

Embedded Systems CSEN701

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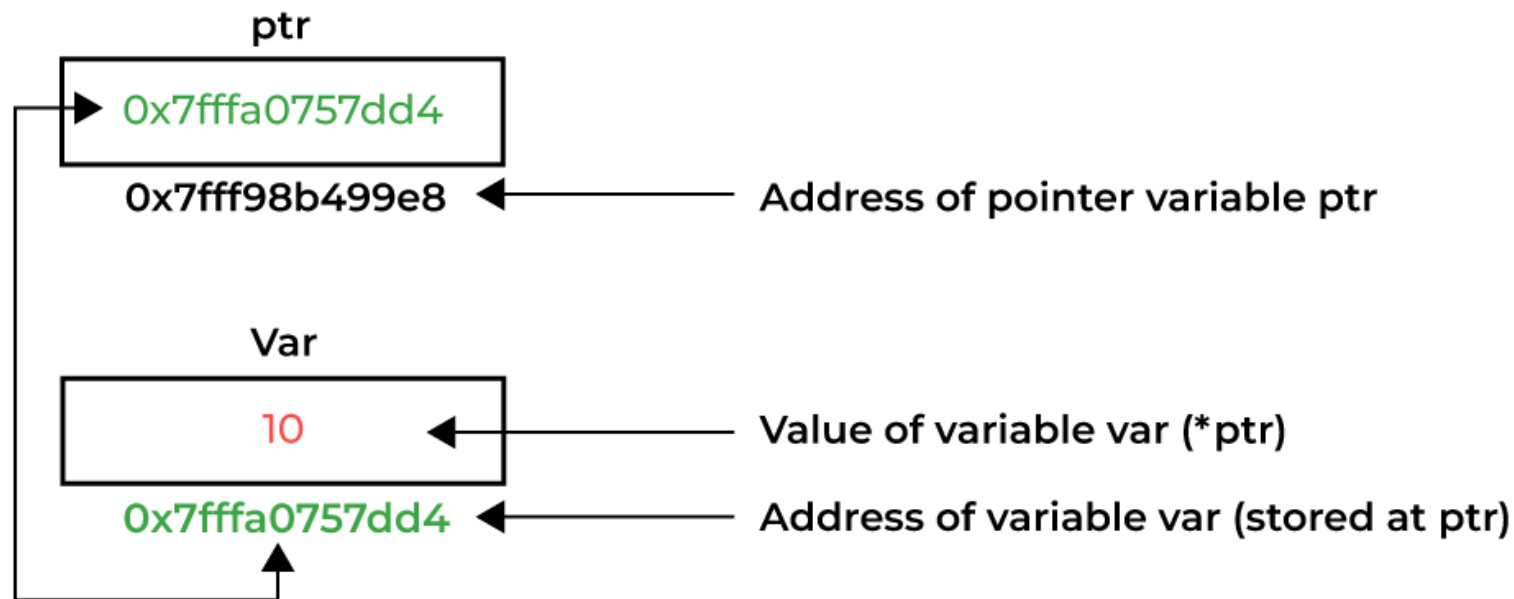
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Outline :

- ◎ **Recap.**
- ◎ Arduino Components.
- ◎ Harvard Architecture vs Von Neuman Architecture.
- ◎ AVR architecture.
- ◎ PINs and Ports in AVR.
- ◎ Bitwise operations
- ◎ Examples

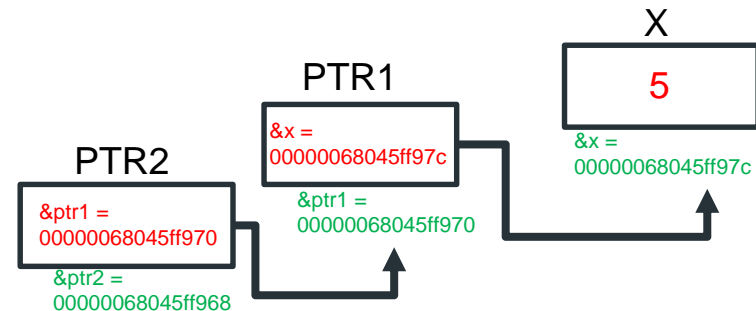
Pointers in C.



Pointers in C.

```
int main ( void ){
    int x = 5 ;
    int *ptr1= &x ;
    int **ptr2 = &ptr1 ; // Pointer to pointer to integer

    printf( " value of X : = %d \n" , x ) ;
    printf( " value of address X = %p \n " , &x ) ;
    printf( " value of the pointer 1 = %p \n" , ptr1 ) ;
    printf( " value of address pointer 1 = %p \n" , &ptr1 ) ;
    printf( " value of Asterisk POINTER 1 = %d \n " , *ptr1 ) ;
    printf( " value of ASTERISK address of pointer 1 = %p \n " , *&ptr1 ) ;
    printf( " value of pointer 2 = %p \n " , ptr2 ) ;
    printf( " value of asterisk pointer 2 = %p \n " , *ptr2 ) ;
    printf( " value of double asterisk pointer 2 = %d \n " , **ptr2 ) ;
    printf( " value of address pointer 2 = %p \n " , &ptr2 ) ;
    printf( " value of asterisk address pointer 2 = %p \n " , *&ptr2 ) ;
}
```



value of X : = 5
 value of address X = 00000068045ff97c
 value of the pointer 1 = 00000068045ff97c
 value of address pointer 1 = 00000068045ff970
 value of Asterisk POINTER 1 = 5
 value of ASTERISK address of pointer 1 = 00000068045ff97c
 value of pointer 2 = 00000068045ff970
 value of asterisk pointer 2 = 00000068045ff97c
 value of double asterisk pointer 2 = 5
 value of address pointer 2 = 00000068045ff968
 value of asterisk address pointer 2 = 00000068045ff970

Pass By Value

VS

Pass By address

```

3=void increment( int a){
4   a = a+5 ; // a new Local variable is created
5   printf( " the value of 'a' inside increment is %d  ", a) ;
6   printf( " the address of 'a' is %p \n ", &a) ;
7 } // local variable value is lost once we get out of the function
8= int main( void) {
9   int x = 5 ;
10  printf( " the value of 'x' before increment is %d ", x) ;
11  printf( " the address of 'x' is %p \n ", &x) ;
12  increment(x) ;
13  printf( " the value of 'x' after increment is %d ", x) ;
14 // X is passed by value . the value of x is copied to a local variable a
15 // real value of x in not altered !!!!
16 }

```

Console ×

terminated> (exit value: 0) tut_2_CSEN701.exe [C/C++ Application] C:\Users\Abdalla\workspace\tut_2_CSEN701\Debug\tut_2_CSEN701.exe (10/5/23

the value of 'x' before increment is 5 the address of 'x' is 00000060383ffc0c
 the value of 'a' inside increment is 10 the address of 'a' is 00000060383ffb0e
 the value of 'x' after increment is 5

```

3=void increment( int * a){
4   *(a) = *(a)+5 ; // pointer to integer is introduced to carry the address of x
5   printf( " the value of 'a' inside increment is %d  ", *a) ;
6   printf( " the address of 'a' is %p \n ", a) ;
7 }
8= int main( void) {
9   int x = 5 ;
10  printf( " the value of 'x' before increment is %d ", x) ;
11  printf( " the address of 'x' is %p \n ", &x) ;
12  increment(&x) ;
13  printf( " the value of 'x' after increment is %d ", x) ;
14 // X is passed by address . the address of x is sent to the function
15 // real value of x is edited !!!!
16 }

```

Console ×

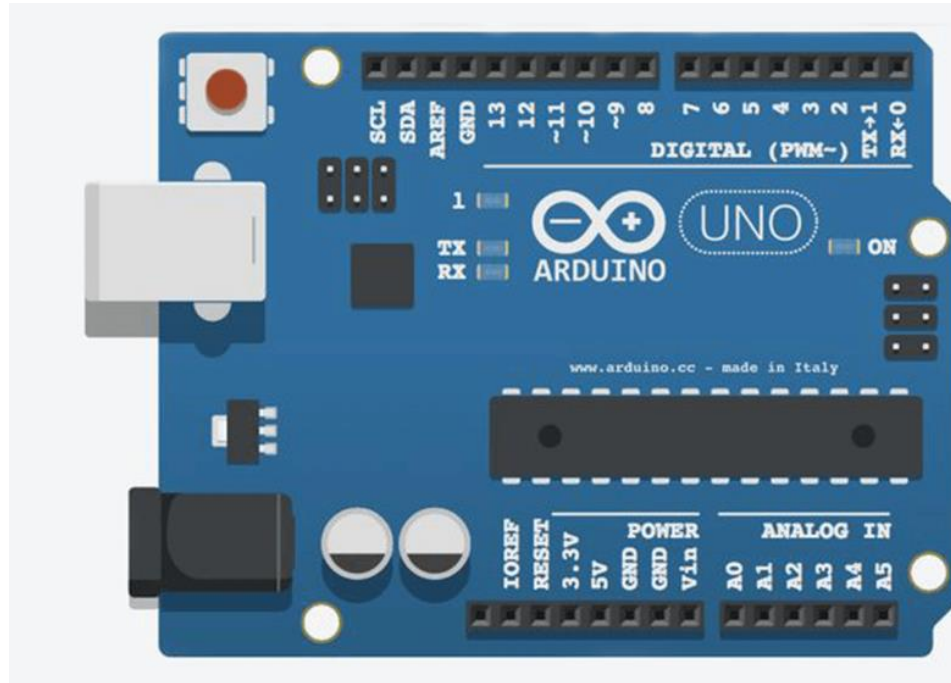
terminated> (exit value: 0) tut_2_CSEN701.exe [C/C++ Application] C:\Users\Abdalla\workspace\tut_2_CSEN701\Debug\tut_2_CSEN701.exe (10/5/23, 6:11 PM)

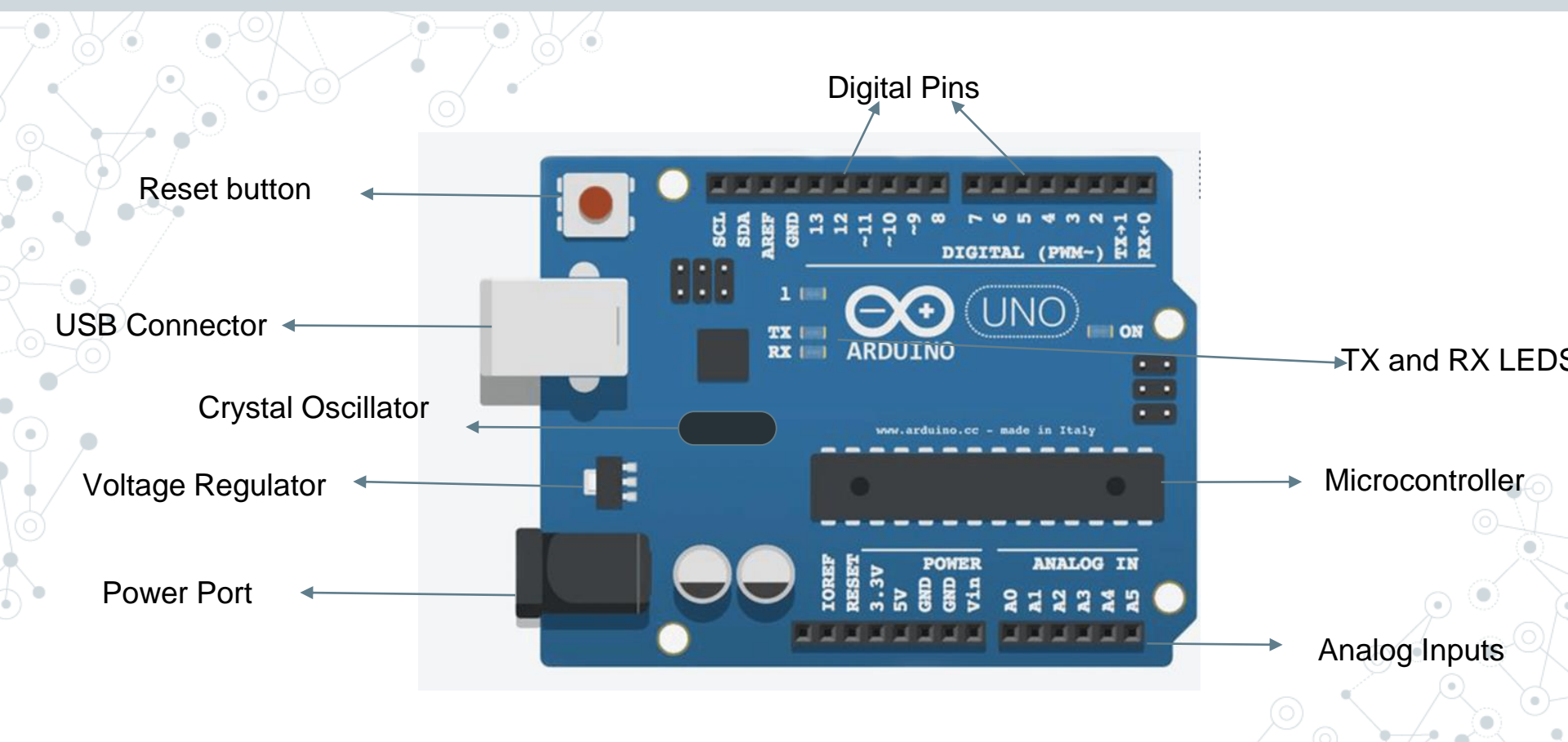
the value of 'x' before increment is 5 the address of 'x' is 0000003f23fff94c
 the value of 'a' inside increment is 10 the address of 'a' is 0000003f23fff94c
 the value of 'x' after increment is 10

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- ◎ Examples

Can you name the components?

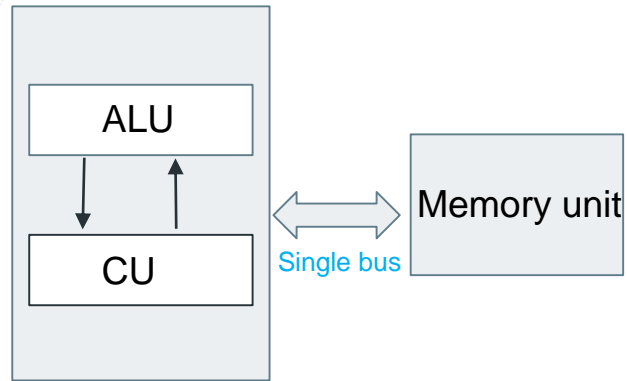




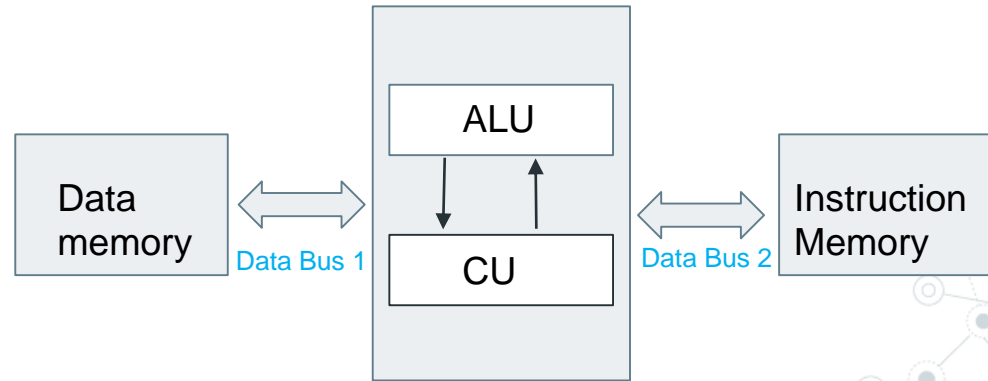
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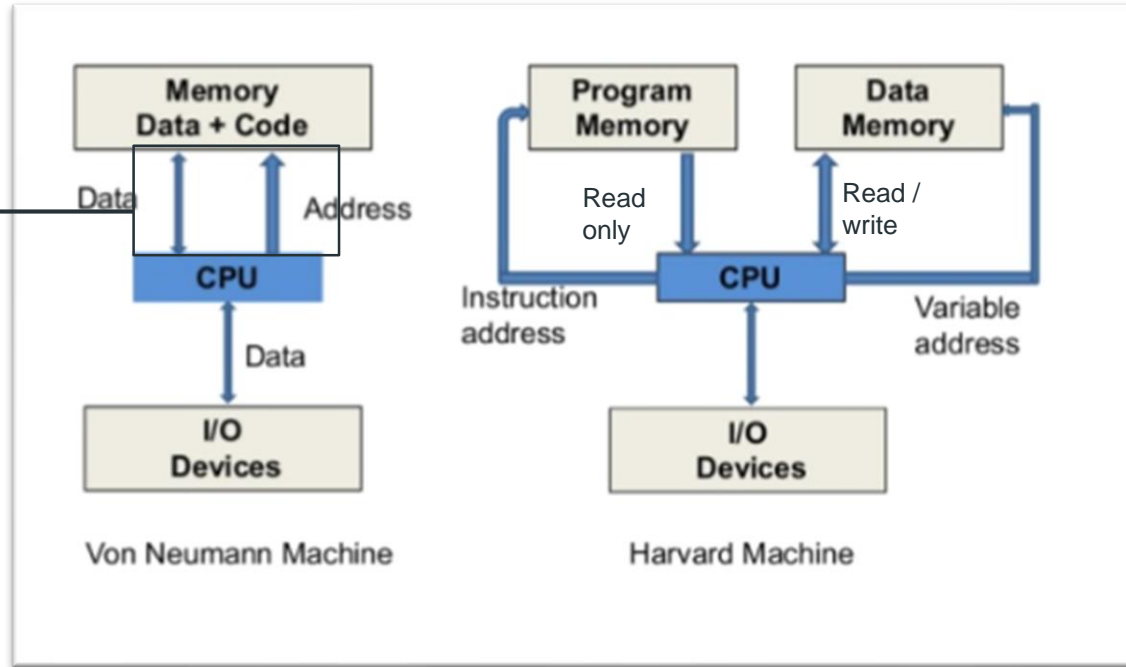
Von Neuman



Harvard



Single data bus



Von Neuman

- Instruction fetch and data operation cannot happen at the time.
- The instructions and data are in the same place so **they use a common bus**.

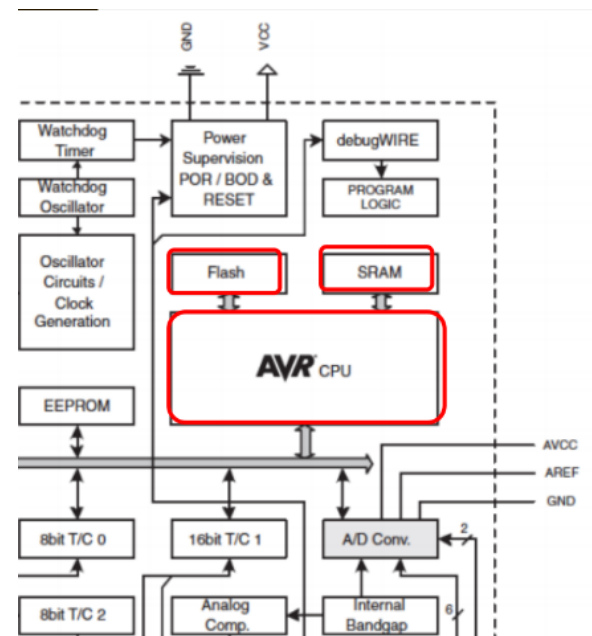
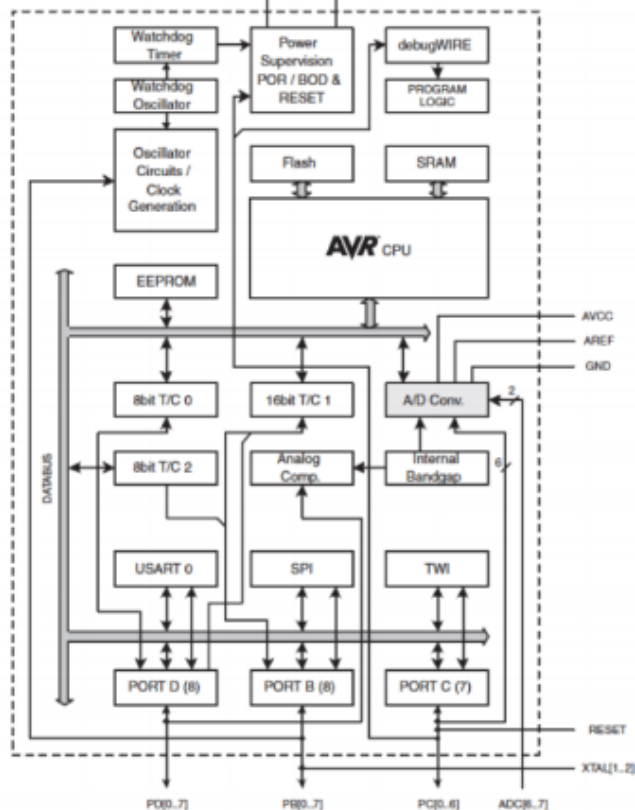
Harvard

- The instructions are in separate memory.
- There are **two buses** one between control unit and instruction memory and one between data memory and control unit.

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AVR architecture from Data Sheet



AVR architecture

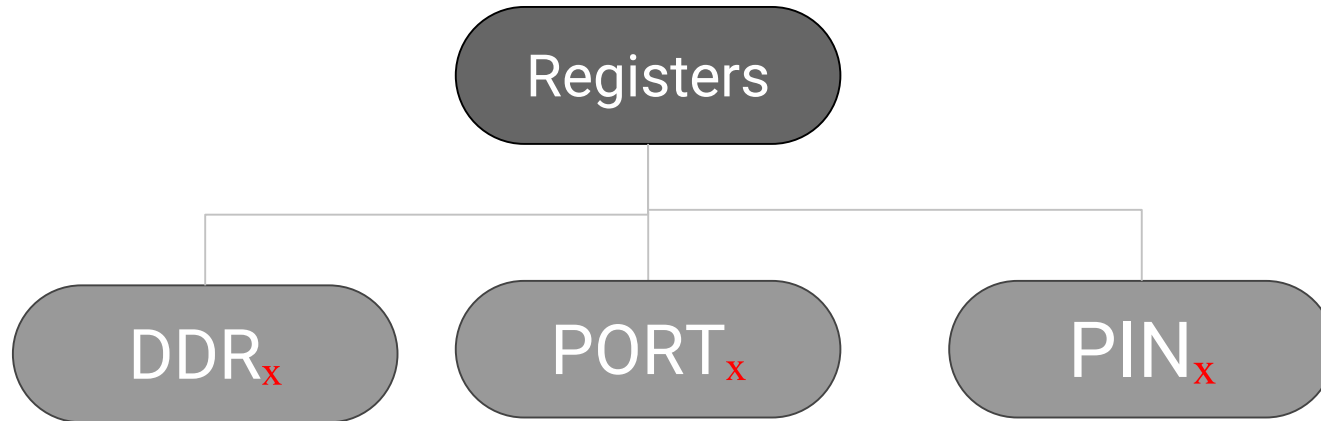
- **Simple Instruction Set:** AVR uses a small, well-defined set of instructions, each of which performs a single operation. This simplicity leads to efficient and fast execution so it's based on **RISC architecture**.
- **Separate Program and Data Memory:** AVR architecture features distinct memory spaces for program instructions (Flash memory) and data (SRAM). **This separation allows for simultaneous access to program and data**, improving performance.
- **Separate Buses:** It employs **separate buses** for program memory and data memory, enabling parallel fetching of instructions and data.

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Ports in Arduino AVR

- ⦿ A port on the Arduino is a group of pins, each consists of 3 types of registers that control the functionality of this port. These registers determine the setup of the pins.



* **x** is the name of the port (A ,B, C or D) *

DDR register

- DDR register is the register the determine the **data direction** for a group of pins .
- You can select whether a certain pin is input or output by changing the value of the corresponding bit in the DDR register .
- Ex:- if we want to set pin 5 in port B as input , then this bit is set to 0 , if we want to set it to output then it is set to 1
- So if all pins are set to input and only pin 5 is set to output in port B, the value of the DDR_B is **00100000 = 0x20**

Bit	7	6	5	4	3	2	1	0
	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:0 – DDRBn: Port B Data Direction [n = 7:0]

PORT register

- ◎ PORT registers have 2 functionalities :
 - If the bit is set to output in DDR register :
 - If a bit in the register is set to **1** , then the corresponding pin is driven **HIGH**
 - If a bit in the register is set to **0** , then the corresponding pin is driven **LOW**

Bit	7	6	5	4	3	2	1	0	
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

PORT register

◎ PORT registers have 2 functionalities :

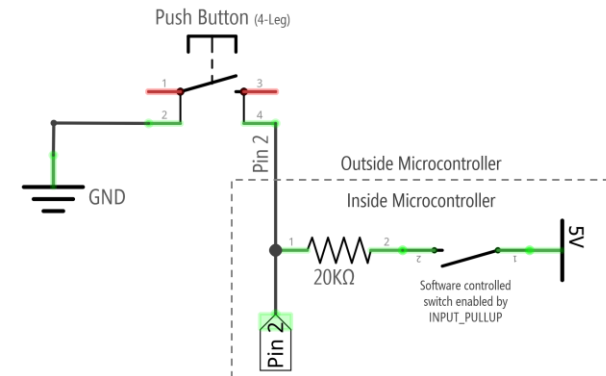
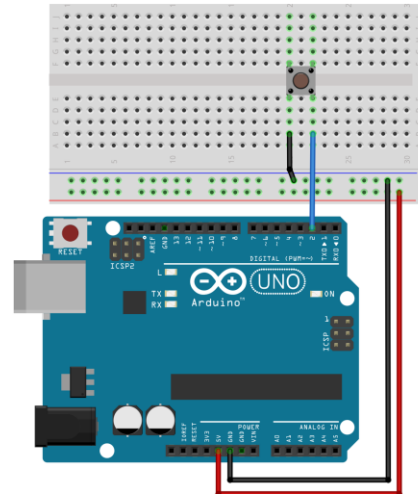
- If the bit is set to input in DDR register :
 - If a bit in the PORT register is set to **1** , then the internal pull up resistor is activated.
 - If a bit in the PORT register is set to **0** , then the pin is tri-stated (default input pin).

Bit	7	6	5	4	3	2	1	0	
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

PORT register

- If the bit is set to input **0** in DDR register and the same bit in the PORT register is set to **1**, then the internal pull up resistor is activated at the corresponding pin.
- The Initial Value of this pin will be High in case of no input signal.

INTERNAL PULL-UP RESISTOR CONFIGURATION



PIN register

- ◎ PIN registers are used to read the input data from a port pin
- ◎ When the pin is set as **input** in the DDR, and the **pull-up resistor is enabled** (in the PORT register) then the bit will indicate the state of the signal at the pin.

Bit	7	6	5	4	3	2	1	0	
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	

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- ◎ Examples

Bitwise operations in C

◎ Bitwise operations are used to directly manipulate registers in embedded C .

◎ Bitwise operations are used to :

- Set bits (**LOGIC HIGH**)
- Clear bits (**LOGIC LOW**)
- Toggle bits (**XORING**)
- Shift bits

Operator	Description
&	bitwise AND
	bitwise OR
^	bitwise exclusive OR
<<	shift left
>>	shift right
~	one's complement

SET BITS

DDRD = 0b00000000 ; DDRD = 0x00 ; (hexadecimal)

Set bits 0 and 2 as outputs :

DDRD = 0b00000101 ; DDRD = 5 ; (PORT Assignment)
DDRD |= 5 ; / (*DDRD = DDRD | 0b00000101*)

DDRD
OR
5

|

00000000

00000101

Hint 1 : any bit
ORED | with 0 is
unchanged

Hint 2 : any bit
ORED | with 1 is
SET

DDRD 00000101 (bit assignment)

Bit	7	6	5	4	3	2	1	0
	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:0 – DDRBn: Port B Data Direction [n = 7:0]

x = 20

00010100

x << 3 =

000101000000

Vacated bitsFilled bits

Fig: Shifting bits towards left 3 times

bit 1	bit 2	&		^	~ bit 1	~ bit 2
0	0	0	0	0	1	1
0	1	0	1	1	1	0
1	0	0	1	1	0	1
1	1	1	1	0	0	0

SET BITS

DDRD = 0b00000000 ; DDRD = 0x00 ; (hexadecimal)
Set bits 0 and 2 as outputs :

$DDRD |= (1<<0) | (1<<2) ;$ (1<<bit number)

DDRD

(1<<0)

(1<<2)

OR

0 0 0 0 0 0 0 0

0 0 0 0 0 0 0 1

0 0 0 0 0 1 0 0

Hint : any bit
ORED | with 0 is
unchanged

DDRD = 0 0 0 0 0 1 0 1

Hint 2 : any bit
ORED | with 1 is
SET

only targeted bits are assigned and set

Bit	7	6	5	4	3	2	1	0
	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:0 – DDRBn: Port B Data Direction [n = 7:0]

DDRD = 0b00000101 ;

DDRD |=5 ;

DDRD |= 0x05 ;

DDRD |= (1<<0)|(1<<2);

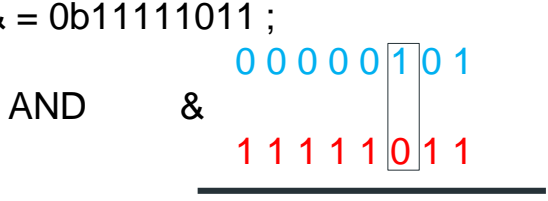


CLEAR BITS

DDRD = 0b00000101 ; DDRD = 0x05 ; (hexadecimal)

Clear bit 2 to change it to input pin :

DDRD = 0b00000001 ; DDRD = 1 ; (PORT Assignment)
DDRD &= 0b11111011 ;



Hint 1 : any bit
ANDED | with 1 is
unchanged

Hint 2 : any bit
ANDED | with 0 is
cleared

DDRD 0 0 0 0 0 0 0 1 (bit assignment)

Bit	7	6	5	4	3	2	1	0
	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:0 – DDRBn: Port B Data Direction [n = 7:0]

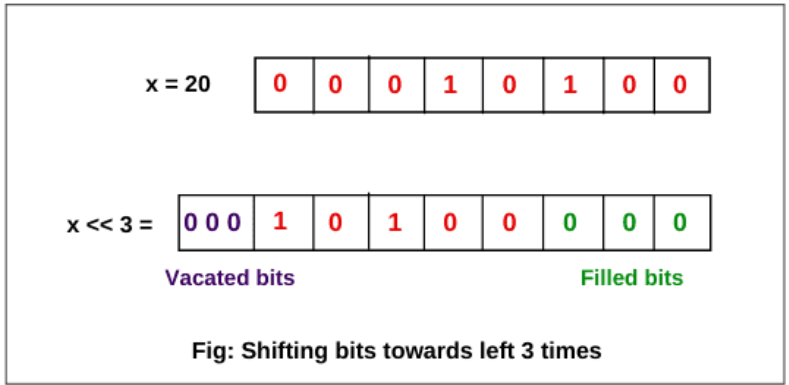


Fig: Shifting bits towards left 3 times

bit 1	bit 2	&		^	~ bit 1	~ bit 2
0	0	0	0	0	1	1
0	1	0	1	1	1	0
1	0	0	1	1	0	1
1	1	1	1	0	0	0

CLEAR BITS

```
DDRD = 0b00000101 ; DDRD = 0x05 ; (hexadecimal)  
Clear bit 2 to change it to input pin :  
DDRD &= 0b11111011 ; 0b11111011 == ~(00000100)  
DDRD &= ~(0b00000100)
```

DDRD

AND

~(1<<2)

0 0 0 0 0 1 0 1

&

1 1 1 1 1 0 1 1

Hint 1 : any bit
ANDED | with 1 is
unchanged

Hint 2 : any bit
ANDED | with 0 is
cleared

DDRD 0 0 0 0 0 0 0 1
only targeted bits are assigned and cleared

Bit	7	6	5	4	3	2	1	0
	DDRB7	DDRB6	DDRB5	DDRB4	DDRB3	DDRB2	DDRB1	DDRB0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 7:0 – DDRBn: Port B Data Direction [n = 7:0]

```
DDRD = 0b00000001 ;
```

```
DDRD &= 0b11111011 ;
```

```
DDRD &= ~(0b00000100) ;
```

```
DDRD &= ~(1<<2);
```



Bitwise operations in a Nutshell

- ❖ SET BIT : $REG \mid = (1 \ll \text{bit_number}) \mid (1 \ll \text{bit_number}) \dots$
- ❖ CLEAR BIT : $REG \&= \sim(1 \ll \text{bit_number}) \& \sim(1 \ll \text{bit_number}) \dots$
- ❖ TOGGLE BIT : $REG \wedge= (1 \ll \text{bit_number}) \wedge (1 \ll \text{bit_number}) \dots$

HINTS :

- ✓ any bit ORED | with 0 is **unchanged**
- ✓ any bit ORED | with 1 is **SET**
- ✓ any bit ANDED | with 1 is **unchanged**
- ✓ any bit ANDED | with 0 is **cleared**
- ✓ any bit XORED | with 1 is **Toggled**

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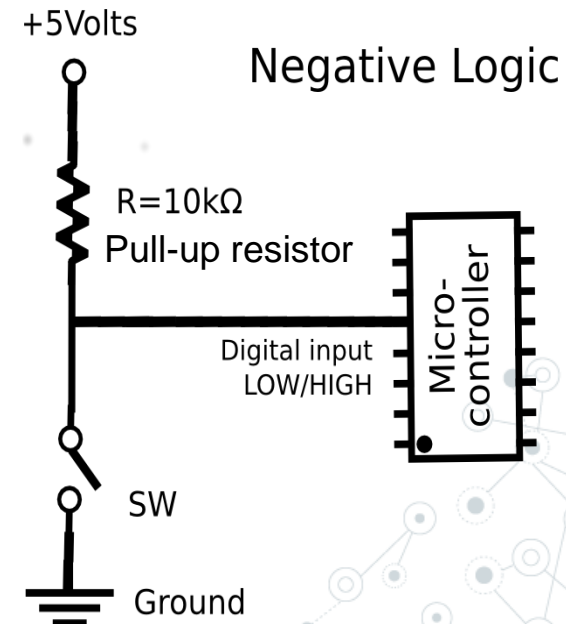
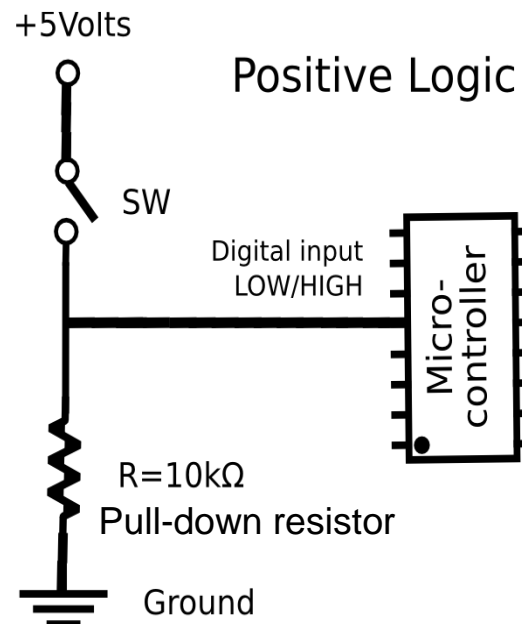
EX1

Implement an embedded C code to :

1. Connect push button A to pin 5 in PORT C (**Positive Logic**)
2. Connect push button B to pin 3 in PORT B (**Negative Logic**)
3. Apply the Internal pullup resistor to pin3 PORT B
4. Configure PIN 2 in PORTD as output
5. Connect Pin 2 to RED LED Pin5-- RED (**Hardware step**)
6. Turn on Red LED when A is pressed
7. Turn off the RED LED when B is pressed .

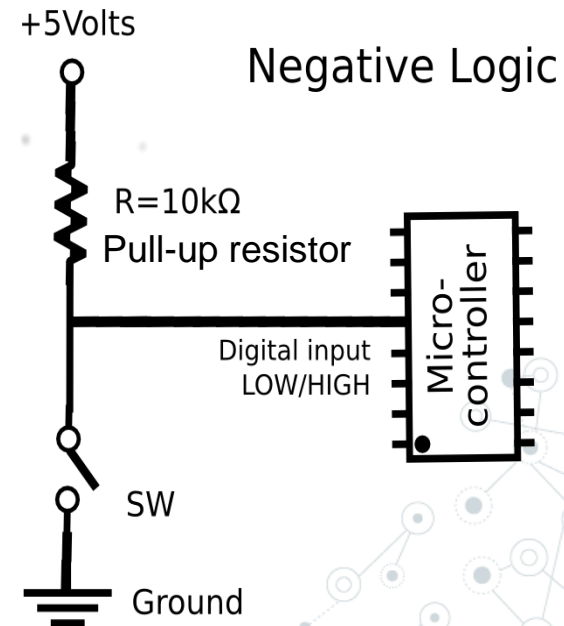
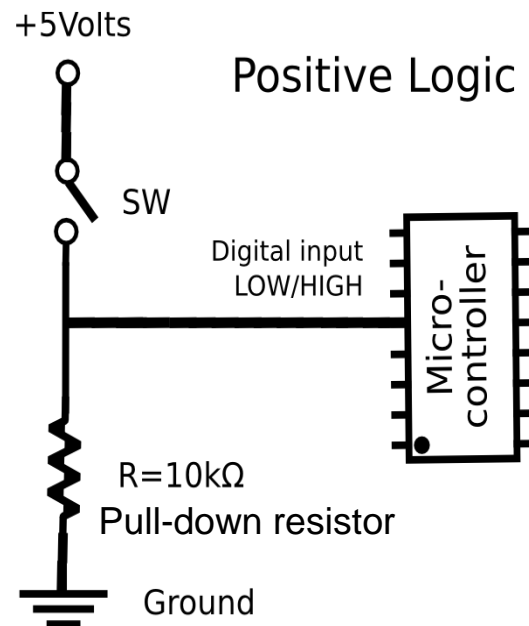
But first we have to understand different digital logics ...

- Positive logic is the **default logic** , the input is initially **low** until the button is ON /activated so it deliver High voltage (**5v**) to the Microcontroller/LED when pressed.
- Sensors/Pins working with positive logic are called **Active-HIGH**.
- Pull-down resistors are associated with positive logic to **pull** the initial pin value **down** to **GND** thus preventing the floating of the input value.
- Button Is OFF/open -- Input = **GND (0V)**
- Button is ON/Closed -- Input = **VCC (5V)**



But first we have to understand different digital logics ...

- © **Negative Logic** connection operates in an opposite manner, the input is initially **high** until the button is On/activated it delivers **GND (0V)** to the Microcontroller/LED.
- © Sensors/Pins working with negative logic are called **Active-Low**.
- © Pull-up resistors are associated with negative logic to **pull** the initial pin value **up** to **High voltage (5V)** thus preventing the floating of the input value .
- © Button Is OFF/open -- Input = **VCC (5V)**
- © Button is ON/Closed -- Input = **GND (0V)**



EX1

```
#include <avr/io.h>
```

```
int main (void){
```

```
    DDRB = 0x00 ; DDRD = 0x00 ; DDRC = 0x00 ; PORTC = 0x00 ; PORTB=0x00; PORTD=0x00 ; // initialize the registers
```

```
    DDRC &=~(1<<5) ; // configure pin5 as input in PORTA ( pushbutton A is connected to PIN 5 in positive Logic )
```

```
    DDRB &=~(1<<3) ; // configure pin3 as input in PORTB ( pushbutton B is connected to PIN 3 in negative Logic )
```

```
    PORTB |= (1<<3) ; // set bit 3 to HIGH to activate the internal pull-up resistor at pin 3
```

```
    DDRD |= (1<<2) ; // configure pin 2 as an output pin at PORTD
```

```
    while (1 ) {
```

```
        if ( PINC & ( 1<<5) ) { // HINT : (PINC & 0b00100000) is only true when bit 5 at PINC is 1 (pushbutton A is pressed +ve L)
```

```
            PORTD |= (1<<2) ; // set the output to HIGH to TURN ON the LED
```

```
        }
```

```
        if ( !(PINB & (1<<3) ) { // (PINB & (1<<3)) is true when Bit 3 is ON ( not pressed ) so it will be false (!) if pressed (-ve L)
```

```
            PORTD &= ~(1<<2) ; // set the output to LOW by clearing bit 2 // pushbutton B is connected in negative logic
```

```
        } }
```

```
    }
```