



TACTICAL DIGITAL TWIN  
RL FOR FOOTBALL STRATEGY

# Tactical Digital Twin in Football

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# Problem introduction

Modern football analytics mainly focuses on **descriptive, post-match metrics.**

However, tactical decisions depend on **contextual, multi-player interactions** that are poorly represented by traditional, player-centric metrics.



Our challenge is to study these interactions through **controlled simulations**, enabling the evaluation of **alternative tactical decisions** in simplified football scenarios.



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# Value proposition

This project supports **Goal 9 (Industry, Innovation, and Infrastructure)** by promoting cutting-edge AI applications in the sports engineering sector, helping to improve infrastructure and innovation in performance optimization technologies.





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# Objectives



**Develop a reproducible framework** (digital twin) under realistic constraints, using real or synthetic data



Apply AI techniques to **simulate and optimize tactical behaviors**



Integrate real tracking or event data for **validation and calibration**



**Design evaluation metrics** to assess tactical effectiveness and realism



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# Research questions

**Counterfactual Reproducibility:** To what extent can agents trained via Proximal Policy Optimization (PPO) successfully resolve high-leverage tactical scenarios extracted from real-world historical event data?

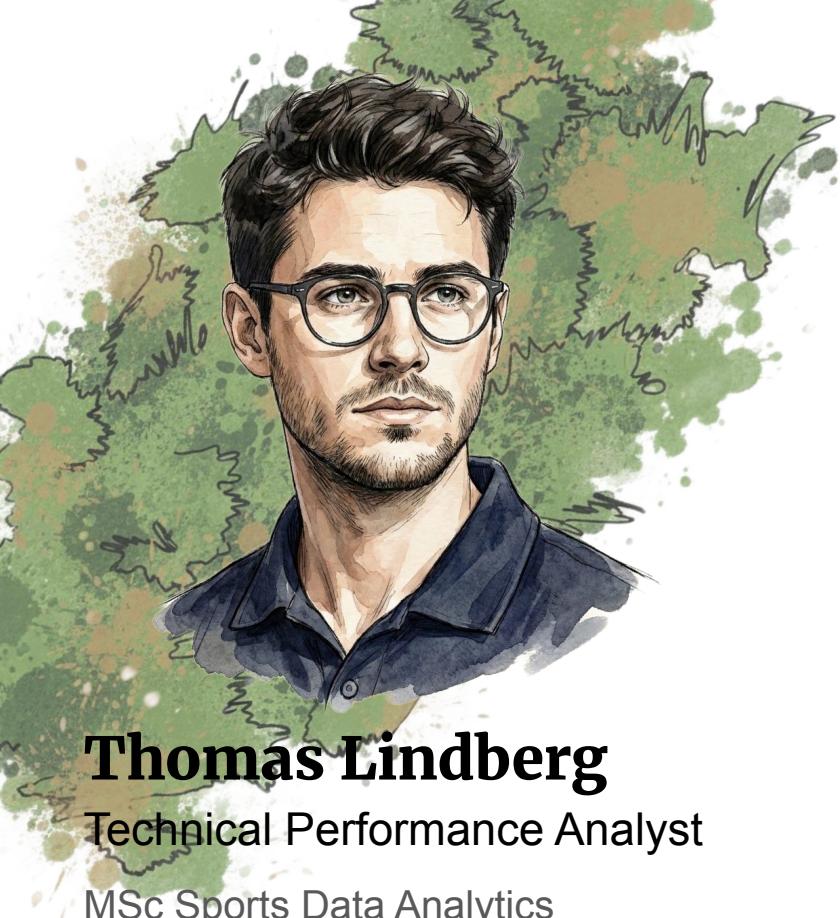
**Impact of Agent Heterogeneity:** How do variations in physical and technical player attributes—specifically locomotion speed and shooting precision—alter the feasibility and selection of optimal tactical trajectories within the simulation?

**Robustness through Adversarial Play:** How does the introduction of an asynchronous adversarial evolution mechanism impact the stability and emergent coordination of offensive passing policies compared to static defensive baselines?

**Reward Shaping and Convergence:** Can the combination of dense spatial potential fields (Elliptical Reward Grids) and sparse event-based rewards sufficiently mitigate the credit assignment problem in complex multi-agent football scenarios?



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**Thomas Lindberg**  
Technical Performance Analyst  
  
MSc Sports Data Analytics  
UEFA B License  
Expert in Python/R & Tracking Data

# User Persona

## GOALS

- Automate tactical feature extraction from raw tracking data
- Run *what-if* match simulations
- Use data models to validate tactical decisions objectively

## FRUSTRATIONS

- Manual data cleaning and tagging take too much time
- Raw coordinates are difficult to translate into tactical insights
- Current tools are too rigid to match our specific scenarios

## NEEDS

- Export raw simulation data for internal team dashboards
- Quickly test tactical changes like pressing or tackling
- Automatically identify opponent habits and defensive gaps

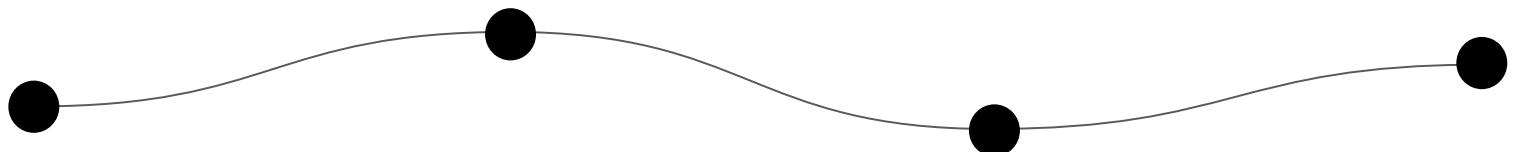


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# Thomas's Journey

## 1. Stuck in Raw Data

Thomas spends hours manually cleaning tracking data after a match. The process is slow, and the raw numbers lack tactical context for the coaches.

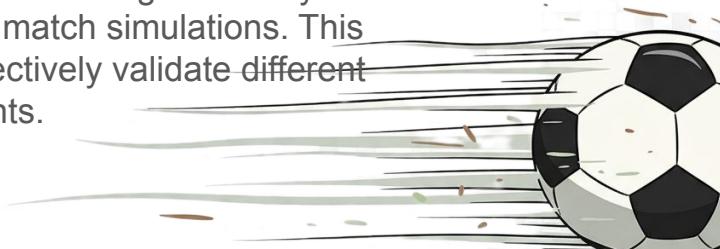


## 2. Searching for Context

He searches for a tool to automate feature extraction from raw data. He needs a platform that can quickly test tactical scenarios ("what-if" analysis).

## 3. Simulating the Pitch

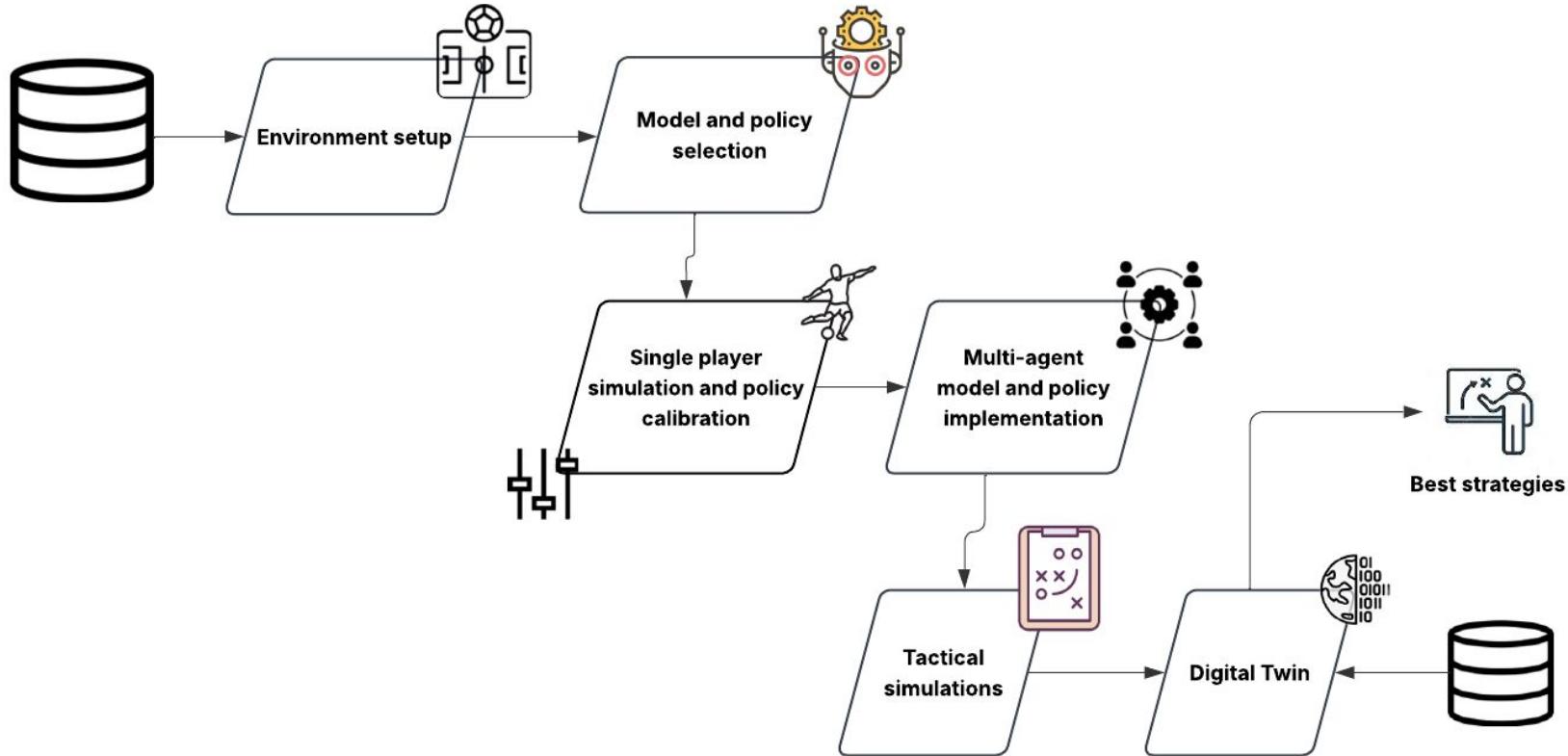
Thomas adopts the new digital twin system to run automated match simulations. This allows him to objectively validate different tactical adjustments.



## 4. Empowering the Staff

He provides the coaching staff with model-validated insights. The clear, evidence-based reports save time and make his tactical briefings more effective.

# Functional Diagram





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# Environment - Objects

**Pitch, Ball, and Players** objects define the simulation world.



**Dimensions:**  
Standard **120×80m** pitch

**Coordinate System:**  
Normalized **[0,1]**

**Position-Based Reward:**  
Elliptical reward grids  
(Heatmaps)



**Ball Radius:**  
Standard **0.11m** football

**Dual Dynamics:**  
Between "Free Physics"  
and "Owned State"

**Tuned Friction:**  
Low-friction decay **0.15%**



**Sensory Constraints:**  
Limited by Field of View

**Probabilistic Execution:**  
Skills incorporate  
parametric noise

**Event-Based Reward:**  
goals, passes, tackles,  
and saves

# Environment - Single Agent

**Setup:** 1v1 on a half-pitch scale

- Attacker: the learning agent, initialized with the ball
- Defender: a programmed bot that follows/chases the attacker (non-learning)
- Objective: drive the ball towards the Goal while evading the defender

**Observation Space:** define the agent's sensory input

- All positions (player, ball) are scaled to [0,1] relative to the pitch size
- Internal States: Shooting Flag (is\_shooting), Shot Power, and Direction.

**Action Space:** define the control output of the agent

- Movement: 2D vector for directional running
- Shooting: Binary Trigger (shoot or not), Power (intensity), and Direction vector.
- Realistic Constraints: must maintain possession while executing these actions



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# Environment - Multi Agent

## Simultaneous Decision-Making

Multiple agents (attackers, defenders, goalkeeper) take decisions at the same timestep

## Role-Specific Behaviors

Each player has a role (ATT, DEF, GK) that shapes how they move, reposition, defend or shoot

## Individual Perspectives

Each agent observes the game from its own viewpoint: own state, ball state, nearby players, tactical context

## Emergent Team Dynamics

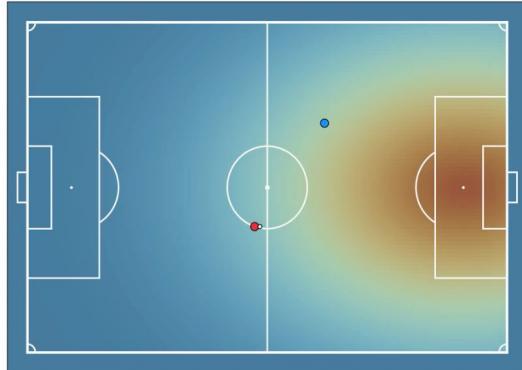
Agents can be rewarded both individually and as a team, leading to coordination patterns: pressing, covering, supporting, blocking



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# Environment - Tactical Scenarios

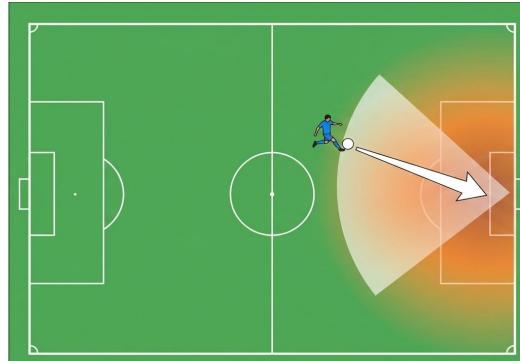
Move



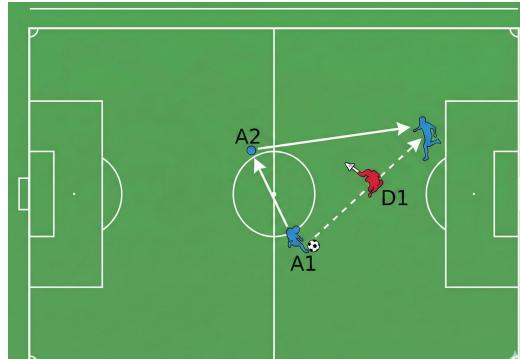
View



Shot



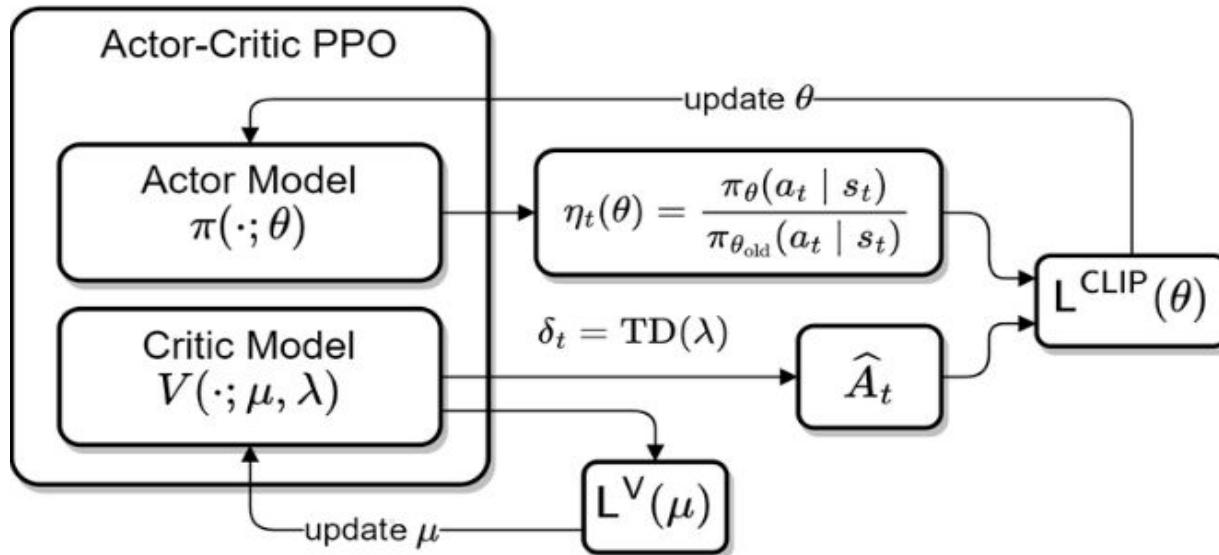
Pass





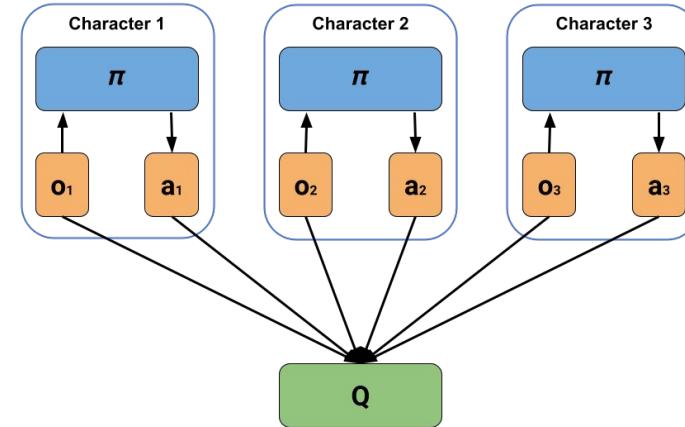
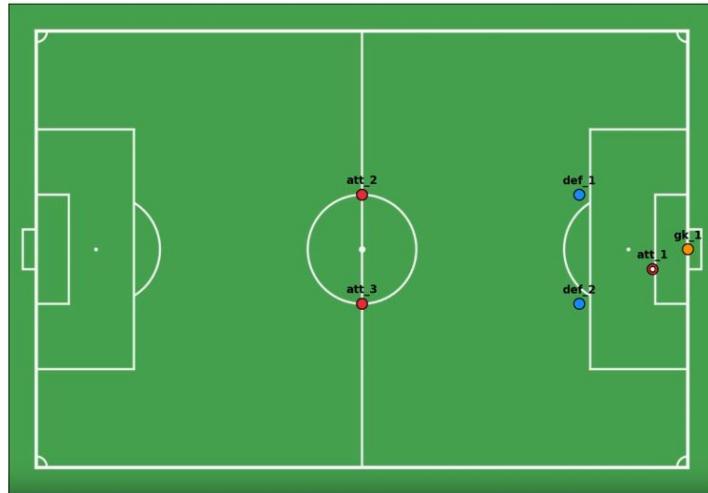
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# PPO



<https://huggingface.co/learn/deep-rl-course/unit8/intuition-behind-ppo>

# MARL



Centralized Training with Decentralized Execution



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# Adversarial Learning

## Asynchronous Evolution Mechanism

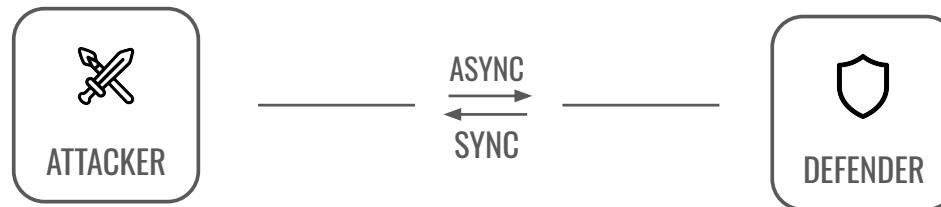
This method replaces the traditional synchronous approach, updating with **alternating freezing training**. In 3000 episodes, the training focus switches every 500 episodes. This simulates a cycle where a “coach gives specific tactical instructions”.

## Opponent Pool

By training against a diverse historical opponent pool, agents will build a tactical memory that ensures they remain robust against any playstyle, not just the latest one.

## Independent Policy Mapping

Each agent has its **own policy network** instead of using a shared central logic. This makes it possible to add *Realistic Attributes* such as different speed multipliers, different base shot power, etc.





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# Realistic Player Profiling

**Player heterogeneity** is introduced by parameterizing agents with different **physical and technical attributes**, enabling the representation of multiple player profiles within the same environment.

The learning algorithm and policy architecture remain **unchanged**.

The following characteristics can be independently modified while keeping the learning algorithm unchanged:

- **Movement speed** (affects displacement per step)
- **Shooting power** (affects ball velocity after shot)
- **Shot precision** (affects angular noise in shot direction)

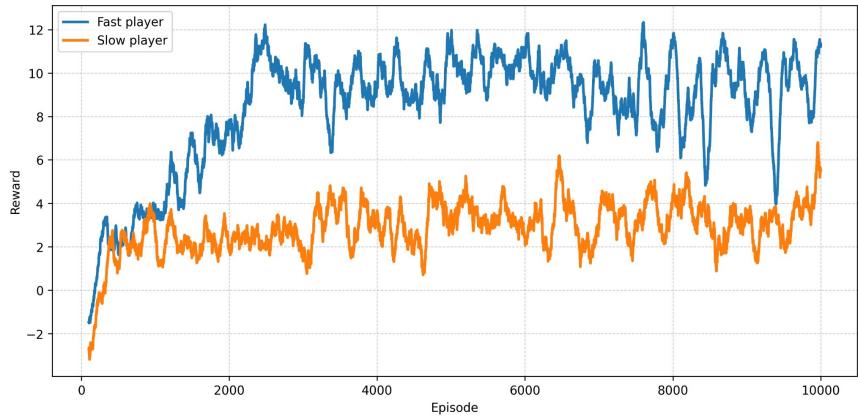
This enables controlled analyses of how individual player skills influence learned behaviors and interaction dynamics.

# Speed-Based Player Categorization

Two agents are trained under **identical conditions**, differing only in **attacker speed**, in a *MOVE* scenario.

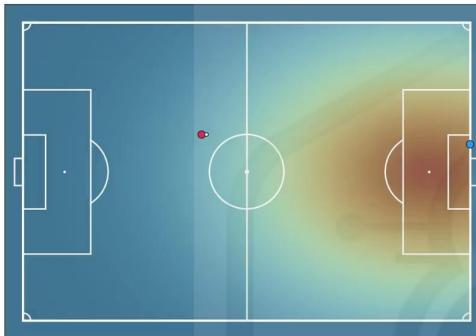
## Training Dynamics: FAST vs SLOW Attacker

Moving average of episode reward (window = 100)

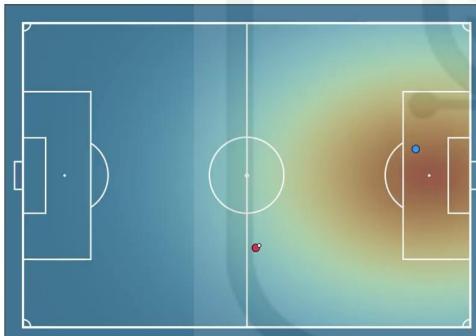


Mean reward (last 10%):  
FAST: 9.33    SLOW: 3.45

Frame: 0/214 | Time: 0.00 s  
Reward: 0.000 | Cumulative: 0.000



Frame: 1/197 | Time: 0.04 s  
Reward: -0.009 | Cumulative: -0.009



With identical training settings, the fast attacker achieves higher average rewards, which corresponds to **longer possession** and **more effective defender bypassing** in the videos.



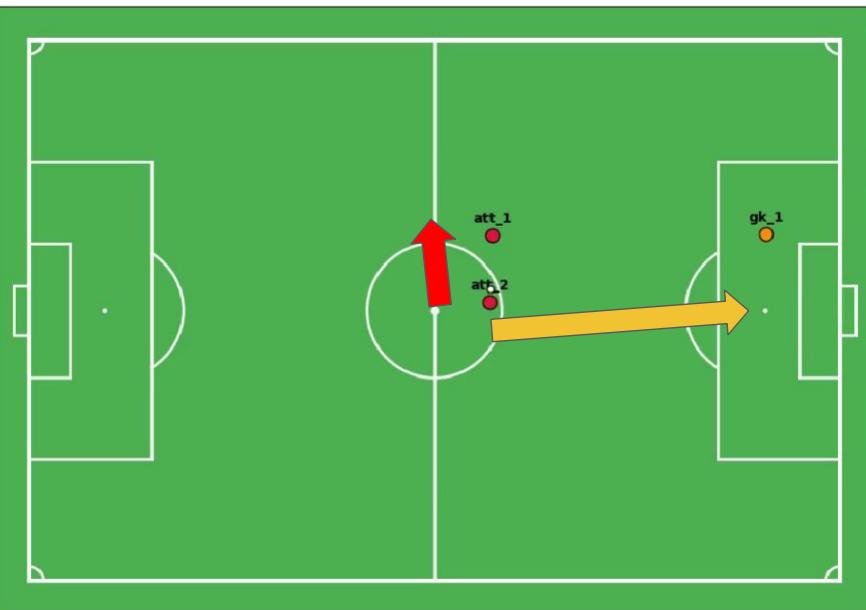
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# What-if

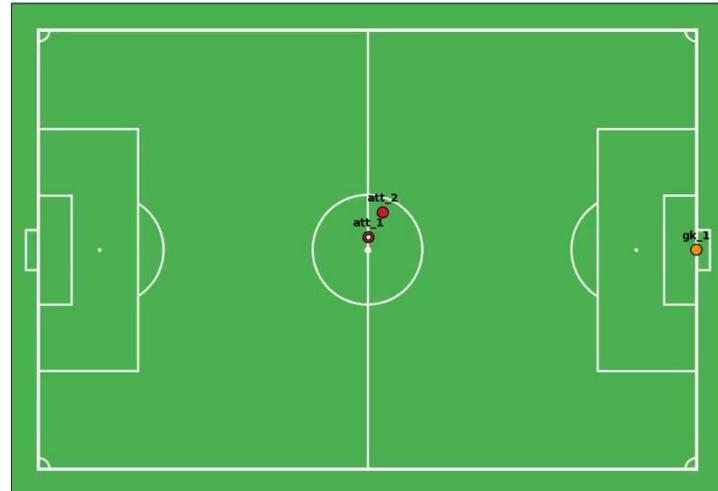
Dataset: **STATSBOMB**



## Assists with failed shot



Frame: 0/240

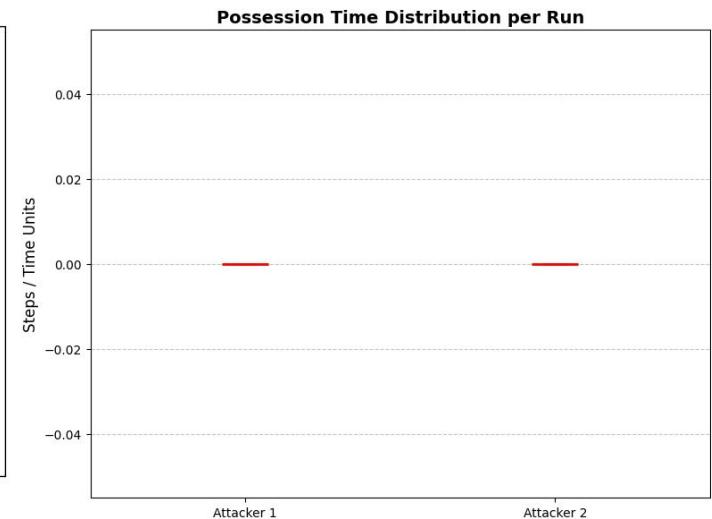
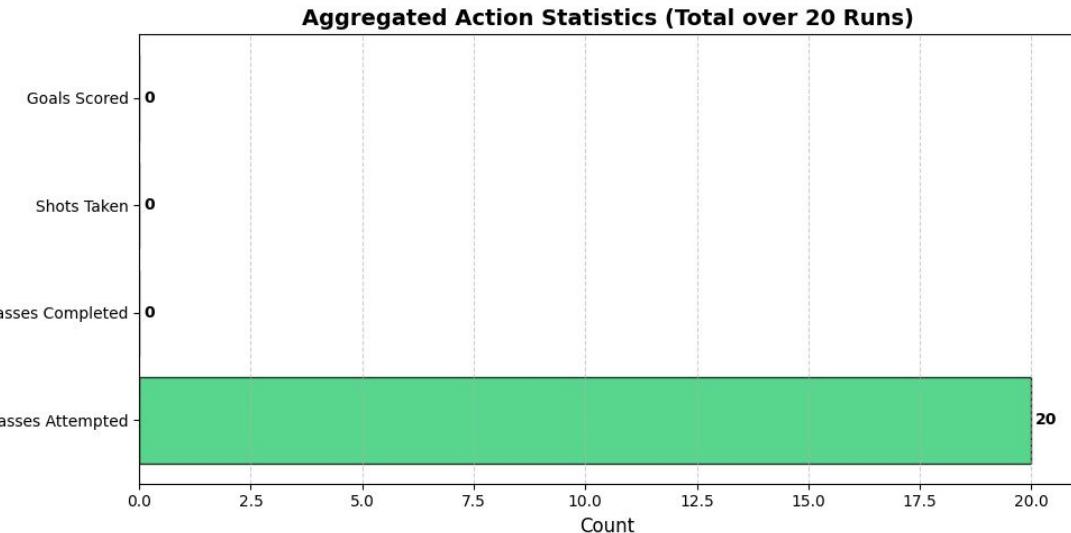




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# What-if

Results show poor performance of the model. The model learns only to pass and often very badly.



# Thank you !



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di Torino



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DB  
MG