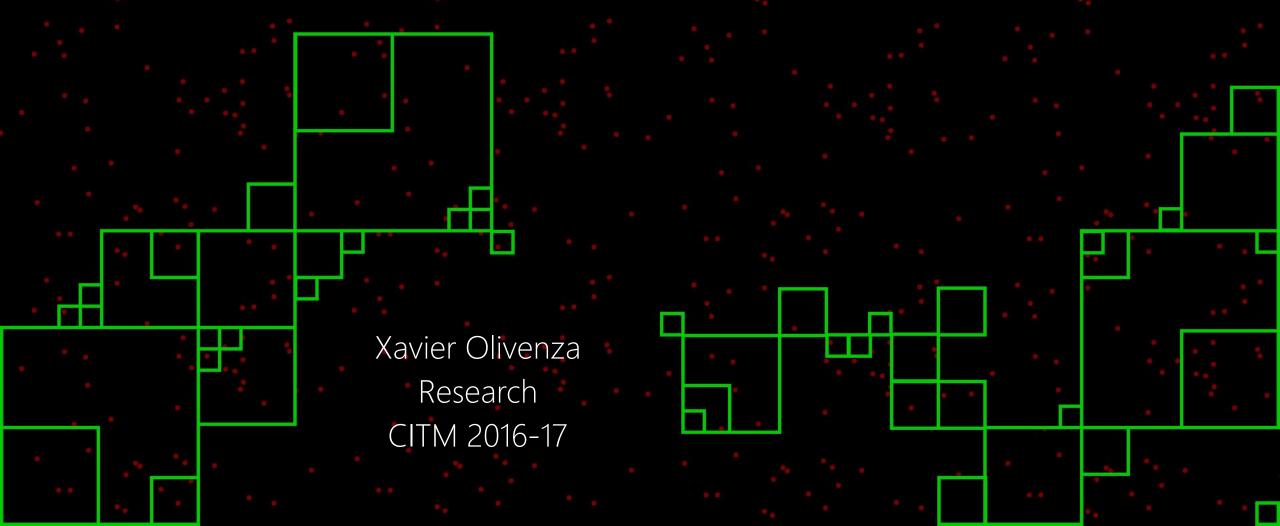
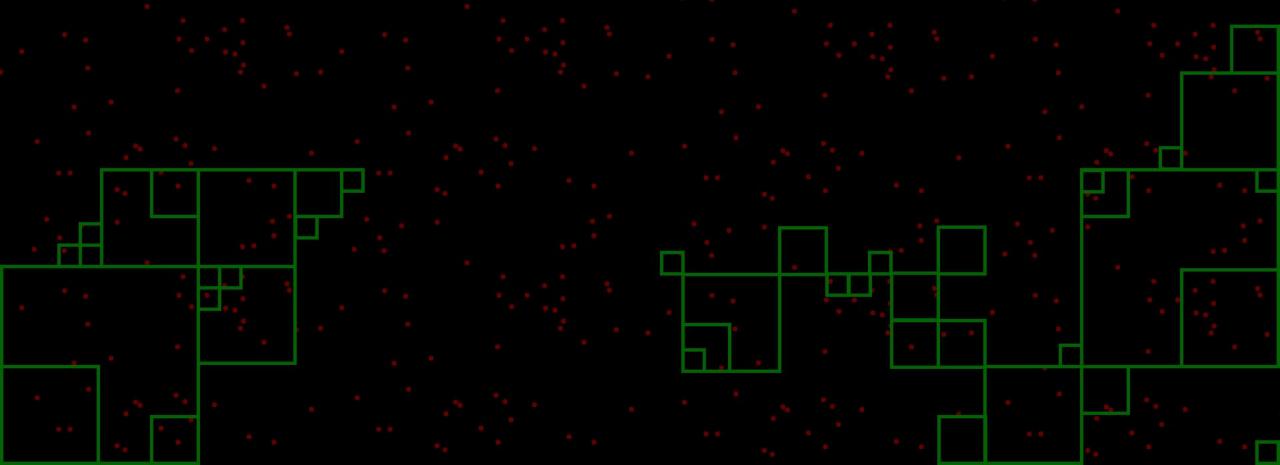
# Optimized Search Manager



## What is a search engine for?

-Search for an entity in an area/range



#### Where I can use this?



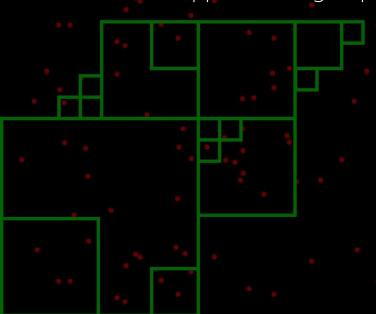


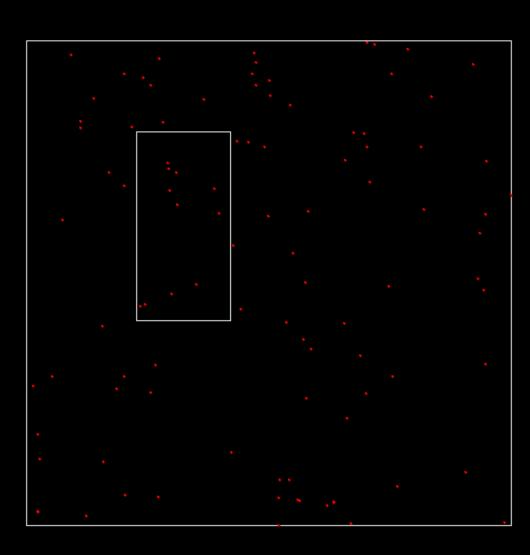
#### Brute force

-You have to do as many checks as entities are evaluated

...

-What happens if we group and order the entities?



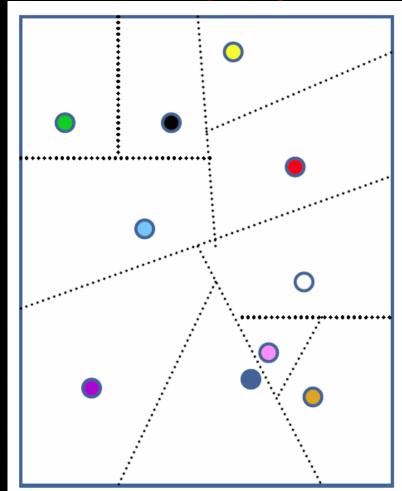


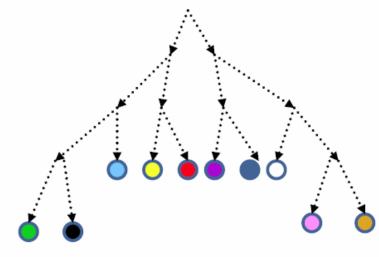
## Space Partitioning

Dividing a space into two or more subsets which do not overlap

·Algorithms that tend to be hierarchical Most common partition data structures:

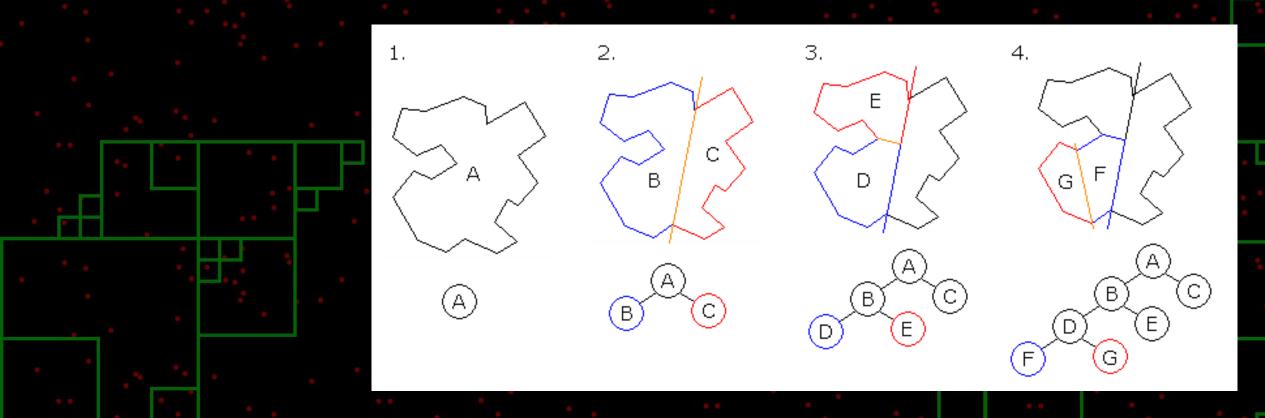
- · BSP Trees
- Quadtrees
- · Octrees
- · K-dimensional trees
- · R-Trees





## Binary Space Partitioning (BSP)

- ·Generalization
- ·Origin: Quickly draw polygonal 3d scenes
- ·Slow generation -> Pre-calculate



## BSP, Where is used?

Id-Teck 1 Doom

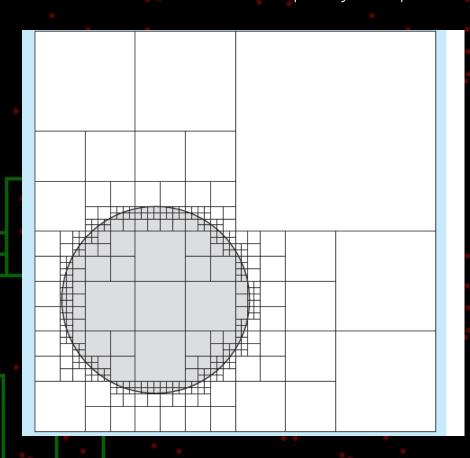


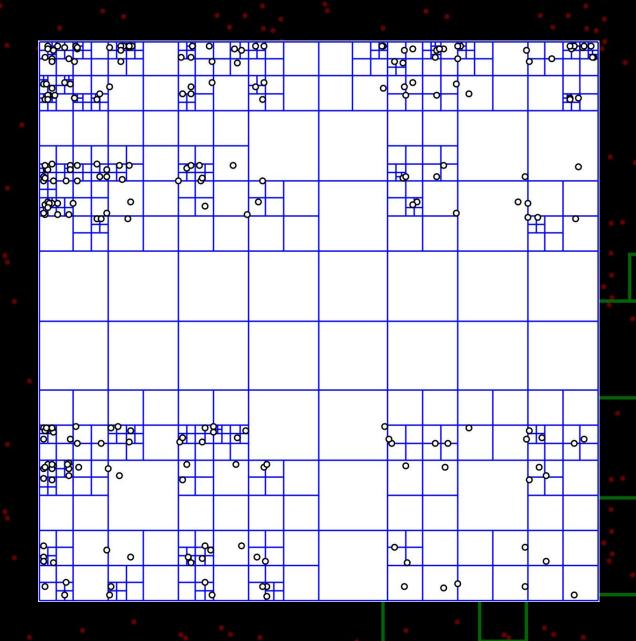
Quake Engine + descendants

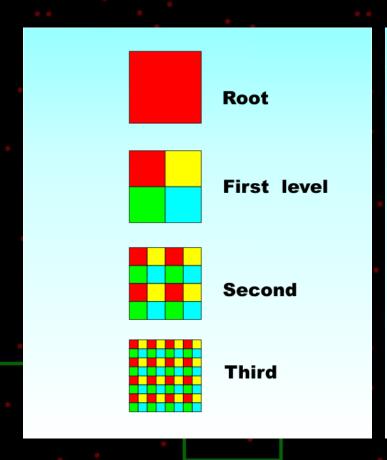


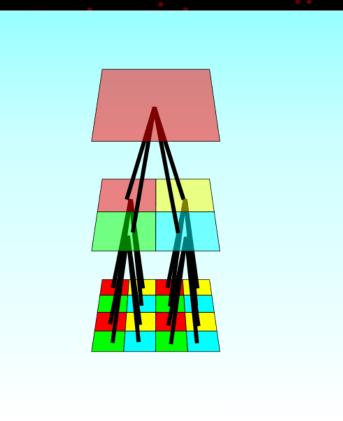
## Quadtree

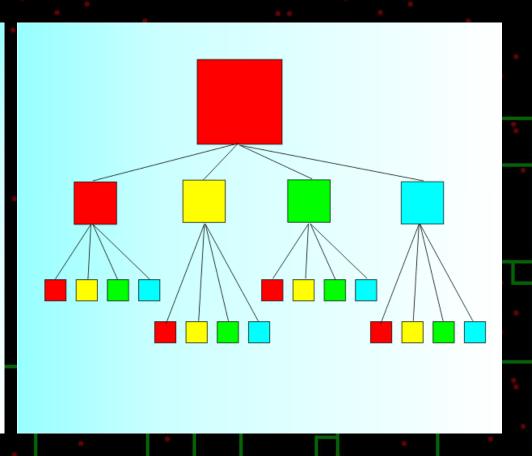
- ·Generally 2D
- ·When it reaches max node capacity -> split















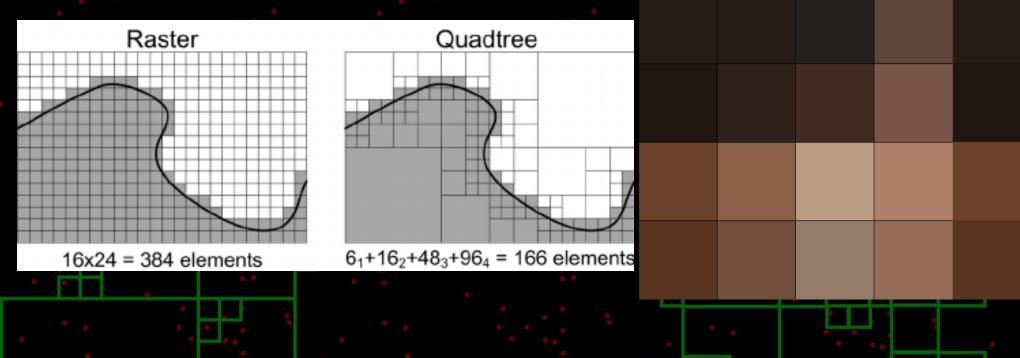




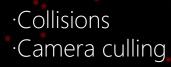


#### Quadtree, Where is used?





## Quadtree, Where is used?

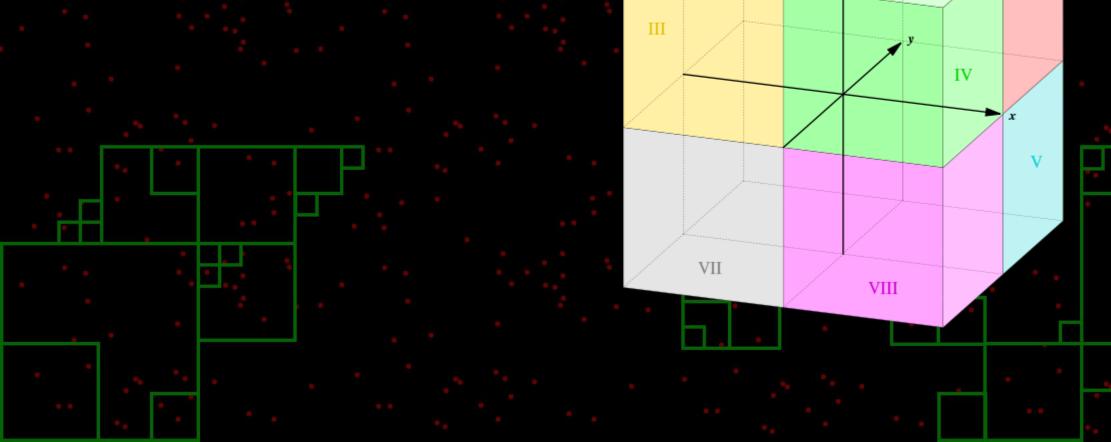




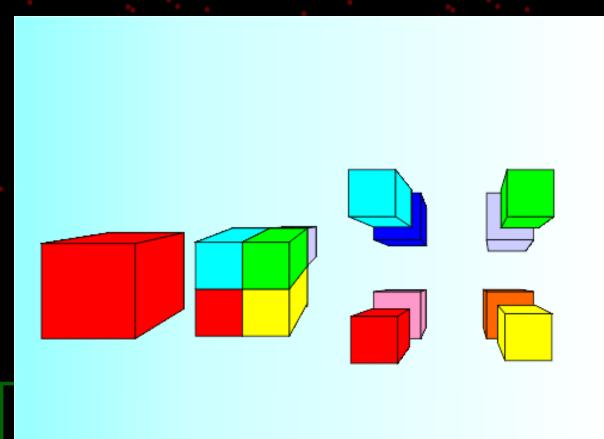
#### Octree

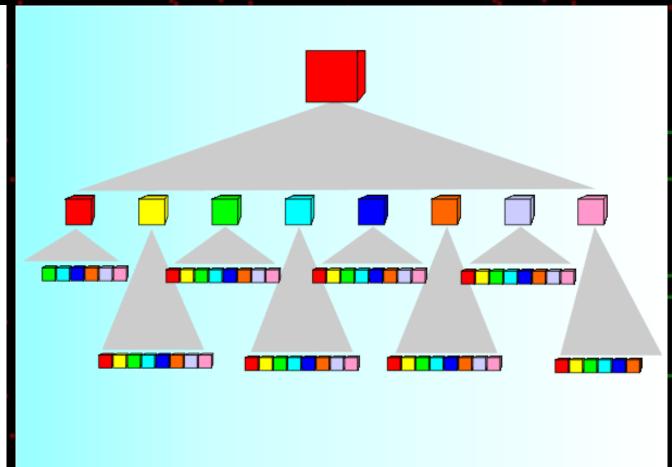
·Quadtree analogue in 3D

·3D graphics and video game engines



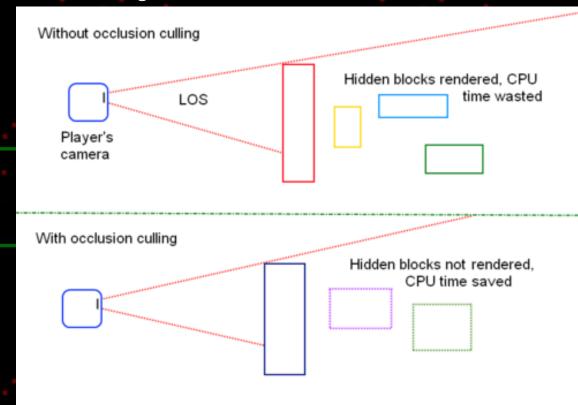
## Octree, Tree

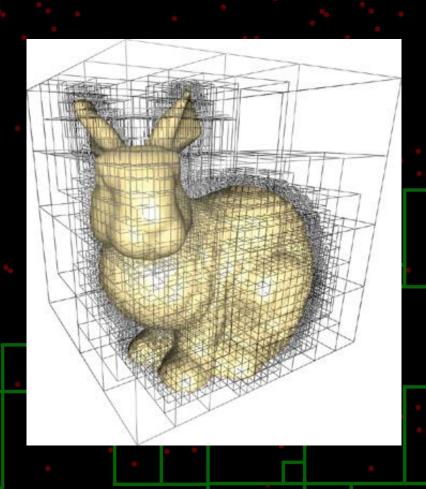




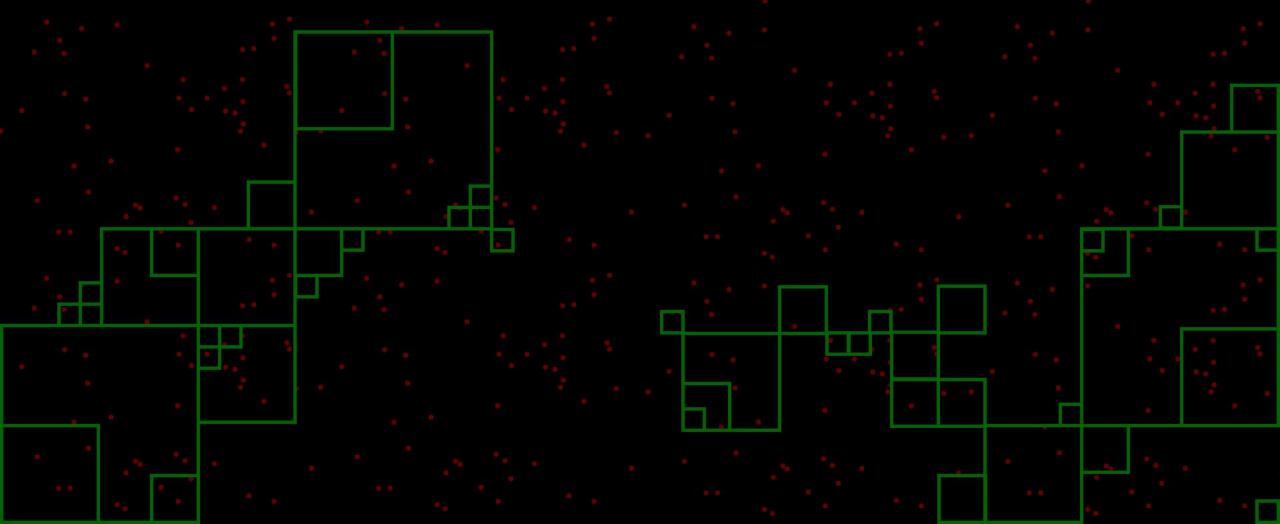
## Octree, Where is used?

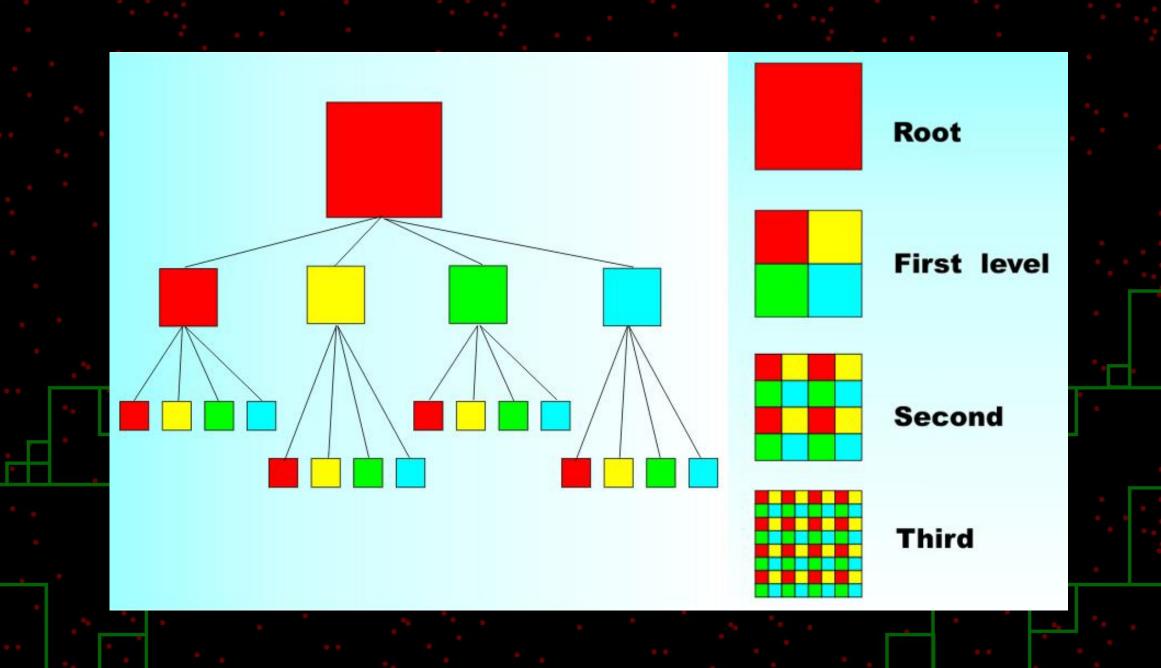
- · 3D Graphics
- · Efficient collision detection in three dimensions
- · Occlusion Culling (OC)

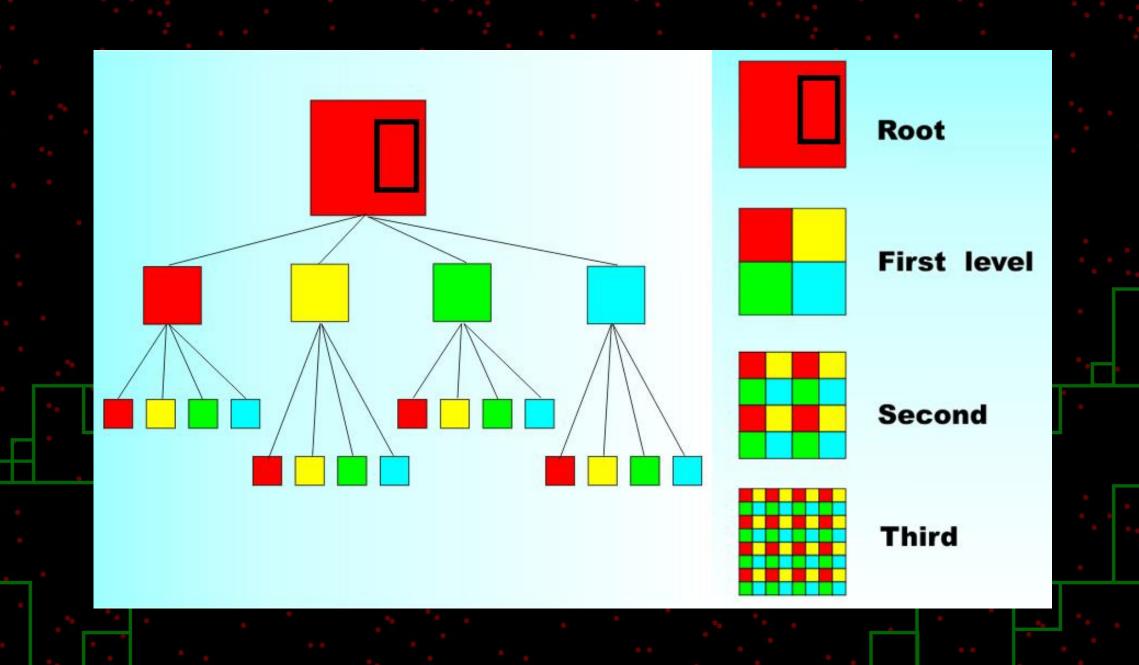


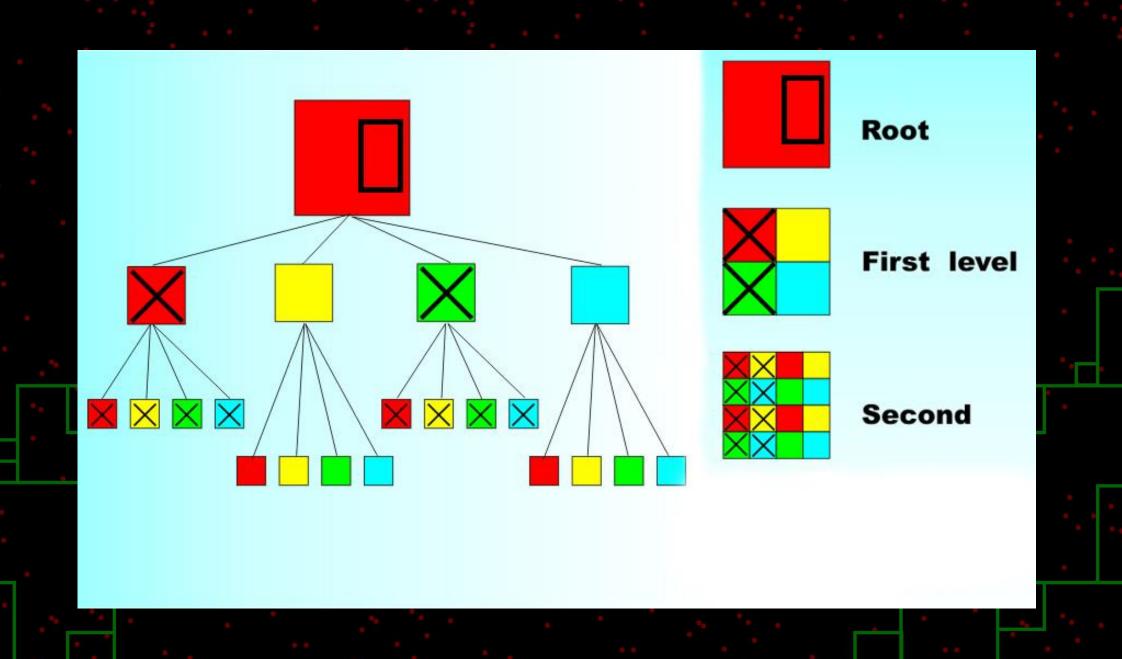


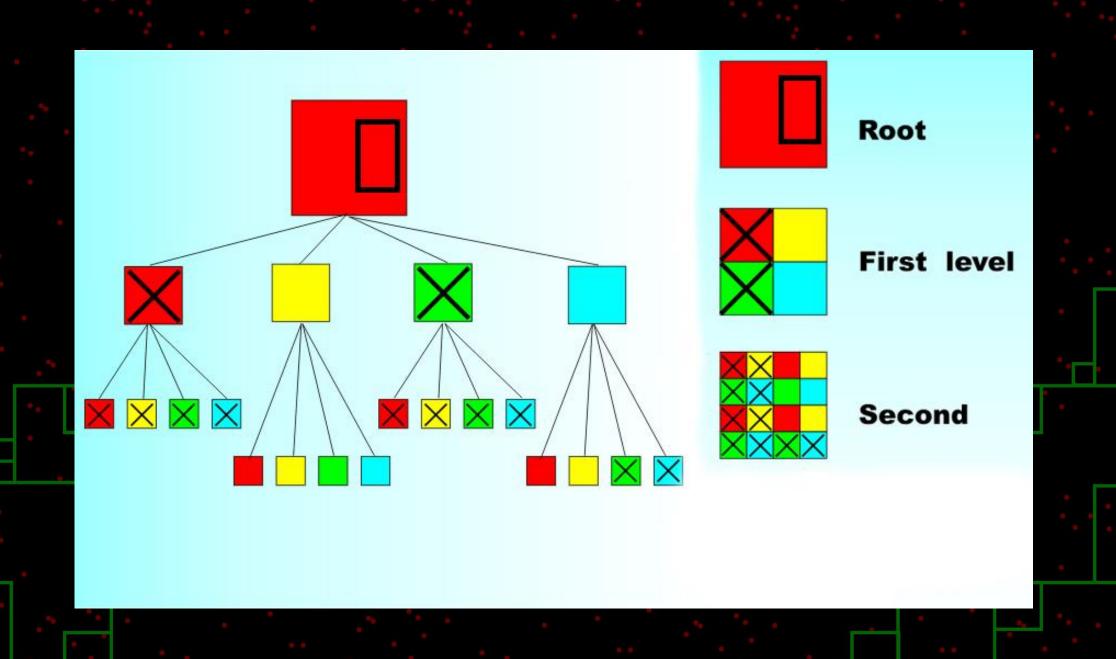
# Why they are faster?



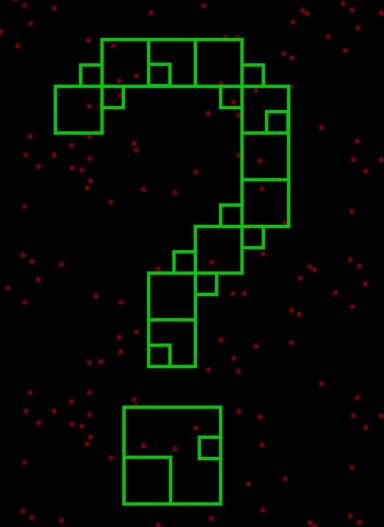








# Any question?

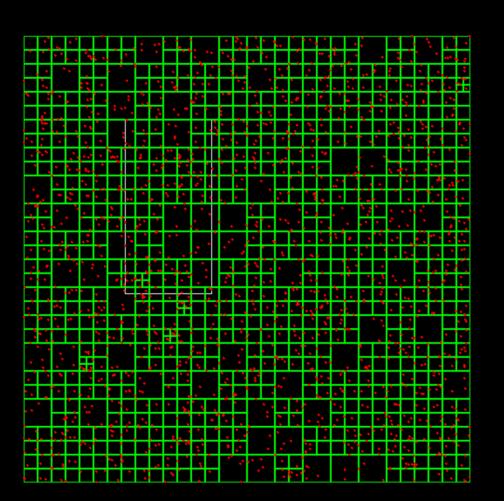


## Before TODOs

- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_second\_Iteration\_faster
- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_second\_Iteration\_faster\_with\_TODOS
- Olivenza\_Xavier\_Research\_Release
- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_ENG
- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_ESP
- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_PPTX
- Olivenza\_Xavier\_Research\_Optimized\_Search\_Manager\_PPTX

# Before TODOs

Normal Search Time: 1.242694 ms, Points in Range = 162 | Quadtree Search Time: 0.471734 ms, Points in Range = 162 | Quadtree AABBs = 1164 | Quadtree checks = 165 | Accepted points 2000/2000 | Mesh ste...



# TODOs wth the Quadtree implementation



```
bool AABB::Insert(iPoint* newpoint)
// TODO 1: If new point is not in the quadtree AABB, return
return false;
```

```
bool AABB::Insert(iPoint* newpoint)
// TODO 1: If new point is not in the quadtree AABB, return
// TODO 2: If in this node there is space for the point, pushback it (remember Max_Elements_in_Same_Node)
return false;
```

```
void AABB::subdivide()
// TODO 3: Calculate the size and position of each of the 4 new nodes
```

```
void AABB::subdivide()
// TODO 3: Calculate the size and position of each of the 4 new nodes
// TODO 4: Now we have all the positions and size of each number we
// can create each child with its AABB
//! Don't forget to set child root!
```

```
bool AABB::Insert(iPoint* newpoint)
// TODO 1: If new point is not in the quadtree AABB, return
// TODO 2: If in this node there is space for the point, pushback it (remember Max_Elements_in_Same_Node)
// TODO 5: Otherwise, subdivide and add the point to one of the new nodes
return false;
```

```
int AABB::CollectCandidates(std::vector < iPoint* > & nodes, const SDL_Rect& r)
uint ret = 1;
// TODO 6: If range is not in the quadtree, returnreturn ret;
```

```
int AABB::CollectCandidates(std::vector < iPoint* > & nodes, const SDL_Rect& r)
uint ret = 1;
// TODO 6: If range is not in the quadtree, return
// TODO 7: See if the points of this node are in range and pushback them to the vector
(remember Max_Elements_in_Same_Node) return ret;
```

```
int AABB::CollectCandidates(std::vector < iPoint* > & nodes, const SDL_Rect& r)
\underline{uint} ret = 1;
// TODO 6: If range is not in the quadtree, return
// TODO 7: See if the points of this node are in range and pushback them to the vector
(remember Max_Elements_in_Same_Node)
// TODO 8: If there is no children, end
return ret;
```

```
int AABB::CollectCandidates(std::vector < iPoint* > & nodes, const SDL_Rect& r)
uint ret = 1;
// TODO 6: If range is not in the quadtree, return
// TODO 7: See if the points of this node are in range and pushback them to the vector
(remember Max_Elements_in_Same_Node)
// TODO 8: If there is no children, end
// TODO 9: Otherwise, add the points from the children (Recursive)
return ret;
```

## Optional Homework

·Moving entities? Adapt the code for it. Maybe you will need a Remove method...

# Any last question?

