# ADRIANO HENRIQUE ROSSETTE LEITE

### **Automation Engineer**

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### **EXPERIENCE**

### **Robotics Researcher**

#### UNIFEI - Federal University of Itaiubá

March 2010 - April 2018

- ♥ Itajubá, MG, Brazil
- Subject Monitor: Solids Engineering and Robotics Laboratory;
- Scientific Research Initiation in Robotics: Computer Vision and Navigation;
- Science without Borders (CsF) scholar at TTU;
- Expertinos Autonomous Robotics Team member and leader;
- Mobile Autonomous Robotics Challenges and Competitions participant (LARC, CBR, HRATC and RoboCup);
- Awarded the Control and Automation Engineering Student of the year;
- Teaching Internship

## Software Application Developer

#### Cecília Prado Tricot

April 2017 - November 2017

♀ Jacutinga, MG, Brazil

- · Remote work;
- Code versioning using the git tool;
- Java EE 7;
- Local database interactions using the Hibernate framework:
- JSF Graphical components using the Primefaces framework;
- Software engineering applied to design and development of an application for monitoring employees production efficiency.

# **Control and Automation Engineer**

# **HVEX - High Voltage Equipments**

Margardian October 2015 - June 2016

- ♥ Itajubá, MG, Brazil
- Specification and installation of the workshop electric and pneumatic systems;
- Specification and installation of the company camera monitoring
- Design, components purchase and construction of a electric power regulator panel.

# **Human Resources Intern**

#### **Delphi Automotive Systems**

## January 2008 - Agost 2008

- ♀ Jacutinga, MG, Brazil
- Candidate appointment scheduling for the recruitment team;
- Registration of employee in agreements;
- Document delivery and employee signature collection on the production line.

### **SKILLS**

Design Petri Nets State Machine
Graphs Automata Supervisory Contro
Design Patterns
Programming UNIX/Linux Ladder
Matlab/Octave Simulink LabVIEW
SCADA C++ Java Python C#
SQL PROLOG FTEX ROS UML
Assembly Arduino Raspberry Pi
Al Planning Scheduling
Optimization Methods
Computer & Industrial Networks CAN
PROFIBUS Protobuf
Control Analysis & Design
Compensation PID Lead-Lag
Pole Placement State Observer
Discrete Continuous Filtering
Adaptive Predictive Robust

### **IDIOMS**

**English** Italian



# **FORMATION**

M.Sc. in Electrical Engineering Federal University of Itajubá (UNIFEI)

March 2016 - April 2018

B.Sc. in Control and Automation **Engineering** 

Federal University of Itajubá (UNIFEI)

March 2010 - December 2015

B.Sc. in Computer Engineering (extension)

Tennessee Technological University (TTU)

## Agost 2013 - May 2014