

# A Saddle Point Condition

## Optimization Methods in Management Science

### Master in Management

#### HEC Lausanne

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# Critical Point

- A **critical** point or a **stationary** point of a differentiable function  $\mathbb{R}^n \rightarrow \mathbb{R}$  is a point where its gradient is null
- We remind that the gradient of  $f$  at a point  $\mathbf{x} = (x_1, \dots, x_n)$  is the vector  $\nabla f(\mathbf{x})$  of its partial derivatives:

$$\nabla f(\mathbf{x}) = \begin{pmatrix} \frac{\partial f(\mathbf{x})}{\partial x_1} \\ \vdots \\ \frac{\partial f(\mathbf{x})}{\partial x_n} \end{pmatrix}$$

- A **saddle** point is a critical point which is not a maximum, nor a minimum
- **A critical point can be a local minimum, a local maximum, or a saddle point**

## Example of a Saddle Point

A saddle point (in red) on the graph of  $z = x^2 - y^2$ :

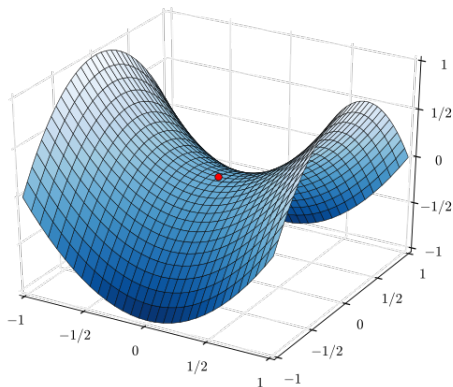


Image source: <https://commons.wikimedia.org/w/index.php?curid=20570051>

# Definiteness of Symmetric Matrices

- A  $n \times n$  symmetric real matrix  $\mathbf{Q}$  is said to be **positive definite** (resp. **negative definite**) if the scalar  $\mathbf{z}^T \mathbf{Q} \mathbf{z}$  is  $> 0$  (resp.  $< 0$ ) for every non-null vector  $\mathbf{z}$  of  $n$  real numbers
- A  $n \times n$  symmetric real matrix  $\mathbf{Q}$  is said to be **positive semi-definite** (resp. **negative semi-definite**) if the scalar  $\mathbf{z}^T \mathbf{Q} \mathbf{z}$  is  $\geq 0$  (resp.  $\leq 0$ ) for every vector  $\mathbf{z}$  of  $n$  real numbers
- A matrix that is not positive semi-definite and not negative semi-definite is called **indefinite**
- Positive and negative definite matrices are always **invertible**. This is not the case for positive and negative semi-definite matrices

# Conditions for Optimality for Unconstrained Optimization

## Theorem (Second Order Optimality Conditions)

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be twice differentiable at a point  $\bar{\mathbf{x}} \in \mathbb{R}^n$

- (1) (Necessity) If  $\bar{\mathbf{x}}$  is a local minimum (resp. local maximum), then  $\nabla f(\bar{\mathbf{x}}) = 0$  and  $\nabla^2 f(\bar{\mathbf{x}})$  is **positive semi-definite** (resp. **negative semi-definite**)
- (2) (Sufficiency) If  $\nabla f(\bar{\mathbf{x}}) = 0$  and  $\nabla^2 f(\bar{\mathbf{x}})$  is **positive definite** (resp. **negative definite**), then  $\bar{\mathbf{x}}$  is a local minimum (resp. local maximum)
- (3) If  $\nabla f(\bar{\mathbf{x}}) = 0$  and  $\nabla^2 f(\bar{\mathbf{x}})$  is indefinite, then  $\bar{\mathbf{x}}$  is a **saddle point**