



derivation of the Laplacian from rectangular to spherical coordinates

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We begin by recognizing the familiar conversion from rectangular to [spherical coordinates](http://planetmath.org/node/34491) (<http://planetmath.org/node/34491>) (note that ϕ is used to denote the [azimuthal angle](http://planetmath.org/node/34491) (<http://planetmath.org/node/34491>), whereas θ is used to denote the [polar angle](http://planetmath.org/node/34491) (<http://planetmath.org/node/34491>))

$$x = r \sin(\theta) \cos(\phi), y = r \sin(\theta) \sin(\phi), z = r \cos(\theta), \quad (1)$$

and [conversely](http://planetmath.org/node/39554) (<http://planetmath.org/node/39554>) from spherical to [rectangular coordinates](http://planetmath.org/node/36016) (<http://planetmath.org/node/36016>)

$$r = \sqrt{x^2 + y^2 + z^2}, \theta = \arccos\left(\frac{z}{r}\right), \phi = \arctan\left(\frac{y}{x}\right). \quad (2)$$

Now, we know that the [Laplacian](http://planetmath.org/node/33030) (<http://planetmath.org/node/33030>) in rectangular coordinates is defined¹ in the following [way](http://planetmath.org/node/31384) (<http://planetmath.org/node/31384>)

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}. \quad (3)$$

We also know that the [partial derivatives](http://planetmath.org/node/30841) (<http://planetmath.org/node/30841>) in rectangular coordinates can be [expanded](http://planetmath.org/node/40380) (<http://planetmath.org/node/40380>) in the following way by using the [chain rule](http://planetmath.org/node/32561) (<http://planetmath.org/node/32561>)

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial x}, \quad (4)$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial y} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial y}, \quad (5)$$

$$\frac{\partial f}{\partial z} = \frac{\partial f}{\partial r} \frac{\partial r}{\partial z} + \frac{\partial f}{\partial \theta} \frac{\partial \theta}{\partial z} + \frac{\partial f}{\partial \phi} \frac{\partial \phi}{\partial z}. \quad (6)$$

The next step is to convert the [right](http://planetmath.org/node/36456) (<http://planetmath.org/node/36456>)-hand [side](http://planetmath.org/node/41602) (<http://planetmath.org/node/41602>) of each of the above three [equations](http://planetmath.org/node/37330) (<http://planetmath.org/node/37330>) so that it only has partial derivatives in [terms](http://planetmath.org/node/33376) (<http://planetmath.org/node/33376>) of r , θ and ϕ . We can do this by substituting the following values (which are easily derived from (2)) in their respective [places](http://planetmath.org/node/36640) (<http://planetmath.org/node/36640>) in the above three equations

$$\begin{aligned} \frac{\partial r}{\partial x} &= \sin(\theta) \cos(\phi), \quad \frac{\partial \theta}{\partial x} = \frac{1}{r} \cos(\theta) \cos(\phi), \quad \frac{\partial \phi}{\partial x} = -\frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)}, \\ \frac{\partial r}{\partial y} &= \sin(\theta) \sin(\phi), \quad \frac{\partial \theta}{\partial y} = \frac{1}{r} \cos(\theta) \sin(\phi), \quad \frac{\partial \phi}{\partial y} = \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)}, \\ \frac{\partial r}{\partial z} &= \cos(\theta), \quad \frac{\partial \theta}{\partial z} = -\frac{1}{r} \sin(\theta), \quad \frac{\partial \phi}{\partial z} = 0. \end{aligned} \quad (7)$$

After the [substitution](http://planetmath.org/node/41772) (<http://planetmath.org/node/41772>), equation (4) looks like the following

$$\frac{\partial f}{\partial x} = \sin(\theta) \cos(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi}. \quad (8)$$

Assuming that f is a sufficiently [differentiable function](http://planetmath.org/node/32919) (<http://planetmath.org/node/32919>), we can replace f by $\frac{\partial f}{\partial x}$ in the above equation and arrive at the following

$$\frac{\partial^2 f}{\partial x^2} = \sin(\theta) \cos(\phi) \frac{\partial}{\partial r} \left[\frac{\partial f}{\partial x} \right] + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial}{\partial \theta} \left[\frac{\partial f}{\partial x} \right] - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial}{\partial \phi} \left[\frac{\partial f}{\partial x} \right]. \quad (9)$$

Now the trick is to substitute equation (8) into equation (9) in [order](http://planetmath.org/node/31727) (<http://planetmath.org/node/31727>) to eliminate any partial derivatives with respect to x . The result is the following equation

$$\frac{\partial^2 f}{\partial x^2} = \sin(\theta) \cos(\phi) \frac{\partial}{\partial r} \left[\sin(\theta) \cos(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right] +$$

$$\frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial}{\partial \theta} \left[\sin(\theta) \cos(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right] -$$

$$\frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial}{\partial \phi} \left[\sin(\theta) \cos(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right].$$

In the hopes of simplifying the above equation, we operate the derivatives on the operands and get

$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} = & \sin(\theta) \cos(\phi) \left[\sin(\theta) \cos(\phi) \frac{\partial^2 f}{\partial r^2} - \frac{1}{r^2} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \theta} + \right. \\ & \left. \frac{1}{r^2} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \phi \partial r} \right] \\ & \sin(\theta) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \frac{1}{r} \sin(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r} \frac{\sin(\phi) \cos(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} - \\ & \left. \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \right] \\ & \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial^2 f}{\partial \theta \partial \phi} - \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \phi^2} \end{aligned}$$

After further simplifying the above equation, we arrive at the following form

$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} = & \left[\sin^2(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r^2} - \frac{1}{r^2} \cos(\theta) \sin(\theta) \cos^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \sin(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} + \right. \\ & \left. \frac{1}{r^2} \sin(\phi) \cos(\phi) \frac{\partial f}{\partial \phi} - \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial \phi \partial r} \right] \\ & \frac{1}{r} \sin(\theta) \cos(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \frac{1}{r^2} \sin(\theta) \cos(\theta) \cos^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \cos^2(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial \theta^2} + \\ & \left. \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi) \cos^2(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} - \frac{1}{r^2} \frac{\cos(\theta) \sin(\phi) \cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \right] \\ & \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \phi} + \frac{1}{r^2} \frac{\cos(\theta) \sin^2(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \theta} - \frac{1}{r^2} \frac{\cos(\theta) \cos(\phi) \sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} + \\ & \left. \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r^2} \frac{\sin^2(\phi)}{\sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2} \right] \end{aligned}$$

Notice that we have derived the first term of the right-hand side of equation (3) (i.e. $\frac{\partial^2 f}{\partial x^2}$) in terms of spherical coordinates. We now have to do a [similar \(http://planetmath.org/node/32278\)](http://planetmath.org/node/32278) arduous [derivation \(http://planetmath.org/node/42513\)](http://planetmath.org/node/42513) for the rest of the two terms (i.e. $\frac{\partial^2 f}{\partial y^2}$ and $\frac{\partial^2 f}{\partial z^2}$). Lets do it!

After we substitute the values of (7) into equation (5) we get

$$\frac{\partial f}{\partial y} = \sin(\theta) \sin(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi}. \quad (10)$$

Again, assuming that f is a sufficiently differentiable function, we can replace f by $\frac{\partial f}{\partial y}$ in the above equation and arrive at the following

$$\frac{\partial^2 f}{\partial y^2} = \sin(\theta) \sin(\phi) \frac{\partial}{\partial r} \left[\frac{\partial f}{\partial y} \right] + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial}{\partial \theta} \left[\frac{\partial f}{\partial y} \right] + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial}{\partial \phi} \left[\frac{\partial f}{\partial y} \right]. \quad (11)$$

Now we substitute equation (10) into equation (11) in order to eliminate any partial derivatives with respect to y . The result is the following

$$\begin{aligned} \frac{\partial^2 f}{\partial y^2} = & \sin(\theta) \sin(\phi) \frac{\partial}{\partial r} \left[\sin(\theta) \sin(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right] + \\ & \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial}{\partial \theta} \left[\sin(\theta) \sin(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right] + \\ & \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial}{\partial \phi} \left[\sin(\theta) \sin(\phi) \frac{\partial f}{\partial r} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} \right]. \end{aligned}$$

Now we operate the [operators \(http://planetmath.org/node/31982\)](http://planetmath.org/node/31982) and get

$$\begin{aligned} \frac{\partial^2 f}{\partial y^2} = & \sin(\theta) \sin(\phi) \left[\sin(\theta) \sin(\phi) \frac{\partial^2 f}{\partial r^2} - \frac{1}{r^2} \cos(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \right. \\ & \left. \frac{1}{r^2} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial r \partial \phi} \right] \\ & \cos(\theta) \sin(\phi) \frac{\partial f}{\partial r} - \frac{1}{r} \sin(\theta) \sin(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial^2 f}{\partial \theta^2} - \frac{1}{r} \frac{\cos(\phi) \cos(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \end{aligned}$$

$$\left[\frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \right]$$

$$\frac{1}{r} \cos(\theta) \cos(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \sin(\phi) \frac{\partial^2 f}{\partial \theta \partial \phi} - \frac{1}{r} \frac{\sin(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r} \frac{\cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \phi^2} \Big]$$

and after some simplifications

$$\begin{aligned} \frac{\partial^2 f}{\partial y^2} = & \left[\sin^2(\theta) \sin^2(\phi) \frac{\partial^2 f}{\partial r^2} - \frac{1}{r^2} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \right. \\ & \left. \frac{1}{r^2} \sin(\phi) \cos(\phi) \frac{\partial f}{\partial \phi} + \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \phi} \right] \\ & \frac{1}{r} \cos^2(\theta) \sin^2(\phi) \frac{\partial f}{\partial r} - \frac{1}{r^2} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \cos^2(\theta) \sin^2(\phi) \frac{\partial^2 f}{\partial \theta^2} - \\ & \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi) \cos^2(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r^2} \frac{\cos(\theta) \sin(\phi) \cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \Big] \\ & \frac{1}{r} \cos(\phi) \sin(\phi) \frac{\partial^2 f}{\partial r \partial \phi} + \frac{1}{r^2} \frac{\cos(\theta) \cos^2(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \frac{\cos(\theta) \cos(\phi) \sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} - \\ & \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r^2} \frac{\cos^2(\phi)}{\sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2} \Big] \end{aligned}$$

Now its time to derive $\frac{\partial^2 f}{\partial z^2}$. After our substitution of value in (7) into equation (6) we get

$$\frac{\partial f}{\partial z} = \cos(\theta) \frac{\partial f}{\partial r} - \frac{1}{r} \sin(\theta) \frac{\partial f}{\partial \theta}. \quad (12)$$

Once more, assuming that f is a sufficiently differentiable function, we can replace f by $\frac{\partial f}{\partial z}$ in the above equation which gives [US \(http://planetmath.org/node/42525\)](http://planetmath.org/node/42525) the following

$$\frac{\partial^2 f}{\partial z^2} = \cos(\theta) \frac{\partial}{\partial r} \left[\frac{\partial f}{\partial z} \right] - \frac{1}{r} \sin(\theta) \frac{\partial}{\partial \theta} \left[\frac{\partial f}{\partial z} \right]. \quad (13)$$

Now we substitute equation (12) into equation (13) in order to eliminate any partial derivatives with respect to z and we arrive at

$$\begin{aligned} \frac{\partial^2 f}{\partial z^2} = & \cos(\theta) \frac{\partial}{\partial r} \left[\cos(\theta) \frac{\partial f}{\partial r} - \frac{1}{r} \sin(\theta) \frac{\partial f}{\partial \theta} \right] - \\ & \frac{1}{r} \sin(\theta) \frac{\partial}{\partial \theta} \left[\cos(\theta) \frac{\partial f}{\partial r} - \frac{1}{r} \sin(\theta) \frac{\partial f}{\partial \theta} \right]. \end{aligned}$$

After operating the operators we get

$$\begin{aligned} \frac{\partial^2 f}{\partial z^2} = & \cos(\theta) \left[\cos(\theta) \frac{\partial^2 f}{\partial r^2} + \frac{1}{r^2} \sin(\theta) \frac{\partial f}{\partial \theta} - \frac{1}{r} \sin(\theta) \frac{\partial^2 f}{\partial r \partial \theta} \right] - \\ & \frac{1}{r} \sin(\theta) \left[-\sin(\theta) \frac{\partial f}{\partial r} + \cos(\theta) \frac{\partial^2 f}{\partial r \partial \theta} - \frac{1}{r} \cos(\theta) \frac{\partial f}{\partial \theta} - \right. \\ & \left. \frac{1}{r} \sin(\theta) \frac{\partial^2 f}{\partial \theta^2} \right] \end{aligned}$$

and then simplifying

$$\begin{aligned} \frac{\partial^2 f}{\partial z^2} = & \left[\cos^2(\theta) \frac{\partial^2 f}{\partial r^2} + \frac{1}{r^2} \cos(\theta) \sin(\theta) \frac{\partial f}{\partial \theta} - \frac{1}{r} \cos(\theta) \sin(\theta) \frac{\partial^2 f}{\partial r \partial \theta} \right] + \left[\frac{1}{r} \sin^2(\theta) \frac{\partial f}{\partial r} - \right. \\ & \left. \frac{1}{r} \sin(\theta) \cos(\theta) \frac{\partial^2 f}{\partial r \partial \theta} + \frac{1}{r^2} \sin(\theta) \cos(\theta) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \sin^2(\theta) \frac{\partial^2 f}{\partial \theta^2} \right] \end{aligned}$$

Now that we have all three terms of the [right hand side \(http://planetmath.org/node/37330\)](http://planetmath.org/node/37330) of equation

(3)(i.e. $\frac{\partial^2 f}{\partial x^2}$, $\frac{\partial^2 f}{\partial y^2}$ and $\frac{\partial^2 f}{\partial z^2}$), we add them all together (because of equation (3)) to get the laplacian in terms of r , θ and ϕ

$$\begin{aligned} \nabla^2 f = & \left[\sin^2(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r^2} - \frac{1}{r^2} \cos(\theta) \sin(\theta) \cos^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \cos(\theta) \sin(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} + \right. \\ & \left. \frac{1}{r^2} \sin(\phi) \cos(\phi) \frac{\partial f}{\partial \phi} - \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial \phi \partial r} \right] \\ & \frac{1}{r} \sin(\theta) \cos(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \frac{1}{r^2} \sin(\theta) \cos(\theta) \cos^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \cos^2(\theta) \cos^2(\phi) \frac{\partial^2 f}{\partial \theta^2} + \\ & \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi) \cos^2(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} - \frac{1}{r^2} \frac{\cos(\theta) \sin(\phi) \cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \Big] \\ & \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \phi} + \frac{1}{r^2} \frac{\cos(\theta) \sin^2(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \theta} - \frac{1}{r^2} \frac{\cos(\theta) \cos(\phi) \sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} + \end{aligned}$$

$$\begin{aligned}
& \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \frac{1}{r^2} \frac{\sin^2(\phi)}{\sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2} \Bigg] \\
& \frac{1}{r^2} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial^2 f}{\partial r \partial \theta} - \frac{1}{r^2} \sin(\phi) \cos(\phi) \frac{\partial f}{\partial \phi} + \\
& \frac{1}{r} \sin(\phi) \cos(\phi) \frac{\partial^2 f}{\partial r \partial \phi} \Bigg] \\
& \frac{1}{r^2} \sin(\theta) \cos(\theta) \sin^2(\phi) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \cos^2(\theta) \sin^2(\phi) \frac{\partial^2 f}{\partial \theta^2} - \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi) \cos^2(\theta)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \\
& \frac{1}{r^2} \frac{\cos(\theta) \sin(\phi) \cos(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} \Bigg] \\
& \frac{1}{r^2} \frac{\cos(\theta) \cos^2(\phi)}{\sin(\theta)} \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \frac{\cos(\theta) \cos(\phi) \sin(\phi)}{\sin(\theta)} \frac{\partial^2 f}{\partial \theta \partial \phi} - \frac{1}{r^2} \frac{\sin(\phi) \cos(\phi)}{\sin^2(\theta)} \frac{\partial f}{\partial \phi} + \\
& \frac{1}{r^2} \frac{\cos^2(\phi)}{\sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2} \Bigg] \\
& \left[\frac{1}{r} \sin^2(\theta) \frac{\partial f}{\partial r} - \frac{1}{r} \sin(\theta) \cos(\theta) \frac{\partial^2 f}{\partial r \partial \theta} + \frac{1}{r^2} \sin(\theta) \cos(\theta) \frac{\partial f}{\partial \theta} + \frac{1}{r^2} \sin^2(\theta) \frac{\partial^2 f}{\partial \theta^2} \right].
\end{aligned}$$

It may be hard to believe but the truth is that the above [expression \(http://planetmath.org/node/403071\)](http://planetmath.org/node/403071), after some miraculous simplifications of course, reduces to the following succinct form and we finally arrive at the Laplacian in spherical coordinates!

$$\nabla^2 f = \frac{\partial^2 f}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r^2} \frac{1}{\sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2} + \frac{2}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\cos(\theta)}{\sin(\theta)} \frac{\partial f}{\partial \theta}. \quad (14)$$

We can write the Laplacian in an [even \(http://planetmath.org/node/34703\)](http://planetmath.org/node/34703) more [compact \(http://planetmath.org/node/30503\)](http://planetmath.org/node/30503) form as²

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left[r^2 \frac{\partial f}{\partial r} \right] + \frac{1}{r^2 \sin(\theta)} \frac{\partial}{\partial \theta} \left[\sin(\theta) \frac{\partial f}{\partial \theta} \right] + \frac{1}{r^2 \sin^2(\theta)} \frac{\partial^2 f}{\partial \phi^2}. \quad (15)$$

Keywords:

laplacian, spherical, coordinates, partial derivatives

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Topic

Major Section:

Reference

Mathematics Subject Classification

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