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T13  
a

$$X_t = \log(S_t) = f(S_t) \quad ; \quad D_x f(x) = \frac{1}{x} \quad ; \quad D_x^2 f(x) = -x^{-2} ;$$

Ho:  $ds_t = \underbrace{\mu S_t}_{\mu(t)} dt + \underbrace{\sigma S_t}_{\sigma(t)} dW_t$

$$df(S_t) = dX_t = \left( \frac{1}{S_t} \mu S_t + \frac{1}{2} \left( -\frac{1}{S_t^2} \right) \sigma^2 S_t^2 \right) dt + \frac{1}{S_t} \sigma S_t dW_t$$

$$= \left( \mu - \frac{\sigma^2}{2} \right) dt + \sigma dW_t \Rightarrow X_t = \log S(0) + \left( \mu - \frac{\sigma^2}{2} \right) t + \sigma W_t$$

$$[X, X]_t = \sigma dW_t \sigma dW_t = \cancel{\sigma^2 dt} \sigma^2 t$$



$$\underline{b)} \quad V_0(\varphi) = 1 ; \quad \varphi_t^1 = \frac{2}{3} \frac{V_t(\varphi)}{S_t} \Rightarrow \varphi_t^0 = \frac{1}{3} \frac{V_t(\varphi)}{B_t}$$

$$V_t(\varphi) = \varphi_t^1 S_t^x + \varphi_t^0 S_t^y B_t^0 ; \quad \cancel{dV_t(\varphi) = \varphi_t^1 dS_t}$$

$$\cancel{= \frac{2}{3} \frac{V_t(\varphi)}{S_t} dS_t}$$

$$dV_t(\varphi) = \varphi_t^1 dS_t + \varphi_t^0 dB_t$$

$$= \varphi_t^1 (\mu S_t dt + \sigma S_t dW_t) + \varphi_t^0 (r B_t dt)$$

$$= \frac{2}{3} \frac{V_t(\varphi)}{S_t} (\mu S_t dt + \sigma S_t dW_t) + \frac{1}{3} \frac{V_t(\varphi)}{B_t} (r B_t dt)$$

$$\hookrightarrow = \frac{2}{3} (V_t(\varphi) \mu dt + V_t(\varphi) \sigma dW_t) + \frac{1}{3} r \cdot V_t(\varphi) dt$$

$$= \left( \frac{2}{3} \mu V_t(\varphi) + \frac{1}{3} r V_t(\varphi) \right) dt + \frac{2}{3} \sigma V_t(\varphi) dW_t$$

$$= \underbrace{\left( \frac{2}{3} \mu + \frac{1}{3} r \right)}_{\mu_V(t)} V_t(\varphi) dt + \underbrace{\frac{2}{3} \sigma}_{\sigma_V(t)} V_t(\varphi) dW_t = dV_t(\varphi)$$

$\Rightarrow V_t(\varphi)$  is geom. Brownian motion.