

Eigenvalues

$$A \underset{\substack{\uparrow \\ \text{eigenvector}}}{X} = \lambda \underset{\substack{\leftarrow \\ \text{eigenvalue}}}{X}, \quad X \neq 0$$

$$A \in \mathbb{C}^{n \times n} \text{ or } \mathbb{R}^{n \times n}$$

$$A \underset{\substack{\uparrow \\ \text{eigenvector}}}{X} - \lambda \underset{\substack{\leftarrow \\ \text{eigenvalue}}}{X} = 0$$

$$\underbrace{(A - \lambda I)}_{\substack{\uparrow \\ X \neq 0 ?}} X = 0$$

$$\text{null } (A - \lambda I) \neq \{ \vec{0} \}$$

If $A - \lambda I$ is invertible

$$X = (A - \lambda I)^{-1} 0 = 0$$

$A - \lambda I$ is not invertible

$$|A - \lambda I| = 0$$

Determinant

$$\begin{bmatrix} a_{11} - \lambda & & & \\ \vdots & a_{22} - \lambda & \ddots & \\ \vdots & & \ddots & \\ & & & a_{nn} - \lambda \end{bmatrix}$$

$$\det \begin{bmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{bmatrix} =$$

↑
example

Characteristic
polynomial

$$|A - \lambda I| = \text{poly}_n(\lambda) = 0$$

At most n

If we allow $\lambda \in \mathbb{C}$

At least one λ exists

At least one eigenvector
for each distinct eigen.

\times Not unique (can multiply
by any constant)

Eigenvectors are directions
(not vectors)

Matrix notation

$$\underline{\bar{X}} = [x_1 | x_2 | \dots | x_m]$$

↑ ↑ ↑

linearly independent

capital λ

$$\Lambda = \begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_m & \end{bmatrix}$$

$$A \underline{x}_i = \lambda_i \underline{x}_i, i=1, \dots, m$$

$$A \underline{\bar{X}} = \underline{\bar{X}} \Lambda$$

$$1 \leq m \leq n$$

Is $m = n$? \times not in general

Every λ has an algebraic multiplicity α and a geometric multiplicity β (how many linearly independent eigenvectors)

$$1 \leq \beta \leq \alpha$$

If $m = n$ we call that matrix non-defective or **diagonalizable matrix**

$$m = n \quad \sum \text{ is } [n \times n]$$

$\Rightarrow \sum$ is invertible
Eigenvectors span all of \mathbb{R}^n

$$X^{-1} \text{ exists}$$

$$X^{-1} ; AX = X \Lambda \quad | \quad X^{-1}$$

\rightarrow

$$\boxed{A = X \Lambda X^{-1}}$$

eigenvalue decomposition

If A is defective,
Jordan form (decomposition)

$$\Lambda \rightarrow \begin{bmatrix} 1 & & & \\ - & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

Not computable numerically

Assume A is non-defective

$$X^{-1} A X = \Lambda$$

similarity transform

$A : \mathbb{R}^n \rightarrow \mathbb{R}^n$
linear map

$$y = \sum_{i=1}^n a_i x_i$$

$$Ay = A \sum_i a_i x_i =$$

$$= \sum_i a_i (\underbrace{A x_i}_{\lambda_i x_i}) =$$

$$= \sum_i (a_i \lambda_i) x_i$$

{ In basis formed by eigenvectors
 A is diagonal with λ_i 's
 on the diagonal

{ If x_i 's are orthogonal
 then matrix is called
 unitarily diagonalizable

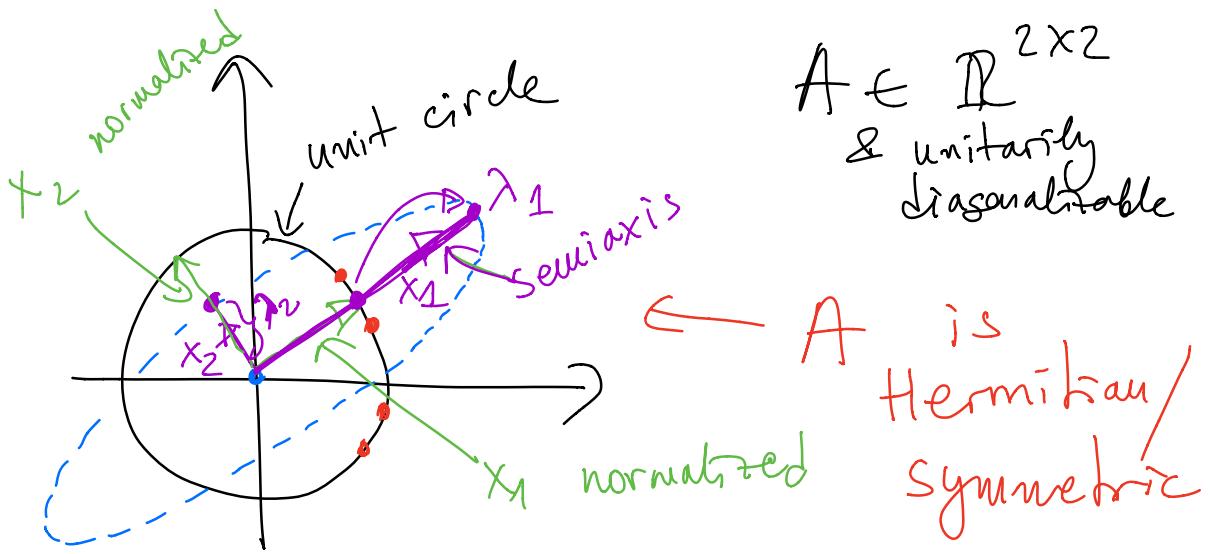
$$X \rightarrow U \text{ orthogonal matrix}$$

$\|x_i\| = 1$
 if and only if
 $A^*A = A^*A$

$$U^{-1} = U^*$$
 complex conjugate transpose

$$A = U \Lambda U^*$$

Assume A can be factorized like this



$$A = U \Lambda U^*$$

$$A^* = (U \Lambda U^*)^* =$$

$$= (U^*)^* \Lambda^* U^*$$

$$= U \Lambda^* U^*$$

If $A^* = A$ Hermitian matrix
or symmetric if in $\mathbb{R}^{n \times n}$

$$\begin{aligned} \Lambda^* &= U^* \\ \Rightarrow \Lambda^* &= \Lambda \end{aligned}$$

eigenvalues are real

{ Theorem: If $A^* = A$ then
A is unitarily diagonalizable
and eigenvalues are real

} From now on assume
A is Hermitian }

If A is not unitarily
diagonalizable, numerically
best to use Schur
decomposition

any matrix } $A = U T U^*$
Eigenvalues on ^{upper triangular} diagonal of T

Eigenvalues

A. Donev, Spring 2021

$$\underbrace{|A - \lambda I|}_{} = 0$$

$$\text{poly}_n(\lambda) = 0$$

Abel's theorem says no closed-form solution for $n \geq 5$

All eigenvalue methods must be iterative/approximate

Sidenote: In fact, solving polynomial eqs is done using eigenvalues (Matlab's roots)

Two cases:

- ① We only want a few eigenvectors - with smallest or largest $|\lambda|$

Google's Page Rank algorithm finds the eigenvector with the largest eigenvalue

(Power Method)

- ② All eigenvectors (next Wed, pre-recorded)
QR algorithm

Power - Method

$$A = X \Lambda X^{-1}$$

$$A^2 = X \Lambda \underbrace{X^{-1} X}_{=I} X^{-1}$$

$$= X \Lambda^2 X^{-1}$$

$$A^n = X \Lambda^n X^{-1}, n \geq 1 \text{ integer}$$

Eigenvalues of A^n are $(\lambda_i)^n$; and eigenvectors are the same.

$$\text{As } n \rightarrow \infty$$

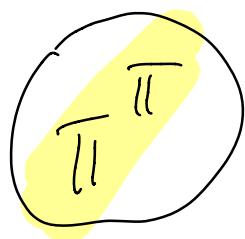
$$\Lambda^n = \begin{bmatrix} \lambda_1^n & \dots \\ & \ddots & \lambda_n^n \end{bmatrix}$$

Largest eigenvalue in modulus

will dominate Λ^n

Aside:

$$A^{\bar{n}} ?$$



$$\pi^{3/4} = (\pi^3)^{1/4} = x$$

$$x^4 = \pi^3$$

$$\ln(\pi^{\bar{\pi}}) = \bar{\pi} \ln(\pi)$$

$$\pi^{\bar{\pi}} = e^{\bar{\pi} \ln \pi}$$

$$A \cdot A = O(n^3) \text{ FLOPS}$$

$$A \cdot x = O(n^2) \text{ FLOPS}$$

$[n \times n] \quad [n \times 1]$

$$(A \dots (A \cdot (A \cdot (A \cdot (A \cdot x)))))$$

n times

$$= A^n x$$

this can be
 computed without
 forming A

Choose a \downarrow random vector q_0

compute $x_n = A^n q_0$

$$x_n = \underbrace{\sum_{i=1}^n \lambda_i \underbrace{\sum_{j=1}^{i-1} q_j}_{a}}_{q_0}$$

$$\sum_{i=1}^n q_0 = a$$

$$\sum \boxed{a} = \boxed{q_0}$$

\vec{a} is \vec{q}_0 expressed in the eigenbasis of A

$$x_n = \sum \left(\lambda^n a \right)$$

$$\lim_{n \rightarrow \infty} x_n = ?$$

$$\lambda^n \xrightarrow[n \rightarrow \infty]{} \begin{bmatrix} \lambda_1^n & & \\ & \ddots & \\ & & 0 \end{bmatrix}$$

Assume $\lambda_1 > \lambda_2 \geq \lambda_3 \geq \lambda_4 \dots$
strict inequality

$$\lambda^n a \rightarrow \begin{bmatrix} \lambda_1^n a_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$X \begin{bmatrix} \lambda_1^n a_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = x_1 \cdot (\lambda_1^n a_1)$$

$$x_n \rightarrow (\lambda_1^n a_1) x_1$$

$$\frac{x_n}{\|x_n\|} \rightarrow x_1$$

~~aside~~

$$\begin{bmatrix} a \\ 1 \\ \vdots \\ a_n \end{bmatrix} \begin{bmatrix} b_1 \\ 1 \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} ab_1 \\ 1 \\ \vdots \\ a_n b_n \end{bmatrix}$$

$$x_n \rightarrow x_1$$

flow about λ_1

$$\underline{Ax_n} \approx \lambda_1 x_n$$

$$\lambda_1 = \frac{(Ax_n)_{1,2,3,\dots,n}}{(x_n)_{1,2,3,\dots,n}}$$

Rayleigh quotient

$$x_n \cdot A x_n = x_n^T A x_n \rightarrow$$

$$= \lambda_1 (x_1^T x_1)$$

$$= \lambda_1 (\underbrace{x_1^T x_1})$$

$$= \lambda_1$$

$$\lambda_1 \approx x_n \cdot (A x_n)$$

If x_n is normalized

$$\lambda_1 \approx \frac{x_n \cdot (A x_n)}{x_n \cdot x_n}$$

$$\min_{x \neq 0} \frac{x^T A x}{x^T x} = \lambda_{\min}$$

$$\max_{x \neq 0} \frac{x^T A x}{x^T x} = \lambda_{\max}$$

$$\Rightarrow |\lambda_1| \leq |\lambda_{\max}|$$

Algorithm (Power method)

1) Choose random q_0

$$\begin{cases}
 \tilde{q}_k = A q_{k-1} & \text{(One matrix vector multiply)} \\
 q_k = \frac{\tilde{q}_k}{\|\tilde{q}_k\|} \\
 \lambda_k = q_k^T A q_k \\
 r_k = \|A q_k - \lambda_k q_k\|_2 & \text{residual } 10^{-9} \\
 \text{Stop if } r_k < \epsilon \cdot \lambda_k
 \end{cases}$$

This guarantees 9 digits in
If $\epsilon = 10^{-9}$

$$\vec{q}_0 = \sum_{i=1}^n \vec{a}_i$$

$$q_0 = \sum_{i=1}^n a_i x_i$$

$$a_i \neq 0 \quad \forall i$$

(why we choose q_0 random)

$$\vec{q}_n = A^n q_0 = A^n \sum a_i x_i$$

$$= \sum a_i (A^n x_i) =$$

$$= a_i (\lambda_i^n x_i)$$

$$= \sum (a_i \lambda_i^n) x_i$$

$$\tilde{q}_m = \sum a_i \lambda_1^n \cdot \left(\frac{\lambda_i}{\lambda_1} \right)^n x_i$$

$$\delta = \left| \frac{\lambda_2}{\lambda_1} \right| \quad \delta < 1$$

$$\tilde{q}_m \rightarrow a_1 \lambda_1^n x_1 + O(\delta^n)$$

normalize it

$$\| q_m - (\pm x_1) \| = O(\delta^n)$$

linearly convergent

$$q_m \rightarrow x_1 + O(\delta) x_2 + O(\delta) x_3 + \dots$$

.

$$\begin{aligned}\lambda_n &= q_n \cdot (A q_m) \\ &= \underbrace{x_1 \cdot (A x_1)}_{\lambda_1} + O(\delta) \sum_{i,j \neq 1}^2 x_i \cdot (A x_j)\end{aligned}$$

$$\lambda_n = \lambda_1 + O(\delta^2)$$

$$||\lambda_n - \lambda_1|| = O(\delta^{2n})$$

Eigenvalue is more accurate

If $\delta \ll 1$, iteration
 (power method) converges very
 fast, especially for eigenvalue
 Eigenvalue algorithms converge
 well (rapidly) if eigenvalues are
 (well) separated

In Matlab

(QR method)

$$[X, \Lambda] = \text{eig}(A)$$

all eig & vectors

$O(n^3)$ but expensive
(much more than LU)

$$[X, \Lambda] = \text{eigs}(A, n_{\text{eig}})$$

a few of
eig & vectors

sparse
(Power method)

QR algorithm

for eigenvalues

$A = QR$
 unitary upper triangular
 Gram-Schmidt orthogonalization
 $O(n^3)$ FLOPS

Similarity transformations

$$A_k \xrightarrow{\text{iteration}} A_{k+1}$$

Assume
A is
symmetric

$$A_n = A$$

$$A_{k+1} = P_k^{-1} A_k P_k$$

or $P_k A_k P_k^{-1}$
 invertible

$\left\{ \begin{array}{l} A_{k+1} \text{ has the same} \\ \text{eigenvalues as } A_k \end{array} \right.$

$$A_{k+1} = P_k^{-1} A_k P_k$$

$$A_k = \underbrace{X_k}_{\text{unitary}} \cap_k \underbrace{X_k^*}_{\text{diagonal}} \quad (\text{eigenvalues})$$

$$A_{k+1} = \left(P_k^{-1} X_k \right) \cap_k \left(X_k^{-1} P_k \right)$$

$$X_{k+1} = P_k^{-1} X_k$$

$$X_{k+1}^{-1} = X_k^{-1} P_k$$

$$\Rightarrow A_{k+1} = \underbrace{X_{k+1} \cap_k X_{k+1}^{-1}}_{\text{eigenvalue decomposition}}$$

$$A_{k+1} = X_{k+1} \wedge X_{k+1}^{-1}$$

has the same eigenvalues as A

We want

$$(?) A_k \longrightarrow \text{diagonal matrix}$$

QR method $A_1 = A$

Algorithm!

$$\left\{ \begin{array}{l} A_k = Q_k R_k \\ A_{k+1} = R_k Q_k \end{array} \right.$$

swap order

$$\begin{aligned} A_{k+1} &= Q_k^{-1} A_k Q_k \\ &\quad (\text{i.e. } P_k = Q_k^{-1}) \\ &= (Q_k^* Q_k) R_k Q_k = P_k R_k \end{aligned}$$

Identity

$$A_k \rightarrow \Lambda$$

(Diagonal matrix
of eigenvalues)

$$Q_1 Q_2 \dots Q_h = \prod_{i=1}^h \theta_i \rightarrow X$$

s.t.

$$A = X^{-1} \Lambda X$$

Why it works? $A = X^{-1} \Lambda X$

Computes the same sequence Q_k as Q_R

$$A_k = X^{-1} \Lambda X$$

Diagonal matrix = $Q_k R_k$ eigenvalues as $k \rightarrow \infty$

$$A_k = Q_k^* A Q_k$$

similar transf.
similar matrices:
same eigenvalues

$$A_k \rightarrow \text{diagonal matrix}$$

$$A = \Theta R$$

↑
orthonormal basis for
range / column space of A