Q-Learning adalah algoritma reinforcement learning. Tujuan Q-Learning adalah untuk membentuk kebijakan/policy berdasarkan lingkungannya (reward atau punishment).

Sebuah agen Q-learning tediri atas set *States* dan set *Actions*. Dengan melakukan action, agen mengalami trasnsisi ke state lain. Tujuan agen adalah memaksimalkan total reward kedepanya dengan cara melihat dan mengakumulasi reward pada state selanjutnya.

Q-Learning menggunakan formula berikut untuk melakukan tranisi:

$$Q(state, action) \leftarrow (1 - \alpha)Q(state, action) + \alpha \bigg(reward + \gamma \max_{a} Q(next \ state, all \ actions)\bigg)$$

Nilai  $\alpha$  mempengaruhi learning rate agen. Nilai yang besar dapat mempercepat proses learning, namun akan menghasilkan osilasi pada skenario tertentu.

Nilai  $\gamma$  mempengaruhi agen dalam mengambil reward sekarang vs masa depan (nilai mendekati 0, agen akan memperioritaskan reward sekarang)

Berikut adalah algoritma Q-Learning:

- 1. Inisialisasi tabel Q
- 2. Untuk setiap episode
  - a. Inisialisasi state s
  - b. Untuk setiap langkah pada episode tersebut

Lakukan action random pada state tersebut secara random (eksploratif)

Saat mengambil aksi action, cek nilai rewardnya pada state' (state masa depan)

Update: 
$$Q(state, action) \leftarrow (1 - \alpha)Q(state, action) + \alpha \left(reward + \gamma \max_{a} Q(next state, all actions)\right)$$
  
Update: State  $\leftarrow$  state'

## Hasil running program menggunakan python

## Parameter:

Episode= 1500, maximum step = 100,  $\alpha$  = 0.5,  $\gamma$  = 1.0

Nilai reward pada tabel berikut, close untuk lanjut

| -1.0 | -2.0 | -3.0 | -2.0 | -3.0 | -3.0 | -4.0 | -1.0 | -4.0 | -2.0 | -1.0 | -2.0 | -3.0 | -3.0 | 500.0 |
|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-------|
| -1.0 | -3.0 | -1.0 | -2.0 | -4.0 | -1.0 | -4.0 | -1.0 | -4.0 | -2.0 | -4.0 | -2.0 | -2.0 | -2.0 | -1.0  |
| -4.0 | -2.0 | -1.0 | -4.0 | -2.0 | -1.0 | -2.0 | -4.0 | -2.0 | -3.0 | -2.0 | -1.0 | -2.0 | -4.0 | -4.0  |
| -4.0 | -2.0 | -4.0 | -1.0 | -3.0 | -2.0 | -3.0 | -2.0 | -4.0 | -2.0 | -4.0 | -1.0 | -2.0 | -4.0 | -2.0  |
| -4.0 | -2.0 | -2.0 | -3.0 | -2.0 | -3.0 | -1.0 | -1.0 | -4.0 | -2.0 | -1.0 | -3.0 | -4.0 | -2.0 | -4.0  |
| -4.0 | -3.0 | -3.0 | -4.0 | -2.0 | -3.0 | -4.0 | -2.0 | -2.0 | -1.0 | -1.0 | -2.0 | -1.0 | -2.0 | -1.0  |
| -2.0 | -3.0 | -2.0 | -1.0 | -1.0 | -3.0 | -2.0 | -1.0 | -4.0 | -3.0 | -1.0 | -1.0 | -2.0 | -3.0 | -3.0  |
| -3.0 | -1.0 | -1.0 | -4.0 | -4.0 | -3.0 | -1.0 | -2.0 | -3.0 | -1.0 | -1.0 | -4.0 | -4.0 | -3.0 | -3.0  |
| -3.0 | -1.0 | -4.0 | -2.0 | -3.0 | -3.0 | -1.0 | -4.0 | -4.0 | -4.0 | -2.0 | -2.0 | -2.0 | -2.0 | -1.0  |
| -3.0 | -4.0 | -4.0 | -2.0 | -3.0 | -4.0 | -3.0 | -3.0 | -2.0 | -2.0 | -3.0 | -4.0 | -3.0 | -4.0 | -1.0  |
| -3.0 | -4.0 | -1.0 | -1.0 | -1.0 | -4.0 | -4.0 | -4.0 | -4.0 | -1.0 | -2.0 | -4.0 | -2.0 | -2.0 | -1.0  |
| -1.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -4.0 | -1.0 | -2.0 | -4.0 | -1.0 | -2.0 | -4.0  |
| -2.0 | -2.0 | -1.0 | -2.0 | -2.0 | -2.0 | -4.0 | -3.0 | -1.0 | -4.0 | -1.0 | -4.0 | -2.0 | -2.0 | -2.0  |
| -2.0 | -1.0 | -3.0 | -1.0 | -4.0 | -4.0 | -1.0 | -3.0 | -3.0 | -1.0 | -1.0 | -2.0 | -3.0 | -4.0 | -3.0  |
| -2.0 | -2.0 | -1.0 | -4.0 | -4.0 | -4.0 | -2.0 | -2.0 | -3.0 | -1.0 | -2.0 | -2.0 | -1.0 | -1.0 | -3.0  |

Vektor setiap cell, close untuk lanjut

| <b>→</b> | <b>→</b> | <b>→</b> | → | _ →      | ı        | <b>→</b> | _ →      | <b>→</b> | T 1      | t        | t        | <b>→</b> | <b>→</b> | 1        |
|----------|----------|----------|---|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| <b>→</b> | →        | →        | t | →        | 1        | →        | →        | t        | t        | →        | →        | <b>→</b> | t        | Î        |
| <b>→</b> | -        | →        | → | <b>→</b> | 1        | <b>→</b> | t        | t        | →        | <b>→</b> | t        | 1        | 1        | 1        |
| <b>→</b> | _ →      | →        | → | →        | ı        | 1        | t        | →        | t        | _ →      | t        | t        | t        | t        |
| <b>→</b> | -        | →        | 1 | <b>→</b> | →        | <b>→</b> | <b>→</b> | →        | t        | 1        | 1        | 1        | <b>→</b> | +        |
| <b>→</b> | <b>→</b> | _ →      | t | -        | -        | 1        | <b>+</b> |          | →        | <b>→</b> | <b>→</b> | <b>→</b> | <b>-</b> | +        |
| <b>→</b> | →        | →        | → | +        | <b>→</b> | <b>→</b> | T T      | T T      | t        | t        | t        | →        | <b>+</b> | +        |
| <b>→</b> | 1        | →        | t | →        | →        | t        | t        | t        | <b>→</b> | →        | →        | →        | →        | <b>→</b> |
|          | <b>→</b> | →        | t | +        | -        | T T      | <b>+</b> | t        | →        | <b>→</b> | +        | T T      | <b>+</b> | +        |
| <b>→</b> | l t      | <b></b>  | t | +        | 1        | t        | 1        | t        | 1        | t        | t        | T T      | ļ        | 1        |
| <b>→</b> | _ →      | →        | → | →        | t        | t        | t        | t        | t        | t        | t        | t        | T T      | t        |
| <b>→</b> | →        | t        | t | t        | t        | t        | t        | -        | 1        | -        | -        | -        | -        | 1        |
| <b>→</b> | <b>→</b> | t        | t | t        | t        | t        | t        | t        | t        | →        | t        | t        | t        | t        |
| <b>→</b> | -        | 1        | 1 | 1        | →        | 1        | 1        | →        | →        | →        | 1        | 1        | 1        | 1        |
| Î        | t        | t        | t | t        | t        | t        | t        | t        | t        | t        | t        | t        | t        | t        |

Hijau = pergerakan si agen, close untuk lanjut

| -1.0 | -2.0 | -3.0 | -2.0 | -3.0 | -3.0 | -4.0 | -1.0 | -4.0 | -2.0 | -1.0 | -2.0 | -3.0 | -3.0 | 500.0 |
|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-------|
| -1.0 | -3.0 | -1.0 | -2.0 | -4.0 | -1.0 | -4.0 | -1.0 | -4.0 | -2.0 | -4.0 | -2.0 | -2.0 | -2.0 | -1.0  |
| -4.0 | -2.0 | -1.0 | -4.0 | -2.0 | -1.0 | -2.0 | -4.0 | -2.0 | -3.0 | -2.0 | -1.0 | -2.0 | -4.0 | -4.0  |
| -4.0 | -2.0 | -4.0 | -1.0 | -3.0 | -2.0 | -3.0 | -2.0 | -4.0 | -2.0 | -4.0 | -1.0 | -2.0 | -4.0 | -2.0  |
| -4.0 | -2.0 | -2.0 | -3.0 | -2.0 | -3.0 | -1.0 | -1.0 | -4.0 | -2.0 | -1.0 | -3.0 | -4.0 | -2.0 | -4.0  |
| -4.0 | -3.0 | -3.0 | -4.0 | -2.0 | -3.0 | -4.0 | -2.0 | -2.0 | -1.0 | -1.0 | -2.0 | -1.0 | -2.0 | -1.0  |
| -2.0 | -3.0 | -2.0 | -1.0 | -1.0 | -3.0 | -2.0 | -1.0 | -4.0 | -3.0 | -1.0 | -1.0 | -2.0 | -3.0 | -3.0  |
| -3.0 | -1.0 | -1.0 | -4.0 | -4.0 | -3.0 | -1.0 | -2.0 | -3.0 | -1.0 | -1.0 | -4.0 | -4.0 | -3.0 | -3.0  |
| -3.0 | -1.0 | -4.0 | -2.0 | -3.0 | -3.0 | -1.0 | -4.0 | -4.0 | -4.0 | -2.0 | -2.0 | -2.0 | -2.0 | -1.0  |
| -3.0 | -4.0 | -4.0 | -2.0 | -3.0 | -4.0 | -3.0 | -3.0 | -2.0 | -2.0 | -3.0 | -4.0 | -3.0 | -4.0 | -1.0  |
| -3.0 | -4.0 | -1.0 | -1.0 | -1.0 | -4.0 | -4.0 | -4.0 | -4.0 | -1.0 | -2.0 | -4.0 | -2.0 | -2.0 | -1.0  |
| -1.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -3.0 | -4.0 | -1.0 | -2.0 | -4.0 | -1.0 | -2.0 | -4.0  |
| -2.0 | -2.0 | -1.0 | -2.0 | -2.0 | -2.0 | -4.0 | -3.0 | -1.0 | -4.0 | -1.0 | -4.0 | -2.0 | -2.0 | -2.0  |
| -2.0 | -1.0 | -3.0 | -1.0 | -4.0 | -4.0 | -1.0 | -3.0 | -3.0 | -1.0 | -1.0 | -2.0 | -3.0 | -4.0 | -3.0  |
| -2.0 | -2.0 | -1.0 | -4.0 | -4.0 | -4.0 | -2.0 | -2.0 | -3.0 | -1.0 | -2.0 | -2.0 | -1.0 | -1.0 | -3.0  |