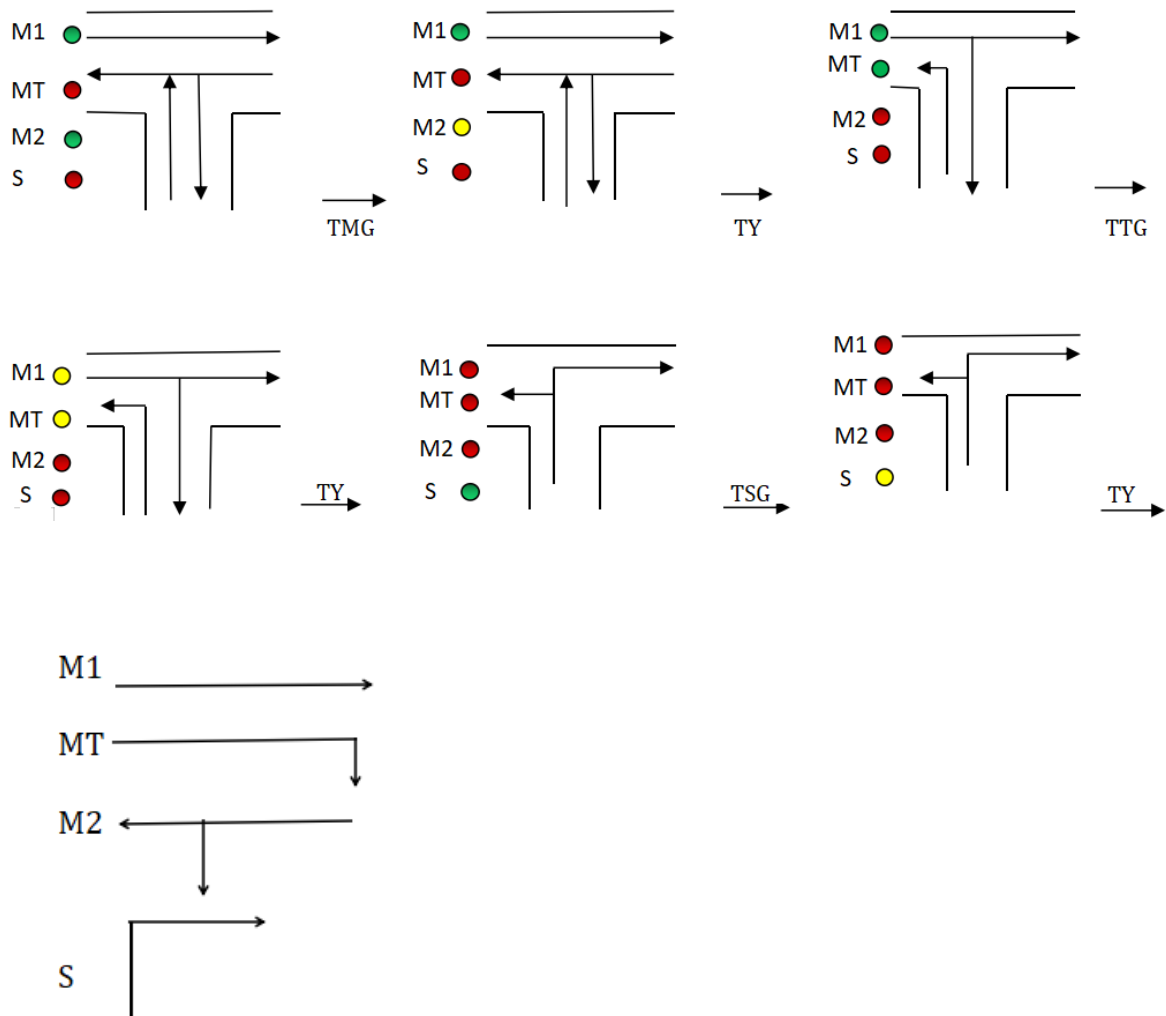


States explained through schematic diagram:



*where the direction of vehicles is explained through this image.

State Transition Table with time delays stated:

| PRESENT STATE | INPUT | NEXT STATE | S T | M1 | M2 | MT | S |
|---------------|-------------------------|------------|-----|-----|-----|-----|-----|
| ABC | | A*B*C* | | RYG | RYG | RYG | RYG |
| 000 | - | 001 | 1 | 000 | 000 | 000 | 000 |
| 001 | $\overline{\text{TMG}}$ | 001 | 0 | 001 | 001 | 100 | 100 |
| | TMG | 010 | 1 | | | | |
| 010 | $\overline{\text{TY}}$ | 010 | 0 | 001 | 010 | 100 | 100 |
| | TY | 011 | 1 | | | | |
| 011 | $\overline{\text{TTG}}$ | 011 | 0 | 001 | 100 | 001 | 100 |
| | TTG | 100 | 1 | | | | |
| 100 | $\overline{\text{TY}}$ | 100 | 0 | 010 | 100 | 010 | 100 |
| | TY | 101 | 1 | | | | |
| 101 | $\overline{\text{TSG}}$ | 101 | 0 | 100 | 100 | 100 | 001 |
| | TSG | 110 | 1 | | | | |
| 110 | $\overline{\text{TY}}$ | 110 | 0 | 100 | 100 | 100 | 010 |
| | TY | 001 | 1 | | | | |
| 111 | - | 000 | 0 | 000 | 000 | 000 | 000 |