

Bias-Variance Tradeoff

Optimal Prediction

Goal: Predict $Y \in \mathbb{R}^d$ given $X \in \mathbb{R}^d$ if $(X, Y) \sim P_{XY}$

Find function η that minimizes

$$\mathbb{E}_{XY}[(Y - \eta(X))^2] = \mathbb{E}_X \left[\mathbb{E}_{Y|X}[(Y - \eta(x))^2 | X = x] \right]$$

(Hint: for any x , $\eta(x) = c_x$ where c_x minimizes $\mathbb{E}_{Y|X}[(Y - c_x)^2 | X = x]$)

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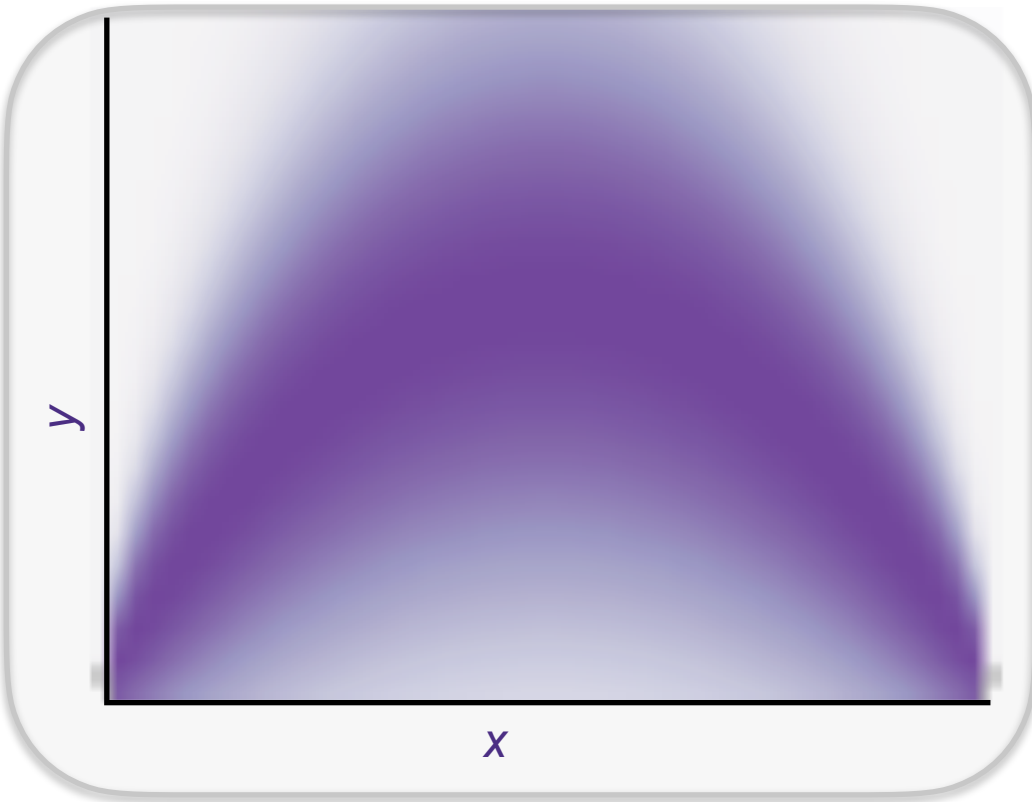
$$\begin{aligned} 0 &= \frac{d}{dc_x} \mathbb{E}_{Y|X}[(Y - c_x)^2 | X = x] \\ &= \mathbb{E}_{Y|X} \left[\frac{d}{dc_x} (Y - c_x)^2 | X = x \right] \\ &= \mathbb{E}_{Y|X}[-2(Y - c_x) | X = x] = -2\mathbb{E}_{Y|X}[Y | X = x] + 2c_x \end{aligned}$$

Squared Error Optimal Predictor: $\eta(x) = \mathbb{E}_{Y|X}[Y | X = x]$

Statistical Learning

$$\mathbb{E}_{XY}[(Y - \eta(X))^2]$$

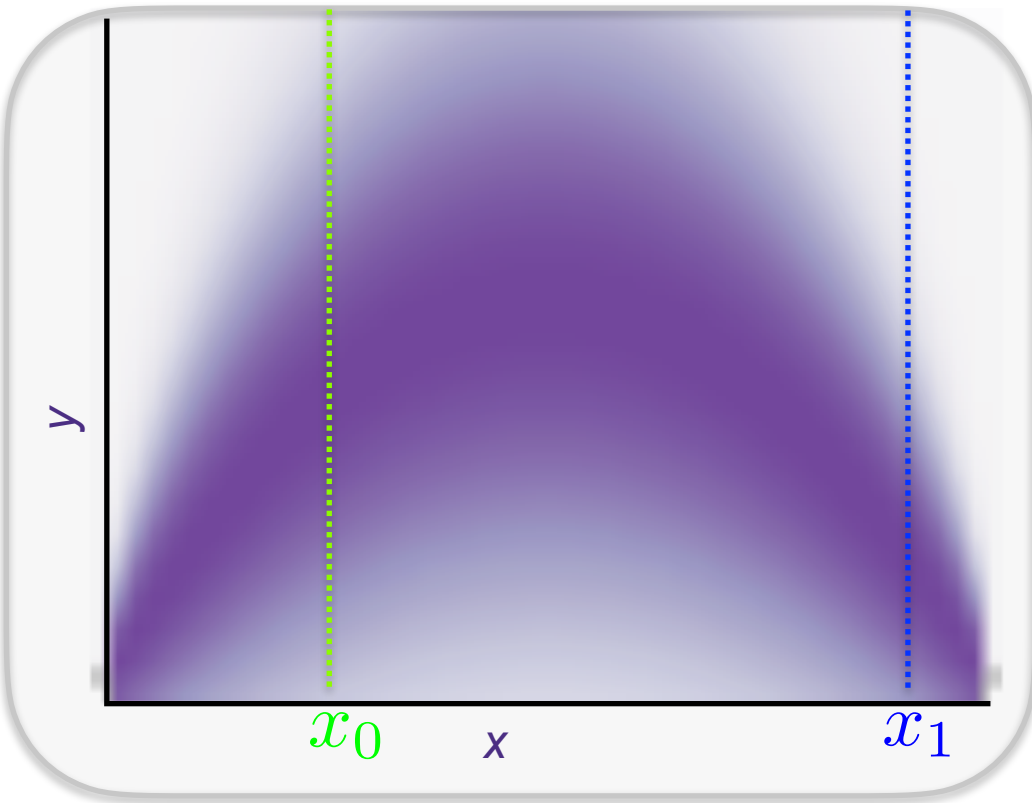
$$P_{XY}(X = x, Y = y)$$



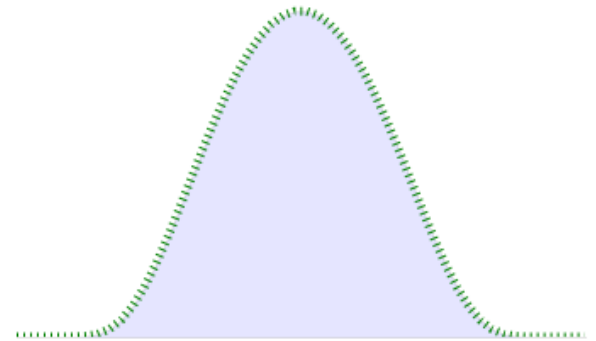
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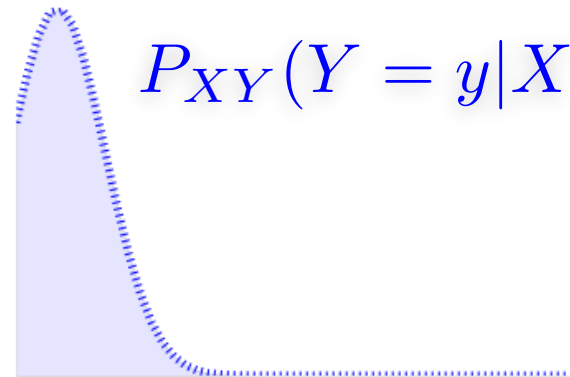
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$$P_{XY}(Y = y|X = x_0)$$



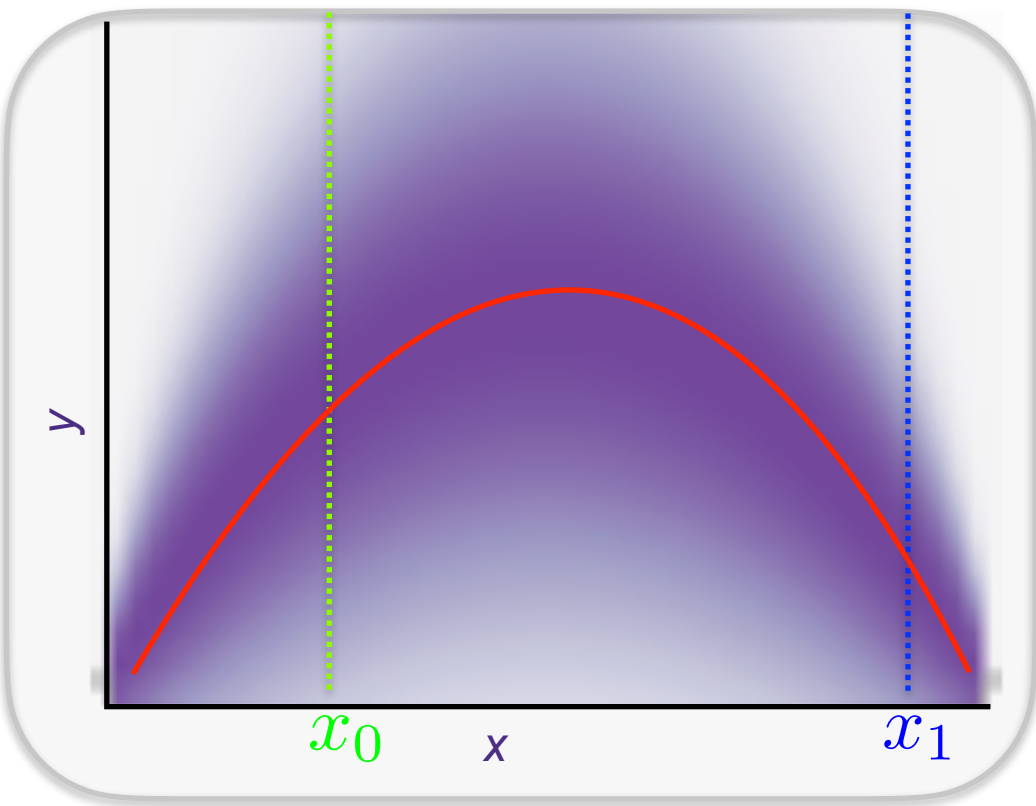
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Statistical Learning

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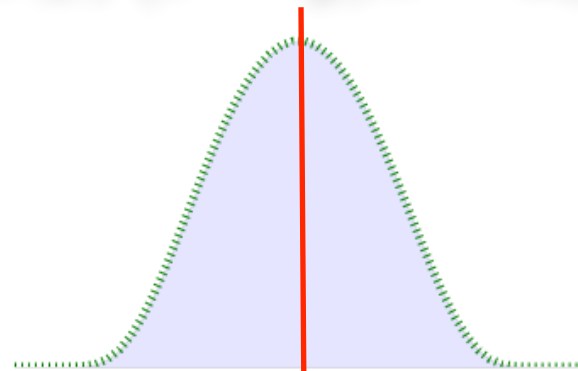
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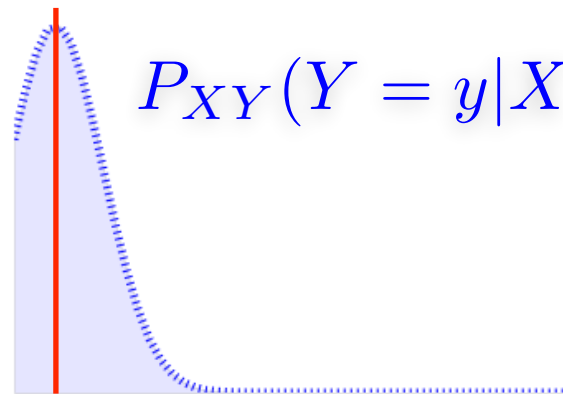
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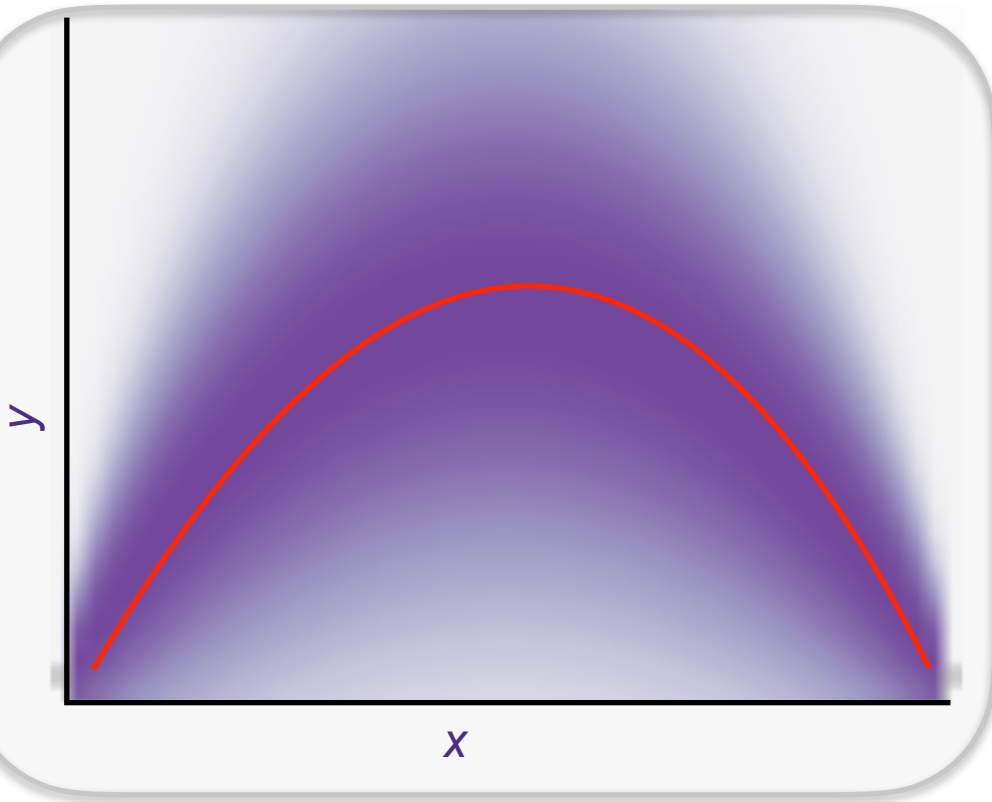


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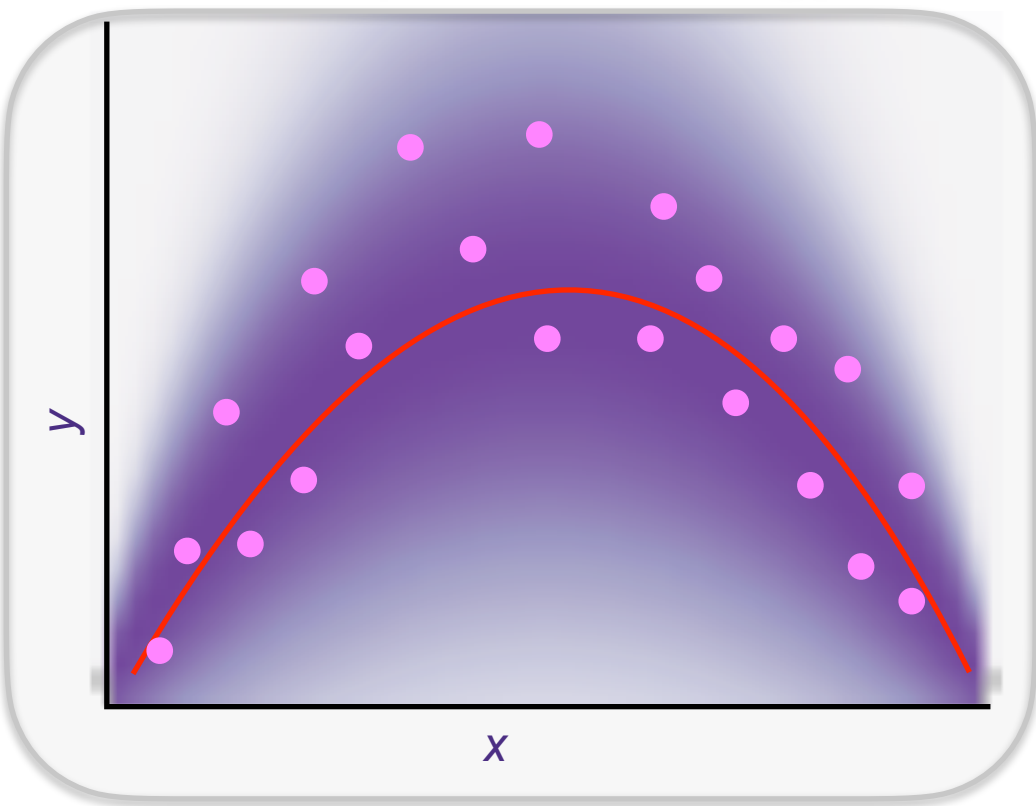
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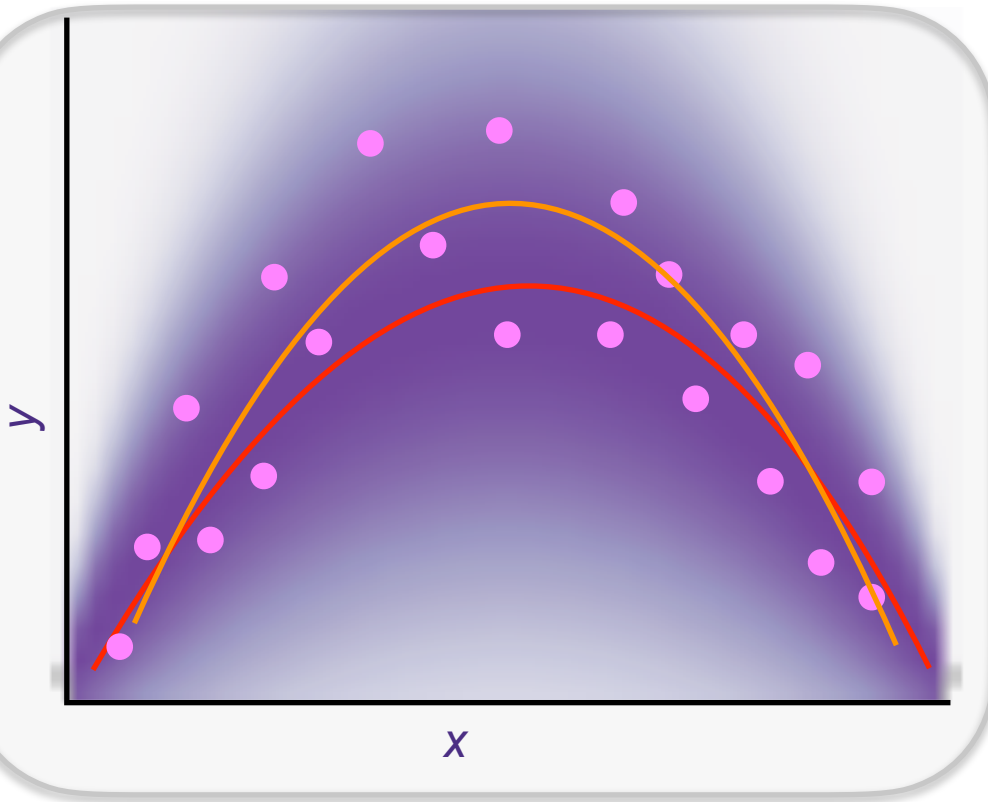
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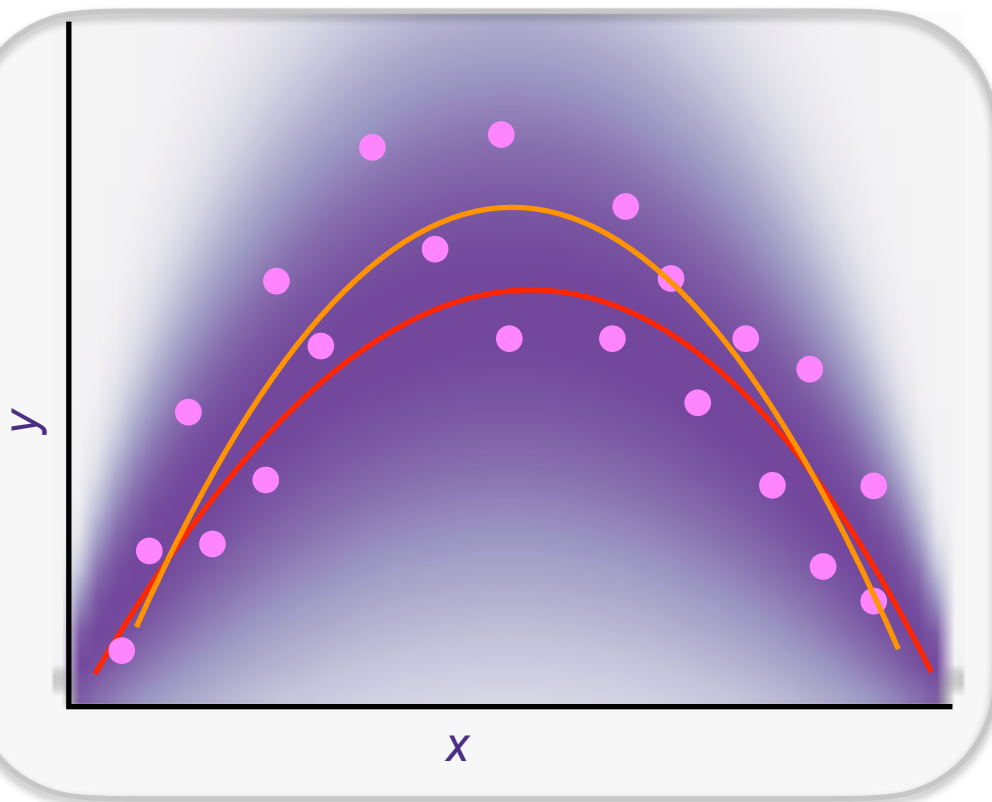
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and are restricted to a
function class (e.g., linear)
so we compute:

$$\hat{f} = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$$

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We care about future predictions: $\mathbb{E}_{XY}[(Y - \hat{f}(X))^2]$

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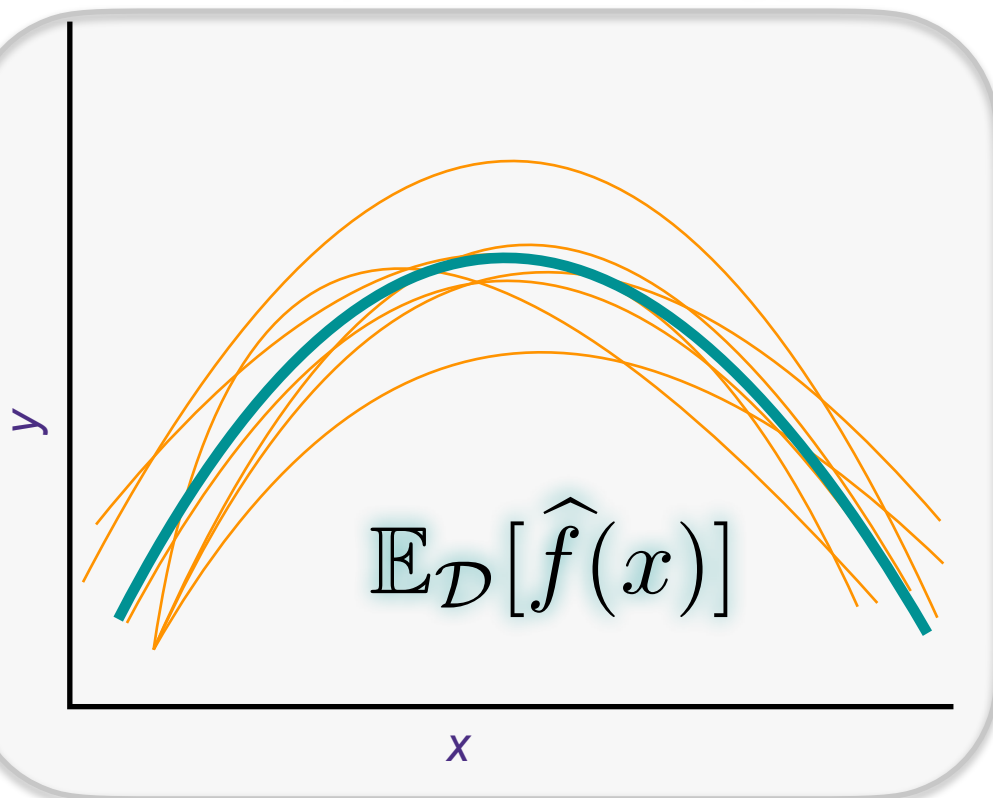
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Each draw $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$ results in different \hat{f}

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Bias-Variance Tradeoff

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$$\mathbb{E}_{Y|X}[\mathbb{E}_{\mathcal{D}}[(Y - \hat{f}_{\mathcal{D}}(x))^2]|X = x] = \mathbb{E}_{Y|X}[\mathbb{E}_{\mathcal{D}}[(Y - \eta(x) + \eta(x) - \hat{f}_{\mathcal{D}}(x))^2]|X = x]$$

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irreducible error

Caused by stochastic
label noise

learning error

Caused by either using too
“simple” of a model or not
enough data to learn the model
accurately

Bias-Variance Tradeoff

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Bias-Variance Tradeoff

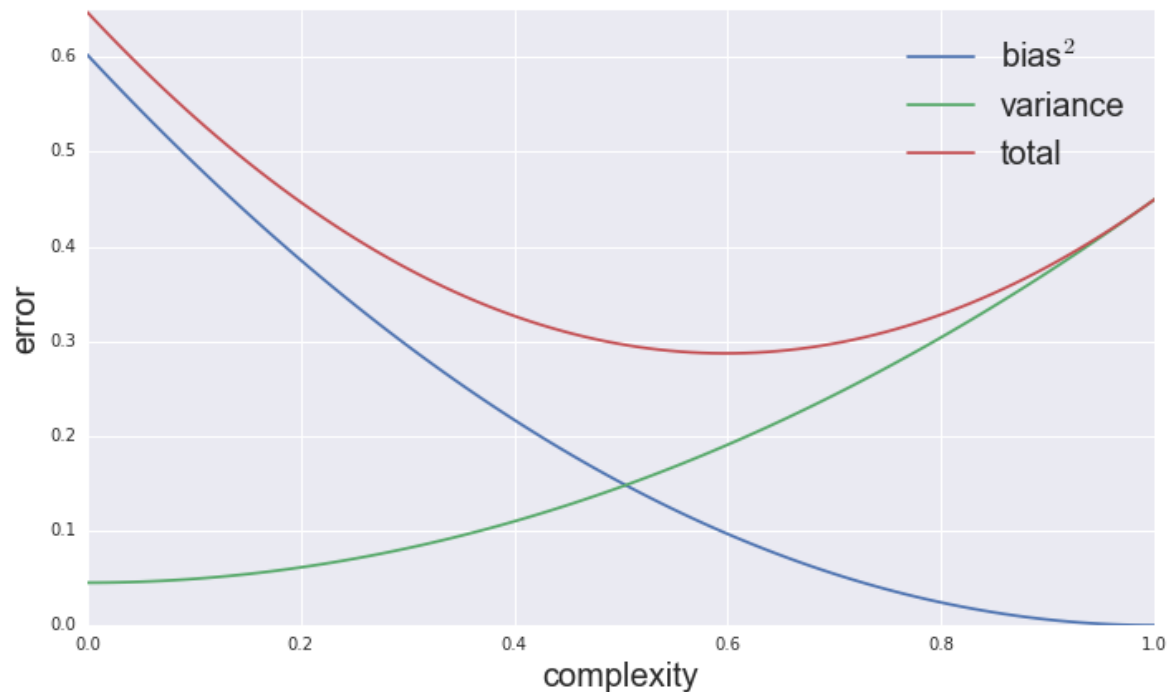
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irreducible error

$$+ \underbrace{(\eta(x) - \mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)])^2}_{\text{biased squared}} + \underbrace{\mathbb{E}_{\mathcal{D}}[(\mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)] - \hat{f}_{\mathcal{D}}(x))^2]}_{\text{variance}}$$

biased squared

variance



Overfitting

Bias-Variance Tradeoff

- > Choice of hypothesis class introduces learning bias
 - More complex class → less bias
 - More complex class → more variance
- > But in practice??

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- > Choice of hypothesis class introduces learning bias
 - More complex class → less bias
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- > But in practice??
- > Before we saw how increasing the feature space can increase the complexity of the learned estimator:

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

$$\hat{f}_{\mathcal{D}}^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

Complexity grows as k grows

Training set error as a function of model complexity

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TRAIN error:

$$\mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$
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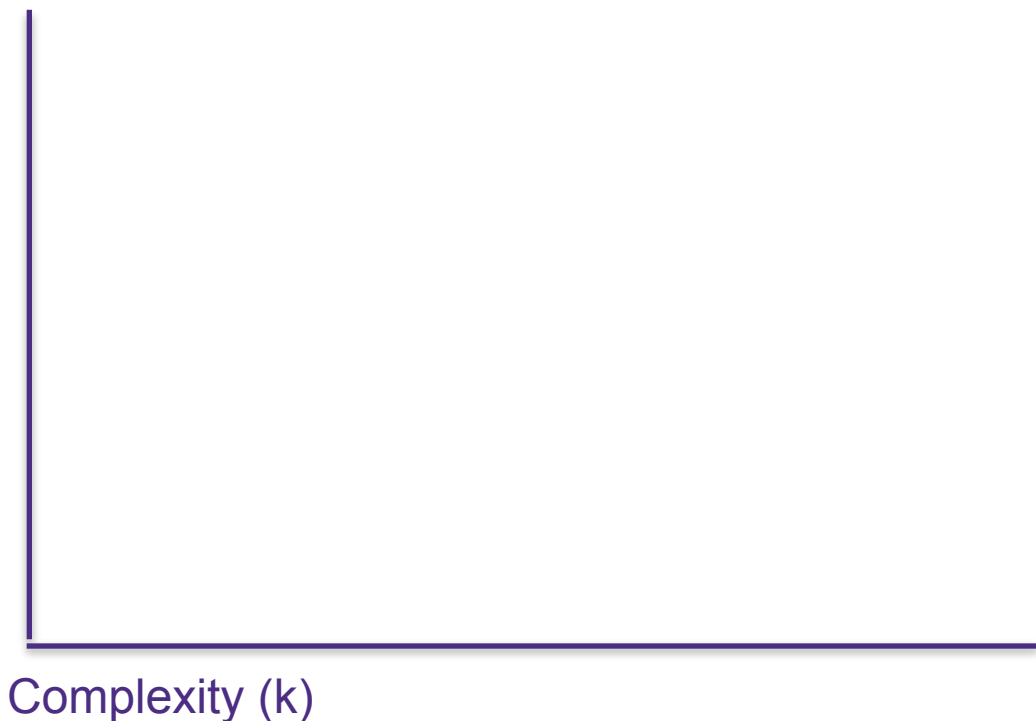
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TEST error:

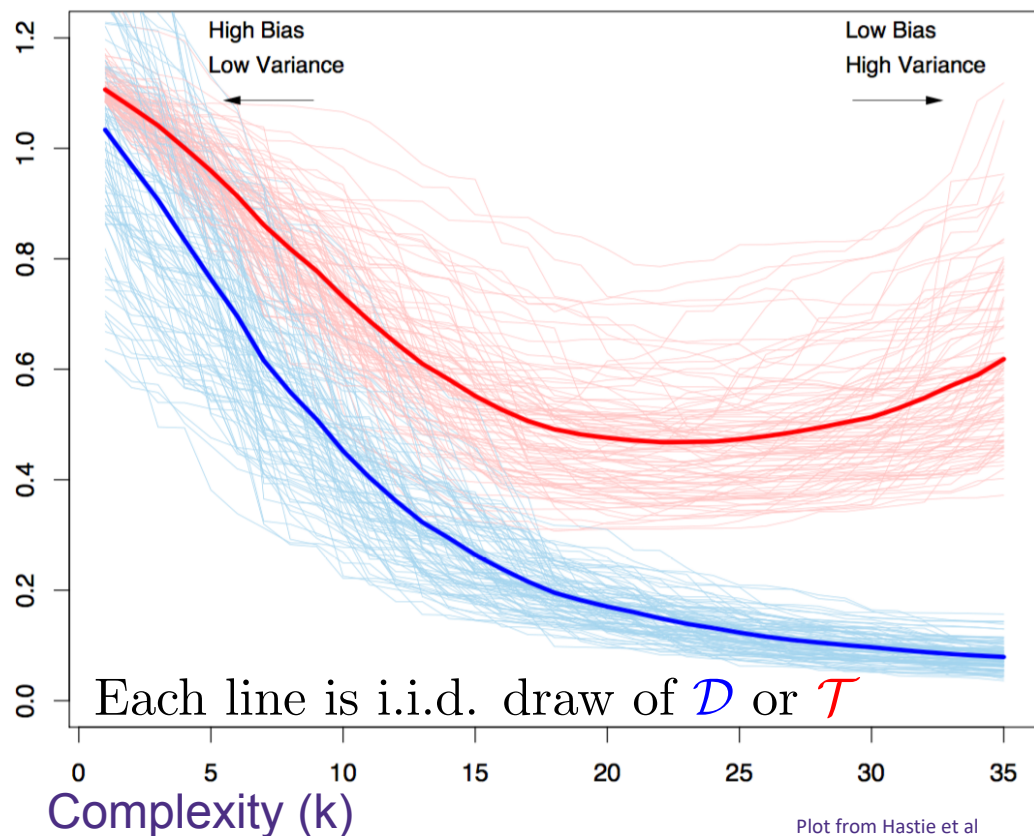
$$\mathcal{T} \stackrel{i.i.d.}{\sim} P_{XY}$$
$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

Training set error as a function of model complexity

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TRAIN error is **optimistically biased** because it is evaluated on the data it trained on. **TEST error** is **unbiased** only if \mathcal{T} is never used to train the model or even pick the complexity k .

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Test set error

> Given a dataset, randomly split it into two parts:

– Training data: \mathcal{D}

– Test data: \mathcal{T}

Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

> Use **training data** to learn predictor

▪ e.g., $\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$

▪ use **training data** to pick complexity k

> Use **test data** to report predicted performance

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

How many points do I use for training/testing?

> Very hard question to answer!

- Too few training points, learned model is bad
- Too few test points, you never know if you reached a good solution

> Bounds, such as Hoeffding's inequality can help:

$$P(|\hat{\theta} - \theta^*| \geq \epsilon) \leq 2e^{-2N\epsilon^2}$$

> More on this later the quarter, but still hard to answer

> Typically:

- If you have a reasonable amount of data 90/10 splits are common
- If you have little data, then you need to get fancy (e.g., bootstrapping)