# Info-gap robustness assessment of reliability evaluations using several OpenTURNS features

#### OpenTURNS User's Day

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### Scientific context

Uncertainty framework

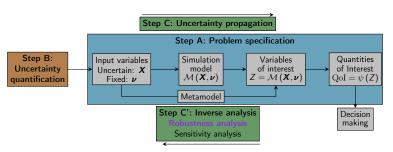


Figure 1: General uncertainty quantification and propagation framework.

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- Industrial application
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- Conclusion



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# Info-gap applied to reliability analysis

■ Robustness curves (Ben-Haïm, 2006):

#### decision 1

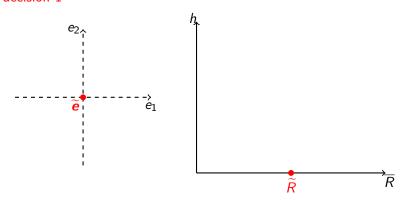


Figure 2: Nested convex sets with robustness curves.



■ Robustness curves (Ben-Haïm, 2006):

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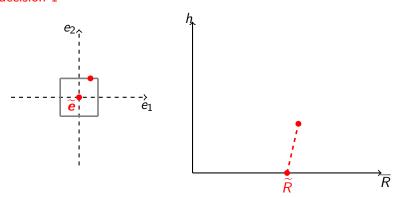


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2 3 4 6 Reference

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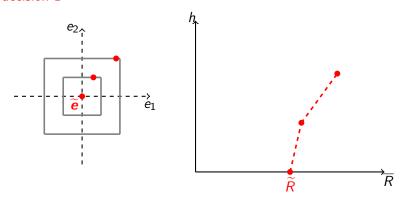


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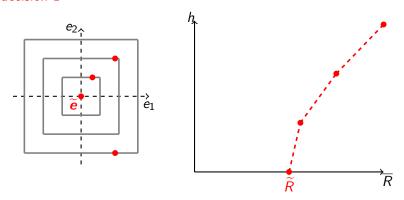


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■ Robustness curves (Ben-Haïm, 2006):

decision 1 vs decision 2

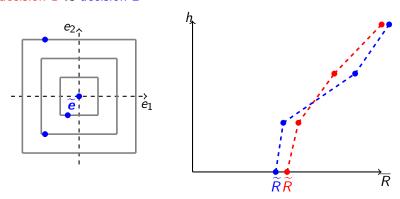


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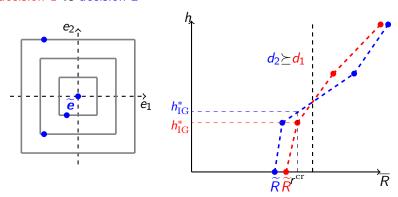


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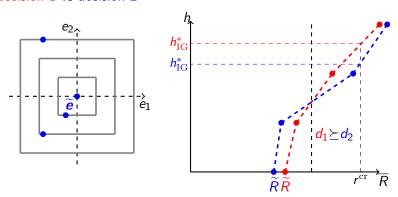


Figure 2: Nested convex sets with robustness curves.



#### ■ Robustness of reliability evaluations

$$h_{\mathrm{IG}}^{*} = \max_{h} \left\{ \max_{e \in U(h, e)} \mathrm{QoI}(d, e) \leq \mathrm{QoI}^{\mathrm{cr}} \right\}$$
 (1)

- Qol: (small) failure probability, (high-order) quantile, superquantile ...
- ▶ e: input variables, hyperparameters of a probability distribution, model errors, ...

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#### ■ Robustness of reliability evaluations

$$h_{\mathrm{IG}}^{*} = \max_{h} \left\{ \frac{\max}{\mathrm{e} \in U\left(h, \overset{\sim}{\mathrm{e}}\right)} \mathrm{QoI}\left(\mathsf{d}, \mathsf{e}\right) \leq \mathrm{QoI}^{\mathrm{cr}} \right\}$$
(1)

- ▶ Qol: (small) failure probability, (high-order) quantile, superquantile ...
- ▷ e: input variables, hyperparameters of a probability distribution, model errors, ...
- Q1 How to apply IG uncertainty models to the reliability framework?



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#### ■ Robustness of reliability evaluations

$$h_{\mathrm{IG}}^{*} = \max_{h} \left\{ \max_{\mathbf{e} \in U(h, \widetilde{\mathbf{e}})} \left[ \mathrm{QoI}(\mathbf{d}, \mathbf{e}) \right] \leq \mathrm{QoI}^{\mathrm{cr}} \right\}$$
 (1)

- ▷ e: input variables, hyperparameters of a probability distribution, model errors, ...
- Q2 How to propagate hybrid uncertainty (aleatory and epistemic) in order to estimate the bounds of the QoI?



■ Robustness of reliability evaluations

$$h_{\mathrm{IG}}^{*} = \max_{h} \left\{ \left| \max_{\mathsf{e} \in U\left(h, \overset{\circ}{\mathsf{e}}\right)} \mathrm{QoI}\left(\mathsf{d}, \mathsf{e}\right) \right| \leq \mathrm{QoI}^{\mathrm{cr}} \right\}$$
(1)

- ▷ Qol: (small) failure probability, (high-order) quantile, superquantile ...
- ▶ e: input variables, hyperparameters of a probability distribution, model errors, ...
- Q3 How to efficiently reduce the computational burden induced by both the Qol estimator and the IG formulation?



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### 2 – Hybrid reliability analysis

Failure probability estimation under aleatory uncertainty

$$P_{f} = \Pr\left[g\left(\mathbf{X}\right) \leq 0\right] = \int_{g(\mathbf{x}) \leq 0} f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x} = \int_{\mathbb{R}^{n_{\mathbf{X}}}} 1_{g(\mathbf{x}) \leq 0} f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x} \qquad (2)$$

Failure probability estimation under hybrid uncertainty

$$P_{\rm f} = \Pr\left[g\left(\boldsymbol{X}, \boldsymbol{Y}\right) \le 0\right] \tag{3}$$

- Random vector  $\boldsymbol{X} \sim f_{\boldsymbol{X}}$
- Epistemic vector **Y**: intervals, convex sets, possibility distribution, Dempster-Shafer structures, p-boxes, probability distribution ...
- ightharpoonup Only the bounds  $\left[\underline{P_f},\overline{P_f}\right]$  of the failure probability can be estimated
- Need for a common framework for estimating and comparing these bounds



### 2 – Hybrid reliability analysis

- Random sets as a unifying framework (Alvarez, 2006)
  - ▷ With  $\Omega = [0,1]^{n_X+n_Y}$  and  $\alpha_{Y_i} \sim U(0,1)$ , one retrieves several uncertainty representations:

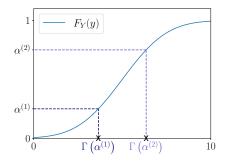


Figure 3: Random set with a probabilistic cdf.



### 2 – Hybrid reliability analysis

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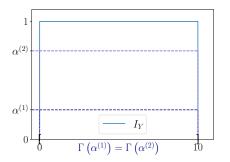


Figure 4: Random set with an interval.



- Random sets as a unifying framework (Alvarez, 2006)
  - $\triangleright$  With  $\Omega = [0,1]^{n_{\mathbf{X}} + n_{\mathbf{Y}}}$  and  $\alpha_{Y_i} \sim U(0,1)$ , one retrieves several uncertainty representations:

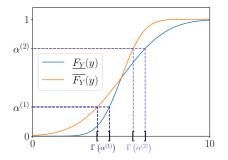


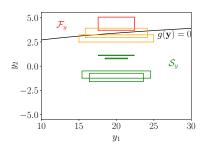
Figure 5: Random set with a p-box.

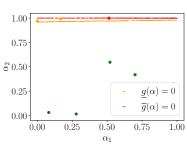


■ Random sets in the reliability framework (Alvarez et al., 2018)

$$\overline{P_{f}} = \Pr \left[ \min_{\Gamma(\alpha)} g(\alpha) \le 0 \right] = \int_{\Omega} \mathbb{1}_{\underline{g}(\alpha) \le 0} d\alpha$$
 (5a)

$$\underline{P_{\mathbf{f}}} = \Pr \left[ \max_{\Gamma(\alpha)} g(\alpha) \le 0 \right] = \int_{\Omega} \mathbb{1}_{\overline{g}(\alpha) \le 0} d\alpha \tag{5b}$$





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# 3 – Reliability of penstocks



Figure 6: Example of a penstock operated by EDF.

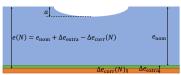


Figure 7: illustration of a penstock presenting a planar flaw of height *a*.

- Main characteristics (Ardillon et al., 2022)
  - ▶ Failure mode (Step A): brittle failure affecting welds due to corrosion and the presence of a default
  - $\triangleright$  **Simulation model** (Step A): analytical expressions  $\rightarrow$  fast to compute
  - ▶ Qol (Steps A and C): small failure probability

$$P_{f} = \Pr\left(\left\{G_{N+1}\left(\boldsymbol{X}, \boldsymbol{Y}\right) \leq 0\right\} \cap \left\{G_{N}\left(\boldsymbol{X}, \boldsymbol{Y}\right) > 0\right\} \cap \left\{G_{HPT}\left(\boldsymbol{X}, \boldsymbol{Y}\right) > 0\right\}\right) \tag{6}$$

- ▶ Uncertain inputs dimension (Step A):  $n_X + n_Y = 6$
- ▶ IG motivation (Step C'): are there some nominal configurations of penstocks more robust than others?
- ▶ Challenge (Step C): complexity of the failure domain and of the failure probability estimation



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#### ■ IG uncertainty model (Step B)

Variable $X_i$	Distribution	Param. 1	Param. 2	Param. 3
$X_1 = R_m \text{ (MPa)}$	Lognormal	480	24	-
$X_2 = \varepsilon \text{ (MPa)}$	Normal	0	16.816	-
$Y_1 = \Delta e_{\text{extra}} \text{ (mm)}$	Normal	$\theta_{1}$	0.25	-
$Y_2 = \Delta e_{\text{corr}} \text{ (mm) (mm)}$	Normal	$\theta_2$	0.4	-
$Y_3 = a \text{ (mm)}$	Uniform	0	$\theta_3$	-
$Y_4 = K_{\rm IC}  (MPa.\sqrt{m})$	Weibull Min	$\theta_{f 4}$	4	20

Table 1: Input probabilistic modeling of  $\boldsymbol{X}$  for the penstock use-case.

▶ Parametric p-box uncertainty model

$$D_{\theta}\left(h,\widetilde{\theta}\right) = \sum_{i=1}^{4} I_{\theta_{i}}(h) \text{ with } \begin{cases} I_{\theta_{i}}(h) = \left[\widetilde{\theta}_{i}\left(1-h\right), \widetilde{\theta}_{i}\left(1+h\right)\right] & \text{if } \widetilde{\theta}_{i} > 0\\ I_{\theta_{i}}(h) = \left[-h, h\right] & \text{if } \widetilde{\theta}_{i} = 0 \end{cases}$$

$$\tag{7}$$

Robustness function

$$h_{\mathrm{IG}}^{*} = \max_{h} \left\{ \max_{\theta \in D_{\mathbf{B}}(h,\widetilde{\theta})} P_{\mathrm{f}}(\theta) \le P_{\mathrm{f}}^{\mathrm{cr}} \right\}$$
(8)



- Failure probability estimator (Step C)
  - ▶ FISSTAR: FORM-IS-Tested Automatically-Rapid seaRch: current algorithm used for the failure probability estimations
  - ▶ Line sampling: directional technique investigated in order to better target the restricted failure domain

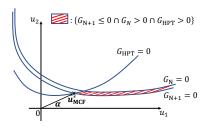


Figure 8: Illustration of the failure domain for the reliability of penstocks.

"Standard" Line Sampling (Koutsourelakis, 2004)

$$\triangleright \mathbf{u} = \mathbf{u}^{\parallel} \alpha + \mathbf{u}^{\perp}$$

$$P_{f} = \mathbb{E}_{\varphi_{\mathbf{u}^{\perp}}} \left[ \int_{G(\mathbf{u}^{\parallel} \alpha + \mathbf{u}^{\perp}) \leq 0} \varphi\left(\mathbf{u}^{\parallel}\right) d\mathbf{u}^{\parallel} \right]$$

$$= \mathbb{E}_{\varphi_{\mathbf{u}^{\perp}}} \left[ \Phi\left(-r\left(\mathbf{u}^{\perp}\right)\right) \right]$$
(9)

LS estimator:  

$$\mathbf{u}^{\perp,(i)} = \mathbf{u}^{(i)} - (\mathbf{u}^{(i)}\alpha)\alpha^{\top}$$

$$\widehat{P}_{f} = \frac{1}{n_{LS}} \sum_{i=1}^{n_{LS}} \Phi\left(-r\left(\mathbf{u}^{\perp,(i)}\right)\right)$$

$$= \frac{1}{n_{LS}} \sum_{i=1}^{n_{LS}} \rho_{f}^{(i)}$$
(10)

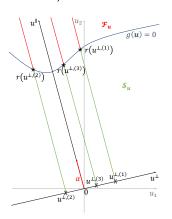


Figure 9: LS illustration.



- LS applied to the reliability of penstocks
  - ho Case 1: no root ightarrow  $p_{\rm f}^{(i)}=0$
  - $\triangleright \quad \mathsf{Case 2: two roots} \rightarrow \quad \rho_{\mathrm{f}}^{(i)} = \Phi\left(-r_1\left(\boldsymbol{u}^{\perp,(i)}\right)\right) \Phi\left(-r_2\left(\boldsymbol{u}^{\perp,(i)}\right)\right)$

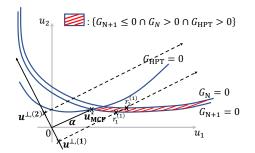
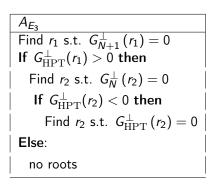


Figure 10: LS applied to the restricted failure domain



■ Adapted LS algorithms for each formulation  $E_i$  $E_3 = \{G_{N+1} < 0 \cap G_N > 0 \cap G_{HPT} > 0\}$ 



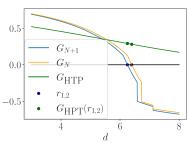


Figure 11: Roots search on  $E_3$ 

■ Application of the methodology for the robustness evaluation (Step C')

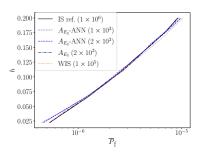


Figure 12: Comparison of robustness curves.

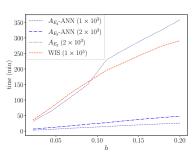


Figure 13: Comparison of the cumulative time needed for the robustness assessment.

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# Conclusion: thank you OpenTURNS

- Data analysis
  - $\circ$  ...
- Probabilistic modeling
  - Standard parametric models
  - Copulas
  - O Convex sets, possibility distributions, DS structures, p-boxes, random sets
- Meta modeling
  - Artificial neural networks (Keras)
- Reliability, sensitivity
  - O MC, FORM, IS, SS
  - Line Sampling
- Numerical methods
  - Uniform Random Generator
  - Distribution realizations + random set realizations
  - Optimization Algorithms : NLopt (DIRECT) + root search (scipy)
    - Isoprobabilistic transformation



2 3 4 6 References

### References I

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