

Sprint 1 - Endurance Design Document

April 5, 2021

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1. Executive Summary

1.1 Project Overview

The purpose of this project is for the robot to be able to go through a triathlon course by following the algorithm and the audience would be the class. There are three parts to the triathlon; endurance, accuracy, and agility. Each part of the course gets more difficult.

Product/Service Description

The robot is a sphere and us being used to get around an obstacle course without knocking anything over, light up, and speak. In the first sprint the robot has to be able to go in the shape of a square and also light up and speak.

1.2 Product Context

This product is related to other products because it is a robot and can be managed by different types of coding. For this specific project we are using block code. This robot would be self-contained because everything needed to control it is in the app. The app is what connects it to be able to control it through bluetooth.

1.3 User Characteristics

- Student/faculty/staff/other: students can learn how to use block code, teachers can gain experience by using it to teach.
- experience: gives one experience on computing, especially block code.
- technical expertise
- other general characteristics that may influence the product

1.4 Assumptions

Some assumptions are that this is an easy first part of the triathlon. The equipment availability is pretty easy (using the robotics classroom) because Christina is very available with the room's hours.

1.5 Constraints

- parallel operation with an old system
- audit functions (audit trail, log files, etc.): log files on systems design document
- access, management and security: sign into robotics classroom, figure out time with school
- criticality of the application
- system resource constraints (e.g., limits on disk space or other hardware limitations): save on laptop, in google docs, folders
- other design constraints (e.g., design or other standards, such as programming language or framework)

1.6 Dependencies

- This new product will require a daily download of data from sphero app
- Endurance needs to be completed before we can start the next
- figuring out time to get to the classroom and test out robot

2. Requirements

Functional Requirements

Req#	Requirement	Comments	Priority	Date Rvwd	SME Reviewed / Approved
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ENDUR_01	robot will start with green light and say 'ready, set, go' then move forward to first corner and stop	starts on yellow square with blue tape	1	3/30	approved
ENDUR_02	after stopping robot turns red and says 'I'm done and I need water' then turn right at corner	moves forward then stops	1	3/30	approved
ENDUR_03	robot will move forward to next corner, stop, and turn right	third corner	1	3/30	approved
ENDUR_04	robot will stop at the third corner turn 90 degrees and then move forward	robot should end at beginning corner	1	3/30	approved
ENDUR_05	robot stops at beginning corner	robot ends	1	3/30	approved

2.1 Security

2.1.1 Protection

- encryption: practicing the code and algorithms to encrypt it
- activity logging, historical data sets: keeping track of work
- restrictions on intermodule communications
- data integrity checks

2.1.2 Authorization and Authentication

I did not use any authorization or authentication apps because i didn't feel we needed it for this project since it was simple.

Requirements Confirmation/Stakeholder sign-off

Include documentation of the approval or confirmation of the requirements here. For example:

Meeting Date	Attendees (name and role)	Comments
03/22/2021	Adrianna Lanfranco	confirmed
03/22/2021	Dylan Leray	confirmed.....

3. System Design

This section will provide all details concerning the technical design, staffing, coding, and testing the system

3.1 Algorithm

Develop and describe here the algorithm that will be used to provide the required performance of your software

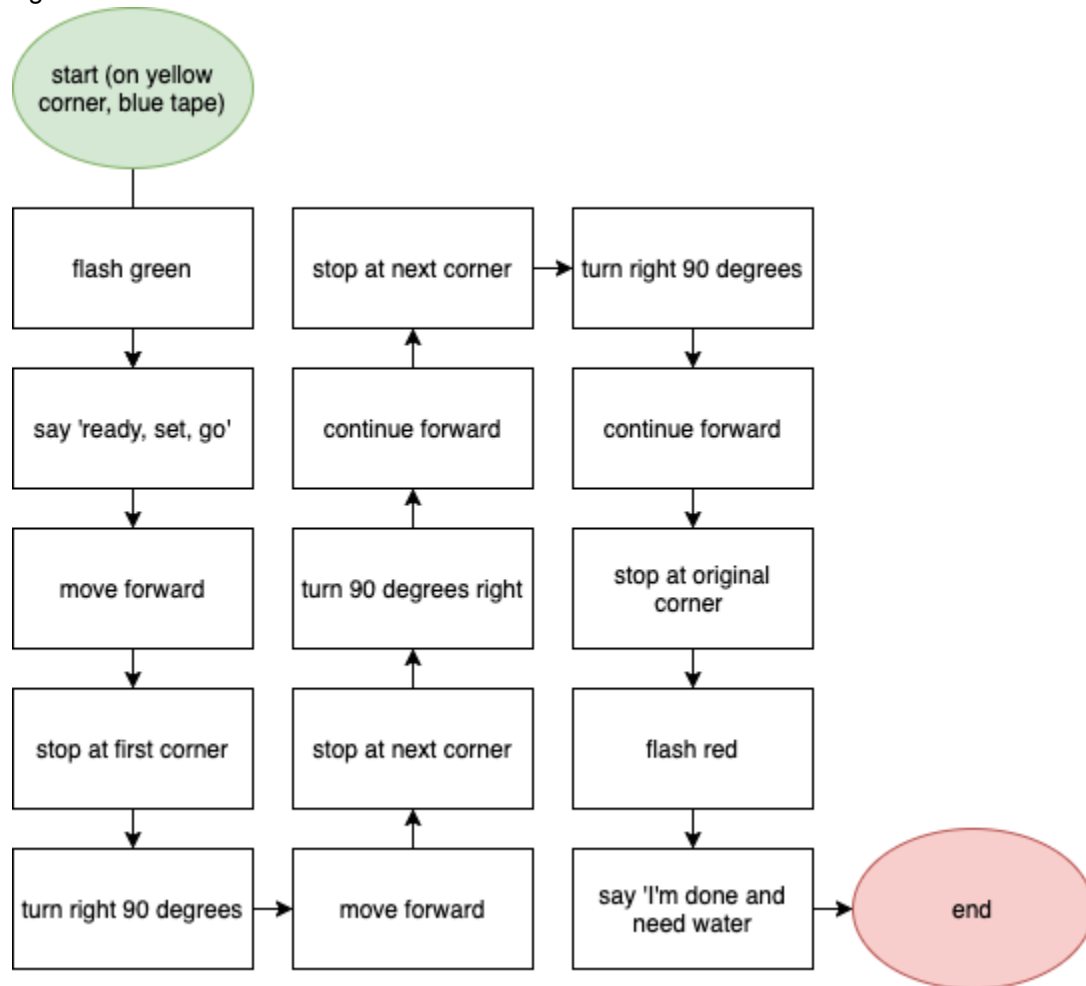
- robot will begin at starting spot
- robot will flash green
- robot will say 'ready, set, go'
- robot will move forward
- robot will stop at first corner
- robot will turn 90 degrees
- robot will move forward
- robot will stop at next corner

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- robot will turn right
- robot will move forward
- robot will turn right at third corner
- robot will move forward
- robot will stop at original corner
- robot will turn red
- robot will speak 'i'm done and need water'
- robot will then completely stop

3.2 System Flow

Develop a flowchart (and show here) that accurately depicts how your software application will act to fulfill the algorithm

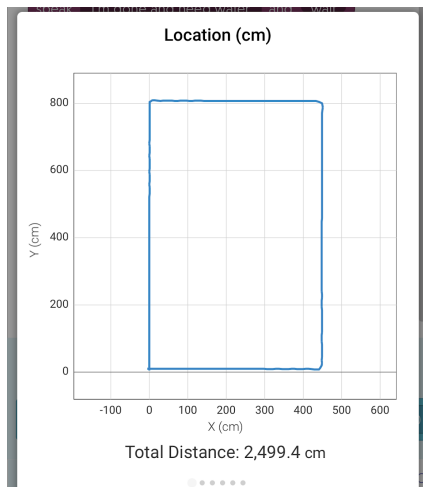


3.3 Software

Describe software languages/platforms/api's used to develop and deploy this application

- Sphero
 - block code

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3.4 Hardware

Describe hardware platforms that were used to develop, test and demonstrate this application

- sphero robot
- adrianna: mac

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3.5 Test Plan

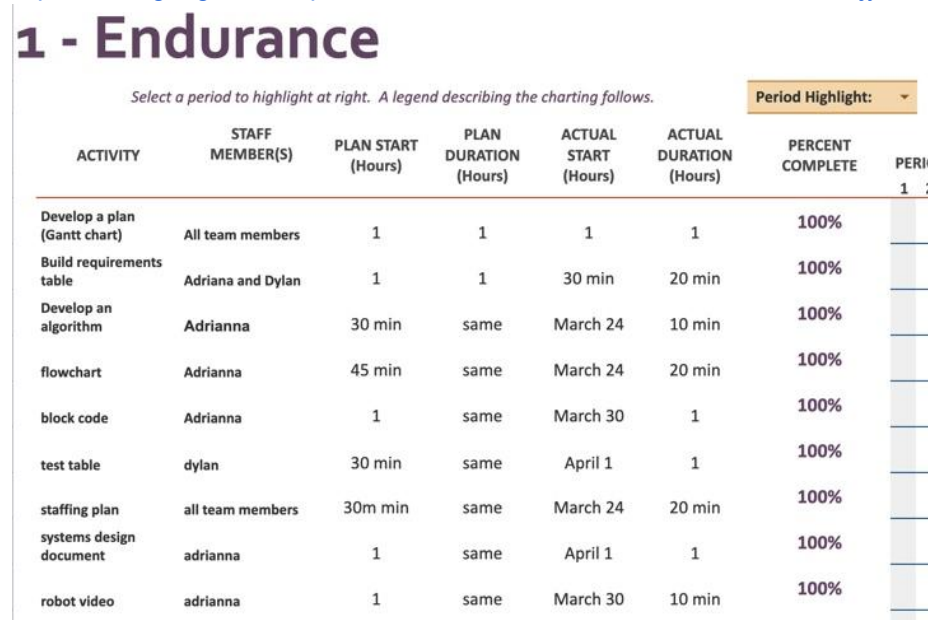
Include a test plan showing all unit tests performed for this application, Include test rational, test date, staff member, pass/fail status

Reason for Test Case	Test Date	Expected Output	Observed Output	Staff Name	Pass/Fail
create code	3/30/21	figure out code	block code	adrianna lanfranco	P
test the code	3/30/21	code to work	took about an hour, robot kept favoring the left side	adrianna lanfranco	P
practice the code multiple times	3/30/21	make sure code works more than one time	took about 20 min	adrianna lanfranco	p
record video	3/30/21	record final video	record video after testing	adrianna lanfranco	P
upload work to system design doc	3/30/21	make sure all documents are included	forgot a few(fixed)	adrianna lanfranco	P

3.6 Task List/Gantt Chart

Embed your gantt chart here

<https://docs.google.com/spreadsheets/d/1mQ2GAyJUJ4ceKCrHbuEUnoJfPLMvCCb/edit#gid=1479078586>



3.7 Staffing Plan

Insert a chart/table that depicts the roles and responsibilities of each team member that worked on this project

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Name	Role	Responsibility	Reports To
adrianna lanfranco	member	flow chart, algorithm, code,video,	all members
dylan leray			