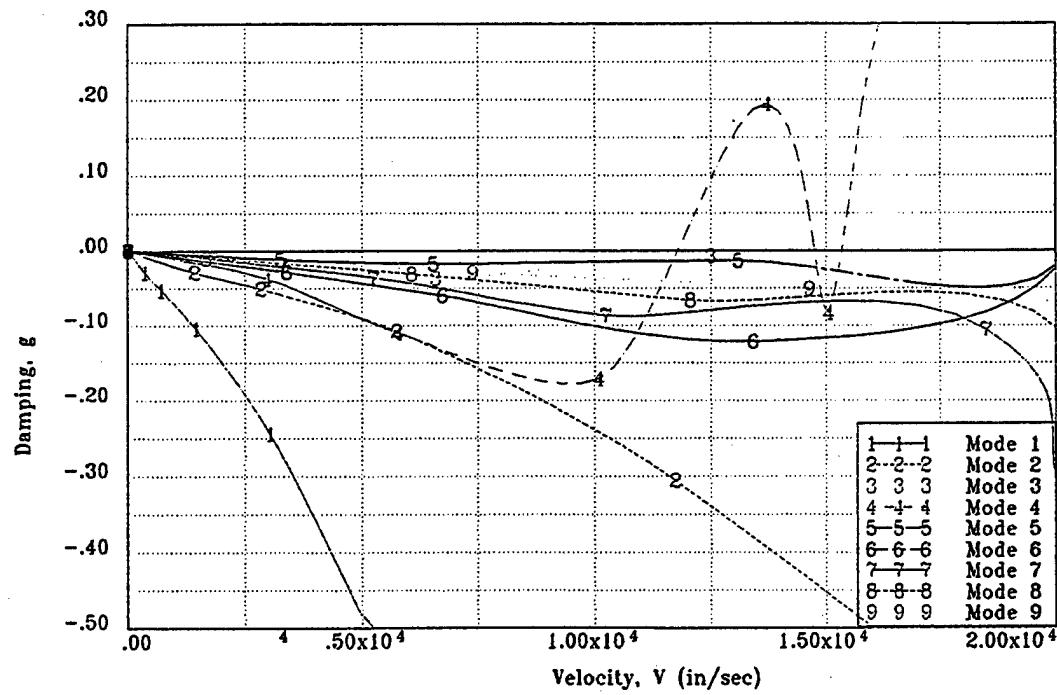
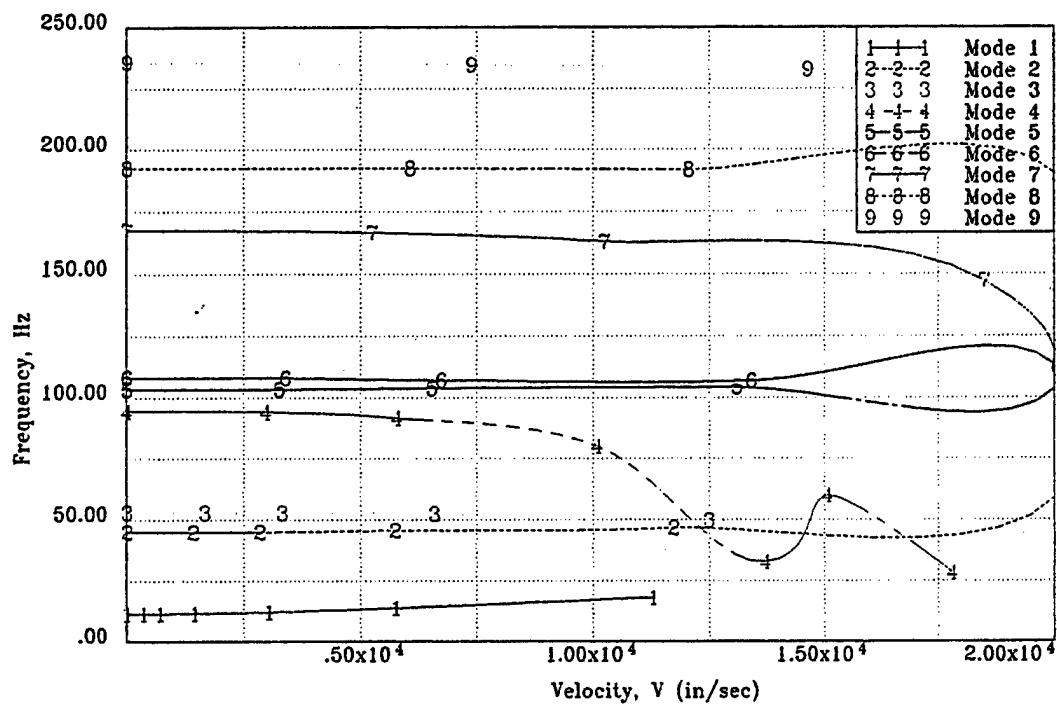


Figure 4.3.11 V-f and V-g Plots of DAST Model: $M = 0.80$, by ZTAIC of ASTROS* (Flutter Speed = 11,800 in/sec, Flutter Frequency = 56.0 Hz)

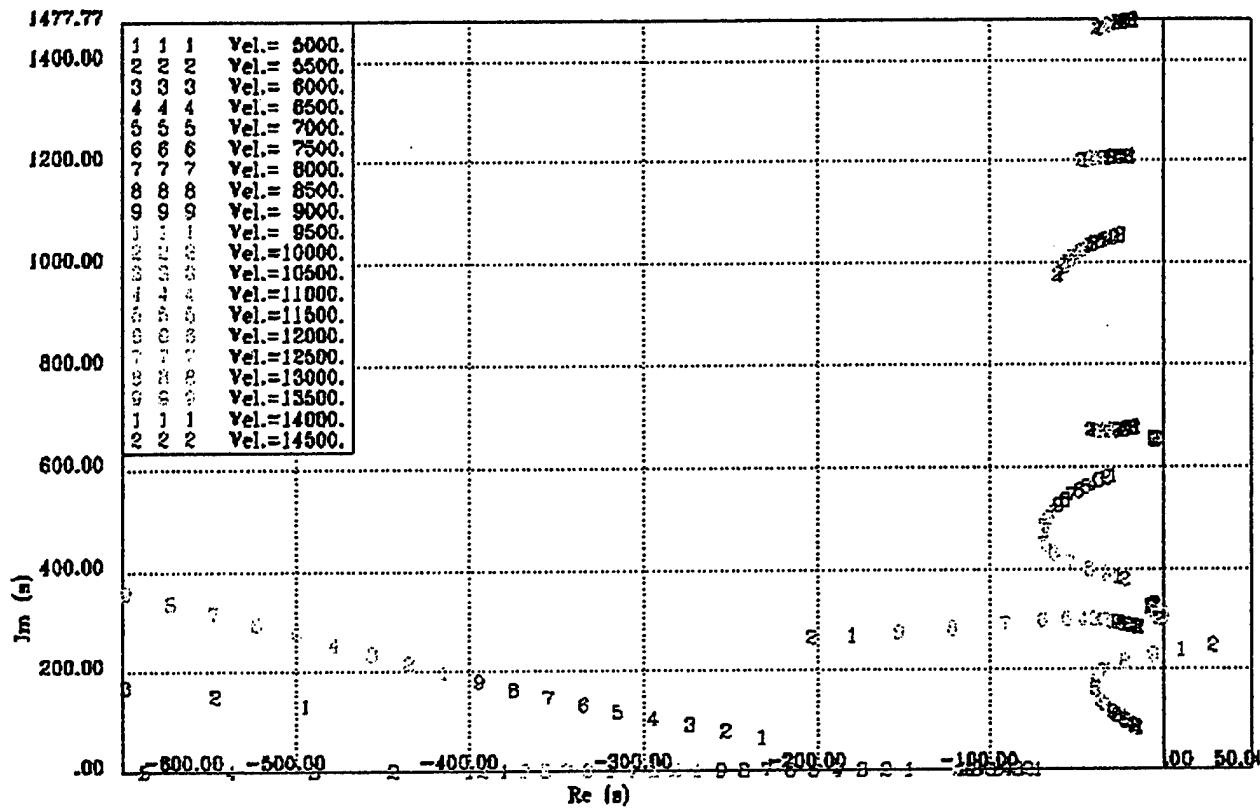


Figure 4.3.12 Root-Locus Plot of DAST Model: $M = 0.80$, by ZTAIC of ASTROS* (Flutter Speed = 12,893 in/sec, Flutter Frequency = 49.3 Hz).

4.4 Case 2.b: DAST (Drones for Aerodynamic and Structural Testing) Wing Model Optimization

- **Purpose:** To test a composite structural wing model in static aeroelastic, normal modes, and combined optimization.
- **Description of input and results:**

4.4.1 Static Aeroelastic Optimization

Static aeroelastic structural design optimization was performed in the 10g pull-up trim condition. The total weight of the wing skins and the spar caps was optimized. At the final design point, the trim parameters angle-of-attack and control surface deflection angle were required to match those of the analysis. The design variables were the ply thicknesses of the composite material skins and the areas of the spar caps. The minimum thicknesses of the individual plies were assumed to be 0.01 in. A displacement constraint at the wing tip, 5.506 in, was the same as the displacement from the original analysis. The Tsai-Wu failure criteria were used as strength constraints for the composite material. The required stresses in the CBAR elements were taken to be the von Mises stresses.

The design variables were defined by **DESVARP** entries, and each ply thickness was a design variable. Then, the properties of some of the elements were defined to the same design variables, with the effect of linking the variables. The number of properties to be determined was 989 and the number of global design variables was 254. The design variables and their numbering are shown in Fig 4.4.1.

As a result of the design optimization for static aeroelasticity, the wing weight was reduced from 89.49 *lbs* to 10.96 *lbs* in only 18 iterations. The iteration history of the design optimization is shown in Table 4.4.1. The results from the final analysis satisfied the constraints. Required CPU time was 2 hours 40 minutes 33.3 seconds.

4.4.2 Normal Modes Optimization

In the normal modes optimization, the constraint was a lower bound on the first elastic natural frequency of the structure. The required frequency was 11.288 *Hz*, the same as that calculated in the analysis of the original structure.

As a result, the weight was reduced from 89.49 *lbs* to 9.43 *lbs*. This result was obtained in only 9 iterations. The iteration history of the design optimization is shown in Table 4.4.2. The required CPU time was 18 minutes 34.0 seconds.

4.4.3 Multidisciplinary Design Optimization for Static Aeroelasticity and Normal Modes

Multidisciplinary design optimization for static aeroelasticity and normal modes was performed simultaneously. The displacements and stresses in a 10g trim condition and the lowest natural frequency were again used as the constraints.

As a result, the weight was reduced from 89.49 *lbs* to 10.86 *lbs*. This result was obtained in only 11 iterations. The CPU time was 2 hours 53 minutes 42.3 seconds. The iteration history of the design optimization is shown in Table 4.4.3 and Fig 4.4.2. The final design variables are presented in Table 4.4.4. In the layer list, 1, 2, 3, and 4 identify the 90° , $+45^\circ$, -45° , and 0° directions of the skin layers, respectively. Here, the thickness of the layer in the 0° direction with layer list number 4 (in the spar direction) was larger than those of the other layers.