

Outline

- Industrial Context
- Building the Digital Twin
 - HiFi Model
 - Metamodel
- Using it
 - For Uncertainty Propagation
 - To Monitor a Given Machine
- Conclusion and Outlook



Outline

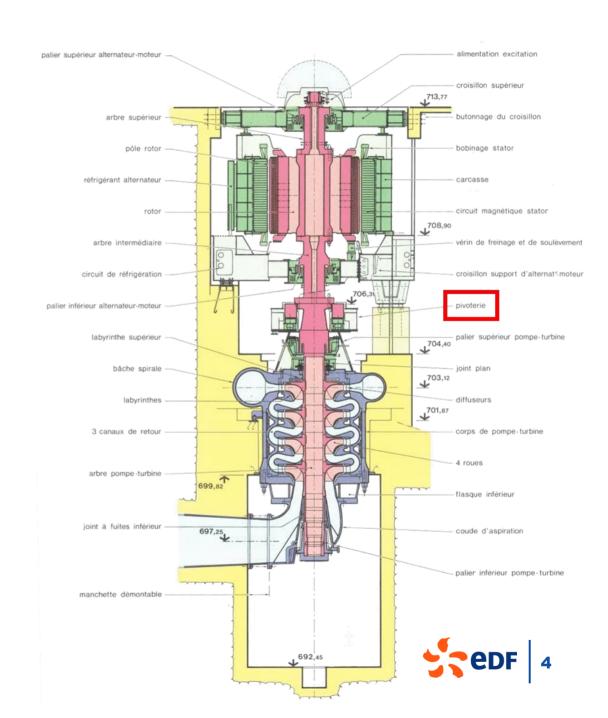
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Industrial Context

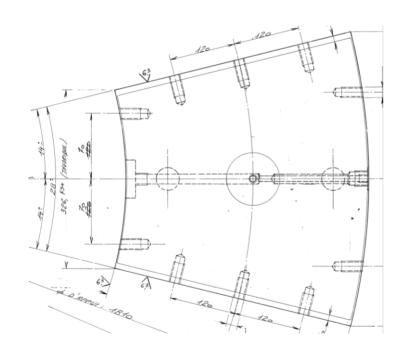
- Hydraulic turbine thrust bearing
 - Key function
 - axial load transfer
 - Costly damage
 - 7M€ from 2016 to 2018

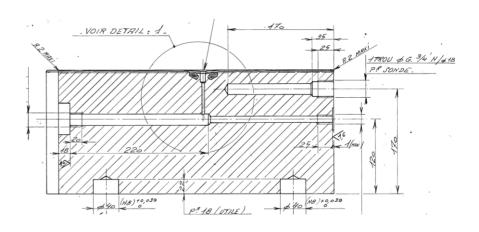




Industrial Context

- Monitored by a single temperature sensor
 - Placed 3cm below the surface and centered in the bearing





Industrial Context

- Digital Twin R&D vision [2]
 - Possibly high-fidelity model
 - Dedicated to a specific targeted problem
 - Powered by measurements
 - To detect a malfunction (monitoring) or analyze a specific situation (diagnosis)
- Expectation vis-à-vis the Digital Twin of the thrust bearing of Grand'Maison
 - Monitoring

[2] Vision of the ERMES department on the Digital Twin, EDF Technical report H 6125-1722-2021-01109-FR

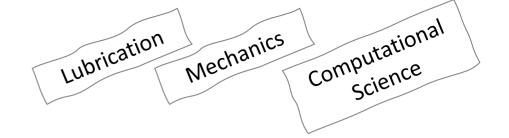


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High-fidelity Model



Coupled formulation

Finite volumes and

Finite Elements

- Thermo-Elasto-Hydro-Dynamic (TEHD) model of the thrust bearing by coupling between Legos (lubrication) and code aster (mechanical) software
 - Multi-physics, multi-scale
- Formulation TEHD

TE...

$$\boldsymbol{\sigma} = \boldsymbol{C_{el}}\boldsymbol{\epsilon} - \alpha \Delta \boldsymbol{T} \boldsymbol{C_{el}} \boldsymbol{I} \qquad \begin{cases} \rho C_p \frac{\partial T}{\partial t} + div(\phi) = 0 \\ \phi = -\lambda \cdot \nabla T \end{cases}$$

...HD

$$\frac{\partial}{\partial x} \left(G_1 \frac{\partial p}{\partial x} \right) + \frac{\partial}{\partial z} \left(G_1 \frac{\partial p}{\partial z} \right) = U \frac{\partial}{\partial x} \left[(1 - \theta) G_2 \right] + \frac{\partial \left[(1 - \theta) \rho h \right]}{\partial t}$$

$$\rho C_p \left[\frac{\partial T}{\partial t} + \frac{\partial (uT)}{\partial x} + \frac{\partial (vT)}{\partial y} + \frac{\partial (wT)}{\partial z} \right] = \lambda \frac{\partial^2 T}{\partial y^2} + \mu \left[\left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial w}{\partial y} \right)^2 \right]$$

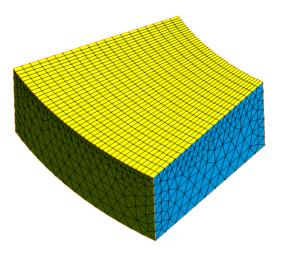
- Highly non-linear simulation
 - Solution time between 20 min and more than 2h
- Need to drastically reduce the evaluation time





Model input parameters

- Pad geometry
- Lubricant
 - Lubricant density (RO) [kg/m3]
 - 853.0
 - Specific heat of the lubricant (CHALEUR) [J/kg/K]
 - 2000.0
 - Thermal conduction coefficient (KHL) [W/m/K]
 - 0.13
 - Fluid supply temperature (TALIM) [degree C]
 - 45.0 ∈ [30; 55]



Model input parameters

- Velocity
 - Collar angular velocity (OMEGA) [tr/mn]
 - 600.0
- Loads
 - Norm of external static load (WES) [N]
 - 539550.0 ∈ [250.E3; 540.E3]
- Temperature
 - Collar constant temperature (TABR) [degree C]
 - 55.0 ∈ TALIM+[0; 50]
 - Oil recycling coefficient (RECYC) [%]
 - 85 ∈ [0; 100]

Model input parameters

Temperature

- Ambient T. (TAMBP) [degree C]
 - 45.0
- Inlet T. (TEF) [degree C]
 - 45.0

Boundary conditions

- Inlet pressure (PLP) [Pa]
 - 100000.0

Model output parameters

- Relevant physical quantities
 - Hmin, Tmax, Pmax in oil film

- Quantities to be compared with measurements
 - Tprobe

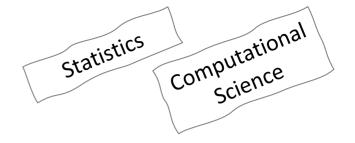


Methodology

- Define a HiFi Thermo-Elasto-Hydro-Dynamic (TEHD) model of the bearing
 - Provided by EDF engineers
- Vary the input parameters of the model and compute the relevant quantities
- Build a metamodel based on previous results



Methodology



- Definition of the high-fidelity model G of the bearing
- Identification
 - of the input parameters that characterize the equipment's operation
 - Drawing on available measurements
 - Of the outputs that characterize the equipment's health
 - If possible, to compare with measurements

• Construction of the metamodel $ilde{G}$

- Parameters of the metamodel (e.g. degree of the polynomial)
- Sufficiently large size n_a of the design of learning experiments
- Generation of a design of experiments $\mathcal{X}_a = \{\mathbf{x}^{(1)}, ..., \mathbf{x}^{(n)}\}$ associated with random vector \mathbf{X}
- Evaluation of model outputs $\mathcal{Y}_a = \{\mathbf{y}^{(1)}, ..., \mathbf{y}^{(n)}\}$ by model evaluation G
- Construction of metamodel \tilde{G} , which approximates G with accuracy to be determined

Methodology

• Validation of the metamodel \tilde{G}

- Selection of a sufficiently large validation design size n_v
- Generation of a design of experiments $\mathcal{X}_v = \{\mathbf{x}^{(1)}, ..., \mathbf{x}^{(n)}\}$ associated with the random vector \mathbf{X}
- Evaluation of model output $\mathcal{Y}_v = \{\mathbf{y}^{(1)}, ..., \mathbf{y}^{(n)}\}$ by evaluation of model G
- Evaluation of metamodel outputs $\mathcal{Y}'_{v} = \{\mathbf{y}'^{(1)}, ..., \mathbf{y}'^{(n)}\}$ by evaluation of metamodel \tilde{G}
- Determination of the deviation between \mathcal{Y}_{v} and \mathcal{Y}_{v} , which must satisfy a given criterion



Computational Science Python Shell SLURM

- Input:
 - Load
 - T oil supply
 - T shaft
 - Recycling rate

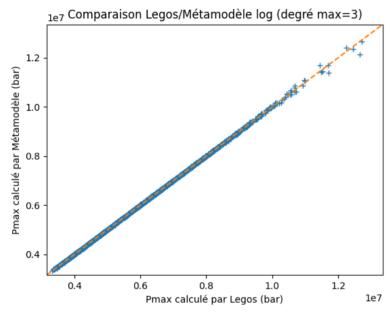
- Range of variation
 - [250; 540] kN
 - [30; 55] °C
 - Talim + [0; 50] °C
 - [0; 100] %

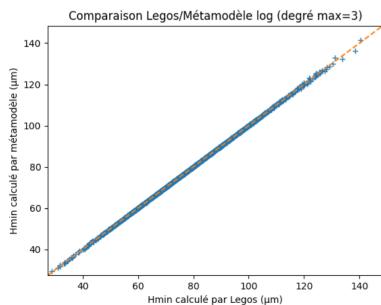
- Output
 - Pmax
 - Tmax
 - Hmin
 - Tprobe in 3 points around the theoretical position

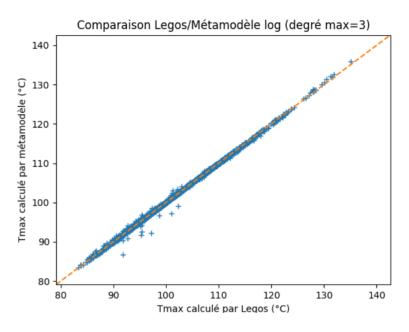
- For the inputs: random draw according to uniform distribution
- Polynomial chaos
- 2000 simulations to build the model
 - ✓ Single solution time: between 20 min and 2h
 - ✓ Parallel solution on EDF R&D cluster: 2500 results in 1 day
- 500 simulations for model validation

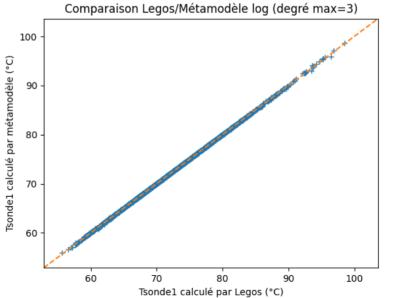














Reliability

- Learning base of 2000 simulations
 - $Q_2 = [0.999913, 0.998122, 0.99993, 0.999933, 0.999933, 0.999933]$
- Validation base of 500 simulations
 - $Q_2 = [0.999915, 0.998537, 0.999917, 0.999931, 0.999931, 0.999931]$

Performance

Metamodel evaluation : ~3.e-5 s

Export

- Easily export the metamodel as a polynomial
- But evaluation in OpenTURNS is preferred (flexibility, performance, scalability)

```
def polyGM(wes, talim, dt, re):
             def poly(xx0, xx1, xx2, xx3):
                          x0 = 6.89655172413793081e-06*(xx0-395000)
                          x1 = 0.080000000000000001665 \times (xx1-42.5)
                          x2 = 0.0400000000000000000033*(xx2-25)
                          x3 = 0.020000000000000000416*(xx3-50)
                          return np.array([15.5993,102.464,4.34388,72.5981,72.3595,72.8033]) + np.array([0.269326,4.93465,-0.181507,2.10261,2.09978,2.10061]) * (1.73205 * x0) +
np.array([0.0337926, 4.23664, -0.114819, 5.24478, 5.27776, 5.20956]) * (1.73205 * x1) + <math>np.array([0.000267558, 0.837838, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.114819, 5.24478, 5.27776, 5.20956]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.114819, 5.24478, 5.27776, 5.20956]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.0337926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.037926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + <math>np.array([0.037926, 4.23664, -0.0801463, 0.701439, 0.722108, 0.682507]) * (1.73205 * x1) + \\ (1.73205 * x1) + (1.73205 * x
x^2) + np.array([0.0710881,4.44855,-0.113681,4.92222,4.96248,4.8793]) * (1.73205 * x^3) + np.array([-0.0187358,-0.169745,0.00782219,-0.0835755,-0.082128,-0.0848066]) * (-0.082128,-0.0848066)
1.11803 + 3.3541 * x0**2) + np.array([0.00969675, 0.350995, -0.0119131, 0.107225, 0.108172, 0.105475]) * ((1.73205 * x0) * (1.73205 * x1)) + np.array([0.0050355, 0.797338, -0.0119131, 0.107225, 0.108172, 0.105475])
0.0204107, 0.143264, 0.14622, 0.140077) * ((1.73205 * x0) * (1.73205 * x2)) + np.array([0.0163678, 0.28551, -0.0129543, 0.260619, 0.261321, 0.259268]) * ((1.73205 * x0) *
(1.73205 * x3)) + np.array([0.00370576, 0.404428, -0.00209024, 0.21477, 0.213017, 0.216245]) * (-1.11803 + 3.3541 * x1**2) + np.array([0.00732481, 1.19426, -0.00209024, 0.21477, 0.213017, 0.216245])
0.0117639, 0.406104, 0.407277, 0.404315]) * ((1.73205 * x1) * (1.73205 * x2)) + np.array([0.00612331, 0.203418, 0.00237175, 0.149927, 0.1417, 0.158002]) * ((1.73205 * x1) *
(1.73205 * x3)) + np.array([0.00421135,0.600557,-0.00868402,0.111148,0.112916,0.10916]) * (-1.11803 + 3.3541 * x2**2) + np.array([0.0166096,1.33418,-0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112916,0.112
0.0228652, 1.1064, 1.10997, 1.10174) * ((1.73205 * x2) * (1.73205 * x3)) + np.array([0.0113299, 0.499431, -0.0117073, 0.564053, 0.563604, 0.564456]) * (-1.11803 + 3.3541 *
x3**2) + np.array([0.00263682,0,-0.00090607,0.0126441,0.0123289,0.0129106]) * (-3.96863 * x0 + 6.61438 * x0**3) + np.array([0.000849687,0,-0.00090607,0.0126441,0.0123289,0.0129106])
0.000278201, 0.0162081, 0.0160392, 0.0162322) * ((-1.11803 + 3.3541 * x0**2) * (1.73205 * x1)) + np.array([0.0017717, 0.0931773, -0.00126602, 0.0353856, 0.0354583, 0.0350407])
* ((-1.11803 + 3.3541 * x0**2) * (1.73205 * x2)) + np.array([0,-0.124199,0.00100414,-0.0132816,-0.0139134,-0.0126875]) * <math>((-1.11803 + 3.3541 * x0**2) * (1.73205 * x2)) + np.array([0,-0.124199,0.00100414,-0.0132816,-0.0139134,-0.0126875])
np.array([0.001056,-0.0385535,-0.000818417,0.0058737,0.00601778,0.00555466]) * ((1.73205 * x0) * (-1.11803 + 3.3541 * x1**2)) + np.array([0.00354928,0.159613,-0.00818417,0.00818417,0.0088737,0.00601778,0.00555466])
0.00430059, 0.0805405, 0.0812053, 0.0793082) * ((1.73205 * x0) * (1.73205 * x1) * (1.73205 * x2)) + np.array([0.000922633,-0.183642,0.000669539,-0.0304405,-0.0308419,-
0.0301453]) * ((1.73205 * x0) * (1.73205 * x1) * (1.73205 * x3)) + np.array([0.0020289,0.136922,-0.00339964,0.0561628,0.0567422,0.0552875]) * ((1.73205 * x0) * (-1.11803)
+ 3.3541 * \times 2**2)) + np.array([0.00463657,0.0886418,-0.003131,0.050864,0.0508911,0.0503563]) * ((1.73205 * \times 2**2)) + np.array([0.00463657,0.0886418,-0.003131,0.050864,0.0508911,0.0503563]) *
np.array([0.000893778, -0.203872, 0.00119797, -0.0634035, -0.0644517, -0.062312]) * ((1.73205 * x0) * (-1.11803 + 3.3541 * x3**2)) + <math>np.array([0.-0.0395469, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.000180722, -0.00018072, -0.00018072, -0.00018072, -0.00018072, -0.00018072, -0.00018072, -0
0.0129769, -0.0128067, -0.0131769]) * (-3.96863 * x1 + 6.61438 * x1**3) + np.array([0.0012834,0.077977,-0.00162338,0.0174295,0.017607,0.0169858]) * ((-1.11803 + 3.3541 *
x1**2) * (1.73205 * x2)) + np.array([-0.000229625,-0.150633,0,-0.0710436,-0.0702665,-0.0718228]) * ((-1.11803 + 3.3541 * x1**2) * (1.73205 * x3)) +
np.array([0.00150281, 0.268943, -0.00242826, 0.0504768, 0.0507294, 0.0498739]) * ((1.73205 * x1) * (-1.11803 + 3.3541 * x2**2)) + np.array([0.00358788, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.0451455, -0.045
0.00314931, 0.0637257, 0.0636546, 0.0634541) * ((1.73205 * x1) * (1.73205 * x2) * (1.73205 * x3)) + np.array([-0.00134542,-0.190119,0.00259862,-0.13956,-0.139932,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,-0.13956,
0.139095]) * ((1.73205 * x1) * (-1.11803 + 3.3541 * x3**2)) + np.array([0.000498105,0.161067,-0.00113193,0.0211751,0.0213776,0.0208633]) * (-3.96863 * x2 + 6.61438 *
x^2**3) + np.array([0.00161123,0.0593789,-0.00152871,0.0573089,0.056972,0.0573396]) * ((-1.11803 + 3.3541 * x^2**2) * (1.73205 * x^3)) + np.array([0.0025699,0.0820464,-
0.00198255, 0.0570014, 0.0561445, 0.0578167) * ((1.73205 * x2) * (-1.11803 + 3.3541 * x3**2)) + np.array([0.000469852, -0.0628267, 0.000356894, -0.00641126, -0.00696054, -0.00696054])
0.005777291) * (-3.96863 * x3 + 6.61438 * x3**3)
```

```
resu = _poly(wes, talim, dt, re)
Pmaxlog, Tmax, Hminlog, Tsonde1, Tsonde2, Tsonde3 = resu
return np.exp(Pmaxlog), Tmax, np.exp(Hminlog), Tsonde1, Tsonde2, Tsonde3
```



Benefits of the Metamodel

Extreme speed of evaluation with good accuracy

- Easily allows
 - Uncertainty propagation to assess the sensitivity of the Digital Twin
 - Customizing the Digital Twin for a specific machine

Outline

- Industrial Context
- Building the Digital Twin
 - HiFi Model
 - Metamodel
- Using it
 - For Uncertainty Propagation
 - To Monitor a Given Machine
- Conclusion and Outlook

Uncertainty Propagation



- Input:
 - Load
 - T oil supply
 - T shaft
 - Recycling rate

- Range of variation
 - *𝒩*(WES, 30.e3) kN
 - *𝒩* (Talim, 2) °C
 - Talim + $\mathcal{N}(DT, 2)$ °C
 - *𝒩*(RECYC, 20) %

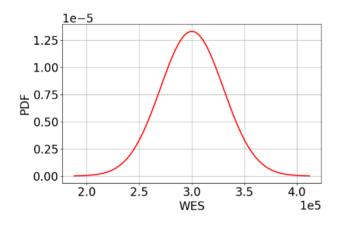
- Output
 - Pmax
 - Tmax
 - Hmin
 - Tprobe in 3 points around the theoretical position

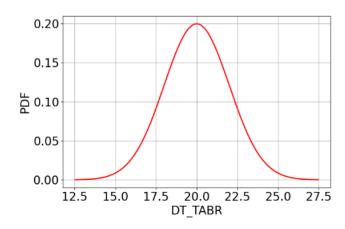
- Propagation of uncertainty on output parameters
 - Drawing of 5000 samples of input parameters
 - Outputs Evaluations
- Outputs with uncertainty
 - Allows quantify the risk of exceeding a given threshold
 - No "Yes" or "No" but "You have x% of chance to exceed the threshold"

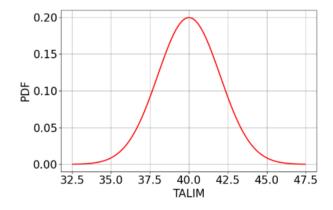


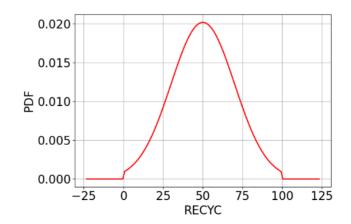
Uncertainty Propagation

Input parameters





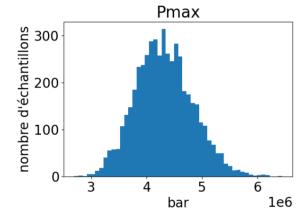


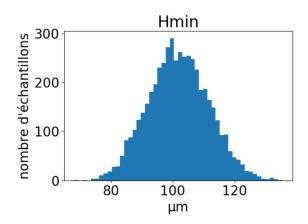


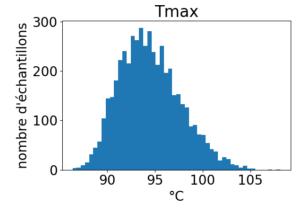


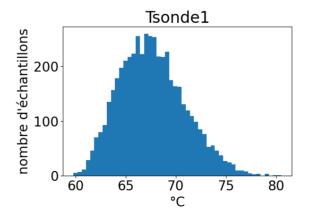
Uncertainty Propagation

Outputs











Customizing the Digital Twin

- Load measurements carried out at GM in September 2020 by EDF/DTG
 - G06 chosen for this test
 - Temperatures also recorded in the monitoring system during the pumping and turbining measurements

$$y^{obs} = \begin{cases} T_{\text{measure}}^{\text{pumping}} \\ T_{\text{turbining}}^{\text{turbining}} \end{cases}$$

• Digital Twin's fitting taking into account uncertainties about parameters

$$x = \begin{cases} \begin{cases} WES \\ TALIM \\ TABR \\ RECYC \end{cases} \\ \begin{cases} WES \\ TALIM \\ TABR \\ RECYC \end{cases} \end{cases} turbining$$

$$y = egin{cases} T_{ ext{twin}}^{ ext{pumping}} \\ T_{ ext{turbining}}^{ ext{turbining}} \end{cases}$$

3DVar Approach



Functional to minimize

minimize
$$\min_{x} J(x)$$

$$J(x) = (x - x^{b})^{T} B^{-1}(x - x^{b}) + (y - y^{obs})^{T} R^{-1}(y - y^{obs})$$

- x^b initial value of x
- B and R Covariance matrices of background noise error and observational error
- Implemented in the ADAO Module of the Salomé Platfom

Customizing the Digital Twin

- Initial value for x
 - Turbining
 - WES = 398 tons, TALIM=48.8 °C, TABR=58.8 °C, RECYC=80%
 - Pumping
 - WES = 492 tons, TALIM=48.1 °C, TABR=58.1 °C, RECYC=80%
- Identified values for x
 - Turbining
 - WES = 373 tons, TALIM=47.6 °C, TABR=59.6 °C, RECYC=30%
 - Pumping
 - WES = 464 tons, TALIM=47.2 °C, TABR=55.3 °C, RECYC=36%
 - Significant decreases in variance for these parameters



Customizing the Digital Twin

- Comparing Digital Twin Measures
 - Pumping
 - Tmetal_metaModel = 71.9 et Tmetal_PI = 65.1 => 10% error
 - Pmax= 5.5 MPa, Tmax=100. °C, Hmin=85. μm
 - Turbining
 - Tmetal_metaModel = 74.3 et Tmetal_ PI = 68.7 => 7% error
 - Pmax= 7.3 MPa, Tmax=105. °C, Hmin=72. μm
- Tailored Digital Twin
 - Dedicated to monitoring this specific machine

Outline

- Industrial Context
- Building the Digital Twin
 - HiFi Model
 - Metamodel
- Using it
 - For Uncertainty Propagation
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Conclusion

- Metamodel construction methodology taking into account uncertainty on input parameters
 - High-fidelity model + metamodel over a range of input parameter variations
- Enables easy propagation of uncertainty
 - Quantifies the risk of exceeding thresholds
- Allows the Digital Twin to be customized for a given machine
 - Access to quantities that are crucial to equipment health, but inaccessible to measurement
- 1
- Strong multidisciplinary dimension around the Digital Twin technology
- ! ^
 - All done in the Salome_Meca platform

Outlook

- Evaluation of the Digital Twin on other Grand'Maison machines
- Integration of the evaluation of the load applied to the thrust bearing
 - Work in progress
 - Allows the Digital Twin to be used for monitoring purposes
- Generalization to other machines

Thank you for your attention