

We want to find the classical path that minimizes the action, however, simply varying S_M is incorrect because the variable \vec{n} is not free; it is constrained to the surface of a sphere:

$$\vec{n}^2 - 1 = 0$$

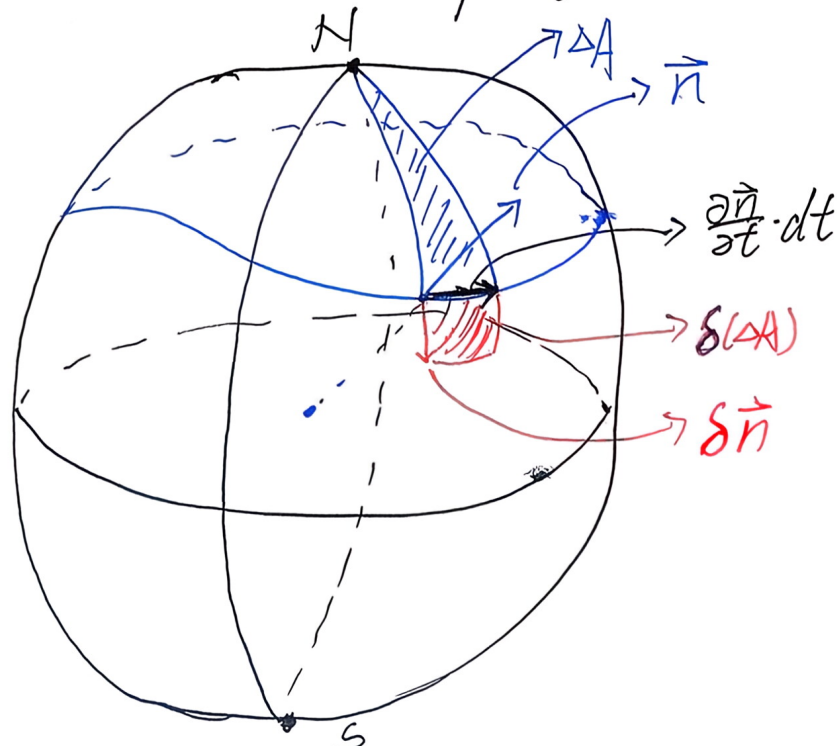
To handle this, we introduce a Lagrange multiplier field λ . So the total action becomes:

$$S_{\text{tot}} = S_M + \int d^d x dt \cdot \frac{\lambda}{2} (n^2 - 1)$$

Now, we can safely solve the variation equation below:

$$\delta S_{\text{tot}} = 0$$

We first need to variation of the Wess-Zumino term δS_{WZ} . Geometrically, the S_{WZ} is proportional to the area swept out by the spin vector on the unit sphere.



From the picture, we can see that the variation of this area element $\delta(A)$ with respect to a small change in path $\delta \vec{n}$ is given by:

$$\vec{n} \cdot \delta(A) = \delta \vec{n} \times \left(\frac{\partial \vec{n}}{\partial t} \right) dt$$

we product \vec{n} on the both sides of the equation:

$$\delta(A) = \vec{n} (\delta \vec{n} \times \frac{\partial \vec{n}}{\partial t}) dt.$$

$$= -\delta \vec{n} (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) dt.$$

Therefore, the variation of the Wess-Zumino part of the action is:

$$\begin{aligned} \cancel{\delta \left(\int \frac{S}{\chi} \right)} \delta \left(\frac{S}{a_0^d} \int d^d x S_{WZ}(\vec{n}) \right) &= \delta \left(\frac{S}{a_0^d} \int d^d x -A_r(\vec{n}) \right) \\ &= \frac{S}{a_0^d} \int d^d x \left[\delta \vec{n} \cdot (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) \right] \end{aligned}$$

This implies the functional derivative is:

$$\begin{aligned} \cancel{\delta S_W} \cancel{\delta S_g} \\ \frac{\delta S_g}{\delta \vec{n}} &= \frac{S}{a_0^d} \cdot (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) \end{aligned}$$

Next, we calculate the variation of energy term:

$$\begin{aligned} \delta \left[\int d^d x dt (\nabla \cdot \vec{n})^2 \right] &= \int d^d x dt \frac{d}{dt} \delta \left(\frac{\partial \vec{n}}{\partial x_i} \right)^2 \\ &= \int d^d x dt \cdot \frac{d}{dt} 2 \cdot \left(\frac{\partial \vec{n}}{\partial x_i} \right) \cdot \delta \left(\frac{\partial \vec{n}}{\partial x_i} \right) \end{aligned}$$

and we use the partial integration method:

$$\begin{aligned}
 \int d^d x \sum_i \frac{d}{dx_i} \left(\frac{\partial \vec{n}}{\partial x_i} \right) \cdot \delta \left(\frac{\partial \vec{n}}{\partial x_i} \right) \frac{\partial \vec{n}}{\partial x_i} &= \frac{\partial \vec{n}}{\partial x_i} = \partial_i \vec{n} \\
 &= 2 \int d^d x \sum_i \frac{d}{dx_i} (\partial_i \vec{n}) \cdot \partial_i (\delta \vec{n}) \partial^d (\delta \vec{n}) \\
 &= 2 \left\{ \frac{d}{dx_i} (\partial_i \vec{n}) \cdot \delta \vec{n} \right\} - \int d^d x \sum_i \frac{d}{dx_i} \delta \vec{n} \cdot \partial_i \vec{n} \\
 &= -2 \int d^d x \nabla \cdot (\nabla^2 \vec{n}) \cdot \delta \vec{n}
 \end{aligned}$$

So the variation of energy term is

$$\frac{\delta S_0}{\delta \vec{n}} = \frac{N S^2}{G_0^{d-2}} (\nabla^2 \vec{n})$$

Finally, we calculate the variation of λ term:

$$\delta \int d^d x dt \frac{\lambda}{2} (\vec{n}^2 - 1) = \int d^d x dt \cdot \lambda \vec{n} \cdot \delta \vec{n}$$

So the variation of λ term is:

$$\frac{\delta S_\lambda}{\delta \vec{n}} = \lambda \vec{n}$$

Now we can get the total action's variation:

$$\delta S_{\text{tot}} = 0$$

$$\Rightarrow \frac{S}{a_0^d} (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) + \lambda \vec{n} = - \frac{|J| S^2}{a_0^{d-2}} \nabla^2 \vec{n}.$$

To find the value of the Lagrange multiplier, take the dot product of the above ~~equation~~ equation with \vec{n} :

$$\begin{aligned} & \frac{S}{a_0^d} \underbrace{\vec{n} \cdot (\vec{n} \times \frac{\partial \vec{n}}{\partial t})}_{=0} + \lambda \underbrace{\vec{n} \cdot \vec{n}}_{=1} = - \frac{|J| S^2}{a_0^{d-2}} (\vec{n} \cdot \nabla^2 \vec{n}) \\ & = \frac{S}{a_0^d} \frac{\partial \vec{n}}{\partial t} (\vec{n} \times \vec{n}) \\ & = 0 \end{aligned}$$

Thus: $\lambda = - \frac{|J| S^2}{a_0^{d-2}} (\vec{n} \cdot \nabla^2 \vec{n})$

Now, ~~sub~~ substitute the λ back into equation:

$$\frac{S}{a_0^d} (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) - \left[\frac{|J| S^2}{a_0^{d-2}} (\vec{n} \cdot \nabla^2 \vec{n}) \right] \vec{n} = - \frac{|J| S^2}{a_0^{d-2}} \nabla^2 \vec{n}.$$

Rearrange to group the derivative terms on the right:

$$\frac{S}{a_0^d} (\vec{n} \times \frac{\partial \vec{n}}{\partial t}) = - \frac{|J| S^2}{a_0^{d-2}} [\nabla^2 \vec{n} - (\vec{n} \cdot \nabla^2 \vec{n}) \vec{n}]$$

If we look at: $\vec{n} \times (\vec{n} \times \nabla^2 \vec{n})$:

$$\begin{aligned}\vec{n} \times (\vec{n} \times \nabla^2 \vec{n}) &= \vec{n} \cdot (\vec{n} \cdot \nabla^2 \vec{n}) - \nabla^2 \vec{n} (\vec{n} \cdot \vec{n}) \\ &= \vec{n} (\vec{n} \cdot \nabla^2 \vec{n}) - \nabla^2 \vec{n}.\end{aligned}$$

So.

$$\frac{S}{a_0^3} (\vec{n} \times \partial_t \vec{n}) = \frac{|J| S^2}{a_0^{d+2}} [\vec{n} \times (\vec{n} \times \nabla^2 \vec{n})]$$

Simplified to:

~~we can~~ $\vec{n} \times \frac{\partial \vec{n}}{\partial t} = \vec{n} \times \left[\frac{|J| S^2}{a_0^2} \nabla^2 \vec{n} \right]$

We can get the Landau-Lifshitz equation:

$$\frac{\partial \vec{n}}{\partial t} = |J| S^2 a_0^2 (\vec{n} \times \nabla^2 \vec{n})$$