Robotics Project Report 1

Abdulkarim Dawalibi Adnan Altukleh

We started to build a cube, then a cylinder, and modified them to be like a body and wheel for the robot. The wheel and body have been colored, then we defined a joint between them like a connection. we had a problem with the ground where the robot fall and dived under the ground, to solve the issue we created a new file with new ground physics, and imported configurations to the new ground (file).