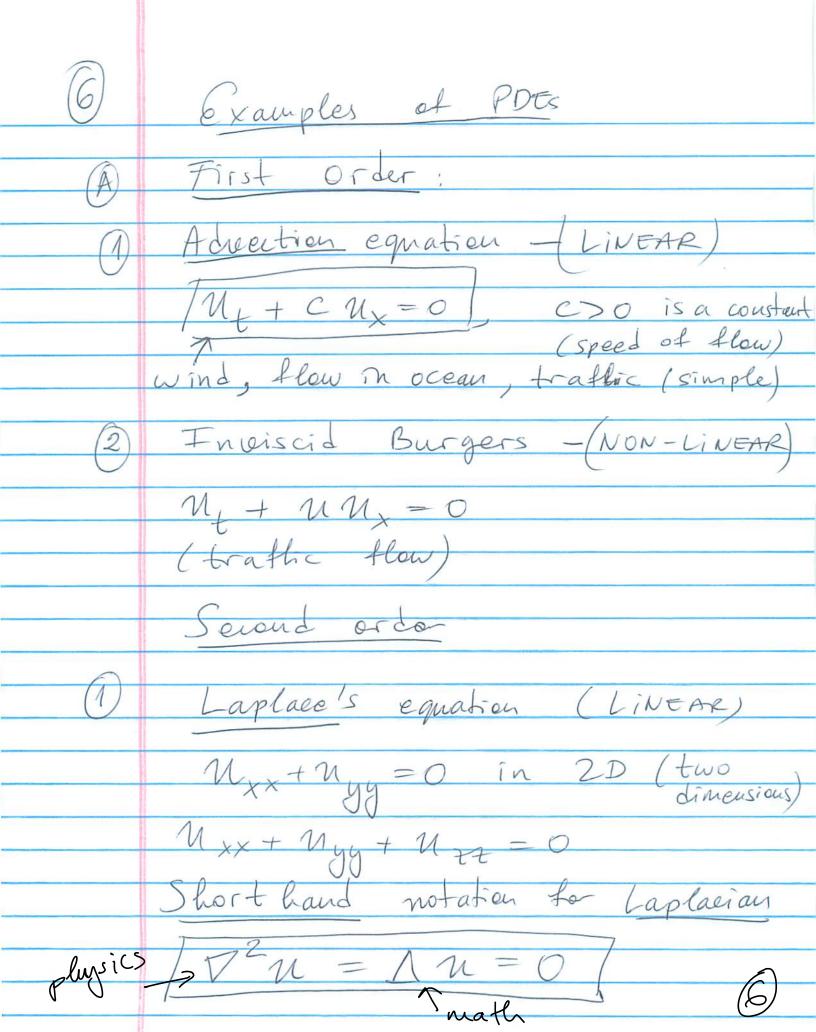
PDE SPRING 2018 LECTURE 1 Why are Partial Differential (Equations (PDEs) important? They are the cornerstone of macroscopic (large/human scale) Examples of PDEs in action: Weather prediction or climate modeling (Navier-Stokes equations) 2) Essentially all engineering, especially mechanical & acrospace elasticity fluid flow (Bridges) (air planes, rochets, ships) Electromagnetism (Maxwell's equations)
(cell phones, radio communication) Everything around us that we can see 2 mteraet with can be described by a PDE 1

There are different kinds of PDEs related to different physics, Diffusion (heat conduction, polutant dispersal viscosity of liquids Advection (hurricanes wind dispersal / flow, airplane design, traffic flow) 3) Deformation & Elasticity (electric fields, elastic materials, magnetism) and others. Coupse WEBPAGE; https: adonev.g;thub.io/PDE 2022 p:// Cims. NYU. EDU/~ DONEY/ Feaching VISIT THE WEBPAGE ASAP Two Three text books (PDE)
Applied PDE, Essential PDE

Ordinary Differential Equation (ODE): $\frac{du(t)}{dt} = f(t, u(t))$ Explicit: $F\left(t, u(t), \frac{du}{dt}, \frac{du}{dt}, \dots, t\right) = 0$ Implicit: For PDES there is more than one dependent variable: M(x,y,z,...t)
space time $\frac{\partial n}{\partial x} = u_x = \partial_x n$ $\frac{\partial^2 u}{\partial t \partial \mathbf{x}} = u_{tx} = u_{xt} = \frac{\partial^2 u}{\partial x \partial t}$ twice Litterentiable $\frac{\partial^2 n}{\partial x^2} = \mathcal{U}_{xx} = \frac{\partial^2 n}{\partial x^2}$

Order of PDE the order of a PDE is the highest order of derivative that appears in equation. General PDE: T(u, x,y, 7 t,... -> Ux, My, MZ, Mt, ..., -> Mxx, Mxy, ..., Mtt, Mtx, ..., > Uxxx, Uxyz, ...) = 0 Examples: $U_{t} = u_{xx}$ is second order What Loes it mean to solve a PDE? Try $u(x,t) = e^{-t} \operatorname{sm}(x)$ a) $u_t = -e^{-t} \sin x = -u$ $u_{xx} = e^{-t} \cos x = 0$ $u_{xx} = -e^{-t} \sin x = -u$ c) $U_{t} = U_{xx}$ as needed

So $u(x,t) = e \sin(x)$ is a solution of the PDE. Is it the only? How to we choose among many (physical systems choose one after all)? All of these are topics of the field of PDEs: Mathematical Analysis Practice (1) Show that $u = \ln(r)$, where $r = \sqrt{x^2 + y^2}$, solves $\nabla^2 u = 0 = \partial_{xx} u + \partial_{yy} u$ 2) Show that u = 1/r solves $\nabla^{t}u(x,y,t) = \partial_{xx}u + \partial_{yy}u + \partial_{tz}u = 0$ these are the Laplace equation in



(2)	Second order contd.
2	Poisson's Egnation (e.g. electrostatics, (cariant of Laplace)
	$p^2 n = f(x, y, t,)$ Linear
23	Non-linear Poisson: $P^2 n = f(x,y,z,n)$ NON-LINEAR
(3)	Heat or diffusion eq (LiNeAe)
	$M_t = k M_{xx}, k > 0$ is constant
gen	erally $M_t = k \nabla^2 u = k \Delta u$
(4)	Wave equation (LINEAR)
	(e.g. sound or worker)
	Mtt = C Mxx, C = sound speed Speed of light
	or more general speed of light Mitt = CTM
	()

A doction - diffusion - reaction (pollutant transport) (Liver) $u_{t} + c u_{x} = k u_{xx} + ru$ (constants (reaction rate) (speed of flow) Or rn > f(n) for nonlinear Black - Scholes eq. (LiNEDR)
(stock prices) $u + \frac{6^2}{2} x^2 u_{xx} + r x u_x = r u$ option
option
option
price
volatility
stoch price
rate Third order Korteveg de Vries (kdV) eq. nt+6nux+uxx=0 describes solitons (e.g. lossless communication)

excercise: hat u= solves the heat equation $M_{+} = M_{\times \times}$ Dimensional Analysis (PHYSICS) t = time = [s] = [seconds X = space = [m] = [meters 2 has units of T m-2 has units of DX DX n has some units In es. kg, K (temperature)

- m Caffreient Practice What mits loes · M++ CN+=0 $u_{t} = c^{2}u_{xx}$ The answer must not depend on the choice of the units! Principle This means that special functions must have dimensionless arguments (no unit) 1 e-x7/4t IS NOT

Later we will construct a solution of the form (x-s)/4kt $u(x,t) = \frac{1}{\sqrt{4\pi kt}} \quad \int u(s,0) e \, ds$ Cheek units make sense $\begin{bmatrix} \frac{1}{\sqrt{kt}} \end{bmatrix} = \frac{1}{\sqrt{m^2 \cdot s}} = \frac{1}{m}$ Unit of integral $\begin{bmatrix} () & ds \\ () & ds \end{bmatrix} = \begin{bmatrix} ds \\ () & ds \end{bmatrix} = \begin{bmatrix} ds \\ () & ds \end{bmatrix}$ So the unit of the whole expression is [n]. m = [n] as it has to be. Showing that this is a solution
Showing calculus only (move
requires calculus only (move
derivatives mide the integral) it (1)