# UNIVERSITY OF OSLO



# **IN4310 Linear Algebra Review**

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## A Bit of Background

Research Agenda: Learning under Resource Constraints in Real World

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Norwegian Centre for Knowledge-driven Machine



# A Bit of Background









### What Is This Course About?

Algorithms, Practice, Theory, Major Issues of Deep Learning

Main Application: Image Data

Not a Pure Programming and Math/Stats Course

Useful Tools for Industry/Academic Career

## **Matrix**

$$\begin{bmatrix} 1 & 2 & 3 \\ a & b & c \end{bmatrix}$$

#### **Notation**

 $A \in \mathbb{R}^{m \times n}$  matrix with m rows and n columns with real entries

 $\mathbf{x} \in \mathbb{R}^n$  n-dimensional column vector

 $\mathbf{x}^{\top}$  the transpose of  $\mathbf{x}$  (row vector)

 $\mathbf{a}_j \in \mathbb{R}^m$  or  $A_{:,j} \in \mathbb{R}^m$  j-th column of A

$$A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \cdots \ \mathbf{a}_n]$$

$$A = \begin{bmatrix} \mathbf{b}_1^\top \\ \vdots \\ \mathbf{b}_m^\top \end{bmatrix}$$

## **Vector-Vector Products and Matrix-Vector Products**

Let  $\mathbf{x}, \mathbf{v} \in \mathbb{R}^n$  and  $A \in \mathbb{R}^{m \times n}$ 

Inner product or dot product  $\mathbf{x}^{\top}\mathbf{y} = \sum_{i=1}^{n} x_i y_i$ 

Outer product 
$$\mathbf{x}\mathbf{y}^{ op} = \begin{bmatrix} x_1y_1 & x_1y_2 & \cdots & x_1y_n \\ x_2y_1 & x_2y_2 & \cdots & x_2y_n \\ \vdots & \vdots & \ddots & \vdots \\ x_ny_1 & x_ny_2 & \cdots & x_ny_n \end{bmatrix}$$

Writing 
$$A$$
 by rows  $\mathbf{y} = A\mathbf{x} = \begin{bmatrix} \mathbf{b}_1^\top \\ \vdots \\ \mathbf{b}_m^\top \end{bmatrix} \mathbf{x} = \begin{bmatrix} \mathbf{b}_1^\top \mathbf{x} \\ \vdots \\ \mathbf{b}_m^\top \mathbf{x} \end{bmatrix}$ 

Writing 
$$A$$
 by columns  $\mathbf{y} = A\mathbf{x} = [\mathbf{a}_1 \ \mathbf{a}_2 \ \cdots \ \mathbf{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n \mathbf{a}_i x_i$ 

## Transpose, Symmetric Matrices, and Trace [1]

Transpose of  $A \in \mathbb{R}^{m \times n}$  denoted by  $A^{\top} \in \mathbb{R}^{n \times m}$   $\left(A^{\top}\right)_{ij} = A_{ji}$ 

$$\left(A^{\top}\right)^{\top} = A; \quad (AB)^{\top} = B^{\top}A^{\top}; \quad (A+B)^{\top} = A^{\top} + B^{\top}$$

Square matrix  $A \in \mathbb{R}^{n \times n}$  is symmetric if  $A = A^{\top}$ 

Trace of a square matrix  $\operatorname{tr}(A) = \sum_{i=1}^n A_{ii}$ 

$$\operatorname{tr}(A) = \operatorname{tr}(A^{\top}); \quad \operatorname{tr}(A+B) = \operatorname{tr}(A) + \operatorname{tr}(B); \quad \operatorname{tr}(AB) = \operatorname{tr}(BA)$$

$$\operatorname{tr}(ABC) = \operatorname{tr}(BCA) = \operatorname{tr}(CAB)$$

#### **Norms**

Informally a measure of the length of a vector

Euclidean or 
$$\ell_2$$
 norm  $\|\mathbf{x}\|_2 = \sqrt{\sum_{i=1}^n x_i^2}$ 

$$\|\mathbf{x}\|_2^2 = \mathbf{x}^{\top}\mathbf{x}$$

$$\ell_1$$
 norm  $\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$ 

$$\ell_{\infty} \text{ norm } \|\mathbf{x}\|_{\infty} = \max_{i} |x_{i}|$$

$$\ell_p$$
 norm for some  $p \ge 1$   $\|\mathbf{x}\|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p}$ 

Frobenius norm 
$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n A_{ij}^2} = \sqrt{\operatorname{tr}(A^{\top}A)}$$

### **Quadratic Forms and Positive Semidefinite Matrices**

Let  $A \in \mathbb{R}^{n \times n}$  and  $\mathbf{x} \in \mathbb{R}^n$ . The scalar  $\mathbf{x}^{\top} A \mathbf{x}$  is quadratic form

$$\mathbf{x}^{\top} A \mathbf{x} = \sum_{i=1}^{n} \sum_{j=1}^{n} x_i A_{ij} x_j$$

$$\mathbf{x}^{\top} A \mathbf{x} = (\mathbf{x}^{\top} A \mathbf{x})^{\top} = \mathbf{x}^{\top} A^{\top} \mathbf{x} = \mathbf{x}^{\top} \left( \frac{1}{2} A + \frac{1}{2} A^{\top} \right) \mathbf{x}$$

A symmetric A is positive definite if for all non-zero  $\mathbf{x}$ ,  $\mathbf{x}^{\top}A\mathbf{x}>0$  A is positive semidefinite if for all non-zero  $\mathbf{x}$ ,  $\mathbf{x}^{\top}A\mathbf{x}\geq0$   $(A\succeq0)$  A is negative definite if for all non-zero  $\mathbf{x}$ ,  $\mathbf{x}^{\top}A\mathbf{x}<0$  A is negative semidefinite if for all non-zero  $\mathbf{x}$ ,  $\mathbf{x}^{\top}A\mathbf{x}\leq0$   $(A\preceq0)$  A is indefinite if it is neither PSD nor NSD

## **Eigenvalues and Eigenvectors**

Given  $A\in\mathbb{R}^{n\times n}$ ,  $\lambda\in\mathbb{C}$  is an eigenvalue of A with corresponding non-zero eigenvector  $\mathbf{x}\in\mathbb{C}^n$  if  $A\mathbf{x}=\lambda\mathbf{x}$ 

 $(\lambda, \mathbf{x})$  is an eigenvalue-eigenvector pair if  $(\lambda \mathbf{I} - A)\mathbf{x} = 0, \ \mathbf{x} \neq 0$ 

 $(\lambda \mathbf{I} - A)\mathbf{x} = 0$  has non-zero solution iff  $\lambda \mathbf{I} - A$  is singular

$$\det(\lambda \mathbf{I} - A) = 0$$

Trace equals sum of eigenvalues  $\operatorname{tr}(A) = \sum_{i=1}^n \operatorname{eig}(A) = \sum_{i=1}^n \lambda_i$ 

Determinant equals product of eigenvalues  $\det(A) = \prod_{i=1}^{n} \lambda_i$ 

## Matrix Calculus: Gradient

 $g: \mathbb{R}^{m \times n} \to \mathbb{R}$  takes an  $m \times n$  matrix input and returns a real value

The gradient of g w.r.t. A is a matrix of partial derivatives

$$\nabla_{A}g(A) = \begin{bmatrix} \frac{\partial g(A)}{\partial A_{11}} & \frac{\partial g(A)}{\partial A_{12}} & \dots & \frac{\partial g(A)}{\partial A_{1n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial g(A)}{\partial A_{m1}} & \frac{\partial g(A)}{\partial A_{m2}} & \dots & \frac{\partial g(A)}{\partial A_{mn}} \end{bmatrix}$$

 $f: \mathbb{R}^n \to \mathbb{R}$  takes an *n*-dimensional vector input

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \begin{bmatrix} \frac{\partial f(\mathbf{x})}{\partial x_1} \\ \vdots \\ \frac{\partial f(\mathbf{x})}{\partial x_n} \end{bmatrix}$$

## Matrix Calculus: Hessian

 $f:\mathbb{R}^n o \mathbb{R}$  takes a vector input and returns a real scalar

The Hessian matrix w.r.t.  $\mathbf{x}$  is  $n \times n$  matrix of partial derivatives

$$\nabla_{\mathbf{x}}^{2} f(\mathbf{x}) = \begin{bmatrix} \frac{\partial^{2} f(\mathbf{x})}{\partial x_{1}^{2}} & \frac{\partial^{2} f(\mathbf{x})}{\partial x_{1} \partial x_{2}} & \cdots & \frac{\partial^{2} f(\mathbf{x})}{\partial x_{1} \partial x_{n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^{2} f(\mathbf{x})}{\partial x_{n} \partial x_{1}} & \frac{\partial^{2} f(\mathbf{x})}{\partial x_{n} \partial x_{2}} & \cdots & \frac{\partial^{2} f(\mathbf{x})}{\partial x_{n}^{2}} \end{bmatrix}$$

$$\left(\nabla_{\mathbf{x}}^2 f(\mathbf{x})\right)_{ij} = \frac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j}$$

Exercise: Suppose  $f(\mathbf{x}) = \mathbf{x}^{\top} A \mathbf{x}$ . Then show

$$\nabla_{\mathbf{x}} \mathbf{x}^{\top} A \mathbf{x} = 2A \mathbf{x}, \quad \nabla_{\mathbf{x}}^2 \mathbf{x}^{\top} A \mathbf{x} = 2A$$

Hint: Show 
$$\frac{\partial f(\mathbf{x})}{\partial x_i} = 2\sum_{j=1}^n A_{ij}x_j$$
 and  $\frac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j} = 2A_{ij}$ 

#### References

[1] Z. Kolter and C. Do. Linear algebra review. https: //cs229.stanford.edu/section/cs229-linalg.pdf.