

Hierarchical Concurrent EFSM

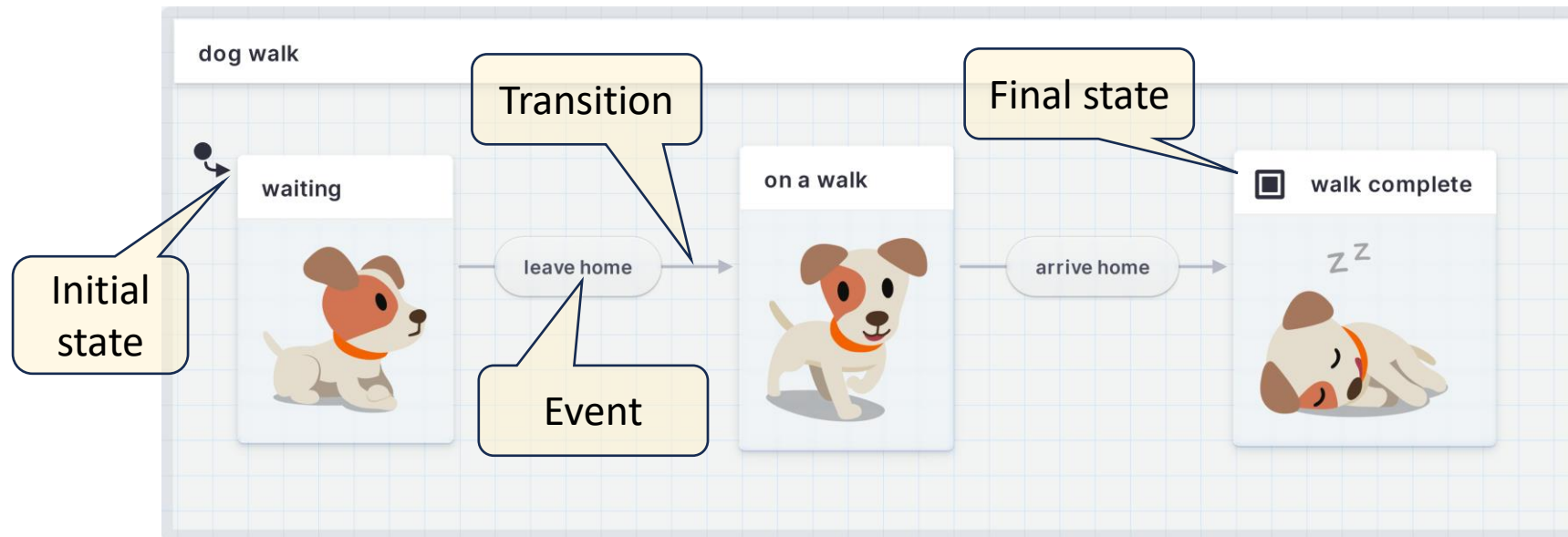
Application-level EFSM such as path-following

Statecharts

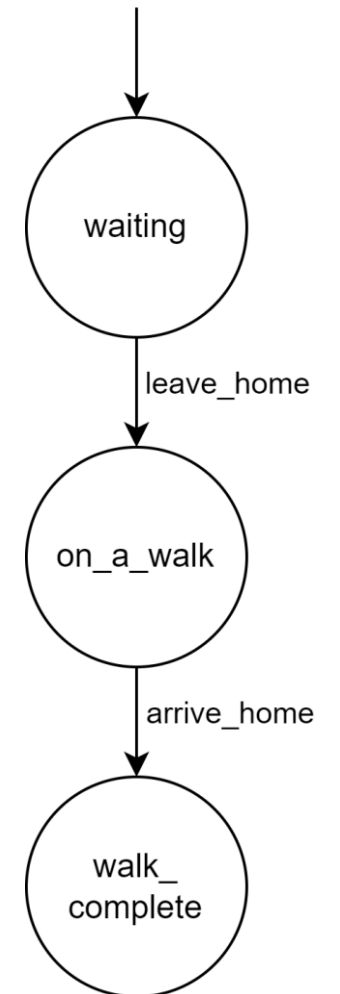
- Definitions
 - *Visual language for modeling the executable behavior of complex reactive event-based systems*
[<https://sismic.readthedocs.io/en/latest/format.html>]
 - **Diagrams that represent** state machines, including compound states, which are states with *refinements*, the foundation of **hierarchical state machines**

Statecharts, introduction 1/3

- A flat statechart on Stately.ai

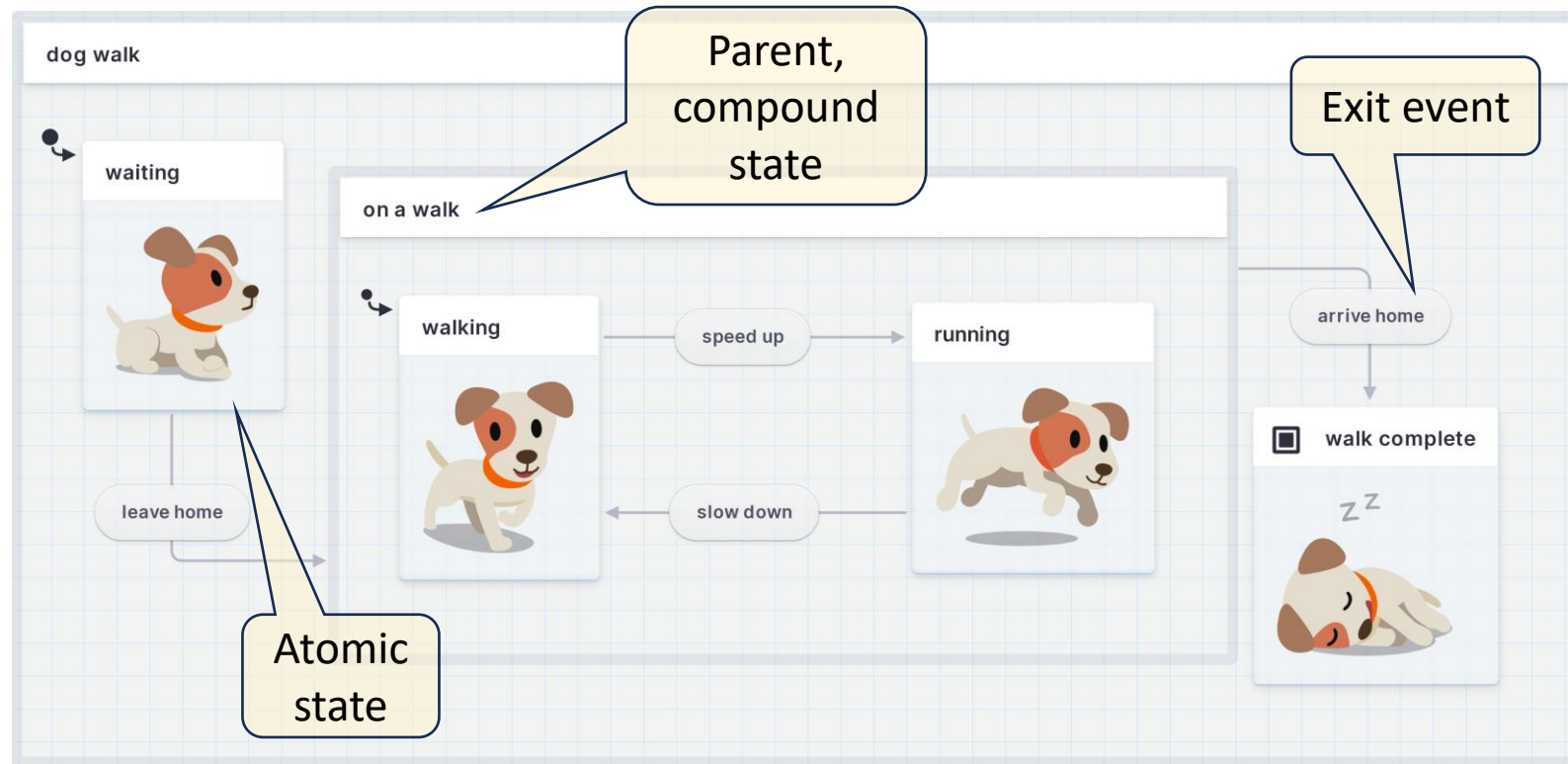


Source: <https://stately.ai/docs/state-machines-and-statecharts>

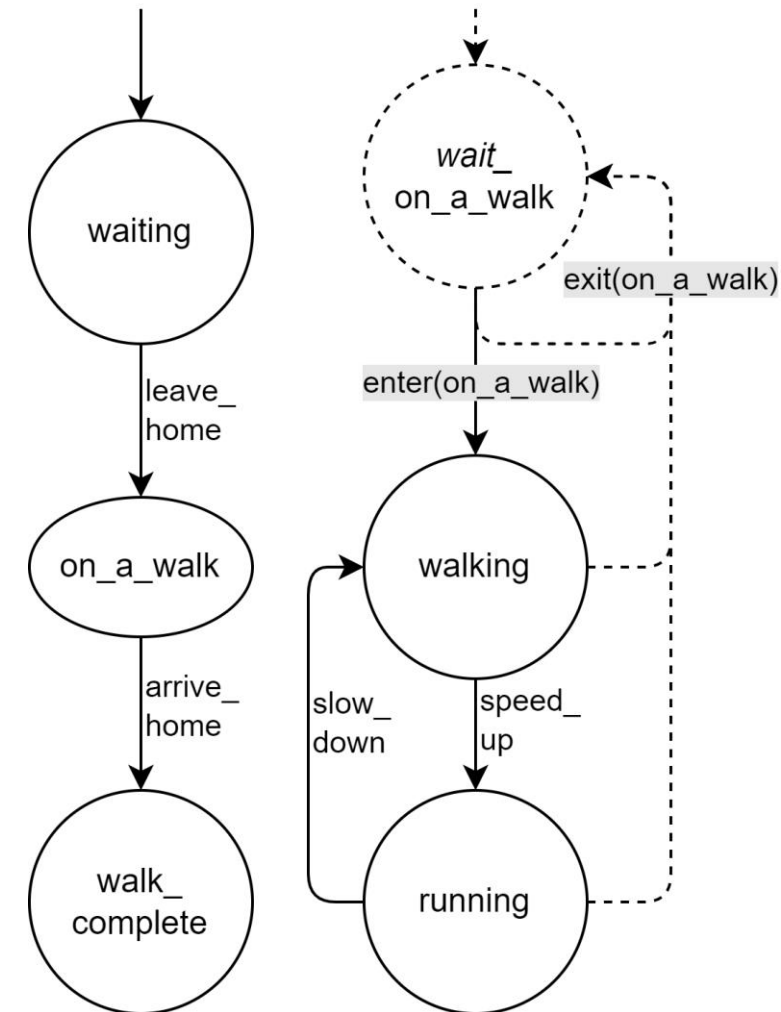


Statecharts, introduction 2/3

- A hierarchical statechart on Stately.ai

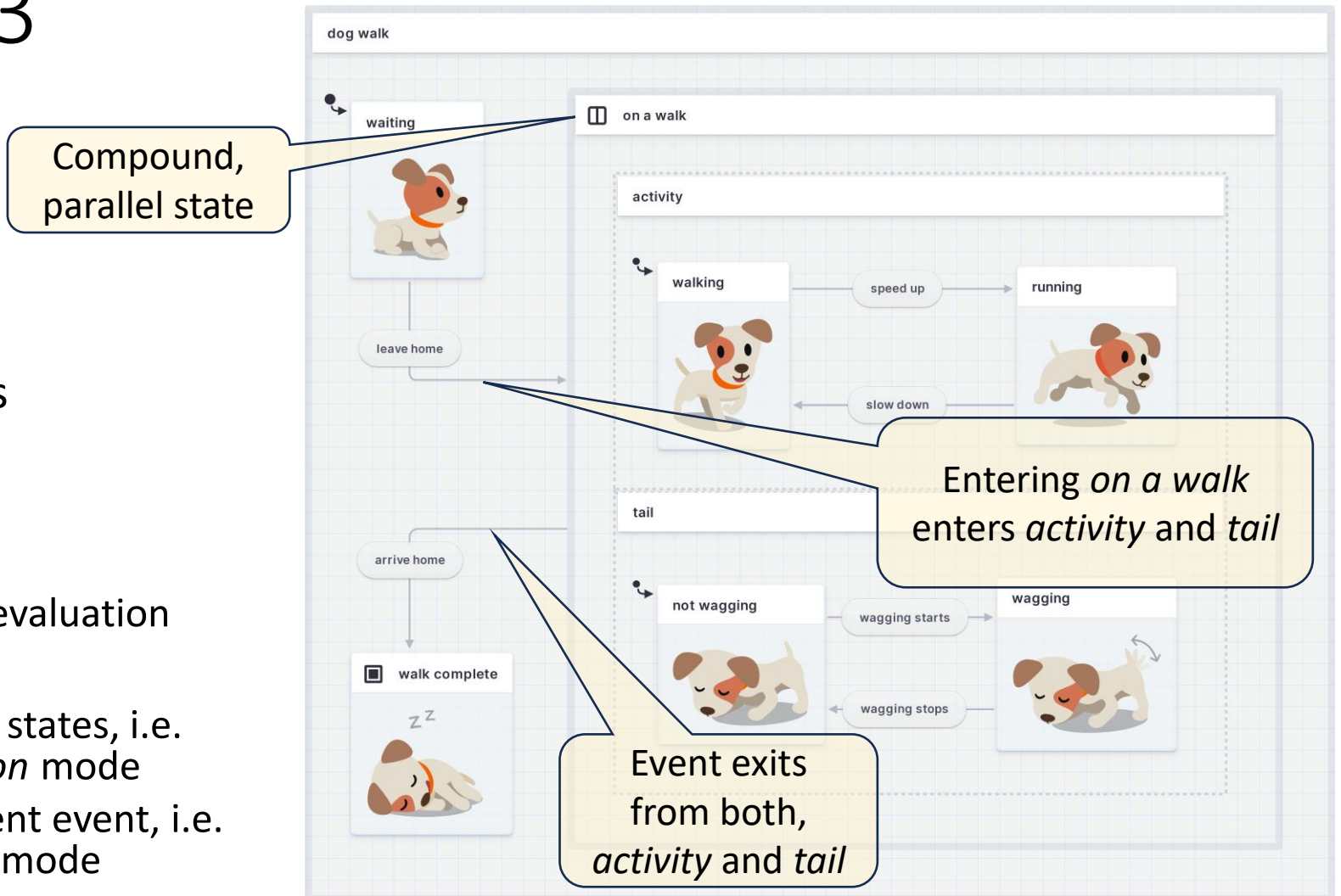


Source: <https://stately.ai/docs/state-machines-and-statecharts>



Statecharts, introduction 3/3

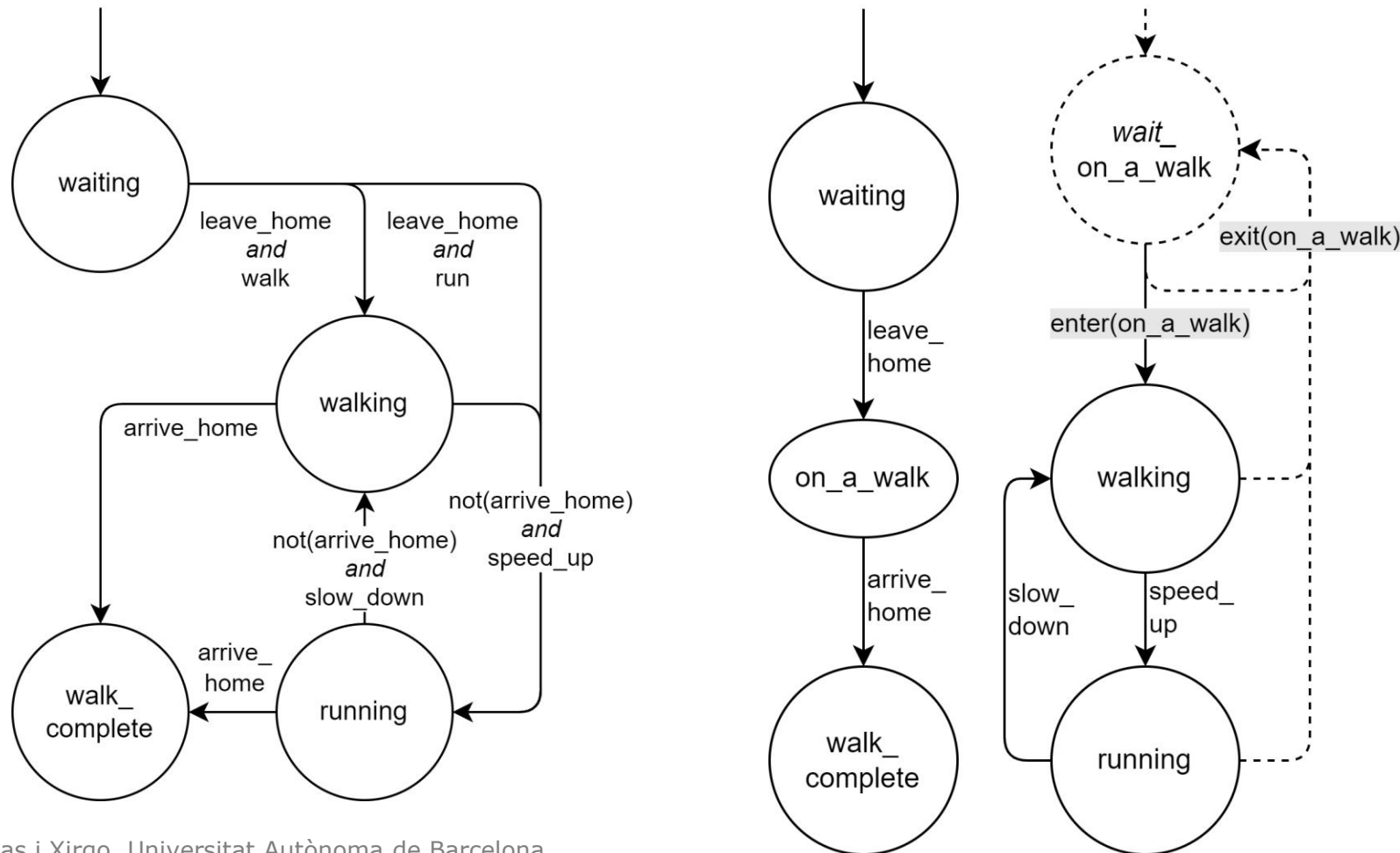
- A hierarchical, concurrent statechart on Stately.ai
- Other features
 - History compound states
 - Shallow
 - Deep
 - Preemptive transitions
 - Top-down, conditional evaluation
 - Synchronization
 - Exit upon reaching final states, i.e. *Transition-on-Completion* mode
 - Exit upon outgoing parent event, i.e. *Transition-Immediately* mode



Source: <https://stately.ai/docs/state-machines-and-statecharts>

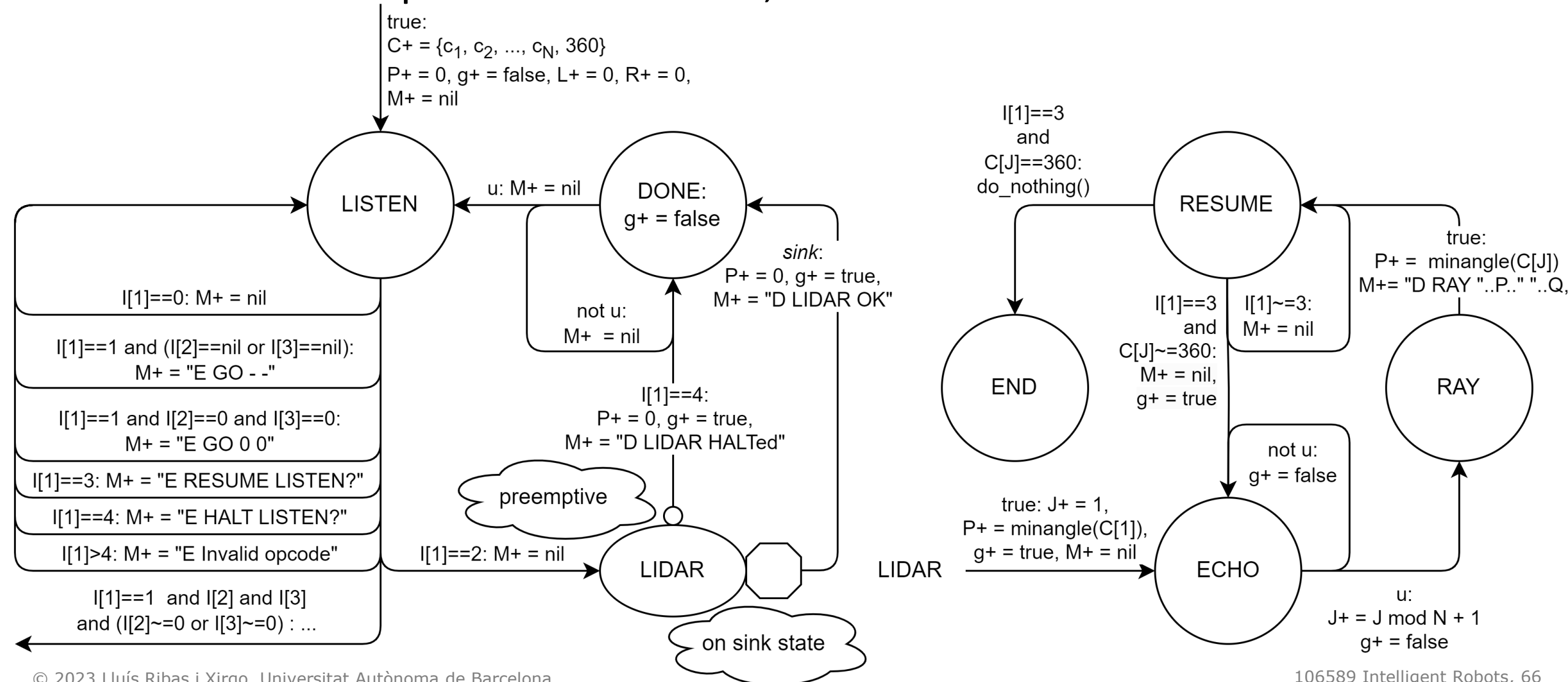
Hierarchical, concurrent EFSM

- Hierarchy minimizes number of arcs w.r.t flat version



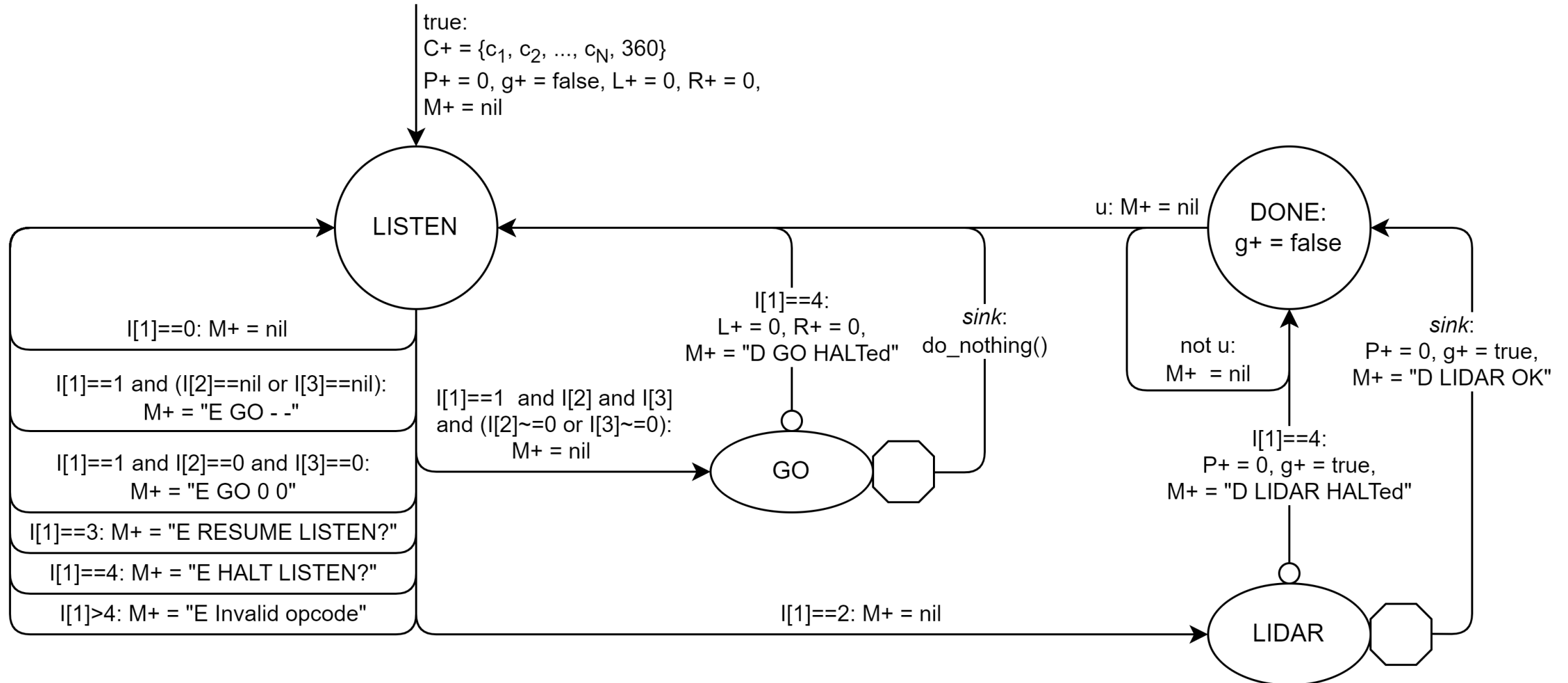
Hierarchical, concurrent EFSM

- Robot basic operations controller, L0Main + LIDAR refinement



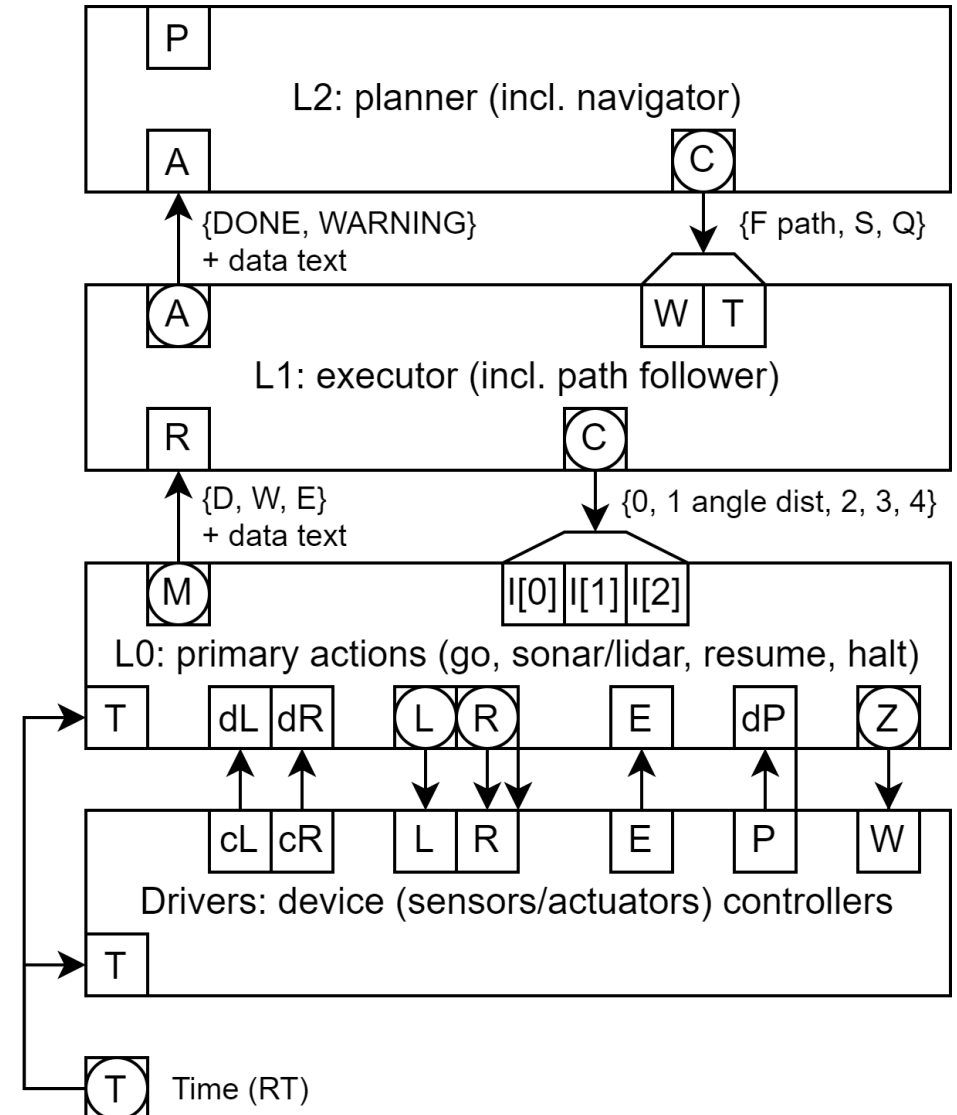
Hierarchical, concurrent EFSM

- Robot basic operations controller, L0Main + **GO refinement**



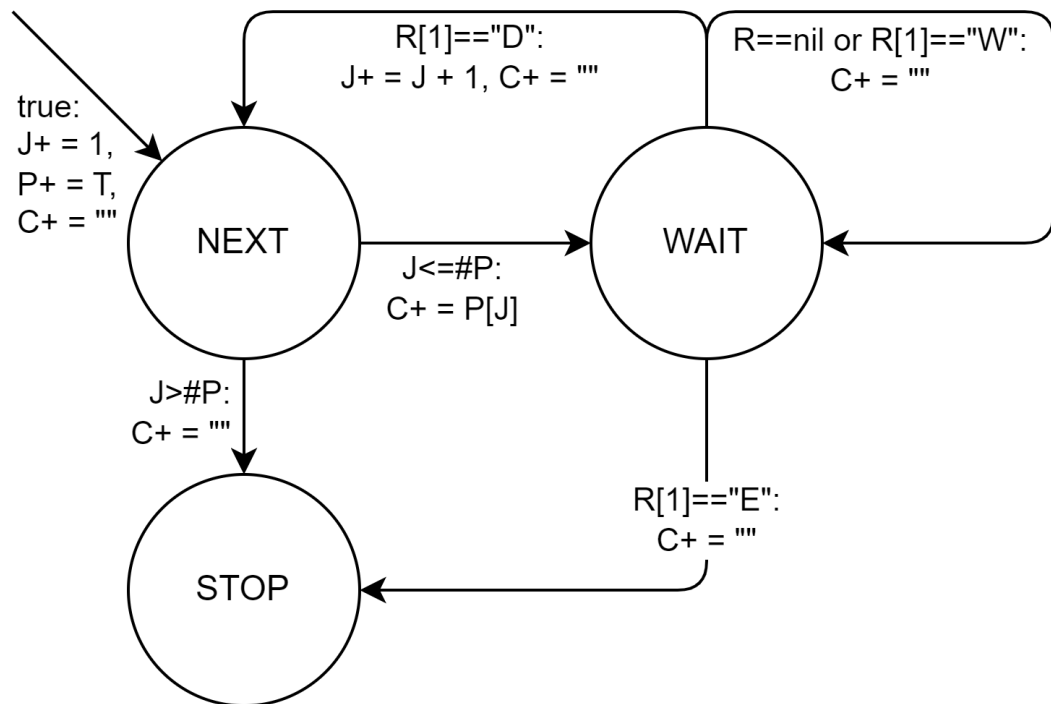
Hierarchical, concurrent EFSM

- Layered architecture
 - Communications' based hierarchy
 - All assignments consistent
 - Need for explicit synchronization protocols



Exercise 6: Path follower implementation

- Path follower



.....
 $R[1] == "a"$ must be replaced by $(R \text{ and } \text{string.sub}(R, 1, 1) == "a")$ in Lua

