

# 10-601 Introduction to Machine Learning

Machine Learning Department  
School of Computer Science  
Carnegie Mellon University

# Experimental Design

+

# k-Nearest Neighbors

## KNN Readings:

Mitchell 8.2  
HTF 13.3  
Murphy --  
Bishop 2.5.2

## Prob. Readings: (next lecture)

Lecture notes from 10-600  
(See Piazza post for the pointers)

Murphy 2  
Bishop 2  
HTF --  
Mitchell --

Matt Gormley  
Lecture 3  
January 25, 2016

# Reminders

- **Background Exercises (Homework 1)**
  - Released: Wed, Jan. 25
  - Due: Mon, Jan. 30 at 5:30pm
- **Website updates**
  - Office hours Google calendar on “People”
  - Readings on “Schedule”
- **Meet Als: Sarah, Daniel, Brynn**

# Outline

- **k-Nearest Neighbors (KNN)**
  - Special cases
  - Choosing k
  - Case Study: KNN on Fisher Iris Data
  - Case Study: KNN on 2D Gaussian Data
- **Experimental Design**
  - Train error vs. test error
  - Train / validation / test splits
  - Cross-validation
- **Function Approximation View of ML**

# K-NEAREST NEIGHBORS

# k-Nearest Neighbors

*Whiteboard:*

- Special cases
- Choosing k

# **KNN ON FISHER IRIS DATA**

# Fisher Iris Dataset

Fisher (1936) used 150 measurements of flowers from 3 different species: Iris setosa (0), Iris virginica (1), Iris versicolor (2) collected by Anderson (1936)

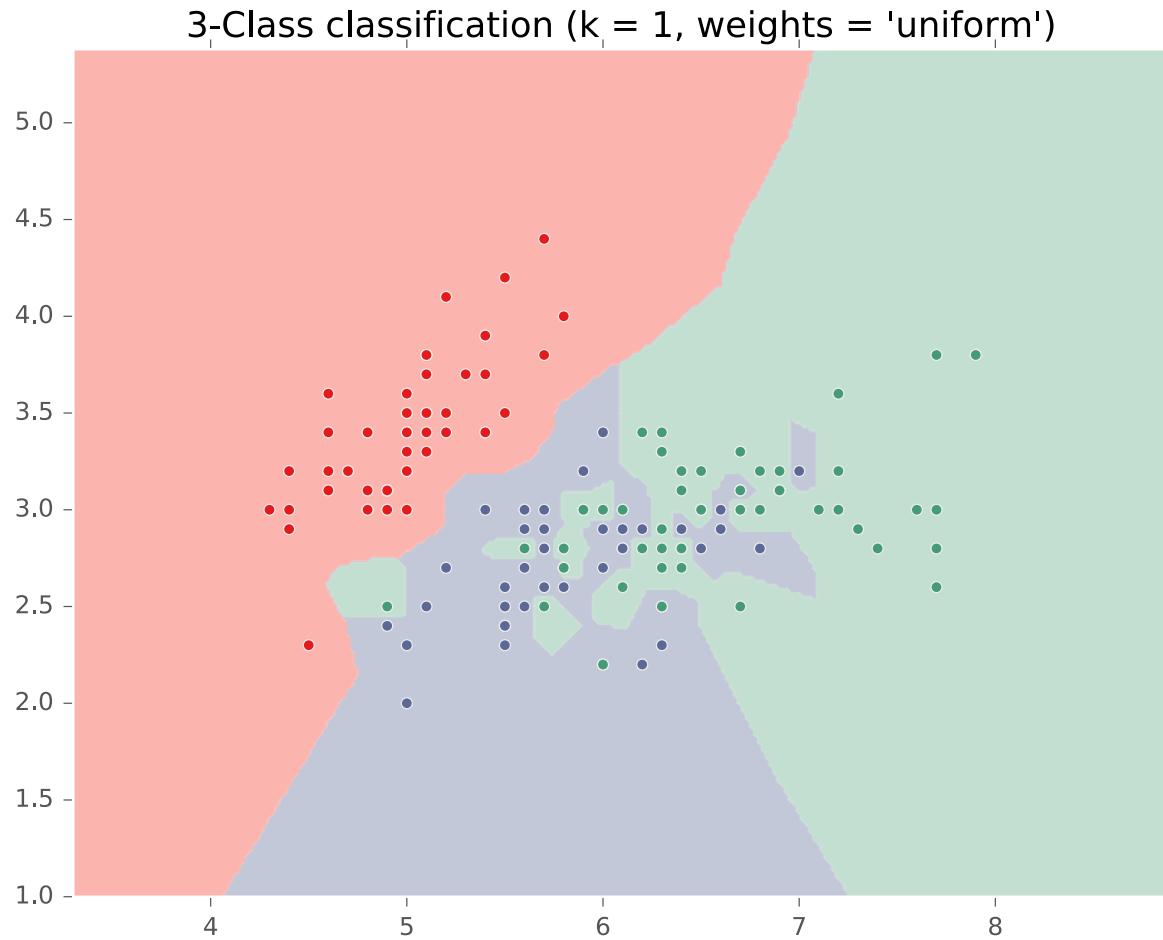
Species	Sepal Length	Sepal Width	Petal Length	Petal Width
0	4.3	3.0	1.1	0.1
0	4.9	3.6	1.4	0.1
0	5.3	3.7	1.5	0.2
1	4.9	2.4	3.3	1.0
1	5.7	2.8	4.1	1.3
1	6.3	3.3	4.7	1.6
1	6.7	3.0	5.0	1.7

# KNN on Fisher Iris Data



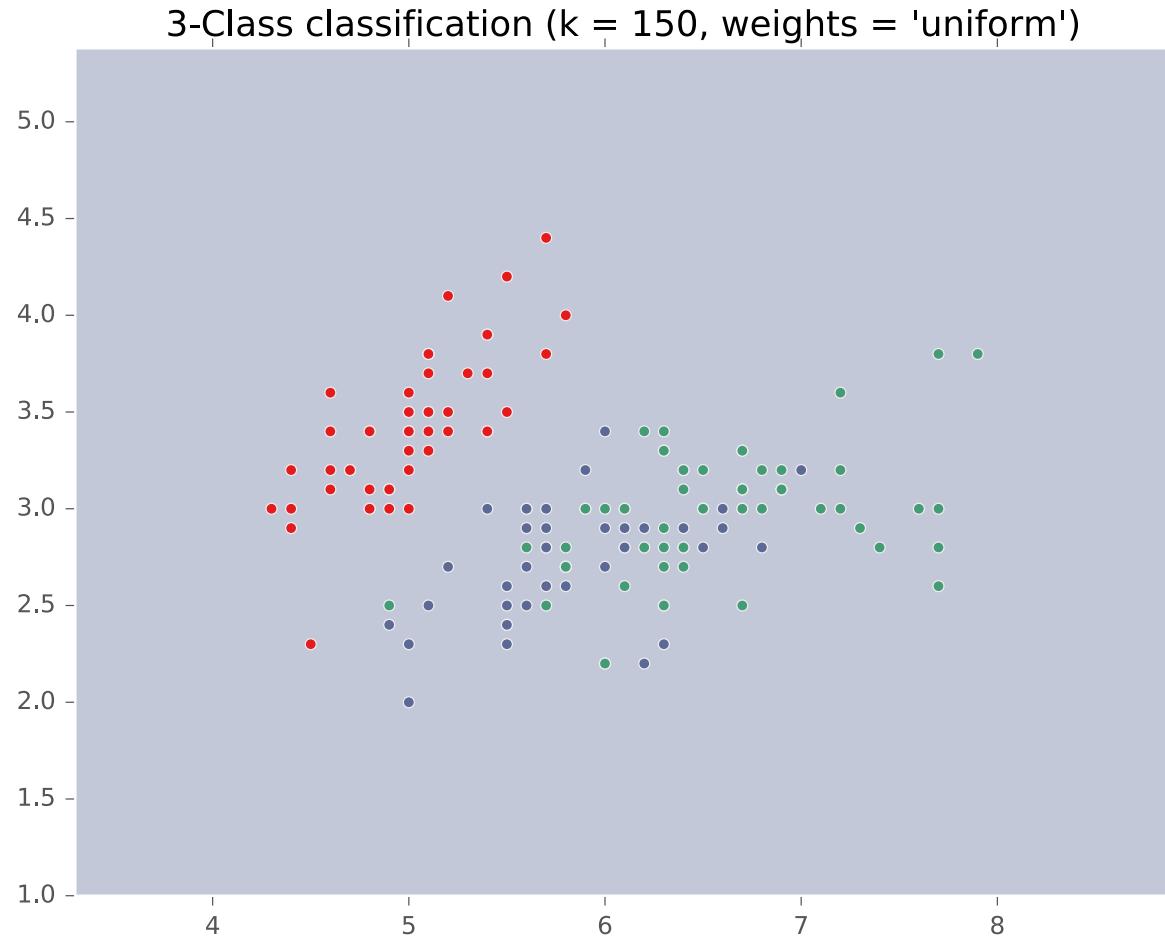
# KNN on Fisher Iris Data

## Special Case: Nearest Neighbor



# KNN on Fisher Iris Data

## Special Case: Majority Vote

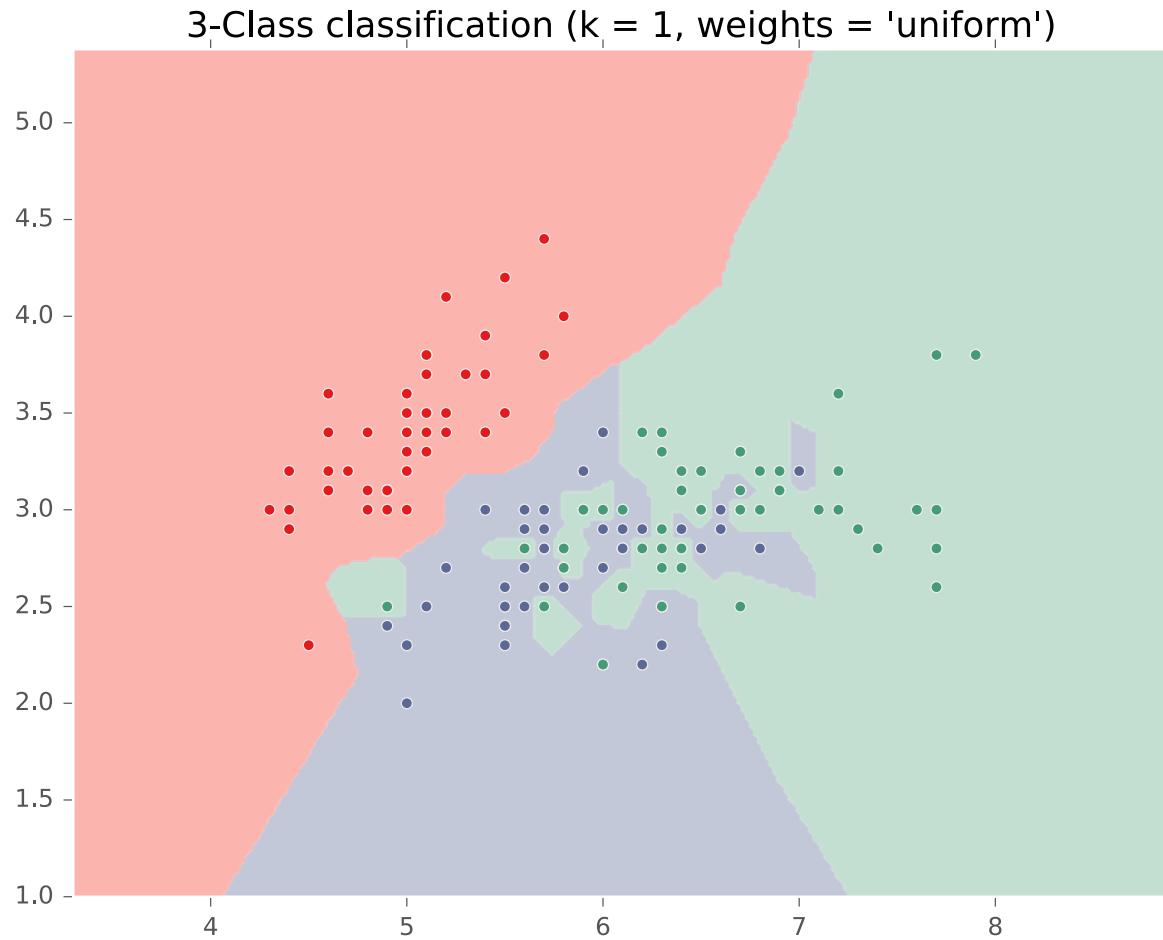


# KNN on Fisher Iris Data

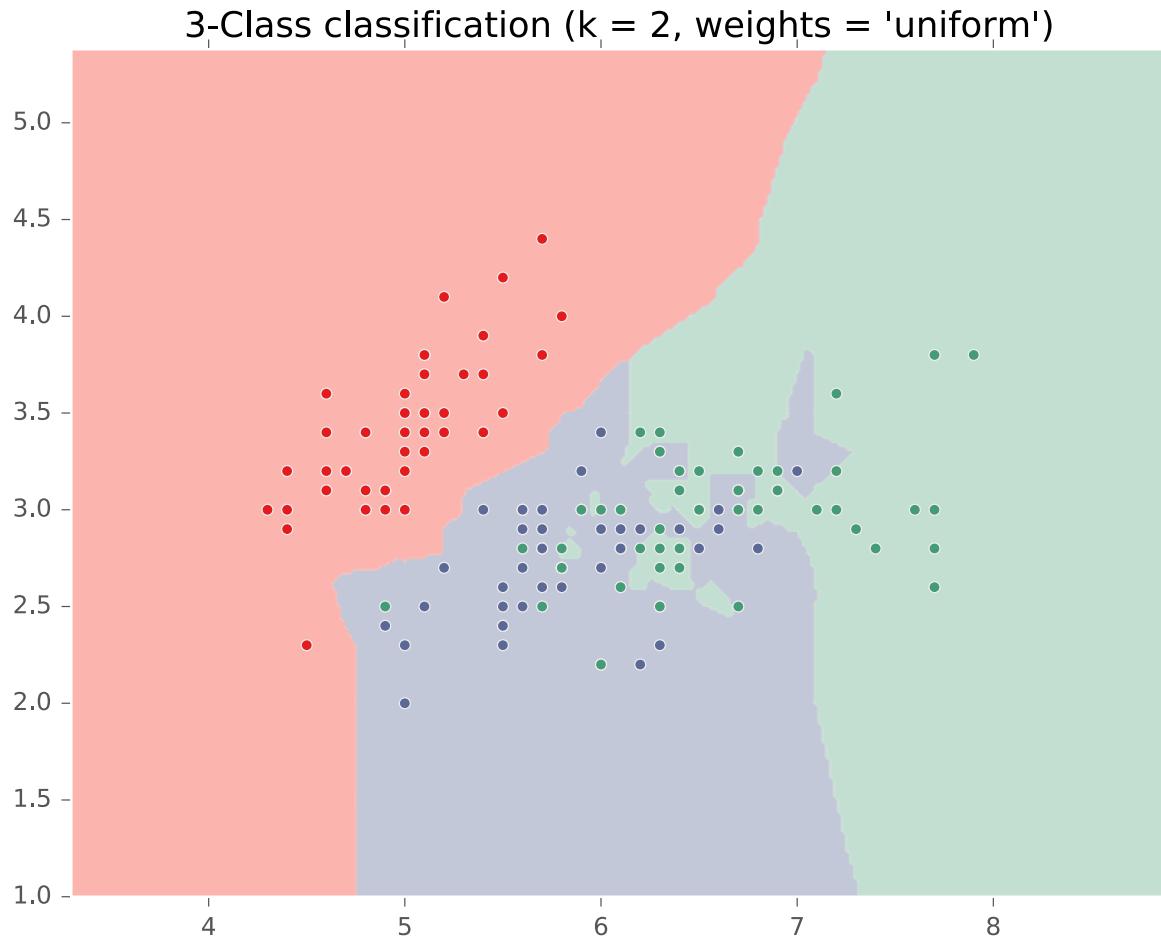


# KNN on Fisher Iris Data

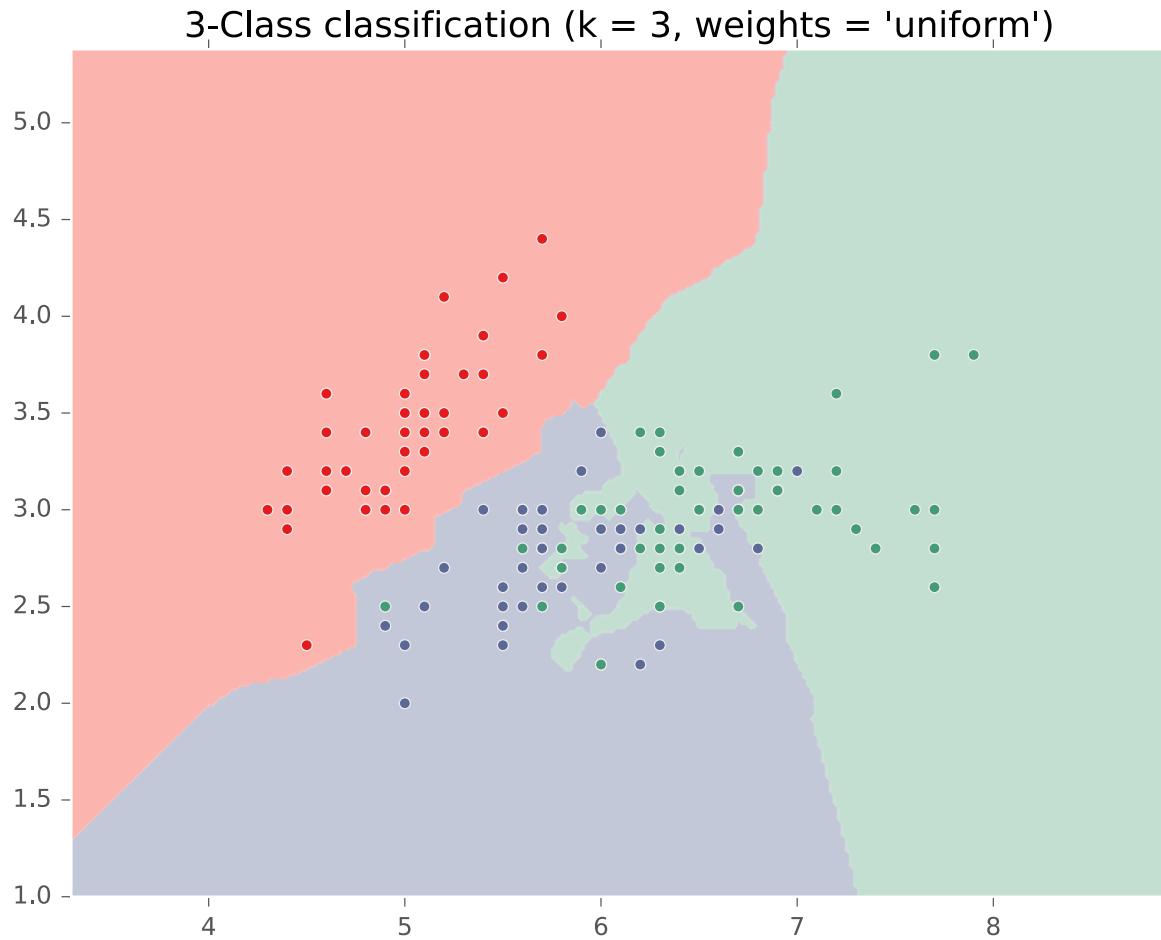
## Special Case: Nearest Neighbor



# KNN on Fisher Iris Data



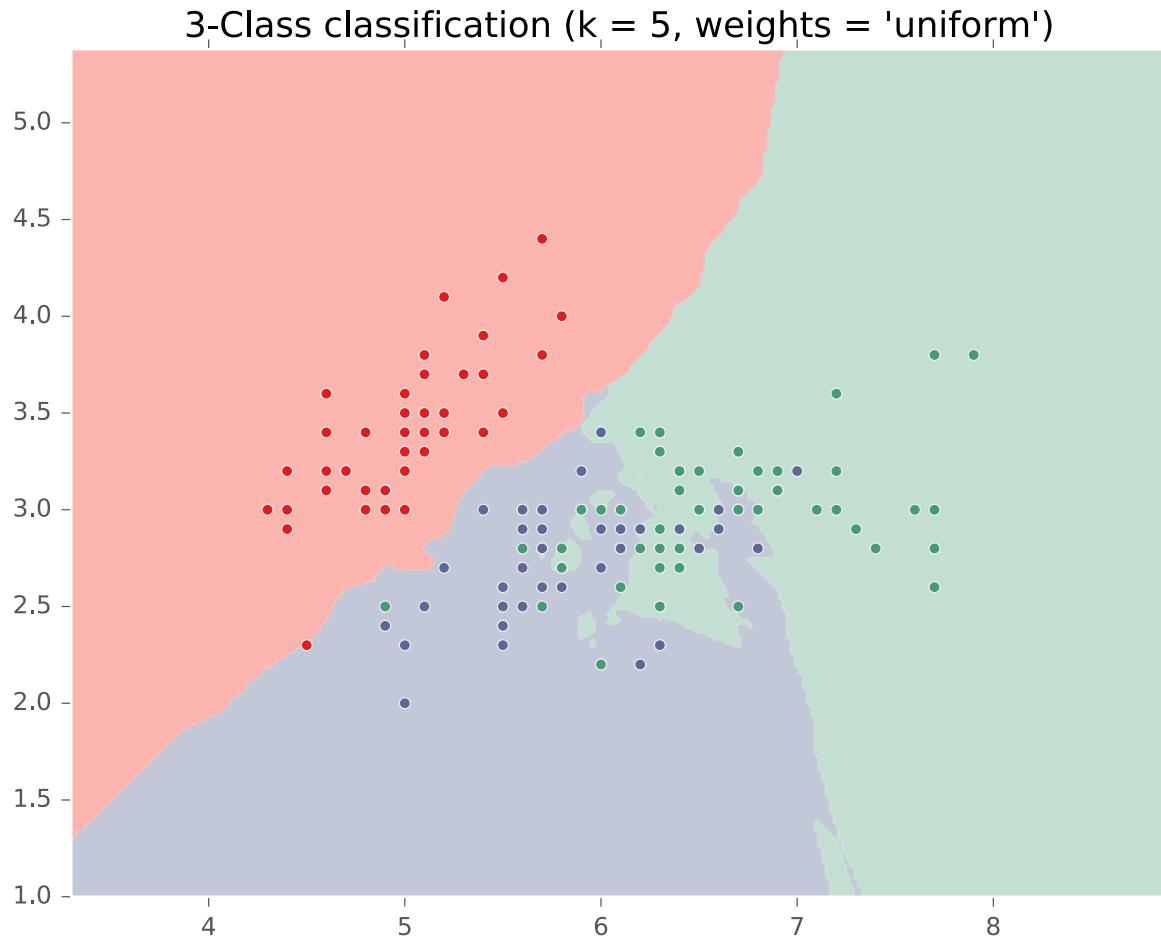
# KNN on Fisher Iris Data



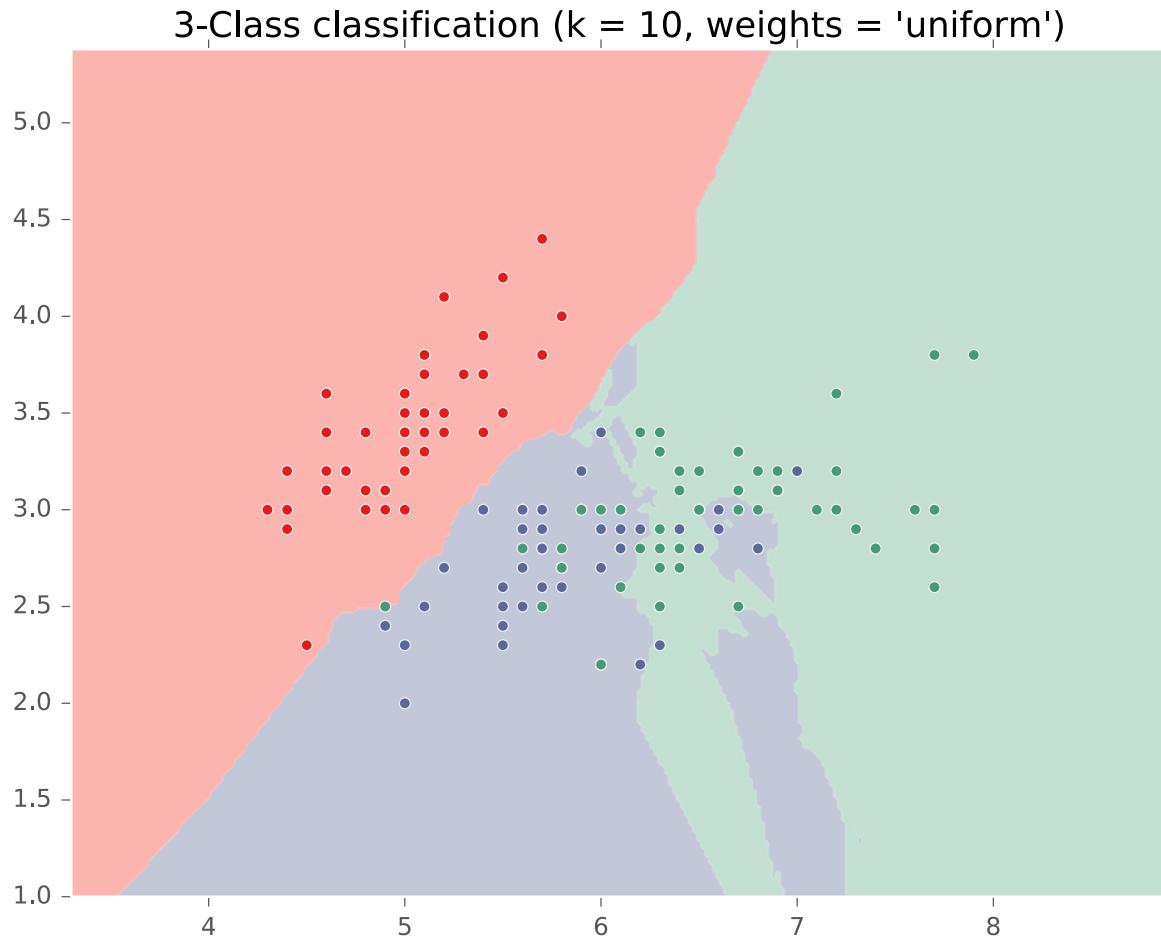
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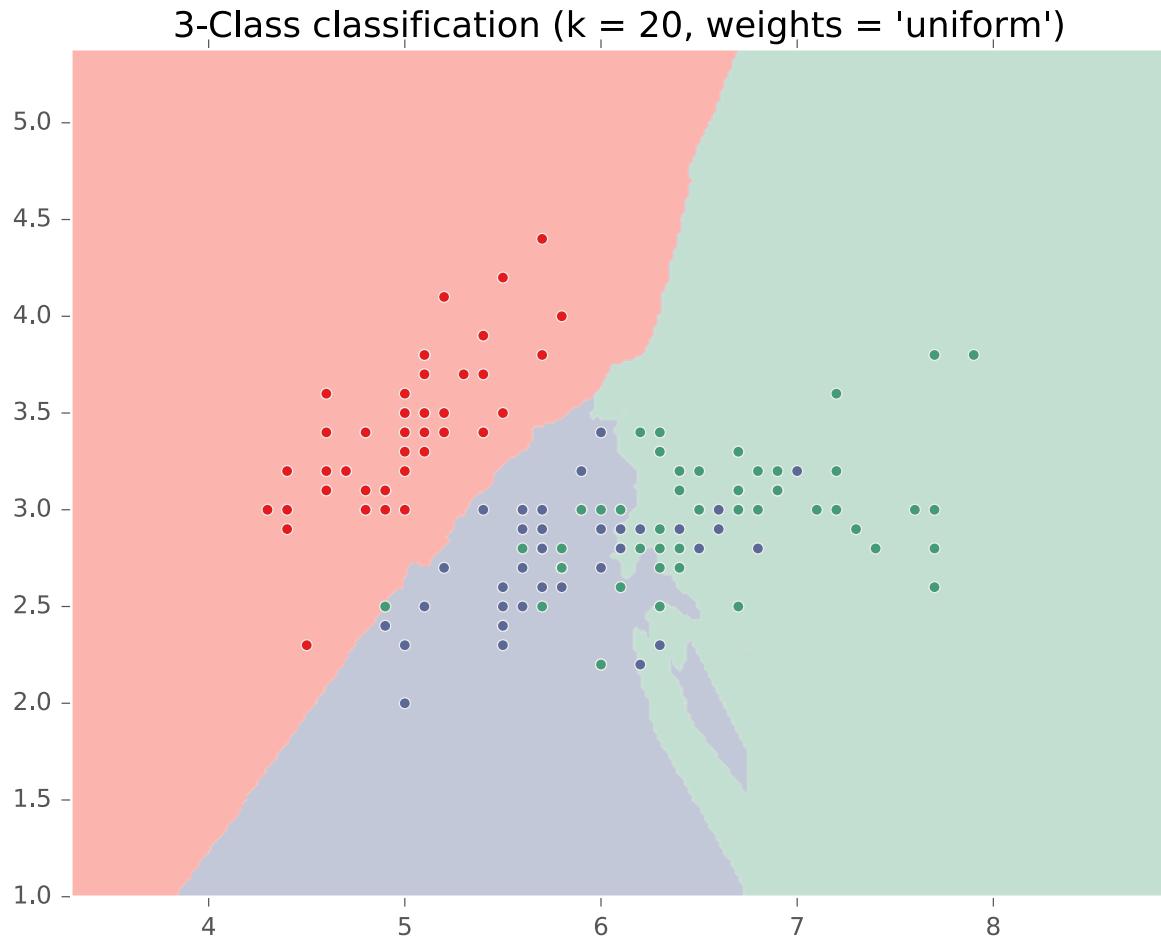
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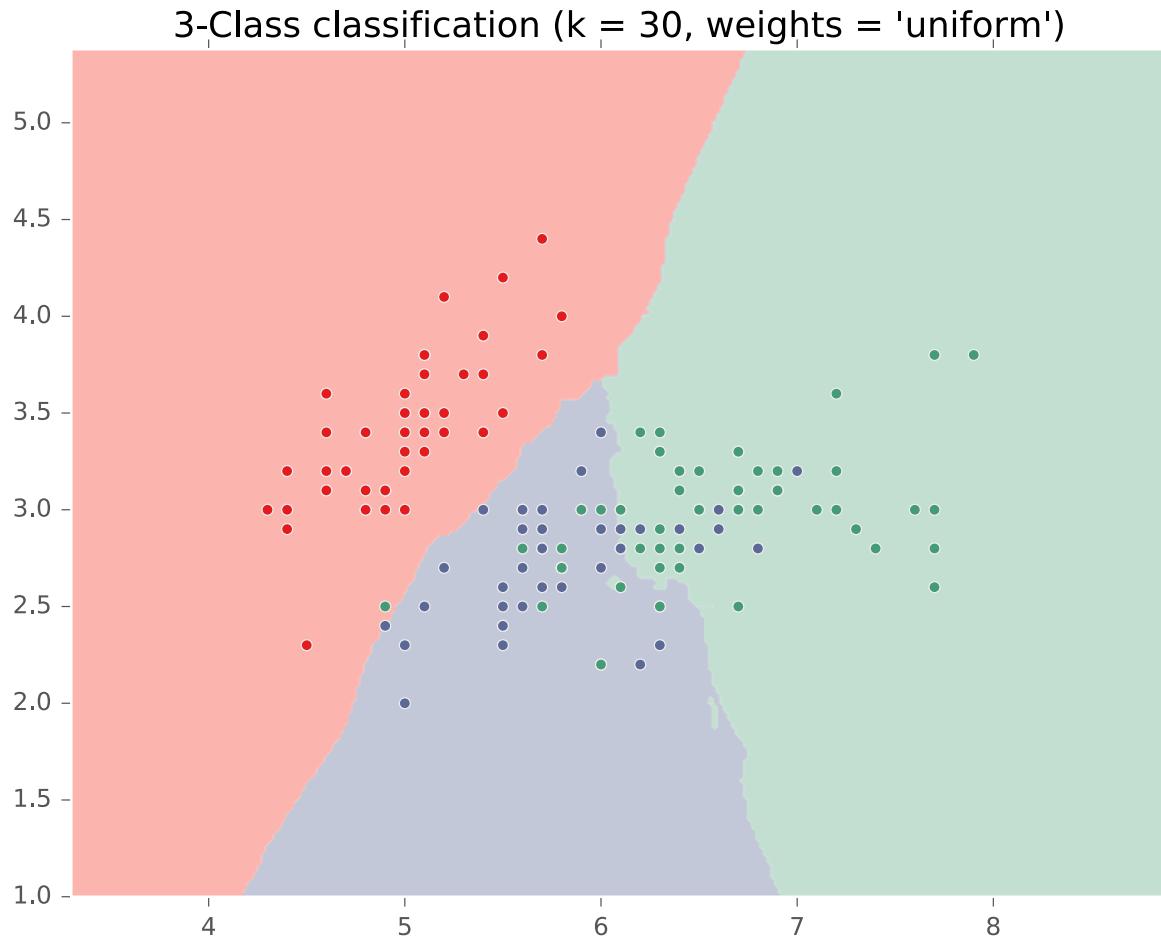
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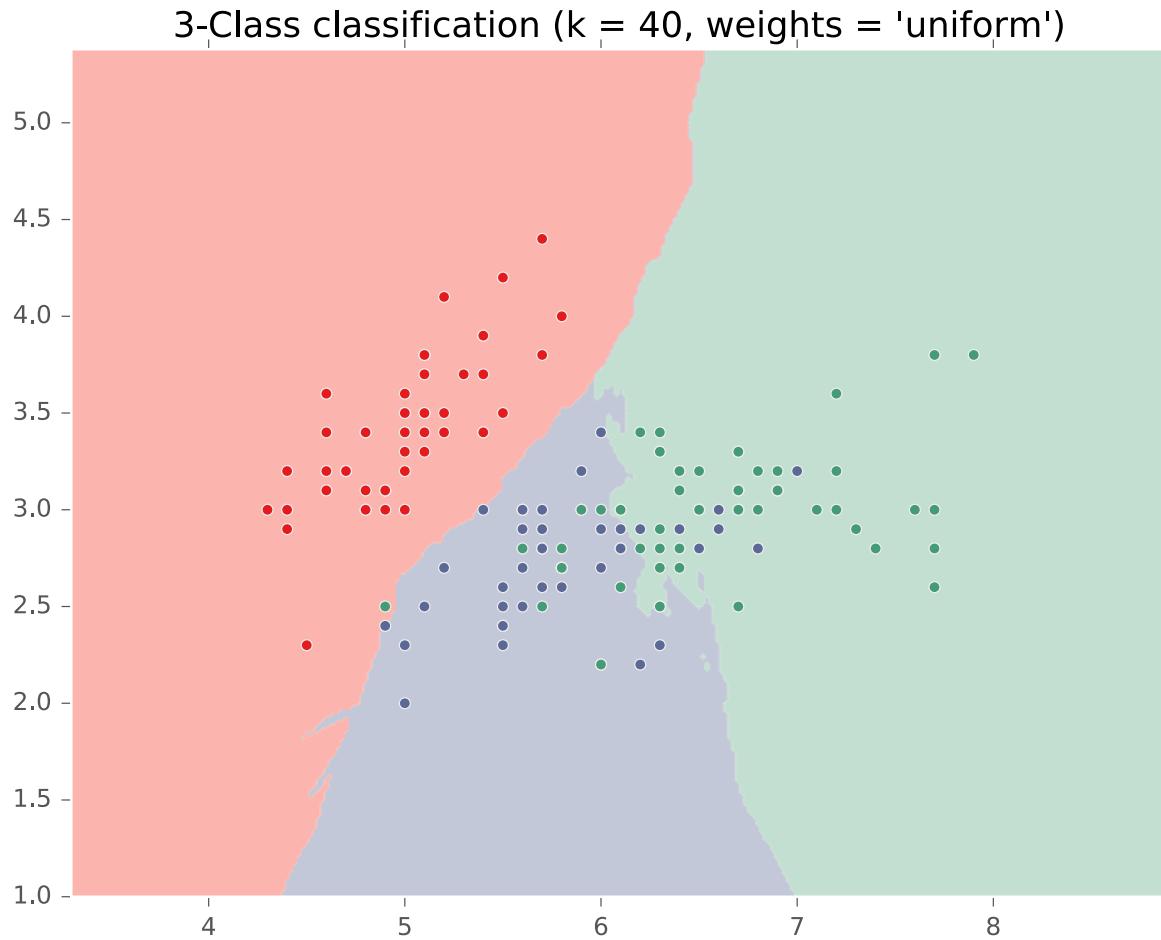
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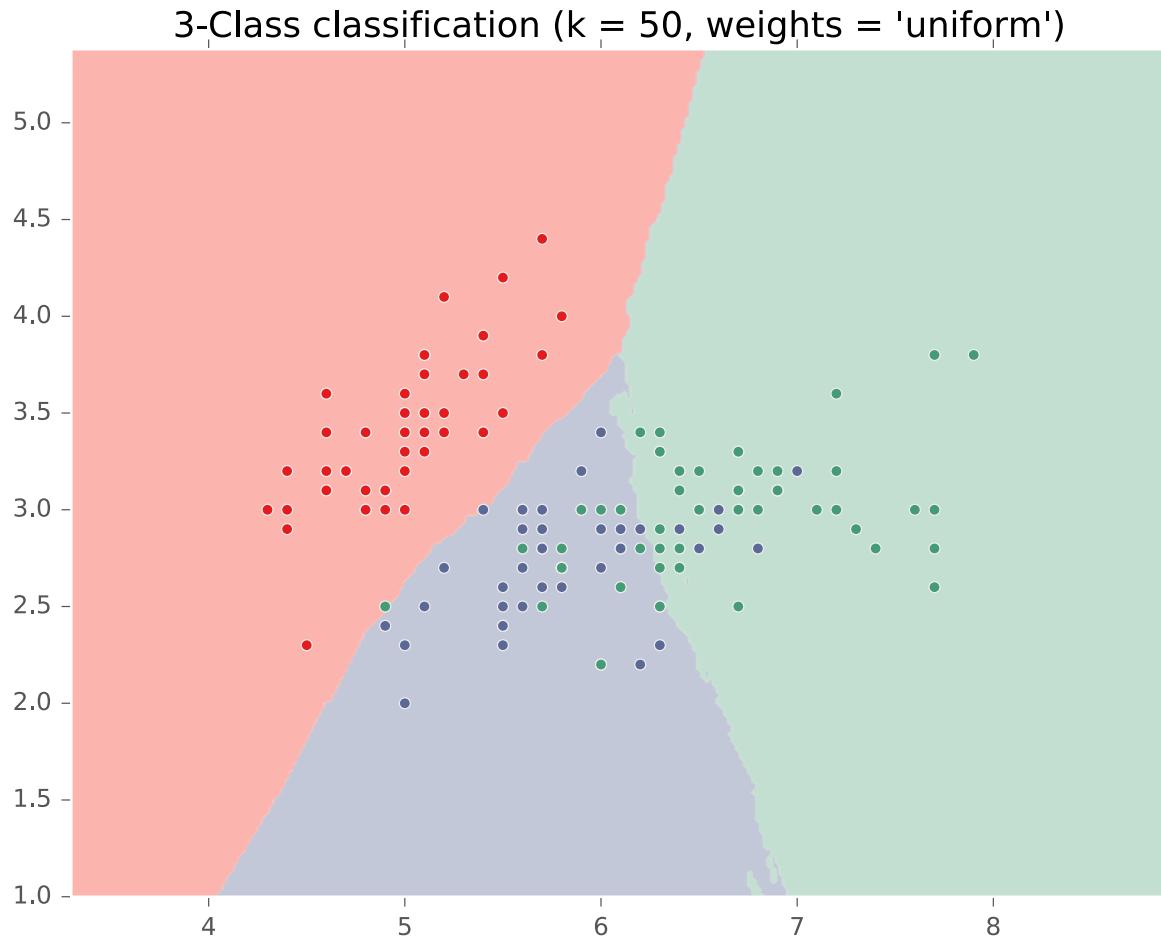
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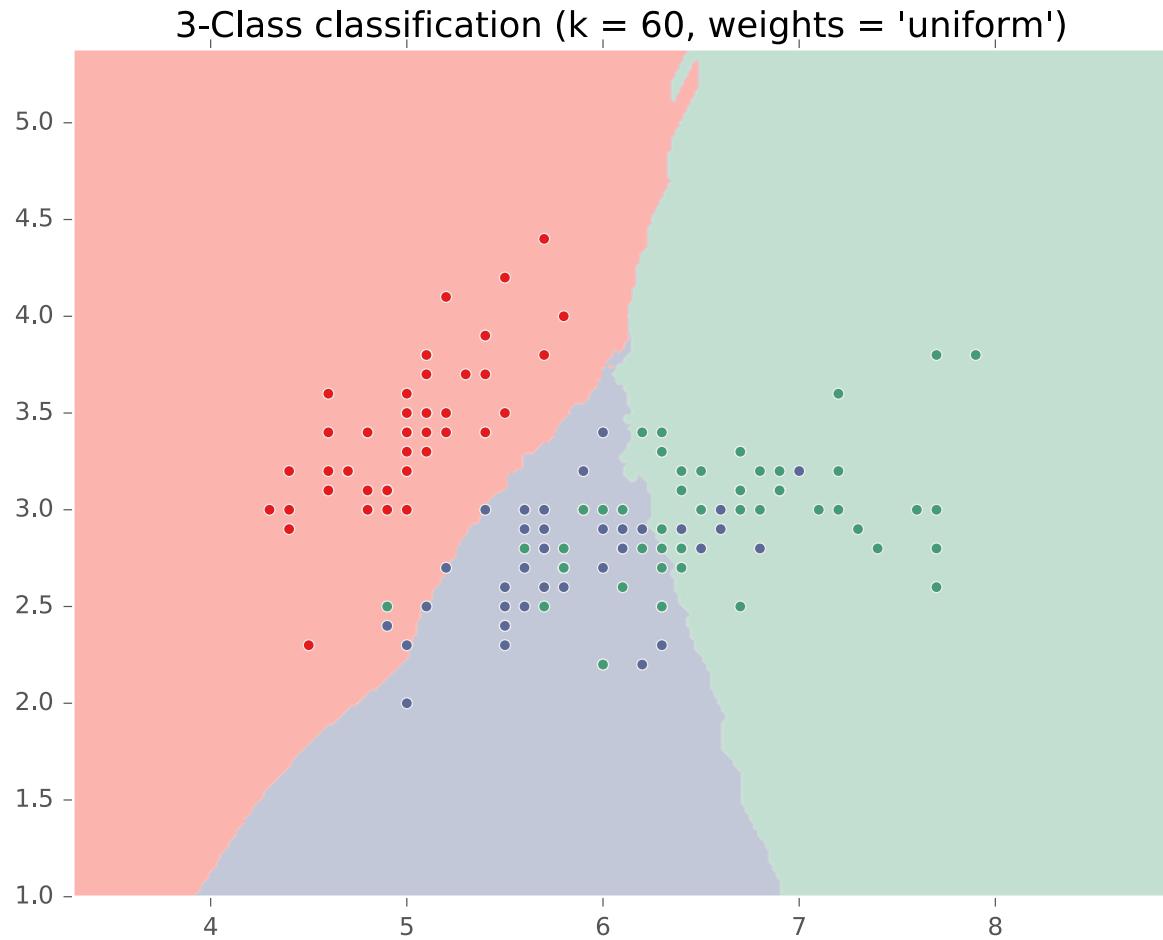
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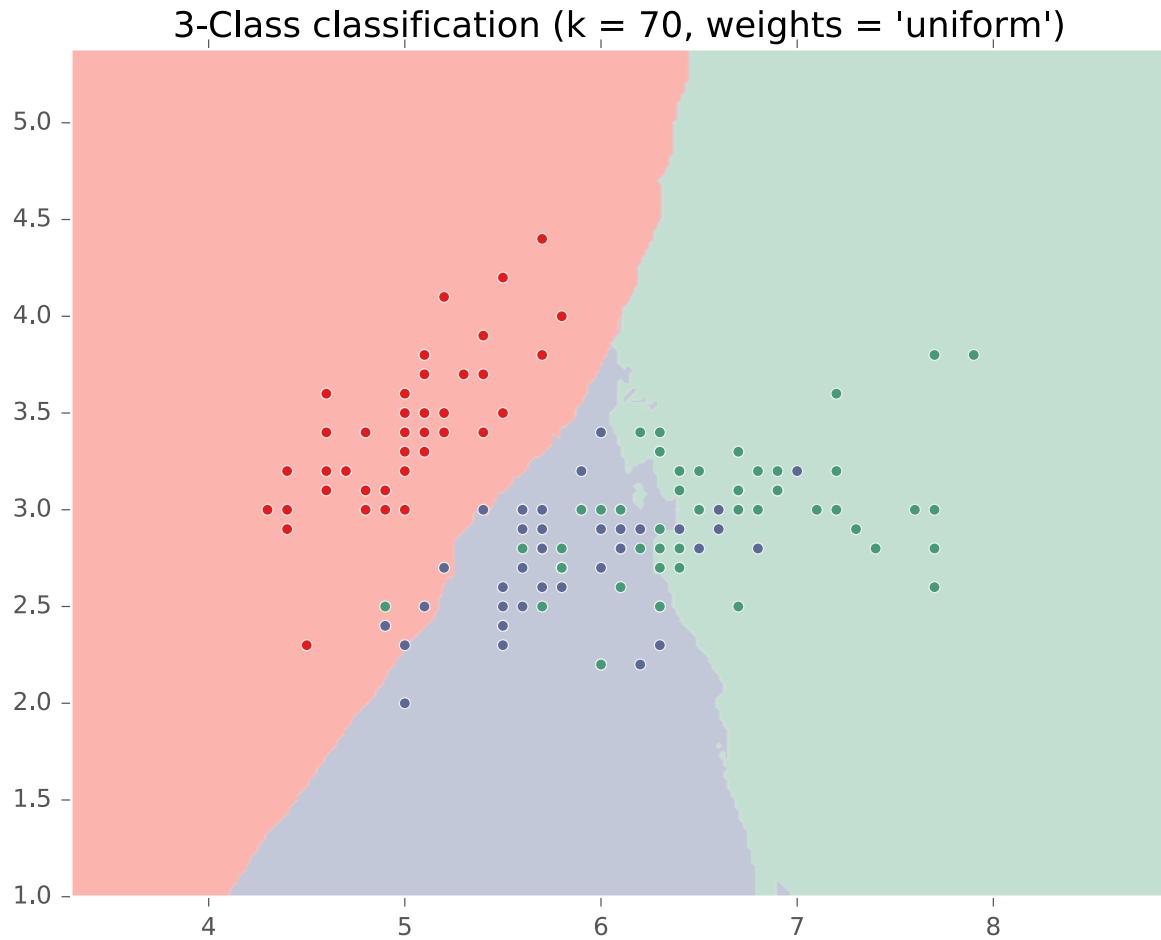
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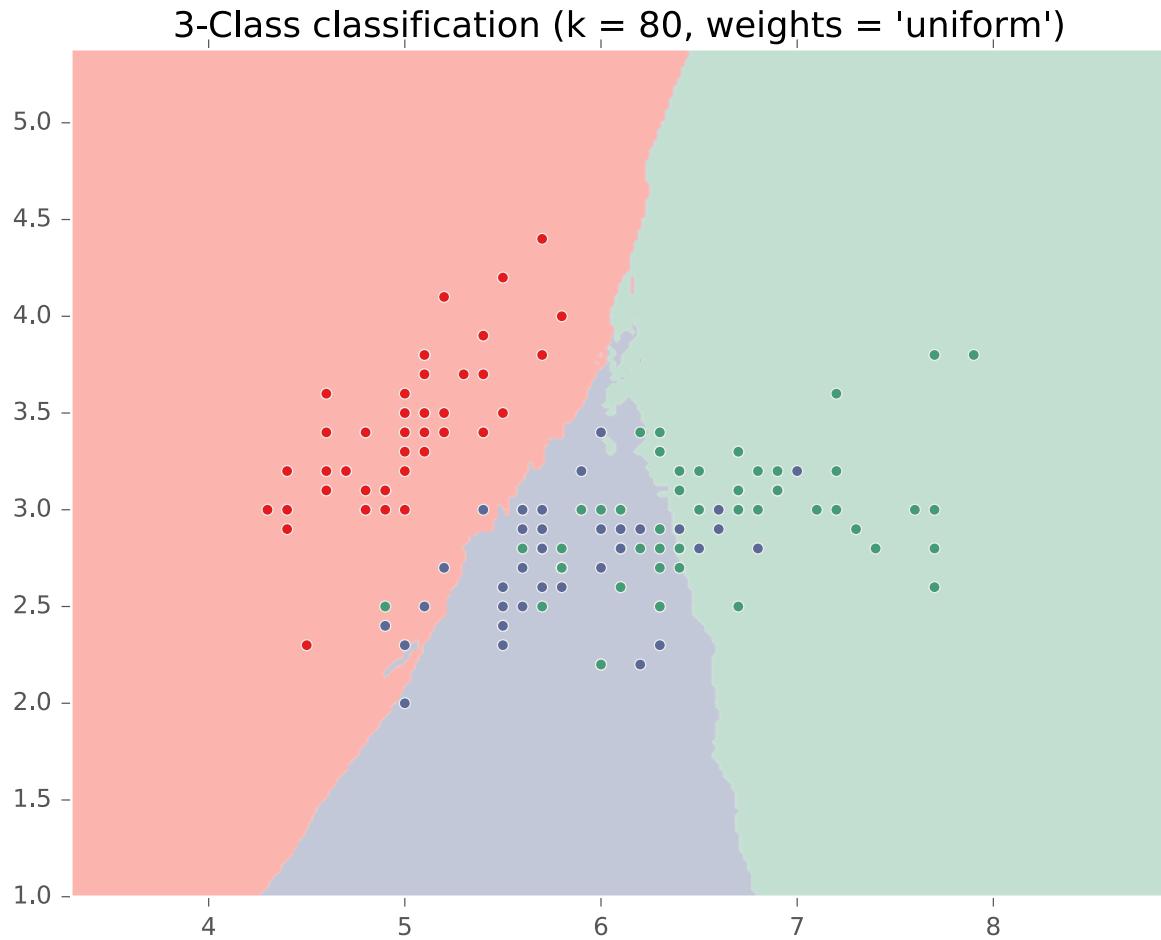
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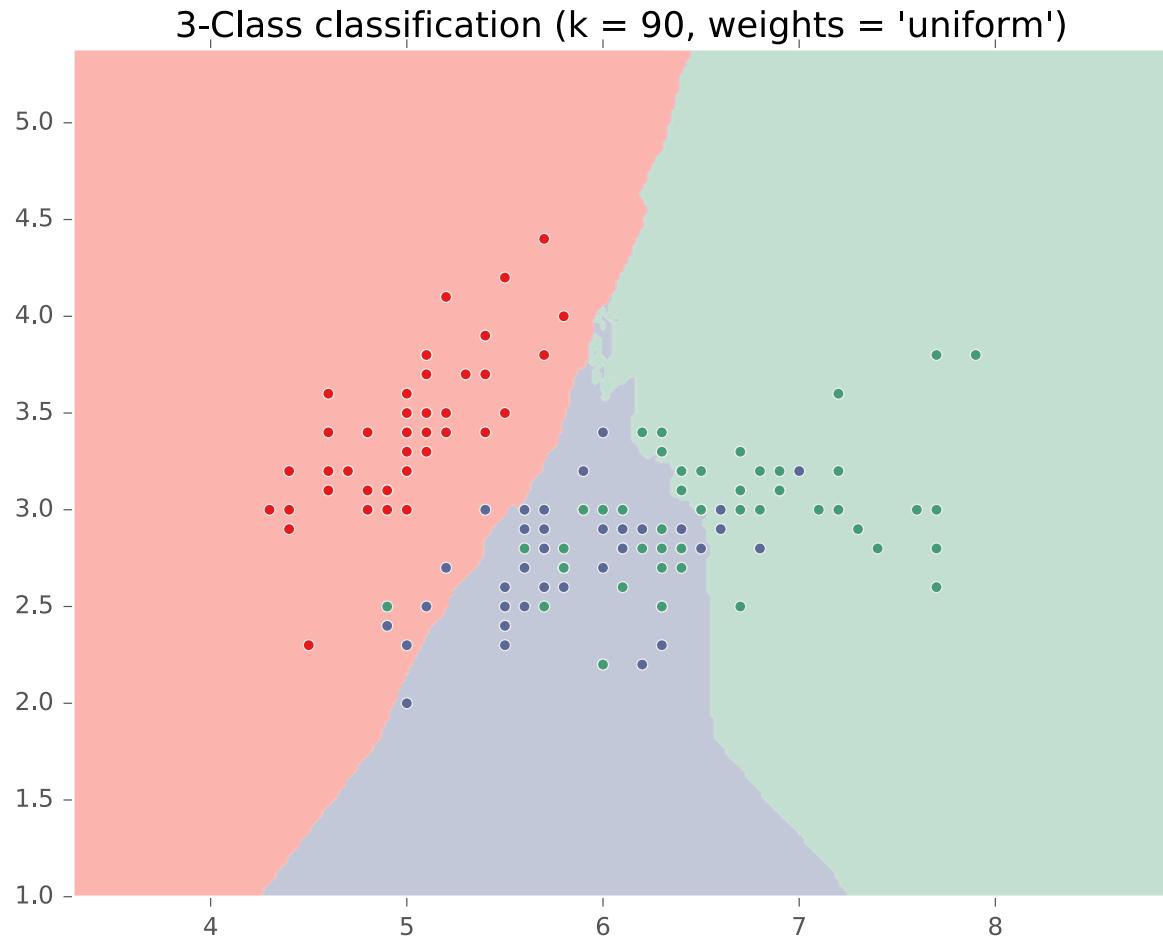
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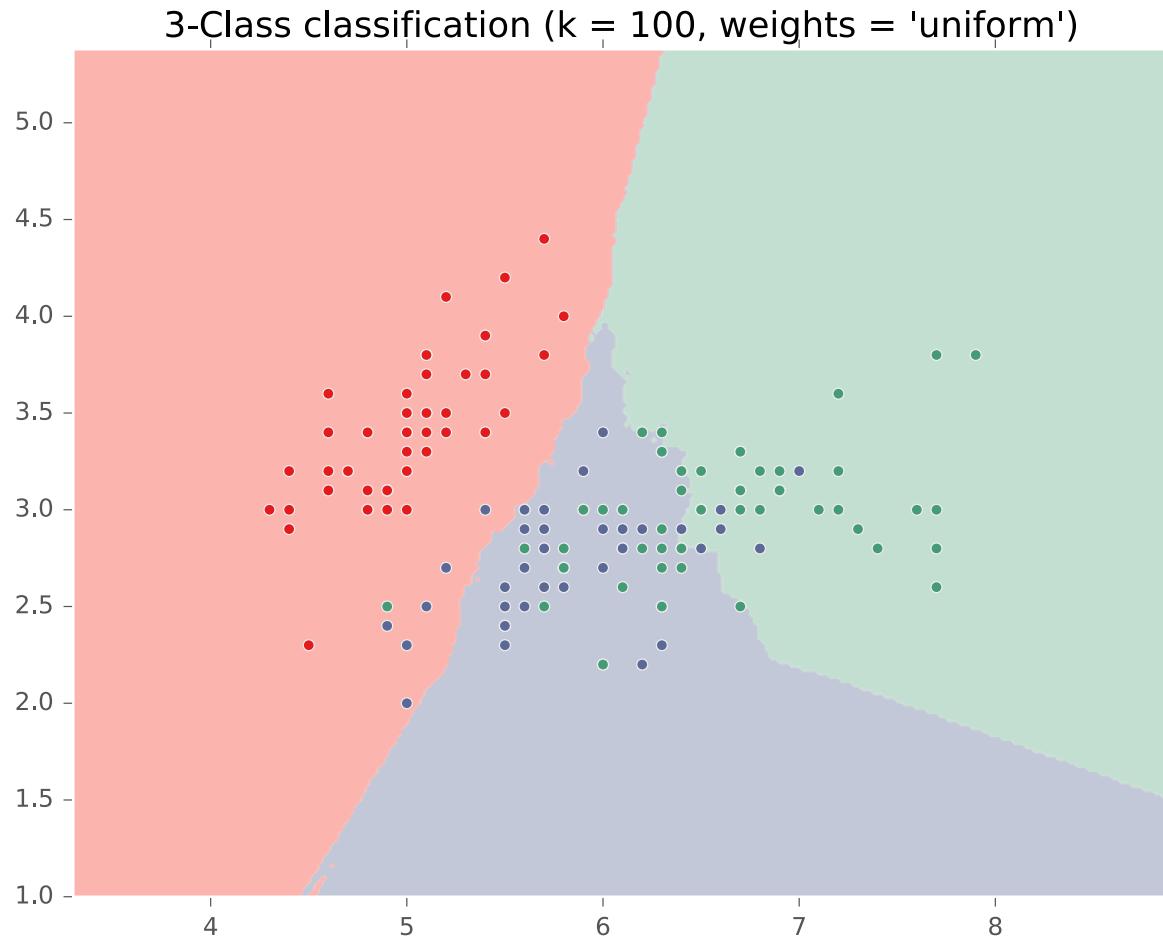
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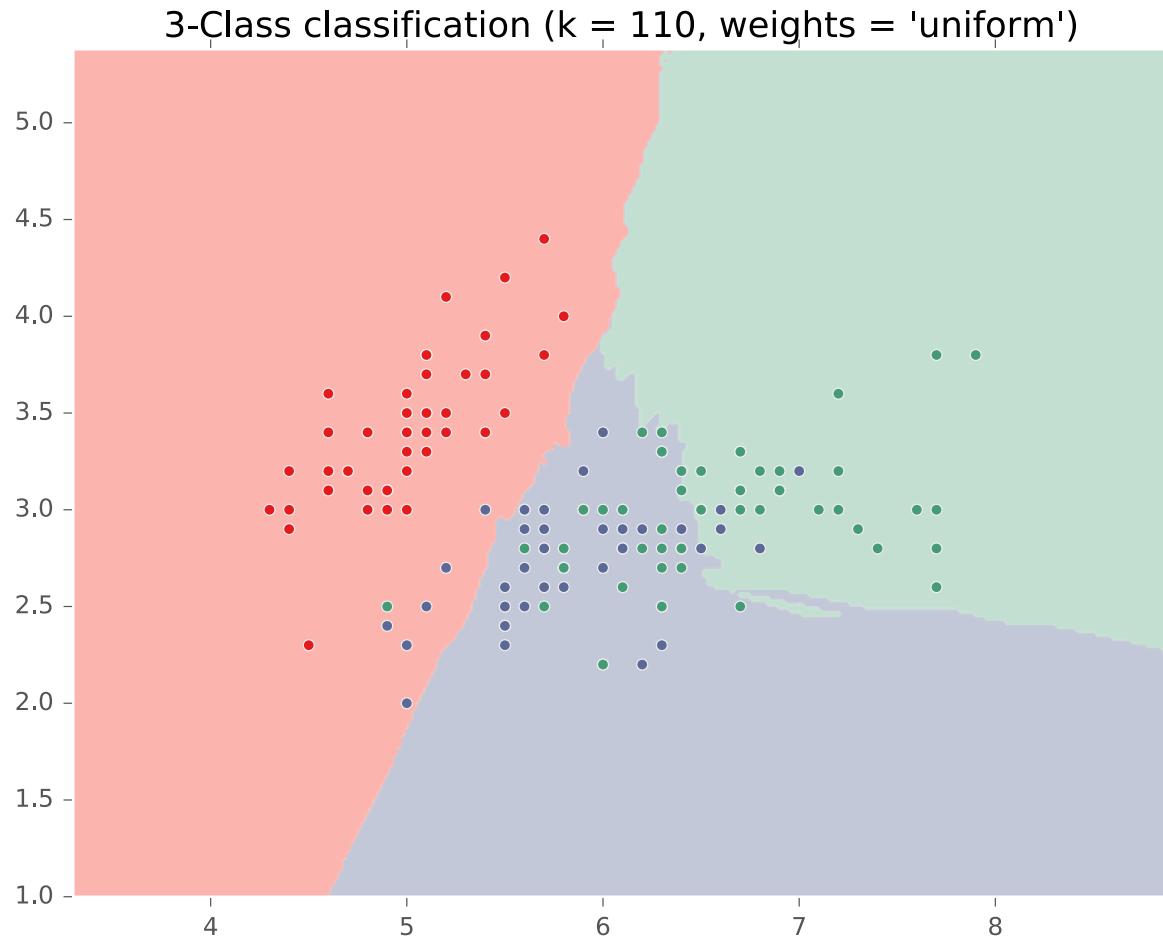
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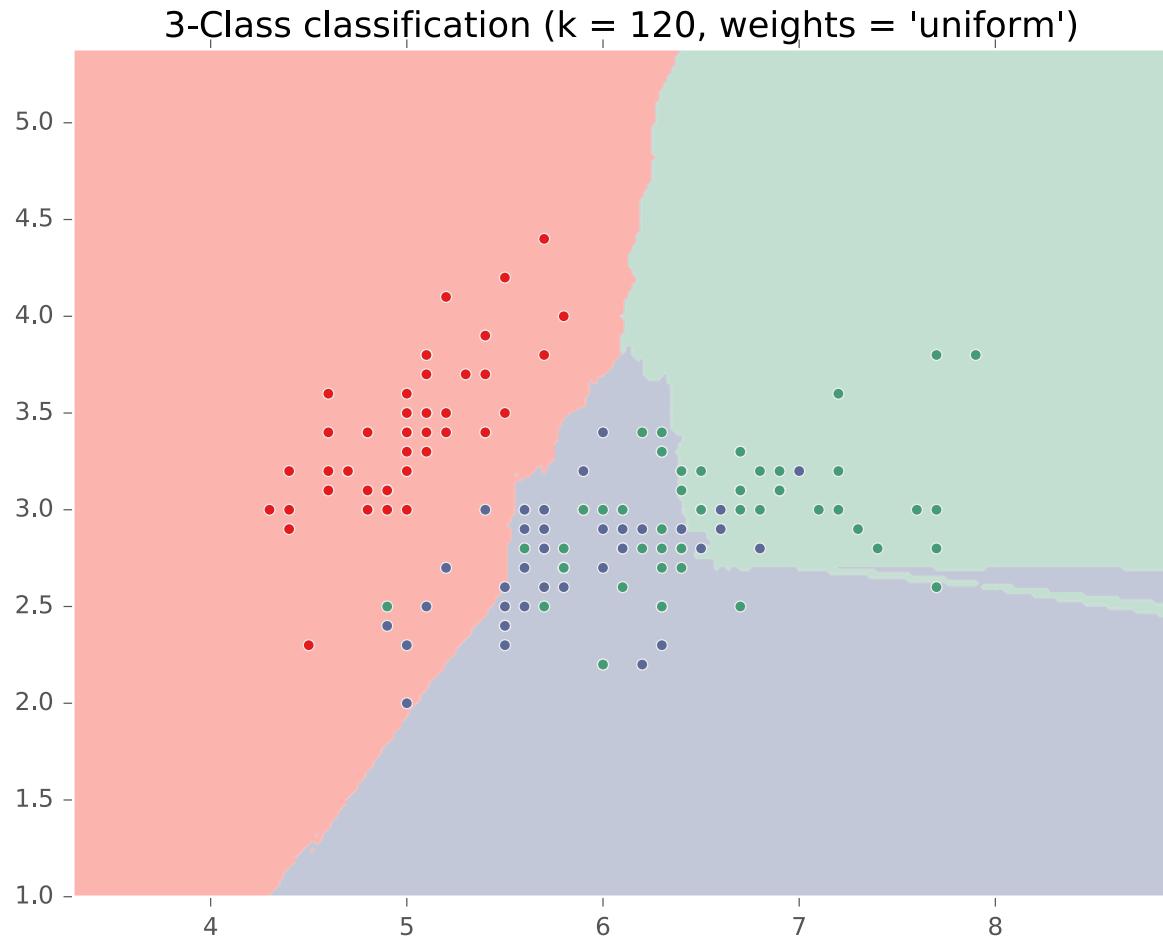
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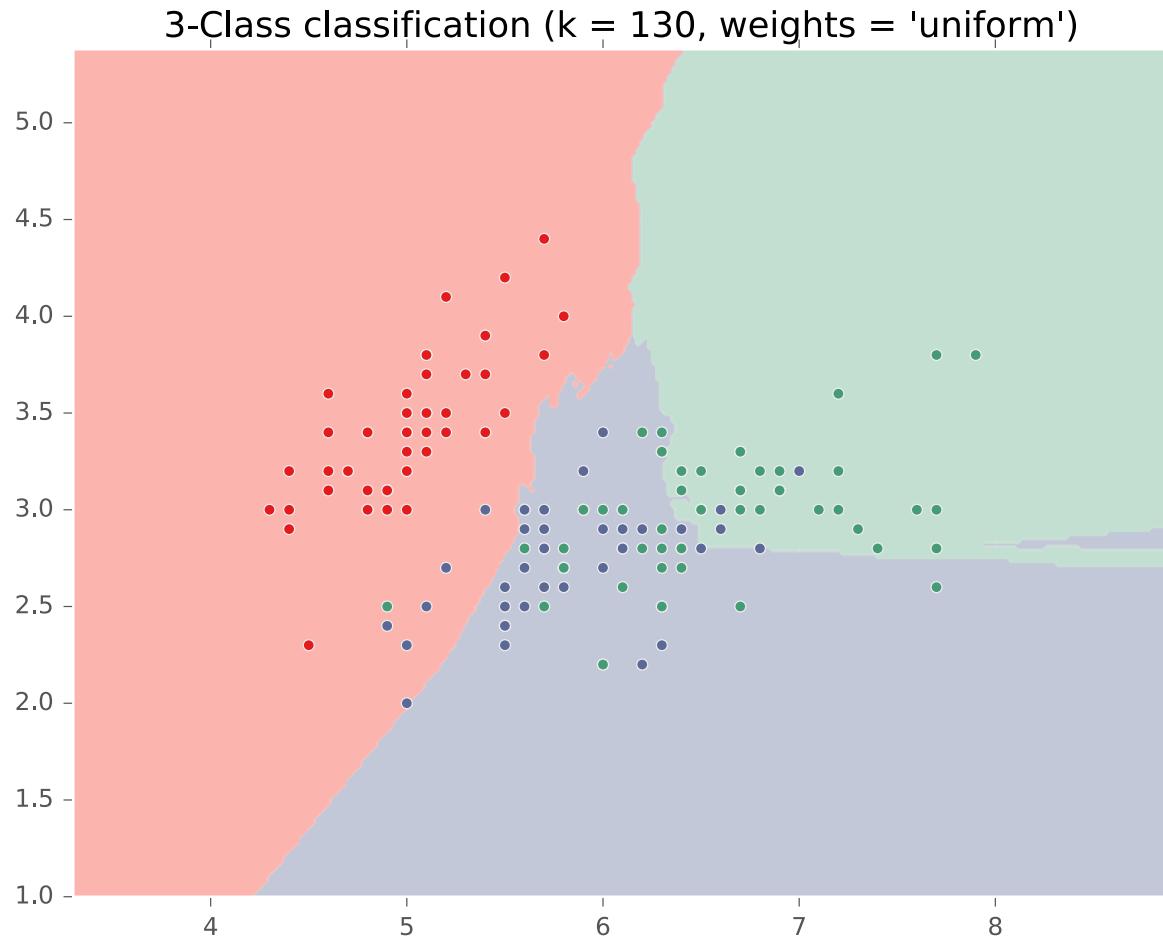
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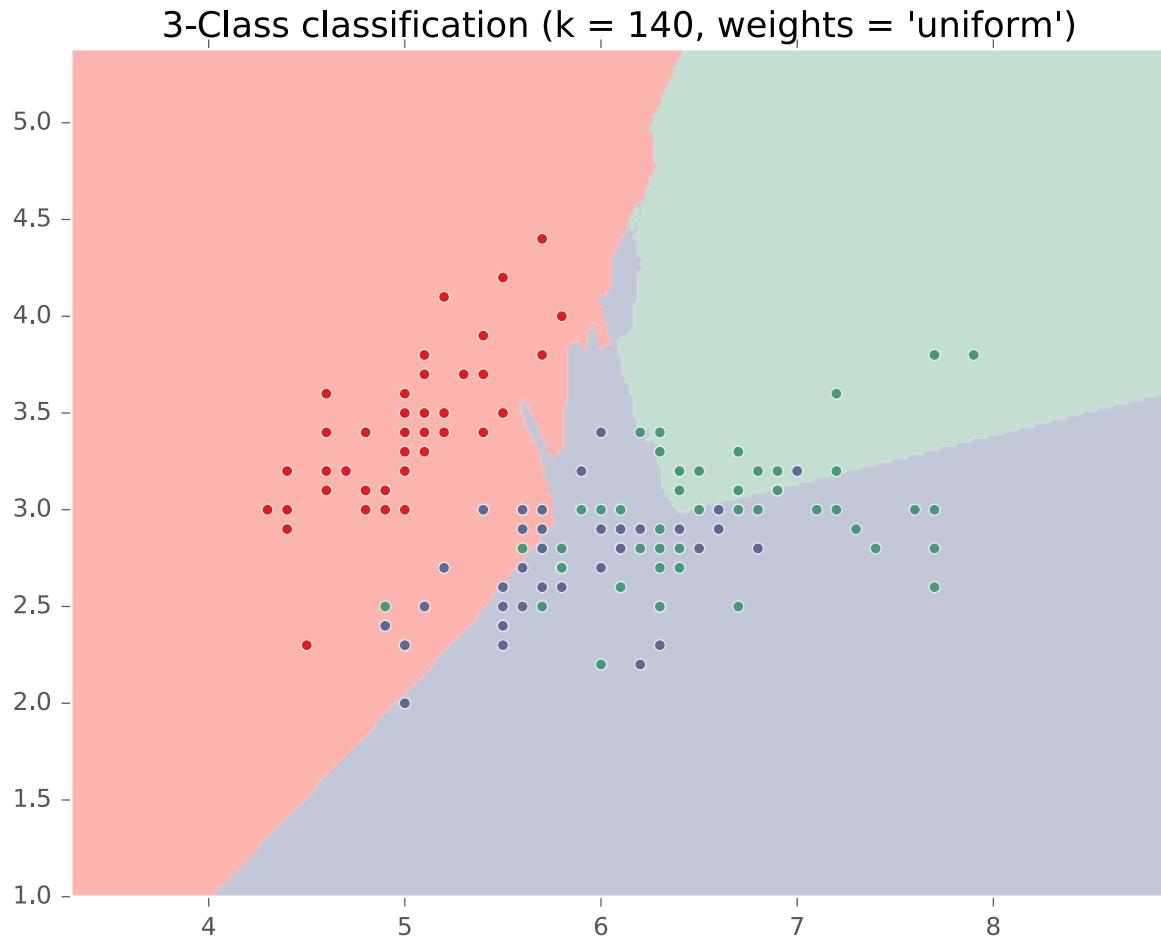
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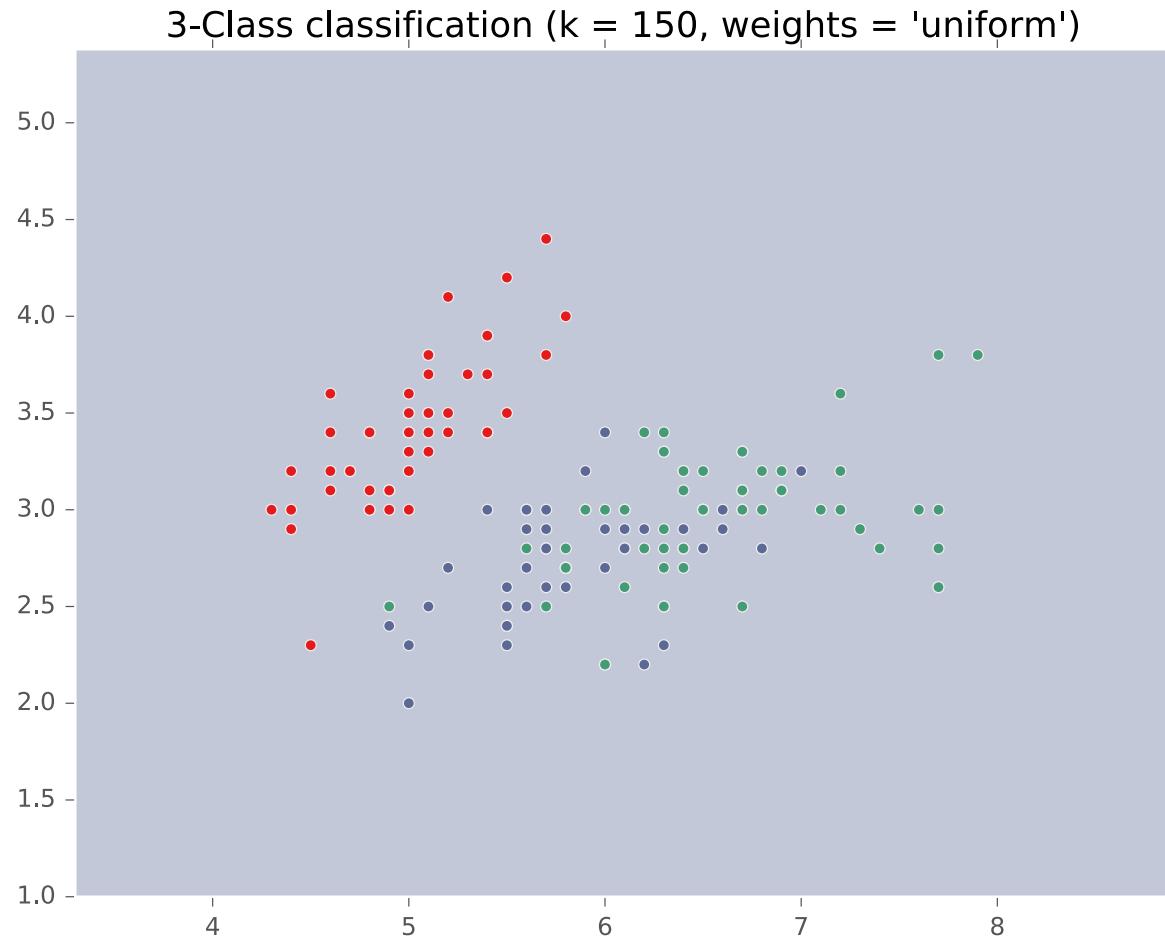


# KNN on Fisher Iris Data



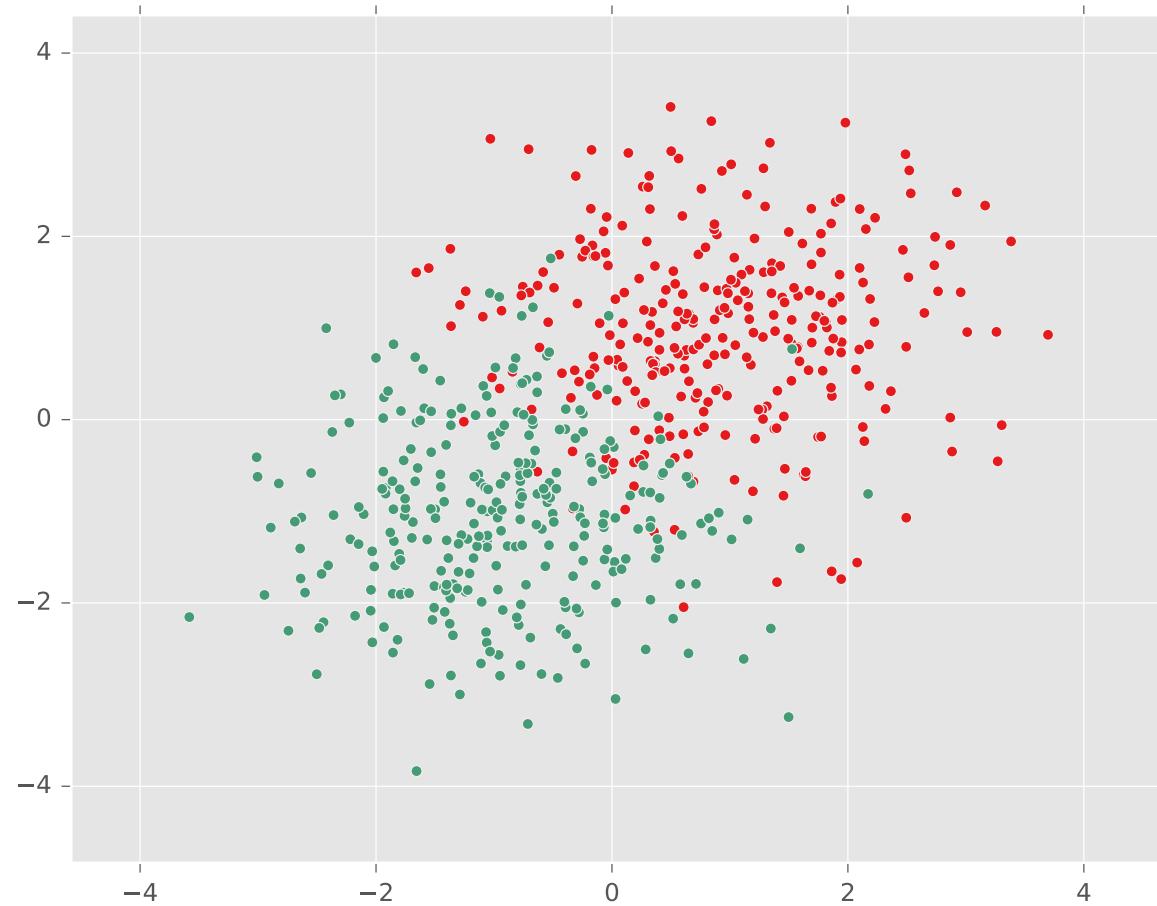
# KNN on Fisher Iris Data

## Special Case: Majority Vote

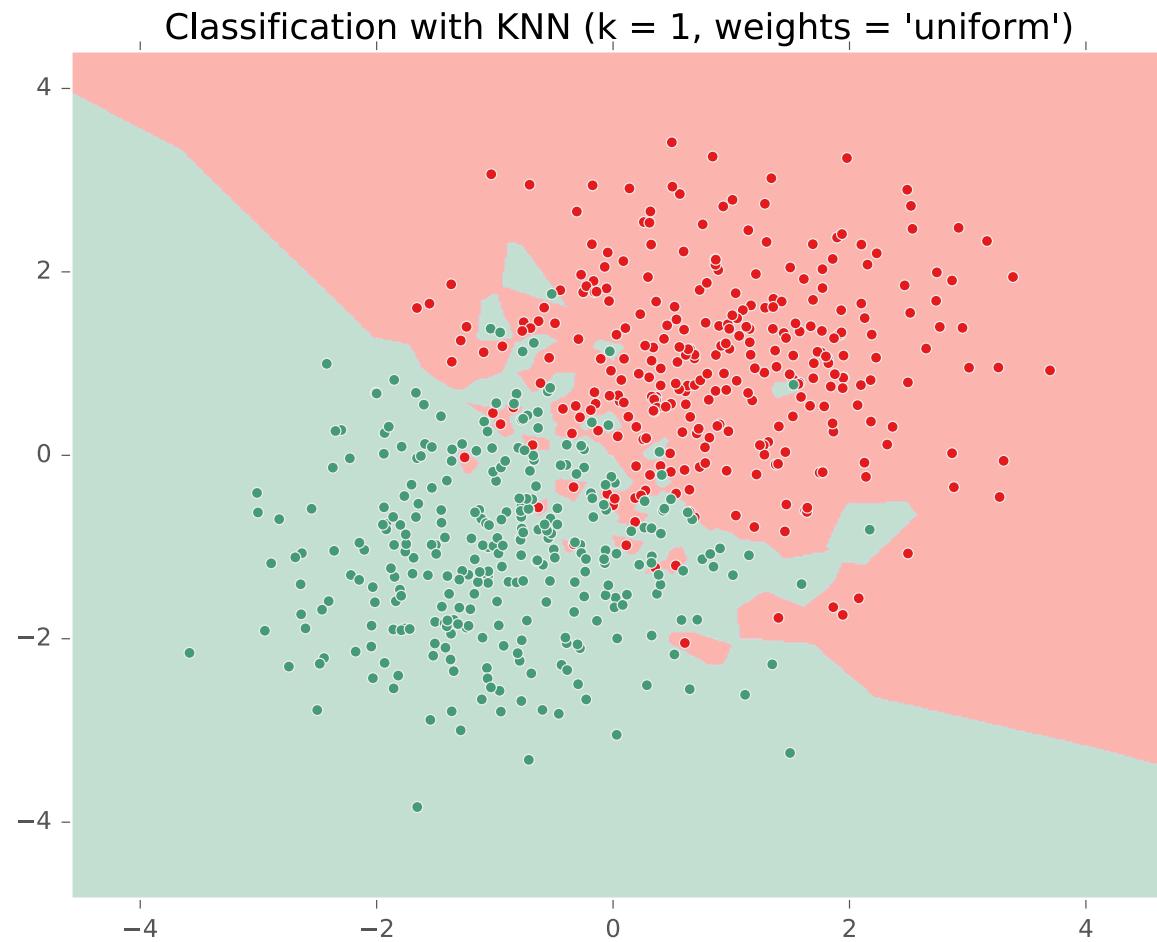


# KNN ON GAUSSIAN DATA

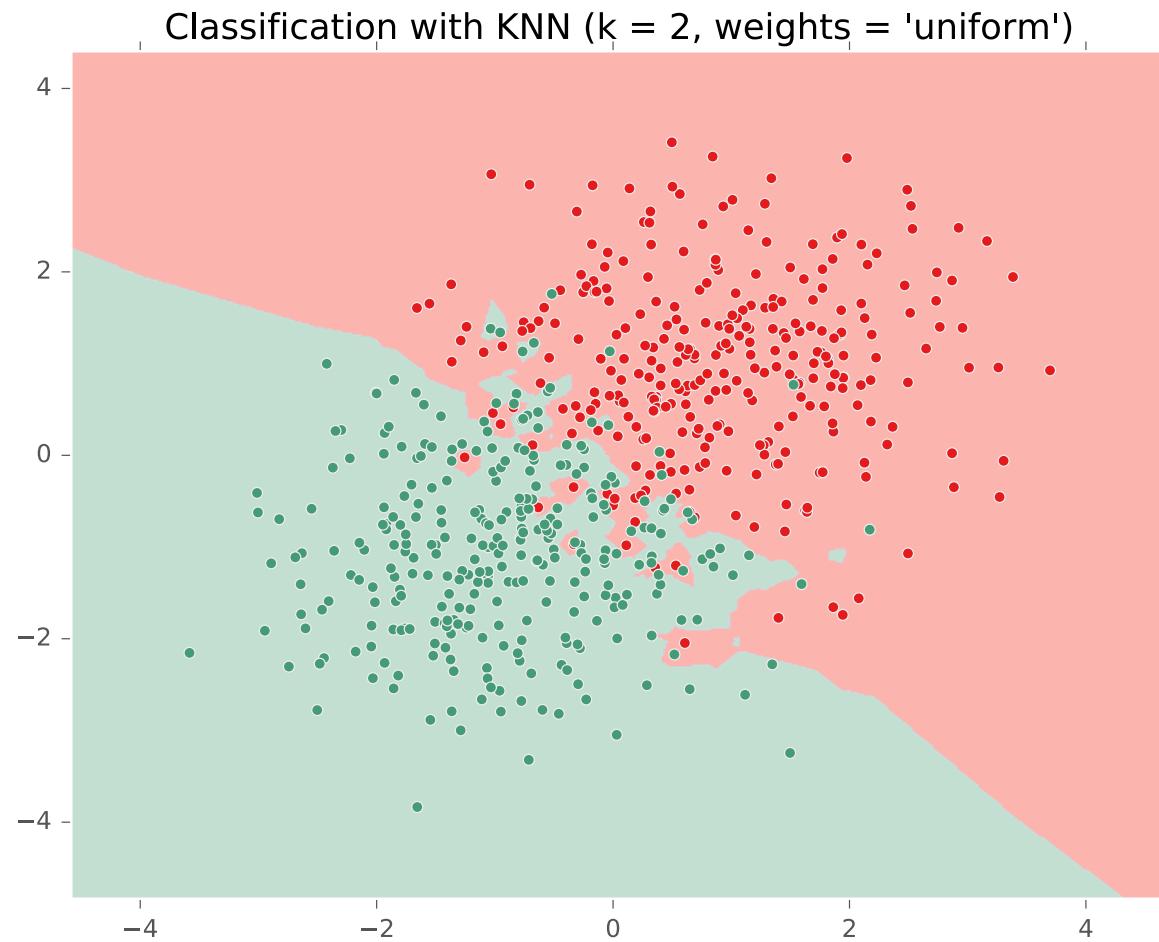
# KNN on Gaussian Data



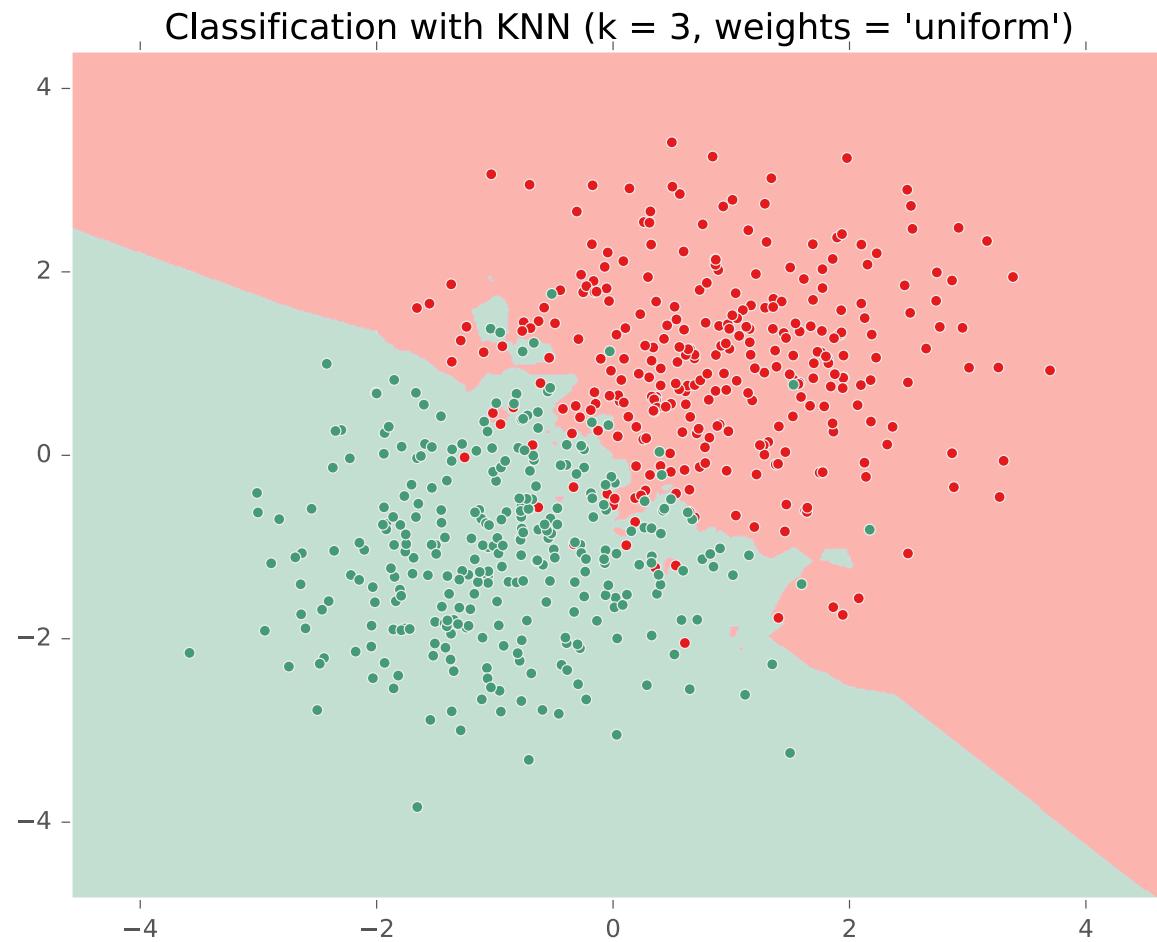
# KNN on Gaussian Data



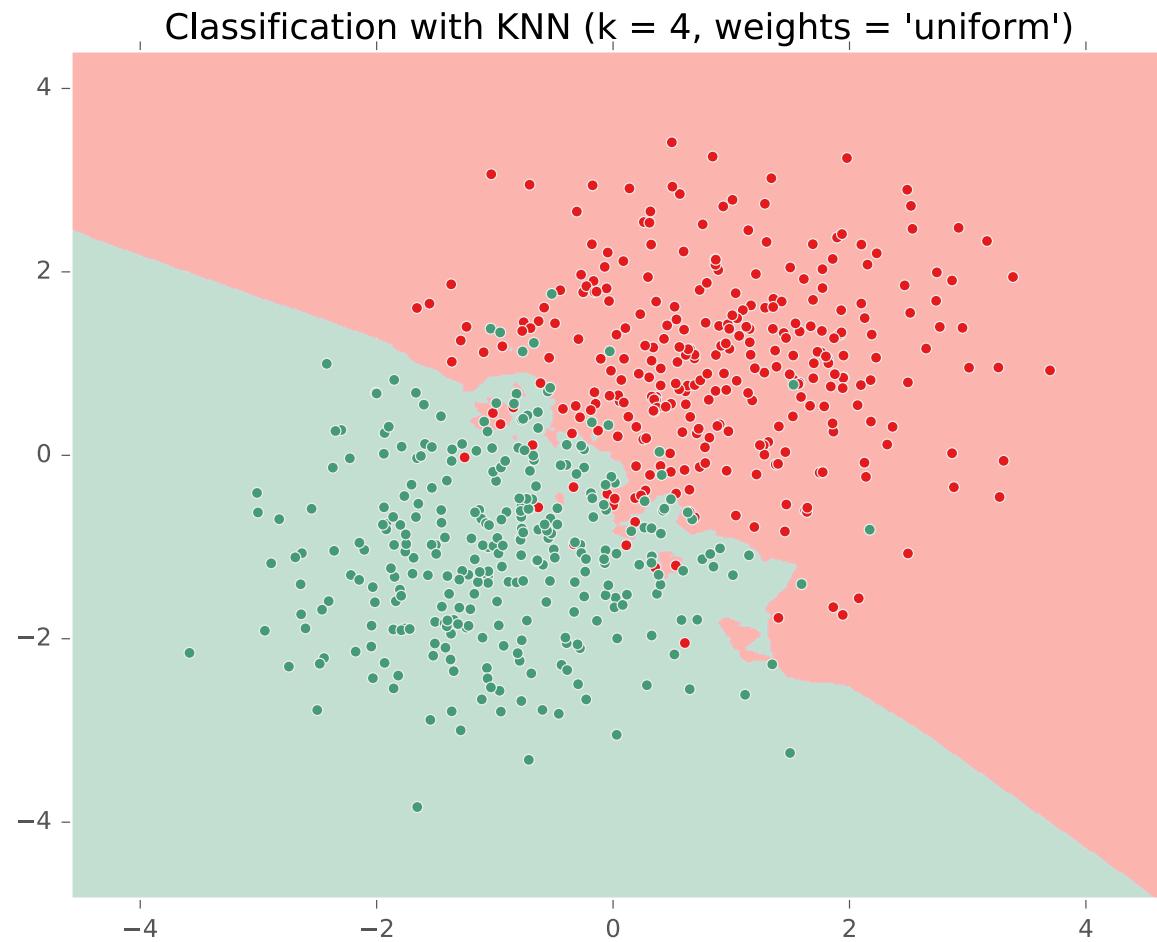
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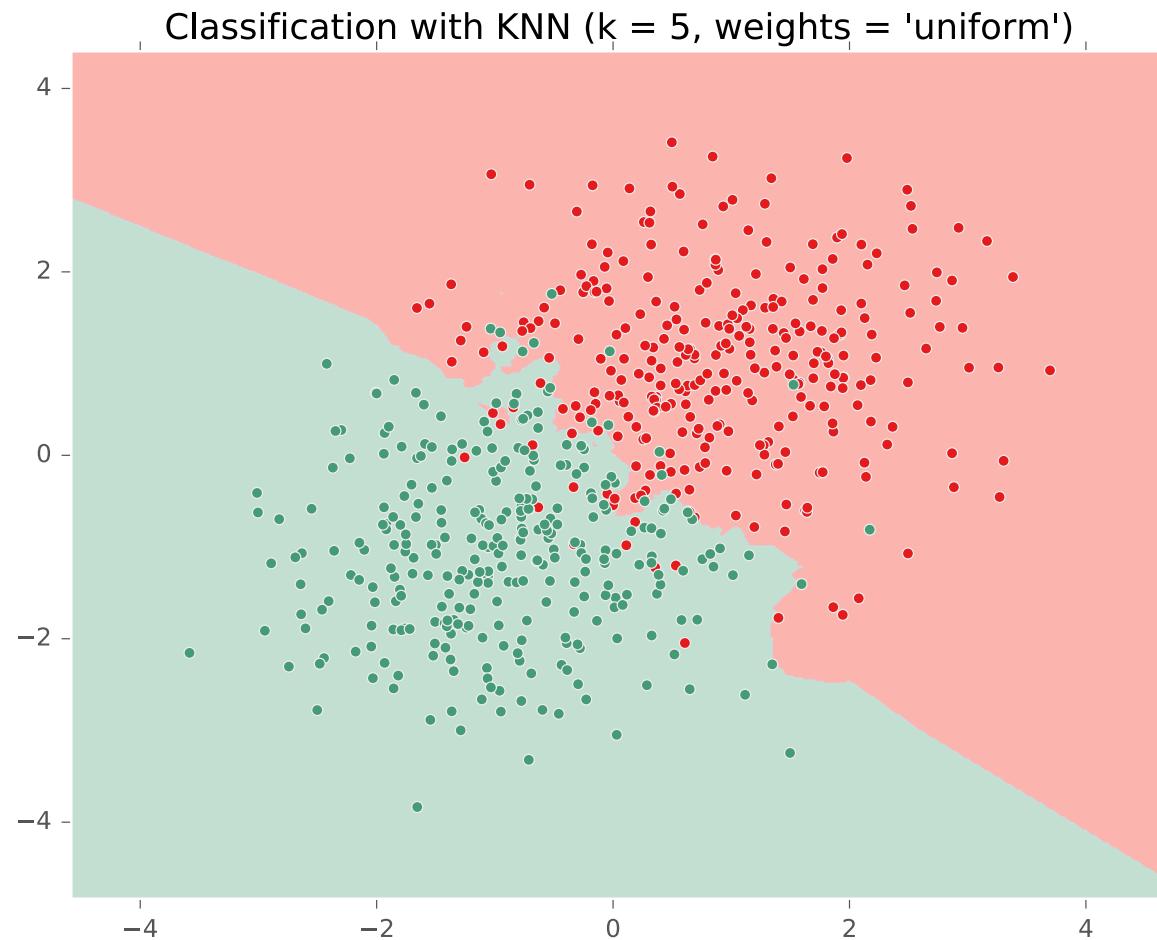
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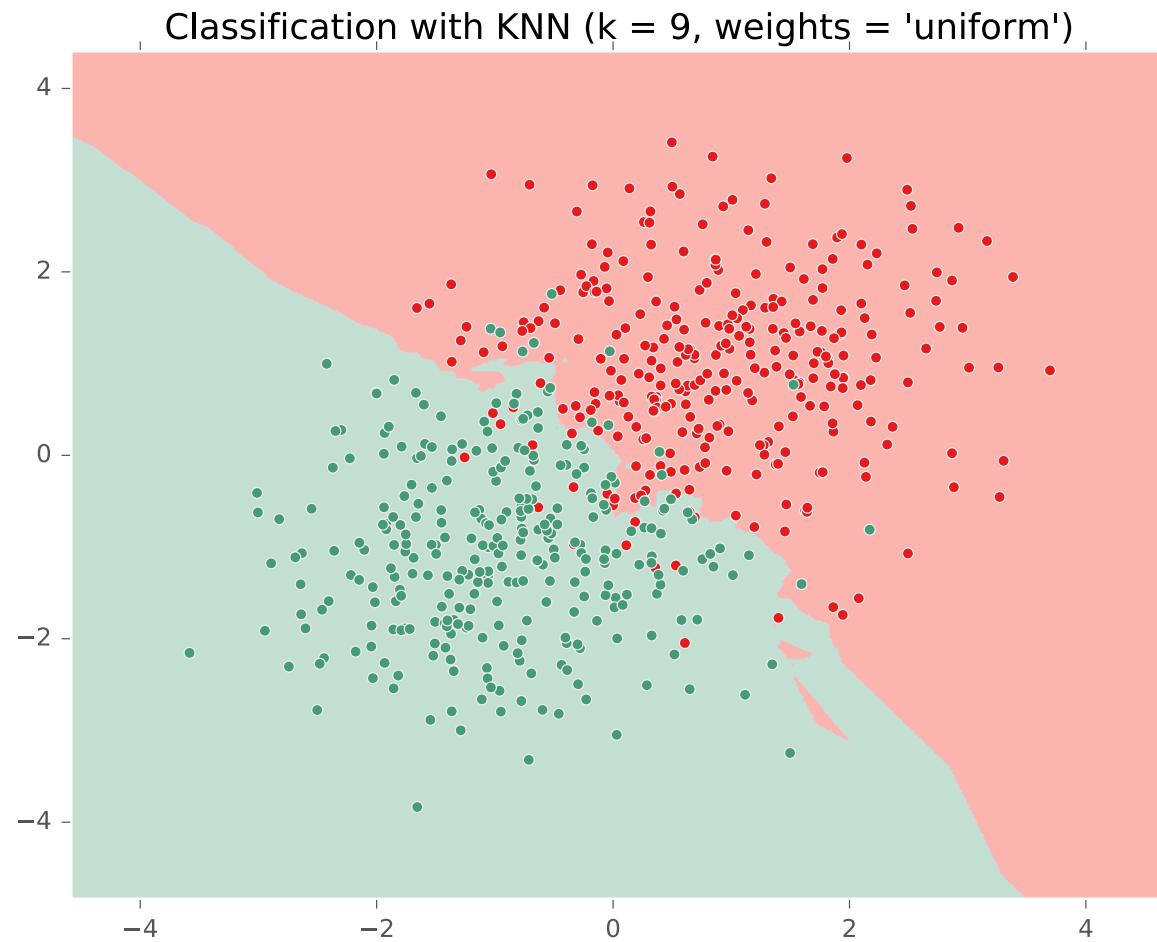
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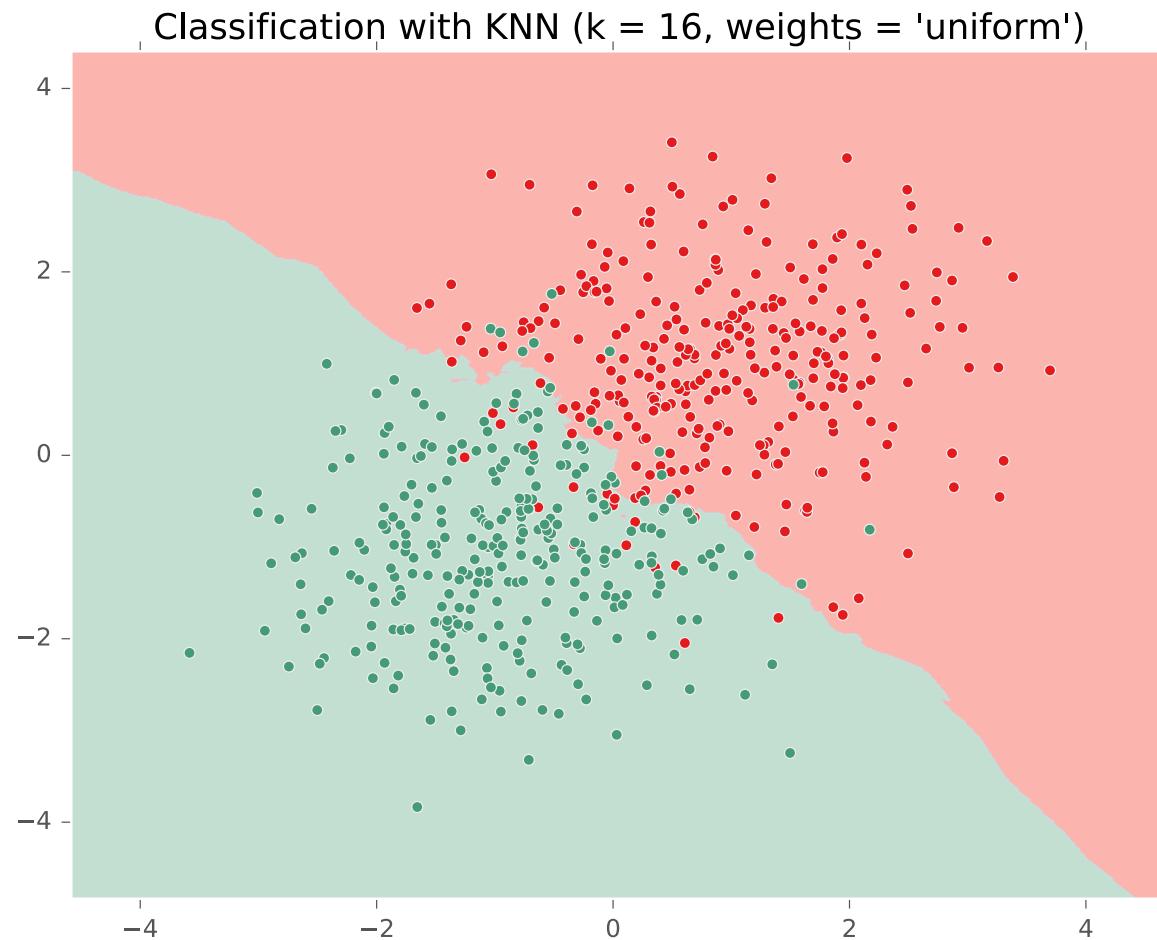
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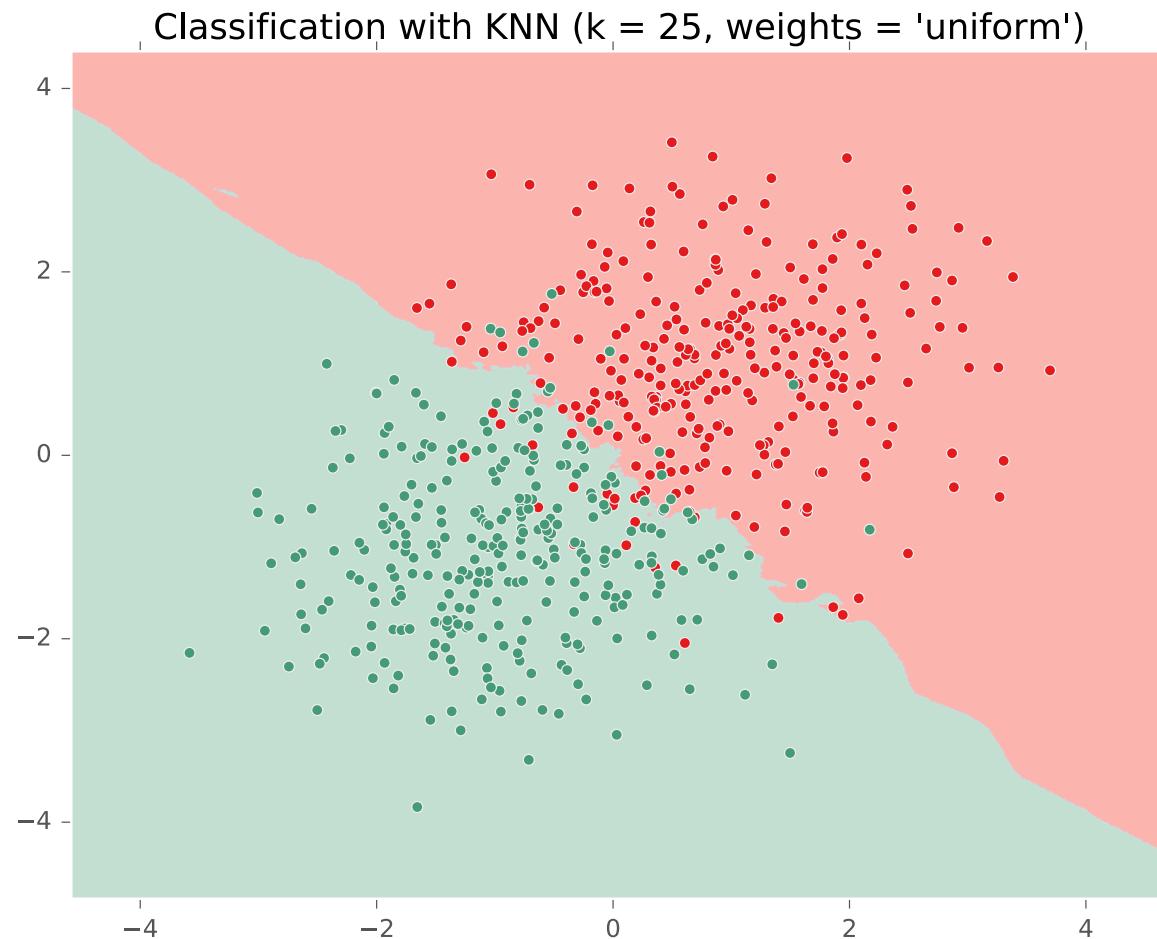
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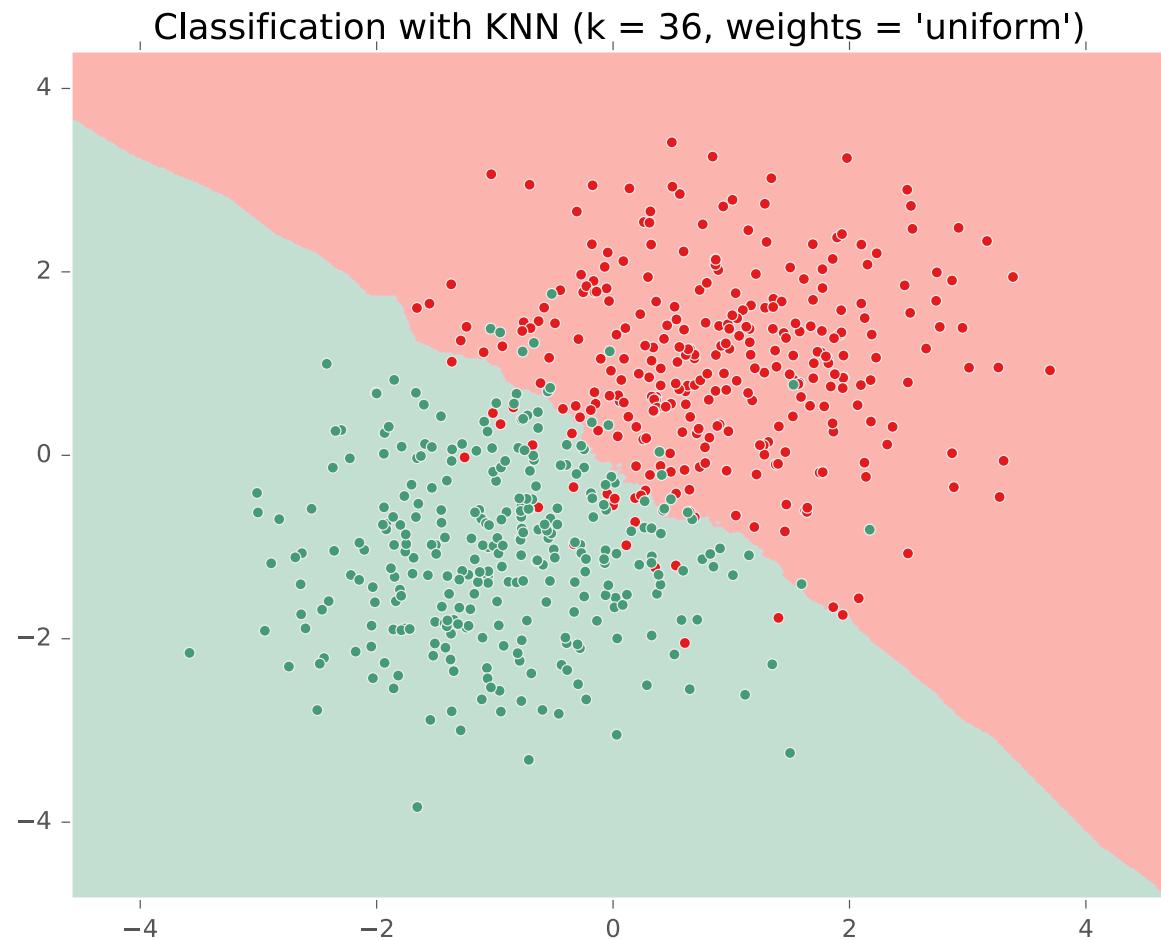
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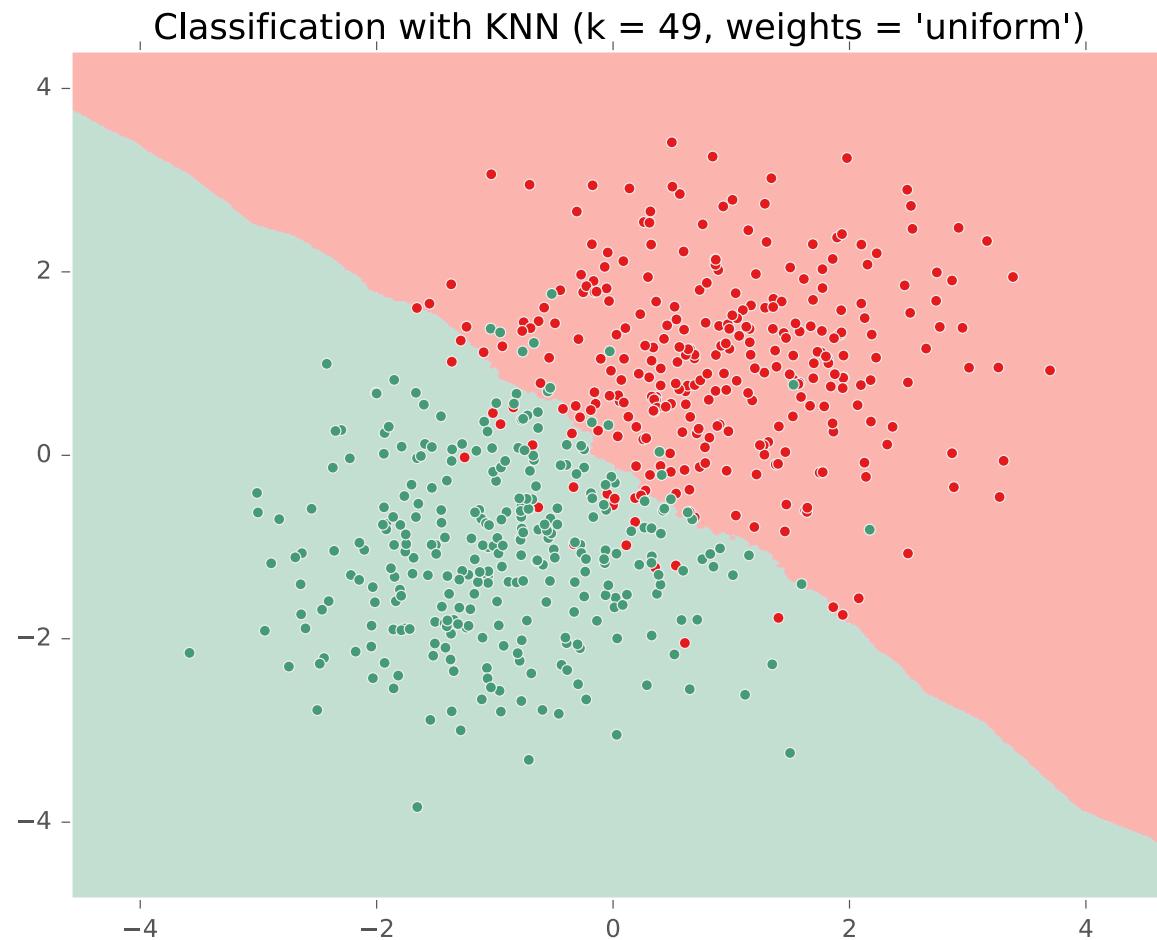
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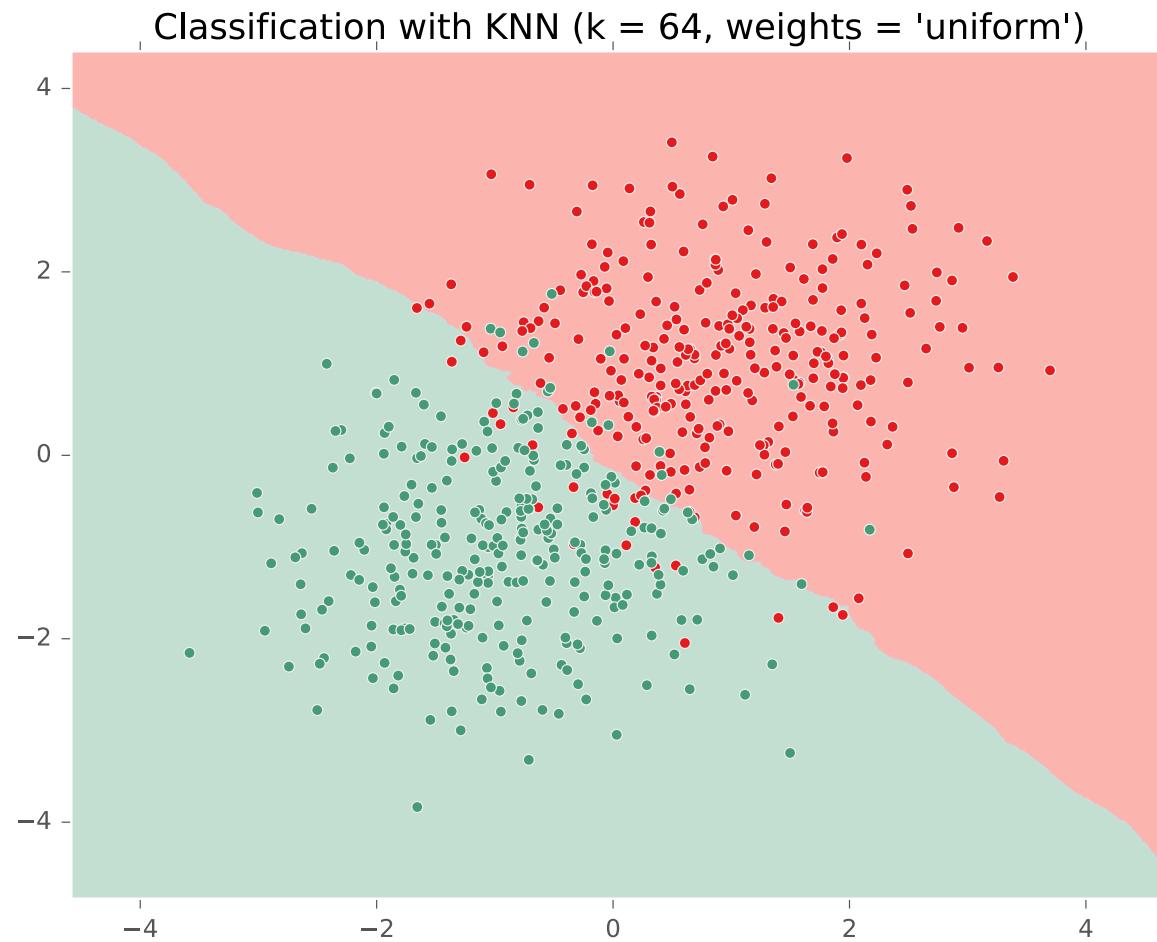
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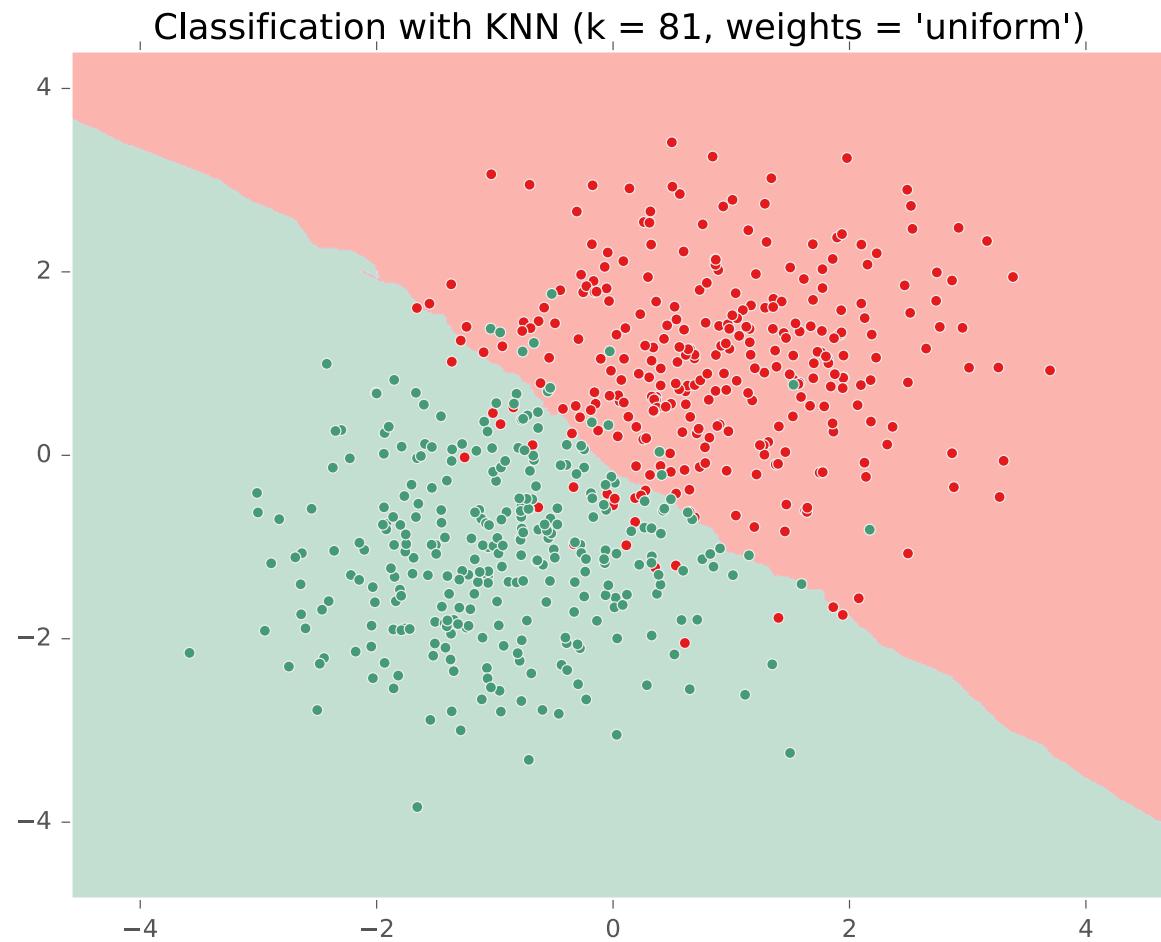
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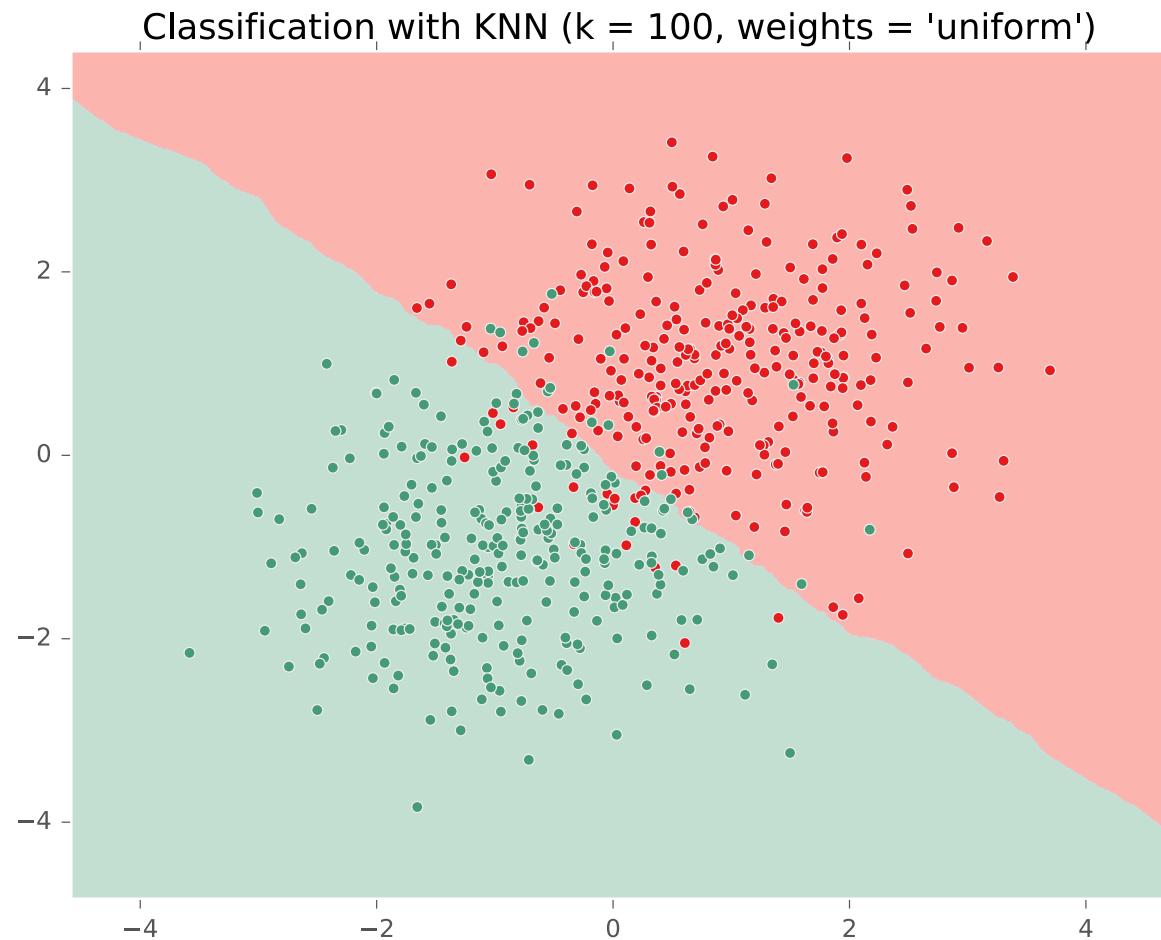
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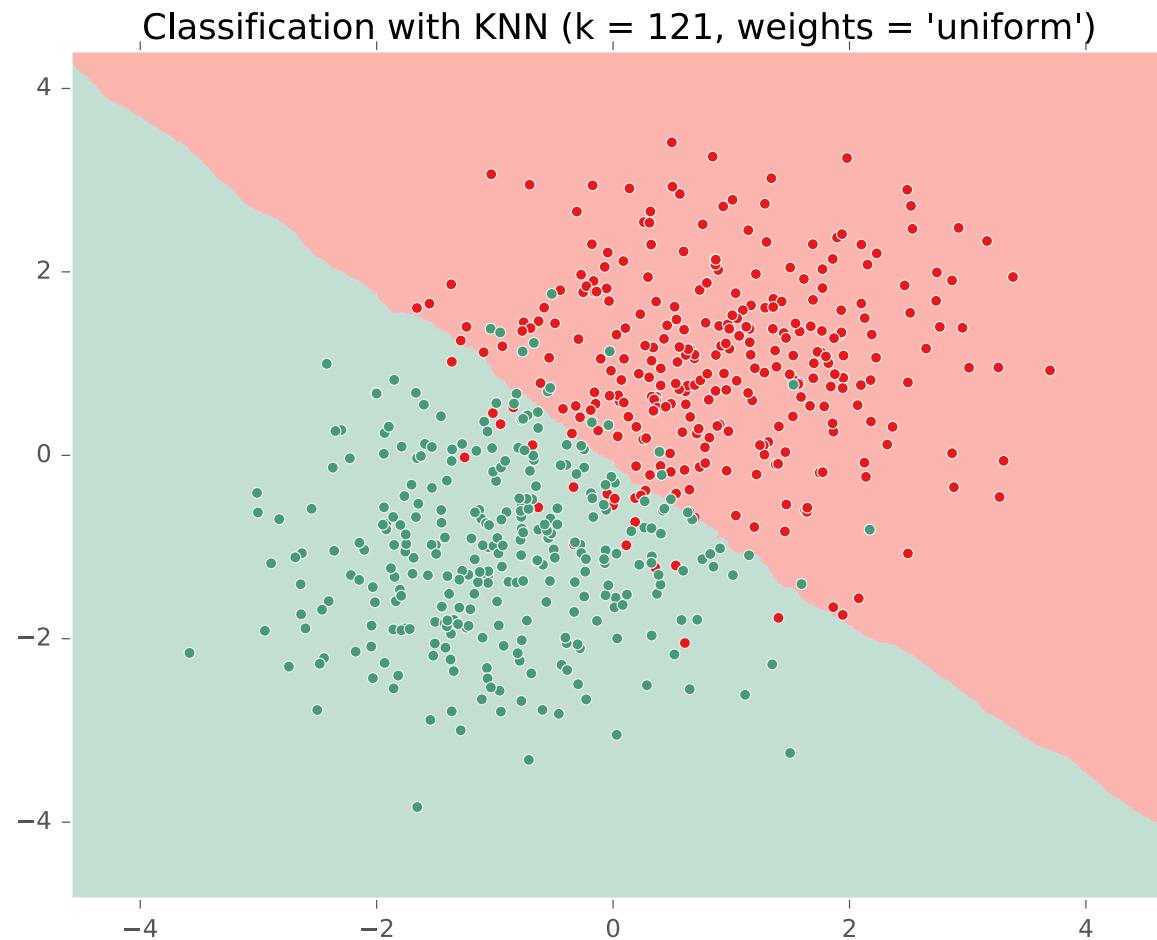
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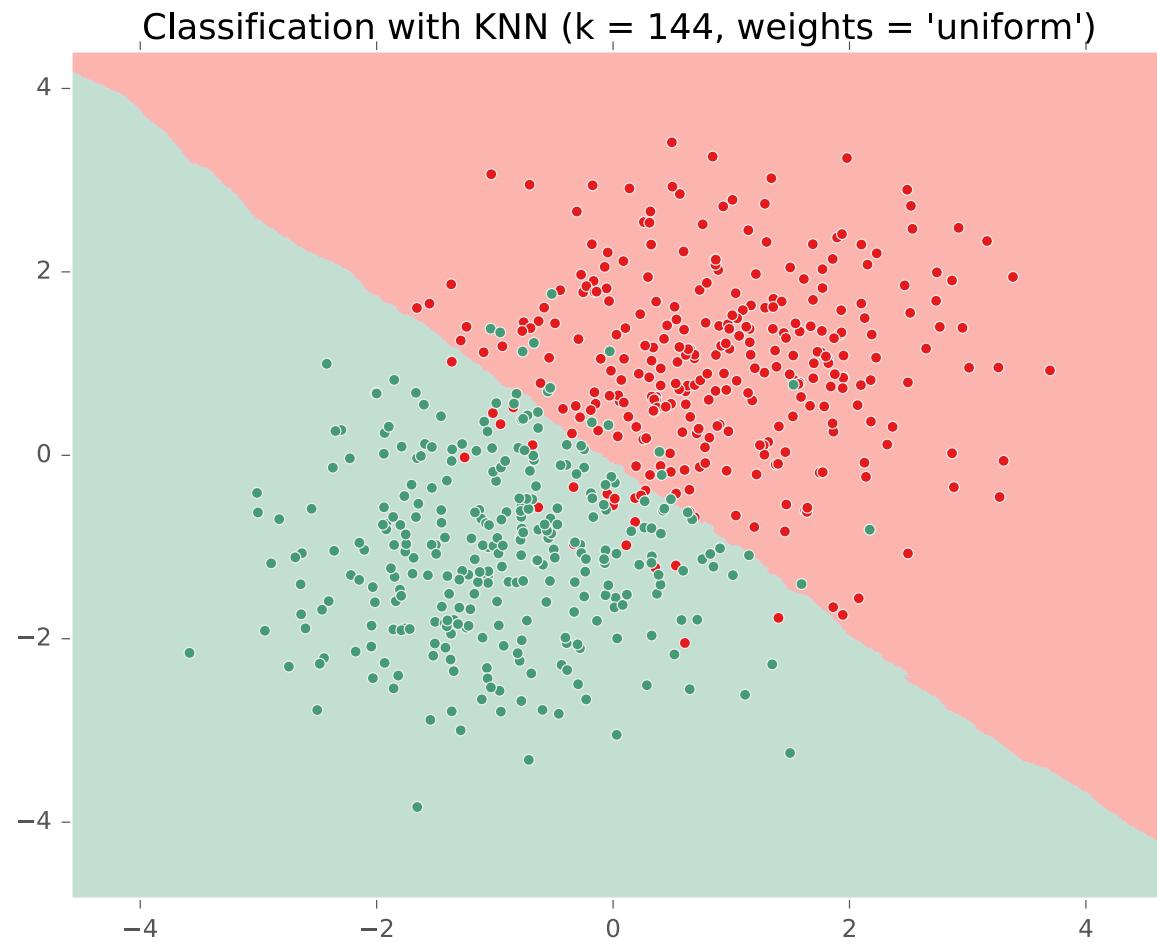
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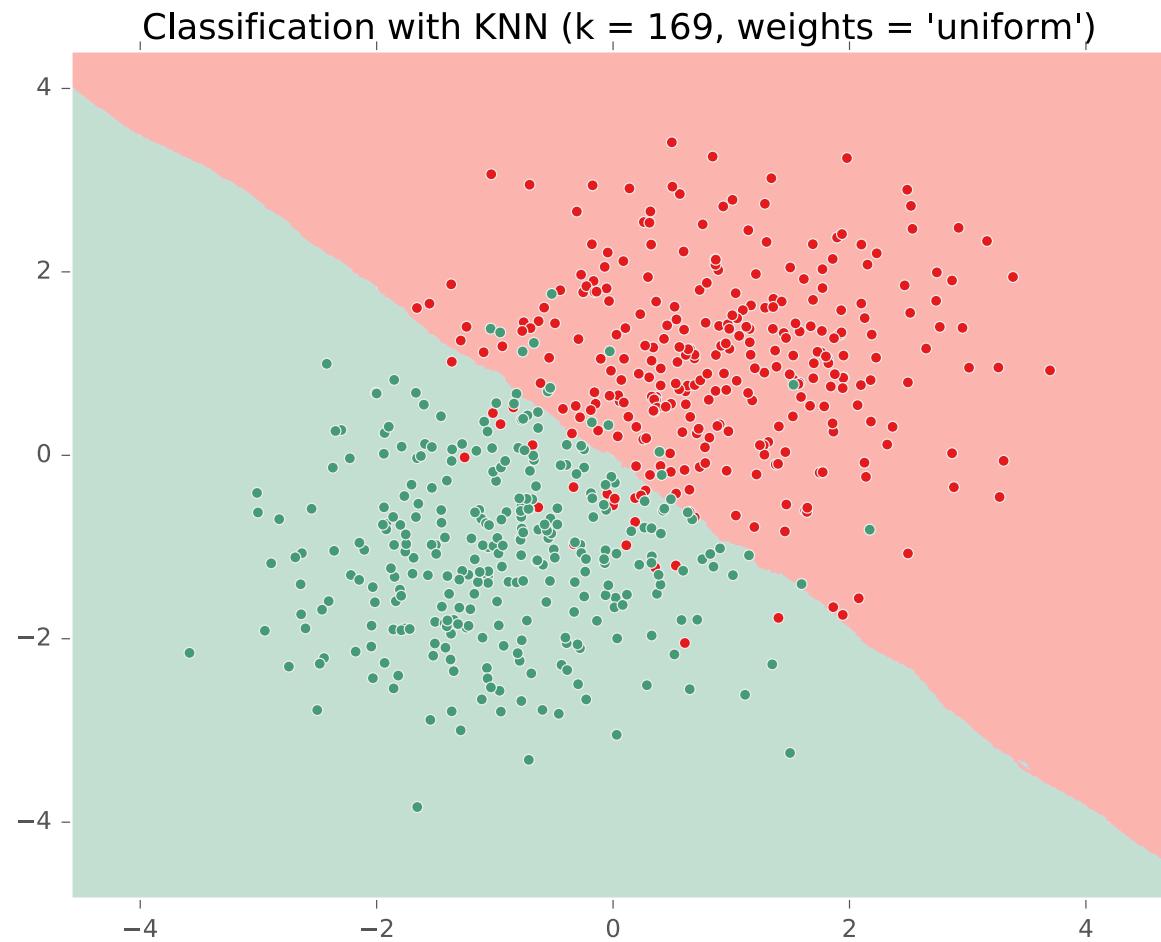
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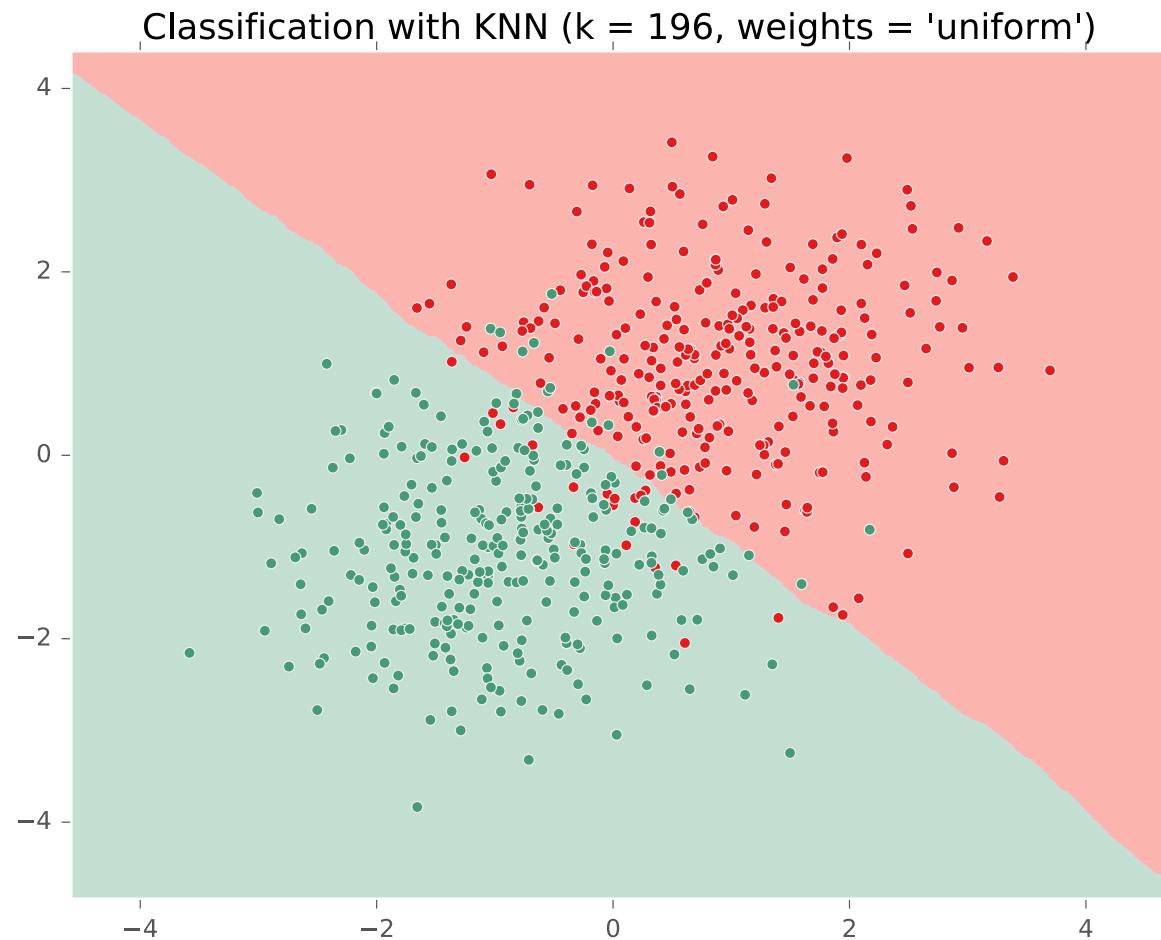
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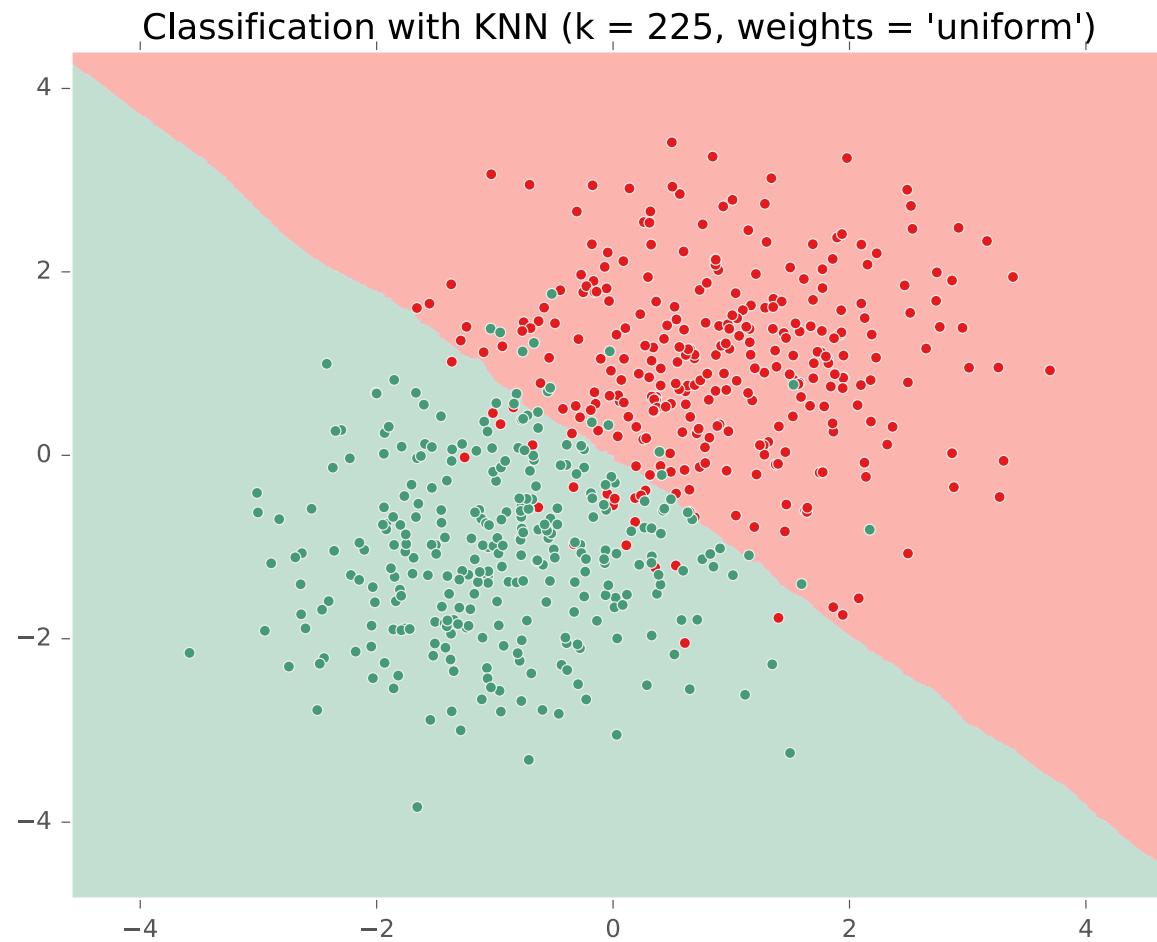
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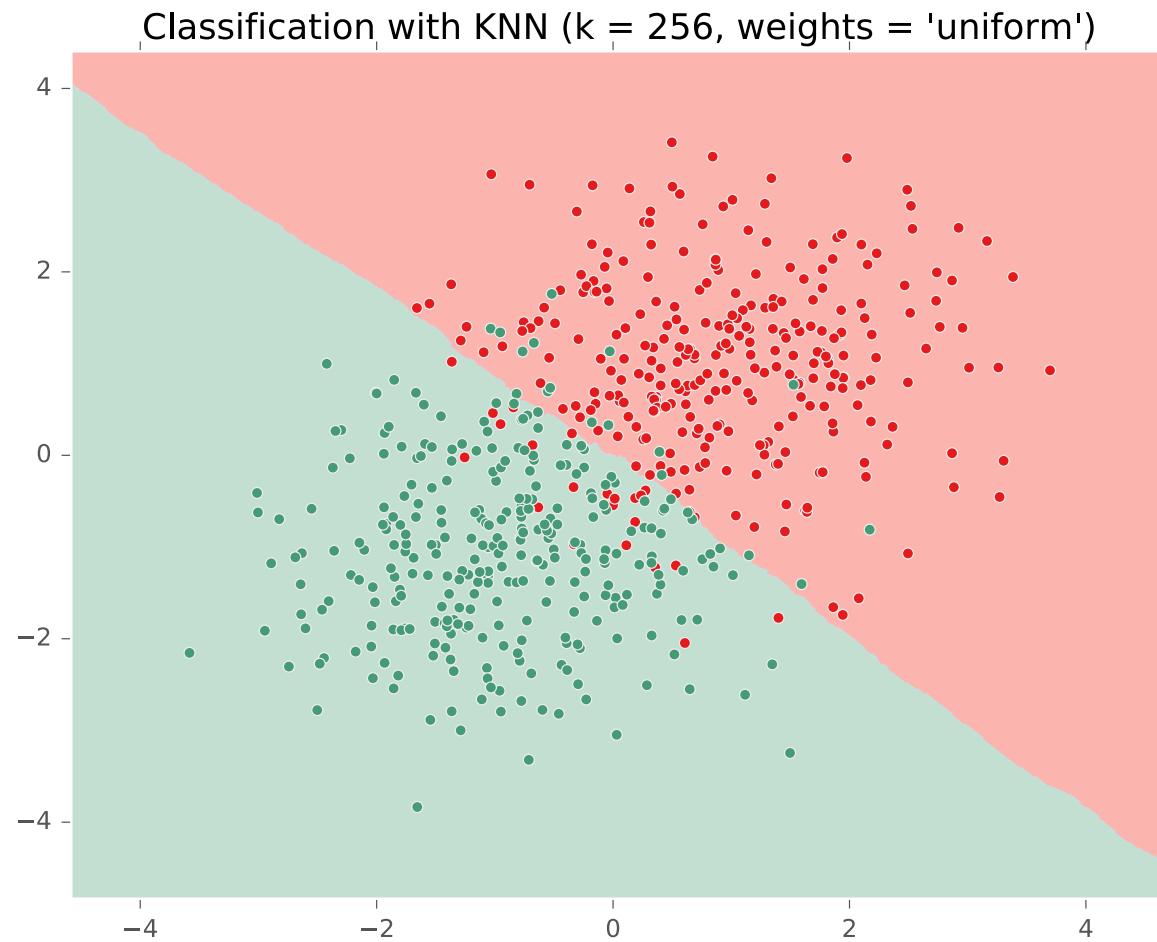
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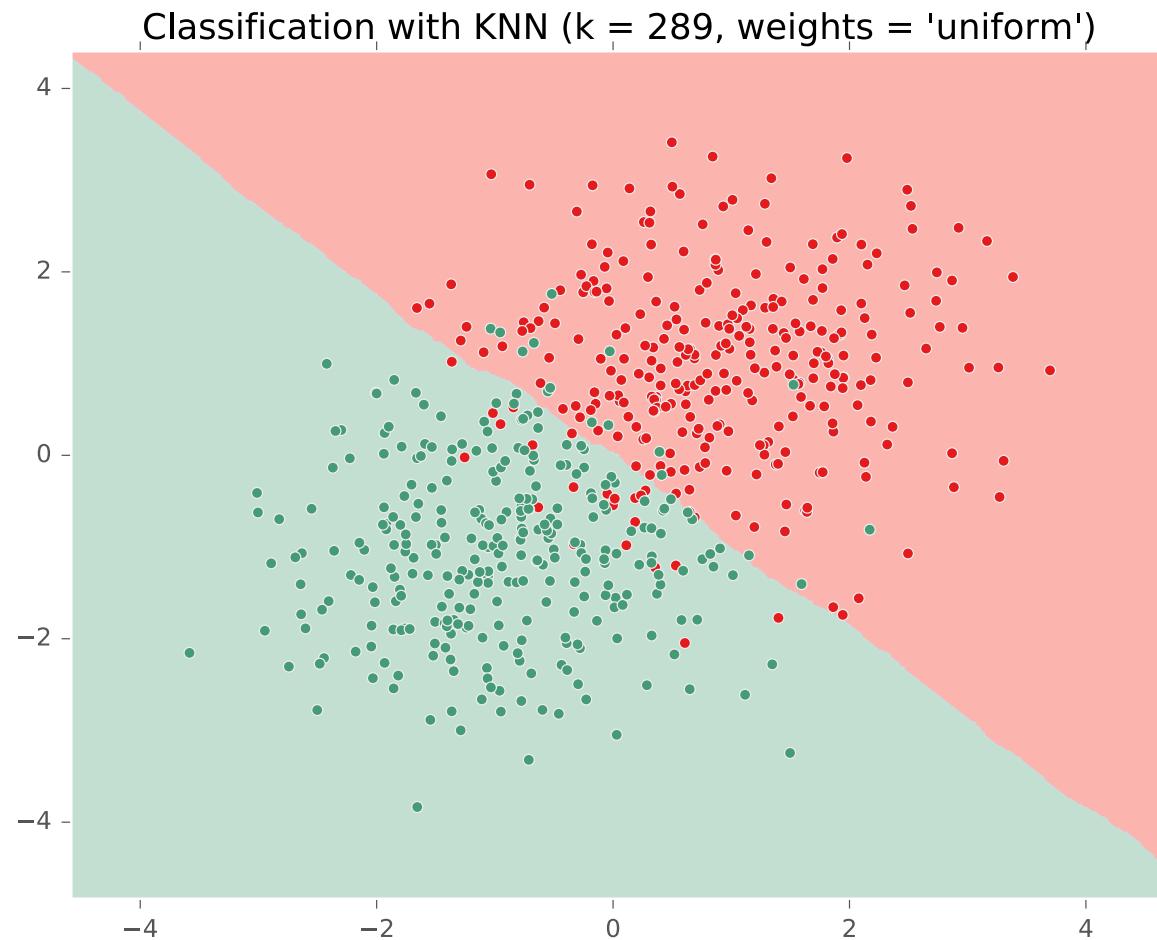
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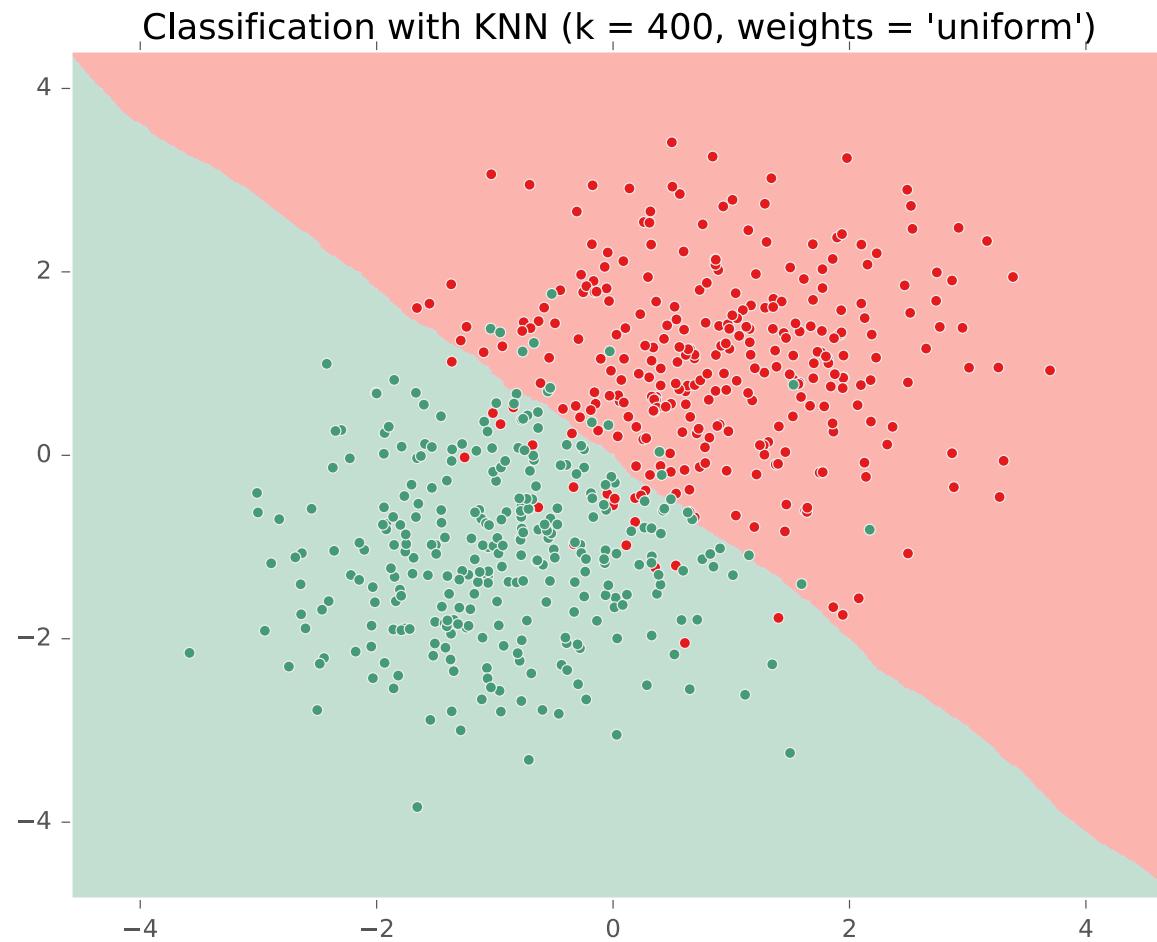
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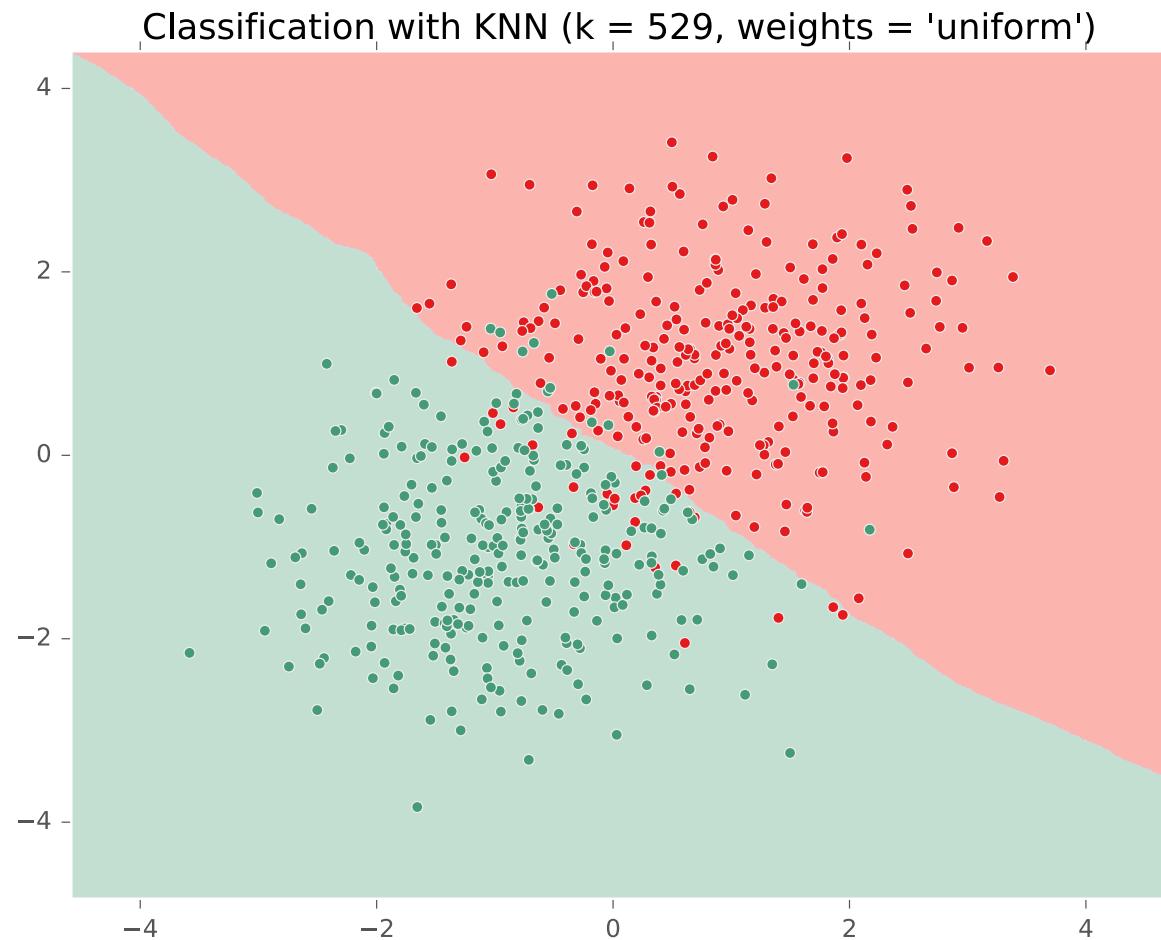
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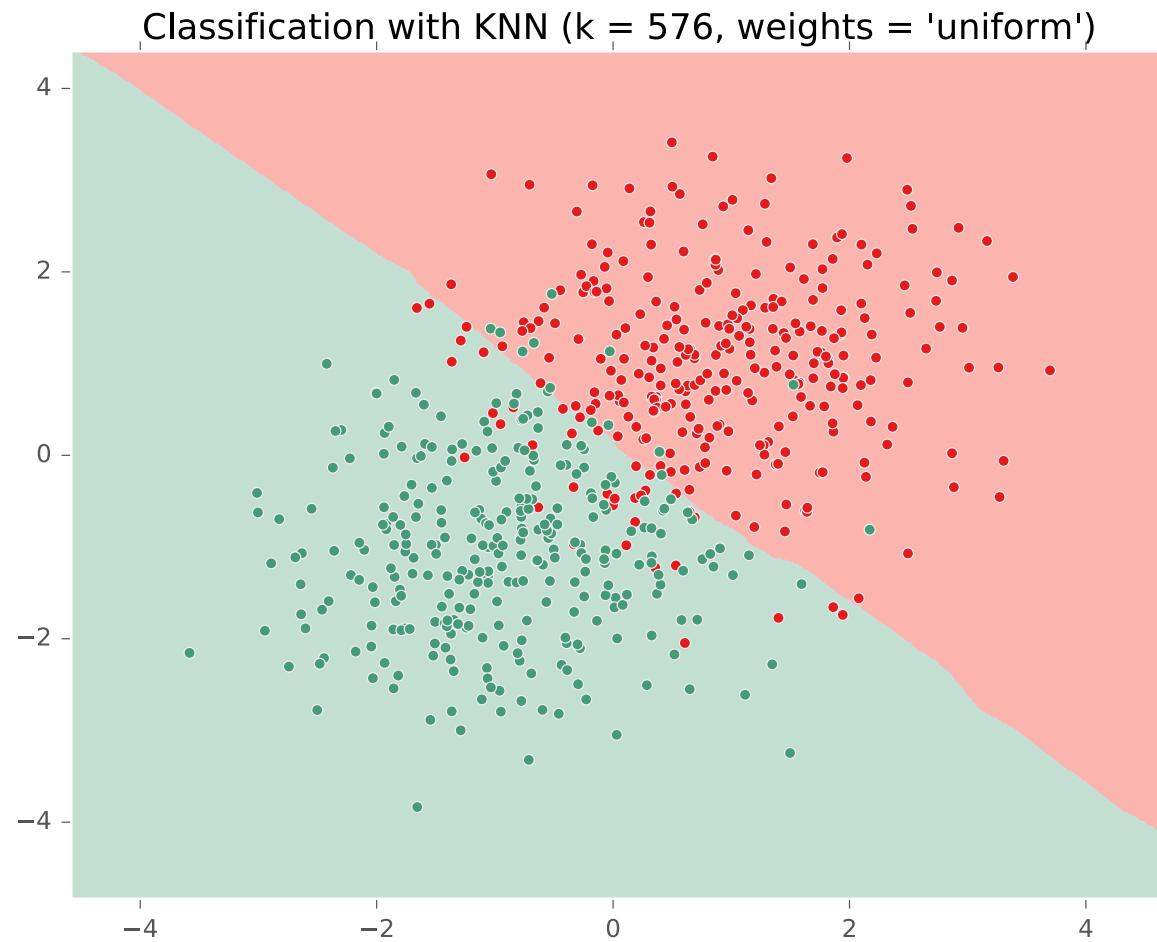
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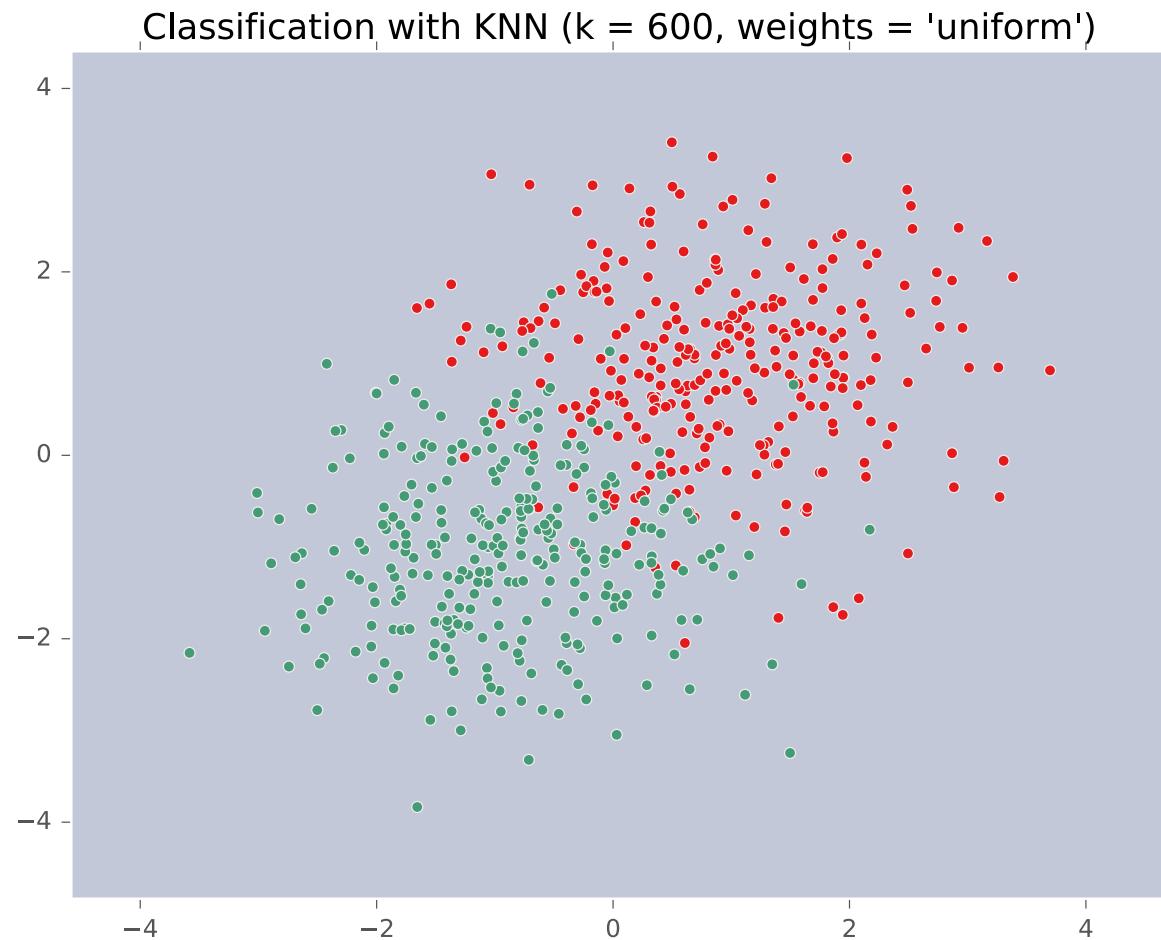
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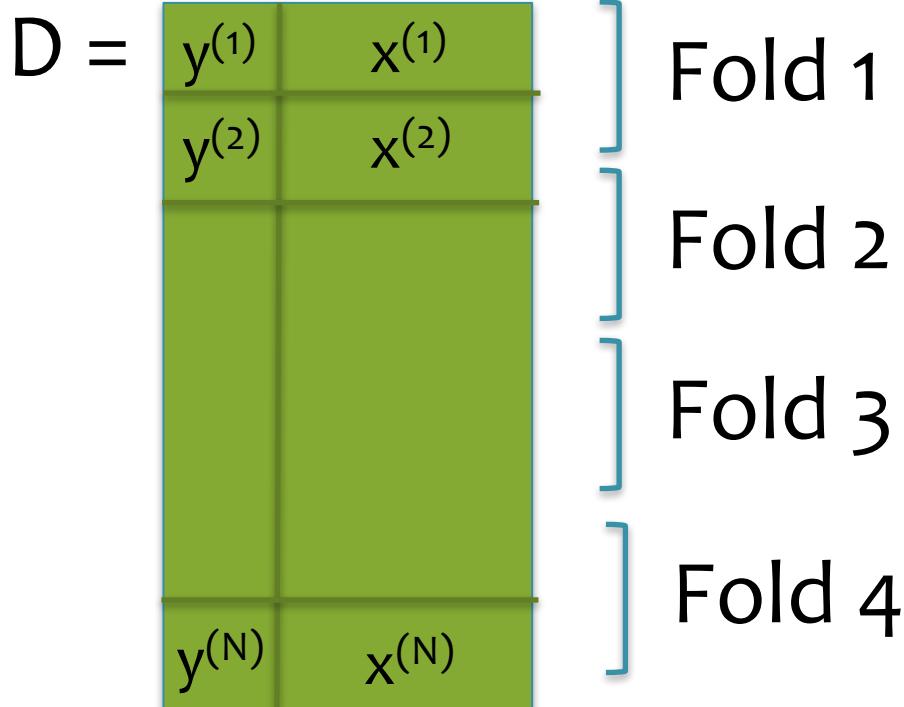
# KNN on Gaussian Data



# **CHOOSING THE NUMBER OF NEIGHBORS**

# F-Fold Cross-Validation

**Key idea:** rather than just a single “validation” set, use many! (Error is more stable. Slower computation.)



Divide data into folds (e.g. 4)

1. Train on folds  $\{1,2,3\}$  and predict on  $\{4\}$
2. Train on folds  $\{1,2,4\}$  and predict on  $\{3\}$
3. Train on folds  $\{1,3,4\}$  and predict on  $\{2\}$
4. Train on folds  $\{2,3,4\}$  and predict on  $\{1\}$

Concatenate all the predictions and evaluate error

# Math as Code

How to implement?

$$y^{\max} = \underset{y \in Y}{\operatorname{argmax}} f(y)$$

It depends on how large the set  $Y$  is!

If it's a small enumerable set  $Y = \{1, 2, \dots, 77\}$ ,  
then:

```
ymax = -inf
for y in {1,2,...77}:
    if f(y) > ymax:
        ymax = y
return ymax
```

# Math as Code

How to implement?

$$v^{\max} = \max_{y \in Y} f(y)$$

It depends on how large the set  $Y$  is!

If it's a small enumerable set  $Y = \{1, 2, \dots, 77\}$ ,  
then:

```
vmax = -inf
for y in {1,2,...77}:
    if f(y) > vmax:
        vmax = f(y)
return vmax
```

# Function Approximation View of ML

*Whiteboard*

# Beyond the Scope of This Lecture

- k-Nearest Neighbors (KNN) for **Regression**
- **Distance-weighted KNN**
- Cover & Hart (1967) **Bayes error rate bound**
- KNN for Facial Recognition (see **Eigenfaces** in PCA lecture)

# Takeaways

- **k-Nearest Neighbors**
  - Requires careful choice of  $k$  (# of neighbors)
  - Experimental design can be just as important as the learning algorithm itself
- **Function Approximation View**
  - **Assumption:** inputs are sampled from some unknown distributions
  - **Assumption:** outputs come from a fixed unknown function (e.g. human annotator)
  - **Goal:** Learn a hypothesis which closely approximates that function