

# Enhanced Metamodeling and Sensitivity Analysis for Complex Models Using Tree-PCE

PhD Student: BEN SAID Faten<sup>1,2</sup>

**Directors:** REYGNER Julien<sup>1</sup>, EL KADI ABDERREZZAK  
Kamal<sup>2,3</sup>

**Supervisors:** AURELIEN Alfonsi<sup>1</sup>, GOEURY Cedric<sup>2,3</sup>, ZAOUI Fabrice<sup>2</sup>, DUTFOY Anne<sup>2</sup>  
<sup>1</sup>CERMICS, <sup>2</sup>EDF R&D, <sup>3</sup>LHSV



14 June 2024



LABORATOIRE  
D'HYDRAULIQUE  
SAINT-VENANT



# Table of contents

- 1 Context.
- 2 Sobol' indices.
- 3 Polynomial Chaos method.
  - Sobol' indices from PCE.
- 4 Tree-Polynomial Chaos method.
  - Tree-PCE Algorithm.
  - Applications.
  - Sobol indices from Tree-PCE.
- 5 Application to a test case.

# Context

## Challenges in Hydro-Sediment Modeling:

- Accurate prediction of sediment transport and deposition.
- Complex interactions between water flow and sediment movement.
- Different sources of uncertainty (data, measures, empirical laws,...).

## Impact of Uncertainty:

- Uncertainty affects model predictions and decision-making.
- Understanding and quantifying uncertainty is crucial for model validation and improvement.

## Goal:

- Perform sensitivity analysis to identify the most influential parameters.

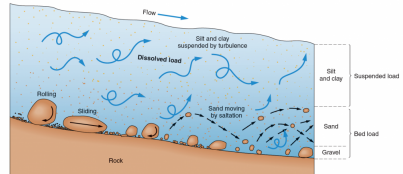


Figure: Sediment Transport

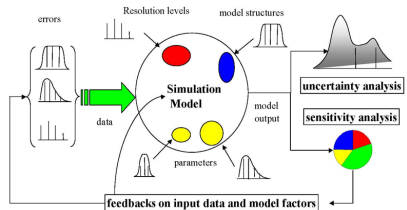


Figure: Uncertainty and Sensitivity Analysis

# Sobol' indices [1]

## Sobol' indices.

Let  $X \in \mathbb{R}^d$  be a random vector,  $G \in \mathbb{L}^2(P_X)$ ,  $A \in \mathcal{P}_d$ ,

- The closed Sobol' index associated to  $A$  is defined as

$$S_A^{clos} = \frac{\text{Var}E[G(X)|X_A]}{\text{Var}G(X)}$$

This index is also called the first-order Sobol' index associated to the input vector  $X_A$ .

- The total Sobol' index associated to  $X_A$  is defined as

$$S_A^T = 1 - S_A^{clos}$$

# Estimation of Sobol' indices by Polynomial Chaos method (PCE) [2]

## PCE method.

Let  $Y = G(X)$  with  $G : X \in \mathcal{D}_X \subset \mathbb{R}^d \mapsto Y = G(X) \in \mathbb{R}$ .

Assume that  $Y \in \mathbb{L}^2(P_X)$  : Hilbert space, which allows writing :

$$Y = \sum_{|\alpha|=0}^P y_\alpha \Phi_\alpha(X) = \sum_{|\alpha|=0}^P y_\alpha \prod_{i=1}^d \phi_{\alpha_i}^{(i)}(X_i)$$

with

- $\{\Phi_\alpha\}_{|\alpha|=0}^P$  is a multivariate basis of the Hilbert space orthonormal with respect to the measure of  $X$ . such that  $\Phi_\alpha = \prod_{i=1}^d \phi_{\alpha_i}^{(i)}(x_i)$  with  $\{\phi_j^{(i)}\}_j$  is an univariate orthonormal basis with to the measure of  $X_i$ .
- $\{y_\alpha\}_{|\alpha|=0}^P$  are coefficients (the coordinates of  $Y$  in the basis  $\{\Phi_\alpha\}_{|\alpha|=0}^P$ ).

## Sobol' indices from PCE method

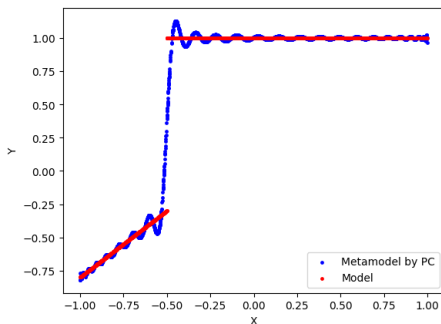
Let  $A \subset \{1, \dots, d\}$ , We have

$$S_i = \frac{\sum_{\alpha \in J_i} y_\alpha^2}{\sum_{\alpha \in A, \alpha \neq 0} y_\alpha^2} \quad \text{where} \quad J_i = \{\alpha \in A, \alpha_i > 0, \alpha_{j \neq i} = 0\}$$

$$S_i^T = \frac{\sum_{\alpha \in J_i^T} y_\alpha^2}{\sum_{\alpha \in A, \alpha \neq 0} y_\alpha^2} \quad \text{where} \quad J_i^T = \{\alpha \in A, \alpha_i > 0\}$$

# Limitation of PCE Method

- Dealing with discontinuous models, PCE method may encounter challenges in accurately capturing model's discontinuities.



**Figure:** Approximation of a discontinuous function by PCE Method with total degree = 50

# Aim of this work

Adaptation of Polynomial Chaos method for Models with Discontinuities :

- 1 Identify points of discontinuity and divide the domain into subdomains, each separated by a point of discontinuity.
- 2 Apply PCE within each subdomain.
- 3 Estimate the Sobol indices using the meta-models obtained.

# Identify points of discontinuity.

## Tree-PCE Algorithm

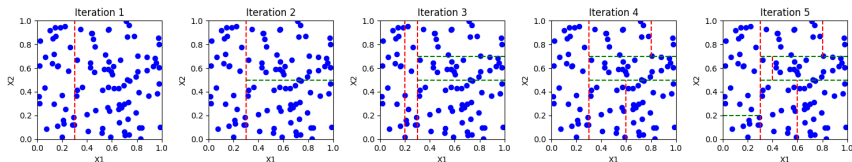


Figure: Tree-PCE iterations

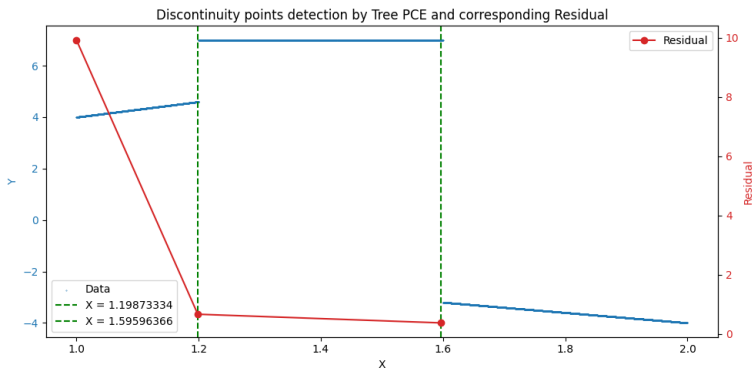
- Select thresholds to classify data in a way that minimizes the Leave-One-Out (LOO) residual error of local PCEs.
- Refines iteratively the classification until the residual errors no longer improve.



# Applications : Example 1D

For  $X \in U([1, 2])$ ,

$$Y = f(X) = \begin{cases} 3X + 1 & \text{if } X < 1.2 \\ 7 & \text{if } 1.2 < X < 1.6 \\ -2X & \text{else} \end{cases}$$



# Example 2D

For  $X_1, X_2 \in U([1, 2])$ ,

$$Y = \begin{cases} 3X_1 + 2X_2 & \text{if } X_1 < 1.7 \\ 15X_2 + 4X_1 & \text{if } X_1 < 1.5 \\ \begin{cases} -2X_2 & \text{if } X_2 < 1.8 \\ -8X_1 - 6X_2 & \text{if } X_2 < 1.3 \\ 8X_1 & \text{else} \end{cases} & \text{else} \end{cases}$$

3D Scatter plot of X vs Y

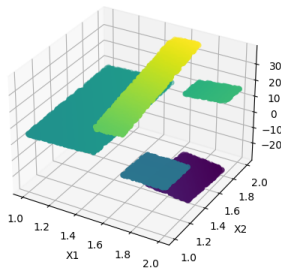


Figure:  $Y = f(X)$

# Detection of Points of Discontinuity by Tree-PCE

Detected points:

Step	$X_1$	$X_2$
1	1.696861	-
2	1.499787	-
2	-	1.797811
3	-	1.298169
4	1.794994	-

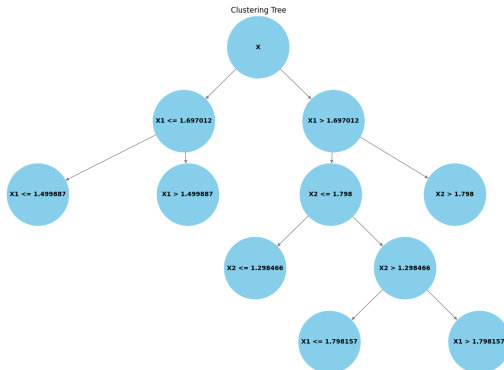


Figure: Clustering Tree

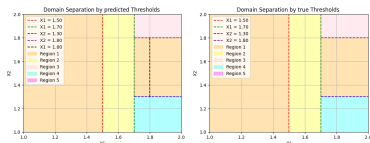


Figure: Comparison of Predicted Classes and Real Classes

# Example with Triangular Domain

For  $X_1, X_2 \in U([1, 2])$ ,

$$Y = f(X) = \begin{cases} 0 & \text{if } X_1 < X_2 \\ 1 & \text{else} \end{cases}$$

3D Scatter plot of X vs Y

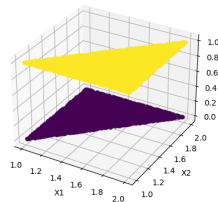


Figure:  $Y=f(X)$

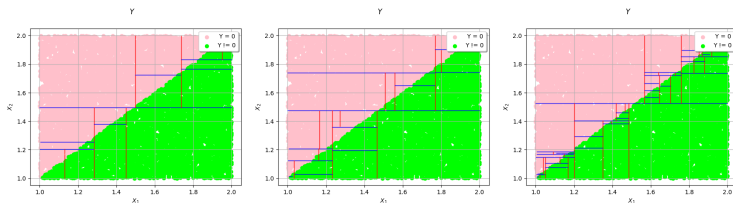


Figure: Application of Tree-PCE

# Metamodel identified from Tree-PCE

The output of Tree-PCE is:

- (i) a collection of  $d$ -dimensional rectangles  $\mathcal{R}^r$ ,  $r = 1, \dots, R$ , indexed by some binary tree, which form a partition of the domain  $\mathcal{D}_x$ ;
- (ii) on each rectangle  $\mathcal{R}^r$ , which we denote by  $\mathcal{R}^r = \prod_{i=1}^d \mathcal{I}^{(i),r}$ , a local PCE model

$$\forall x \in \mathcal{R}^r, \quad y \simeq \sum_{|\alpha| \leq p} y_{\alpha}^r \psi_{\alpha}^r(x), \quad \psi_{\alpha}^r(x) = \prod_{i=1}^d \phi_{\alpha_i}^{(i),r}(x_i),$$

where for each  $i \in \{1, \dots, d\}$ ,  $(\phi_j^{(i),r})_{j \geq 0}$  is a family of orthonormal polynomial in  $L^2(f_{X_i|\mathcal{I}^{(i),r}})$ , with in particular  $\phi_0^{(i),r}(x_i) = 1$  for any  $x_i \in \mathcal{I}^{(i),r}$ .

## Metamodel identified from Tree- PCE.

Extending the definition of  $\phi_j^{(i),r}$  to  $\mathcal{D}_{x_i}$  by setting  $\phi_j^{(i),r}(x_i) = 0$  if  $x_i \notin \mathcal{I}^{(i),r}$ , we thus obtain the global approximation

$$Y \simeq \tilde{Y} = \sum_{r=1}^R \sum_{|\alpha| \leq p} y_{\alpha}^r \psi_{\alpha}^r(X).$$

# Sobol indices from Tree- PCE

## Sobol indices from Tree-PCE.

We have,

$$\mathbb{E}[\tilde{Y}] = \sum_{r=1}^R \sum_{|\alpha| \leq p} y_{\alpha}^r \prod_{i=1}^d \mathbb{E} \left[ \Phi_{\alpha_i}^{(i),r}(X_i) \right].$$

$$\mathbb{E}[\tilde{Y}^2] = \sum_{r=1}^R \sum_{|\alpha| \leq p} (y_{\alpha}^r)^2 \mathbb{P}(X \in \mathcal{R}^r).$$

$$\mathbb{E}[\tilde{Y}|X_I] = \sum_{r=1}^R \sum_{|\alpha| \leq p, \alpha_{I^c} = 0} y_{\alpha}^r \left( \prod_{i \in I} \Phi_{\alpha_i}^{(i),r}(X_i) \right) \mathbb{P}(X_{I^c} \in \mathcal{R}_{I^c}^r),$$

$$\mathbb{E} \left[ \mathbb{E}[\tilde{Y}|X_I]^2 \right] = \sum_{r,r'=1}^R \mathbb{P}(X_{I^c} \in \mathcal{R}_{I^c}^r) \mathbb{P}(X_{I^c} \in \mathcal{R}_{I^c}^{r'}) \sum_{\substack{|\alpha| \leq p, \alpha_{I^c} = 0 \\ |\alpha'| \leq p, \alpha'_{I^c} = 0}} y_{\alpha}^r y_{\alpha'}^{r'} C_{\alpha, \alpha'}^{r, r'}(I),$$

with

$$C_{\alpha, \alpha'}^{r, r'}(I) = \prod_{i \in I} \mathbb{E} \left[ \Phi_{\alpha_i}^{(i),r}(X_i) \Phi_{\alpha'_i}^{(i),r'}(X_i) \right] = \prod_{i \in I} \int_{\mathcal{I}^{(i),r} \cap \mathcal{I}^{(i),r'}} \Phi_{\alpha_i}^{(i),r}(x_i) \Phi_{\alpha'_i}^{(i),r'}(x_i) f_{X_i}(x_i) dx_i, .$$

- if  $\mathcal{I}^{(i),r} = \mathcal{I}^{(i),r'}$ , then

$$C_{\alpha, \alpha'}^{r, r'}(I) = \prod_{i \in I} 1_{\{\mathcal{I}^{(i),r} = \mathcal{I}^{(i),r'}, \alpha_i = \alpha'_i\}} \mathbb{P}(X_i \in I^{i,(r)})$$

Sobol indices :

$$S_A = \frac{\mathbb{E}[\mathbb{E}[Y|X_A]^2] - \mathbb{E}[Y]^2}{\mathbb{E}[Y^2] - \mathbb{E}[Y]^2} \quad , \quad S_A^T = 1 - S_{A^c}$$

# Example

For  $X_1, X_2 \in U([1, 2])$ ,

$$Y = f(X) = \begin{cases} 3X_1 + 5X_2 & \text{if } X_1 < 1.3 \text{ and } X_2 < 1.5 \\ 2 & \text{if } X_1 < 1.3 \text{ and } X_2 > 1.5 \\ -4X_2 & \text{if } X_1 > 1.3 \text{ and } X_2 < 1.5 \\ -3X_1 - 6X_2 & \text{else} \end{cases}$$

3D Scatter plot of X vs Y

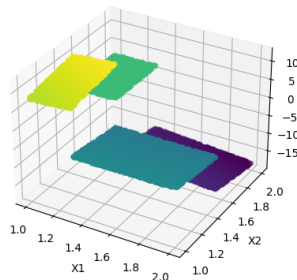


Figure:  $Y=f(X)$

# Detection of points of discontinuity by Tree-PCE

Detected points :

Step	$X_1$	$X_2$
1	1.292942	-
2	-	1.504695
3	-	1.494980

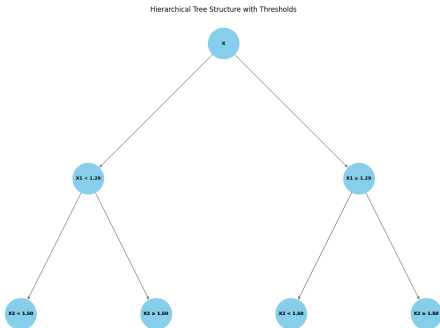


Figure: clustering Tree

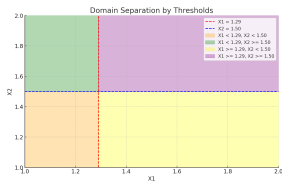


Figure: Domain Partition



# Sobol indices from Tree-PCE

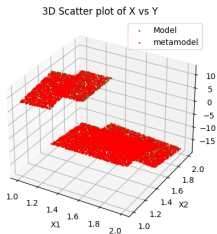


Figure: Metamodel vs Model

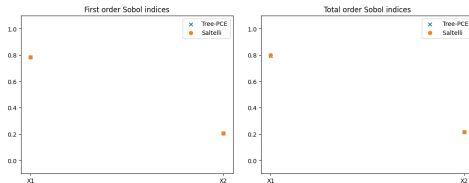


Figure: Comparison of Sobol' indices from Tree-PCE and Saltelli

# Hydro-sediment test case

Simulation Model : TELEMAC-MASCARET [4].

## • TELEMAC-MASCARET :

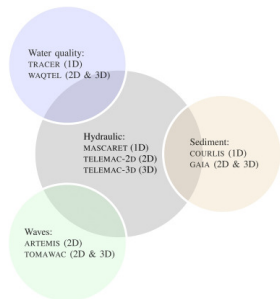
- Used in the field of free-surface environmental flows.
- Use high-capacity algorithms based on the finite-element or volume-element methods.

## • Telemac-2D :

- Solves the Saint-Venant equations in two dimensions in non-steady state.

## • Gaia:

- Simulate sediment and morphodynamic processes in coastal areas, rivers, lakes and estuaries, etc.



# Hydro-sediment test case

Yen's [3] experience.

- Five tests conducted in a 180 canal bed, with the same sediment grain size distribution but varying input hydrographs.
- The canal bed comprised a layer of sand approximately 20 cm thick, with an initial median diameter  $d_{50} = 1$  mm.
- The initial flow depth  $h_0 = 5.44$  cm.
- Measurements were recorded at the peak and the end of each hydrograph.
- The hydro-sedimentary 2D model (TELEMAC-2D/GAIA) [4] is used to simulate the experience using the Meyer-Peter and Müller [5] formula for bedload

$$q_b^* = \begin{cases} \alpha_{MPM}(\theta - \theta_{cr})^{1.5} & \text{if } \theta > \theta_{cr} \\ 0 & \text{else} \end{cases}$$

with  $q_b^*$  the non-dimensional bedload rate,  $\alpha_{MPM}$  a factor (equal to 8 in the original formula),  $\theta$  the Shields number, and  $\theta_{cr}$  the critical Shields number for initiation of motion of sediments.

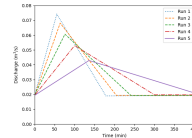


Figure: Hydrographs for experiments.

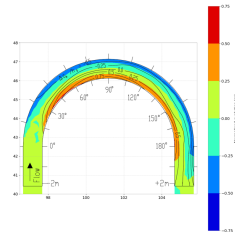


Figure: Contours of bed deformation for Run 4 at the end of the experiment. Negative values indicate erosion

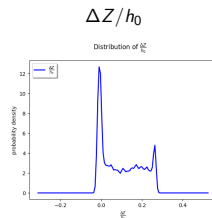
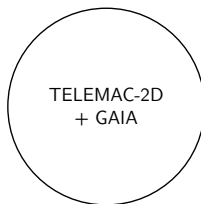
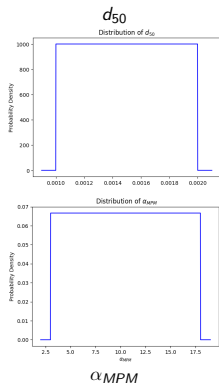
# Uncertainty Propagation

- Inputs :

- Median diameter of sediment  $d_{50} \sim U([0.001, 0.002])$
- Coefficient of Meyer-Peter and Müller  $\alpha_{MPM} \sim U([3, 18])$
- $d_{50}$  and  $\alpha_{MPM}$  are independent.

- Output (QoI) :

- Normalised bottom elevation variation  $\frac{\Delta Z}{h_0} = \frac{Z_t - Z_{t_0}}{h_0}$



# Uncertainty Analysis

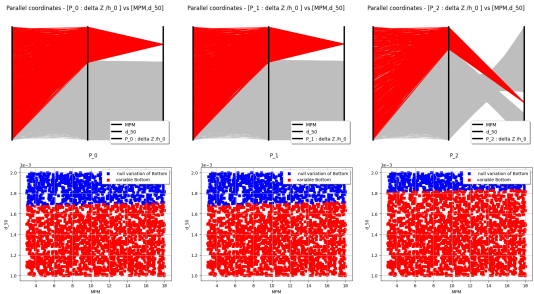
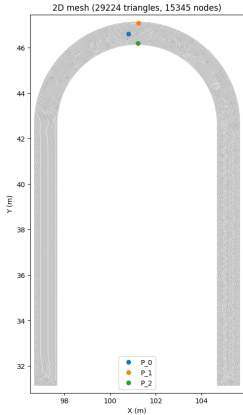


Figure: Bottom elevation variation

Figure: Points of interest

# Application of Tree-PCE

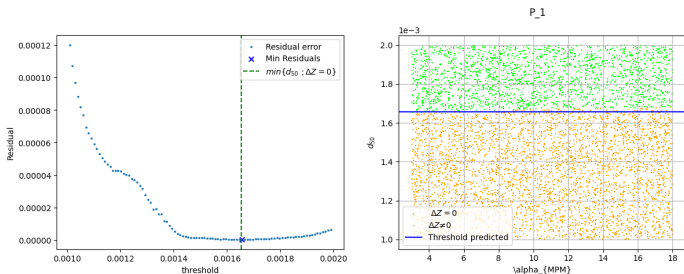


Figure: Detection of threshold

# Comparison of Classic PCE and Tree-PCE

$N_{train} = 1000$

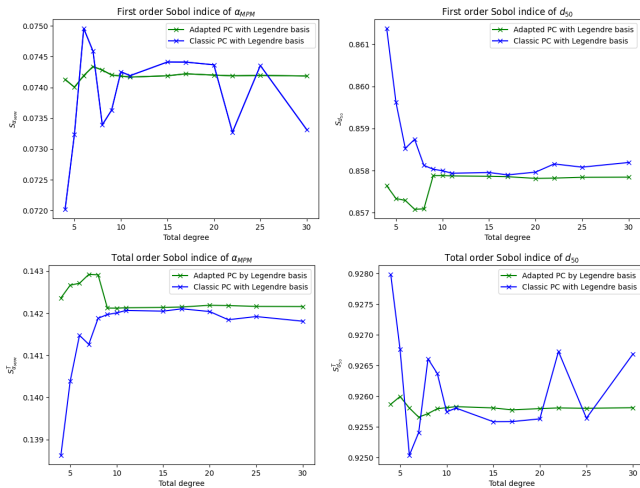


Figure: Convergence of Sobol' indices of  $d_{50}$  and  $\alpha_{MPM}$

# Conclusion and perspectives

- Propagate uncertainty across 4 variables then all variables within the test case and implement Tree-PCE method in such scenarios.
- Model the dependencies between parameters and generalise the Tree-PCE method for dependent variables.



## References

- [1] A. Saltelli.  
Making best use of model evaluations to compute sensitivity indices.  
*Computer Physics Communications*, 2002, 145, 280–297.
- [2] B. Sudret.  
Global sensitivity analysis using polynomial chaos expansions.  
*Reliability Engineering & System Safety*, 2008, 93(7), 964-979.
- [3] Yen, C. L., & Lee, K. T. (1995). Bed topography and sediment sorting in channel bend with unsteady flow.  
*Journal of Hydraulic Engineering*, 121(8), 591-599.
- [4] J.M. Hervouet.  
*Free Surface Flows*, 2007.
- [5] E. Meyer-Peter, R. Müller.  
Formulas for bed-load transport.  
*Proc. IAHR World Congress*, Stockholm, 1948.

# Questions ?

Thank you for your attention !  
Questions ?