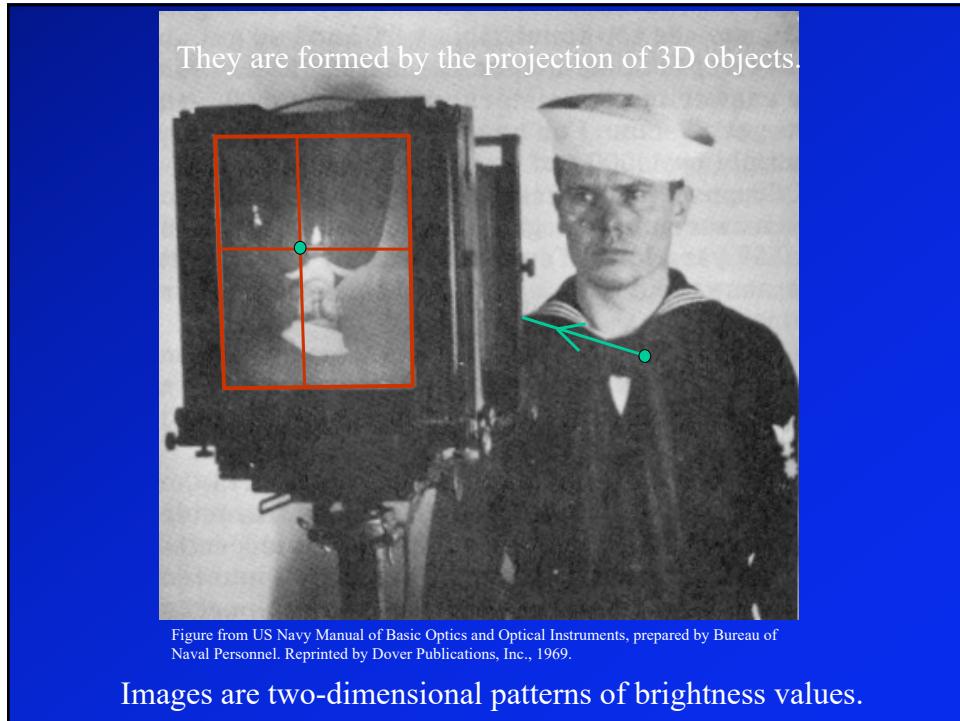
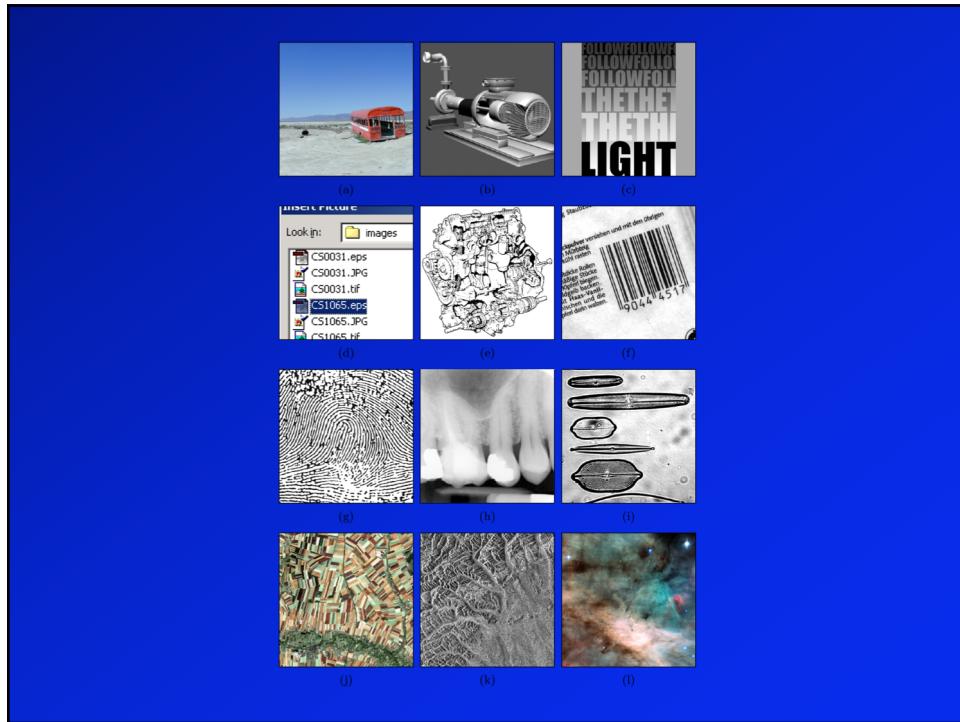


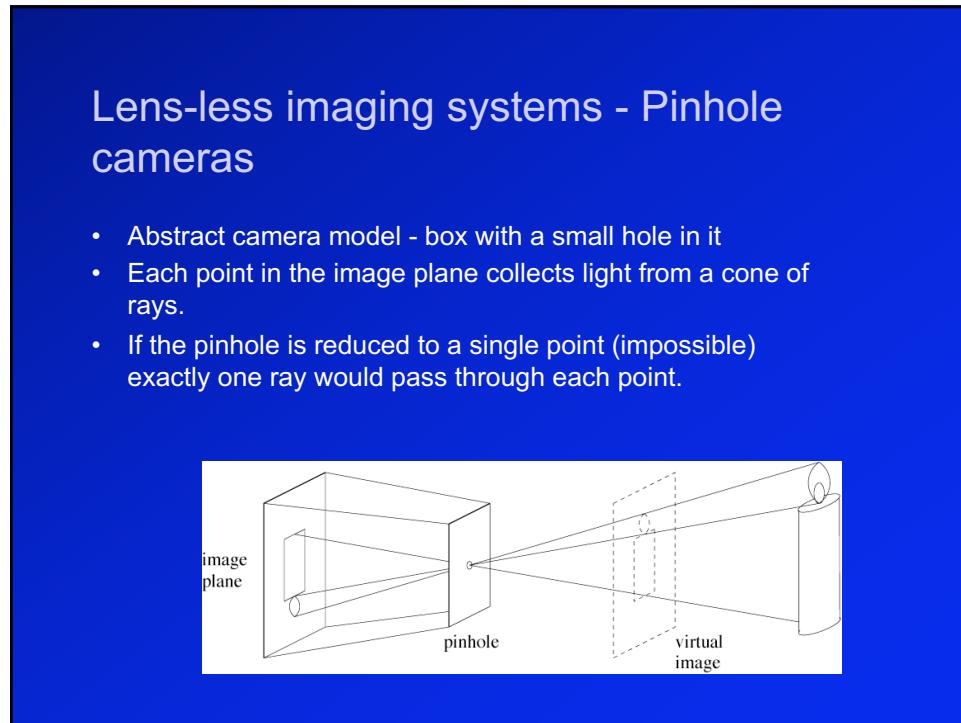
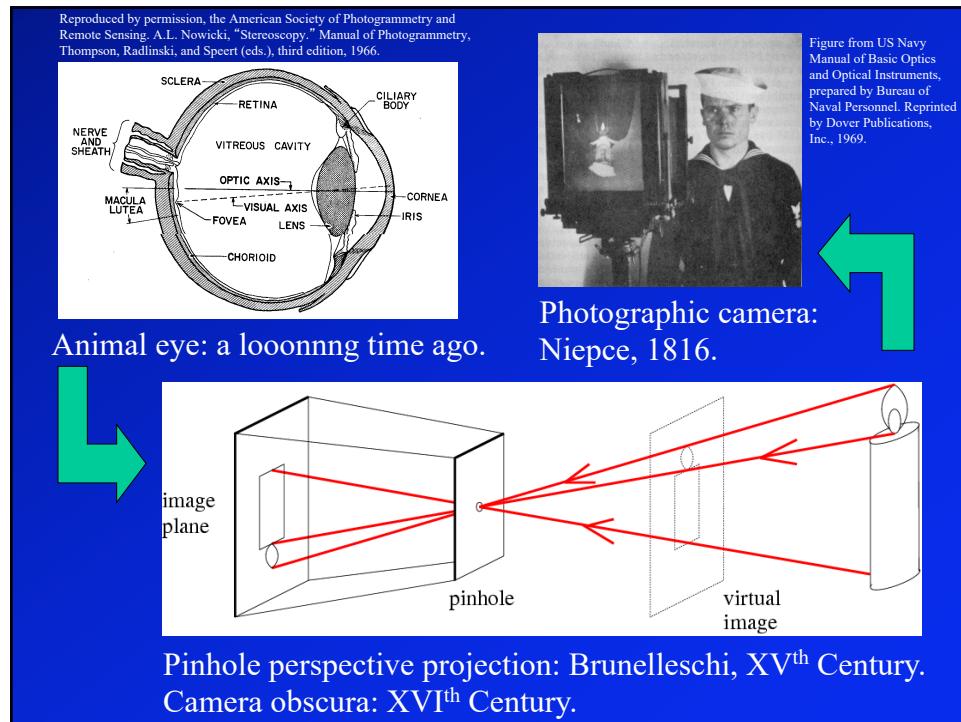
## Cameras and Lenses

Ahmed Elgammal  
Dept of Computer Science  
Rutgers University

## Outlines

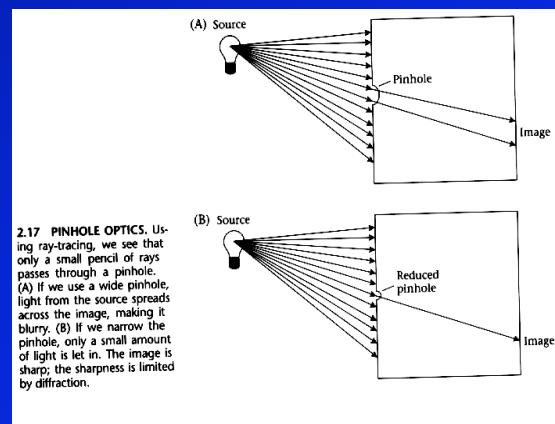
Cameras and lenses !





## pinhole optics

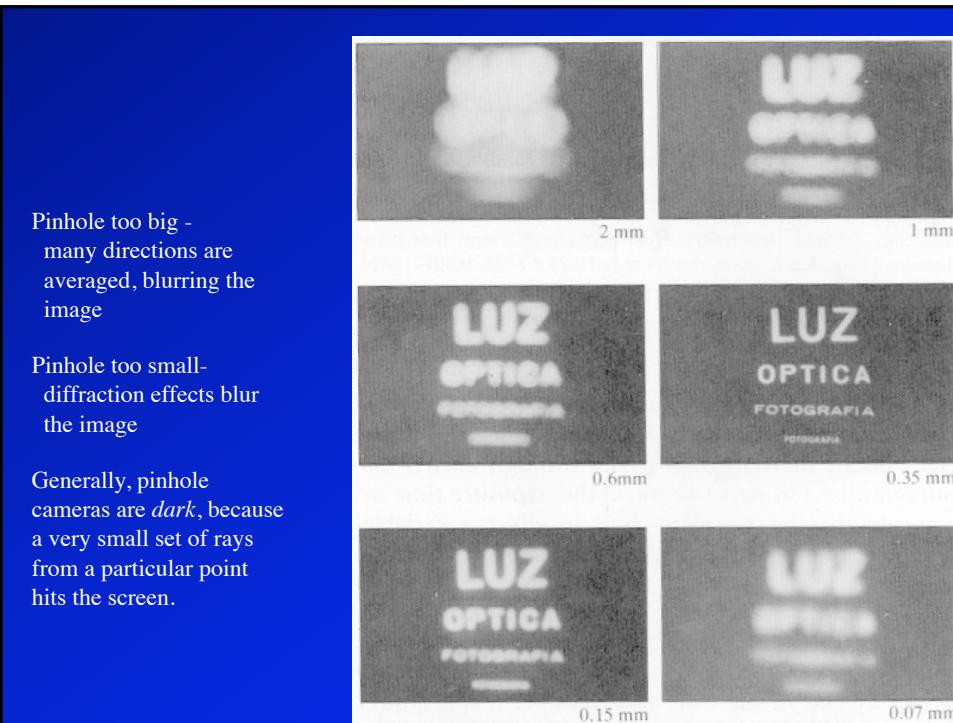
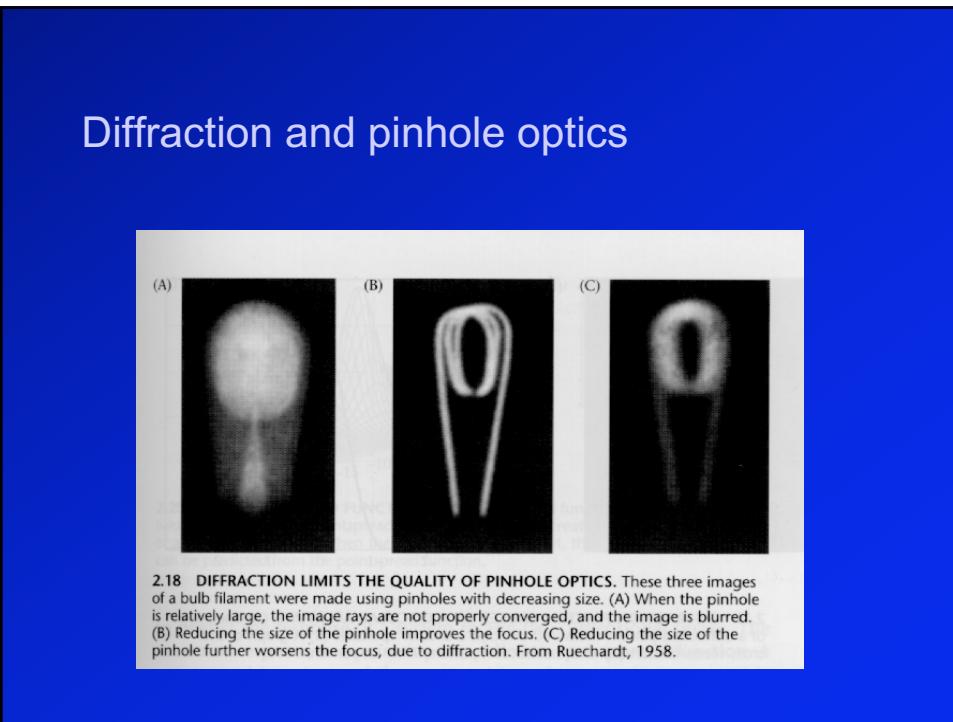
- Pinhole optics focuses images
  - without lens
  - with infinite depth of field
- Smaller the pinhole
  - better the focus
  - less the light energy from any single point



## Diffraction

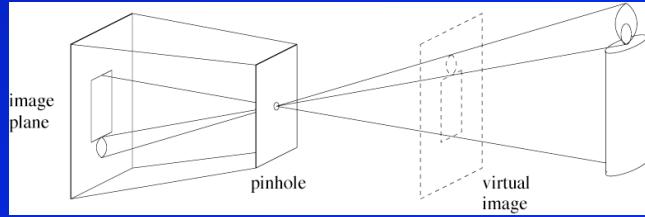
- Two disadvantages to pinhole systems
  - light collecting power
  - diffraction
- Diffraction
  - when light passes through a small aperture it does not travel in a straight line
  - it is scattered in many directions
  - process is called diffraction and is a quantum effect
- Human vision
  - at high light levels, pupil (aperture) is small and blurring is due to diffraction
  - at low light levels, pupil is open and blurring is due to lens imperfections

$$\theta = \frac{\lambda}{D}$$

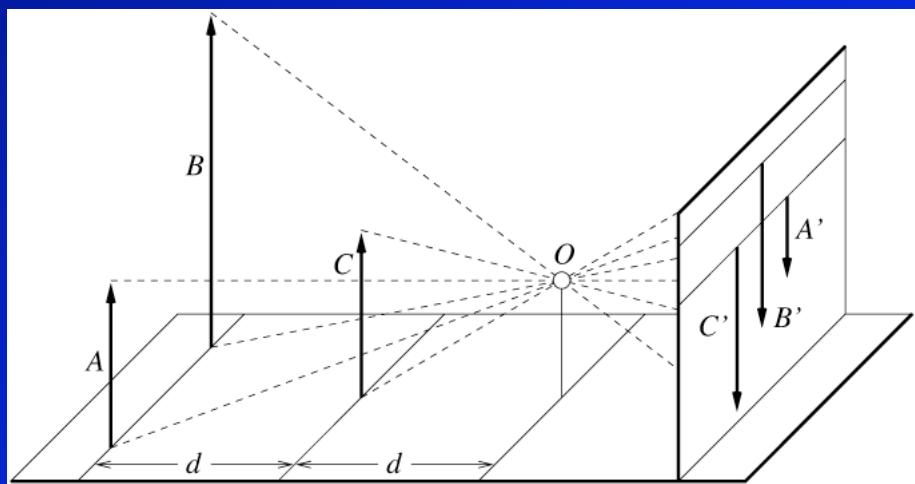


## Pinhole Perspective

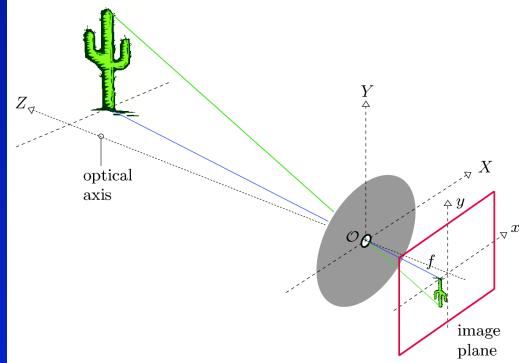
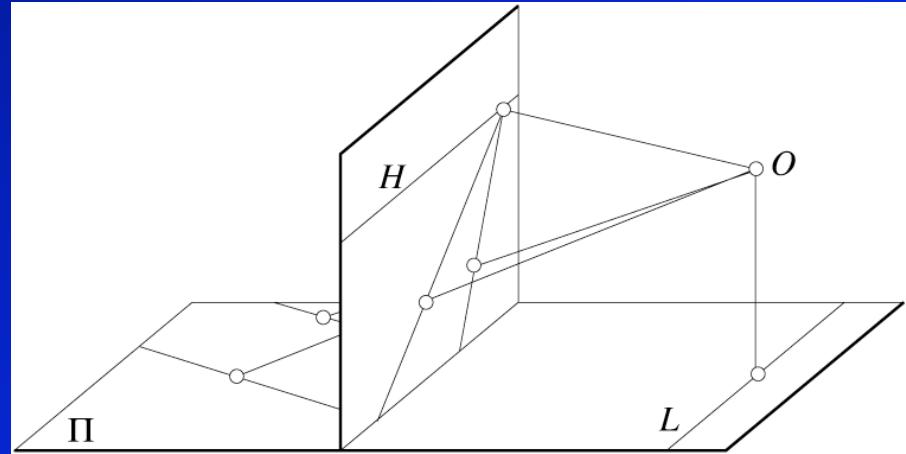
- Abstract camera model - box with a small hole in it
- Assume a single point pinhole:
  - Pinhole (central) perspective projection {Brunelleschi 15<sup>th</sup> Century}
  - Extremely simple model for imaging geometry
  - Doesn't strictly apply
  - Mathematically convenient – acceptable approximation.
  - Concepts: image plane, virtual image plane
  - Moving the image plane merely scales the image.

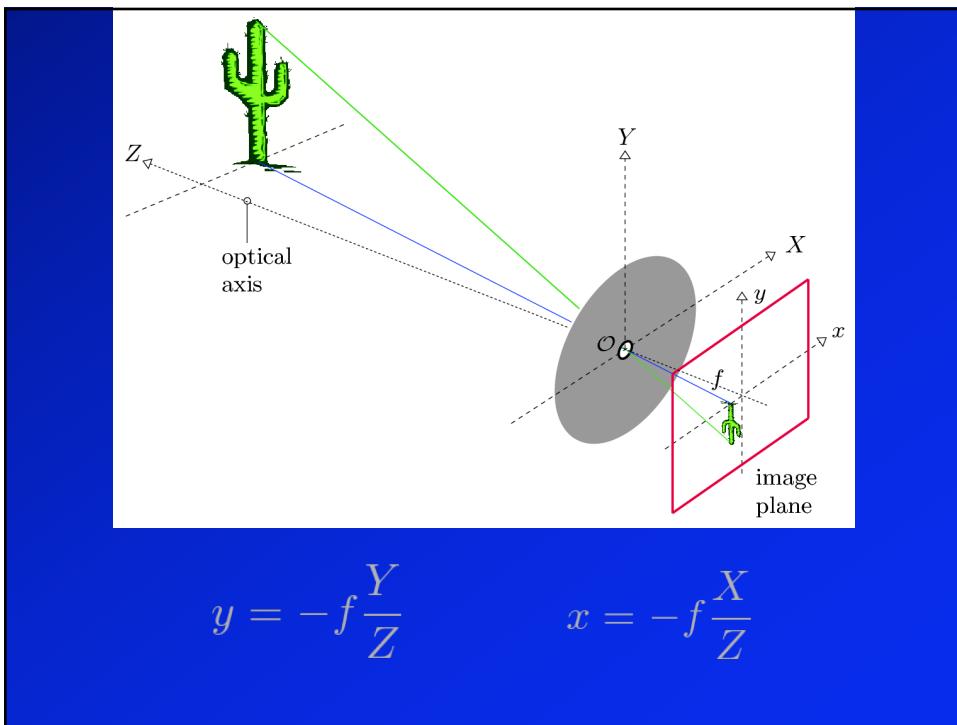
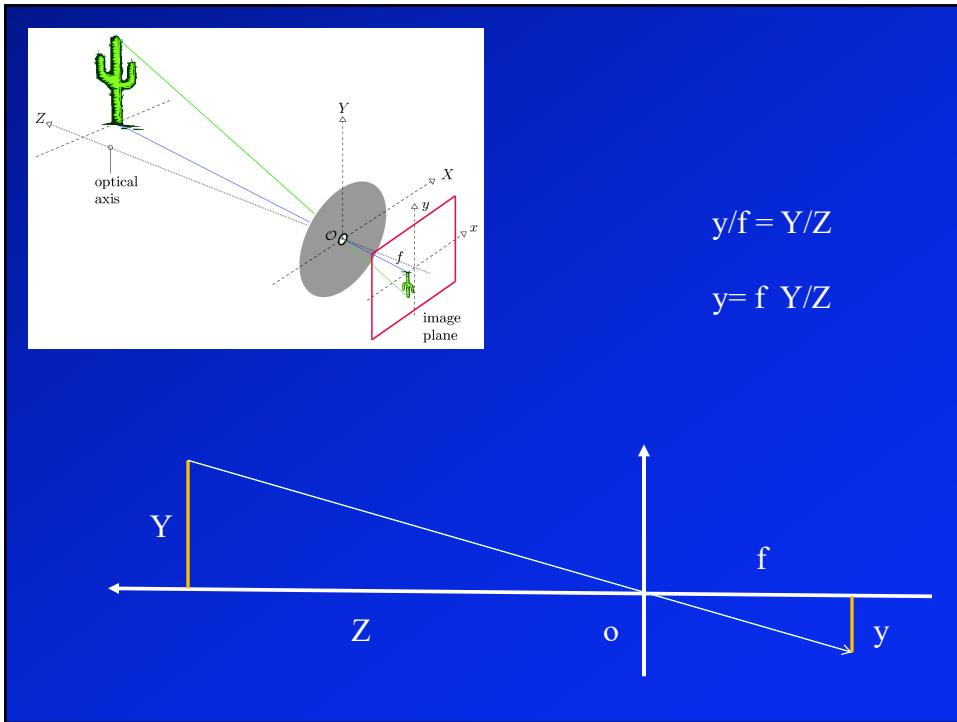


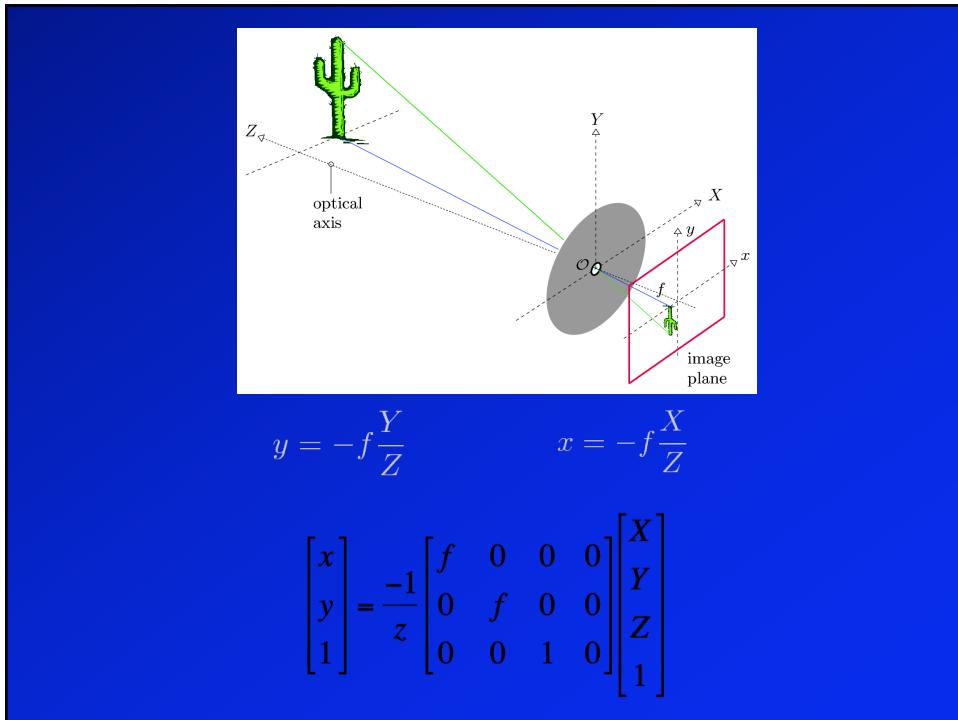
Distant objects are smaller



Parallel lines meet

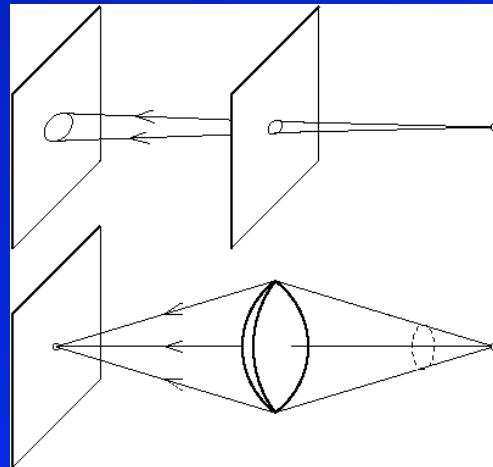






## The reason for lenses

- Because of pinhole cameras limitations, we do need lenses
- With a lens, diverging rays from a scene point are converged back to an image point



## Kepler's retinal theory

Even though light rays from "many" surface points hit the same point on the lens, they approach the lens from different directions.

Therefore, they are refracted in different directions - separated by the lens

## Snell's law

- Willebrord Snellius (Snel) 1621
- Descartes' law, Earlier known by Ibn Sahl 940-1000!, earlier by Ptolemy!
- If  $\phi_1$  is the angle of incidence and  $\phi_2$  is the angle of refraction then

$$\frac{\sin \phi_1}{\sin \phi_2} = \frac{v_1}{v_2} = \frac{n_2}{n_1}$$

$$n_1 \sin \phi_1 = n_2 \sin \phi_2$$

$$n_i = c / v_i$$

Where  $n$  and  $n'$  are the refractive indices of the two media

- Refractive index is the ratio of speed of light in a vacuum ( $c$ ) to speed of light in the medium ( $v$ )
- Paraxial approximation:  $n\phi = n'\phi'$

reflected ray

surface normal  $\phi$

refracted ray

incident ray

Refractive indices

glass - 1.52  
water - 1.333  
air - 1.000 - mercifully

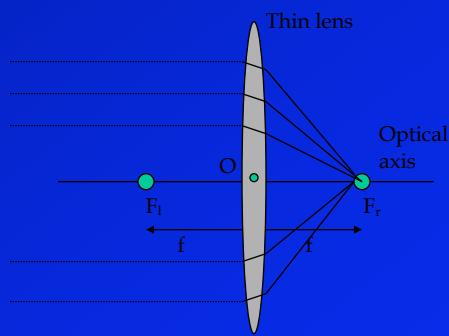
## Applying Snell' s Law twice

- Pass light into and out of a prism (symmetric piece of glass)
  - By combining many infinitesimally small prisms we form a convex lens that will bring all of the refracted rays incident from a given surface point into coincidence at a point behind the lens
  - If the image or film plane is placed that distance behind the lens, then that point will be in focus
  - If the image plane is in front of or behind that ideal location, the image of that point will be out of focus



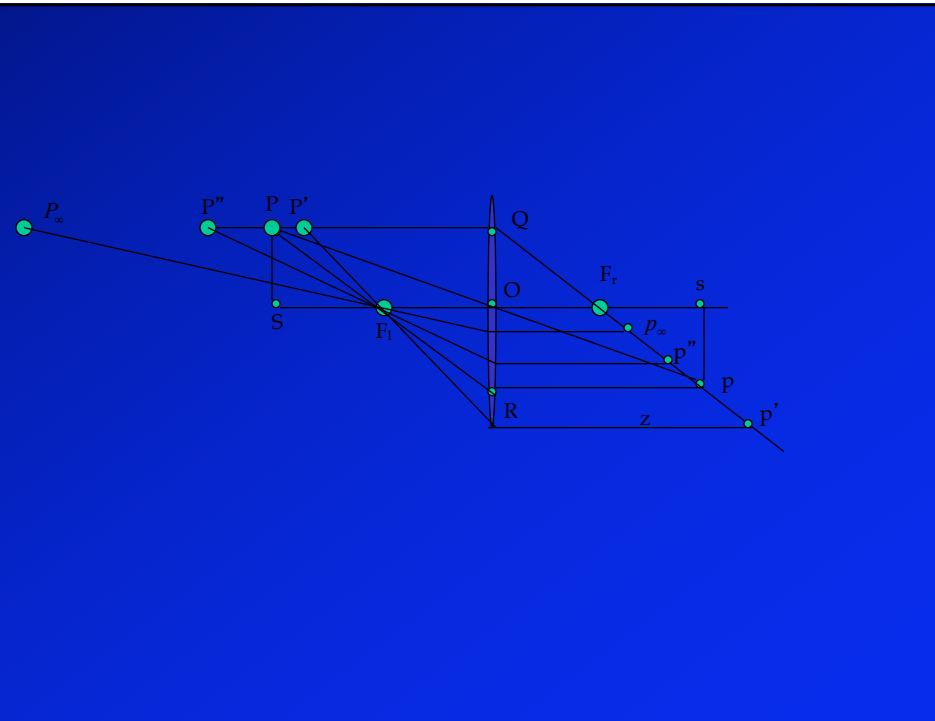
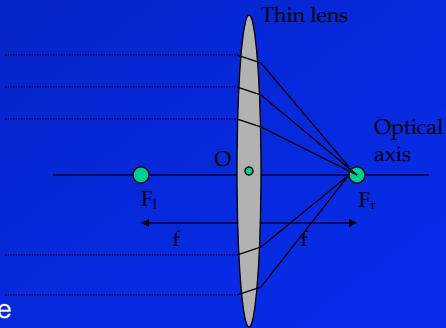
## Thin lenses

- The optical behavior is determined by:
  - optical axis going through the lens center O and perpendicular to the lens center plane
  - the left and right focus ( $F_l$  and  $F_r$ ) located a distance  $f$ , called the focal length, from the lens center



## Thin lenses

- The shape of the lens is designed so that all rays parallel to the optical axis on one side are focused by the lens on the other side:
  - Any ray entering the lens parallel to the optical axis on one side goes through the focus on the other side.
  - Any ray entering the lens from the focus on one side, emerges parallel to the optical axis on the other side.



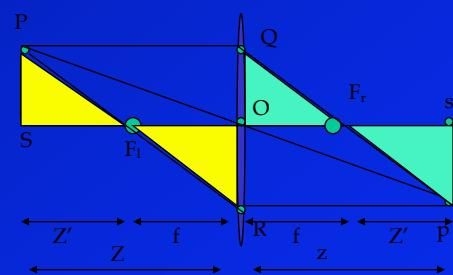
## Thin-lens equation

- relates the distance between the point being viewed and the lens to the distance between the lens and the ideal image (where the rays from that point are brought into focus by the lens)
  - Let P be a point being viewed that is not too far from the optical axis.
  - $Z + f$  is the distance of P from the lens along the optical axis
  - The thin lens focuses all the rays from P onto the same point, p

## Thin-lens equation

- p can be determined by intersecting two known rays, PQ and PR.
  - PQ is parallel to the optical axis, so it must be refracted to pass through  $F_r$ .
  - PR passes through the left focus, so emerges parallel to the optical axis.
- Note two pairs of similar triangles
  - $PF_lS \leftrightarrow ROF_l$  and  $psF_r \leftrightarrow QOF_r$

$$\frac{1}{Z} + \frac{1}{z} = \frac{1}{f}$$

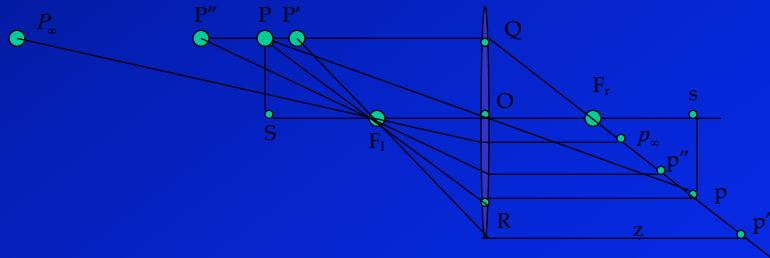


- $PS/OR = Z'/f$
- $QO/sp = f/z'$
- But  $PS = QO$  and  $OR = sp$
- So,  $Z'/f = f/z'$ , or  $Z'z' = f^2$
- Let  $Z = Z' + f$  and  $z = z' + f$

$$\frac{1}{Z} + \frac{1}{z} = \frac{1}{f}$$

## Thin-lens equation

$$\frac{1}{Z} + \frac{1}{z} = \frac{1}{f}$$

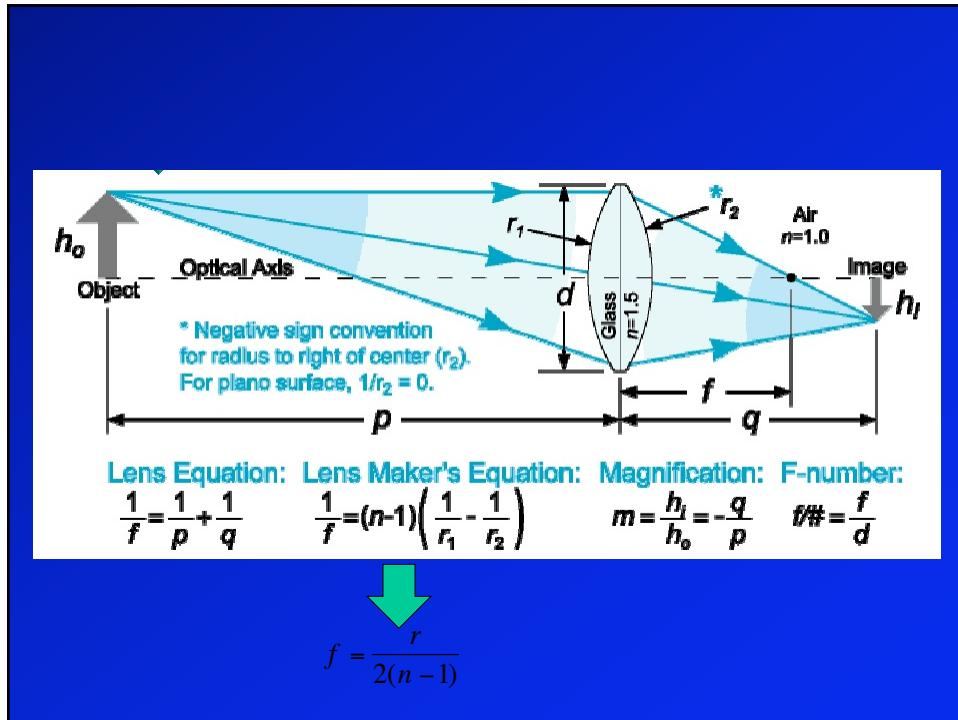


- $Z$ : distance between object and lens
- $z$ : distance between object's image and lens
- Note:
  - as  $Z$  gets large,  $z$  approaches  $f$
  - as  $Z$  approaches  $f$ ,  $z$  approaches infinity

## Depth of field

$$\frac{1}{Z} + \frac{1}{z} = \frac{1}{f}$$

- Notice that the distance behind the lens,  $z$ , at which a point,  $P$ , is brought into focus depends on  $Z$ , the distance of that point from the lens
  - familiar to us from rotating the focus ring of any camera.
- In real lenses, system is designed so that all points within a given range of distances  $[Z_1, Z_2]$  are brought into focus at the same distance behind the lens center.
  - This is called the depth of field of the lens.



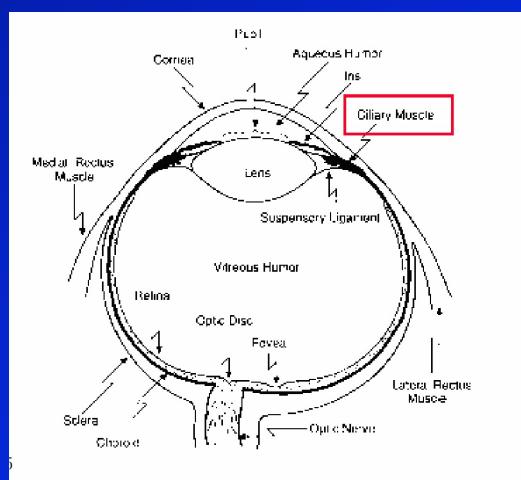
## Optical power and accommodation

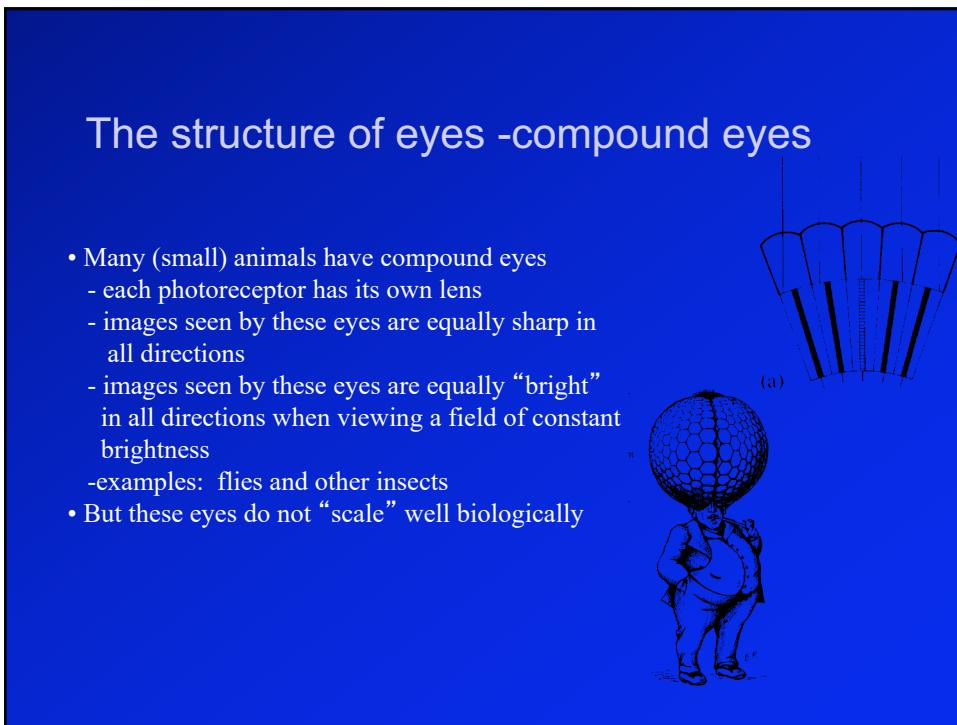
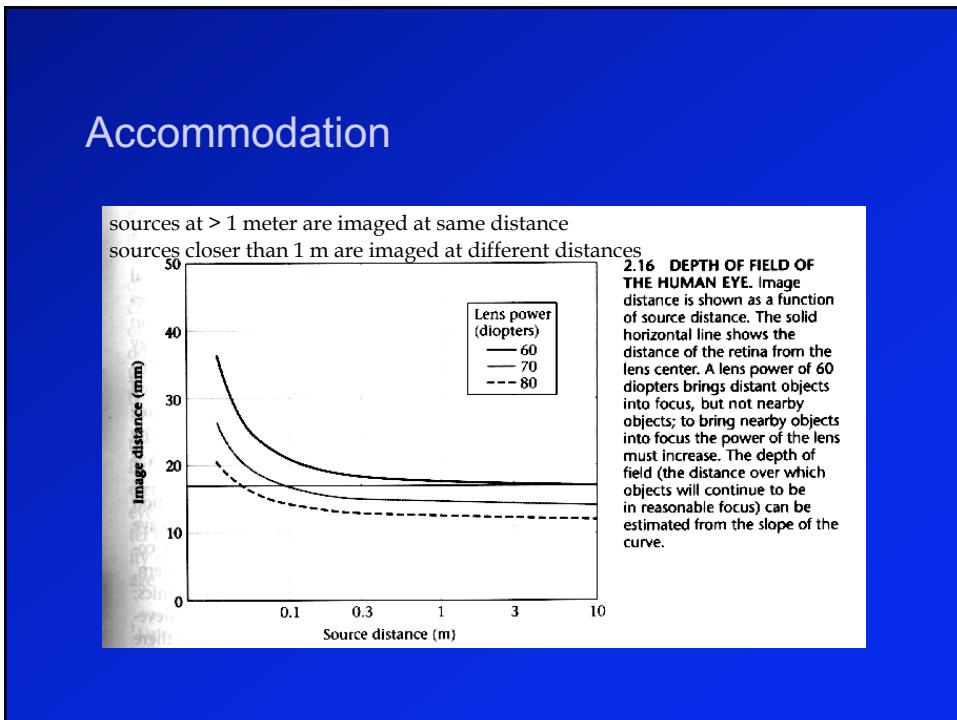
- Optical power of a lens - how strongly the lens bends the incoming rays
  - short focal length lens bends rays significantly
  - it images a point source at infinity at distance  $f$  behind the lens. The smaller  $f$ , the more the rays must be bent to bring them into focus sooner.
  - optical power is  $1/f$ , measured in meters. The unit is called the *diopter*
  - Human vision: when viewing faraway objects the distance from the lens to the retina is .017m. So the optical power of the eye is 58.8 diopters

## Accommodation

- How does the human eye bring nearby points into focus on the retina?
  - by increasing the power of the lens
  - muscles attached to the lens change its shape to change the lens power
  - accommodation: adjusting the focal length of the lens
  - bringing points that are nearby into focus causes faraway points to go out of focus
  - depth-of-field: range of distances in focus
- Physical cameras - mechanically change the distance between the lens and the image plane

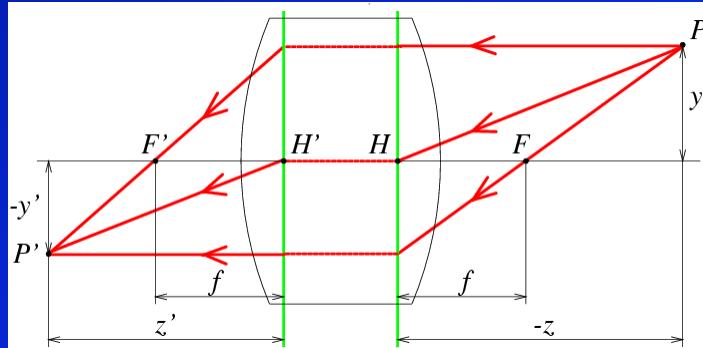
## Accommodation





## Real lenses

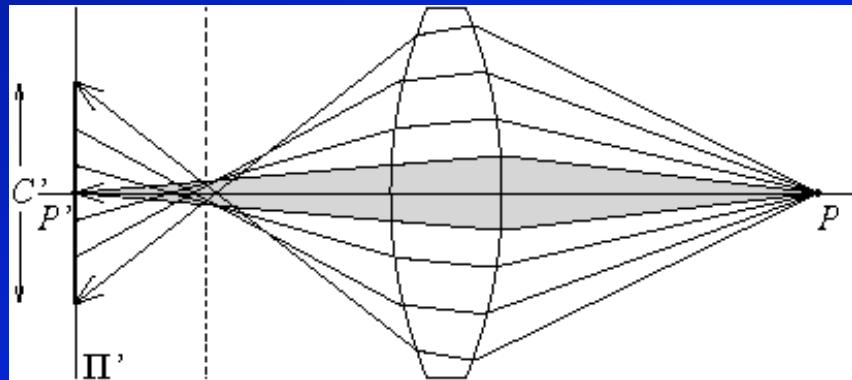
- Thick lenses



## Lens imperfection

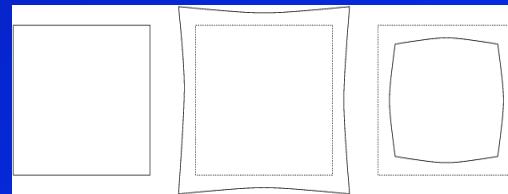
- Lens imperfections might cause rays not to intersect at a point
  - deviations in shape from the ideal lens
  - material imperfections that might cause the refractive index to vary within the lens
- Scattering at the lens surface
  - Some light entering the lens system is reflected off each surface it encounters (Fresnel's law gives details)
  - Machines: coat the lens, interior
  - Humans: live with it (various scattering phenomena are visible in the human eye)
- Geometric aberrations.
- Chromatic aberrations.

## Spherical aberration



## Radial Distortion

- Barrel: image magnification decreases with distance from the optical axis.
- Pincushion: image magnification increases with the distance from the optical axis.

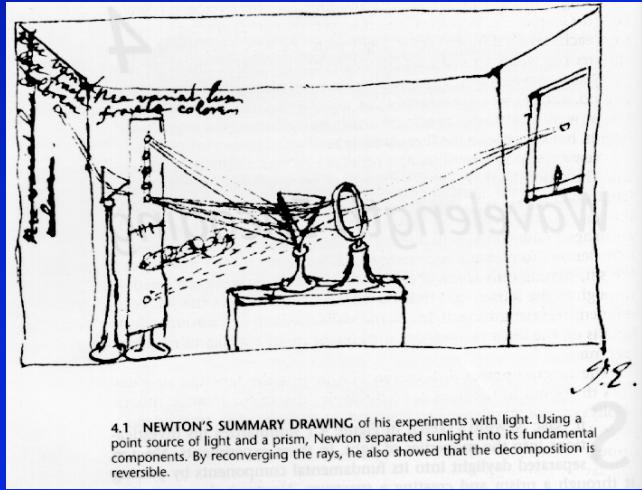


$$\begin{aligned}\hat{x}_c &= x_c(1 + \kappa_1 r_c^2 + \kappa_2 r_c^4) \\ \hat{y}_c &= y_c(1 + \kappa_1 r_c^2 + \kappa_2 r_c^4),\end{aligned}$$



## Complications of color

- Spectral composition of light
  - Newton's original prism experiment
  - light decomposed into its spectral components



## Complications of color

- Why does the prism separate the light into its spectral components?
  - prism bends different wavelengths of light by different amounts
  - refractive index is a function of wavelength
  - shorter wavelengths are refracted more strongly than longer wavelengths

Wavelength	Color (*)
700	Red
610	Orange
580	Yellow
540	Green
480	Blue
400	Violet

\* - viewed in isolation

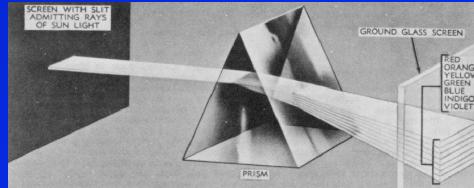
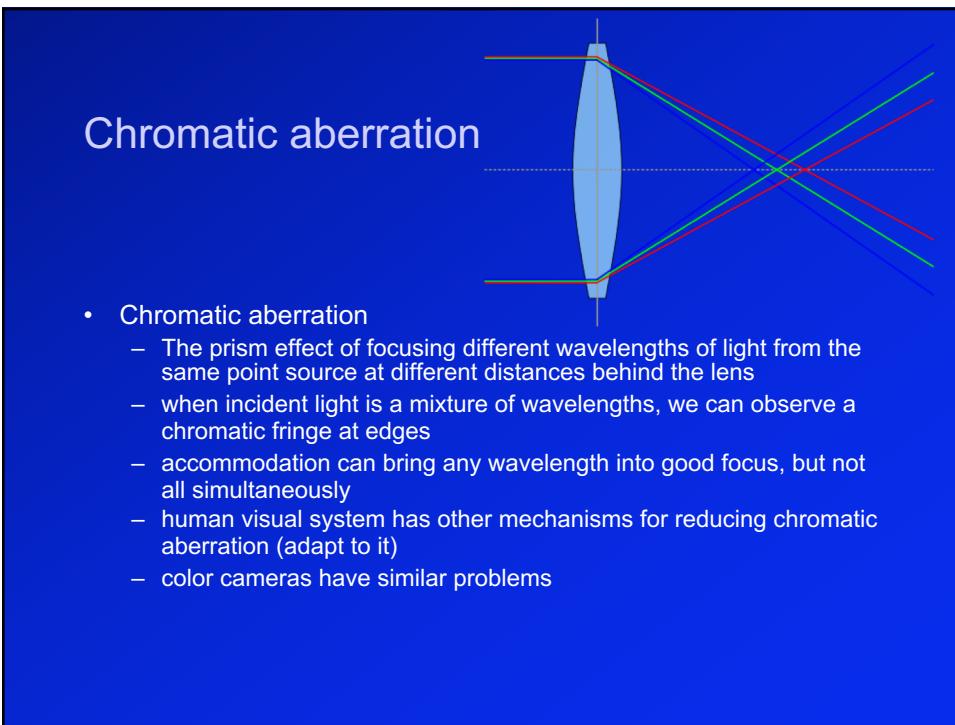
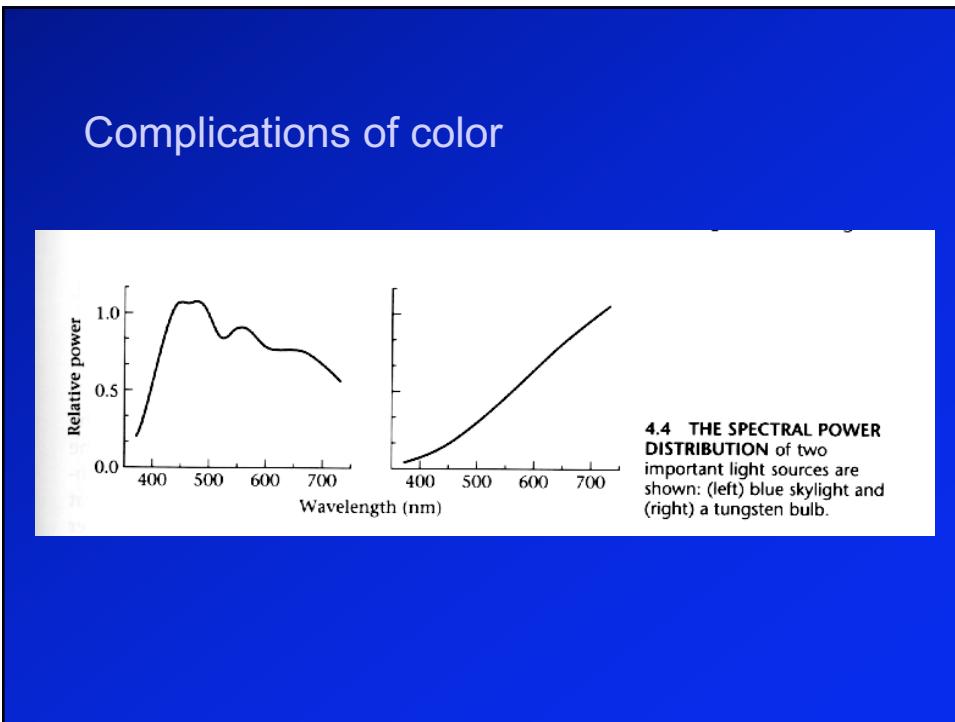


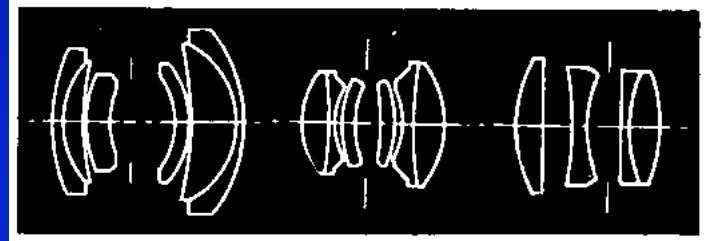
Figure from US Navy Manual of Basic Optics and Optical Instruments, prepared by Bureau of Naval Personnel. Reprinted by Dover Publications, Inc., 1969.



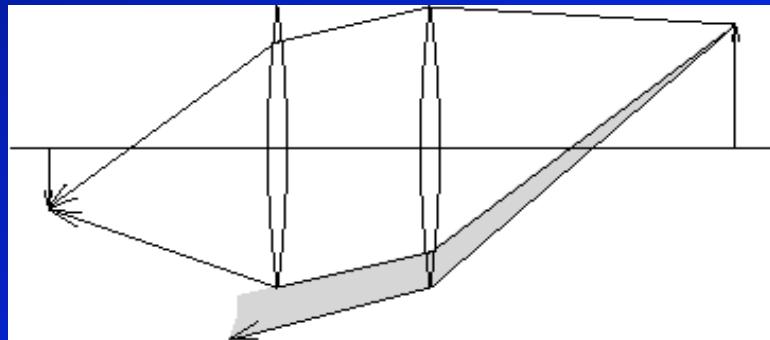


## Lens systems

- Aberrations can be minimized by aligning several simple lenses (compound lenses)



## Vignetting



- Vignetting effect in a two-lens system. The shaded part of the beam never reaches the second lens.
- Result: brightness drops at image periphery.



## Sensing

Milestones:

First Photograph: Niepce 1816

Daguerreotypes: Louis Daguerre  
(1839)

Photographic Film (Eastman,  
1889)

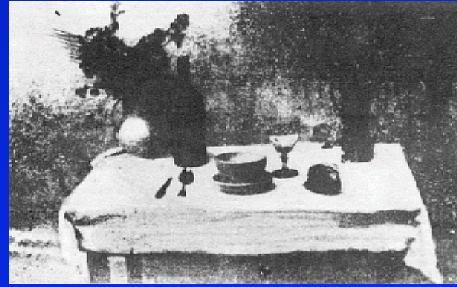
Cinema (Lumière Brothers,  
1895)

Color Photography (Lumière  
Brothers, 1908)

Television (Baird, Farnsworth,  
Zworykin, 1920s)

CCD Cameras (Charge Couple Device) (1970)

CMOS Cameras (Complementary Metal Oxide Silicon)



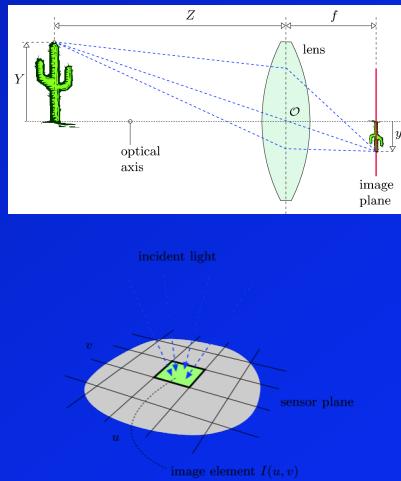
Collection Harlingue-Viollet.  
Photographs (Niepce, "La Table Servie," 1822)



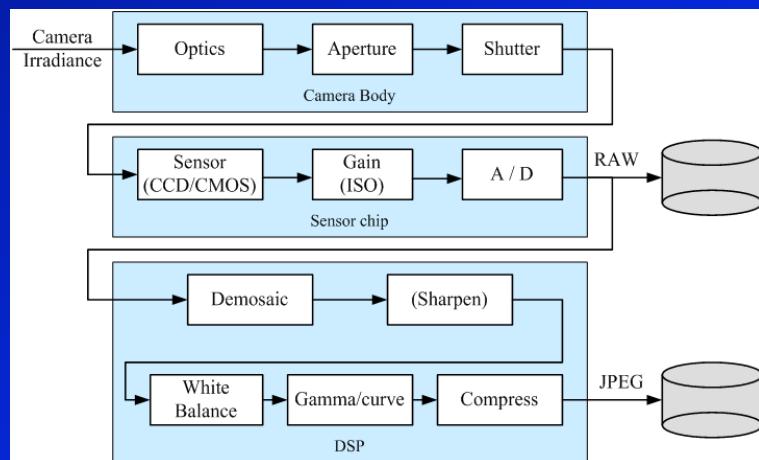
"Boulevard du Temple", taken by Daguerre in 1838 in Paris  
First person in a photograph. 10 mins exposure

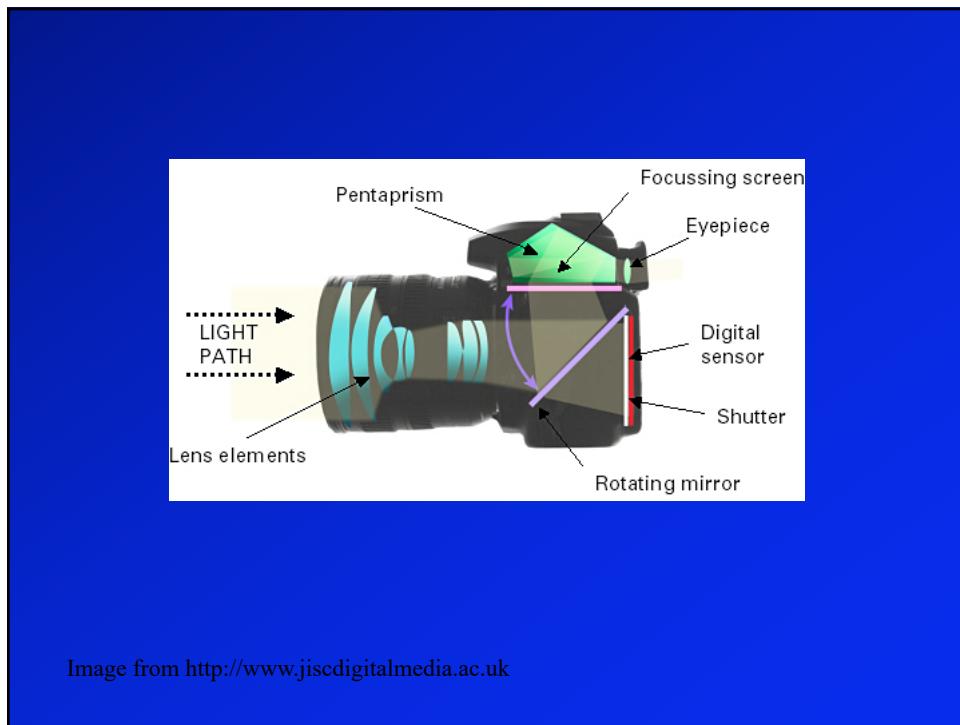
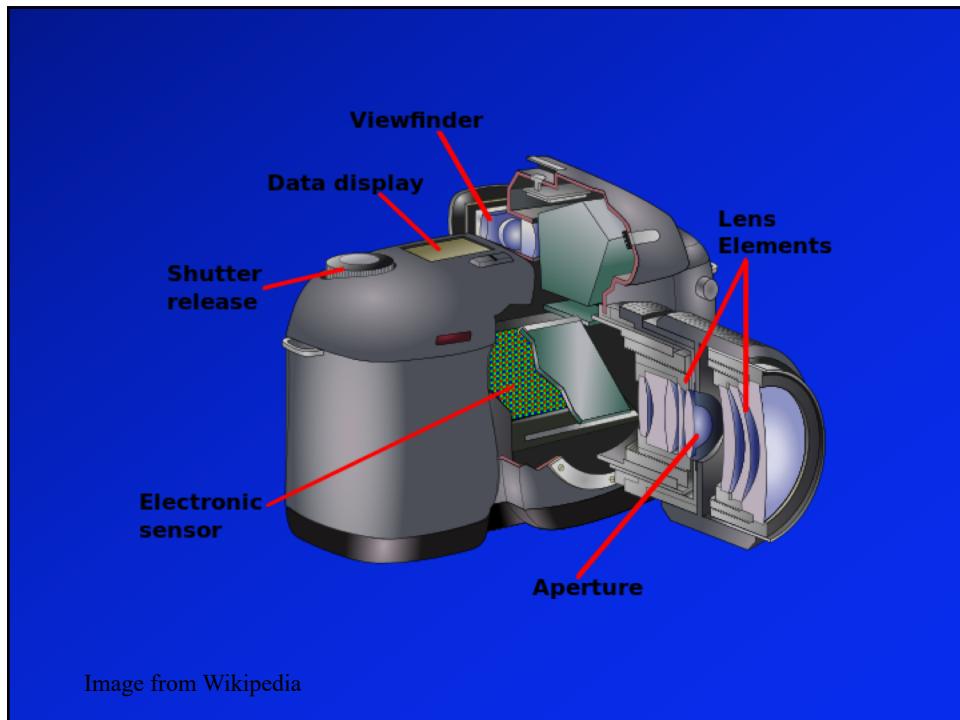
## Digitizing images

- What is projected on the image plan is a distribution of light energy that is:
  - Two-dimensional
  - Time-dependent
  - Continuous
- To go digital:
  - Spatial sampling
  - Temporal sampling
  - Quantization of pixel values



## Digital camera





- Three concepts from film-based cameras:
  - Aperture
  - Shutter Speed
  - ISO: film density

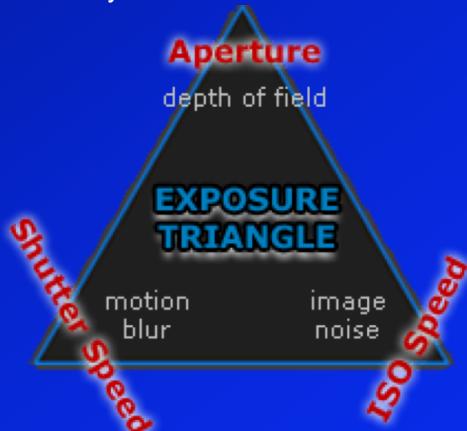
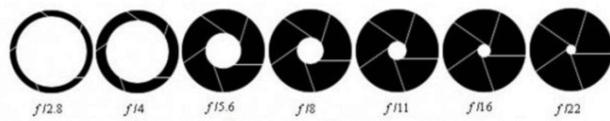


Image from: <http://www.cambridgeincolour.com>

### APERTURE SCALE



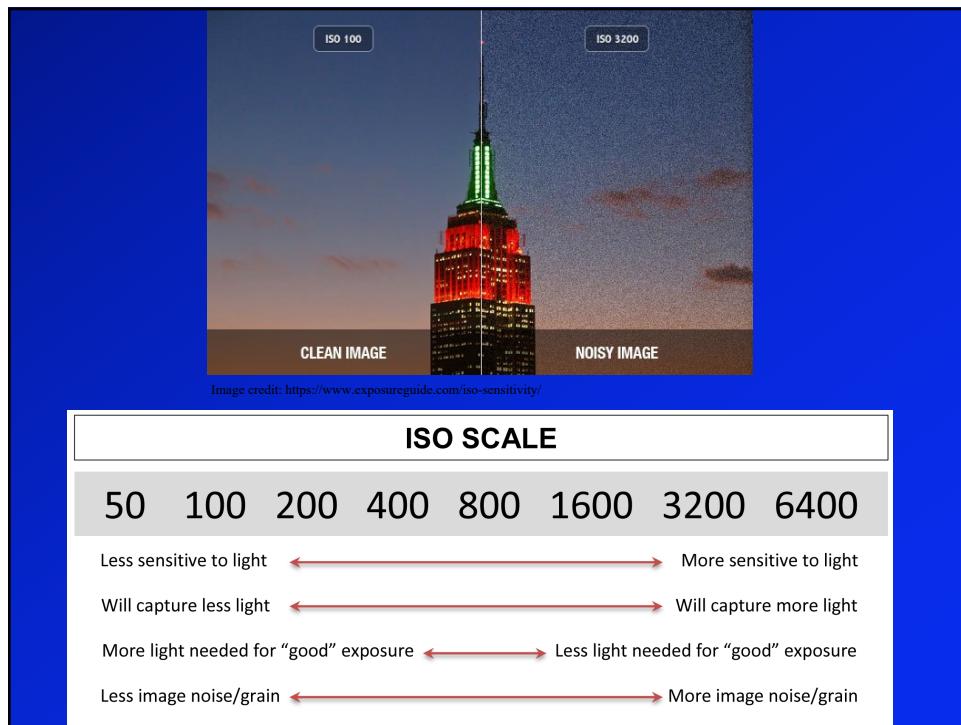
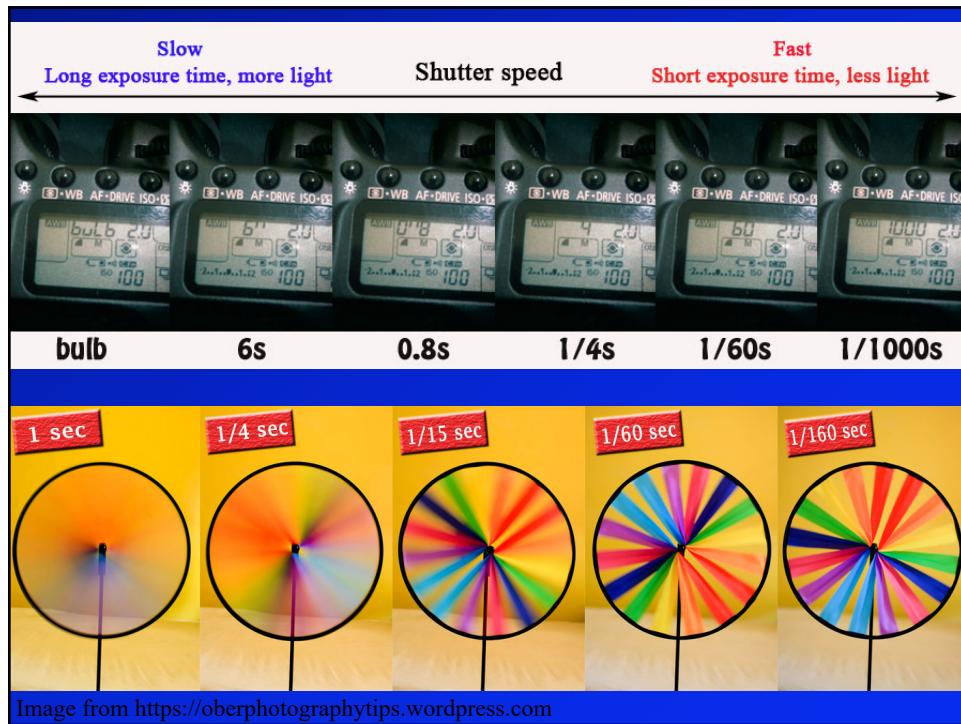
Large aperture

Small aperture

More light strikes image sensor ← → Less light strikes image sensor

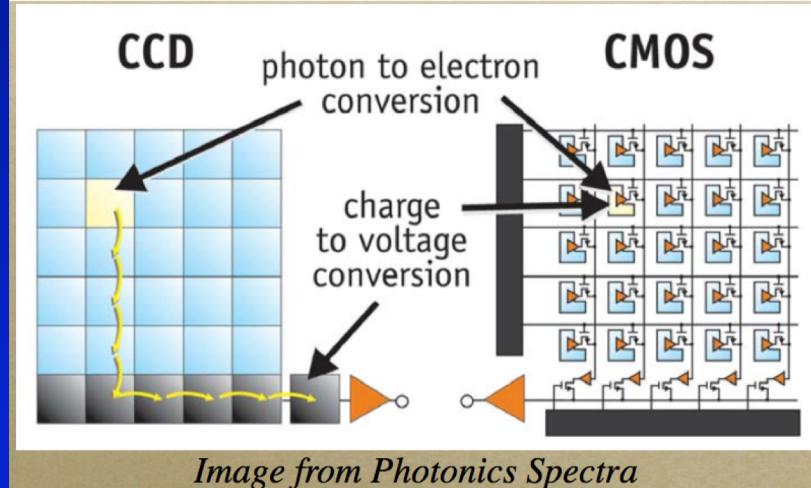
Shallow Depth of Field (Focus) ← → Deep Depth of Field (Focus)

Image from <https://oberphotographytips.wordpress.com>



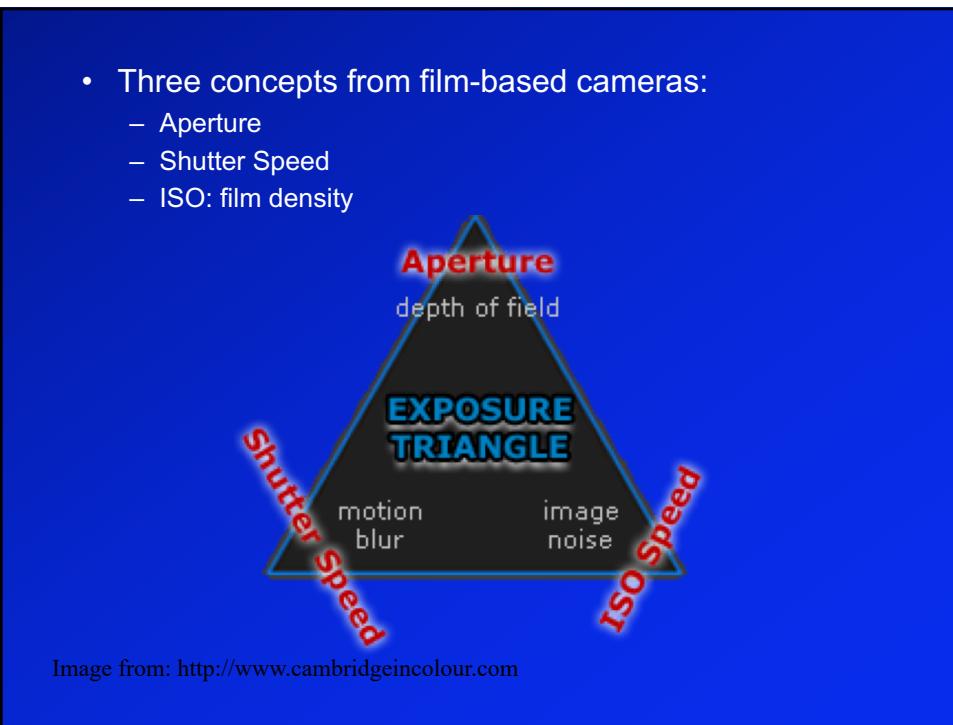
## CCD & CMOS

- CCD Cameras (Charge Couple Device) (1970)
  - Accumulate signal charge in each pixel proportional to the local illumination intensity
  - CCD transfers each pixel's charge packet sequentially to convert its charge to a voltage
- CMOS Cameras (Complementary Metal Oxide Silicon)
  - Accumulate signal charge in each pixel proportional to the local illumination intensity
  - The charge-to-voltage conversion takes place in each pixel

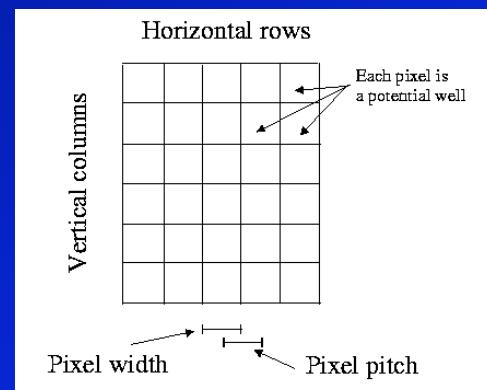


<i>CMOS</i>	<i>CCD</i>
◦ <i>Easier to manufacture</i>	◦ <i>Higher fill factor</i>
◦ <i>Camera-on-a-chip</i>	◦ <i>Smaller noise</i>
◦ <i>Lower power consumption</i>	◦ <i>Smaller dark current</i>
◦ <i>Smaller sensor</i>	◦ <i>Better pixel uniformity</i>
◦ <i>Higher speeds</i>	◦ <i>Better dynamic range</i>
◦ <i>Selective ROI windowing</i>	◦ <i>Non-rolling electronic shutter</i>
◦ <i>Natural anti-blooming</i>	

Check out: [CCD vs. CMOS: Facts and Fiction](#) by Dave Litwiller, in Photonics Spectra, January 2001

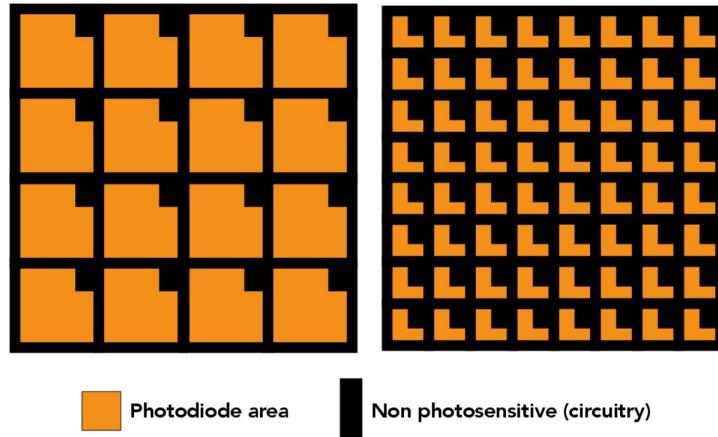


- Several Parameters for a Digital camera
  - Mechanical and/or Electronic shutter
    - Rolling shutter vs. global shutter
  - Sampling pitch: the physical spacing between adjacent sensors (typically in  $\mu m$ )
    - Small sampling pitch -> higher sampling density -> higher resolution. But also implies smaller area per sensor -> less light sensitivity + more noise
  - Fill Factor: the active sensing area size as a fraction of the available sensing area
  - Chip Size: larger chip size is preferred since each sensor can be more photo-sensitive, however more expensive.



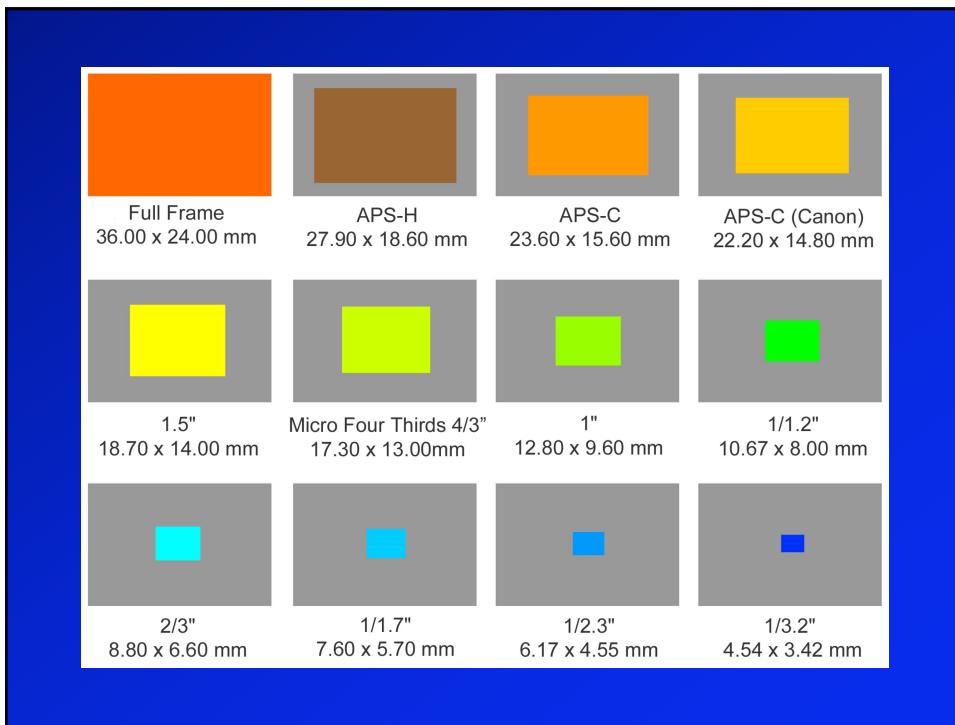
## Pixel Fill Factor

Fraction of pixel area that integrates incoming light.



CS184/284A, Lecture 18

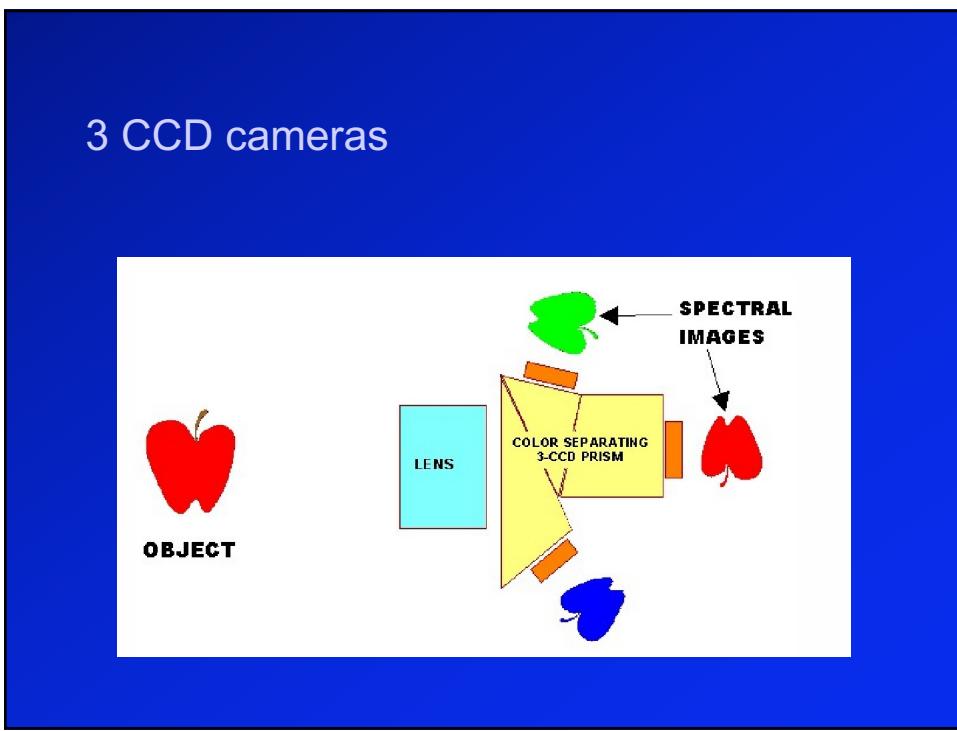
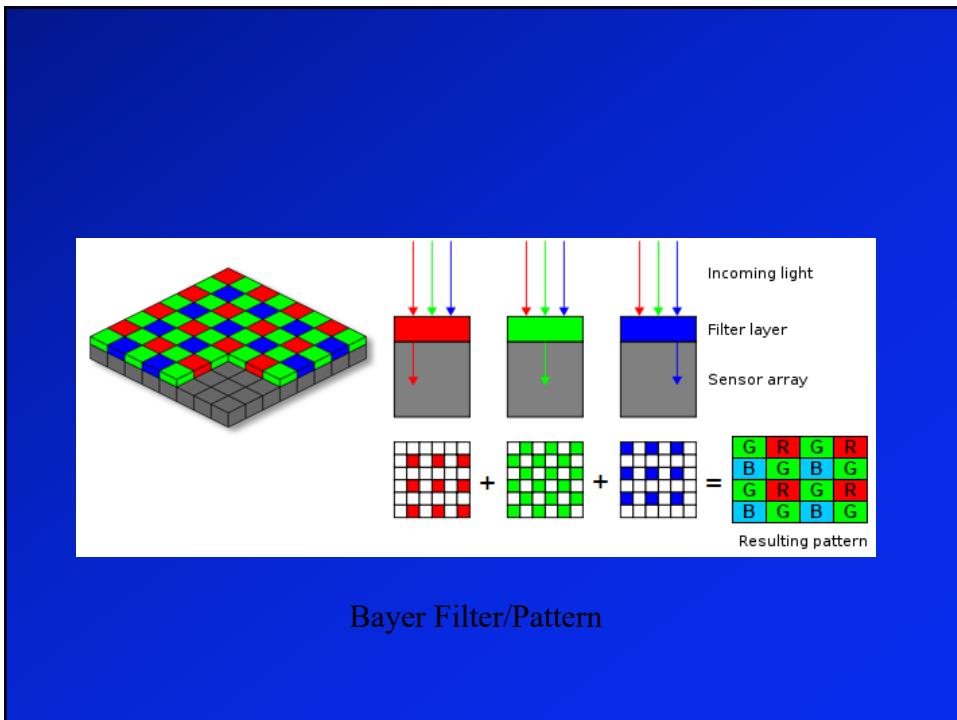
Ren Ng, Spring 2016



- Analog gain: sensed signal is amplified
  - Automatic gain control: amplification is a function of the exposure
  - Manual setting: digital ISO setting
    - Higher ISO: more gain which implies better under low light condition.
    - However more noise (amplifies the sensor noise)
- ADC resolution: Analog to digital conversion: how many bits are used to quantize the received signal at each sensor unit
  - 16 bits for RAW format
  - 8 bits for JPEG
  - Less bits: quantization error
  - More bits increases the noise (effect of input noise – more bits than is actually needed)

## Color cameras

- Two types of color cameras
  - Single CCD array
    - in front of each CCD element is a filter - red, green or blue
    - color values at each pixel are obtained by hardware interpolation
      - subject to artifacts
      - lower intensity quality than a monochromatic camera
      - similar to human vision
  - 3 CCD arrays packed together, each sensitive to different wavelengths of light



## Depth Cameras

- Stereo camera
- Laser scanners
- Structured-Light cameras
- Time-of-Flight Cameras

## Sources

- Computer Vision a Modern approach: 1.1
- Szeliski “Computer Vision Algorithms and Application”

### Sec 2.3.1

- Burger and Burge, Digital Image Processing Ch 2
- Wandell, Foundations of Vision
- Some Slides by:
  - D. Forsyth @UC Berkeley
  - J. Ponce @UIUC
  - L. Davis @UMD