



Causal normalizing flows: from theory to practice

Adrián Javaloy

NeurIPS 2023 – Oral

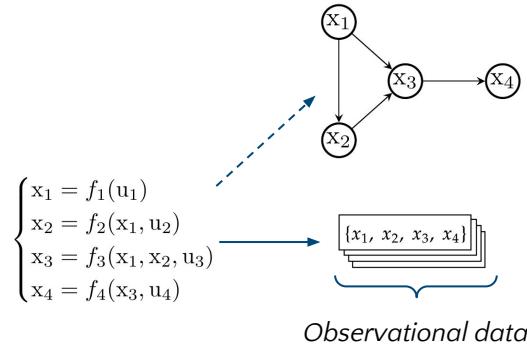
Pablo Sánchez-Martín



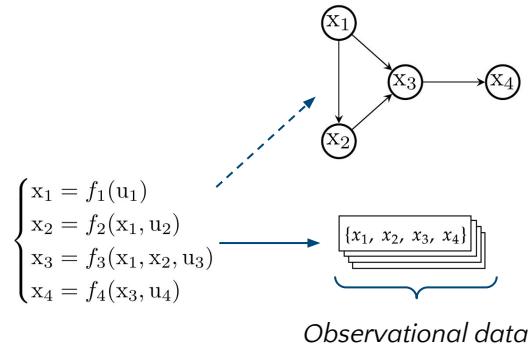
Isabel Valera



Motivation

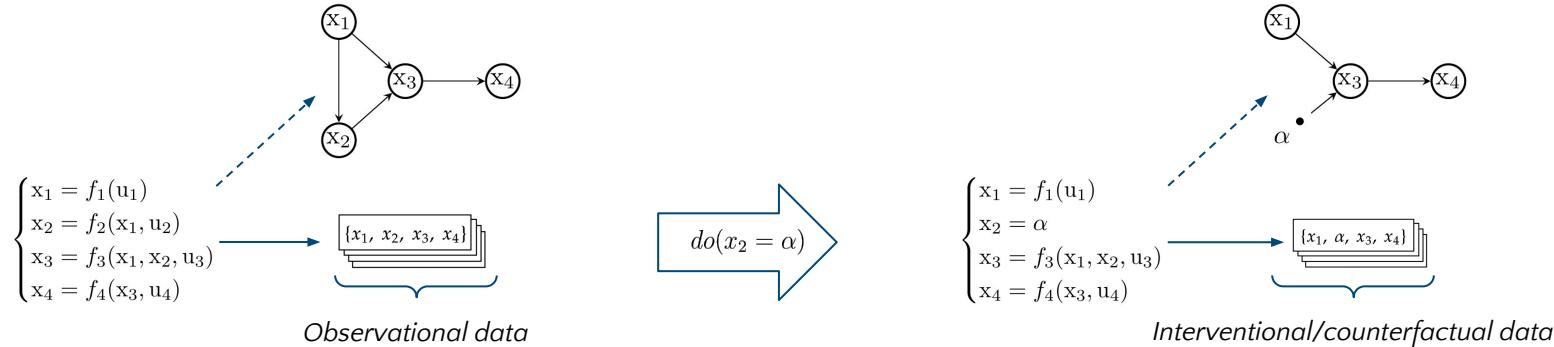


Motivation



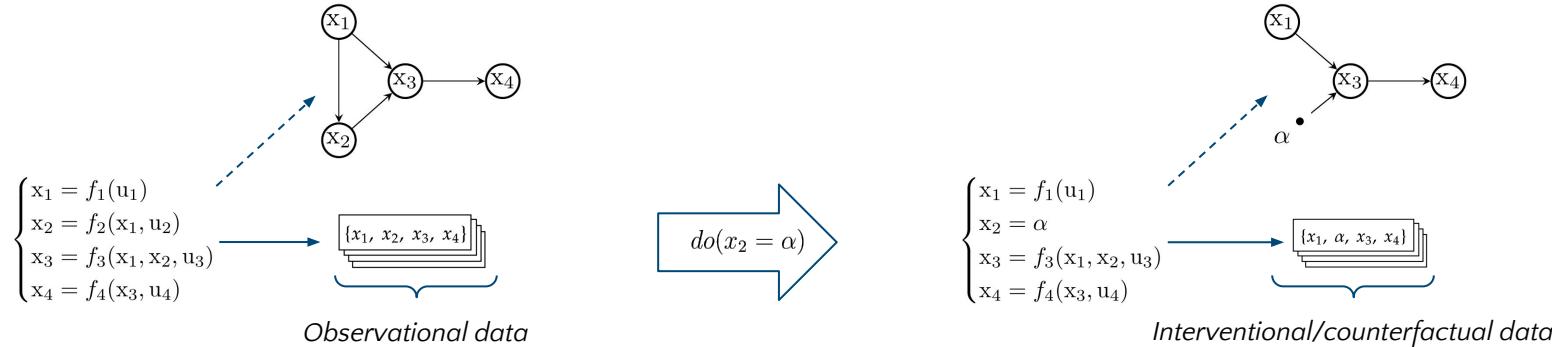
“Will I get my health insurance application approved?”

Motivation



“Will I get my health insurance application approved?”

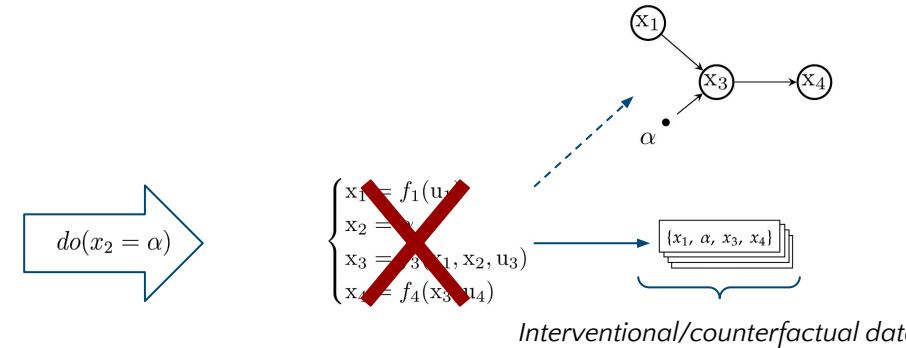
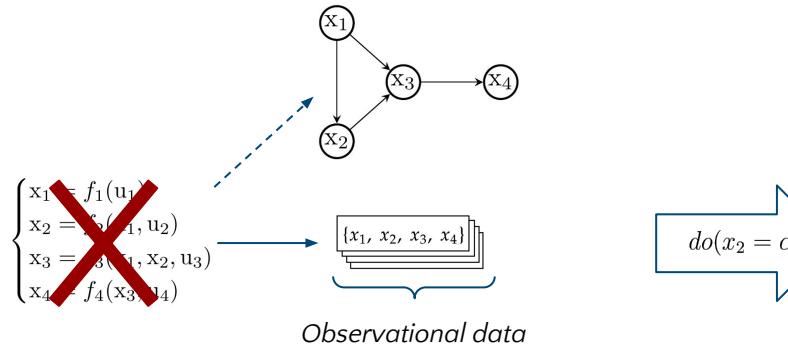
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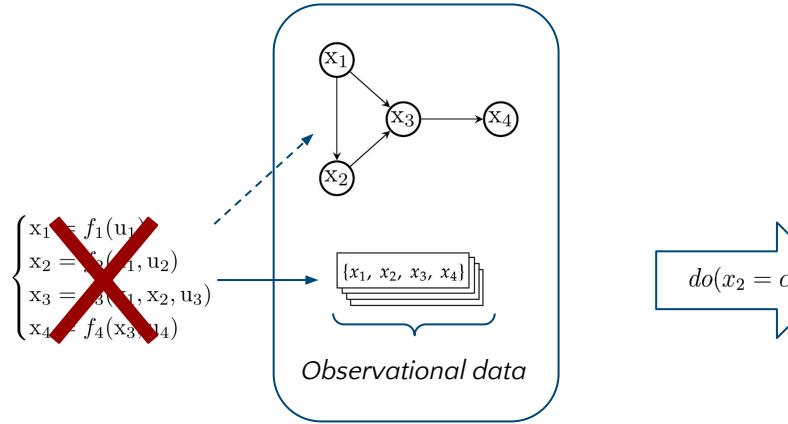
“Will I get my health insurance application approved?”

“I got my application rejected. Would I have gotten it if I were younger?”

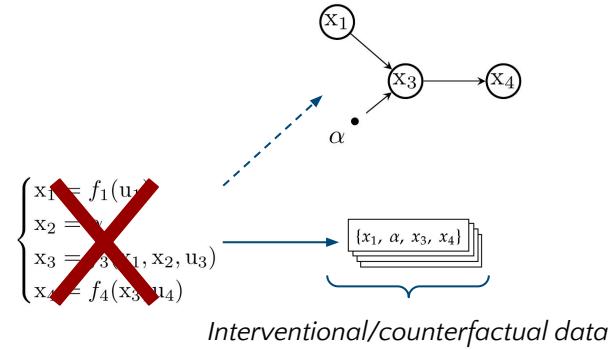
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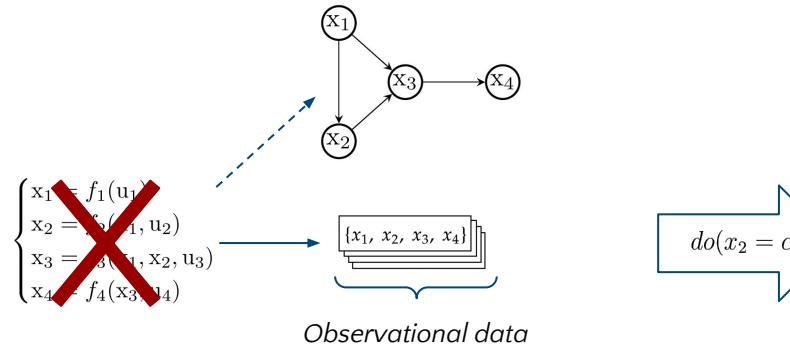
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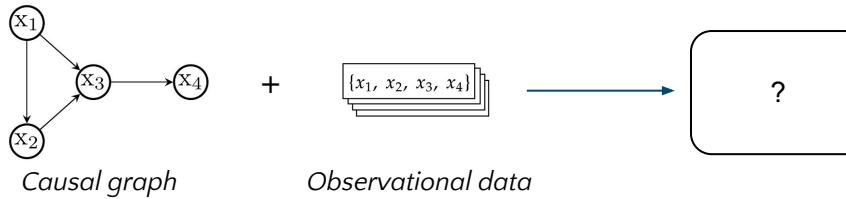
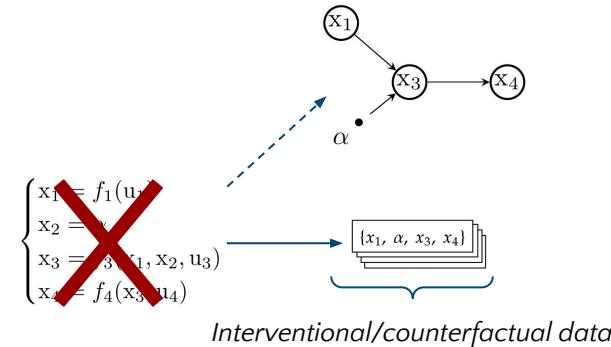
$do(x_2 = \alpha)$



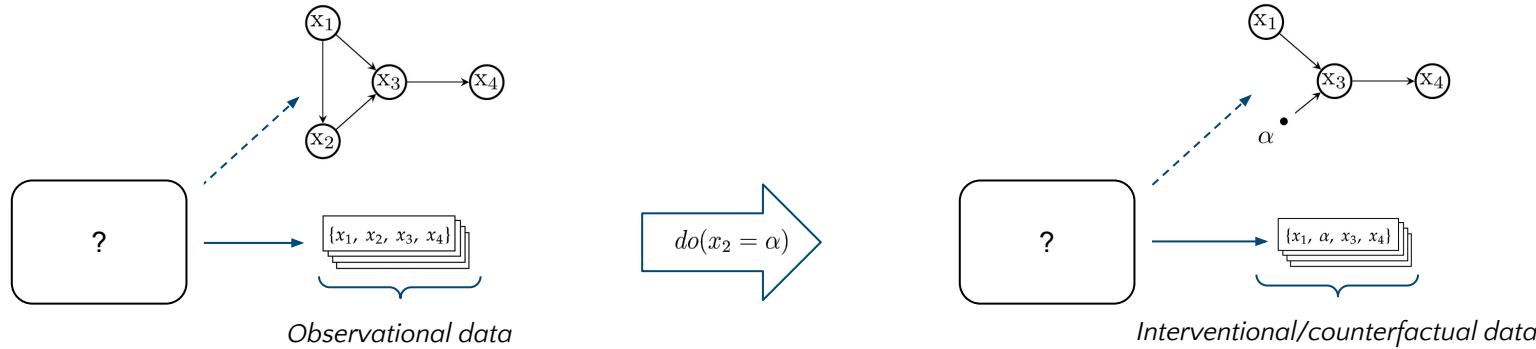
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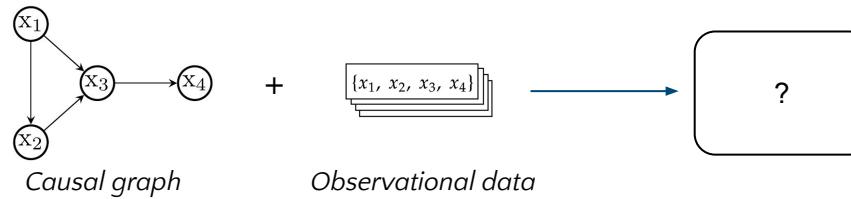
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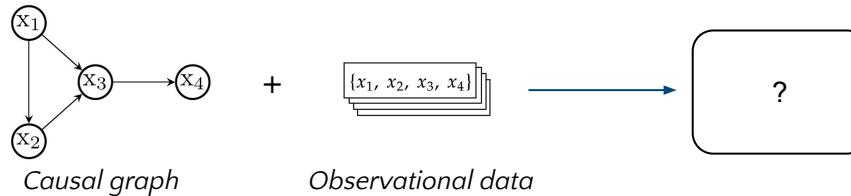
Motivation



How to approach this problem...



How to approach this problem...



1. Model each variable individually:

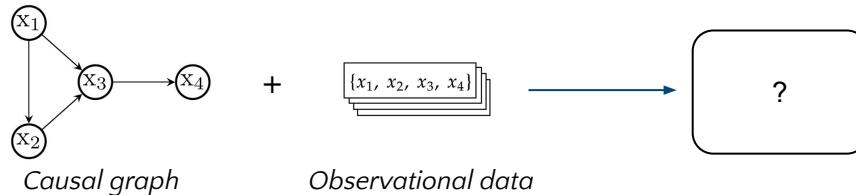
E.g.: a linear function, spline, GP¹, NN², ...

- ✗ Independent functions ✓ Straightforward
- ✗ No amortization ✓ Causally consistent
- ✗ Seq. error propagation ✓ Easy do-operator

[1] Karimi, Amir-Hossein, et al. "Algorithmic recourse under imperfect causal knowledge: a probabilistic approach." *Advances in neural information processing systems* 33 (2020): 265–277.

[2] Parafita, Álvaro, and Jordi Vitrià. "Estimand-Agnostic Causal Query Estimation With Deep Causal Graphs." *IEEE Access* 10 (2022): 71370–71386.

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✗ Independent functions

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2. Model the SCM with a Deep Neural Network.

E.g.: VACA,¹ CAREFL,² ...

✓ Expressive

✗ Without guarantees

✓ Parameter amortization

✗ Complex NN training

✓ Parallel computations
do-operator

✗ Inexact

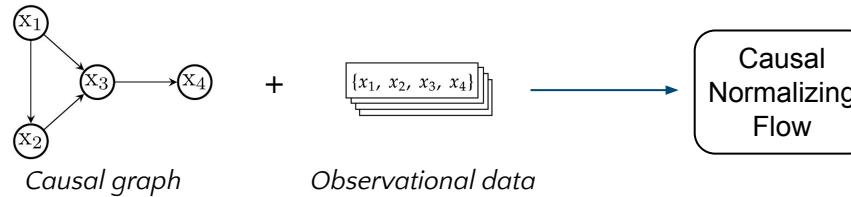
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[3] Sánchez-Martin, P., M. Rateike, and I. Valera. "VACA: Designing Variational Graph Autoencoders for Causal Queries". Proceedings of the AAAI Conference on Artificial Intelligence, vol. 36, no.

[4] Khemakhem, Ilyes, et al. "Causal autoregressive flows." International conference on artificial intelligence and statistics. PMLR, 2021.

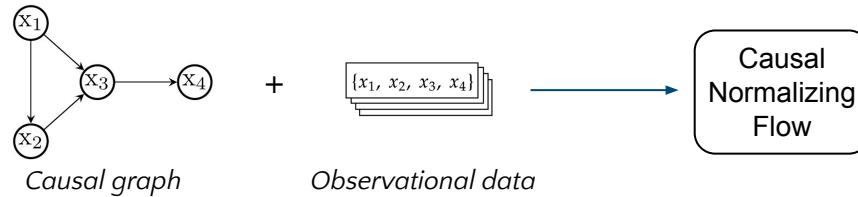
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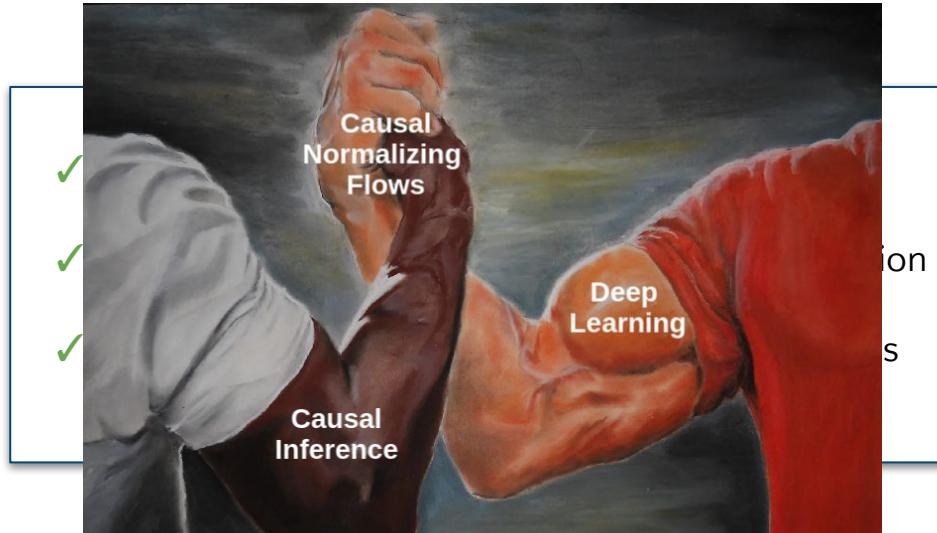
Causal Normalizing Flows:

- ✓ Straightforward ✓ Expressive
- ✓ Causally consistent ✓ Parameter amortization
- ✓ Easy do-operator ✓ Parallel computations

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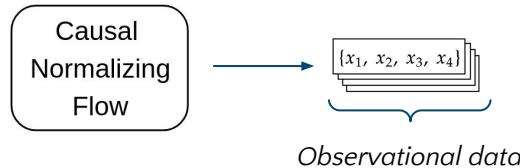
Causal Normalizing Flows:



In a nutshell

Causal
Normalizing
Flow

In a nutshell

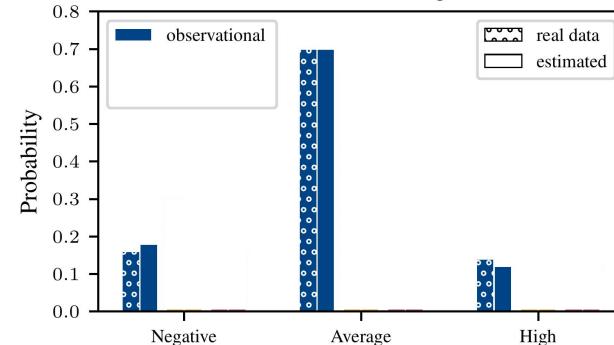


Capabilities

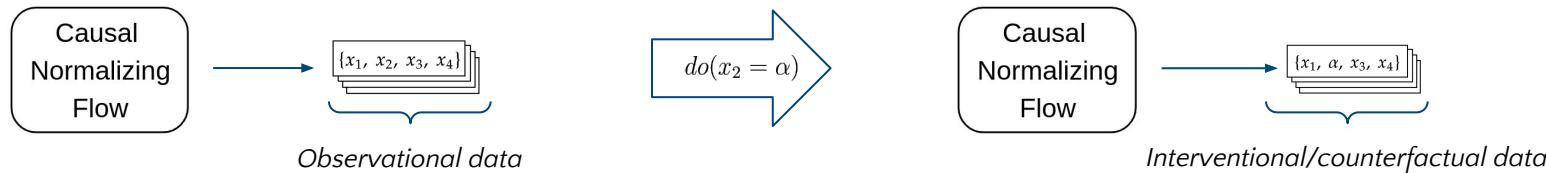
1. Generate observational data.

Objectives

German Credit - Checking account

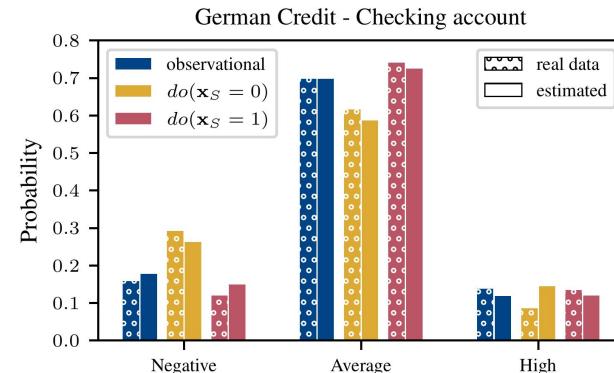


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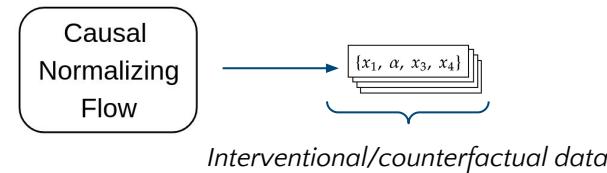
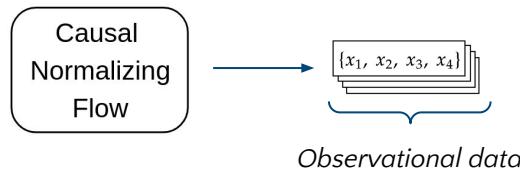


Capabilities

1. Generate observational data.
2. Generate interventional data.
3. Generate counterfactual data.

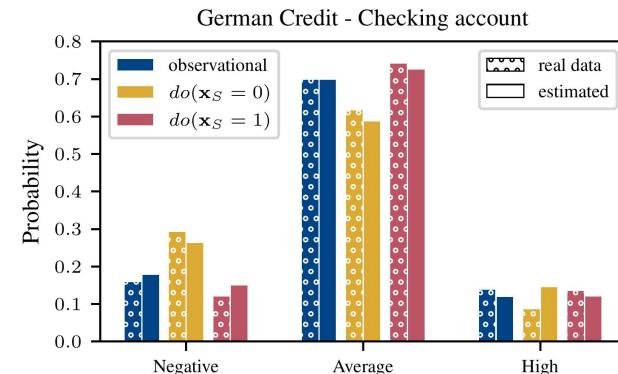


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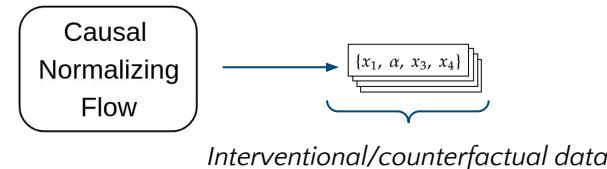
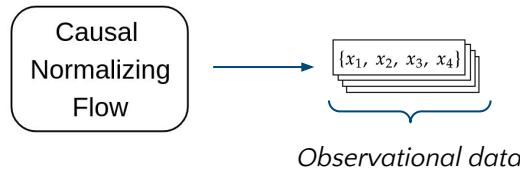


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In a nutshell



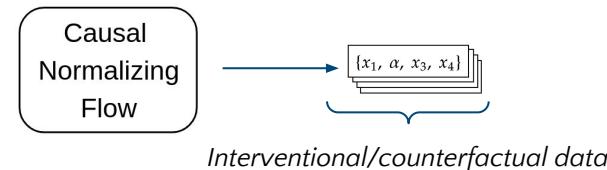
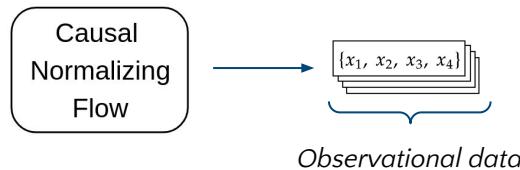
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Objectives

1. Fit the observed data accurately.

In a nutshell

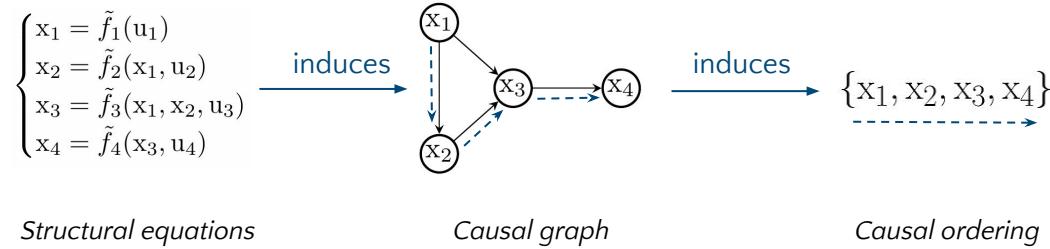


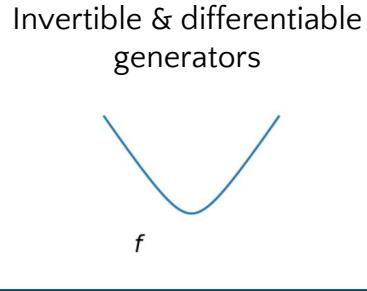
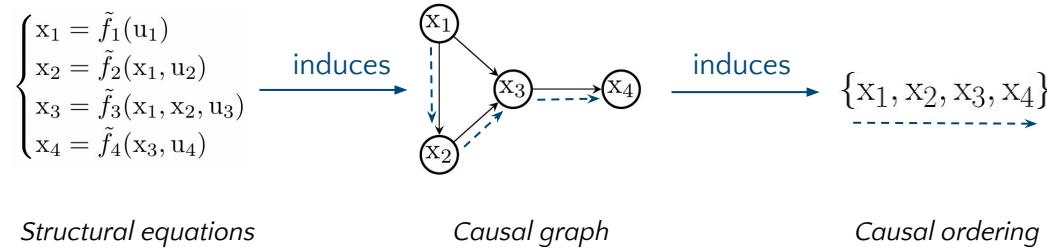
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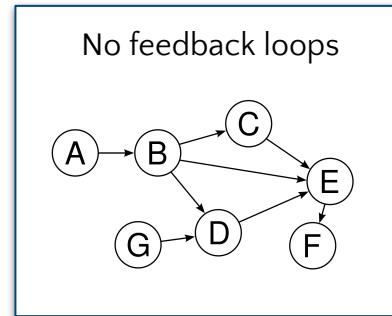
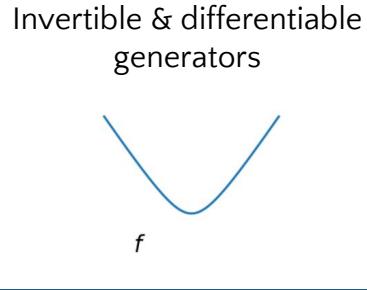
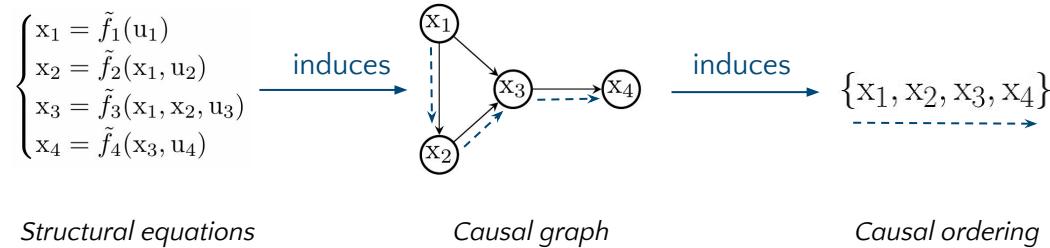
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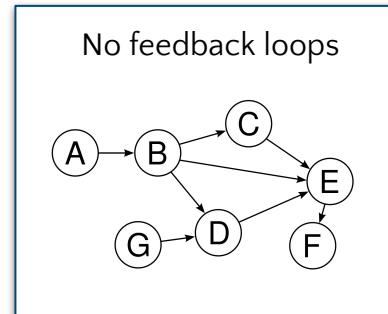
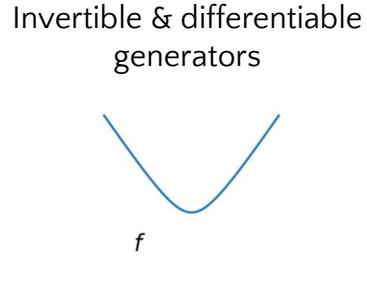
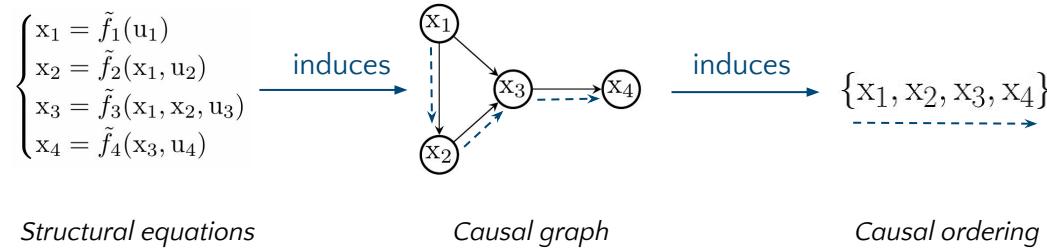
Objectives

1. Fit the observed data accurately.
2. Identify the exogenous variables.
3. Ensure causal consistency wrt. the true SCM.









Causal sufficiency

$$p(\mathbf{u}) = \prod_i p(\mathbf{u}_i)$$

ANFs and SCMs under the same umbrella

SCM→Structural Causal Model

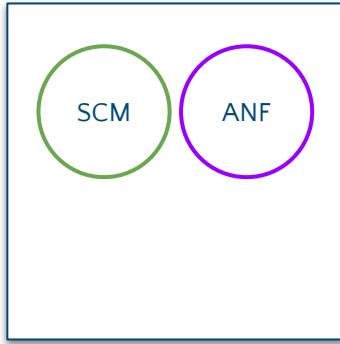
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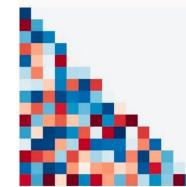
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ANFs:

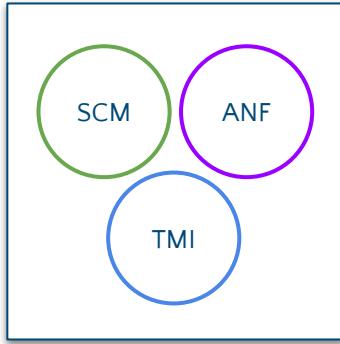
- Invertible differentiable neural networks.
- Transform random variables, $T_\theta(\mathbf{x}) =: \mathbf{u} \sim P_u$.
- Autoregressive and monotonic.



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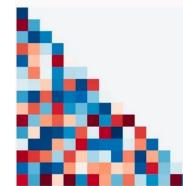
SCM→Structural Causal Model
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TMI→Triangular Monotonic Incr. Map



Triangular Monotonic Increasing (TMI) maps.

$$f(x) = \begin{bmatrix} f_1(x_1) \\ f_2(x_1, x_2) \\ \vdots \\ f_d(x_1, \dots, x_d) \end{bmatrix}$$

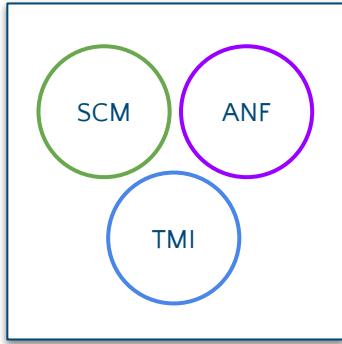
$$\partial_{x_i} f_i(x_1, x_2, \dots, x_i) \geq 0$$



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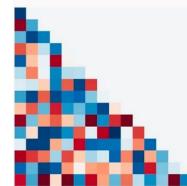
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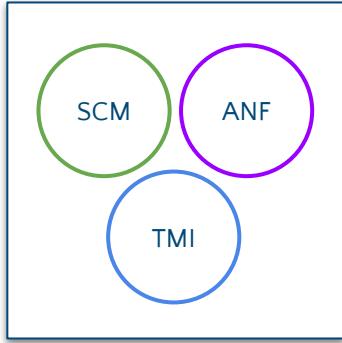
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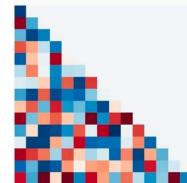
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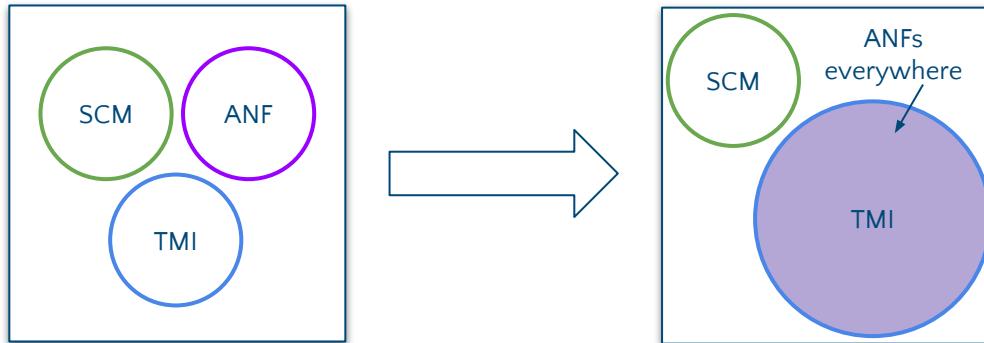
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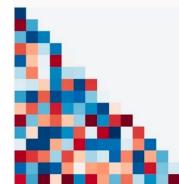
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ANFs are TMI maps
and
universal approximators of any other TMI map.

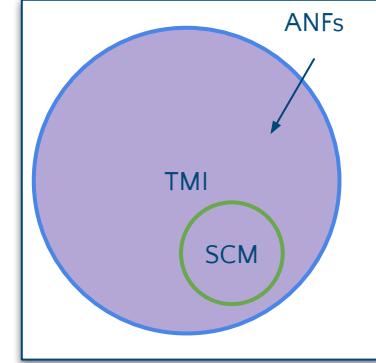
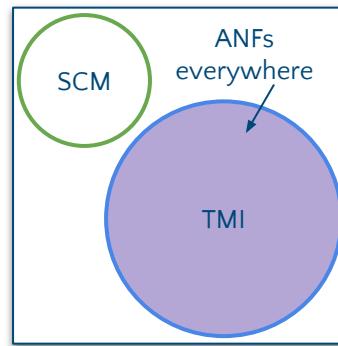
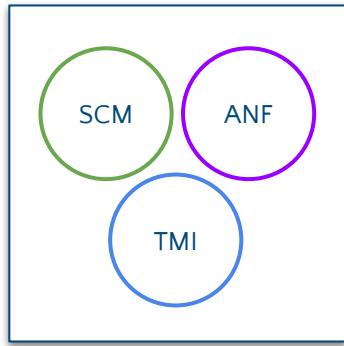


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Structural equations
can be always
unrolled & monotonized

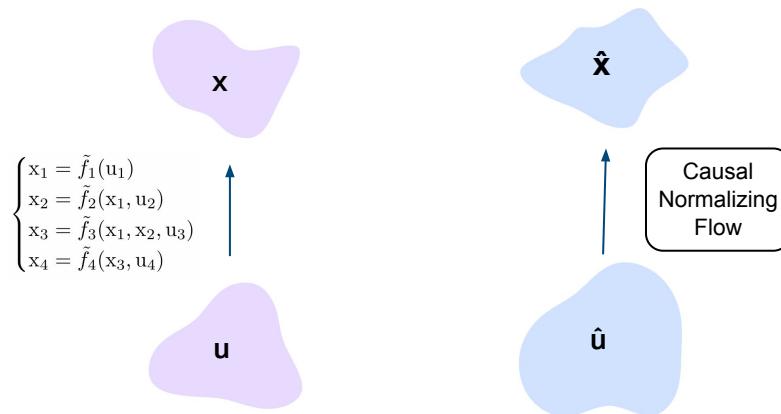
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Isolating the exogenous variables

2. Identify the exogenous variables.

$\mathcal{F} \times \mathcal{P}_\mathbf{u}$ – Family of TMI maps with fully-factorized distributions.

Theorem 1 (Identifiability). If two elements of the family $\mathcal{F} \times \mathcal{P}_\mathbf{u}$ (as defined above) produce the same observational distribution, then the two data-generating processes differ by an invertible, component-wise transformation of the variables \mathbf{u} .



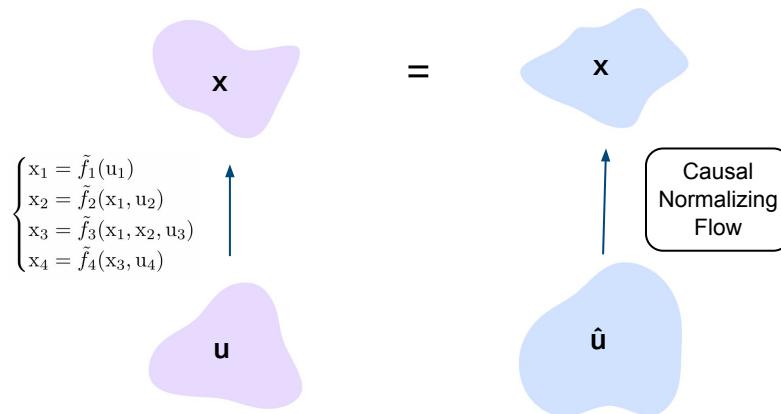
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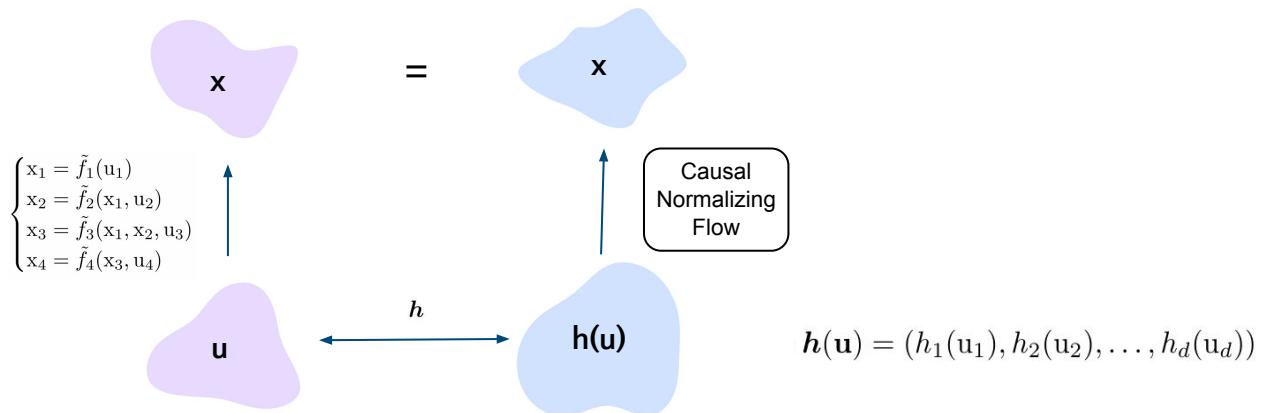
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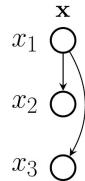
Causal consistency

3. Ensure causal consistency wrt. the true SCM.

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Recursive



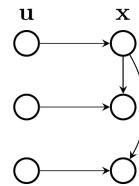
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Recursive



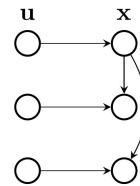
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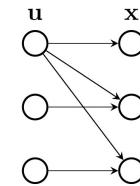
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x

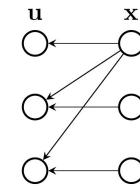
Recursive



Generative



Abductive



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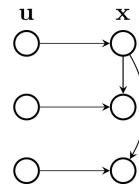
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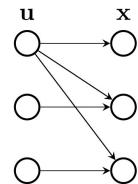
Causal
Normalizing
Flow

\hat{x}

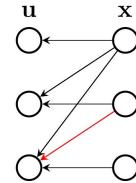
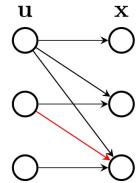
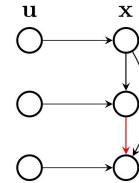
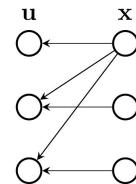
Recursive



Generative



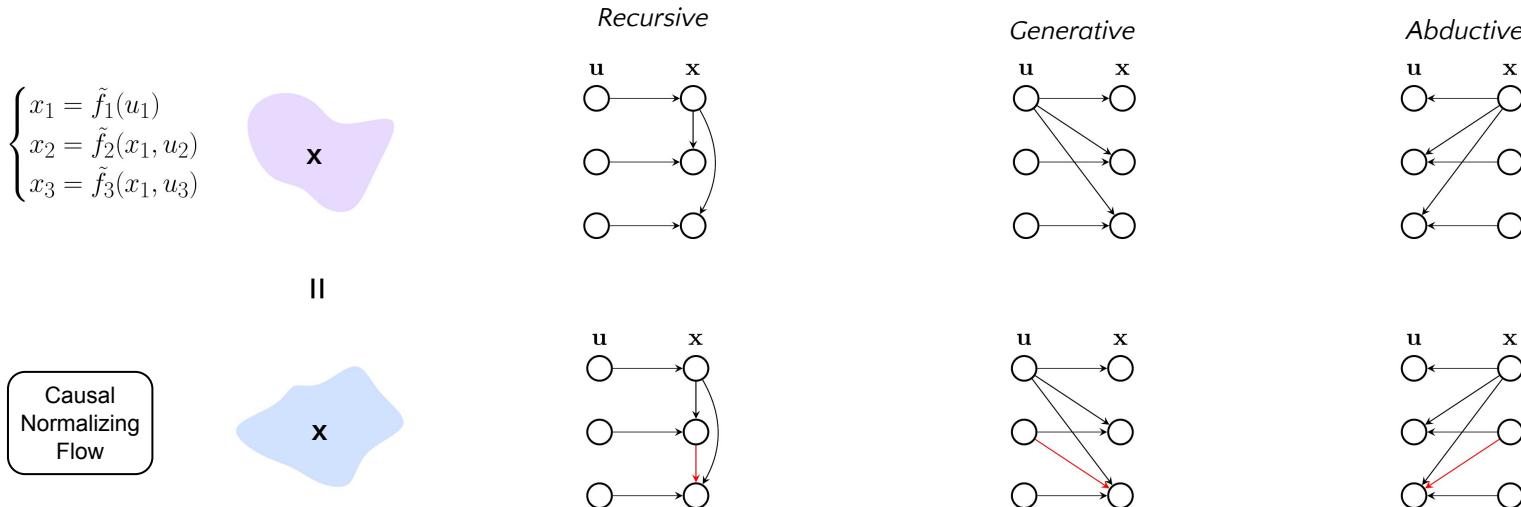
Abductive



Causal consistency

3. Ensure causal consistency wrt. the true SCM.

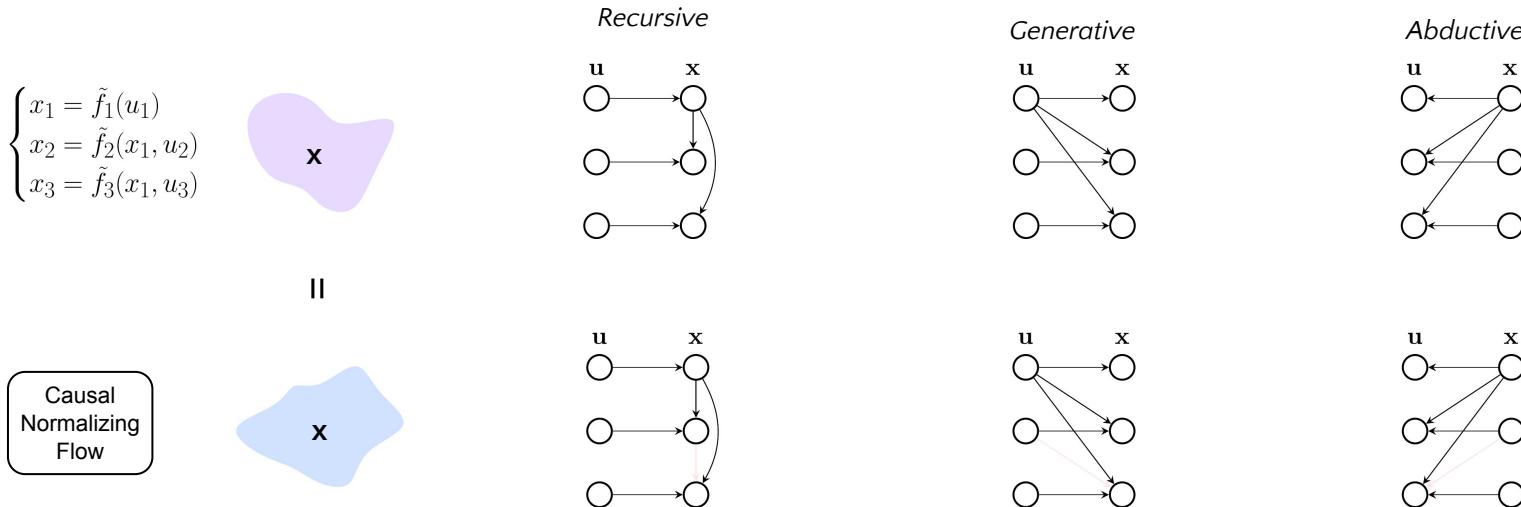
Corollary 2 (Causal consistency). If a causal NF T_θ isolates the exogenous variables of an SCM \mathcal{M} , then $\nabla_{\mathbf{x}} T_\theta(\mathbf{x}) \equiv \mathbf{I} - \mathbf{A}$ and $\nabla_{\mathbf{u}} T_\theta^{-1}(\mathbf{u}) \equiv \mathbf{I} + \sum_{n=1}^{\text{diam}(\mathbf{A})} \mathbf{A}^n$, where \mathbf{A} is the causal adjacency matrix of \mathcal{M} . In other words, T_θ is causally consistent with the true data-generating process, \mathcal{M} .



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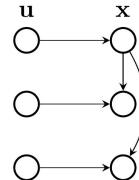


II

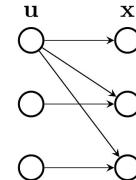
Causal
Normalizing
Flow



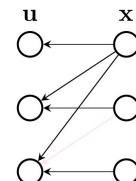
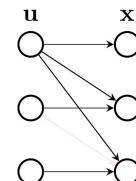
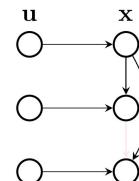
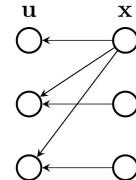
Recursive



Generative



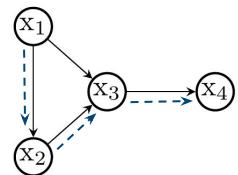
Abductive



Theory vs. practice

In theory...

ANF + causal ordering is enough.



Causal graph

$\{x_1, x_2, x_3, x_4\}$

Causal ordering

Theory vs. practice

In theory...

ANF + causal ordering is enough.

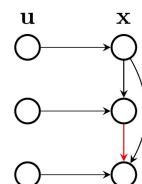


... but in practice ...

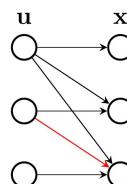
Neural networks ❤️ local optima.



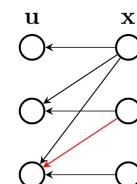
Recursive



Generative



Abductive



Causal
Normalizing
Flow



Theory vs. practice

In theory...

ANF + causal ordering is enough.



... but in practice ...

Neural networks ❤ local optima.



Wait!

With **G** we can design a causally consistent network!



Network design

3. Ensure causal consistency wrt. the true SCM.

	Design Choices		Model Properties		Time Complexity	
	Network Type	Causal Asumption	Causal Consistency		Sampling	Evaluation
			$u \rightarrow x$	$x \rightarrow u$		
Flow direction	$u \rightarrow x$	Generative	Ordering	✗	✗	$\mathcal{O}(L)$
		Generative	Graph G	✓	✗	$\mathcal{O}(L)$
	$x \rightarrow u$	Abductive	Ordering	✗	✗	$\mathcal{O}(dL)$
		Abductive ($L > 1$)	Graph G	✗	✗	$\mathcal{O}(dL)$
		Abductive ($L = 1$)	Graph G	✓	✓	$\mathcal{O}(dL)$

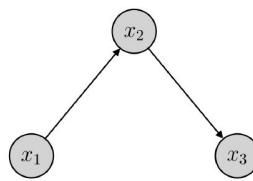
Network design



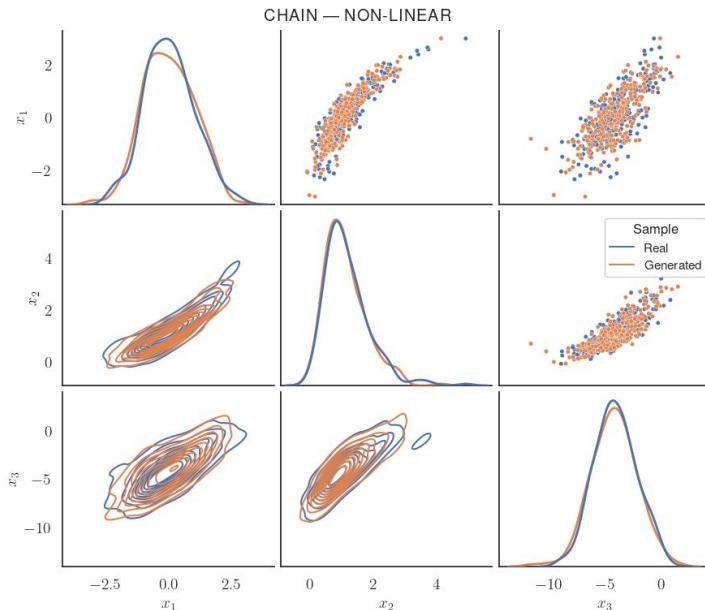
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		Abductive ($L > 1$)	Graph G	✗	✗	$\mathcal{O}(dL)$
		Abductive ($L = 1$)	Graph G	✓	✓	$\mathcal{O}(dL)$

Qualitative results

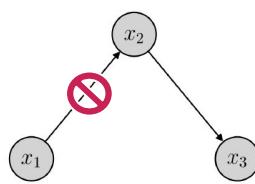


(a) 3-CHAIN

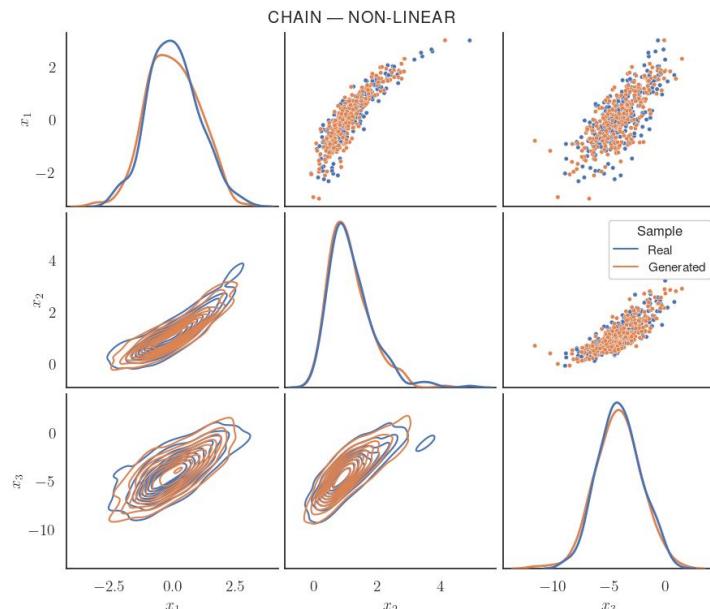


(a) Observational distribution.

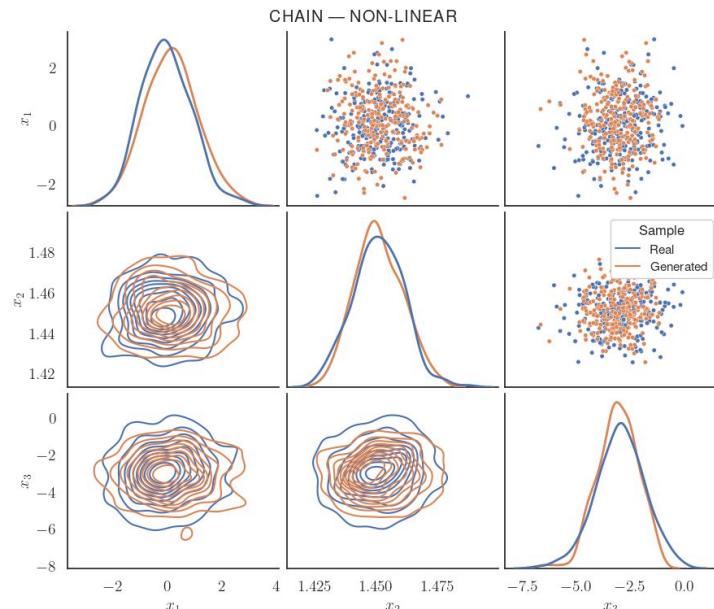
Qualitative results



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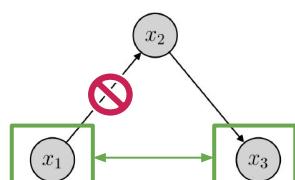


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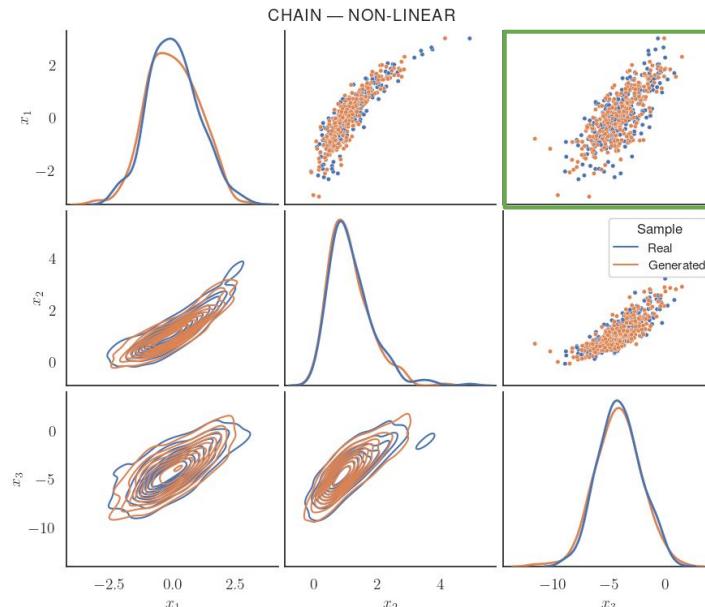


(b) Interventional distribution

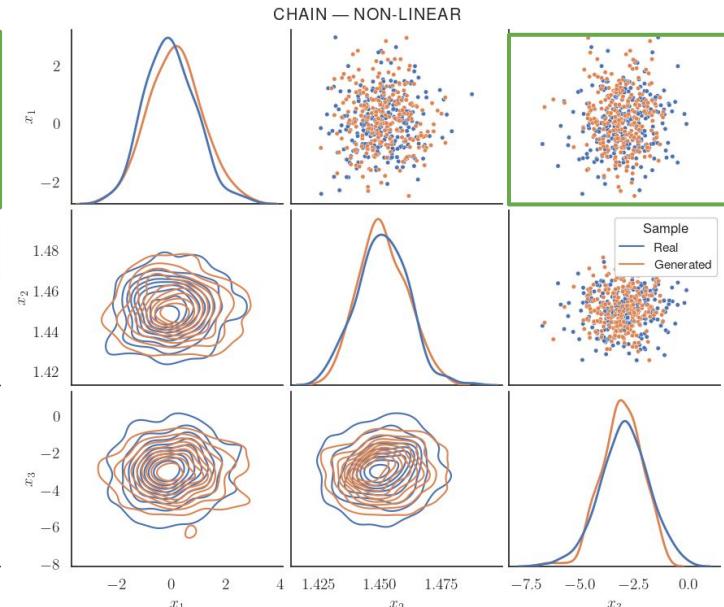
Qualitative results



(a) 3-CHAIN



(a) Observational distribution.



(b) Interventional distribution

Quantitative results

Dataset	Model	Performance			Time Evaluation (μs)		
		Observ.	Interv.	Counter.	Training	Evaluation	Sampling
Fork LIN	CausalNF	0.00 _{0.00}	0.03 _{0.01}	0.01 _{0.00}	0.52 _{0.05}	0.59 _{0.08}	1.57 _{0.57}
	CAREFL [†]	0.00 _{0.00}	0.04 _{0.01}	0.02 _{0.00}	0.60 _{0.17}	0.78 _{0.16}	2.39 _{1.06}
	VACA	8.75 _{0.73}	0.87 _{0.02}	1.43 _{0.02}	45.84 _{4.64}	34.66 _{2.39}	73.29 _{4.70}
LargeBD NLIN	CausalNF	1.51 _{0.04}	0.02 _{0.00}	0.01 _{0.00}	0.52 _{0.10}	0.60 _{0.17}	3.05 _{0.66}
	CAREFL [†]	1.51 _{0.05}	0.05 _{0.01}	0.08 _{0.01}	0.84 _{0.47}	1.18 _{0.17}	8.25 _{1.29}
	VACA	53.66 _{2.07}	0.39 _{0.00}	0.82 _{0.02}	164.92 _{11.10}	137.88 _{15.72}	167.94 _{25.75}
Simpson SYMPROD	CausalNF	0.00 _{0.00}	0.07 _{0.01}	0.12 _{0.02}	0.59 _{0.17}	0.60 _{0.11}	1.51 _{0.30}
	CAREFL [†]	0.00 _{0.00}	0.10 _{0.02}	0.17 _{0.04}	0.49 _{0.15}	0.81 _{0.19}	1.91 _{0.33}
	VACA	13.85 _{0.64}	0.89 _{0.00}	1.50 _{0.04}	49.26 _{4.09}	37.78 _{3.41}	79.20 _{14.60}

12 datasets in the paper!

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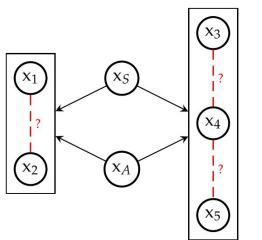
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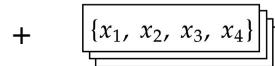
12 datasets in the paper!

Use-case: fairness auditing and classification

German Credit

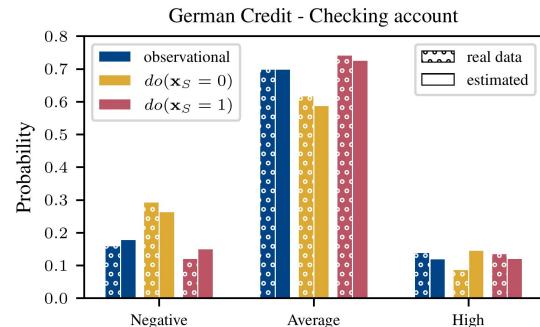


*Partial
Causal graph*



*Mixed-typed
Observational data*

Causal
Normalizing
Flow



Use-case: fairness auditing and classification

	Logistic classifier			SVM classifier		
	full	unaware	fair x	full	unaware	fair x
F1-score	72.28 _{6.16}	72.37 _{4.90}	59.66 _{8.57}	76.04 _{2.86}	76.80 _{5.82}	68.28 _{5.74}
Accuracy	67.00 _{3.83}	66.75 _{2.63}	54.75 _{5.91}	69.50 _{3.11}	71.00 _{3.83}	59.25 _{2.99}

[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Use-case: fairness auditing and classification

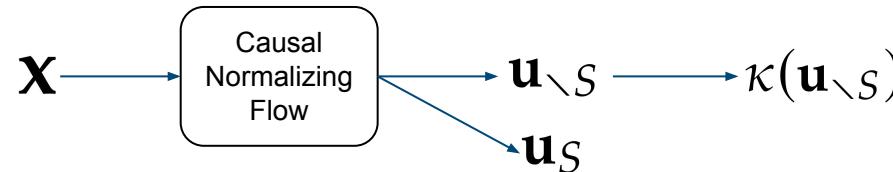
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Unfairness	5.84 _{2.93}	2.81 _{0.72}	0.00 _{0.00}	6.65 _{2.45}	2.78 _{0.40}	0.00 _{0.00}

Causal Normalizing Flow → $\mathbb{E}_{\mathbf{x}^f} [P(\kappa(\mathbf{x}^f) = 1 \mid do(\mathbf{x}_S = 1), \mathbf{x}^f) - P(\kappa(\mathbf{x}^f) = 1 \mid do(\mathbf{x}_S = 0), \mathbf{x}^f)]$

[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Use-case: fairness auditing and classification

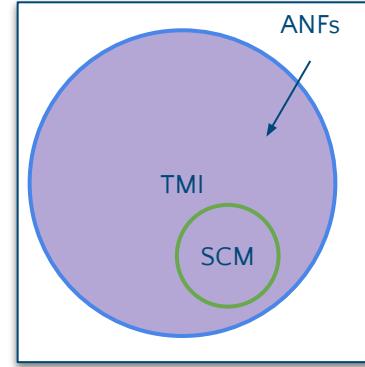
	Logistic classifier				SVM classifier			
	full	unaware	fair x	fair u	full	unaware	fair x	fair u
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Accuracy	67.00 _{3.83}	66.75 _{2.63}	54.75 _{5.91}	66.50 _{3.70}	69.50 _{3.11}	71.00 _{3.83}	59.25 _{2.99}	69.75 _{1.26}
Unfairness	5.84 _{2.93}	2.81 _{0.72}	0.00 _{0.00}	0.00 _{0.00}	6.65 _{2.45}	2.78 _{0.40}	0.00 _{0.00}	0.00 _{0.00}



[1] Kusner, Matt J., et al. "Counterfactual fairness." Advances in neural information processing systems 30 (2017).

Concluding remarks

- Causal normalizing flows are a **natural choice** to learn SCMs.
- We provide **theoretical** results, and practical ways to:
 - **efficiently** capture a causal model, and
 - **exactly** perform causal inference.
- Lots of interesting future work! **Get in touch!**
 - Confounders?
 - Non-bijective generators?
 - Better loss functions?
 - Misspecifications?
 - Applications?





About to
graduate!

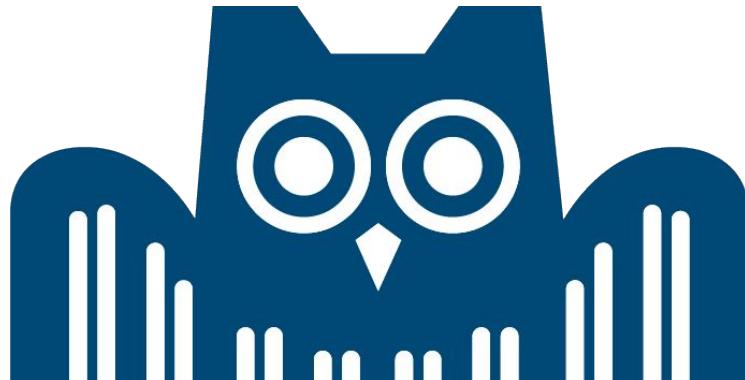
Today at Poster #822

5:15 p.m. – 7:15 p.m



Hiring!

Questions?



X [arxiv: 2306.05415](https://arxiv.org/abs/2306.05415)

G [psanch21/causal-flows](https://github.com/psanch21/causal-flows)

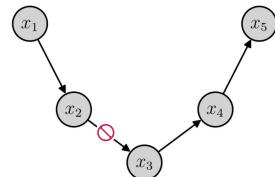
Does it work?



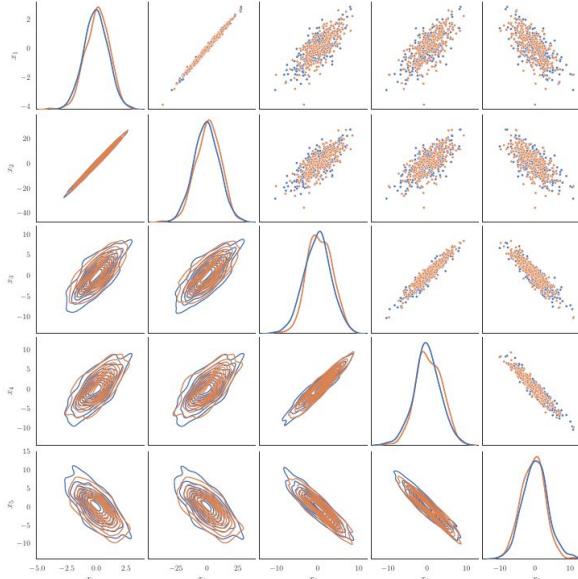
Theoretically: App. C \Rightarrow Intuition: the u_i of the intervened value is set to cancel out the influence of its parents.



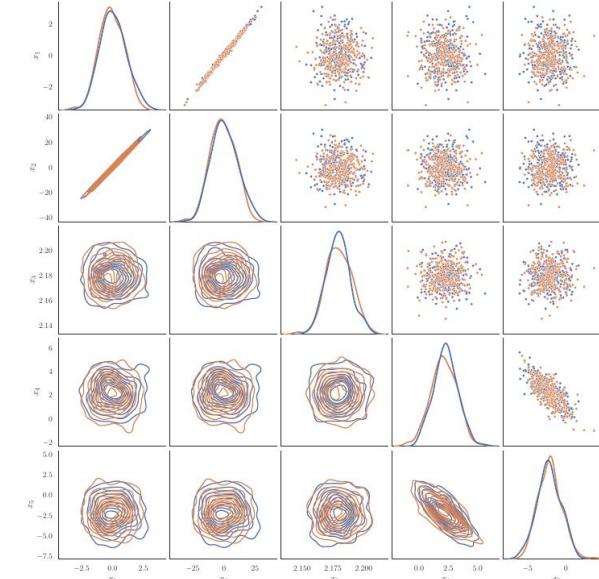
Empirically:



(c) 5-CHAIN



(a) Observational distribution.



(b) Interventional distribution $do(x_3 = 2.18)$.

Structural Causal Models

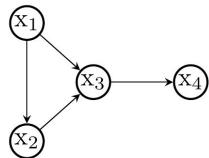
causal generator exogenous distribution

An SCM is a tuple $\mathcal{M} = (\tilde{\mathbf{f}}, P_{\mathbf{u}})$ describing a data-generating process to transform exogenous variables \mathbf{u} into (observed) endogenous variables \mathbf{x} .

$$\mathbf{u} := (u_1, u_2, \dots, u_d) \sim P_{\mathbf{u}}, \quad x_i = \tilde{f}_i(x_{\text{pa}_i}, u_i), \quad \text{for } i = 1, 2, \dots, d.$$

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases} \longrightarrow \boxed{\{x_1, x_2, x_3, x_4\}}$$

- Causal graph



- Adj. matrix

$$\mathbf{G} := \nabla_{\mathbf{x}} \tilde{\mathbf{f}} \neq 0$$

$$\mathbf{G} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

- Causal ordering

$$\pi = (1 \ 2 \ 3 \ 4)$$

We can use SCMs for causal inference, i.e., reason about what-if questions:
How the world would have been if X happened.

$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \alpha \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) \end{cases} \longrightarrow \boxed{\{x_1, \alpha, x_3, x_4\}}$$

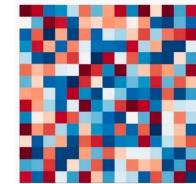
Normalizing flows



An NF is a tuple (T_{θ}, P_u) that express the probability density of observed variables \mathbf{x} as the transformation of base variables \mathbf{u} :

$$T_{\theta}(\mathbf{x}) =: \mathbf{u} \sim P_u \quad \text{with log-density} \quad \log p(\mathbf{x}) = \log p(T_{\theta}(\mathbf{x})) + \log |\det(\nabla_{\mathbf{x}} T_{\theta}(\mathbf{x}))|$$

Learn θ via MLE!



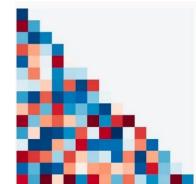
Jacobian

Autoregressive NFs (ANFs) model each layer of the network as:

$$\mathbf{z}_i^l := \tau_i^l(\mathbf{z}_{i-1}^{l-1}; \mathbf{h}_i^l), \quad \text{where} \quad \mathbf{h}_i^l := c_i^l(\mathbf{z}_{1:i-1}^{l-1})$$

transformer
(str. monotonic)

conditioner
(only takes prev. inputs)



Jacobian

SCMs as TMI maps

We can always write an SCM as a TMI map.

1. Unroll the SCM.



$$\begin{cases} x_1 = \tilde{f}_1(u_1) \\ x_2 = \tilde{f}_2(x_1, u_2) = \tilde{f}_2(\tilde{f}_1(u_1), u_2) \\ x_3 = \tilde{f}_3(x_1, x_2, u_3) = \tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3) \\ x_4 = \tilde{f}_4(x_3, u_4) = \tilde{f}_4(\tilde{f}_3(\tilde{f}_1(u_1), \tilde{f}_2(\tilde{f}_1(u_1), u_2), u_3), u_4) \end{cases}$$

2. “Monotonize” the SCM.

Always possible. How? Apply a Knöthe–Rosenblatt (KR) transport following the causal graph:

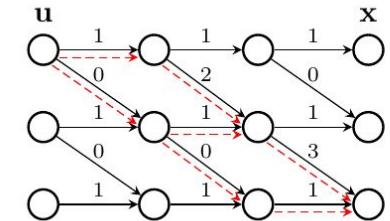
$$K_m(x_{1:m-1}, x_m) = F_\nu^{-1}\{F_\mu(x_m | x_{1:m-1}) \mid K_1(x_1), \dots, K_{m-1}(x_{1:m-1})\}$$

If P_u is a standard uniform distribution \Rightarrow Darmois construction.

Network designs

- Generative networks:
 - Defined from \mathbf{u} to \mathbf{x} .
 - The conditioner only takes the input according to \mathbf{G} .

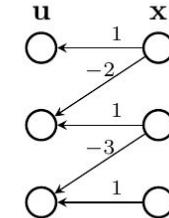
$$\mathbf{z}_i^{l-1} = \tau_i(\mathbf{z}_i^l; \mathbf{h}_i^{l-1}), \quad \text{where} \quad \mathbf{h}_i^{l-1} = c_i(\mathbf{z}_{\text{pa}_i}^l)$$



- Abductive networks:

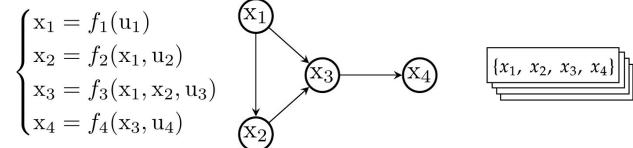
- Defined from \mathbf{x} to \mathbf{u} .
- The conditioner only takes the input according to \mathbf{G} .

$$\mathbf{z}_i^l = \tau_i(\mathbf{z}_i^{l-1}; \mathbf{h}_i^l), \quad \text{where} \quad \mathbf{h}_i^l = c_i(\mathbf{z}_{\text{pa}_i}^{l-1})$$



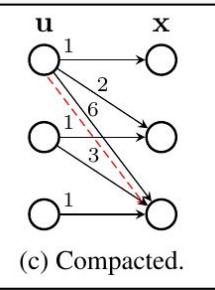
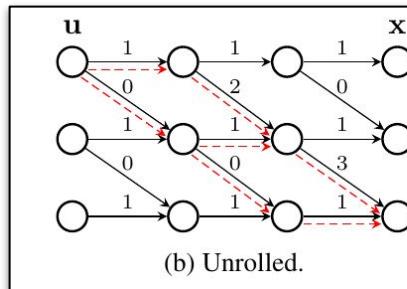
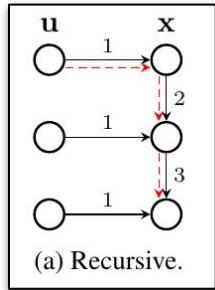
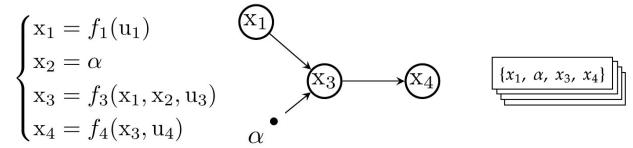
Usual implementation

The do-operator simulates an *external intervention* in the system, breaking any causal relationships going to the intervened node.



The usual implementation yields an intervened SCM with a new set of equations, $\mathcal{M}^{\mathcal{I}} = (\tilde{\mathbf{f}}^{\mathcal{I}}, P_{\mathbf{u}})$

However, it only works for the recursive formulation.



Our implementation

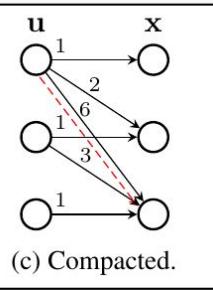
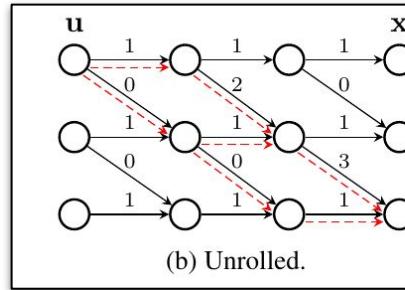
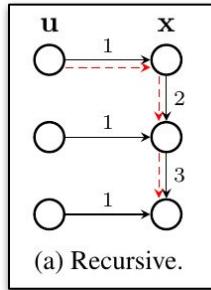
We propose to instead update $P_{\mathbf{u}}$ to put mass only on those values of \mathbf{u} that yield the intervened value, $\mathcal{M}^{\mathcal{I}} = (\mathbf{f}, P_{\mathbf{u}}^{\mathcal{I}})$.

$$p^{\mathcal{I}}(\mathbf{u}) = \delta \left(\left\{ \tilde{f}_i(\mathbf{x}_{\text{pa}_i}, \mathbf{u}_i) = \alpha \right\} \right) \cdot \prod_{j \neq i} p_j(\mathbf{u}_j)$$

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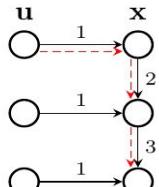
1: function SAMPLEINTERVENEDDIST( $i, \alpha$ )
2:    $\mathbf{u} \sim P_{\mathbf{u}}$ 
3:    $\mathbf{x} \leftarrow T_{\theta}^{-1}(\mathbf{u})$ 
4:    $\mathbf{x}_i \leftarrow \alpha$ 
5:    $\mathbf{u}_i \leftarrow T_{\theta}(\mathbf{x})_i$ 
6:    $\mathbf{x} \leftarrow T_{\theta}^{-1}(\mathbf{u})$ 
7:   return  $\mathbf{x}$ 
8: end function

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The multiple representations of SCMs

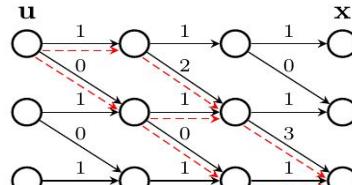
$$\mathbf{x} = \mathbf{G}\mathbf{x} + \mathbf{I}\mathbf{u}$$



(a) Recursive.

$$\begin{cases} x_1 = u_1 \\ x_2 = 2x_1 + u_2 \\ x_3 = 3x_2 + u_3 \end{cases}$$

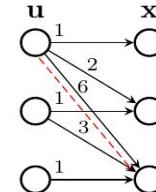
$$\mathbf{x} = \mathbf{G}_3(\mathbf{G}_2(\mathbf{G}_1\mathbf{u}))$$



(b) Unrolled.

$$\begin{cases} z_1^1 = u_1 \\ z_2^1 = u_2 \\ z_3^1 = u_3 \end{cases} \Rightarrow \begin{cases} z_1^2 = z_1^1 \\ z_2^2 = 2z_1^1 + z_2^1 \\ z_3^2 = z_3^1 \end{cases} \Rightarrow \begin{cases} x_1 = z_1^2 \\ x_2 = z_2^2 \\ x_3 = 3z_2^2 + z_3^2 \end{cases}$$

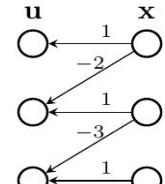
$$\mathbf{x} = (\mathbf{G}^2 + \mathbf{G} + \mathbf{I})\mathbf{u}$$



(c) Compacted.

$$\begin{cases} x_1 = u_1 \\ x_2 = 2u_1 + u_2 \\ x_3 = 6u_1 + 3u_2 + u_3 \end{cases}$$

$$\mathbf{u} = (\mathbf{I} - \mathbf{G})\mathbf{x}$$



(d) Inverted.

$$\begin{cases} u_1 = x_1 \\ u_2 = x_2 - 2x_1 \\ u_3 = x_3 - 3x_2 \end{cases}$$

