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Presentation on

SMART TRAFFIC LIGHT SYSTEM

Group No:15

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INTRODUCTION

- In many urban areas, traditional traffic light systems operate on fixed timing schedules, disregarding fluctuating traffic densities.
- This often leads to inefficiencies, particularly during peak hours, as drivers experience unnecessary delays at intersections, even when the traffic flow is low on certain approaches.
- Such rigid control increases congestion, contributes to higher emissions, and wastes fuel due to prolonged idle times.
- The SMART TRAFFIC LIGHT SYSTEM aims to address these issues by dynamically adjusting traffic light timings in real-time, based on the actual traffic density at a four-way junction.
- By implementing sensors to monitor traffic conditions and a microcontroller to process and adjust signal timings, the system prioritizes lanes with higher density, optimizing the flow and reducing wait times.



PROBLEM STATEMENT

To design an effective solution ‘SMART TRAFFIC LIGHT SYSTEM’ and reduce traffic congestions by dynamically adjusting traffic light timings, particularly at a four-way junction, the system improves traffic flow, reduces congestion, and minimizes wait times.





COMPONENTS

- LPC2138 Microcontroller: For processing sensor data and controlling traffic light timings.
- IR Sensors: To detect the presence and density of vehicles on each road.
- Traffic Light LEDs: Red, yellow, and green LEDs to simulate real traffic lights.
- Timer Module: For controlling timing intervals.
- Power Supply: To power the components.
- Connecting Wires and Resistors: Basic wiring to connect the sensors, microcontroller, and lights.

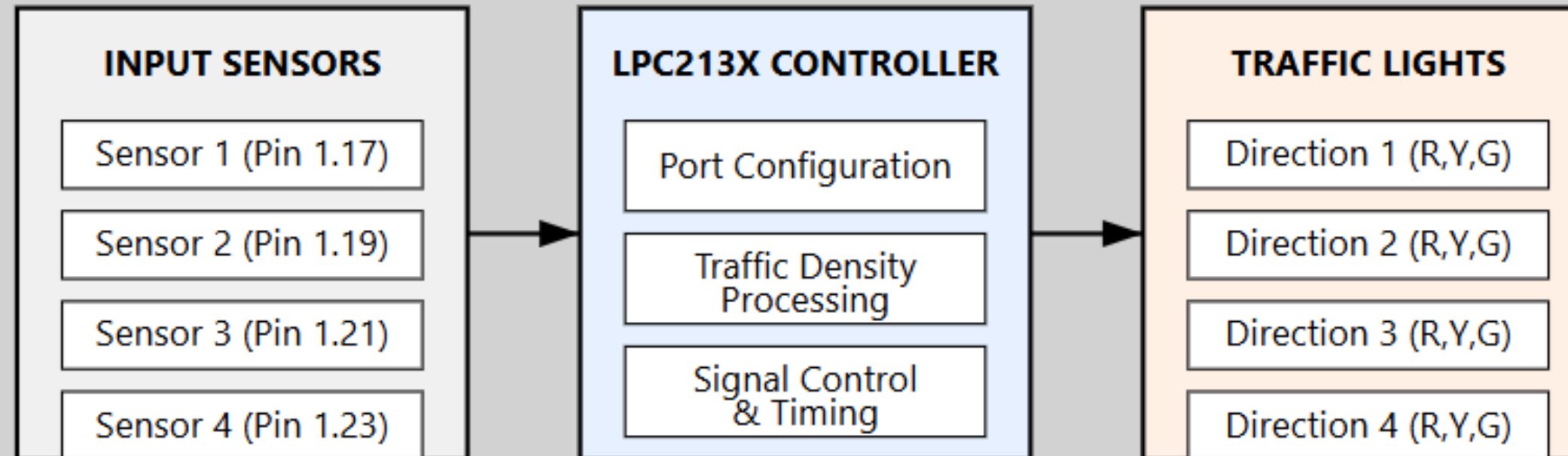


METHODOLOGY

- Density Detection:
 1. IR sensors detect traffic density, and depending on the traffic density it sends data to the microcontroller.
 2. IR sensors positioned at strategic intervals along each lane
 3. Multiple sensors per lane for accurate vehicle counting.
- Timer Adjustment: The LPC2138 calculates timer changes based on traffic density on each road. If density is more it increases the timer otherwise it executes the normal timer delay.
- Traffic Light Control: The microcontroller manages the lights, prioritizing lanes with higher density by extending green-light times.

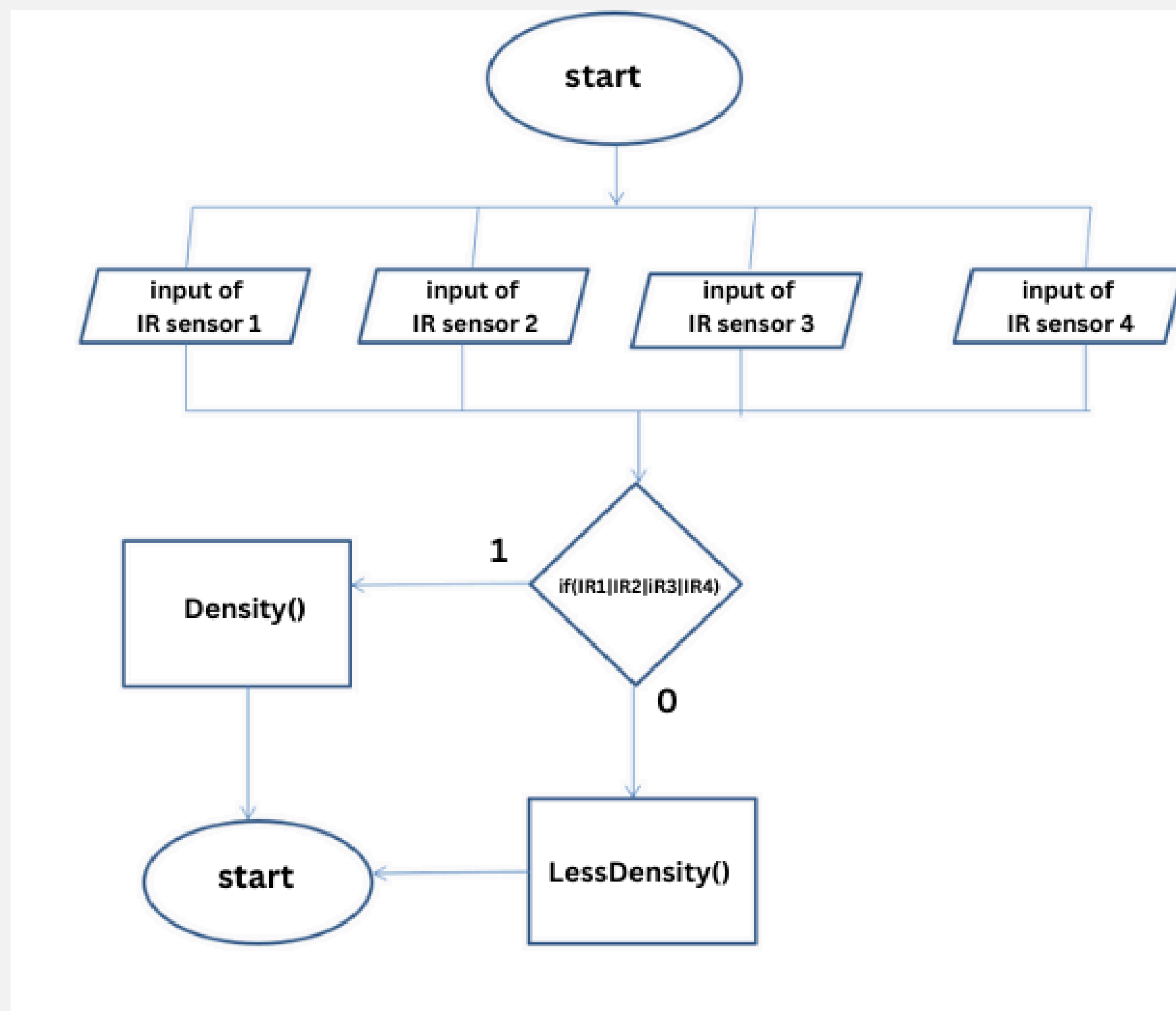


BLOCK DIAGRAM





FLOW CHART





CALCULATIONS

- $C\text{-Clk} = 60\text{MHz}$
- $P\text{-Clk} = 1/4 * C\text{-Clk} = 1/4 * 60 = 15\text{MHz}$
- $\text{Delay} = \text{NOC} * 1/P\text{-Clk}$
- Initial Delay:-(2secs)(for less density)
- $2\text{secs} = \text{NOC} * 1/15\text{MHz}$
- $\text{NOC} = 3000 \times 10^4$
- $\text{PR} = 9999$, $\text{MR0} = 3000$
- Additional delay(4 secs)(for more density):
- $\text{PR} = 9999$, $\text{MR0} = 6000$



ALGORITHM

- Initialize static flag variable as 0.
- In Delay Function:-
 - Reset the timer.
 - Update the value of MR0 with the passed value.
 - Enable Timer Control Register.
 - Initialize PR.
 - Wait for timer interrupt flag bit.
- In ISR of External Interrupt 0:-
 - Update the port 1 values using IOPIN1 register to prioritize the traffic signal 1.
 - Call the delay function.
 - Update flag variable.
 - Clear vector address.



ALGORITHM

- In ISR of External Interrupt 1:-
 - Update the port 1 values using IOPIN1 register to prioritize the traffic signal 2.
 - Call the delay function.
 - Update flag variable.
 - -Clear vector address.
- In ISR of External Interrupt 2:-
 - Update the port 1 values using IOPIN1 register to prioritize the traffic signal 3.
 - Call the delay function.
 - Update flag variable.
 - Clear vector address.
- In ISR of External Interrupt 3:-
 - Update the port 1 values using IOPIN1 register to prioritize the traffic signal 4.
 - Call the delay function.
 - Update flag variable.
 - Clear vector address.

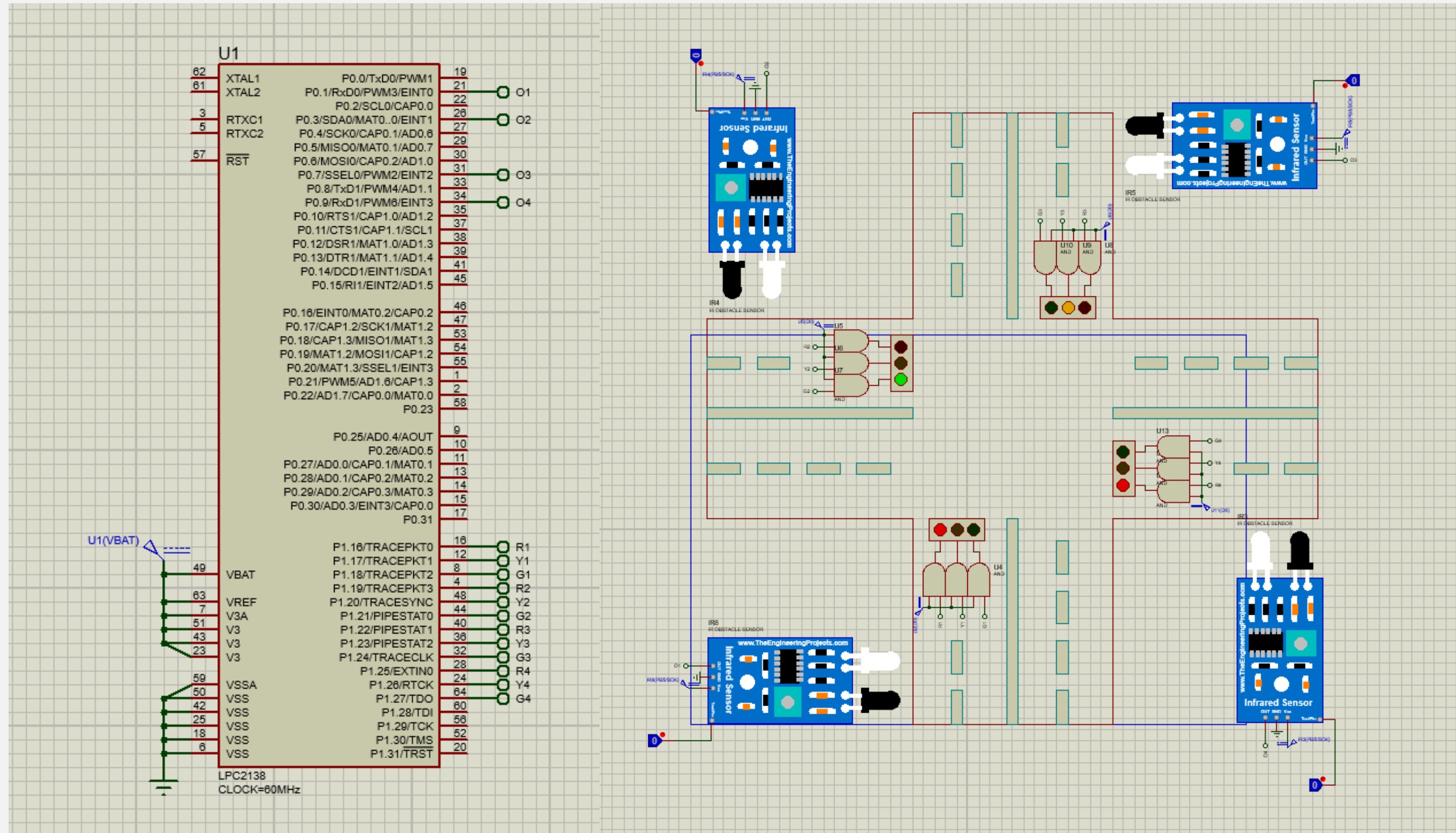


ALGORITHM

- In `intr_init()` function:-
 - Update PINSEL for all the external interrupts.
 - Configure all the interrupts as VIRQ.
 - Load VICVectAddr and VICVectCntl registers with appropriate value for all the external interrupt isrs.
 - Enable interrupts.
 - Configure them as Rising Edge sensitive .
- In `Intial()` function:-
 - Load appropriate values for IOPIN register along with delay to continue the initial loop sequence of traffic lights.
- In main function:-
 - Call the `intr_init()` function.
 - Use IODIR1 register to configure all the GYR LED pins as output.
 - In while loop:-
 - Use if else ladder to read values of flg and write code snippets for cyclic rotation.
 - In else call the 'initial()' function.



CIRCUIT





ADVANTAGES

- Reduces congestion and waiting times.
- Prevents accidents by reducing collision risks by optimizing traffic light timings.
- Lowers fuel consumption and vehicle emissions.
- Real-time traffic monitoring and adaptive control.
- Reduced manual intervention in traffic management.
- Efficient coordination between multiple intersections.



DISADVANTAGES

- High initial setup costs.
- Requires regular maintenance and calibration.
- Sensor performance can be impacted by weather or dirt.



CONCLUSION

- The smart traffic light system designed in this project offers an effective solution to traffic congestion by dynamically adjusting traffic light durations based on real-time vehicle density.
- Using components like the LPC2138 microcontroller and IR sensors, this system provides a cost-effective and efficient way to reduce waiting times, fuel consumption, and emissions.
- This approach, while needing regular maintenance, shows promise for scalable implementation across busy intersections and urban centers.