

27th
Nov

FOR implication

$$p \rightarrow q$$

• CONVERSE

$$\hookrightarrow p \text{ IAI } q$$

$$q \text{ IAI } p$$

$$q \rightarrow p$$

• INVERSE

\hookrightarrow ubai ma negation

$$\neg p \rightarrow \neg q$$

• CONTRAPOSITIVE

$$\hookrightarrow \neg q \rightarrow \neg p$$

logical
equivalence.

same TT

CONVERSE

\hookrightarrow computed by interchanging the hypothesis & conclusion.

If we have conditional statement $p \rightarrow q$,
the converse is $q \rightarrow p$.

Inverse

↳ Negation of both hypothesis & the conclusion.

If we have conditional statement $p \rightarrow q$ the inverse is $\neg p \rightarrow \neg q$.

Contrapositive

↳ computed by interchanging hypothesis & conclusion of inverse.

If we have conditional statement $p \rightarrow q$ the contrapositive is $\neg q \rightarrow \neg p$.

PROVE contrapositive is logically equivalent to $p \rightarrow q$.

p	q	$\neg p$	$\neg q$	$p \rightarrow q$	$\neg q \rightarrow \neg p$
T	T	F	F	T	T
T	F	F	T	F	F
F	T	T	F	T	T
F	F	T	T	T	T

Among these three conditional statement formed from $p \rightarrow q$, only contrapositive is logically equivalent to $p \rightarrow q$.

e) Bi-conditional or Bi-implication (\leftrightarrow)

Let p & q be two propositions, the bi-conditional statement $p \leftrightarrow q$ is "p if & only if q"

It is true when p & q have same truth values otherwise false.

• Ways to express \leftrightarrow

- (i) p if & only if q
- (ii) p iff q
- (iii) p is necessary & sufficient condⁿ for q
- (iv) if p then q & conversely.

$$p \leftrightarrow q \Leftrightarrow (p \rightarrow q) \wedge (q \rightarrow p)$$

• Truth Table

p	q	$p \leftrightarrow q$
T	T	T
T	F	F
F	T	F
F	F	T

① I go to the beach whenever it is a sunny summer day.

p: It is a sunny summer day

q: I go to the beach.

$p \rightarrow q$

CONVERSE

$q \rightarrow p$

If I go to the beach then it is a sunny summer day.

INVERSE

$\neg p \rightarrow \neg q$

I do not go to the beach whenever it is not a sunny summer day.

CONTRAPOSITIVE

$\neg q \rightarrow \neg p$

If I do not go to the beach then it is not a sunny summer day.

② I will ski tomorrow only if it snows today.

Chap: 2

27th NOV the z-transform

Defⁿ

Let $x(t)$ be a discrete time signal function
define for discrete values of 't' where
 $t = KT$

T ← sampling period

$K = 0, 1, 2, \dots$

Then, the z-transform of $x(t)$ is denoted by
 $Z[x(t)]$ & is defined by

$$Z[x(t)] = Z[x(KT)] = \sum_{K=0}^{\infty} x(KT) z^{-K}$$

$$= X(z)$$

Here,

'z' is complex variable

'Z' is operator of z-transform

yo z ho!!
=

Above expression is also called one sided or unilateral z -transform.

↳ The one-sided or unilateral z -transform of sequence of $x(k)$ or $x(n)$ is given by:

$$Z[x(n)] = \sum_{n=0}^{\infty} x(n) z^{-n} = X(z)$$

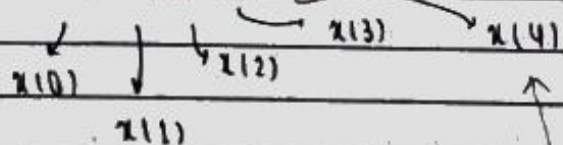
$$Z[x(k)] = \sum_{k=0}^{\infty} x(k) z^{-k} = X(z)$$

where,

' z ' is complex variable

& ' Z ' is operator of z -transform

1. $x(k) = \{1, 8, 4, 3, 7\}$



Its z -transform is

$$\sum_{k=0}^{\infty} x(k) z^{-k}$$

For discrete signal function $x(t)$ where $-\infty < t < \infty$

Then,

$$Z[x(t)] = Z[x(kT)] = \sum_{k=-\infty}^{\infty} x(kT) z^{-k} = X(z)$$

where,

' z ' is complex variable

T is sampling period

' Z ' is operator of z -transform

Above exp is called two-sided or bilateral z -transform

Region of convergence 'ROC'

It is defined as the region where the z -transform of a e^n exists.

The z -transform of sequence $x(k)$ is

$$Z[x(k)] = \sum_{k=0}^{\infty} x(k) z^{-k}$$

ROC is the range of ' z ' for which z -transform converges.

since z -transform is a power series, it converges when $x(k)z^{-k}$ is absolutely summable i.e. finite sum.

stated differently $\sum_{k=0}^{\infty} x(k)z^{-k} < \infty$ must be satisfied for convergence.

• Properties of ROC

- (i) ROC of z -transform is indicated with the circle in the z -plane.
- (ii) ROC can not contain any pole.
- (iii) If $x(k)$ is right sided sequence then ROC extend outward from outermost pole of $X(z)$.

z transform of some std f^n / sequence / signals

(i) unit-step f^n

f^n defined by $u(k) = \begin{cases} 1 & \text{for } k \geq 0 \\ 0 & \text{for } k < 0 \end{cases}$

is unit step f^n .

By defn of z-transform

$$Z[u_k] = \sum_{k=0}^{\infty} u_k z^{-k} = \sum_{k=0}^{\infty} 1 \cdot z^{-k}$$

$$= 1 + z^{-1} + z^{-2} + z^{-3} + \dots$$

$$= 1 + \frac{1}{z} + \frac{1}{z^2} + \frac{1}{z^3} + \dots$$

$$\Rightarrow \frac{1}{1 - \frac{1}{z}} \quad \text{for } \left| \frac{1}{z} \right| < 1$$

$$= \frac{z}{z - 1} \quad \text{for } |z| > 1$$

then,

$$\therefore Z[u_k] = \frac{z}{z - 1}, \quad |z| > 1$$

sum of geometric series.

↳ ROC lies outside of circle $|z| = 1$

② Polynomial f^n

L f^n defined by relation

$$x(k) = \begin{cases} a^n & \text{for } k \geq 0 \\ 0 & \text{for } k < 0 \end{cases}$$

is polynomial f^n

By defn of z-transform

$$Z[x(k)] = \sum_{k=0}^{\infty} x(k) z^{-k}$$

$$= \sum_{k=0}^{\infty} a^k z^{-k}$$

$$= \sum_{k=0}^{\infty} \left(\frac{a}{z}\right)^k$$

$$= 1 + \left(\frac{a}{z}\right)^1 + \left(\frac{a}{z}\right)^2 + \left(\frac{a}{z}\right)^3 + \dots$$

$$\Rightarrow \frac{1}{1 - \frac{a}{z}}$$

$$\frac{1}{z - a}$$

for

$$\left| \frac{a}{z} \right| < 1$$

$$\Rightarrow |z| > |a| \quad \text{for } |z| > 0$$

$$z[n] = \frac{3}{3-0} \quad \text{for } |z| > 0$$

↳ ROC lies outside of circle $|z| = 0$

In particular,

$$Q = 1$$

$$z[1^n] = z[1] = \frac{3}{3-1}$$

$$Q = -1$$

$$z[(-1)^n] = \frac{3}{3+1}$$

③ Exponential f^n

↳ f^n defined by $x(t) = \begin{cases} e^{at} & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases}$

$n \in \mathbb{K} \Rightarrow \text{sequence}$

discrete time signal

$x[n] = \delta[n] \Rightarrow \text{auxiliary}$

is exponential f^n

By defn of z-transform

$$Z[x(t)] = Z[x(n)]$$

$$= \sum_{k=0}^{\infty} x(kT) z^{-k}$$

$$= \sum_{k=0}^{\infty} e^{-a k T} z^{-k}$$

$$= \sum_{k=0}^{\infty} (e^{-aT} z^{-1})^k$$

$$= 1 + (e^{-aT} z^{-1})^1 + (e^{-aT} z^{-1})^2 + \dots$$

$$= \frac{1}{1 - e^{-aT} z^{-1}} = \frac{z}{z - e^{-aT}}$$

$$\therefore z[e^{-aT}] = \frac{z}{z - e^{-aT}}$$

similarly

$$z[e^{aT}] = \frac{z}{z - e^{aT}}$$

\$

$$z[e^{an}] = \frac{z}{z - e^a} \quad \begin{matrix} \text{variable} \\ \text{variable} \end{matrix}$$

$$z[e^{-aK}] = \frac{z}{z - e^{-a}}$$

④ Unit-Impulse or Dirac-Delta fⁿ $\delta(K)$

$$\text{fⁿ defined by } \delta(K) = \begin{cases} 1 & \text{for } K=0 \\ 0 & \text{for } K \neq 0 \end{cases}$$

is Dirac-Delta fⁿ

By defⁿ,

$$z[\delta(K)] = \sum_{K=0}^{\infty} \delta(K) z^{-K}$$

$$= \delta(0) + \delta(1)z^{-1} + \delta(2)z^{-2} + \dots$$

$$= 1 + 0 + 0 + 0 \dots$$

$$= 1$$

$$\therefore z[\delta(K)] = 1$$

⑤ Unit-Ramp fⁿ

$$\text{fⁿ defined by } x(t) = \begin{cases} t & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases} \text{ is}$$

Unit-Ramp fⁿ

⑥ sinusoidal fⁿ

L fⁿ defined by $x(t) = \begin{cases} \sin \omega t & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases}$

is sinusoidal fⁿ

Z-transform of t^n where 'n' is the integer

Soln

$$\text{let } x(t) = t^n$$

$$x(kt) = (kt)^n$$

\downarrow
t ayese kt ie replace

By defⁿ of Z-transform

$$Z[x(t)] = Z[x(kt)]$$

$$= \sum_{k=0}^{\infty} x(kt) z^{-k}$$

$$= X(z)$$

$$\therefore Z[t^n] = \sum_{k=0}^{\infty} (kt)^n z^{-k} = X(z) \quad \text{L ii)$$

similarly,

$$Z[t^{n+1}] = \sum_{k=0}^{\infty} (kT)^{n+1} z^{-k}$$

now,

diff. both sides w.r.t. 'z', we get

$$\frac{d}{dz} [Z[t^{n+1}]] = \frac{d}{dz} \left[\sum_{k=0}^{\infty} (kT)^{n+1} z^{-k} \right]$$

$$= \sum_{k=0}^{\infty} (kT)^{n+1} \frac{d}{dz} (z^{-k})$$

$$= \sum_{k=0}^{\infty} (kT)^{n+1} (-k) z^{-k-1}$$

$$= \sum_{k=0}^{\infty} \frac{(kT)^{n+1}}{kT} \frac{(-k) z^{-k}}{z}$$

$$= -\frac{1}{Tz} \sum_{k=0}^{\infty} (kT)^n z^{-k}$$

$$\frac{d}{dz} [z(t^{n-1})] = \frac{-1}{Tz} \times (z) \quad [\text{from eqn (i)}]$$

$$\Rightarrow X(z) = -Tz \frac{d}{dz} [z(t^{n-1})]$$

$$\therefore z(t^n) = -Tz \frac{d}{dz} [z(t^{n-1})]$$

Put $n=1$

$$z(t) = -Tz \frac{d}{dz} [z(t^0)]$$

$$= -Tz \frac{d}{dz} [z(1)]$$

$$\frac{z}{z-1}$$

$$= -Tz \frac{d}{dz} \left(\frac{z}{z-1} \right)$$

$$= -Tz \frac{(z-1) \cdot 1 - z \cdot 1}{(z-1)^2}$$

$$= -Tz \left(\frac{z-1-z}{(z-1)^2} \right)$$

$$Z(t) = \frac{Tz}{(z-1)^2}$$

Put $n=2$

$$Z(t^2) = -Tz \frac{d}{dz} [Z(t)] \quad \therefore Z(t) = -Tz \frac{d}{dz} \left[\frac{Tz}{(z-1)^2} \right]$$

$$= -T^2 z \frac{d}{dz} \left[\frac{z}{(z-1)^2} \right]$$

$$= -T^2 z \frac{(z-1)^2 \cdot 1 - z \cdot 2(z-1) \cdot 1}{(z-1)^4}$$

$$= -T^2 z \frac{(z-1)^2 - 2z(z-1)}{(z-1)^4}$$

$$= -T^2 z \frac{(z-1) [(z-1) - 2z]}{(z-1)^4}$$

$$= \frac{-T^2 z [z-1-2z]}{(z-1)^3}$$

$$= \frac{-T^2 z [-1-z]}{(z-1)^3}$$

$$\therefore Z(t^2) = \frac{T^2 z [z+1]}{(z-1)^3}$$

similarly,
we obtain

$$Z[K^n] = -3 \cdot \frac{d}{dz} Z[K^{n-1}]$$

T hat x0

$$Z[K] = \frac{3}{(3-1)^2}$$

$$Z[K^2] = \frac{3(3+1)}{(3-1)^3}$$