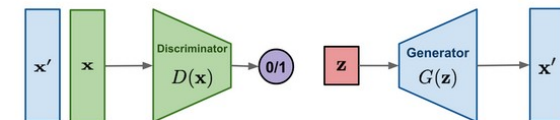
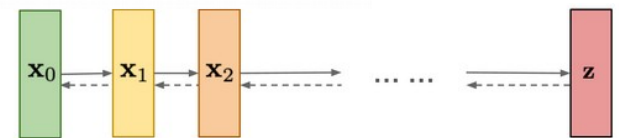
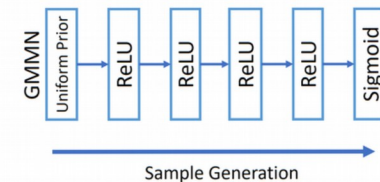
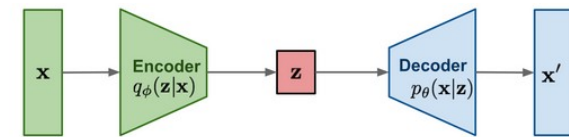
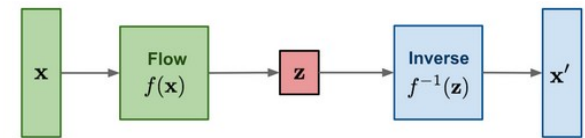


Diffusion Models

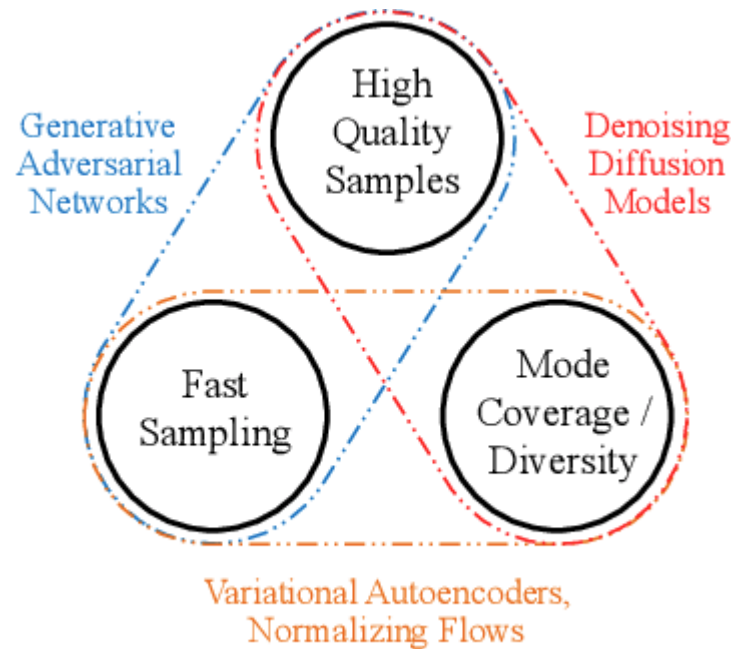
Narada Warakagoda

Generative modelling approaches with Deep Learning

- Normalizing Flows
- Variational Auto Encoders (VAE)
- Moment Matching Networks (MMN)
- Diffusion models
- Generative Adversarial Networks (GAN)

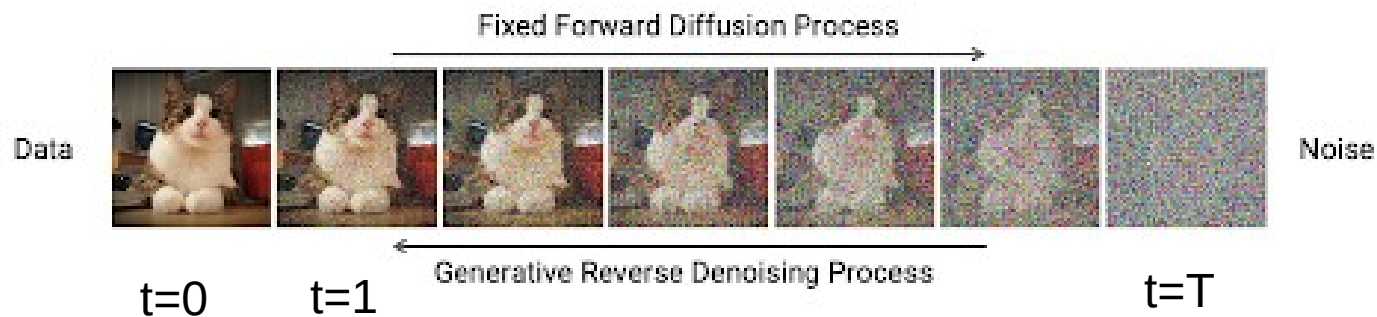
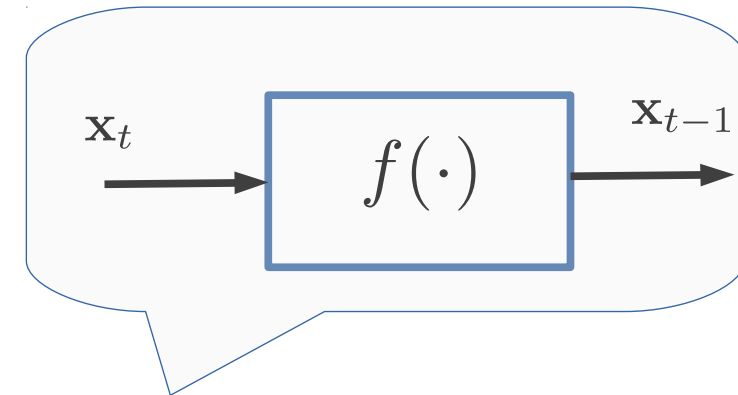


Generative modeling trilemma




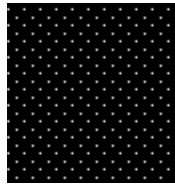
Denoising Diffusion Models (DDM) principle

- Forward diffusion process
 - Add noise to the image at each step
 - Stop when the result is only noise
- Reverse diffusion process
 - Learn a mapping (neural net) from the noisy image to the previous image at each step
- Generation
 - Apply the mapping recursively starting from noise

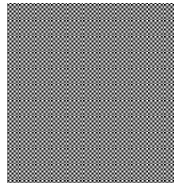


DDM Algorithm

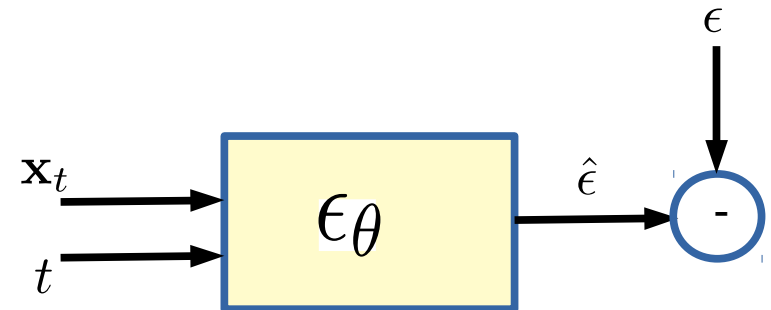
Forward 



\mathbf{x}_{t-1}



$\mathbf{x}_t = \mathbf{x}_{t-1} + \epsilon$



Algorithm 1 Training

- 1: **repeat**
- 2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$
- 3: $t \sim \text{Uniform}(\{1, \dots, T\})$
- 4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 5: Take gradient descent step on
 $\nabla_{\theta} \|\epsilon - \epsilon_{\theta}(\sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon, t)\|^2$
- 6: **until** converged

\mathbf{x}_t

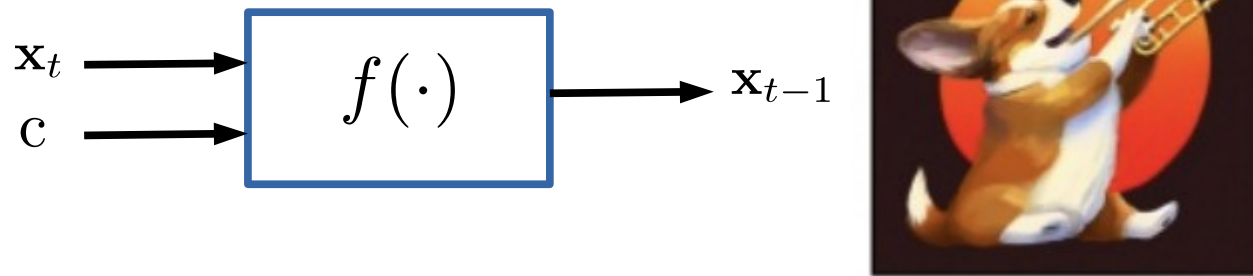
Algorithm 2 Sampling

- 1: $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 2: **for** $t = T, \dots, 1$ **do**
- 3: $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ if $t > 1$, else $\mathbf{z} = \mathbf{0}$
- 4: $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$
- 5: **end for**
- 6: **return** \mathbf{x}_0

$\hat{\epsilon}$

Text-to-image generation

- Conditional generation
 - Condition (c) = text string (eg: A corgi playing a flame throwing trumpet)



Famous diffusion systems

- GLIDE
- DALL-E2
- IMAGEN

