

FINDING THE (AD)OPTIMAL CAT PHOTO

MILESTONE 2 PRESENTATION

Kyra Ballard

Andrew Fu

Shravan Nageswaran

Emily Xie

Harvard University

IACS Capstone, Spring 2020



PROBLEM

- About 6.5M dogs and cats each year enter animal shelters, according to the ASPCA
- But approximately 1.5M of these are put down



That's **1** in **4**
pets.

THE **QUALITY OF THE PHOTO OF A PET IS
CORRELATED TO ITS LIKELIHOOD OF
BEING **ADOPTED****



GOALS



increase adoption rates

decrease euthanasia for shelter cats

SPONSOR: AUSTIN PETS ALIVE!

- Animal shelter based in Texas
- No-kill shelter
- Saved over **70,000 animal lives** since 2008



Austin Pets Alive! is not your average animal shelter. We pioneer innovative lifesaving programs designed to save the animals most at risk of euthanasia.



Adopt

Looking for a furry friend to add to the family? We have thousands of animals that would love to be part of your home.



Foster

Open your heart and home to a pet in need, and be the bridge to a dog or cat's forever home.



Volunteer

Our volunteers make lifesaving possible – become a volunteer today!

SPONSOR: ADOPTIMIZE

- Software company
- Primary goals
 - Increase adoption
 - Decrease euthanasia
 - Increase shelter engagement
- Algorithm that optimizes image taking
 - For the best chance of adoption



Increases Adoption
Rates



Saves Lives

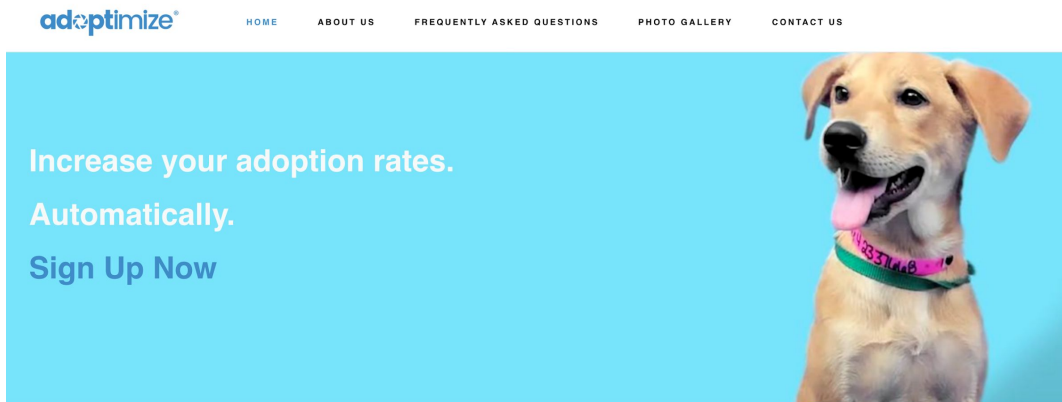


Increases Online
Engagement

SPONSOR: ADOPTIMIZE

Dog model process

- Takes in **video** of animal
- Selects **optimal shot**
- Automatically **edits** image
- Outputs **enhanced optimal** image



IMPACT



124% increase in adoption
41% reduction in euthanasia



27% increase in adoption
56% reduction in euthanasia

SCOPE OF WORK

In scope

- Model taking cat videos and outputting best frame
 - Length: <60s
 - Unobstructed view of a single cat
- Functional web app for mobile devices

Out of scope

- Stylized front-end
- Measuring adoption rates

CHALLENGES

| | |
|---|--|
| Behavior <ul style="list-style-type: none">○ Fur covering face○ Not facing camera | Video Quality <ul style="list-style-type: none">○ Unstable camera○ Camera quality (phone vs. laptop) |
| Dataset <ul style="list-style-type: none">○ Small number of cat videos○ No labeled data | Limitations <ul style="list-style-type: none">○ Environment○ Equipment |

The data poses some **challenges...**



THE DATA

The Good



- Full body visible
- Looking directly at camera
- Clear, high quality image
- Good lighting

The Bad



- Full body not visible
- Can't distinguish facial features
- Looking away from camera
- Blurry image
- Darker area

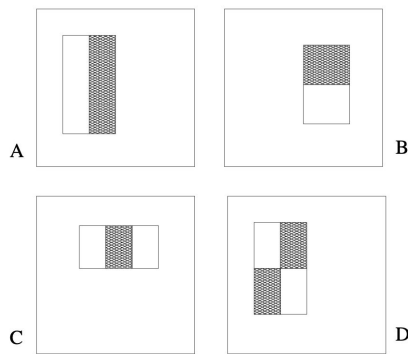
HEURISTICS

- Detection of Cat Features
- Variance of Laplacian
- Relative Size of Cat Head

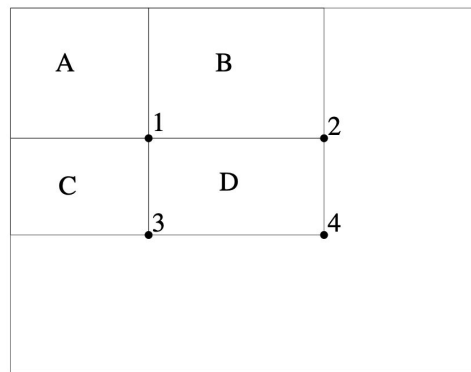


LITERATURE REVIEW: VIOLA-JONES

- *Rapid Object Detection using a Boosted Cascade of Simple Features*
- Haar-like Features
 - Pre-Compute Integral Image
- AdaBoost on Decision Stumps
- Cascade
- Sliding Windows



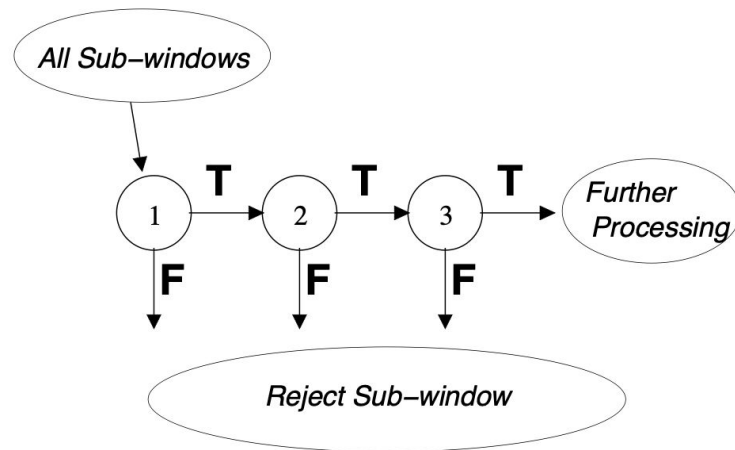
Haar-like Features



After post-processing, rectangle features can be calculated with array lookups as opposed to sums

LITERATURE REVIEW: VIOLA-JONES

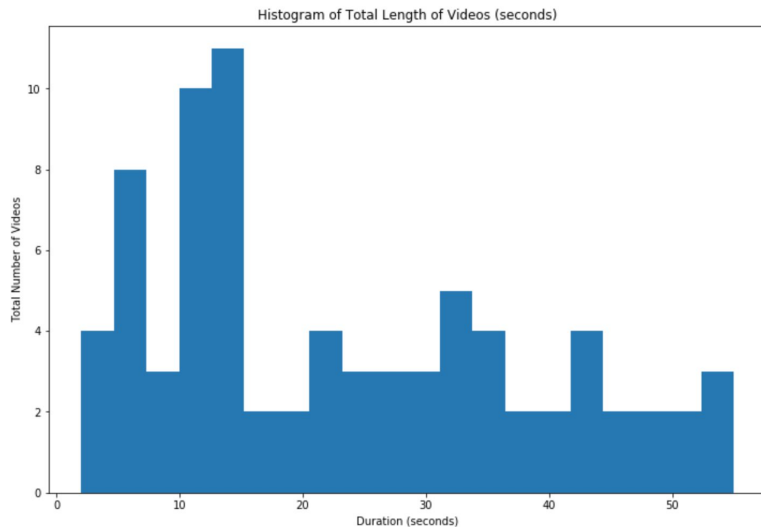
- *Rapid Object Detection using a Boosted Cascade of Simple Features*
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High-level view of cascade approach

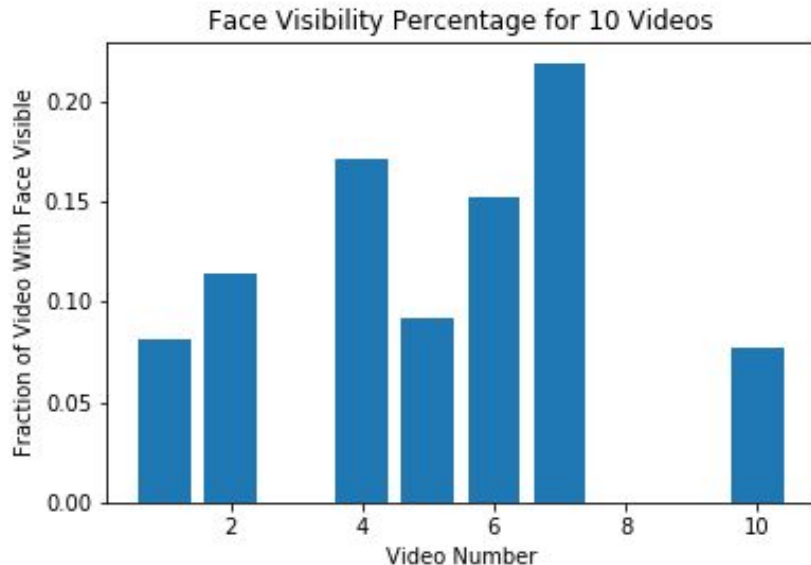
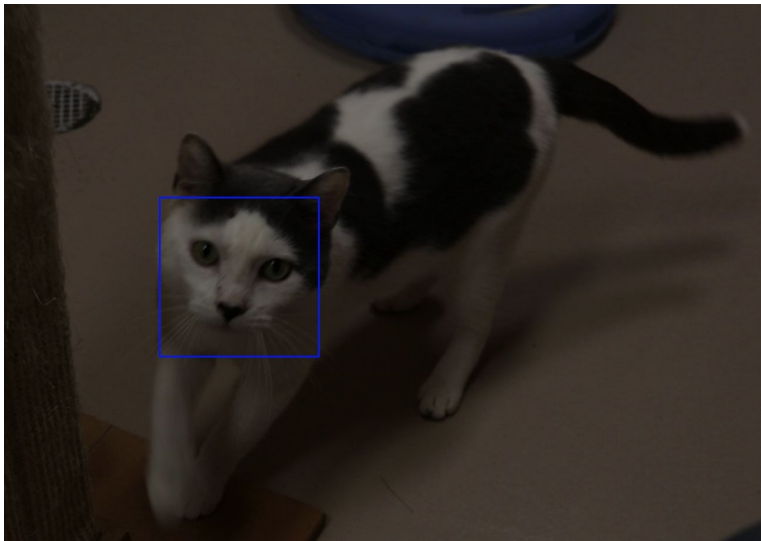
EDA: GENERAL DATA SENSE

- Initial data cleaning yielded 80 videos
- Duration: Avg: 23 seconds. Min 2 seconds. Max 55 seconds

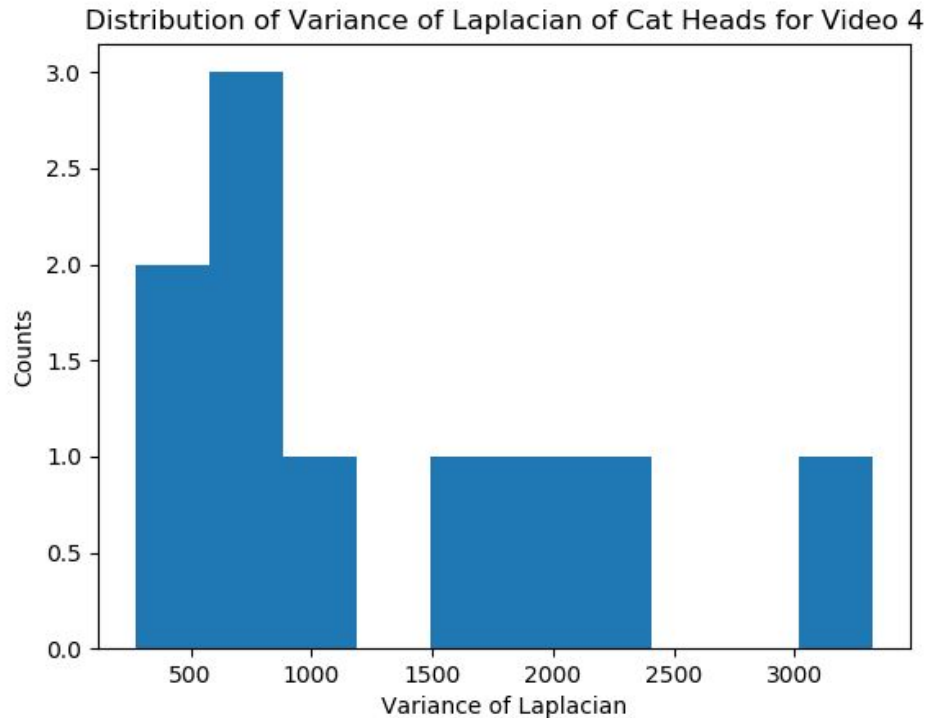


EDA: CAT FACE DETECTION

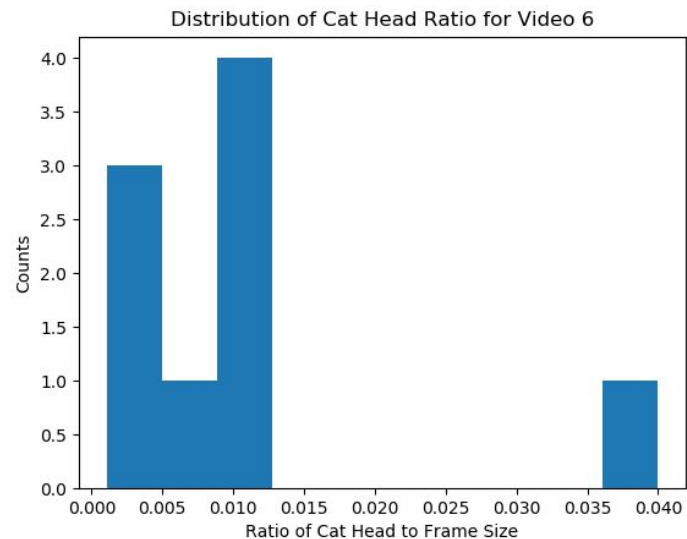
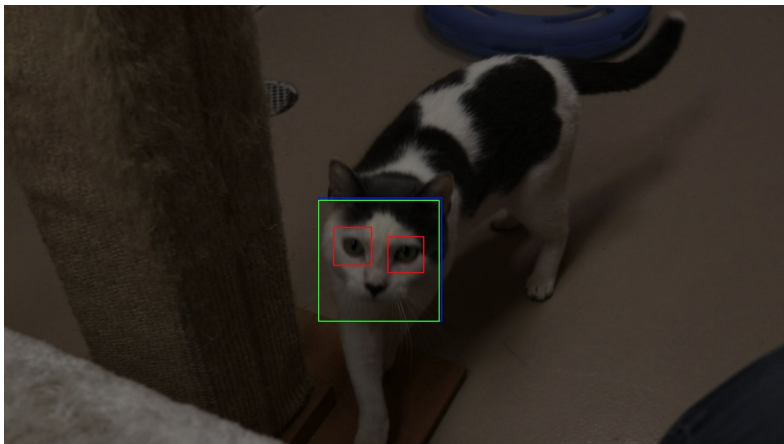
- Ran cat face detection using Haar Cascade
- Subsample of 10 videos
- Every 10th frame per video



EDA: MEASURES OF SHARPNESS



EDA: HEAD SIZE RATIOS



BASELINE VS. DEVELOPED MODEL

baseline

random image selected from set of
frames with cat head detected

developed

image selected from set of frames
with cat head detected, with
highest combined scores of
sharpness and best cat head ratio

TESTING THE MODELS

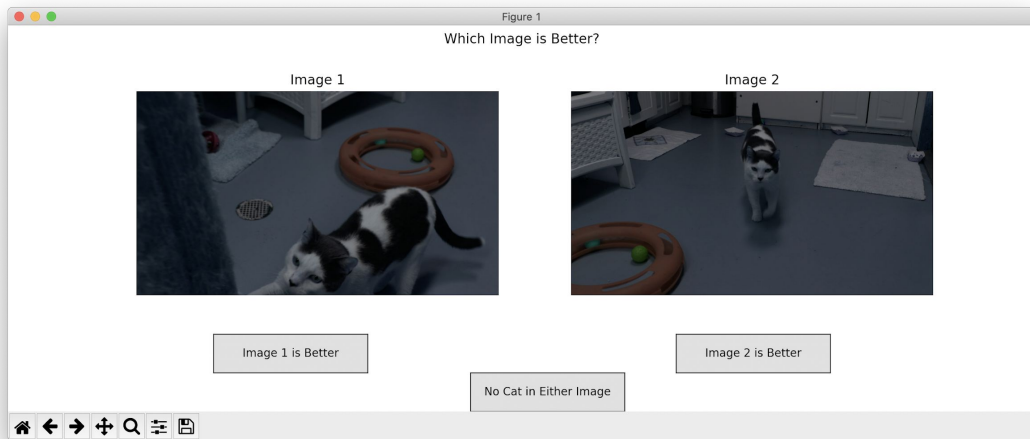
Implementation

Blind A/B testing: baseline vs.
developed output

Results

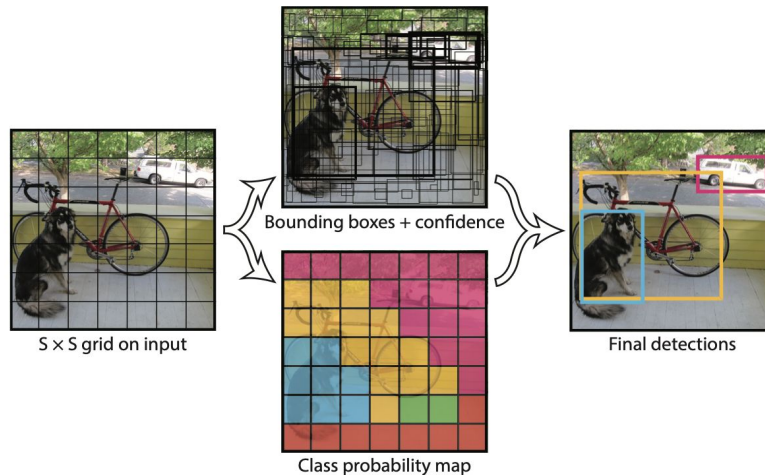
64% of the time developed model
produced “better” image

Testing interface




LITERATURE REVIEW: YOLO

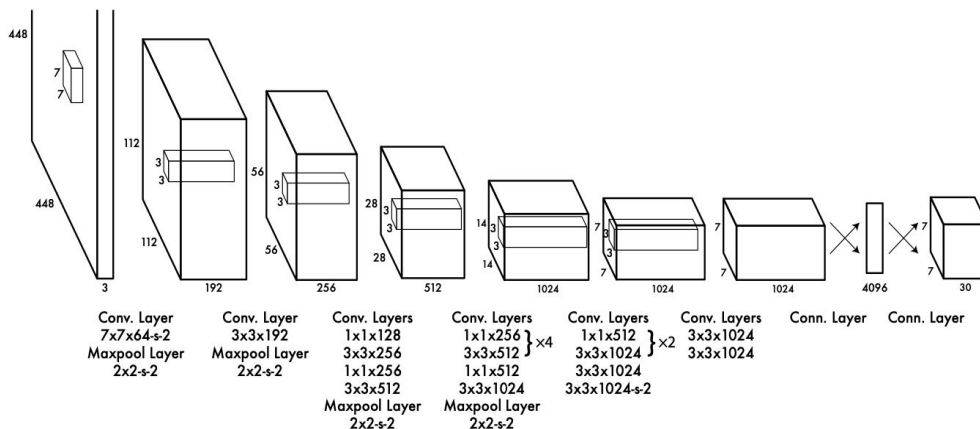
- *You Only Look Once: Unified, Real-Time Object Detection*
- Simultaneous Box and Class Proposal
- Simplicity: CNN
- Optimized for Speed



Each grid cell is responsible for producing exactly $B=2$ bounding boxes representing existence of any object with center in the cell

LITERATURE REVIEW: YOLO

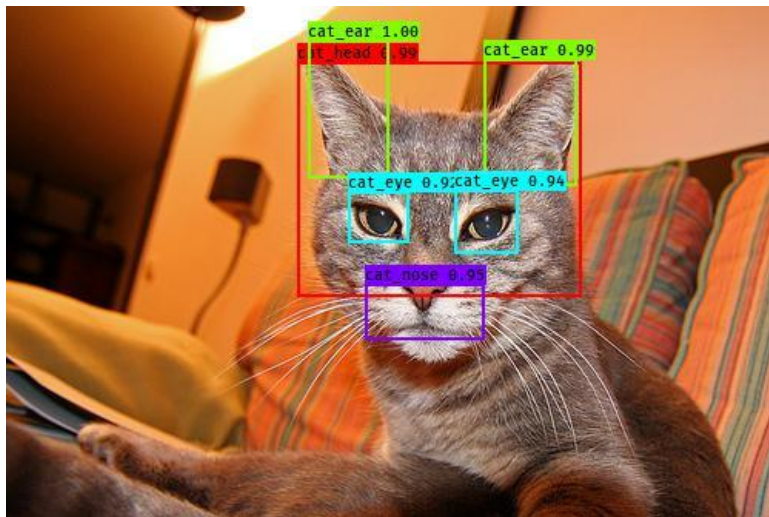
- *You Only Look Once: Unified, Real-Time Object Detection*
 - Simultaneous Box and Class Proposal
 - Simplicity: CNN
 - Optimized for Speed
- 
- The diagram illustrates a CNN architecture with four stages of feature maps. The first stage is a small 3D box labeled with '7' on its top and side faces. The second stage is a tall, narrow vertical rectangle labeled '448' on its left side. The third stage is a trapezoidal shape labeled '112' at its base. The fourth stage is a smaller trapezoidal shape. The diagram shows the spatial dimensions of the feature maps at different layers of the network.



YOLO architecture; note only convolutional and fully connected layers

TRAINING YOLO

- YOLO vs Haar Cascade
- 4 Features
 - Eyes, Nose, Ears, Head
- 100 Training Examples
- AWS EC2 g3s.xlarge
 - NVIDIA Tesla M60 GPU
- mAP: 71.96%




REGRESSION: LABELING

- Data-driven approach to weighting features
- Likert scale
 - Resulting in classes 1-5 (excluding images without cats) that would serve as the 'y'-values to fit the regression model

Figure 1

How strongly do you agree with the following statement?
I am more likely to adopt this cat after seeing this photo.

Image

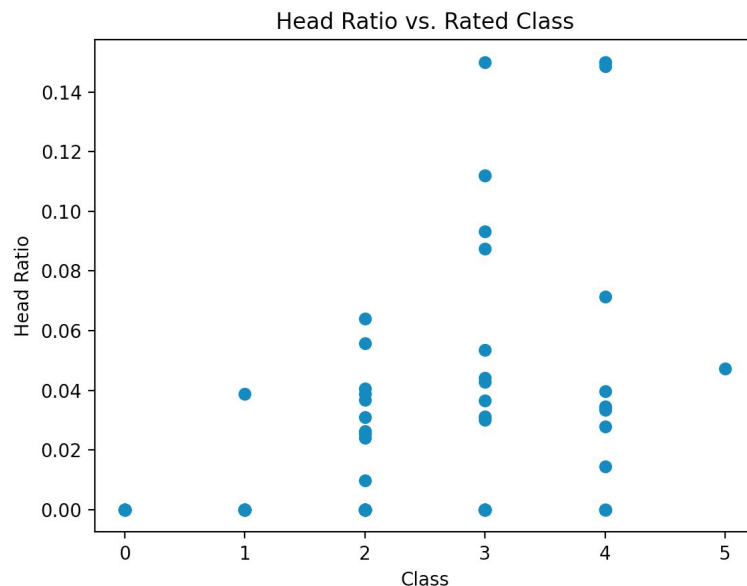
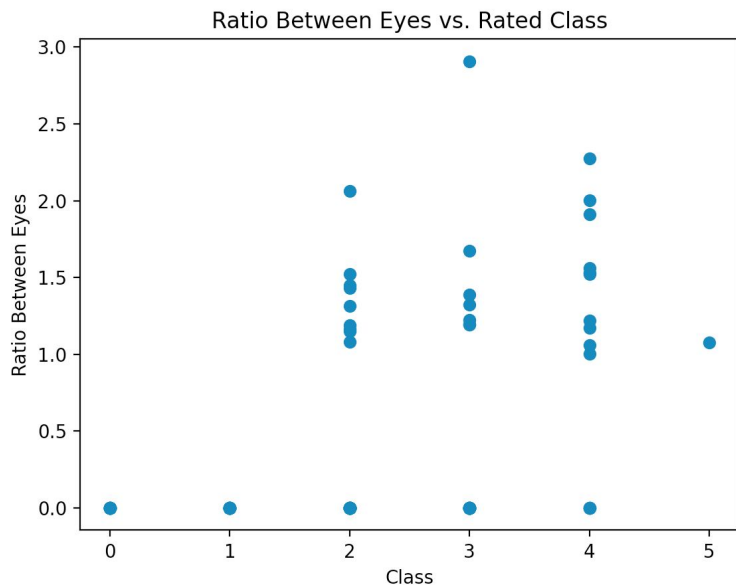


No Cat Found Strongly Disagree Disagree Neither Agree nor Disagree Agree Strongly Agree

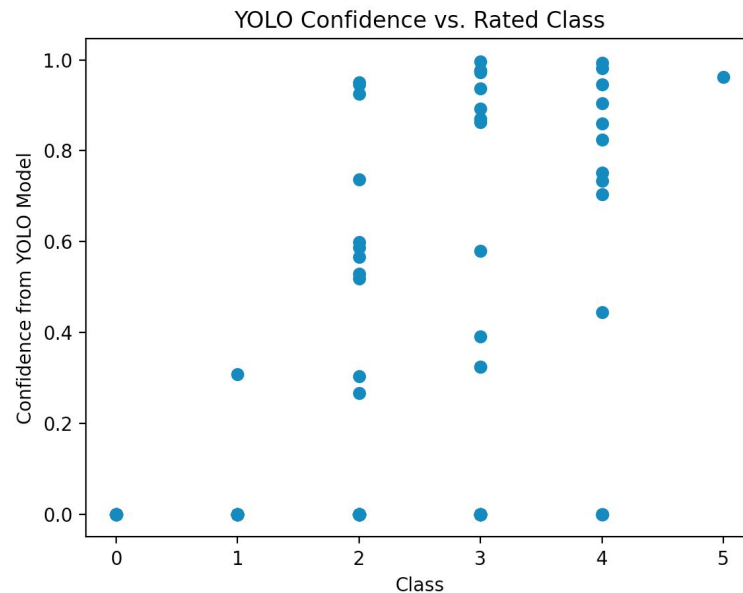
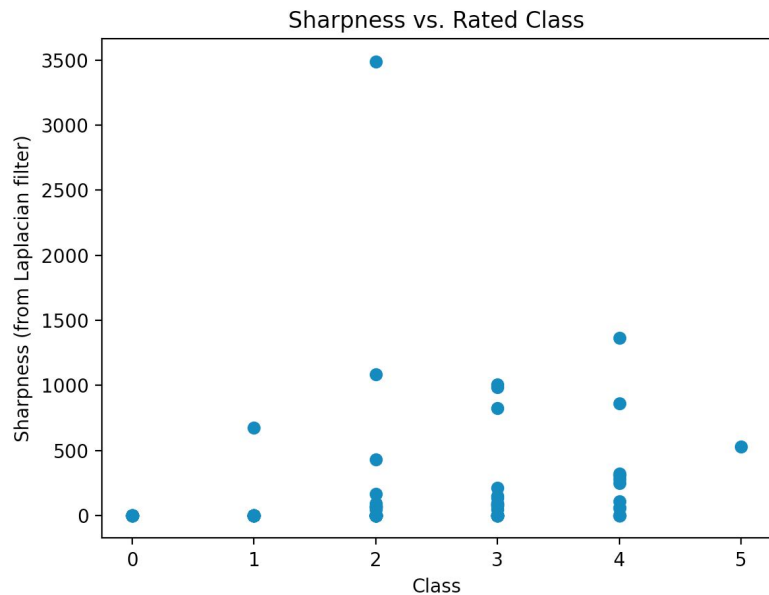
Quit

Navigation icons: home, back, forward, zoom in, zoom out, search, and save.

REGRESSION: EDA ON PREDICTORS



REGRESSION: EDA ON PREDICTORS

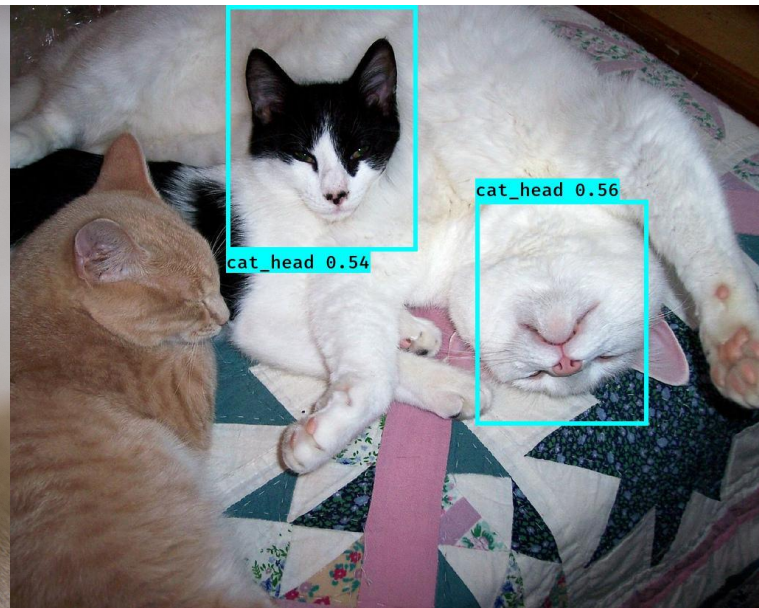
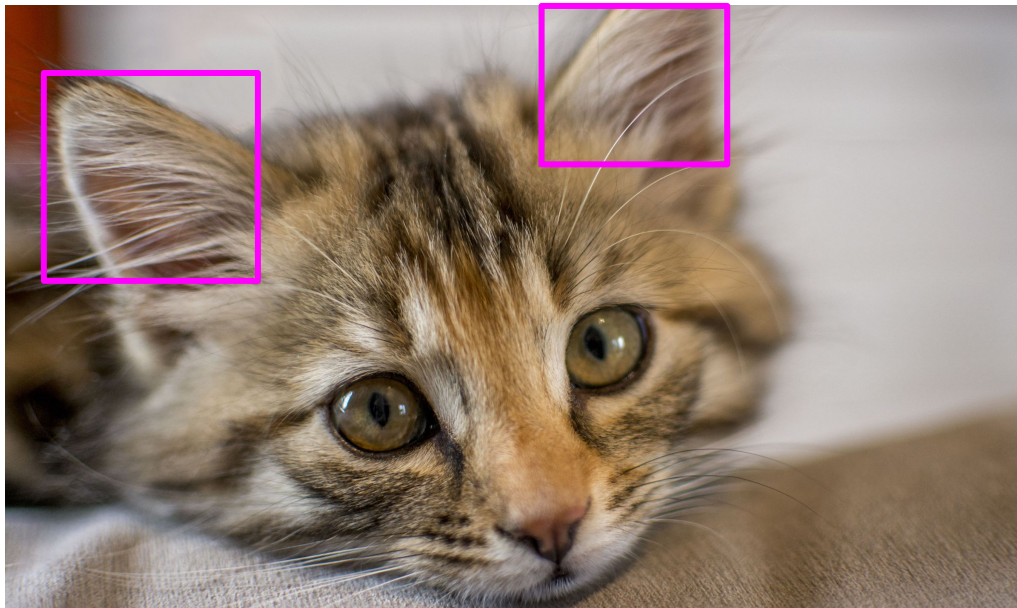


REGRESSION: RESULTS

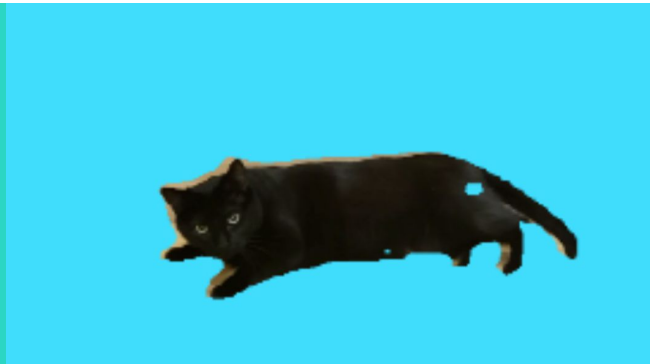
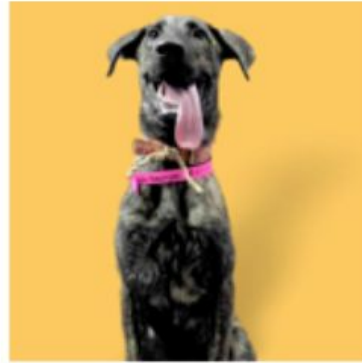
- Used 'out-of-box' sklearn Logistic Regression for Python
- Need to fine-tune model on more data, some of the metrics we had didn't perform as we would have liked to

| | Eye-Ratio | Head-Ratio | Confidence | Sharpness |
|---|-----------|------------|-------------|-------------|
| 1 | Red | Light Red | Red | Light Red |
| 2 | Green | Red | Red | Light Green |
| 3 | Red | Green | Green | Light Red |
| 4 | Green | Green | Green | Light Green |
| 5 | Red | Light Red | Light Green | Light Red |

NEXT STEPS: REFINING MODEL



NEXT STEPS: BACKGROUND SUBTRACT



NEXT STEPS: WEB INTERFACE



THANK YOU

Questions?

