Objective

The objective of this expertiment is to introduce and familiarcize the uner with Ranpberry Pi, a small single-board computer. The experiment Provider inforcemention on the haredware required to net up Rappberery p; and how to net up the opercating nyotem on it. The experiment also Providen a banic idea of phython language and how to control an LED uning Rappberery Pi and phython programming. The user will bearn how to create a circuit using a breedbord and components such on an LED, arcenistors and jumper withen, and how to write phython code to control the LED. The experciment in derigned to provide on introduction to Ranpberry Pi and itn capabilities, and to help uners get started with using thin powereful tool for various Projecto.

apparcatus:

- 7. Activated Ranpbercry Pi
- 2. LED
- 3. Renintore (220 Ohm)
- 4. Breed board
- 5. Jumpere wires.

Theorey:

The experiment provides information on the components required to net up a Ranpbererry Pi, including the Reinphercry PI board, monitorudinplay, and connectivity cable, keyboard, moune, power supply, 50 cared, Etherenet cable (optional), and audio lead. The expertiment also provide the gaudince on netting up the operating system on Ranpberrry Pi. Ranpbian in the official opercotting nyotem for all models of Ranpbercry Pi, but there are also thired-party operating systems available. It provides an introduction to phython, a popular programming language that can be used to control the GIPIO Pins of Rasp berry Pi. The GPIO Pinn are used to interctace with exterinal components, such an LEDs, buttons, and semporen. The experiment demonstreates how to control an LED uning Phython code. Which in

executed from a linux envirconment using a tereminal and ohell percipting. It includes the use of a breadboard, an eppential component in electronic chrouit design, to create a circuit that interctaces with Raspberery Pi. The circuit includen an LED, a renintor, and jumper wiren-The experciment demonstrates how to write phython code that intercocts with the corp GIPIO Pinn to control the LED, turning it on and offovercall the theory of the experiment in to Provide an introduction to Raspberery Pi, its components, and capabilities. The expertiment demonstrates how to net up a Rangberrry Pi and provides an Introduction to phython progreamming and circuit deolgn, highlighting the potential for variour projects.

Preocedure!

- I. Grathers all necessary components required for setup, such as Raspberery Pi board, monitors display and connectivity cable, keyboard and mouse, powers supply, so cared, Etherenet cables and audio lead.
- 2. Install the operating system on the 5D cared Rasphian is the official operating system fore all models of the Raspherery Pi, but you can also use third-party operating systems such as ubuntu mate, Snappy Ubuntu Corce, windows 10 IO T corce, OSMC, Libraelec, Pinet, and RISC OS.
- 3. Connect the Raspbercry Pi board to the. monitors, keyboard, and moune. One the powers nupply to provide powers to the Ranpbercry p; board.

- 4. Boot up the Ranpbererry PI and log in with the unerename and pannworld preovided by the operating pyotem.
- 5. familiarcize yourcnelf with the linux environment by using the terminal and shell such percipting. You can also use text editors such can Givin, Nano Editors, Emaco Editors, and Pico Editors.
- 6. Explore the capabilities of Rasp berry Pl by developing small projects such as controlling an LED using phython programming language and Gipso Pins of Raspberrry Pl.
- 7. Continue exploring and developing morre complex projecto with Rappbertry Pi, such as automation data logging, and robotich.

Code:

nano blinkLED.py
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
GPIO.setup(14, GPIO.OUT)
GPIO.output(14, GPIO.HIGH)
print "LED is ON"
time.sleep(2)
GPIO.output(14, GPIO.LOW)
print "LED is OFF"

```
File
          Edit
                         Tabs
                                      Help
    GNU mano 2.2.6
import RP1 GPI0 as GPI0
import time
GPIO.setmode(GPIO.BCM)
GPIO.setwarnings(False)
GPIO.setup(14,GPIO.OUT)
GPIO.setup(15,GPIO.OUT)
GPIO.setup(16,GPIO.OUT)
while(True):
GPIO.output(14,GPIO.HIGH)
print "RED ON"
                  time.sleep(4)
GPIO.output(14,GPIO.LOW)
print "RED OFF"
                   for i in range (0,3):

print "Yellow Start"

GPI0.output(15,GPI0.HIGH)
                                    print "Yellow ON"
time.sleep(0.5)
GPIO.output(15,GPIO.LOW)
print "Yellow OFF Blink"
time.sleep(0.5)
                  GPIO.output(16,GPIO.HIGH)

print "GREEN ON"

time.sleep(4)

GPIO.output(16,GPIO.LOW)

print "GREEN OFF"
```

Figure: Code for traffic signal set up in Raspberry Pi

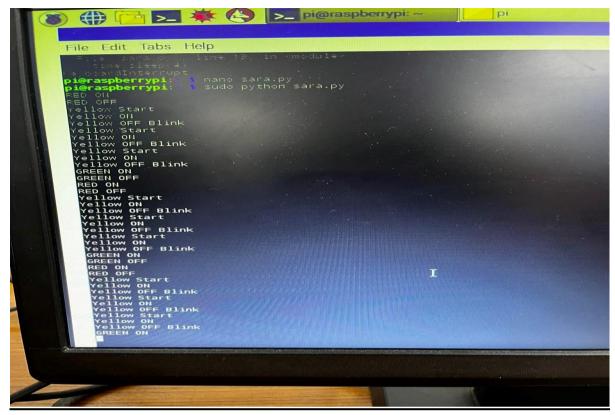


Figure: Code for blink LED

Simulation:

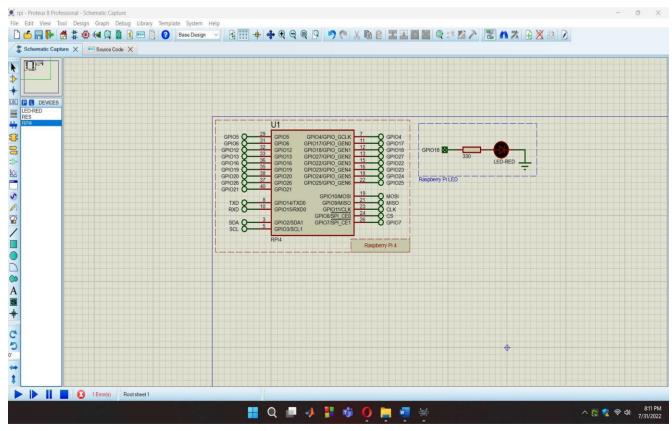


Figure: LED OFF

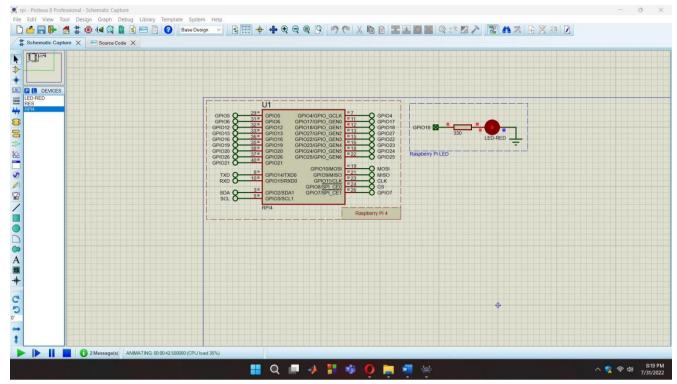


Figure: LED ON

Lab Simulation:

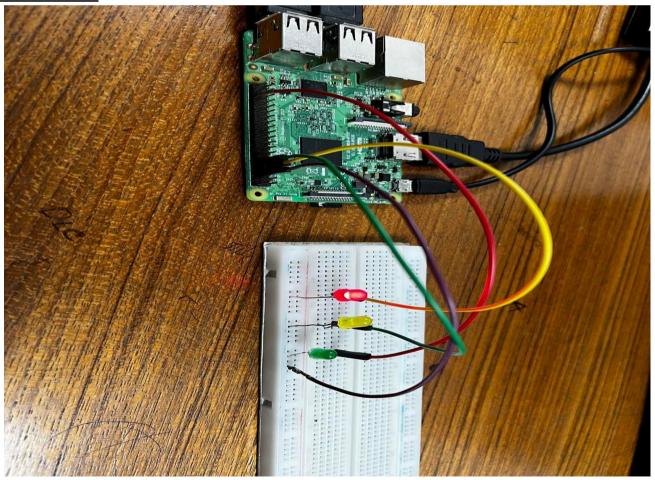


Figure: Red light is ON

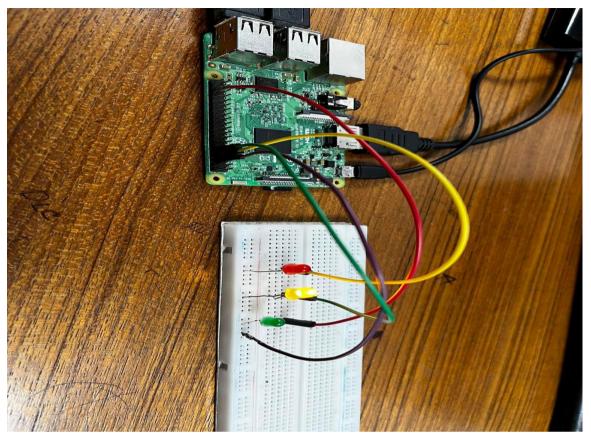


Figure: Yellow light is ON

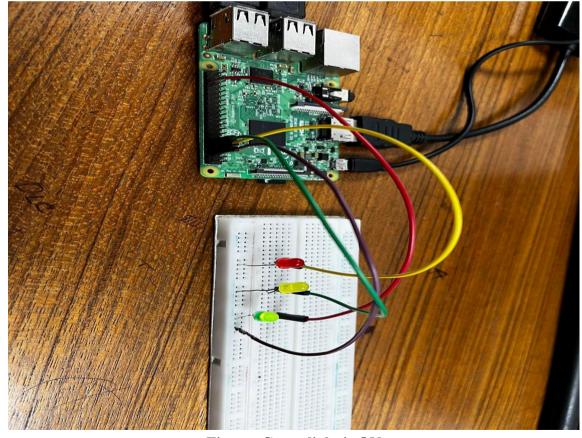


Figure: Green light is ON

Report:
All codes, scripts and proteus simulation of the blink program and traffic light system is attached above.

Direcursion:

some advanced features in proteur proffensional 8.9 may not be included in earlier vernions. Therefore, in order to use all the functions, we must download and install the 8.9 version. Developing a new project in crucial. If we don't net up the ideal conditions for our dentred endeavor, we won't ever receive the repulto we want. phython code in used to develop every project on the Rangberry Pi, So we must be carreful while using certain nytaxen. Because proteur 8.9 doen not ahech thin, we must determine whether any pins have been innued more than once after opening a new component. The same pin my be annigned to two separate components. Therceforce, beforce simulating the preoject, we must consider that for the temporary delay.

conclusion:

Thin experciment provided a bank underentanding of Rangberry Pi, its components, and how to Det up with an operating syntem. Additionally experciment demonstrated how to control an LED uning phython progreamming language with the CIPIO Pim OF the Rangberry Pi, 91 in important to note that Rangberery Pi can be uned for various applications such as automation, data logging, and Robotics. with the knowledge gained from this experiment, one can explore and develop more complex projects with Raspherery Pi.